



Universitat
Pompeu Fabra
Barcelona



UNIVERSITAT POLITÈCNICA
DE CATALUNYA
BARCELONATECH

High-dimensional variable selection and external information

Paul Rognon-Vael

David Rossell

Piotr Zwiernik

Variable selection in high dimension

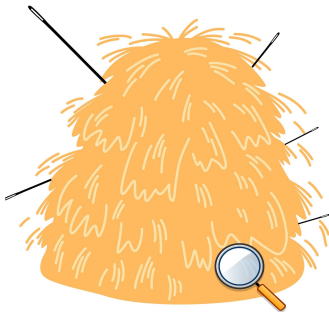
$$y = \mathbf{x}\beta^* + \epsilon$$

with $\epsilon \sim N(\mathbf{0}_n, \sigma^2 \mathbb{I})$, $\mathbf{X} \in \mathbb{R}^{n \times p}$

wlog set $\sigma = 1$

Find: $S := \{i \text{ s.t. } \beta_i^* \neq 0\}$

with size $|S| = s$ unknown



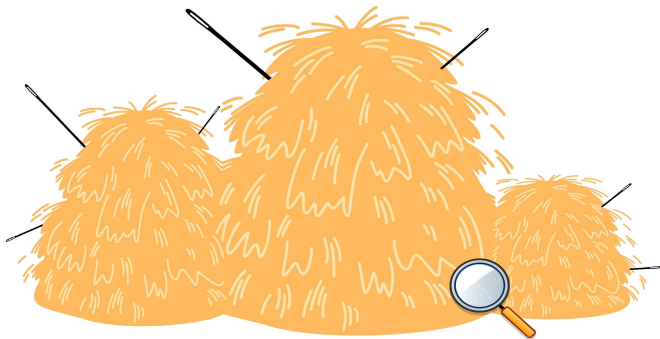
High-dimension ($n < p$): **sparsity imposed** with for example L_0 **penalization** (Bayesian variable selection, BIC...). We select a subset of variables /model:

$$\hat{S} := \arg \min_{\text{models } M} \|\mathbf{y} - \mathbf{x}_M \hat{\beta}_M\|_2^2 + \kappa |M|$$

External information

In many cases, there is **external information on varying sparsity across β^*** :

$$\beta^* = (\underbrace{\beta_1^*, \dots, \beta_{|B_1|}^*}_{\text{Block 1 less sparse}}, \underbrace{\beta_{|B_1|+1}^*, \dots, \beta_{|B_1|+|B_2|}^*}_{\text{Block 2 more sparse}}, \dots)$$



External information

Some cases:

- data integration: e.g. functional annotations on genes, past experiments
- expert knowledge
- meta data on variables

Example in multi-omics:

Type of variable	Clinical	Copy-number variation	miRNA	Mutation	mRNA
Average number	9	57,927	784	15,682	22,980

Table: Average number of variables by block type in 15 multi-omics datasets from The Cancer Genome Atlas [4] analyzed in [1]

Block informed selection

Idea: Assume a **given partition in blocks** B_1, \dots, B_b . B_j has size p_j and s_j active $\beta_i^* \neq 0$.
Let **penalty κ vary by block**.

$$\hat{S}^b := \arg \min_{\text{models } M} \|\mathbf{y} - \mathbf{X}_M \hat{\beta}_M\|_2^2 + \sum_{j=1}^b \kappa_j |M_j|$$

where $M_j = M \cap B_j$

Many examples of improved inference in **applications**. But **theory?**

- How much can we earn?
- Can we lose?
- How to set penalties?

Milder conditions for variable selection consistency

Variable selection consistency with \hat{S}

Assume:

$$(A1) \quad \kappa \gtrsim \ln(p - s)$$

$$(A2) \quad \sqrt{n\rho(\mathbf{X})}\beta_{\min}^* \gtrsim \sqrt{\kappa} + \sqrt{\ln(s)}$$

then $P(\hat{S} = S) \rightarrow 1$ as $n, p \rightarrow +\infty$

Variable selection consistency with \hat{S}^b

Assume:

$$(A3) \quad \kappa_j \gtrsim \ln(p_j - s_j) \quad \forall j$$

$$(A4) \quad \sqrt{n\rho(\mathbf{X})}\beta_{\min,j}^* \gtrsim \sqrt{\kappa_j} + \sqrt{\ln(s_j)} \quad \forall j$$

then $P(\hat{S}^b = S) \rightarrow 1$ as $n, p \rightarrow +\infty$

\hat{S}^b can be variable selection consistent when \hat{S} is not.

