# SLAM Air Quality Monitoring Robot

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Hardware

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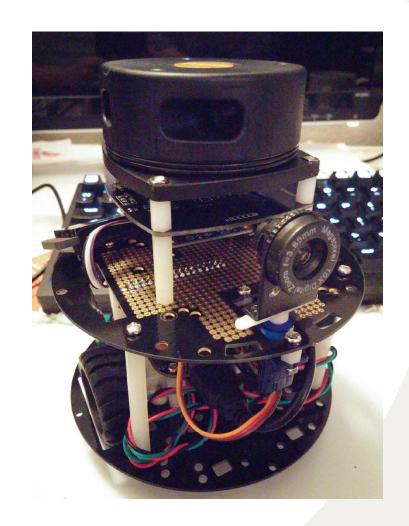
Software

#### Outline

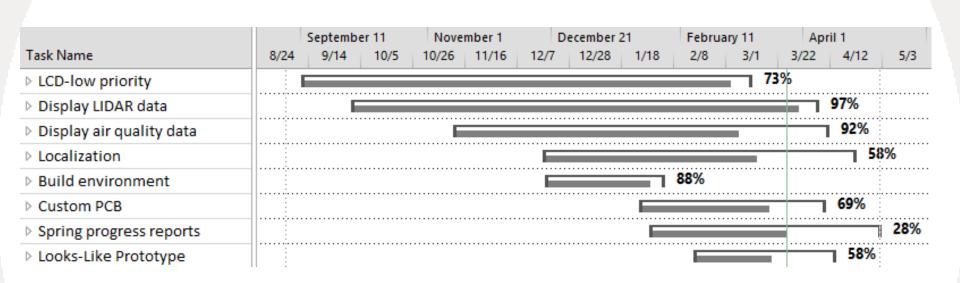
- Project Definition (Prototype)
- Schedule & Budget
- Ideal Final Product
- Looks-like prototype
- Software progress since report 2
- Hardware progress since report 2
- Remaining work

# **Project Definition**

- Simultaneous Localization and Mapping
- Knows where it is, where it is going
- Monitors and maps air quality
- Small, modular
- Only in pre-known environments



# Schedule & Budget



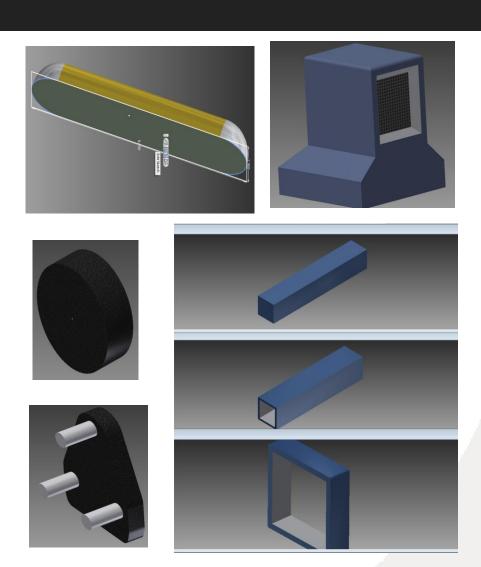
- LIDAR: \$400
- Electronics+Mechanics: \$300
- Environment: \$75
- 3D printing: \$25

### Ideal Final Product

- Map & remember new environments
- Autonomous
- Influenced by industry feedback, concerns
- Cleanroom safe
- Better/more versatile air quality sensor (\$\$\$)

# Looks-like Prototype (pictures not to scale)

- 2x1.5x2' chassis
- Extendable arm:
  readings can be taken
  <= 6.5' off the ground</li>
- Flashing alert light: yellow (580nm)
- LIDAR unit
- Charging interface at front



#### **New Software**

- Calculate heading from magnetometer
  - Hard+Soft Iron, Magnetic Declination
- Calculate estimated position
  - IMU, optical encoders, speed control
- Built web interface with map and data displays
- Display robot position, and LIDAR readings

## Web Interface

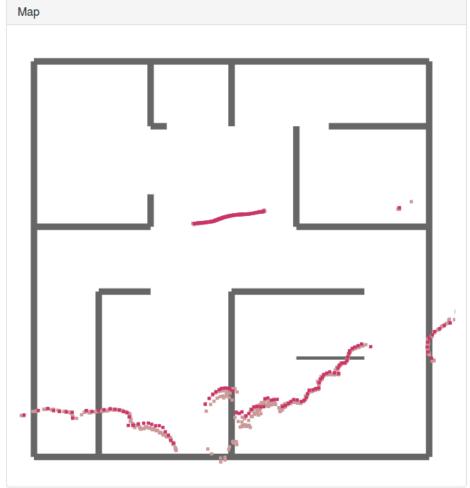
#### SLAMAQBot v0.0.1

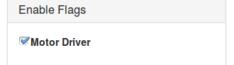
Load: 1.64 | CPU: 82.6 % | RAM: 30.5 MB | Lag: 1.3 ms



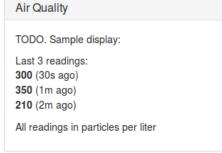
Overall Speed/Direction			
	Speed	Direction	
Desired	0	0	
Actual	0	0	

Motor Speeds			
	Left	Right	
Desired	0	0	
Actual	0	0	





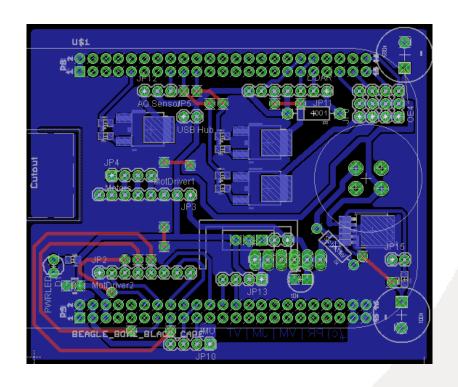




### **New Hardware**

- Built test environment
- Replace IR sensor with LIDAR
- AQ sensor
- Custom PCB





# Remaining Work

- Finish looks-like prototype
- Localization
- Implement custom PCB
- Troubleshooting and testing IMU
- Display AQ heat map on web interface
- Documentation

# Thank You