

hypercubic
lattice:
 $|\vec{e}| = a$

$$\sum_{\vec{e}} e^{i\vec{k} \cdot \vec{e}} = \sum_{j=1}^d (e^{i k_j a} + e^{-i k_j a}) = 2 \sum_{j=1}^d \cos(k_j a)$$

$$\approx 2 \sum_{j=1}^d \left(1 - \frac{k_j^2 a^2}{2}\right) = \underbrace{2d}_q - a^2 k^2$$

$$k^2 = \sum_{j=1}^d k_j^2$$

$$\tilde{\chi}(\vec{k}) = \frac{\beta}{1 - \beta J(q - a^2 k^2)} = \frac{\beta}{1 - \beta J q + \beta J a^2 k^2}$$

$$T > T_c \quad 1 - \beta J q = 1 - \frac{J q}{k_B T} > 0 \quad T_c = \frac{J q}{k_B}$$

$$\tilde{\chi}(\vec{k}) = \frac{1}{k(T - T_c) + J a^2 k^2} = \frac{1}{J a^2} \frac{1}{\frac{k(T - T_c)}{J a^2} + k^2}$$

$$S(\vec{k}) = \tilde{G}(\vec{k}) = \sum_{\vec{r}} G(\vec{r}) e^{-i\vec{k} \cdot \vec{r}} \quad \text{structure factor}$$

structure factor

$$\tilde{G}(\vec{k}) = k_B T \tilde{\chi}(\vec{k}) = \frac{k_B T}{J a^2} \frac{1}{k^2 + \xi^{-2}}$$

$$\xi = \sqrt{\frac{J a^2}{k(T - T_c)}}$$

$$G(\vec{r}) = \frac{1}{N} \sum_{\vec{k}} \tilde{G}(\vec{k}) e^{i\vec{k} \cdot \vec{r}} = \frac{1}{N} \frac{N a^d}{(2\pi)^d} \int e^{i\vec{k} \cdot \vec{r}} \tilde{G}(\vec{k}) d^d k$$

$$= a^d \left(\frac{k_B T}{J a^2}\right) \underbrace{\frac{1}{(2\pi)^d} \int d^d k e^{i\vec{k} \cdot \vec{r}} \frac{1}{k^2 + \xi^{-2}}}_{\text{lattice constant.}}$$

$$\frac{1}{(2\pi)^d} \frac{1}{(\tau \xi)^{\frac{d-2}{2}}} K_{\frac{d-2}{2}}(\tau/\xi)$$

$r \gg \xi$:

$$G(r) \sim \frac{1}{r^{\frac{d-1}{2}}} e^{-r/\xi}$$

correlation length
exponential decay

$T \rightarrow T_c + 0$

$$\tilde{G}(\vec{k}) \sim \frac{1}{k^2}$$

$$G(r) \sim \frac{1}{r^{d-2}}$$

power law

critical exponents: $\xi \sim |T - T_c|^{-\nu}$

$$\boxed{\nu = 1/2}$$

mean-field values

$$\downarrow$$

$$\boxed{\gamma = 0}$$

$$\tilde{G}(\vec{k}) \sim \frac{1}{k^{2-\gamma}}$$

$$\text{and } G(r) \sim \frac{1}{r^{d-2+\gamma}}$$

definition
of the exponent
 γ :

Review of inhomogeneous mean-field results:

$$G(i,j) = \langle s_i s_j \rangle - \langle s_i \rangle \langle s_j \rangle \quad (\text{two-point correlation function})$$

$$r \equiv |i-j|$$

$$G(i,j) = G(r)$$

translational invariance +
isotropic structures

$$\tilde{G}(\vec{k}) = \sum_{\vec{r}} G(\vec{r}) e^{-i\vec{k} \cdot \vec{r}}$$

inhomogeneous mean-field (from Ising model)

$$\tilde{G}(\vec{k}) = \frac{\text{const.}}{k^2 + \xi^{-2}}$$

$$\xi \sim \frac{1}{|t|^{1/2}} = |t|^{-\nu}$$

correlation length

$$\boxed{\nu = 1/2}$$

$$\chi_T = \frac{1}{k_B T} \sum_{\vec{r}} G(\vec{r}) = \frac{1}{k_B T} \lim_{\vec{k} \rightarrow 0} \tilde{G}(\vec{k}) = \text{const.} \xi^2 \sim |t|^{-2\nu}$$