$\rho(\mathbf{X})$ depends on the correlation between variables in S and outside.

Smallest recoverable signals

Standard - \hat{S} :

$$\beta_{\min}^* = O\left(\sqrt{\frac{2 \ln(p-s)}{n}} + \sqrt{\frac{2 \ln(s)}{n}}\right)$$

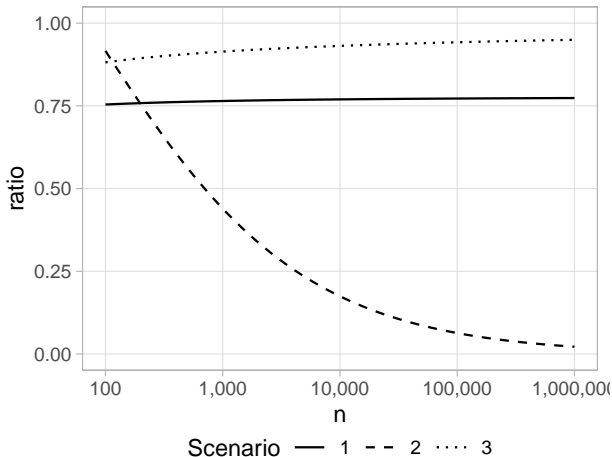
Block informed - \hat{S}^b :

in each block B_j ,

$$\beta_{\min,j}^* := O\left(\sqrt{\frac{2 \ln(p_j - s_j)}{n}} + \sqrt{\frac{2 \ln(s_j)}{n}}\right)$$

Scenario	1	2	3
$p - s$	$\frac{3}{2}n$	$e^{n/10}$	n
$p_j - s_j$	\sqrt{n}	n^2	$n/2$

Ratio of recoverable signal block/standard



Convergence rate at the oracle (optimizing rate)

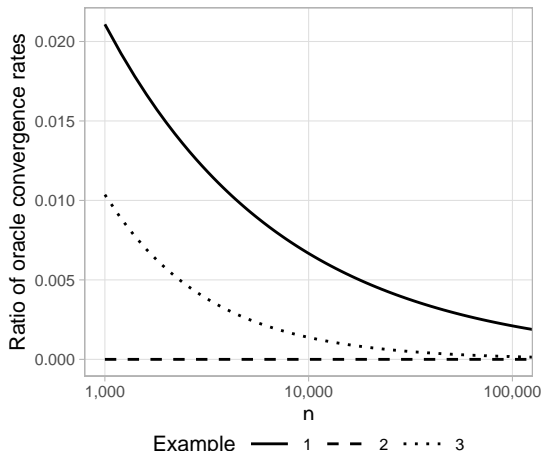
Standard oracle penalty - \hat{S} :

$$\kappa^{OR} \approx \frac{\ln(p/s - 1)}{\sqrt{n\rho(\mathbf{X})}\beta_{\min}^*} + \sqrt{n\rho(\mathbf{X})}\beta_{\min}^*$$

Block informed oracle penalty - \hat{S}^b :

$$\forall j \kappa_j^{OR} \approx \frac{\ln(p_j/s_j - 1)}{\sqrt{n\rho(\mathbf{X})}\beta_{\min,j}^*} + \sqrt{n\rho(\mathbf{X})}\beta_{\min,j}^*$$

Ratio of prob. error block/standard



How to set block penalties? An estimator of sparsity

For any model M ,

$$NC(M) = \frac{e^{-\|\mathbf{y} - \mathbf{x}_M \hat{\beta}_M\|_2^2 - \sum_{j=1}^b \kappa_j |M_j|}}{\sum_L e^{-\|\mathbf{y} - \mathbf{x}_L \hat{\beta}_L\|_2^2 - \sum_{j=1}^b \kappa_j |L_j|}}$$

is a **posterior probability** for model M from a Bayesian perspective (BIC Schwarz [3]).

