# Economics 675: Applied Microeconometrics Fall 2018 - Assignment 2

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# 1 Question 1: Kernel Density Estimation

# 1.1 Expectation and Variance

First, note that  $\hat{f}^{(s)}(x) = \frac{1}{nh_n^{s+1}} \sum_{i=1}^n (-1)^s K^{(s)}\left(\frac{x_i - x}{h_n}\right)$ .

Then we have:

$$\begin{split} \mathbb{E}[\hat{f}^{(s)}(x)] &= \mathbb{E}\Big[\frac{1}{nh_n^{s+1}} \sum_{i=1}^n (-1)^s K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)\Big] \\ &= (-1)^s \frac{1}{h_n^{s+1}} \int K^{(s)} \Big(\frac{z - x}{h_n}\Big) f(z) dz \\ &= (-1)^s \frac{1}{h_n^{s+1}} \int K^{(s)}(u) f(x + uh_n) h_n du \\ &= (-1)^s \frac{1}{h_n^s} \int K^{(s)}(u) f(x + uh_n) du \\ &= (-1)^{s-1} \frac{1}{h_n^{s-1}} \int K^{(s-1)}(u) f^{(1)}(x + uh_n) du \\ &= \dots \text{ (keep rolling back to } s) \\ &= (-1)^{s-s} \frac{1}{h_n^{s-s}} \int K^{(s-s)}(u) f^{(s)}(x + uh_n) du \\ &= \int K(u) f^{(s)}(x + uh_n) du \\ &= \int K(u) \Big[ f^{(s)}(x) + \dots + \frac{u^P h_n^P}{P!} f^{(s+P)}(x) + \frac{u^{P+1} h_n^{P+1}}{(P+1)!} f^{(s+P+1)}(\tilde{x}) \Big] du \\ &= f^{(s)}(x) + h_n^P \mu_P(K) \frac{f^{(P+s)}(x)}{P!} + O(h_n^{P+1}) \end{split}$$

In the third line, using change of variables with  $u = \frac{z-x}{h_n}$ , so  $du = dz*1/h_n$ ; in the fifth line using integration-by-parts; in the second-to-last line, using a Taylor approximation; and in the final line using the definition of  $\mu_{\ell}(K)$ .

Then turning to the variance, we have:

$$\begin{split} \mathbb{V}[\hat{f}^{(s)}(x)] &= \mathbb{V}\Big[\frac{1}{nh_n^{s+1}} \sum_{i=1}^n (-1)^s K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)\Big] \\ &= \frac{n}{n^2 h_n^{2(s+1)}} \mathbb{V}\Big[K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)\Big] \\ &= \frac{1}{nh_n^{2(s+1)}} \Big(\mathbb{E}\Big[K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)^2\Big] - \mathbb{E}\Big[K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)\Big]^2\Big) \\ &= \frac{1}{nh_n^{2(s+1)}} \Big(\mathbb{E}\Big[K^{(s)} \Big(\frac{x_i - x}{h_n}\Big)^2\Big]\Big) \Big(1 + o(1)\Big) \\ &= \frac{1}{nh_n^{2(s+1)}} \Big(\int K^{(s)} \Big(\frac{z - x}{h_n}\Big)^2 f(z) dz\Big) \Big(1 + o(1)\Big) \\ &= \frac{1}{nh_n^{2(s+1)}} \Big(\int K^{(s)} (u)^2 f(x + uh_n) h_n du\Big) \Big(1 + o(1)\Big) \\ &= \frac{1}{nh_n^{2s+1}} \Big(\int K^{(s)} (u)^2 f(x + uh_n) du\Big) \Big(1 + o(1)\Big) \\ &= \frac{1}{nh_n^{2s+1}} \cdot v_s(K) \cdot f(x) \Big(1 + o(1)\Big) \\ &= \frac{1}{nh_n^{2s+1}} \cdot v_s(K) \cdot f(x) + o\Big(\frac{1}{nh_n^{2s+1}}\Big) \end{split}$$

Using the same change-of-variables as above.

#### 1.2 Mean-Squared Error

Start with the given definition of AIMSE[h], then plug in the definition for  $\mu_{\ell}(K)$  and  $\nu_{\ell}(K)$ :

$$\begin{aligned} \text{AIMSE}[h] &= \int \left[ \left( h_n^P \cdot \mu_P(K) \cdot \frac{f^{(P+s)}(x)}{P!} \right)^2 + \frac{1}{nh_n^{1+2s}} \cdot v_s(K) \cdot f(x) \right] dx \\ &= h_n^{2P} \cdot \mu_P(K)^2 \cdot \int \left( \frac{f^{(P+s)}(x)}{P!} \right)^2 dx + \frac{1}{nh_n^{1+2s}} \cdot v_s(K) \\ &= h_n^{2P} \cdot \mu_P(K)^2 \cdot \frac{1}{(P!)^2} \cdot v_{s+P}(f) + \frac{1}{nh_n^{1+2s}} \cdot v_s(K) \end{aligned}$$

From here, we can take the derivative wrt  $h_n$  to find the optimal bandwidth:

$$\frac{\partial}{\partial h_n} \text{AIMSE}[h] = 2P \cdot h_n^{2P-1} \cdot \mu_P(K)^2 \cdot \frac{1}{(P!)^2} \cdot v_{s+P}(f) + \frac{-1-2s}{nh_n^{2+2s}} \cdot v_s(K) = 0$$

Combining terms and solving for  $h_n$  yields the optimal bandwidth as desired:

$$h_n^* = \left[ \frac{(2s+1)(P!)^2}{2P} \frac{v_s(K)}{v_{s+P}(f) \cdot \mu_P(K)^2} \frac{1}{n} \right]^{\frac{1}{2s+2P+1}}$$

My proposed data-driven bandwidth selection procedure:

We choose P and s, we can easily calculate  $\mu_P(K)^2$ , we can calculate  $v_s(K)$ , and we know n. Hence to implement this we only need to estimate  $v_{s+P}(f)$ , but this requires estimating the s+Pth derivative of the density function f, which we do not know.

To estimate  $f^{(s+P)}$ , begin with a generic f (the normal distribution, say). Use this to estimate an initial guess for  $h_{n,0}$ . Using this initial estimate, we can construct  $\hat{f}(x; h_{n,0})$  as defined at the outset of this question, as well as the necessary derivative of  $\hat{f}$ . Using this updated density  $\hat{f}$ , we can then determine the optimal bandwidth  $h_{n,*}$  as desired.

#### 1.3 Implementation

(a) See the code in Appendix A for R, and Appendix B for Stata. Note that I mainly focused on implementing these questions in R, and relied heavily on my classmates to attempt implementation in Stata.

Using R, I compute theoretically the AIMSE-optimal bandwidth for s = 0, n = 1000, using the Epanechnikov kernel, as 0.8199. Using Stata I compute this as [].

(b) See Figures 1 and [Stataref]. Using R, I estimate  $h_{\text{IMSE},\text{LI}} = h_{\text{AIMSE}} = 0.9019$  and the same for  $h_{\text{IMSE},\text{LO}}$ . I estimate the same values, respectively, using STATA as blah and blah.

