

PEV1100 PCI Express to VME64x Interface User Manual

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Record History		
Version	Date	Description of Changes
0.01	May 1, 2008	File creation
0.99	11/27/08	Preliminary release
1.00	06/01/09	First release
2.00	08/20/09	Support for multicrate configurations and real time linux (Xenonai)
3.00	01/12/10	Short PCI IO space and DMA list mode

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1 Introduction

1.1 Document Identification

The PEV1100_UM_081801 is the user's manual of the PEV1100 PCI Express to VME64x Interface.

1.2 Intended Audience

This manual is intended for use by system designers, software developers and support personnel.

It is recommended that the reader has a reasonable background in PC architectures, including experience or knowledge of I/O buses and related protocols.

1.3 Companion Documents

PEV1100 Reference Manual

1.4 References

Reference	Title	Version	Date	Organization
	PCI Local Bus Specification	3.0	Aug 12,2002	PCI-SIG
	PCIe Base Specification	2.0	Jan 4, 2007	PCI-SIG
	PCIe External Cabling Specification	1.0	Dec 20,2006	PCI-SIG
VITA 1-1994 (R2002)	VME64	1	1994	VITA
VITA 1.1-1997(R2005)	VME64 Extensions	1.1	1997	VITA
	VME64 2eSST			VITA
	PMC			
	XMC			
	ExpressLane PEX8112-AA PCI Express to PCI Bridge	1.1	Nov 2007	PLX
	ExpressLane PEX8624-AA 24-lanes/6-ports PCI Express Gen 2 Switch	0.9	Jan 2008	PLX

Table 1: References

1.5 Document Organization

This manual is composed of the following sections

- 1. Introduction
- 2. PEV1100 Capabilities
- 3. Getting Started
- 4. Software references

Section 2 gives an overview of the PEV1100 architecture and describe the features it implements

Section 3 is a step by step procedure to install and run the PEV1100

Section 4 contains a description of the software delivered with the PEV1100.

1.6 Conventions and Notations

Examples, code references and screen copy are inserted in frames an use fixed fonts.

Bold typefaces are used to indicate characters to be typed in.

1.7 Acronyms and Abbreviations

Term	Definition
DMA	Direct Memory Access
IEEE	Institute of Electrical & Electronics Engineers
IO	Input/Output
PC	Personal Computer
PCI	Peripheral Component Interconnect
PCIe	PCI Express
VITA	VMEBUS International Trade Association
VME	Versa Module Eurocard (IEEE1014)

Table 2: Acronyms and Abbreviations

2 Linux Host

2.1 Checking for the PEV1100

2.1.1 Listing PCI devices

The *Ispci* command (you must be superuser to execute that command) lists all PCI devices discovered during the enumeration process. The file "/usr/share/pci.ids" contains a list of all known PCI Ids.

```
linux-host:~>lspci
00:00.0 Memory controller: nVidia Corporation CK804 Memory Controller (rev a4)
00:01.0 ISA bridge: nVidia Corporation CK804 ISA Bridge (rev f1)
00:01.1 SMBus: nVidia Corporation CK804 SMBus (rev a2)
00:02.0 USB Controller: nVidia Corporation CK804 USB Controller (rev a2)
00:02.1 USB Controller: nVidia Corporation CK804 USB Controller (rev a4)
00:07.0 IDE interface: nVidia Corporation CK804 Serial ATA Controller (rev f3)
00:08.0 IDE interface: nVidia Corporation CK804 Serial ATA Controller (rev f3)
00:09.0 PCI bridge: nVidia Corporation CK804 PCI Bridge (rev f2)
00:0b.0 PCI bridge: nVidia Corporation CK804 PCIE Bridge (rev f3)
00:0c.0 PCI bridge: nVidia Corporation CK804 PCIE Bridge (rev f3)
00:0d.0 PCI bridge: nVidia Corporation CK804 PCIE Bridge (rev f3)
00:0e.0 PCI bridge: nVidia Corporation CK804 PCIE Bridge (rev a3)
00:18.0 Host bridge: Advanced Micro Devices [AMD] K8 [Athlon64/Opteron] HyperTransport
Technology Configuration
00:18.1 Host bridge: Advanced Micro Devices [AMD] K8 [Athlon64/Opteron] Address Map
00:18.2 Host bridge: Advanced Micro Devices [AMD] K8 [Athlon64/Opteron] DRAM Controller
00:18.3 Host bridge: Advanced Micro Devices [AMD] K8 [Athlon64/Opteron] Miscellaneous
Control
01:08.0 VGA compatible controller: ATI Technologies Inc ES1000 (rev 02)
02:00.0 Ethernet controller: Broadcom Corporation NetXtreme BCM5722 Gigabit Ethernet PCI
Express
05:00.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
(rev ab)
06:01.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
06:04.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
06:05.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
06:06.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
(rev ab)
06:08.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
(rev ab)
06:09.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch
09:00.0 Bridge: IOxOS Technologies PEV1100 PCI Express VME Bridge (rev 01)
Oa:00.0 PCI bridge: PLX Technology, Inc. PEX8112 x1 Lane PCI Express-to-PCI Bridge (rev
aa)
linux-host:~>
```