An **estimator of sparsity** is:

$$\hat{s}_j := \sum_{i \in B_j} \sum_M NC(M) \mathcal{I}(i \in M) \quad \left(\approx \sum_{i \in B_j} P(\beta_i \neq 0 | \mathbf{y}) \right)$$

Two nice properties:

- If A3 and A4 hold, \hat{s}_j/p_j **consistent**. If A3 only holds, $\hat{s}_j/p_j \leq s_j/p_j$ as $n \rightarrow +\infty$.
- \hat{s}_j/p_j matches the **empirical Bayes** estimate of the prior inclusion probability in B_j

Two-stage proposal - Empirical Bayes

Algorithm:

- 1 Set $\kappa_j = \kappa^\circ = \ln(p) + \frac{1}{2} \ln(n)$ for $j = 1, \dots, b$. Compute \hat{s}_j/p_j for $j = 1, \dots, b$.
- 2 Select the model:

$$\hat{S}^{EB,b} := \arg \min_M \|\mathbf{y} - \mathbf{X}_M \hat{\boldsymbol{\beta}}_M\|_2^2 + \sum_{j=1}^b \kappa_j |M_j| \quad \text{where} \quad \forall j \quad \kappa_j = \ln(p_j/\hat{s}_j - 1) + \frac{1}{2} \ln(n)$$

Setting $\kappa_j = \ln(p_j/\hat{s}_j - 1) + \frac{1}{2} \ln(n)$ is essentially setting prior inclusion probabilities for variables in B_j by empirical Bayes.

Two-stage proposal - Empirical Bayes

Properties of the algorithm:

■ $P(\hat{S}^{EB,b} \subseteq S) \rightarrow 1$ as $n, p \rightarrow \infty$ (no betamin assumption)

■ If the following betamin condition holds:

$$(A5) \quad \sqrt{n\rho(\mathbf{X})}\beta_{\min,j}^* \gtrsim \sqrt{\ln(p_j/s_j^L - 1) + \frac{1}{2}\ln(n)} + \sqrt{\ln(s_j)} \quad \forall j$$

where $s_j^L := \#\{\beta_i^* \in B_j | \sqrt{n\rho(\mathbf{X})}\beta_i^* \gtrsim \sqrt{\kappa^o} + \sqrt{\ln(s_j)}\}$

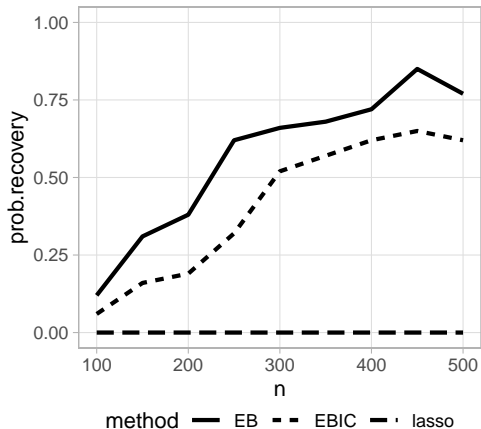
then:

$$P(\hat{S}^{EB,b} = S) \rightarrow 1 \quad \text{as } n, p \rightarrow \infty$$

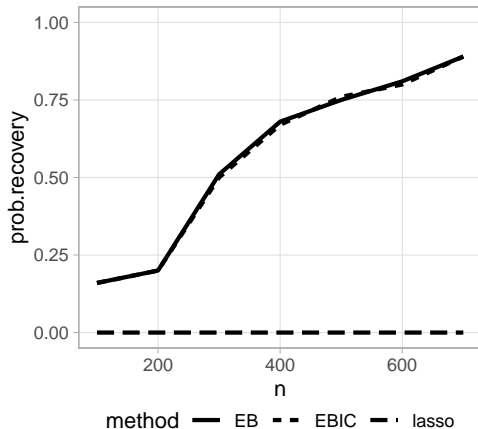
A5 is essentially A4 for penalty $\kappa_j = \ln(p_j/s_j - 1) + \frac{1}{2}\ln(n)$, but slightly stricter. The difference depends on how many signals are missed in step 1.

Simulations

Scenario 1



Scenario 3







Takeaways

We provide **theoretical guarantees** and a **practical method** for the incorporation of external information / data in selection procedure. In doing so, you can:

- 1 tailor the procedure to varying sparsity constraints informed by external data
- 2 recover smaller signals
- 3 get better selection results without increasing the sample size (faster convergence)
- 4 the more discriminative is the external information / data the better.