(susceptibility sum rule)

$$\chi_T \sim |t|^{-\gamma}$$

\Rightarrow

$$\boxed{\gamma = 2\nu = 1}$$

real-space correlations:

$$G(r) = \frac{1}{N} \sum_{\vec{k}} \tilde{G}(\vec{k}) e^{i\vec{k} \cdot \vec{r}} \approx \text{const.} \int \frac{d^d k}{(2\pi)^d} \frac{e^{i\vec{k} \cdot \vec{r}}}{k^2 + \xi^{-2}}$$

$$= \text{const.} \frac{1}{(2\pi)^{d/2}} \frac{1}{(\xi \xi)^{\frac{d-2}{2}}} \cdot K_{\frac{d-2}{2}}\left(\frac{r}{\xi}\right)$$

modified Bessel function

asymptotic behavior of modified Bessel function:

$$K_\nu(x) \approx \begin{cases} \frac{\Gamma(\nu)}{2} \left(\frac{2}{x}\right)^\nu & x \ll 1 \quad (\nu \neq 0) \\ \sqrt{\frac{\pi}{2x}} e^{-x} & x \gg 1 \end{cases}$$

Thus, when $T \neq T_c$, ξ = finite, and

$T \neq T_c$

$$G(r) \approx \text{const.} \frac{1}{\xi^{\frac{d-2}{2}}} \frac{1}{r^{\frac{d-1}{2}}} e^{-\frac{r}{\xi}}$$

$r \gg \xi$

~ exponential (fast) decay
(weakly interacting subsystems)

$T \rightarrow T_c$
($\xi \rightarrow \infty$)

$$G(r) \approx \text{const.} \frac{1}{r^{d-2}}$$

correlations decay "much slower" (in a power law fashion)

at the critical point. The system then

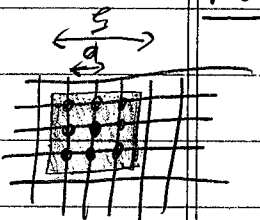
consists of many strongly interacting components.

Central-limit theorem, etc., is expected to break down

Role of fluctuations: the breakdown of the mean-field approximation
(Ginzburg criterion)

$$m_g = \frac{1}{N_g} \sum_{i \in I_g} s_i$$

$$\langle m_g \rangle = \langle s_i \rangle = m$$



correlation volume:

$$V_g = \xi^d \quad [T \sim T_c]$$

$$\langle (\Delta m)^2 \rangle = \frac{1}{N_g^2} \sum_{i,j \in I_g} (s_i - m)(s_j - m) = \frac{1}{N_g^2} \sum_{i,j \in I_g} G(i,j) \approx \frac{1}{N_g} \sum_i G(i,i)$$

$$N_g = \left(\frac{\xi}{a}\right)^d$$

$$\frac{\langle (\Delta m)^2 \rangle}{\langle m_g \rangle^2} = \frac{\frac{1}{N_g} \sum_i G(i,i)}{m^2} = \frac{\sum_i G(i,i)}{N_g m^2} \sim \frac{k_B T \chi_T}{\left(\frac{\xi}{a}\right)^d m^2} = d^d k_B T \frac{\chi_T}{\xi^d m^2}$$

$$\sim \frac{|t|^{-\alpha}}{|t|^{-\nu d} |t|^{2\beta}} = |t|^{-\alpha - 2\beta + \nu d} \quad \xrightarrow{T \rightarrow T_c} \begin{cases} \infty & \nu d - \alpha - 2\beta < 0 \\ \text{finite} & \nu d - \alpha - 2\beta > 0 \end{cases}$$

thus, fluctuations are small in a self-consistent fashion only if $\nu d - \alpha - 2\beta > 0$

-2-

$$\Rightarrow \boxed{d > \frac{2\beta + \alpha}{\nu}} = d_c \text{ (upper critical dimension) } \text{ Ising: } \boxed{d_c = 4}$$

Ginzburg criterion tells us that mean-field behavior (and exponents) will be asymptotically exact for $d > d_c$
 for Ising model $d_c = 4$.
 What about $d = 1, 2, 3$? Is there a phase transition at all?

London - Peierls arguments

$$H=0 \quad \mathcal{H} = -J \sum_{\langle i,j \rangle} s_i s_j \quad J > 0 \quad (\text{ferromagnetic})$$

$d=1$ ground-state ($T=0$) $\dots \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow \dots \quad E_0 = -(N-1)J$
 (or, equivalently, $\dots \downarrow \downarrow \downarrow \downarrow \downarrow \dots$)

consider an open-end system:

$T \geq 0$ lowest energy configuration: (single domain wall)
 $\dots \uparrow \uparrow \uparrow \uparrow \uparrow \downarrow \downarrow \downarrow \downarrow \downarrow \dots$

$N-1$ possible locations of the domain wall

$$F = E - TS$$

$$\Delta S = k_B \ln(N-1)$$

$$\Delta F = \Delta E - T \Delta S = 2J - T k_B \ln(N-1) < 0 \quad \text{for sufficiently large } N$$

