Embodied QA	Can robot pick up the bowl now?

GPT4o: ❌
Yes, the bowl is placed on a flat surface and is accessible.
PhysVLM: ✅
No, the bowl is not within the robot arm's reachable space.

Task Planning	Task goal is to put the can into the bowl, what are the next steps?

GPT4o: ❌ Execution failure
Picking up the can and place it inside the bowl.
PhysVLM: ✅
1-Move close to the can. 2-Pick up the can. 3-Place the can into the bowl. 4- Down.