[Stata figure here]

- (c): True.
- (d) Using R I estimate  $\bar{h}_{AIMSE} = 0.9883$  and using Stata I estimate  $\bar{h}_{AIMSE} = blah$ .

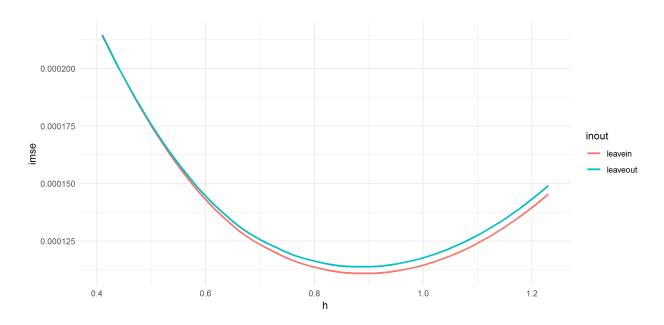


Figure 1: Estimated IMSE (Leave In and Leave Out) as a function of  $h\!\colon \mathbf{R}$ 

### 2 Question 2: Linear Smoothers, Cross-validation, and Series

#### 2.1 Local Polynomial Regression and Series Estimators

For local polynomial regression, I rely on lecture notes available from the University of Manchester here. Define the following:

$$\mathbf{X} = \begin{bmatrix} 1 & x_1 - x & (x_1 - x)^2 & \dots & (x_1 - x)^p \\ 1 & x_1 - x & (x_2 - x)^2 & \dots & (x_2 - x)^p \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_n - x & (x_n - x)^2 & \dots & (x_n - x)^p \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

With weighting/kernel matrix  $\mathbf{W} = \text{diag}\{K_h(x_i - x), i = 1, ..., n\}$ .

Also define the vector  $\mathbf{e}_1$  of length p+1, with a 1 in the first position and 0 elsewhere.

We can write the estimator in the linear smoother form as:

$$\hat{e}(x) = \mathbf{e}_1'(\mathbf{X}'\mathbf{W}\mathbf{X})^{-1}(\mathbf{X}'\mathbf{W}\mathbf{Y})$$

$$= \sum_{i=1}^n \mathbf{e}_1'(\mathbf{X}'\mathbf{W}\mathbf{X})^{-1} \begin{bmatrix} 1\\ (x_i - x)\\ (x_i - x)^2\\ \dots\\ (x_i - x)^p \end{bmatrix} K_h(x_i - x)y_i$$

$$= \sum_{i=1}^n w_{n,i}(x)y_i$$

For series estimators I rely on Bruce Hansen's lecture notes here.

Consider an arbitrary series basis  $\mathbf{z}(\cdot): \mathbb{R}^{d_x} \to \mathbb{R}^K$  and define the regressor matrix  $\mathbf{Z}$  as:

$$\mathbf{Z} = \begin{bmatrix} \mathbf{z}(x_1)' \\ \mathbf{z}(x_2)' \\ \dots \\ \mathbf{z}(x_n)' \end{bmatrix}$$

Then we can write the estimator in the linear smoother form as:

$$\hat{e}(x) = \mathbf{z}(x)'(\mathbf{Z}'\mathbf{Z})^{-1}\mathbf{Z}'\mathbf{Y}$$

$$= \sum_{i=1}^{n} \mathbf{z}(x)'(\mathbf{Z}'\mathbf{Z})^{-1}\mathbf{z}(x_i)y_i$$

$$= \sum_{i=1}^{n} w_{n,i}(x)y_i$$

#### 2.2 Cross-Validation

First focusing on series estimators, and using the hint given in the footnote, we have:

$$\hat{e}(x_{i}) = \mathbf{p}(x_{i})'(\mathbf{P}'\mathbf{P})^{-1}\mathbf{P}\mathbf{Y} 
= \sum_{j} \mathbf{p}(x_{i})'(\mathbf{P}'\mathbf{P})^{-1}\mathbf{p}(x_{j})y_{j} 
= \sum_{j} \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)} + \mathbf{p}(x_{i})\mathbf{p}(x_{i})'\right)^{-1}\mathbf{p}(x_{j})y_{j} 
= w_{n,i}(x_{i})y_{i} + \sum_{j\neq i} \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)} + \mathbf{p}(x_{i})\mathbf{p}(x_{i})'\right)^{-1}\mathbf{p}(x_{j})y_{j} 
= w_{n,i}(x_{i})y_{i} + \sum_{j\neq i} \mathbf{p}(x_{i})'\left(\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1} - \frac{\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})\mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}}{1 + \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})}\right)\mathbf{p}(x_{j})y_{j} 
= w_{n,i}(x_{i})y_{i} + \left(1 - \frac{\mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})}{1 + \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})}\right)\sum_{j\neq i} \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{j})y_{j} 
= w_{n,i}(x_{i})y_{i} + \left(1 - \frac{\mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})}{1 + \mathbf{p}(x_{i})'\left(\mathbf{P}'_{(i)}\mathbf{P}_{(i)}\right)^{-1}\mathbf{p}(x_{i})}\right)\hat{e}_{(i)}(x_{i})$$

And again using the hint, we have

$$w_{n,i}(x_i) = \mathbf{p}(x_i)' \left( \left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1} - \frac{\left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1} \mathbf{p}(x_i) \mathbf{p}(x_i)' \left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1}}{1 + \mathbf{p}(x_i)' \left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1} \mathbf{p}(x_i)} \right) \mathbf{p}(x_i)$$

$$= \frac{\mathbf{p}(x_i)' \left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1} \mathbf{p}(x_i)}{1 + \mathbf{p}(x_i)' \left( \mathbf{P}'_{(i)} \mathbf{P}_{(i)} \right)^{-1} \mathbf{p}(x_i)}$$

Thus we have  $\hat{e}(x_i) = w_{n,i}(x_i)y_i + (1 - w_{n,i}(x_i))\hat{e}_{(i)}(x_i)$ , and after rearranging we have:

$$y_i - \hat{e}_{(i)}(x_i) = \frac{y_i - \hat{e}(x_i)}{1 - w_{n,i}(x_i)}$$

as desired.

#### 2.3 Standard Errors

We know that  $\mathbb{E}[\hat{e}(x)] \to_p e(x)$ , so once we understand the variance term, we can apply Slutsky, LLN, and CLT to show the result.

#### 2.4 Confidence Intervals

Using the conclusion of part (3) above, we have the following:

$$CI_{95\%}(x) = \left[\hat{e}(x) \pm 1.96 \cdot \sqrt{\hat{V}[\hat{e}(x)|x_1, x_2, ..., x_n]}\right]$$

Pointwise valid requires  $\forall x$ ,  $\liminf_n \mathbb{P}[e(x) \in CI(x)] \geq 0.95$ .

Uniformly valid has the stronger requirement that  $\liminf_n \mathbb{P}[\forall x : e(x) \in CI(x)] \geq 0.95$ .

# 2.5 Implementation

(a) See the code in Appendix A for R, and Appendix B for Stata. Note that I mainly focused on implementing these questions in R, and relied heavily on my classmates to attempt implementation in Stata.

(b) See Figures 2 and 3. Based on my simulations, the optimal CV estimator is  $\hat{K}_{CV} = 7$ .