To obtain a "tree" view, just use *lspci* the "-t" option

```
linux-host:->lspci -t
-[0000:00]-+-00.0
+-01.0
+-01.1
+-02.0
+-02.1
+-07.0
+-08.0
+-09.0-[0000:01]----08.0
+-0b.0-[0000:02]----00.0
+-0c.0-[0000:03]--
```

2.1.2 Hot Plug Support

Linux supports PCI Express hot plug through the *pciehp* module. By default this module is not loaded in the kernel. Before loading it you should make sure the root complex of the PC host support hot plugging.

2.1.3 Finding the PEV1100

To identify the PEV1100 in the PCI device list, just search for the PEX8624 PCI Express switch by looking for the "8624" string.

```
linux-host:->lspci | grep 8624
05:00.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:01.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:04.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:05.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:06.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:08.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:09.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
06:09.0 PCI bridge: PLX Technology, Inc. PEX 8624 24-lane, 6-port PCI Express Switch (rev ab)
linux-host:->
```

The first line in the list is the switch upstream port (the first discovered by the enumeration process). It has been located on bus 0xd in slot 0 [0d:00.0]

Then try to identify the FPGA PCI Express End point by looking for the "1100" string.

```
linux-host:~>lspci |grep 1100
09:00.0 Bridge: IOxOS Technologies PEV1100 PCI Express VME Bridge (rev 01)
linux-host:~>
```

It has been located on bus 0x11 in slot 0 [11:00.0]

Using again the *Ispci* command we can do a byte dump of its PCI Configuration Header .

Beware that 16 and 32 bit fields appear in reverse order because PCI is little endian.

```
linux-host:->lspci -x -s 09:00.0
09:00.0 Bridge: IOXOS Technologies PEV1100 PCI Express VME Bridge (rev 01)
00: 57 73 00 11 07 05 10 00 01 00 80 06 10 00 00 00
10: 08 00 00 d0 00 00 00 00 00 00 08 00 00 00
```

```
20: 01 40 00 00 00 00 00 00 00 00 00 00 08 20 50 50 30: 00 00 00 40 00 00 00 00 00 00 ff 00 00 00 linux-host:~>
```