References I

-  **Yingxia Li, Ulrich Mansmann, Shangming Du, and Roman Hornung.** Benchmark study of feature selection strategies for multi-omics data. *BMC Bioinformatics*, 23(1):412, October 2022.
-  **Omiros Papaspiliopoulos and David Rossell.** Bayesian block-diagonal variable selection and model averaging. *Biometrika*, 104(2):343–359, 04 2017.
-  **Gideon Schwarz.** Estimating the Dimension of a Model. *The Annals of Statistics*, 6(2):461 – 464, 1978.
-  **Katarzyna Tomczak, Patrycja Czerwińska, and Maciej Wiznerowicz.** Review of the cancer genome atlas (tcga): an immeasurable source of knowledge. *Contemporary Oncology/Współczesna Onkologia*, pages 68–77, 2015.

Convergence rates at the oracle

Assume the **penalties are set at their oracle values** κ^{OR} and κ_j^{OR} .

With **standard** $L_0(\hat{S})$, the **oracle convergence rate** is:

$$OR := 24 c e^{-\frac{1}{2} \left[\frac{n\rho(\Sigma)}{32} \beta_{\min}^{\star 2} - \max\{\ln(p-s), \ln(s)\} \right]}$$

With **block informed** $L_0(\hat{S}^b)$, the **oracle convergence rate** is:

$$OR^b := 12(2^{2b} - 2b) c' \sum_{j=1}^b e^{-\frac{1}{2} \left[\frac{n\rho(\Sigma)}{32} \beta_{\min, j}^{\star 2} - \max\{\ln(p_j - s_j), \ln(s_j)\} \right]}$$

Ratio of bounds on convergence rates at the oracle penalties:

$$\frac{OR^b}{OR} \sim (2^{2b-1} - b) \sum_{j=1}^b e^{-\frac{1}{2} \left[\frac{n\rho(\Sigma)}{24} (\beta_{\min, j}^{\star 2} - \beta_{\min}^{\star 2}) \right]} e^{-\frac{1}{2} [\max\{\ln(p-s), \ln(s)\} - \max\{\ln(p_j - s_j), \ln(s_j)\}]}$$

Necessary conditions in correlated settings

Theorem

- a) If for some $j = 1, \dots, b$, $\lim_{n \rightarrow \infty} \frac{\kappa_j}{\underline{\lambda}_j^2 \ln(p_j - s_j)} < 1$, where $\underline{\lambda}_j$ depends on the correlation of $\mathbf{X}_{B_j \setminus S_j}$, then $P(\hat{S}^b = S) \not\rightarrow 1$ as $n, p \rightarrow \infty$.
- b) If for some $j \in \{1, \dots, b\}$, $\sqrt{n\bar{\lambda}}\beta_{\min,j}^* = o(\sqrt{\kappa_j})$, where $\bar{\lambda} := \lambda_{\max}\left(\frac{1}{n}\mathbf{X}_S^\top \mathbf{X}_S\right)$, then $P(\hat{S}^b = S) \not\rightarrow 1$ as $n, p \rightarrow \infty$.
- c) If for some $j \in \{1, \dots, b\}$, $\sqrt{n\bar{\lambda}}\beta_{\min,j}^* = o\left(\underline{\lambda}_j \sqrt{\ln(p_j - s_j)}\right)$, then $P(\hat{S}^b = S) \not\rightarrow 1$ as $n, p \rightarrow \infty$.

Properties of \hat{s}/p

For a fixed set of penalties κ_j , denote:

$$s_j^S := \left\{ \beta_i^* \in s_j \mid \sqrt{n\bar{\lambda}}|\beta_i^*| = o(\sqrt{\kappa_j}) \right\}$$
$$s_j^L := \left\{ \beta_i^* \in s_j \mid \sqrt{\frac{n\rho(\mathbf{X})}{8}}|\beta_i^*| - \sqrt{\kappa_j} = \sqrt{\ln(s_j)} + c_j \right\}$$

Assume $\kappa_j \gtrsim \ln(p_j - s_j)$ and $|s_j^S| = O(p_j - s_j)$ for every $j = 1, \dots, b$, then :

$$\frac{|s_j^L|}{p_j} \leq \lim_{n,p \rightarrow \infty} \mathbb{E} \left(\frac{\hat{s}_j}{p_j} \right) \leq \frac{s_j - |s_j^S|}{p_j} \quad \text{for all } j = 1, \dots, b$$