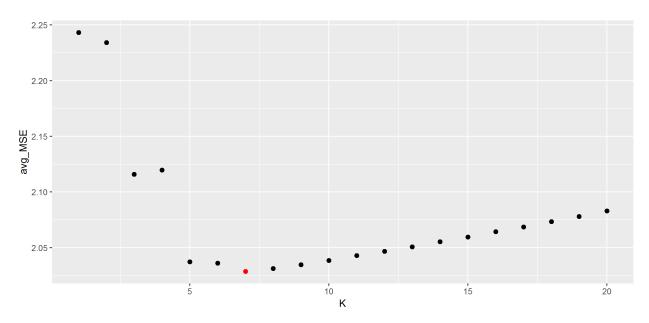


Figure 2: Cross-Validation Simulation Results: R

- (c) See Figures 4 and [Stataref]. [Stata figure here]
- (d) See Figures 5 and [Stataref]. [Stata figure here]

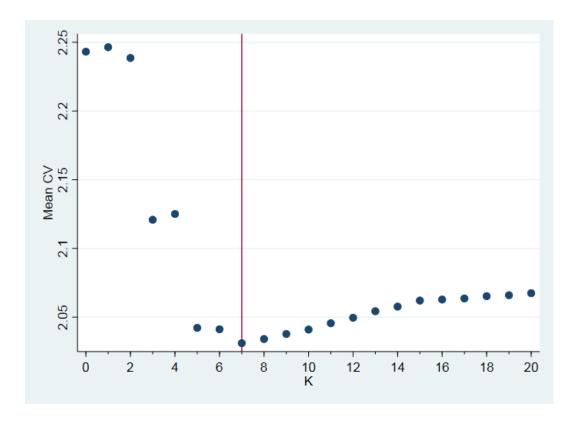


Figure 3: Cross-Validation Simulation Results:  ${\bf R}$ 

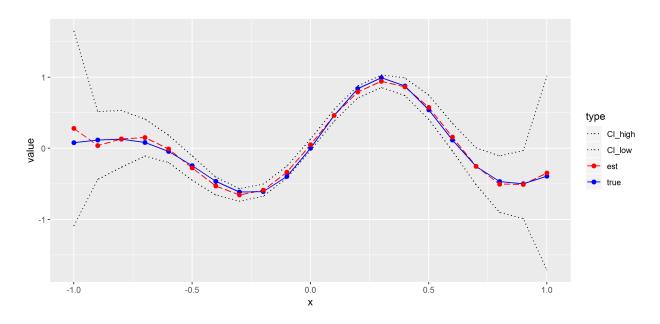


Figure 4: True and Estimated Regression Functions: R

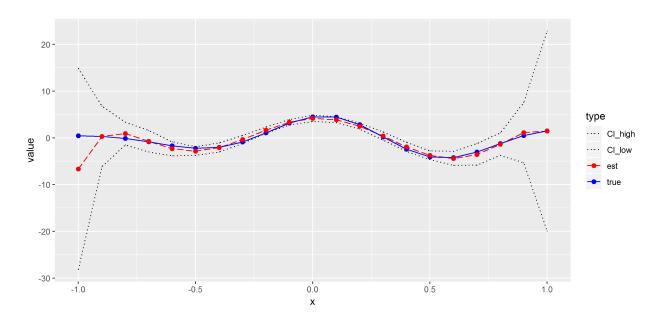


Figure 5: True and Estimated First Derivatives of the Regression Function: R

## 3 Question 3: Semiparametric Semi-Linear Model

#### 3.1 Identification

We apply the Law of Iterated Expectations and substitute in the definition of  $y_i$  to split out the inside of the initial expectation, yielding terms that are assumed to equal zero:

$$\begin{split} \mathbb{E}[(t_i - h_0(\mathbf{x}_i))(y_i - t_i\theta_0)] &= \mathbb{E}\Big[\mathbb{E}[(t_i - h_0(\mathbf{x}_i))(y_i - t_i\theta_0)|\mathbf{x}_i]\Big] \\ &= \mathbb{E}\Big[\mathbb{E}[(t_i - h_0(\mathbf{x}_i))(g_0(\mathbf{x}_i) + \varepsilon_i)|\mathbf{x}_i]\Big] \\ &= \mathbb{E}\Big[\mathbb{E}[(t_i - h_0(\mathbf{x}_i))g_0(\mathbf{x}_i)|\mathbf{x}_i]\Big] + \mathbb{E}\Big[\mathbb{E}[(t_i - h_0(\mathbf{x}_i))\varepsilon_i|\mathbf{x}_i]\Big] \\ &= \mathbb{E}\Big[g_0(\mathbf{x}_i)\mathbb{E}[(t_i - h_0(\mathbf{x}_i))|\mathbf{x}_i]\Big] + \mathbb{E}\Big[\mathbb{E}[(t_i - h_0(\mathbf{x}_i))\varepsilon_i|\mathbf{x}_i, t_i]\Big] \\ &= \mathbb{E}\Big[g_0(\mathbf{x}_i)\mathbb{E}[(t_i - h_0(\mathbf{x}_i))|\mathbf{x}_i]\Big] + \mathbb{E}\Big[(t_i - h_0(\mathbf{x}_i))\mathbb{E}[\varepsilon_i|\mathbf{x}_i, t_i]\Big] \\ &= \mathbb{E}\Big[g_0(\mathbf{x}_i)\mathbb{E}[(t_i - \mathbb{E}[t_i|\mathbf{x}_i])|\mathbf{x}_i]\Big] + \mathbb{E}\Big[(t_i - h_0(\mathbf{x}_i))\mathbb{E}[\varepsilon_i|\mathbf{x}_i, t_i]\Big] \\ &= \mathbb{E}\Big[g_0(\mathbf{x}_i)\cdot 0\Big] + \mathbb{E}\Big[(t_i - h_0(\mathbf{x}_i))\cdot 0\Big] = 0 \end{split}$$

Then taking the initial expectaion, splitting it, and pulling out  $\theta_0$  we have:

$$\mathbb{E}[(t_i - h_0(\mathbf{x}_i))y_i] - \mathbb{E}[(t_i - h_0(\mathbf{x}_i))t_i] \cdot \theta_0 = 0 \implies \theta_0 = \frac{\mathbb{E}[(t_i - h_0(\mathbf{x}_i))y_i]}{\mathbb{E}[(t_i - h_0(\mathbf{x}_i))t_i]}$$

Given this expression for  $\theta_0$ , we can see that it will be identified so long as the denominator is non-zero, i.e.,  $\mathbb{E}[(t_i - h_0(\mathbf{x}_i))t_i] \neq 0$ .

For an IV interpretation, consider the reduced form expression  $y_i = t_i\theta_0 + g_0(\mathbf{x}_i) + \varepsilon_i = t_i\theta_0 + u_i$ . Here,  $u_i$  is uncorrelated with  $t_i$  so we can define an instrument  $z_i = t_i - h_0(\mathbf{x}_i)$ ; we have  $\mathbb{E}[z_i u_i] = 0$  and  $\mathbb{E}[t_i z_i] \neq 0$ , and hence a valid instrument.