A human readable display of that information is obtained with the -v option

```
linux-host:~>lspci -vv -s 09:00.0
09:00.0 Bridge: IOXOS Technologies PEV1100 PCI Express VME Bridge (rev 01)
        Subsystem: Device 2008:5050
        Control: I/O+ Mem+ BusMaster+ SpecCycle- MemWINV- VGASnoop- ParErr- Stepping-
SERR+ FastB2B- DisINTx+
       Status: Cap+ 66MHz- UDF- FastB2B- ParErr- DEVSEL=fast >TAbort- <TAbort- <MAbort-
>SERR- <PERR- INTx-
        Latency: 0, Cache Line Size: 64 bytes
        Interrupt: pin ? routed to IRQ 499
        Region 0: Memory at d0000000 (32-bit, prefetchable) [size=128M]
        Region 2: Memory at b8000000 (32-bit, non-prefetchable) [size=128M]
        Region 4: I/O ports at 4000 [size=4K]
        Capabilities: [40] Power Management version 3
                Flags: PMEClk- DSI+ D1- D2- AuxCurrent=0mA
PME(D0-,D1-,D2-,D3hot-,D3cold-)
                Status: D0 PME-Enable- DSel=0 DScale=0 PME-
        Capabilities: [48] Message Signalled Interrupts: Mask+ 64bit+ Count=1/4 Enable+
                Address: 00000000fee0300c Data: 4142
                Masking: 0000000e Pending: 00000000
        Capabilities: [60] Express (v1) Endpoint, MSI 00
                DevCap: MaxPayload 512 bytes, PhantFunc 1, Latency LOs <64ns, L1 <1us
                        ExtTag+ AttnBtn- AttnInd- PwrInd- RBE+ FLReset-
                DevCtl: Report errors: Correctable- Non-Fatal- Fatal- Unsupported-
                        RlxdOrd+ ExtTag- PhantFunc- AuxPwr- NoSnoop+
                        MaxPayload 128 bytes, MaxReadReq 512 bytes
                DevSta: CorrErr- UncorrErr- FatalErr- UnsuppReq- AuxPwr- TransPend-
                LnkCap: Port #0, Speed 2.5GT/s, Width x4, ASPM L0s L1, Latency L0
unlimited, L1 unlimited
                        ClockPM- Suprise- LLActRep- BwNot-
                LnkCtl: ASPM Disabled; RCB 64 bytes Disabled- Retrain- CommClk-
                        ExtSynch- ClockPM- AutWidDis- BWInt- AutBWInt-
                LnkSta: Speed 2.5GT/s, Width x4, TrErr- Train- SlotClk- DLActive-
BWMamt - ABWMamt -
        Capabilities: [100] Virtual Channel <?>
linux-host:~>
```

We can observe the the FPGA PCI IO window has been allocated at address 0x4000 and the two PCI MEM windows at 0xd0000000 for the prefetchable one (size 128 MBytes) and at 0xb8000000 for the non prefetchable (size 128 MBytes)

2.2 Software installation

The PEV1100 software for Linux is provided as compressed archive file named "PEV1100_x.y.z.tgz" ready to be extracted anywhere in the file system tree

It is important that the **kernel sources package** is installed during the Linux installation. Without this, the kernel header files will not be available for building the PEV1100 device driver module. Typically, this package must be manually selected during the installation process. Please refer to the Linux installation documentation.

Due to the numerous flavors of Linux, IOxOS Technologies cannot support and test on all platforms. In order to provide customers with an easy to replicate platform, PEV1100 software is tested with easily-available Linux distributions. Other flavors of Linux should work ok or with a minimal porting effort. The PEV1100 Linux support has been built and tested on the OSes listed below

Operating System	Kernel
------------------	--------

OpenSuse 10.3	2.6.24-3 SMP x86_64
Opensuse 11.1	2.6.27-7 SMP x86_64
Opensuse 11.1	2.6.28-7 SMP x86_64 with Xenomai 2.4.7

2.2.1 Extracting the sources

The PEV1100 software can be extracted anywhere in the Linux file system. The extraction process will create a directory PEV1100/ containing all software sources provided by IOxOS Technologies to support the PEV1100 interface.

```
linux-host:ioxos> tar xzf PEV1100_2.0.0.tgz
```

The sources are organized as followed:

```
PEV1100/
bin/
cfg/
doc/
drivers/
hotplug/
include/
lib/
modules/
scripts/
src/
examples/
tools/
XprsMon/
XprsTst/
```