Bayesian interpretation of L_0 penalties

Let model M be a p -dimensional vector of variable inclusion indicators $m_i = I(\beta_i \neq 0)$. Consider the joint prior on parameters and models is:

$$p(\beta, M \mid \theta) = p(\beta \mid M)p(M \mid \theta)$$

Posterior model probabilities are:

$$p(M \mid \mathbf{y}, \theta) \propto p(\mathbf{y} \mid M)p(M \mid \theta) \quad \text{where} \quad p(\mathbf{y} \mid M) \approx p(\mathbf{y} \mid \tilde{\beta}^{(M)})n^{-|M|/2} \text{ ([3])}$$

and:

$$\ln p(M \mid \mathbf{y}) \approx -\|\mathbf{y} - \mathbf{X}_M \hat{\beta}_M\|_2^2 - \frac{1}{2} \ln(n)|M| + \ln p(M \mid \theta) + \text{cst}$$

Assume independent inclusion variable, and inclusion probabilities constant by block:

$$p(M \mid \theta) = \prod_{i=1}^p \text{Bern}(m_i; \theta_i) I(M \in \mathcal{M}) \text{ and } \forall i \in B_j, \theta_i = \theta^{(j)}$$

Then $\ln p(M \mid \theta)$ defines the block penalties

$$\kappa_j = \frac{1}{2} \ln(n) + \ln(\theta^{(j)^{-1}} - 1)$$

Thresholding in orthogonal setting ($\mathbf{X}^\top \mathbf{X} = n \mathbf{I}$)

Selection with **most Bayesian procedures [2], LASSO and L_0 penalty** operate by **thresholding the MLE**.

A **generic threshold estimator**:

$$\hat{S} := \left\{ i : |\hat{\beta}_i| > \tau \right\},$$

with standard L_0 : $\tau = \sqrt{\frac{2\kappa}{n}}$

A **generic block informed threshold estimator**:

$$\hat{S}_j^b := \left\{ i \in B_j : |\hat{\beta}_i| > \tau_j \right\} \quad \text{and} \quad \hat{S}^b = \bigcup_j \hat{S}_j^b$$

with block informed L_0 : $\tau_j = \sqrt{\frac{2\kappa_j}{n}}$

Selection consistency when $\mathbf{X}^\top \mathbf{X} = n \mathbf{I}$

Theorem

Suppose that τ and β_{min}^* satisfy:

$$\tau \geq \sqrt{2 \ln(p-s)/n} \quad \text{and} \quad \beta_{min}^* - \tau \geq \sqrt{2 \ln(s)/n}$$

then $P(\hat{S} = S) \rightarrow 1$

Theorem

Suppose that the τ_j 's and $\beta_{min,j}^*$'s satisfy:

$$\tau_j \geq \sqrt{2 \ln(p_j - s_j)/n} \quad \text{and} \quad \beta_{min,j}^* - \tau_j \geq \sqrt{2 \ln(s_j)/n}$$

then $P(\hat{S}^b = S) \rightarrow 1$

Necessary conditions when $\mathbf{X}^\top \mathbf{X} = n \mathbf{I}$

Theorem

a) If for some $j \in \{1, \dots, b\}$, $\lim_{n \rightarrow \infty} \frac{\tau_j}{\sqrt{\frac{2 \ln(p_j - s_j)}{n}}} < 1$, then $P(\hat{S}^b \subseteq S) \not\rightarrow 1$.

b) Assume for some $j \in \{1, \dots, b\}$, $\forall i \in S_j \beta_i^* = \beta_{\min, j}^*$ and $s_j/p_j \leq c < 1$.

If $\lim_{n \rightarrow \infty} \frac{\beta_{\min, j}^* - \tau_j}{\sqrt{\frac{\pi}{2} \frac{\ln(s_j)}{n}}} \leq 1$ then $P(S \subseteq \hat{S}^b) \not\rightarrow 1$.

c) Assume for some $j \in \{1, \dots, b\}$, $\forall i \in S_j \beta_i^* = \beta_{\min, j}^*$ and $s_j/p_j < 1$.

If $\lim_{n \rightarrow \infty} \frac{\beta_{\min, j}^*}{\sqrt{\frac{2 \ln(p_j - s_j)}{n}} + \sqrt{\frac{\pi}{2} \frac{\ln(s_j)}{n}}} < 1$ then $P(\hat{S}^b = S) \not\rightarrow 1$