#### 3.2 Series Estimation

(a) Define matrices as follows (similar to Subsection 2.1 above):

$$\mathbf{P} = \begin{bmatrix} \mathbf{p}^K(\mathbf{x}_1)' \\ \mathbf{p}^K(\mathbf{x}_2)' \\ \dots \\ \mathbf{p}^K(\mathbf{x}_n)' \end{bmatrix}, \quad \mathbf{T} = \begin{bmatrix} t_1 \\ t_2 \\ \dots \\ t_n \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

Then we can define the annihilator matrix  $\mathbf{M}_{\mathbf{P}} = \mathbf{I} - \mathbf{P}(\mathbf{P}'\mathbf{P})^{-1}\mathbf{P}'$ , and regress  $y_i$  on  $t_i$  and  $\mathbf{p}^{K_n}(\mathbf{x}_i)$ , yielding:

$$\hat{\theta}(K) = (\mathbf{T}'\mathbf{M}_{\mathbf{P}}\mathbf{T})^{-1}(\mathbf{T}'\mathbf{M}_{\mathbf{P}}\mathbf{Y})$$

(b) We have  $h_0(\mathbf{x}) = \mathbb{E}[t_i|\mathbf{x}_i] \approx \mathbf{p}^K(\mathbf{x}_i)'\delta_K$ . Thus if we regress  $t_i$  on  $\mathbf{p}^K(\mathbf{x}_i)'$  to estimate  $\hat{\delta}_K$ , we can then estimate  $\hat{h}(\mathbf{x}_i)$ :

$$\hat{h}(\mathbf{x}_i) = \mathbf{p}^K(\mathbf{x}_i)'\hat{\delta}_K = \mathbf{p}^K(\mathbf{x}_i)'(\mathbf{P}'\mathbf{P})^{-1}\mathbf{P}'\mathbf{T}$$

Then we can construct the residuals, and show that with these we yield the same estimate of  $\theta_0$  as in part (a):

Residual of the  $t_i$  regression is  $t_i - \mathbf{p}^K(\mathbf{x}_i)'(\mathbf{P'P})^{-1}\mathbf{P'T} = \mathbf{e}_1'\mathbf{M}_P\mathbf{T}$ , with  $\mathbf{e}_i$  a vector of zeros with a 1 in the i-th element.

Then we can show that the numerator and denominator we derived in part (a) are numerically equivalent to that we find using this method:

$$\hat{\mathbb{E}}[(t_i - h_0(\mathbf{x}_i))y_i] = \frac{1}{n} \sum_{i=1}^n \mathbf{e}_i' \mathbf{M}_{\mathbf{P}} \mathbf{T} y_i = \frac{1}{n} \mathbf{T}' \mathbf{M}_{\mathbf{P}} \sum_{i=1}^n \mathbf{e}_i y_i = \frac{1}{n} \mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{Y}$$

$$\hat{\mathbb{E}}[(t_i - h_0(\mathbf{x}_i))t_i] = \frac{1}{n} \sum_{i=1}^n \mathbf{e}_i' \mathbf{M}_{\mathbf{P}} \mathbf{T} t_i = \frac{1}{n} \mathbf{T}' \mathbf{M}_{\mathbf{P}} \sum_{i=1}^n \mathbf{e}_i t_i = \frac{1}{n} \mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{T}$$

Finally, dividing the numerator by the denominator, we have the same result as in (a) for estimating  $\theta_0$ :

$$\hat{\theta}(K) = \frac{\hat{\mathbb{E}}[(t_i - h_0(\mathbf{x}_i))y_i]}{\hat{\mathbb{E}}[(t_i - h_0(\mathbf{x}_i))t_i]} = (\mathbf{T}'\mathbf{M}_{\mathbf{P}}\mathbf{T})^{-1}(\mathbf{T}'\mathbf{M}_{\mathbf{P}}\mathbf{Y})$$

#### 3.3 Asymptotics

(a) We can show that  $\hat{\theta}(K) - \theta_0 \to_d \mathcal{N}(0, V)$ , and then describe V.

$$\hat{\theta}(K) - \theta_0 = (\mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{T})^{-1} (\mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{Y}) - \theta_0$$

$$= (\mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{T})^{-1} (\mathbf{T}' \mathbf{M}_{\mathbf{P}} (\mathbf{T} \theta_0 + g_0(\mathbf{x}_i) + \varepsilon)) - \theta_0$$

$$= (\mathbf{T}' \mathbf{M}_{\mathbf{P}} \mathbf{T})^{-1} (\mathbf{T}' \mathbf{M}_{\mathbf{P}} (g_0(\mathbf{x}_i) + \varepsilon))$$

(b) This is a straightforward application of the distribution noted in (a):

$$\mathrm{CI}_{95\%} = \left[\hat{\theta}(K) \pm 1.96 \cdot \sqrt{\hat{V}_{\mathrm{HCO}}}\right]$$

### 3.4 Implementation

- (a) See the code in Appendix A for R, and Appendix B for Stata. Note that I mainly focused on implementing these questions in R, and relied heavily on my classmates to attempt implementation in Stata.
- (b) Results are in the following tables; code in the appendices.

Table 1: Monte Carlo Results: R

K	Avg $\hat{\theta}(K)$	Avg Bias	Sample Variance	Avg $\hat{V}_{\text{HCO}}$	Coverage Rate
6	3.044	2.044	0.392	0.346	0.109
11	0.645	-0.355	0.108	0.107	0.997
21	0.654	-0.346	0.108	0.105	0.998
26	0.655	-0.345	0.108	0.105	0.994
56	0.695	-0.305	0.102	0.094	1.000
61	0.727	-0.273	0.095	0.086	1.000
126	1.019	0.019	0.030	0.022	1.000
131	1.018	0.018	0.031	0.022	1.000
252	1.001	0.001	0.033	0.019	1.000
257	0.999	-0.001	0.033	0.019	1.000
262	0.999	-0.001	0.034	0.019	1.000
267	1.001	0.001	0.035	0.019	1.000
272	1.000	0.000	0.036	0.019	1.000
277	1.000	-0.000	0.036	0.019	1.000

[Stata table here]

(c) Using R, I estimate the following:

- Average  $K_{CV}=127.6$ , Median  $K_{CV}=126$
- Average  $\hat{\theta}(K_{CV}) = 1.018$
- Sample Variance of  $\hat{\theta}_{K_{CV}} = .0300$
- Average of  $\hat{\mathbb{V}}_{HCO} = .0224$
- Average Coverage Rate = 90.4%

I also plot some of my results in Figure 6:

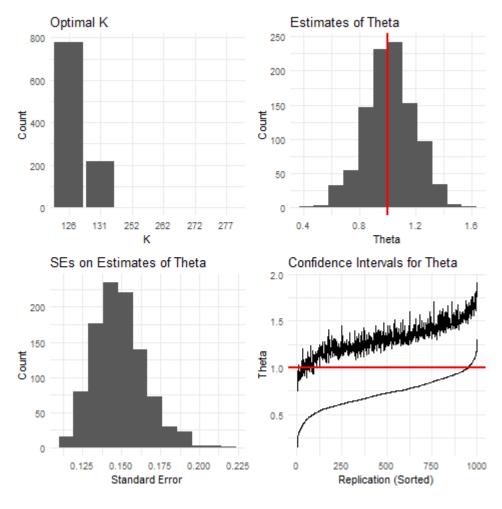


Figure 6: Monte Carlo Results using Cross Validation: R

Using Stata, I estimate the following:

- Average  $K_{CV} =$ , Median  $K_{CV} =$
- Average  $\hat{\theta}(K_{CV}) =$
- Average Bias of  $\hat{\theta}_{K_{CV}} =$
- Sample Variance of  $\hat{\theta}_{K_{CV}} =$

- Average of  $\hat{\mathbb{V}}_{HCO} =$
- Average Coverage Rate =

I also plot some of my results in Figure [Stataref]: [Stata figure here]

#### A R Code

```
# Author: Paul R. Organ
# Purpose: ECON 675, PS2
# Last Update: Oct 10, 2018
# Preliminaries
options (strings As Factors = F)
# packages
require(tidyverse) # data cleaning and manipulation
require (magrittr) # syntax
require (ggplot2) # plots
require (kedd)
               \# kernel \ bandwidth \ estimation
require (car)
               # heteroskedastic robust SEs
require(xtable)
              # tables for LaTeX
setwd('C:/Users/prorgan/Box/Classes/Econ_675/Problem_Sets/PS2')
## Question 1: Kernel Density Estimation
## Q1.3 a
# sample size
    <- 1000
# data generating process
dgp <- function(n){
 # equally weight two distributions
 comps \leftarrow sample(1:2, prob=c(.5,.5), size=n, replace=T)
 # Normal density specs
 mus < -c(-1.5, 1)
 sds \leftarrow sqrt(c(1.5, 1))
 # generate sample
 samp <- rnorm(n=n, mean=mus[comps], sd=sds[comps])
 return (samp)
}
# true dgp
f_{true} \leftarrow function(x) \{.5*dnorm(x, -1.5, sqrt(1.5)) + .5*dnorm(x, 1, 1)\}
# second deriv of normal dist
```

```
norm_2d <- function(u, meanu, sdu){dnorm(u, mean=meanu, sd=sdu)*
                     (((u-meanu)^2/(sdu^4))-(1/(sdu^2)))
\# f for integration (theoretical)
f_{int} \leftarrow function(x) \{ (.5*norm_2d(x, -1.5, 1.5) + .5*norm_2d(x, 1, 1))^2 \}
\# function to calculate (theoretically or empirical) optimal h
optimal_h <- function(x,mu,sd){
  k1 \leftarrow .75^2 * (2 - 4/3 + 2/5)
  k2 < -.75 * (2/3 - 2/5)
  if (x='theoretical'){
    f \leftarrow f_i n t
    k3 <- integrate (f,-Inf, Inf) $val
  } else{
    f \leftarrow function(x, mu, sd)\{norm_2d(x, mu, sd)^2\}
    k3 <- integrate (f,-Inf,Inf,mu=mu,sd=sd)$val
  h \leftarrow (k1/(k3*k2^2)*(1/n))^(1/5)
  \mathbf{return}(h)
}
# theoretically optimal h
h_aimse <- optimal_h('theoretical',NA,NA)
## Q1.3b
# define Kernel function: K(u)=.75(1-u^2)(ind(abs(u)<=1))
K0 <- function(u){
  out <-.75 * (1-u^2) * (abs(u) <= 1)
# function to calculate IMSE
imse \leftarrow function (h, X)
  # empty vectors to fill with results
  e_li \leftarrow rep(NA, n)
  e_lo < - rep(NA, n)
  # loop over each i to do leave one out
  for(i in 1:n){
    # repeat observation for each simulation
    Xi_n \leftarrow \mathbf{rep}(X[i], n)
    \# apply kernel function to (x-x_i)/h
    df \leftarrow K0((Xi_n-X)/h)
    # fhat with i in
    fhat_li \leftarrow mean(df)/h
    # fhat with i out
    fhat_lo \leftarrow mean(df[-i])/h
    \# f(x_i)
    f_xi \leftarrow f_true(X[i])
```

```
\# mse with i in
    e_li[i] \leftarrow (fhat_li-f_xi)^2
    \# mse with i out
    e_lo[i] \leftarrow (fhat_lo-f_xi)^2
  out < c (mean(e_li), mean(e_lo))
  return (out)
# simulate 1000 times
M < -1000
# sequence of h's to test
hs \leftarrow seq(.5, 1.5, .1) * h_aimse
nh <- length(hs)
# empty matrices to fill
imse_li <- matrix(NA, nrow=M, ncol=nh)
imse_lo <- matrix(NA, nrow=M, ncol=nh)
# generate matrix with M rows of sampled data
set . seed (22)
for (m in 1:M) {
  X \leftarrow dgp(n)
  for (j in 1:nh) {
    temp \leftarrow imse(hs[j],X)
    imse_li[m,j] \leftarrow temp[1]
    imse_lo[m, j] \leftarrow temp[2]
}
df <- data.frame(h = hs, leavein = colMeans(imse_li),
                 leaveout = colMeans(imse_lo)) %%
  gather (key = inout, value = imse, -h)
\# plot
p \leftarrow ggplot(df, aes(x=h,y=imse,color=inout)) + geom_smooth(se=F) +
  theme_minimal()
ggsave('q1_3b_R.png')
# averages
h_hat_li <- df %% filter (inout = 'leavein') %%
  filter (imse = min(imse)) %% select (h) %% as.numeric
h_hat_lo <- df %% filter(inout == 'leaveout') %%
  filter (imse = min(imse)) %% select (h) %% as.numeric
## Q1.3d
opt_hs \leftarrow rep(NA,M)
set.seed(22)
for (m in 1:M) {
```

```
X \leftarrow dgp(n)
 mu \leftarrow mean(X)
  sd \leftarrow sd(X)
  opt_hs[m] <- optimal_h(n,mu,sd)
hbar <- mean(opt_hs)
## Question 2: Linear Smoothers, Cross-Validation, and Series
\# clean up
rm(list = ls())
gc()
## Q2.5a
# define datagenerating process
set . seed (22)
dgp <- function(n){
 # input: sample size n
 # output: n draws of X and Y according to DGPs as specified in PSet
 \# X \sim Uniform(-1,1)
 X < - runif(n, -1, 1)
  \# Epsilon \sim x^2 * (Chisq_5 - 5)
 E \leftarrow (X^2) * (rchisq(n,5)-5)
  \# Y \sim exp(-.1*(4x-1)^2) * sin(5x) + Eps
 Y \leftarrow \exp(-0.1 * (4*X-1)^2) * \sin(5*X) + E
  out = data.frame(X=X,Y=Y)
# sample size
n < -1000
\# replications
M < -1000
## Q2.5b
# series truncation
K <- 1:20
nK \leftarrow length(K)
# define series cross-validation function
series_cv <- function(n, X, Y, nK, K){
 # input: n draws of X and Y, series truncation K of length nK
 # output: nK prediction errors
  # start with polynomial basis of X
 X_poly <- cbind(rep(1,n), poly(X, degree = nK))
```

```
# QR decomposition
 X_qr \leftarrow qr(X_poly)
  # coefficients
  coefs \leftarrow qr.coef(X_qr,Y)
  # cycle up through each power and store prediction errors
  out <- rep(NA,nK)
  for(k in 1:nK){
    X_{poly_k} < X_{poly_k}  (K[k]+1)]
    coefs_k \leftarrow matrix(coefs[1:(K[k]+1)],nrow=K[k]+1)
    Y_hat_k <- X_poly_k %*% coefs_k
    # w (see part 1 of question 2)