The file build.all located at the root of the tree is a bash script building all drivers, libraries and utilities for a "classical" linux kernel and, if found in the file system for a a real time linux kernel based on Xenomai 2.4.7

```
# check for Xenomai in the file system
XENODIR="/usr/xenomai"
ls $XENODIR
if [ $? -eq 0 ]; then
XENO=1
else
XENO=0
# build PEV1100 device driver
cd drivers
./build.linux
if [ $XENO -eq 1 ]; then
./build.xeno
fi
# build hotplug device driver
cd ../hotplug
./build
# build libraries
cd ../lib
make
if [
     $XENO -eq 1 ]; then
make xeno
fi
```

```
# build XprsMon
cd ../src/XprsMon
./build.linux
if [ $XENO -eq 1 ]; then
./build.xeno
# build examples
cd ../examples
make
if [
     $XENO -eq 1 ]; then
make xeno
# build configuration tools
cd ../tools
make install
# build test suite
cd ../XprsTst
./build
```

2.2.2 Building Device Driver for the PEV1100

The first operation to performed by the build.all script, is to build the PEV1100 device driver. The directory **PEV1100/drivers/** contains all sources needed to build the loadable module **pev.ko**. As already stated, the Makefile rely on the presence of the Linux kernel sources on the development machine.

The Makefile is written in such a way that the pev driver is expected to run on the machine on which it is compiled.

The *driver/build.linux* script generate a driver for a "classical" Linux and copies the kernel object in the *modules/* directoy under the name *pev-linux.ko*

```
rm -f *.o *.ko *.mod.c
make -C /lib/modules/2.6.28.7-xeno/build M=/home/ioxos/Release/PEV1100 2.0.0/drivers
make[1]: Entering directory `/home/ioxos/kernel/linux-2.6.28.7'
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pevdrvr.o
  CC [M]
  CC [M] /home/ioxos/Release/PEV1100_2.0.0/drivers/pevioctl.o
          /home/ioxos/Release/PEV1100_2.0.0/drivers/pevklib.o
/home/ioxos/Release/PEV1100_2.0.0/drivers/rdwrlib.o
  CC [M]
  CC [M]
  CC [M]
          /home/ioxos/Release/PEV1100_2.0.0/drivers/sflashlib.o
           /home/ioxos/Release/PEV1100_2.0.0/drivers/maplib.o
/home/ioxos/Release/PEV1100_2.0.0/drivers/i2clib.o
  CC [M]
  CC [M]
  CC [M]
           /home/ioxos/Release/PEV1100_2.0.0/drivers/vmelib.o
           /home/ioxos/Release/PEV1100 2.0.0/drivers/dmalib.o
  CC [M]
           /home/ioxos/Release/PEV1100 2.0.0/drivers/histolib.o
  CC [M]
  LD [M]
          /home/ioxos/Release/PEV1100_2.0.0/drivers/pev.o
  Building modules, stage 2.
  MODPOST 1 modules
           /home/ioxos/Release/PEV1100_2.0.0/drivers/pev.mod.o
  CC
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pev.ko
make[1]: Leaving directory `/home/ioxos/kernel/linux-2.6.28.7'
```