$N \rightarrow \infty$ entropy "wins", introduction of domain wall

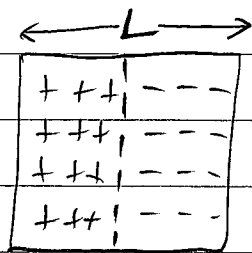
is favorable from the viewpoint of minimizing the free energy

Thus, for $T \geq 0$, fluctuation will destroy the long-range order

$$T > 0 \Rightarrow m = 0$$

There can be no phase transition in the $d=1$ Ising model

$d=2$



$$N = L^2$$

$$(L = \sqrt{N})$$

$$T=0: F_{GS} = E_{GS}$$

$$F_{DW} - F_{GS}$$



$$\Delta F = \Delta E - T \Delta S = 2JL - T k_B \ln(2L) = 2J\sqrt{N} - k_B T \ln(\sqrt{N} \cdot 2)$$

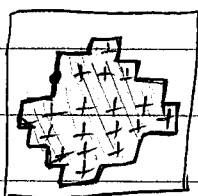
$$= 2J\sqrt{N} - k_B T \ln(2\sqrt{N}) > 0 \quad \text{for sufficiently large } N$$

(domain walls are unfavourable)

But, the above expression underestimates the entropy

Let's overestimate entropy:

Consider more complex domains with length $L \sim \sqrt{N}$



$$\Delta F = 2JL - k_B T \ln \Gamma(L)$$

↑
degeneracy of domain walls with length L

q_i
(coordination number)

$$\Gamma(L) = N \cdot q \cdot \underbrace{(q-1)(q-1) \dots (q-1)}_{L-1} \approx N (q-1)^L$$

$$\Delta F \approx 2JL - k_B T \ln(N (q-1)^L) = 2J\sqrt{N} - k_B T L \ln(q-1) - k_B T \ln(N)$$

$$= 2J\sqrt{N} - k_B T \sqrt{N} \ln(q-1) - k_B T \ln(N) \approx 2J\sqrt{N} - k_B T \sqrt{N} \ln(q-1)$$

$$\Delta F > 0 \quad \text{if} \quad (2J - k_B T \ln(q-1))\sqrt{N} > 0 \quad (\text{system prefers order})$$

$$\text{i.e., } 2J - k_B T \ln(q-1) > 0$$

$$\boxed{T < \frac{2J}{k_B \ln(q-1)} = T_c}$$

phase transition is possible
for $T > T_c$

Landau Theory

$$\tilde{f}(T, H, m) = \frac{1}{2} J q m^2 - k_B T \ln(2) - k_B T \ln \cosh[\beta (J q m + H)]$$

\vdots (see earlier notes and HW)

$$\tilde{f}(T, H, m) \approx a(T) + \frac{1}{2} b(T) m^2 + \frac{1}{4} c(T) m^4 - m H$$

provided that $c(T)$ does not change sign, and $b(T) \propto b_0 (T - T_c)$, the above "free-energy" functional describes a continuous (second-order) phase transition at $T = T_c$.

Note: $\tilde{f}(T, H, m)$ is not the free energy.

The free-energy would be: $f(T, H) = \min_m \{ \tilde{f}(T, H, m) \}$

$$\left. \begin{array}{l} \frac{\partial \tilde{f}}{\partial m} = 0 \\ \frac{\partial^2 \tilde{f}}{\partial m^2} > 0 \end{array} \right\} \Rightarrow m(T, H) \quad f(T, H) = \tilde{f}(T, H, m(T, H))$$

↑ equilibrium magnetization

Landau Theory:

$$\mathcal{L}(T, H, m) = a(T) + \frac{1}{2} b(T) m^2 + \frac{1}{4} c(T) m^4 - m H \quad \mathcal{L} = \mathcal{L} \cdot V$$

$$(H=0) \quad \frac{\partial \mathcal{L}}{\partial m} = b(T) m + c(T) m^3 = 0 \quad \begin{array}{l} b(T) \approx b_0 (T - T_c) \\ c(T) \approx c_0 \end{array}$$

$$b_0 (T - T_c) m + c_0 m^3 = 0$$

$\mathcal{L}(m) \downarrow$

$T > T_c$

$$m = 0$$

$\mathcal{L}(m) \uparrow$

$T < T_c$

$$m = \pm \sqrt{\frac{b_0 (T_c - T)}{c_0}}$$

(spontaneous magnetization)
 $\Rightarrow \beta = 1/2$

inhomogeneous systems ($H \rightarrow h(\vec{r})$)

$\langle s_i \rangle = m_i \rightarrow \varphi(\vec{r})$ (local order parameter)