    w_k <- diag(X_poly_k %*% solve(t(X_poly_k) %*% X_poly_k) %*% t(X_poly_k))
    # prediction error
    cv_k \leftarrow mean(((Y-Y_hat_k)/(1-w_k))^2)
    \# save
    out[k] \leftarrow cv_k
  return (out)
}
# run series cv formula 1000 times, save results for plotting
# we want to capture the MSE for each K for each rep
MSEs <- matrix(NA, ncol=nK, nrow=M)
set . seed (22)
for (m in 1:M) {
  \mathbf{df} \leftarrow \mathrm{dgp}(\mathbf{n})
  MSEs[m,] \leftarrow series\_cv(n=n, X=df$X, Y=df$Y, nK=nK, K=K)
\# average CV(K) across simulations:
averages <- data.frame(K = 1:20, avg_MSE = colMeans(MSEs))
# identify optimal CV estimator
averages %% mutate(Group = (avg_MSE == min(avg_MSE)))
K_CV <- averages %% filter (Group) %% select (K) %% as.numeric
\# plot average CV(K), highlight the optimal one
plot \leftarrow ggplot(data = averages, aes(x = K, y = avg\_MSE, color = Group)) +
  geom_point(size = 2) + scale_color_manual(values=c('black', 'red')) +
  theme(legend.position='none')
plot
ggsave('q2_5b_R.png')
## Q2.5 c
# define grid of evaluation points
grid
        <- seq(-1,1,.1)
eval_pts <- length(grid)
```

```
# we know the true value of the regression function (from dgp defined above)
f_{\text{true}} \leftarrow \exp(-0.1 * (4*\text{grid}-1)^2) * \sin(5*\text{grid})
\# estimate regression function using polynomial basis (7th degree based on (b))
# generate polynomial basis for grid points
grid_poly <- cbind(1, grid, grid^2, grid^3, grid^4, grid^5, grid^6, grid^7)
# define empty matrices to fill with estimates
ests <- matrix(NA, ncol=eval_pts, nrow=M)
SEs <- matrix(NA, ncol=eval_pts, nrow=M)
# simulate M times
set . seed (22)
for (m in 1:M) {
  # draw data
  \mathbf{df} \leftarrow \mathrm{dgp}(n)
 X \leftarrow df X
 Y \leftarrow df Y
  # create polynomial
  X_{-}poly <- cbind (1, X, X^2, X^3, X^4, X^5, X^6, X^7)
  # run regression using drawn data
  reg <-lm(Y \sim X_-poly - 1)
  betas <- coefficients (reg)
  vars <- hccm(reg, type='hc0') # heteroskedasticity-corrected using 'car' package
  # calculate and save estimates and SEs using grid evaluation points
  ests [m,] <- grid_poly %*% betas
  SEs[m,] <- sqrt(diag(grid_poly %*% vars %*% t(grid_poly)))
# average across the simulations to create estimated regression function
f_est <- colMeans(ests)
# calculate average confidence intervals across the simulations
f_est_low <- colMeans(ests)-1.96*colMeans(SEs)
f_est_high <- colMeans(ests)+1.96*colMeans(SEs)
# gather data for plotting
df \leftarrow data.frame(x = grid, true = f_true, est = f_est,
                  CI_low = f_est_low, CI_high = f_est_high) %>%
  gather(key = type, value = value, -x)
# plot in one graph, note specification of options is alphabetical by type
\# types = CI_high, CI_low, est, true
plot \leftarrow ggplot(data = df, aes(x = x, y = value, color = type)) +
  geom_line(aes(linetype=type, color=type)) +
  geom_point(aes(color=type, size=type)) +
  scale_linetype_manual(values = c('dotted', 'dotted', 'longdash', 'solid')) +
  scale_color_manual(values = c('black', 'black', 'red', 'blue')) +
  scale_size_manual(values = c(0,0,2,2))
plot
```

```
ggsave('q2_5c_R.png')
## Q2.5d
# Now estimating the derivative of the regression function
# This will reuse my code from above, with new polynomials (taking derivs)
# true value of derivative of regression function (product rule)
f1_{\text{true}} \leftarrow \exp(-.1*(4*grid-1)^2)*5*\cos(5*grid) +
     \sin(5*grid)*(-.8*(4*grid-1)*exp(-.1*(4*grid-1)^2))
# estimate regression function using polynomial basis (7th degree based on (b))
# generate polynomial basis for grid points, first derivatives of grid_poly
 \mathbf{grid1\_poly} \leftarrow \mathbf{cbind}(0\,,\ 1,\ 2*\mathbf{grid}\,,\ 3*\mathbf{grid}\,^2,\ 4*\mathbf{grid}\,^3,\ 5*\mathbf{grid}\,^4,\ 6*\mathbf{grid}\,^5,\ 7*\mathbf{grid}\,^6) 
# define empty matrices to fill with estimates
ests1 <- matrix(NA, ncol=eval_pts, nrow=M)
SEs1 <- matrix(NA, ncol=eval_pts, nrow=M)
# simulate M times
\mathbf{set} . \mathbf{seed}(22)
for (m in 1:M) {
     # draw data
     \mathbf{df} \leftarrow \mathrm{dgp}(n)
     X \leftarrow df X
     Y \leftarrow df Y
     # create polynomial
     X_{-poly} \leftarrow cbind(1, X, X^2, X^3, X^4, X^5, X^6, X^7)
     \# \ run \ regression \ using \ drawn \ data
     reg <-lm(Y ~ X_poly - 1)
     betas <- coefficients (reg)
      \text{vars} \hspace{0.2cm} < \hspace{0.2cm} -\hspace{0.2cm} \text{hccm} \hspace{0.1cm} (\hspace{0.1cm} \text{reg} \hspace{0.1cm}, \hspace{0.1cm} \text{type='hc0'}) \hspace{0.1cm} \# \hspace{0.1cm} \hspace{0.1cm} heterosked a sticity-corrected \hspace{0.1cm} using \hspace{0.1cm} "car' \hspace{0.1cm} package \hspace{0.1cm} |\hspace{0.1cm} |
     # calculate and save estimates and SEs using grid evaluation points
     ests1[m,] <- grid1_poly %*% betas
     SEs1[m,] <- sqrt(diag(grid1_poly %*% vars %*% t(grid1_poly)))
# average across the simulations to create estimated regression function
f1_est <- colMeans(ests1)
\# calculate average confidence intervals across the simulations
f1_est_low <- colMeans(ests1)-1.96*colMeans(SEs1)
f1_est_high <- colMeans(ests1)+1.96*colMeans(SEs1)
# gather data for plotting
df1 <- data.frame(x = grid, true = f1_true, est = f1_est,
                                                   CI_{low} = f1_{est_{low}}, CI_{high} = f1_{est_{high}}) \%\%