If Xenomai has been installed in the host filesystem, the *driver/build.xeno* script generate a driver for a real time Linux and copies the kernel object in the *modules/* directoy under the name *pev-xeno.ko*

```
rm -f *.o *.ko *.mod.c
make -C /lib/modules/2.6.28.7-xeno/build M=/home/ioxos/Release/PEV1100_2.0.0/drivers
modules
make[1]: Entering directory `/home/ioxos/kernel/linux-2.6.28.7'
```

```
CC [M]
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pevdrvr.o
  CC [M]
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pevioctl.o
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pevklib.o
  CC [M]
  CC [M]
          /home/ioxos/Release/PEV1100_2.0.0/drivers/rdwrlib.o
  CC [M]
          /home/ioxos/Release/PEV1100_2.0.0/drivers/sflashlib.o
          /home/ioxos/Release/PEV1100 2.0.0/drivers/maplib.o
  CC [M]
          /home/ioxos/Release/PEV1100_2.0.0/drivers/i2clib.o/home/ioxos/Release/PEV1100_2.0.0/drivers/vmelib.o
  CC [M]
  CC [M]
  CC [M]
          /home/ioxos/Release/PEV1100 2.0.0/drivers/dmalib.o
  CC [M]
          /home/ioxos/Release/PEV1100 2.0.0/drivers/histolib.o
          /home/ioxos/Release/PEV1100_2.0.0/drivers/pev.o
  LD [M]
  Building modules, stage 2.
  MODPOST 1 modules
          /home/ioxos/Release/PEV1100 2.0.0/drivers/pev.mod.o
  LD [M] /home/ioxos/Release/PEV1100_2.0.0/drivers/pev.ko
make[1]: Leaving directory `/home/ioxos/kernel/linux-2.6.28.7'
```

2.2.3 Building the PEV1100 hotplug driver

The *hotplug*/ directory contains the sources of a device driver to allow the user to power-off/power-on the PEV1100 without rebooting the local host. The build script copies the generated kermel object in the *modules*/ directory under the name *hppev.ko*

```
rm -f *.o *.ko *.mod.c
make -C /lib/modules/2.6.28.7-xeno/build M=/home/ioxos/Release/PEV1100_2.0.0/hotplug
modules
make[1]: Entering directory `/home/ioxos/kernel/linux-2.6.28.7'
    CC [M] /home/ioxos/Release/PEV1100_2.0.0/hotplug/hpdrvr.o
    LD [M] /home/ioxos/Release/PEV1100_2.0.0/hotplug/hppev.o
    Building modules, stage 2.
    MODPOST 1 modules
    CC /home/ioxos/Release/PEV1100_2.0.0/hotplug/hppev.mod.o
    LD [M] /home/ioxos/Release/PEV1100_2.0.0/hotplug/hppev.ko
make[1]: Leaving directory `/home/ioxos/kernel/linux-2.6.28.7'
```

2.2.4 Building the PEV1100 users library

The *lib/* directory contains the sources of the user library interface with the driver. Executing a make in this directory builds the librev.a library file.

```
gcc -I ../include -c pevulib.c
gcc -I ../include -c clilib.c
gcc -I ../include -c tstlib.c
ar r libpev.a pevulib.o clilib.o tstlib.o
ar: creating libpev.a
ranlib libpev.a
```

If Xenomai has been installed in the host filesystem, the "make xeno" generate the library librevrt.a to be used with the pev-xeno device driver in order to create real time linux applications.

```
gcc -I ../include -I /usr/xenomai/include -c pevrtlib.c
ar r libpevrt.a pevrtlib.o
ar: creating libpevrt.a
ranlib libpevrt.a
cp /usr/xenomai/lib/librtdm.a .
cp /usr/xenomai/lib/libnative.a .
```

2.2.5 **Building XprsMon**

XprsMon is a command interpreter allowing a user to debug a VME system controlled by a PC host through

the PEV1100 interface. The sources together with a Makefile shall be found in the *src/XprsMon/*. Executing buil.linux in that directory creates the *XprsMon* executable and copies it in the bin/ directory.

```
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c tty.c
gcc -g -DLITTLE_ENDIAN -DDEBUGrm -f *.o XprsMon
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c XprsMon.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c rdwr.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c conf.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c sflash.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c map.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c script.c -I ../../include -c tst.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c timer.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c vme.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c vme.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c vme.c
gcc -L ../../lib -o XprsMon XprsMon.o rdwr.o conf.o sflash.o map.o script.o tty.o tst.o
timer.o vme.o -lpev -lrt
```

