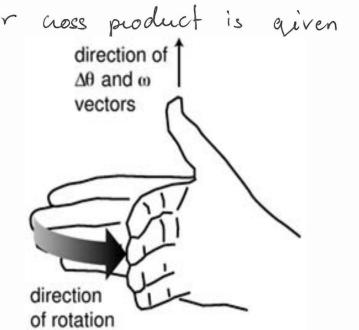
In the early 1800s, electricity meant electrostatics. "galvanism" referred to the effects produced by continuou unents from batteries; and "magnetism" dealt with the field of lodestones, compass needles, and the tenestial magnetic field. While it seemed clear to Some scientists that there must be a relationship between galvanic currents and electric charge, electricity and magnetism appeared to have nothing to do with one another. Nevertheless, as Hans Christian Gersted was lecturing on these topics to advanced students at the university of Copenhagen in the winter of 1819-1820, he tried the experiment of passing current through a wire above, and at right angles to a compas reedle. It had no effect. But after the lecture, he tried the experiment again with a wire unning parallel to the compass needle: the needle suring wide. When the current was reversed, it swung the other way!

This led Ampère, Faraday, and others to wak out a description of the magnetic action of electric current culminating in Maxwell's formulation in the early 1860s currents exert forces on each other that cannot be explained by electrostatics: parallel currents attract each other and opposite currents repel. This is the magnetic force, associated with the magnetic field. This force is empirically determed for a point charge to be: $\vec{F} = q \vec{v} \times \vec{B}$ SE units: Tesla - T T = N.S/(C.m)

with q = change of particle (including sign) $\vec{G} = \text{velocity (including direction)}$ $\vec{B} = \text{magnetic field}$

The direction of the vector by the right hand rule. $\vec{c} = \vec{a} \times \vec{b}$; $|\vec{c}| = |\vec{a}| |\vec{b}| \sin(\phi)$ The direction of \vec{c} is at a right angle to the plane famed by \vec{a} and \vec{b} . (3D)

thinking required!)



In terms of vector components, the vector product $\vec{c} = \vec{a} \times \vec{b}$ is given by:

$$c_{x} = a_{y}b_{3} - a_{3}b_{y}$$

$$c_{y} = a_{3}b_{x} - a_{x}b_{3}$$

$$c_{z} = a_{x}b_{y} - a_{y}b_{x}$$

$$\int \vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$$

$$\vec{b} = b_x \hat{i} + b_y \hat{j} + b_z \hat{k}$$

$$\vec{c} = c_x \hat{i} + c_y \hat{j} + c_z \hat{k}$$

If you are familiar with the use of determinants, You can use the expression:

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_{x} & a_{y} & a_{z} \\ b_{x} & b_{y} & b_{z} \end{vmatrix}$$

Think 10.1. A charged particle is initially moving with velocity or in a magnetic field pointing in the y direction. What is the subsequent motion of

the particle?

- A) It slows down
- B) It moves at constant speed in a circle in the x-3 plane
- c) It curves at constar speed until it travels along the field
- D) It just travels in a straight line at cst speed.

Motion of a charged particle in a uniform field.

If the speed umains constant, $|\vec{F}| = |\vec{q}\vec{v} \times \vec{B}|$ also remains constant. Since $|\vec{F}|$ is constant and always perpendicular to \vec{v} , the motion is circular.

electron OB

Note: the electrostatic force can do work: W=- \int F. dl = 9 DV but the magnetic force cannot because it is always perpen-

diwlar to the motion of the changes:

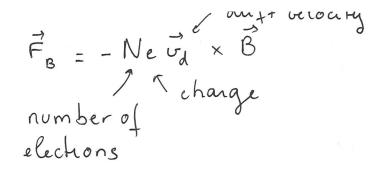
 $W_{m} = -\int_{a}^{b} \vec{F} \cdot d\vec{l} = -q \int_{a}^{b} (\vec{J} \times \vec{B}) \cdot \vec{J} dt = 0$

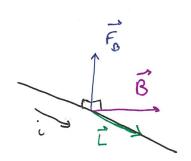
The orbital radius can easily be found:

 $ma = m \frac{v^2}{r}$ for a circular orbit

we know $F_0 = |q| \cup B$, therefore, $r = \frac{m v}{|q| B}$

If now we have a large number of changes dufting in the same direction (i.e., a current), each change experiences a maquetic force. Since changes can't leave the side of the wire, they transfer the force to it





The number of elections can be written as N=nAL where n is the electron density. Substituting - nALe of as iI, we get:

Fo = iL × B for a straight wire in est field

For any wire in a nonuniform fuld,

Example: A long rigid conductor, lying along the direction 2î + 2j, carrying a current i passes through a region of field $\vec{B} = (3 \text{ mT})\hat{i} + x(5 \text{ mT/m})\hat{j}$ Calculate the force on the I'm segment that lies between x = 0 and x = 0.7 m.

$$\vec{F} = \int i d\vec{l} \times \vec{B} = \int i (dx \vec{i} + dy \vec{j}) \times (3\vec{i} + 5x\vec{j})$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ dx & dy & 0 \\ 3 & 5x & 0 \end{vmatrix} = \hat{k} \left(5x \, dx - 3 \, dy \right) \quad \text{and} \quad dx = dy$$

$$\vec{F} = \hat{k} \int_{0}^{0.7} (5x - 3) \, dx$$

Think 10.2: A rectangular loop of wire carries a current I in a plane perpendicular to a magnetic field. What is the net force on the whole wire loop? (B' into the page)

- A) zero
- D) Into the page
- B) Up
- E) Out of the page
- C) Down
- F) left 6) Right

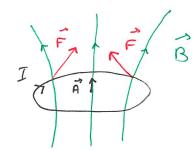
Force on a loop of current.

If the field is uniform then the net force on the entire loop is zero.

If the field diverges then there is a net force along the direction of divergence.

$$\vec{F} = \vec{\nabla} (\vec{\mu} \cdot \vec{B})$$
 with $\vec{\mu} = \vec{I} \vec{A}$

magnetic moment



A uniform magnetic field will exert a torque on a coil that has Nloops and carries a current i. Defining is as the vector associated with the coil

 $\vec{z} = \vec{\mu} \times \vec{B}$ $\vec{\mu} = Ni\vec{A}$

. The maquitude of the magnetic dipole moment is m = NiA

. Its direction is perpendicular to the plane of the coil as given by the right-hand rule.

. The potential energy of the coil is

- · U = µB cos0 has a minimum value of µB for 0 = 0 (position of stable equilibrium)
- . V has a maximum value of + µB for 0 = 180° (position of unstable equilibrium)
- . The Lorque is in a direction to align the dipole with the field.

Consider elections flowing to give current i and duft velocity \vec{v}_d in a strip of conductor in a \vec{B} -field.

A maquetic force will act on the electrons, pushing them to one side of the strip. Electrons will collect on that side until an electric field builds up to oppose the collection

$$\vec{F}_{mag} + \vec{F}_{e} = 0$$

$$= q\vec{v}_{a} \times \vec{B} + q\vec{E}_{4}$$

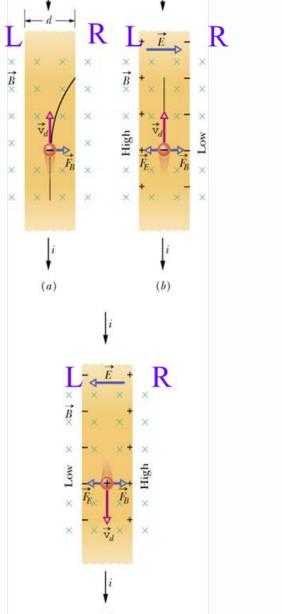
E4 = VdB => DV4 = WEH

and, using $U_d = \frac{J}{ne}$ charge $n = \frac{iB}{et} + \frac{J}{magnetic}$ field

charge thickness difference

election

charge



Just like electrostatic descends from Coulomb's law, maque tostatics derives from the empirical law of Biot-Savant.

For a uniform (constant velocity) motion of a point charge, the field is given by:

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \vec{r}}{r^3} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \hat{r}}{r^2}$$

 \vec{v} = velocity of point charge

· ? = position vector of field point P, relative to the location of the charge. Points from q to P.

. Î = unit vector along P.

$$B = \frac{\mu_0}{4\pi} \frac{|q| \, \sigma |\sin \theta|}{r^2} \quad \text{with } \theta \quad \text{angle between } \vec{\sigma}$$
 and \vec{r} .

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \hat{r}}{r^2} ; \vec{F} = q\vec{v} \times \vec{B}$$

- · Field dependent on change moving.
- · Field perpendicular to velocity of charge and line between change location & point of observation.
- . Field lines form closed circles.

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q\hat{r}}{r^2} ; \vec{F} = q\vec{E}$$

- · Field independent of change motion. Only needs change.
- . Field along line between change and point of observat
- . Field lines radially outward for positive changes, inward for negative changes.