        gather (key = type, value = value, -x)
# plot in one graph, note specification of options is alphabetical by type
\# types = CI_high, CI_low, est, true
```

```
plot \leftarrow ggplot(data = df1, aes(x = x, y = value, color = type)) +
  geom_line(aes(linetype=type, color=type)) +
  geom_point(aes(color=type, size=type)) +
  scale_linetype_manual(values = c('dotted', 'dotted', 'longdash', 'solid')) +
  scale_color_manual(values = c('black', 'black', 'red', 'blue')) +
  scale_size_manual(values = c(0,0,2,2))
ggsave('q2\_5d\_R.png')
## Question 3: Semiparametric Semi-Linear Model
# clean up
\mathbf{rm}(\mathbf{list} = \mathbf{ls}())
gc()
## Q3.4 a
# define data generating process
# sample size
n < -500
# replications
M < -1000
# define data generating process
dgp <- function(n){
  # input: sample size n
  # output: n draws of X and Y according to DGPs as specified in PSet
  \# X \text{ is a } d(5) \text{ by } n \text{ matrix } U(-1,1)
  X \leftarrow \mathbf{matrix}(\mathbf{runif}(n*5, -1, 1), \mathbf{ncol} = 5)
  \# V \sim N(0,1) and U \sim N(0,1)
  V \leftarrow \mathbf{rnorm}(n)
  U \leftarrow \mathbf{rnorm}(n)
  \# Eps = .36...*(1+||X||^2)*V
  E \leftarrow 0.3637899*(1+diag(X \%*\% t(X)))*V
  \# g_{-}\theta(X) = exp(|X||^2)
  G \leftarrow \exp(\operatorname{diag}(X \% * \% \mathbf{t}(X)))
  \# T = ind(||x|| + u >= 0) (times 1 to convert from Boolean to numeric)
  Tee \leftarrow matrix ((sqrt(diag(X%%t(X))) + U >= 0)*1, ncol = 1)
  \# Y \text{ as defined in problem (assuming } \backslash \text{theta} \_0 = 1)
  Y \leftarrow \mathbf{matrix} (\text{Tee} + G + E, \mathbf{ncol} = 1)
  \# returning list with matrix X, vector Y, vector T
  out = list(X=X,Y=Y,Tee=Tee)
# define polynomial basis
K \leftarrow c(6,11,21,26,56,61,126,131,252,257,262,267,272,277)
```

```
\# inputs: data matrix X, `order' K
    # outputs: polynomial basis of 'order' K
    # Note: this gets really ugly at the end,
    # but I was tired and gave up trying to find a more elegant way
    if(K==6){basis <- poly(X, degree=1, raw=T)}
     if (K==11) { basis <- cbind (poly (X, degree=1, raw=T),
                                                               X[,1]^2, X[,2]^2, X[,3]^2, X[,4]^2, X[,5]^2)
     if (K==21){basis <- poly (X, degree=2, raw=T)}
     if (K==26) { basis <- cbind (poly (X, degree=2, raw=T),
                                                               X[,1]^3,X[,2]^3,X[,3]^3,X[,4]^3,X[,5]^3)
     if (K==56) { basis <- poly (X, degree = 3, raw=T) }
     if (K==61) { basis <- cbind (poly (X, degree=3, raw=T),
                                                               X[,1]^4,X[,2]^4,X[,3]^4,X[,4]^4,X[,5]^4)
     if (K==126) { basis <- poly (X, degree=4,raw=T) }
     if (K==131) { basis <- cbind (poly (X, degree=4, raw=T),
                                                                 X[,1]^5,X[,2]^5,X[,3]^5,X[,4]^5,X[,5]^5)
    if (K==252) { basis <- poly (X, degree=5, raw=T) }
     if (K==257) { basis <- cbind (poly (X, degree=5, raw=T),
                                                                 X[,1]^6, X[,2]^6, X[,3]^6, X[,4]^6, X[,5]^6)
     if(K==262){ basis <- cbind(poly(X, degree=5, raw=T)),
                                                                 X[,1]^{\hat{}}6,X[,2]^{\hat{}}6,X[,3]^{\hat{}}6,X[,4]^{\hat{}}6,X[,5]^{\hat{}}6,
                                                                 X[,1]^{7},X[,2]^{7},X[,3]^{7},X[,4]^{7},X[,5]^{7})
    if(K==267){basis <- cbind(poly(X, degree=5, raw=T),
                                                                 X[,1]^6, X[,2]^6, X[,3]^6, X[,4]^6, X[,5]^6,
                                                                  X[,1]^{\hat{}}, X[,2]^{\hat{}}, X[,3]^{\hat{}}, X[,4]^{\hat{}}, X[,5]^{\hat{}}, Y
                                                                 X[,1]^8,X[,2]^8,X[,3]^8,X[,4]^8,X[,5]^8)
     if (K==272) { basis <- cbind (poly (X, degree=5, raw=T),
                                                                 X[,1]^{\hat{}}6,X[,2]^{\hat{}}6,X[,3]^{\hat{}}6,X[,4]^{\hat{}}6,X[,5]^{\hat{}}6,
                                                                  X[,1]^{7},X[,2]^{7},X[,3]^{7},X[,4]^{7},X[,5]^{7},
                                                                 X[,1]^8, X[,2]^8, X[,3]^8, X[,4]^8, X[,5]^8,
                                                                 X[,1]^9,X[,2]^9,X[,3]^9,X[,4]^9,X[,5]^9)
    if(K==277){basis <- cbind(poly(X, degree=5, raw=T),
                                                                 X[\ ,1] \hat{\ }6\ ,X[\ ,2] \hat{\ }6\ ,X[\ ,3] \hat{\ }6\ ,X[\ ,4] \hat{\ }6\ ,X[\ ,5] \hat{\ }6\ ,X[\ ,1] \hat{\ }7\ ,X[\ ,2] \hat{\ }7\ ,X[\ ,3] \hat{\ }7\ ,X[\ ,4] \hat{\ }7\ ,X[\ ,5] \hat{\ }7\ ,X[\ 
                                                                 X[,1]^8, X[,2]^8, X[,3]^8, X[,4]^8, X[,5]^8,
                                                                 X[,1]^9, X[,2]^9, X[,3]^9, X[,4]^9, X[,5]^9,
                                                                 X[,1]^10,X[,2]^10,X[,3]^10,X[,4]^10,X[,5]^10)
    return (basis)
}
## Q3.4b
# number of different orders to test
nK <- length(K)
# define blank matrices to fill with simulated results
thetas <- matrix (NA, ncol = nK, nrow = M)
SEs
                <- matrix (NA, ncol = nK, nrow = M)
\mathbf{set} . \mathbf{seed}(22)
ptm <- proc.time()
```