If Xenomai has been installed in the host filesystem, the build.xeno script generates an **XprsMon** application linked with the real time library and copied in the *bin/* directory under the name **XprsMonRt**.

```
rm -f *.o XprsMon
qcc -q -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
XprsMon.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
gcc -g -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
conf.c
gcc -g -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
sflash.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
map.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
script.c
gcc -g -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
tty.c
gcc -g -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
tst.c
gcc -g -DLITTLE_ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
timer.c
gcc -q -DLITTLE ENDIAN -DDEBUG -DXENOMAI -I ../../include -I /usr/xenomai/include -c
vme.c
gcc -L ../../lib -o XprsMon XprsMon.o rdwr.o conf.o sflash.o map.o script.o tty.o tst.o
timer.o vme.o -lpev -lrt -lpevrt -lnative -lrtdm
```

2.2.6 Installing the PEV1100 examples

The directory src/examples contains few examples of linux applications driving the PEV1100 interface.

```
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -I /usr/xenomai/include -c BerrTst.c
gcc -L ../../lib -o BerrTst BerrTst.o -lpev -lrt
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -I /usr/xenomai/include -c VmeTst.c
gcc -L ../../lib -o VmeTst VmeTst.o -lpev -lrt
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -I /usr/xenomai/include -c DmaTst.c
gcc -L ../../lib -o DmaTst DmaTst.o -lpev -lrt
```

```
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -I /usr/xenomai/include -DXENOMAI -c
DmaTst.c -o DmaTstRt.o
gcc -L ../../lib -o DmaTstRt DmaTstRt.o -lpev -lrt -lpevrt -lnative -lrtdm
```

2.2.7 Installing the PEV1100 configuration tools

A set of configuration tools is provided to allow user's to generate binary objects to be loaded in the SFLASH device. These are useful for those developing new FPGA bitstreams.

```
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c fsm2bin.c
gcc -L ../../lib -o fsm2bin fsm2bin.o
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c mcs2bin.c
gcc -L ../../lib -o mcs2bin mcs2bin.o
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c fpgabuild.c
gcc -L ../../lib -o fpgabuild fpgabuild.o
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c fpgacheck.c
gcc -L ../../lib -o fpgacheck fpgacheck.o
gcc -g -DLITTLE_ENDIAN -DDEBUG -I ../../include -c hppev.c
gcc -L ../../lib -o hppev hppev.o
cp fsm2bin ../../bin
cp fpgabuild ../../bin
cp fpgacheck ../../bin
cp fpgacheck ../../bin
cp hppev ../../bin
```

2.2.8 Installing the PEV1100 test suite

The srcXprsTst/ directory contains a test suite to be controlled from XprsMon. The build script generate the test launcher XprsTst and a test file PevTst containing a set of the test executed for the validation of the PEV1100 hardware.

```
rm -f *.o XprsTst PevTst
gcc -g -DLITTLE_ENDIAN -DDEBUGno -I ../../include -c XprsTst.c
gcc -g -DLITTLE_ENDIAN -DDEBUGno -I ../../include -c tst_0x.c
gcc -L ../../lib -o XprsTst XprsTst.o -lpev -lrt
gcc -g -DLITTLE_ENDIAN -DDEBUGno -I ../../include -c PevTst.c
gcc -L ../../lib -o PevTst PevTst.o tst_0x.o -lpev -lrt
```

2.3 Loading the PEV1100 device driver

Before running any application using the PEV1100, it is mandatory to insert dynamically either the *pev-linux.ko* or the *pev-xeno.ko* device driver in the kernel. This is done by executing the *insmod* program. The driver initialization function allocates dynamically the device major number. This number is needed to create the nodes allowing applications to access the device and can be find in the /proc/devices file once the driver has been successfully installed.

The script file *load* located in the *modules*/ directory performs all these operations. It loads a kernel module according to the argument given, retrieves the device number assigned by the kernel to the PEV1100 device and create the *pev* nodes in the */dev* directory. It shall be noted that <u>you must have superuser privileges</u> to run that script.