Coarse-grained description

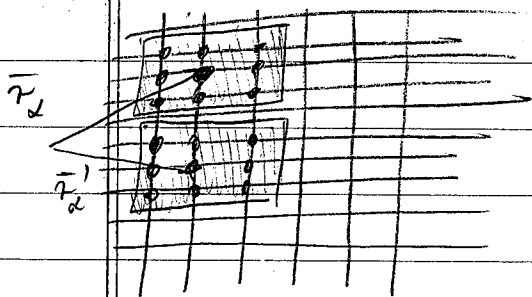
$$L = \int d(T, H; \{\varphi(\vec{r})\}) d^d r$$

$$\mathcal{L} = \frac{1}{2} (\nabla \varphi)^2 + \frac{1}{2} a \cdot t \varphi^2(\vec{r}) + \frac{b}{4} \varphi^4(\vec{r}) - h(\vec{r}) \varphi(\vec{r})$$

↑ coming from domain wall energy

for Ising
($a \cdot \frac{T - T_c}{T_c} = a \cdot t$)

$$\sim [\varphi(\vec{r}) - \varphi(\vec{r} + \vec{e})]^2 \rightarrow (\nabla \varphi)^2$$



$$\vec{r}'_d = \vec{r}_d + \vec{e}$$

$$l = |\vec{e}|$$

$$a \ll l \ll \xi(T)$$

$$\varphi(\vec{r}_d) = \frac{1}{N_d} \sum_{i \in I_d} s_i$$

$$-1 \leq \varphi(\vec{r}_d) \leq 1$$

$\varphi(\vec{r})$ is a slowly varying function of the lattice position \vec{r}_d

continuum limit : $l = \text{fixed}$

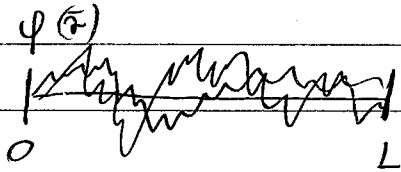
$$\left. \begin{array}{l} a \rightarrow 0 \\ N \rightarrow \infty \end{array} \right\} a^d N = V = \text{const}$$

$\varphi(\vec{r}_d) \rightarrow \varphi(\vec{r})$ continuous, local order parameter

$$\begin{aligned} Z &= \text{Tr}_{\{s\}} e^{-\beta \mathcal{H}[\{s\}]} = \sum_{\{\varphi(\vec{r})\}} \sum_{\{s\}} \delta(\varphi(\vec{r}) - \frac{1}{N_d} \sum_{i \in I_d} s_i) e^{-\beta \mathcal{H}[\{s\}]} \\ &\equiv \sum_{\{\varphi(\vec{r})\}} e^{-\beta L[\{\varphi(\vec{r})\}]} \end{aligned}$$

$$e^{-\beta L[\{\varphi\}]} = \sum_{\{s_i\}} \delta\left(\varphi(\vec{r}) - \frac{1}{N_d} \sum_{i \in \mathcal{V}} s_i\right) e^{-\beta \mathcal{H}[\{s_i\}]}$$

L is a "constrained" free energy when the order parameter profile is constrained to $\varphi(\vec{r})$



$$Z = \sum_{\{\varphi(\vec{r})\}} e^{-\beta L[\{\varphi(\vec{r})\}]}$$

↑ integration over all possible order parameter profiles
(functional integral)

$$\Rightarrow Z = \int \mathcal{D}\varphi(\vec{r}) e^{-\beta L[\{\varphi(\vec{r})\}]}$$

$$L = \int d^d r \mathcal{L}(\{\varphi(\vec{r})\}), \quad \mathcal{L} = \frac{c}{2} (\nabla \varphi)^2 + \frac{a}{2} \varphi(\vec{r})^2 + \frac{b}{4} \varphi(\vec{r})^4 - h(\vec{r}) \varphi(\vec{r})$$

evaluation, e.g., by direct discretization:

$$\begin{aligned} a &> 0 \\ b &> 0 \\ c &> 0 \end{aligned}$$

$$\int \mathcal{D}\varphi = \int \prod_{i=1}^N d\varphi_i$$

$$\langle \varphi(\vec{r}) \rangle = \frac{1}{Z} \int \mathcal{D}\varphi \varphi(\vec{r}) e^{-\beta L} = \frac{1}{\beta} \frac{1}{Z} \frac{\delta Z}{\delta h(\vec{r})}$$

$$\langle \varphi(\vec{r}) \varphi(\vec{r}') \rangle = \frac{1}{Z} \int \mathcal{D}\varphi \varphi(\vec{r}) \varphi(\vec{r}') e^{-\beta L} = \frac{1}{\beta^2} \frac{1}{Z} \frac{\delta^2 Z}{\delta h(\vec{r}) \delta h(\vec{r}')}$$

↑
thermodynamic averages $\langle \dots \rangle$