polybasis <- function(X,K){

```
for (m in 1:M) {
  # draw data
  data \leftarrow dgp(n)
     <- data$X
       <- data$Y
  Tee <- data$Tee
  # cycle through K orders
  for(k in 1:nK){
     # generate basis, add intercept
     X_{-poly} \leftarrow cbind(1, polybasis(X, K[k]))
     # define M_P (I-P(P'P)^{-1}P)
     M_P \leftarrow diag(n) - (X_poly \% solve((t(X_poly) \% X_poly)) \% (t(X_poly))
     \# \ estimate \ theta(K)
     theta <- (t(Tee) %*% M_P %*% Y)/(t(Tee) %*% M_P %*% Tee)
     # sigma (for variance estimate)
     sigma <- diag( as.numeric((M_P %*% (Y - Tee*as.numeric(theta))))^2)
     # standard error
     bread <- solve((t(Tee) %*% M_P %*% Tee))
     se <- sqrt (bread %*% (t (Tee) %*%M_P%*%sigma%*%M_P%*%Tee) %*% bread)
     # save to matrix
     thetas [m, k] <- theta
     SEs [m, k]
                  <- se
}
\mathbf{proc}.\mathbf{time}() - \mathbf{ptm}
# 12 minute runtime
# calculate averages, variances, etc. of simulated values
summ <- matrix(NA, ncol=6, nrow = nK)
for (k in 1:nK) {
  \operatorname{summ}[k,1] \leftarrow K[k] \# 'order' K
  \operatorname{summ}[k,2] \leftarrow \operatorname{mean}(\operatorname{thetas}[,k]) \# \operatorname{avergage} \operatorname{theta}(K)
  \operatorname{summ}[\,\mathrm{k}\,,3\,] \ \leftarrow \ \operatorname{summ}[\,\mathrm{k}\,,2\,] - 1 \ \# \ \operatorname{average} \ \operatorname{bias} \ \operatorname{of} \ \operatorname{theta}(K) \ (\operatorname{assuming} \ \operatorname{theta}\_0 = 1)
  summ[k,4] <- sd(thetas[,k])^2 # sample variance of theta(K)
  summ[k,5] \leftarrow mean((SEs[,k])^2) \# average \ of \ vhat
  # check if CIs for each simulation include 1 (here checking the boundaries)
  summ[k, 6] < 1 - mean(thetas[,k]-1.96*SEs[k] > 1 | thetas[,k]+1.96*SEs[k] < 1)
}
# format
summ % as . data . frame
\mathbf{names}(\mathrm{summ}) \; <\!\!-\; \mathbf{c}\left(\;'\mathrm{K'}\;,\;\;'\mathrm{avg\_theta}\;'\;,\;\;'\mathrm{avg\_bias}\;'\;,
                       'samp_variance', 'avg_vhat', 'coverage_rate')
# write for inclusion in latex document
\mathbf{print} (xtable (summ, digits=\mathbf{c}(0,0,3,3,3,3,3)), include .rownames=\mathbf{F})
```

```
## Q3.4c
\# define crossvalidation function
crossval <- function(X, Y, Tee, nK, K){
  # blank vector to fill with MSE
  MSEs <- rep(NA, nK)
  \# loop through each K to identify optimal bandwidth
  for(k in 1:nK){
    # define polynomial basis
    X_{-poly} \leftarrow cbind(1, Tee, polybasis(X, K[k]))
    # QR decomposition
    X_{poly}Q \leftarrow qr.Q(qr(X_{poly}))
    XX <- X_poly_Q %*% t (X_poly_Q)
    Y_-hat \leftarrow XX \% Y
    W \leftarrow diag(XX)
    MSEs[k] \leftarrow mean(((Y-Y-hat)/(1-W))^2)
  }
  # return the optimal K
  return (K[which.min(MSEs)])
}
\# define blank vectors to fill with simulated results and optimal Ks
# (not matrices now, since we are using optimal K)
thetas <- rep(NA, M)
SEs
       \leftarrow rep (NA, M)
Ks
       \leftarrow rep(NA, M)
# simulate M times
\mathbf{set} . \mathbf{seed} (22)
ptm <- proc.time()
for (m in 1:M) {
  # draw data
  data \leftarrow dgp(n)
     <- data$X
      <- data$Y
  Tee <- data$Tee
  # given data, estimate optimal K using cross validation
  K_{-}CV \leftarrow crossval(X, Y, Tee, nK, K)
  \# generate basis, add intercept
  X_{-}poly \leftarrow cbind (1, polybasis (X, K_{-}CV))
  # define M_P (I-P(P'P)^{-1}P)
  M_{-}P \leftarrow diag(n) - (X_{-}poly \%*\% solve((t(X_{-}poly) \%*\% X_{-}poly)) \%*\% t(X_{-}poly))
  \# estimate theta (K)
  theta <- (t (Tee) %*% M_P %*% Y)/(t (Tee) %*% M_P %*% Tee)
  # sigma (for variance estimate)
  sigma <- diag( as.numeric((M_P %*% (Y - Tee*as.numeric(theta))))^2)
```

```
# standard error
  bread <- solve((t(Tee) %*% M_P %*% Tee))
  se <- sqrt (bread %*% (t (Tee)%*%M_P%*%sigma%*%M_P%*%Tee) %*% bread)
  # save to vectors
  thetas [m] <- theta
  SEs [m]
             <- se
  Ks [m]
             <- K_CV
\mathbf{proc}.\mathbf{time}() - \mathbf{ptm}
# runtime 14 minutes
# prep data for plots to show results
\mathbf{df} \leftarrow \mathbf{data}.\mathbf{frame}(K = Ks, \text{ theta} = \text{thetas}, \mathbf{se} = SEs, \mathbf{rep} = 1:M) \%
  mutate(ci_low = theta - 1.96*se, ci_high = theta + 1.96*se) %%
  arrange(ci_low) %>% mutate(rep_sorted = 1:M)
# panel 1: histogram of optimal Ks
k_df <- df %% group_by(K) %% summarise(Count = n()) %% mutate(K = as.character(K))
p1 \leftarrow ggplot(k_df, aes(x=K,y=Count)) + geom_bar(stat='identity') +
  theme_minimal() + ggtitle('Optimal_K')
р1
# panel 2: distribution of theta
p2 <- ggplot(df, aes(x=theta)) + geom_histogram(bins=12) + theme_minimal() +
  geom_vline(xintercept=1,linetype='solid',color='red',size=1) +
  labs (title='Estimates_of_Theta', x='Theta', y='Count')
p2
# panel 3: distribution of SEs
p3 \leftarrow ggplot(\mathbf{df}, aes(x=se)) + geom_histogram(bins=12) + theme_minimal() +
  labs(title='SEs_on_Estimates_of_Theta', x='Standard_Error', y='Count')
p3
# panel 4: confidence intervals, sorted by lower point
p4 \leftarrow ggplot(\mathbf{df}) +
  geom\_line(aes(x = rep\_sorted, y=ci\_low)) +
  geom\_line(aes(x = rep\_sorted, y=ci\_high)) +
  geom_hline(yintercept=1,linetype='solid',color='red',size=1) +
  theme_minimal() +
  labs (title='Confidence_Intervals_for_Theta', x='Replication_(Sorted)', y='Theta')
p4
# combine with multiplot
source('multiplot.R')
png('q3_4c_R.png')
multiplot(p1, p3, p2, p4, cols=2)
dev.off()
# values for latex
avg_K
          <- mean(Ks)
median_K <- median(Ks)
avg_theta <- mean(thetas)
avg_bias \leftarrow mean(thetas)-1
```

# B Stata Code

Blah