If the PEV1100 is not connected to the host, the device driver installation will fail. Before executing the *load* script, one should check with *lspci* that the PEV1100 has been discovered by the Linux.

To load the Linux "classical" driver, pev-linux shall be given has argument to the load script.

```
linux-host:PEV1100_2.0.0>su
Password:
linux-host:PEV1100_2.0.0>cd modules/
linux-host:modules>./load pev-linux
loading PEV1100 linux driver pev-linux.ko
linux-host:modules>
```

Using the *lsmod* command we can check if the *pev* module has been loaded

```
linux-host:modules>lsmod | grep pev
pev 98672 0
linux-host:modules>
```

and get a list of the nodes created with read/write privileges for everybody.

```
linux-host:modules>ls -1 /dev/pev*

crw-rw-rw- 1 root wheel 250, 0 2009-08-27 15:50 /dev/pev

crw-rw-rw- 1 root wheel 250, 0 2009-08-27 15:50 /dev/pev0

crw-rw-rw- 1 root wheel 250, 1 2009-08-27 15:50 /dev/pev1

crw-rw-rw- 1 root wheel 250, 10 2009-08-27 15:50 /dev/pev10

crw-rw-rw- 1 root wheel 250, 11 2009-08-27 15:50 /dev/pev10

crw-rw-rw- 1 root wheel 250, 12 2009-08-27 15:50 /dev/pev11

crw-rw-rw- 1 root wheel 250, 12 2009-08-27 15:50 /dev/pev12

crw-rw-rw- 1 root wheel 250, 13 2009-08-27 15:50 /dev/pev13

crw-rw-rw- 1 root wheel 250, 14 2009-08-27 15:50 /dev/pev14

crw-rw-rw- 1 root wheel 250, 15 2009-08-27 15:50 /dev/pev15

crw-rw-rw- 1 root wheel 250, 2 2009-08-27 15:50 /dev/pev2

crw-rw-rw- 1 root wheel 250, 3 2009-08-27 15:50 /dev/pev2

crw-rw-rw- 1 root wheel 250, 4 2009-08-27 15:50 /dev/pev3

crw-rw-rw- 1 root wheel 250, 5 2009-08-27 15:50 /dev/pev4

crw-rw-rw- 1 root wheel 250, 6 2009-08-27 15:50 /dev/pev4

crw-rw-rw- 1 root wheel 250, 7 2009-08-27 15:50 /dev/pev5

crw-rw-rw- 1 root wheel 250, 7 2009-08-27 15:50 /dev/pev6

crw-rw-rw- 1 root wheel 250, 7 2009-08-27 15:50 /dev/pev6

crw-rw-rw- 1 root wheel 250, 8 2009-08-27 15:50 /dev/pev8

crw-rw-rw- 1 root wheel 250, 8 2009-08-27 15:50 /dev/pev8

crw-rw-rw- 1 root wheel 250, 8 2009-08-27 15:50 /dev/pev8

crw-rw-rw- 1 root wheel 250, 9 2009-08-27 15:50 /dev/pev8

crw-rw-rw- 1 root wheel 250, 9 2009-08-27 15:50 /dev/pev8

crw-rw-rw- 1 root wheel 250, 9 2009-08-27 15:50 /dev/pev8
```

16 nodes have been created with minor device number going from 0 to 15. The minor device number allows to target a specific PEV1100 board in multi-crate configurations. When opening the device, a match between the position of the rotary encoder located on the board and the minor device number is required.

If compatibility with older version of the driver is needed, the rotary encoder shall be set to position 0.

If Xenomai has been installed in the Linux kernel, one can load the real time driver pev-xeno. It shall be noted that pev-linux and pev-xeno cannot be loaded together. They both offer the same capabilities. However, the pev-xeno version rely on xenomai interrupt service routines and synchronization mechanism in order to guarantee real time performances.

To load the Linux "real time" driver, *pev-xeno* shall be given has argument to the *load* script. If pev-linux is already installed, don't forget to remove it.

```
linux-host:modules>rmmod pev
linux-host:modules>./load pev-xeno
loading PEV1100 xenomai driver pev-xeno.ko
linux-host:modules>
```

When this has been done, we can run applications relying on this driver such *XprsMon* or *XprsMonRt*.

2.4 Using XprsMon to access the PEV1100

The PEV1100 binaries are located in the PEV1100/bin directory. We first add it to the default search PATH:

```
linux-host:~>export PATH=~/PEV1100/bin:$PATH
```

and we execute the PEV1100 command interpreter *XprsMon* for node 1

```
Device driver: pev-linux
XprsMon#1>
```

Basically **XprsMon** implements a set of command (see §3.7) interpreted and executed when the user enters a command line on the keyboard. A command line is an ASCIIi string made of

- a command code
- a command extension (optional)
- · zero or more command parameters

The *help* command displays a list of all supported command codes. "?" is an alias for *help*.

```
XprsMon#1>help
conf
          dm
                     dma
                               de
          dr
                     ds
                                ds1
dp
ds2
          du
                     du1
                               du2
          fifo
dv
                     fm
                               fp
fpga
          fs
                     fs1
                               fs2
          fu1
                     fu2
fu
help
          i2c
                     lql
                               ls
ls1
          ls2
                     lu
                               lu1
lu2
          lv
                     map
                               рс
          pio
pe
                     рm
                               pp
pr
          ps
                     ps1
                               ps2
          pu1
                     pu2
pu
                               pv
рх
          rm
                     re
                               rp
                     rs1
                               rs2
rr
          rs
ru
          ru1
                     ru2
                               rv
rmw
          sflash
                     sign
                               ts
ts1
          ts2
                               tu1
                     tu
tu2
          tv
                     timer
                               tinit
tkill
          tlist
                     tset
                                tstart
tstatus
          tstop
                     tty
                               vme
XprsMon#1>
```

help accept one parameter which is any supported command code in order to display the syntax of the command.

The command extension is separated from the command code by a comma. In the example above, the *pio* command extension <ds> is used to define the data size to be used for the read or write cycle. The command parameters are the cycle target address and the data for a write operation.

It shall be noted that, unless otherwise stated, *XprsMon* integer parameters are interpreted and displayed as hexadecimal values.

2.5 The PEV Configuration

The **conf** command displays a summary of the PEV hardware configuration.

```
XprsMon#1>conf
Static Options [0x81aea200]
VME Interface
A24 Base Address : 000000
```

```
System Controller: 64x- Slot1- SysRstEna-
         Auto ID
                            : disabled
      PLX8624 Switch
         Port0 [P3]
                           : Downstream
         Port1 [P4]
                           : Upstream
                          : Downstream
         Port5 [FPGA]
                          : Downstream : Downstream
         Port6 [PCI]
         Port8 [XMC#1]
         Port9 [XMC#2]
                          : Downstream
      FPGA
         Bit Stream
                           : 1
                          : Disabled
         PON FSM
         MEM size
                           : 512 MBytes
                          : 128 MBytes
         PMEM size
         PMEM mode
                           : A64
   FPGA Status
      Identifier
                           : 0x02031201
      Bit stream loaded : 1
   Shared Memory
     Size
                           : 256 MBytes
   VME Interface
     System Controller : Disabled
      Master
                          : Enabled
                          : Release On Request
: 0
         Request Mode
         Request Level
                           : Enabled
      Slave
        A24 base address : 0x000000
A32 base address : 0x10000000
         A32 window size : 0x10000000
         CR/CSR
                           : Berr- SlvEna+ SysFail- SysFailEna- Reset- AutoID-
      Interrupt Generator
         Vector
                            : 00
         Level
                            : 0
         Mode
                           : Register
         Status
                           : Cleared
   FPGA System Monitor
      Temperature
                          : 44.30 [48.72 - 43.80]
                           : 1.00 [1.00 - 0.98]
: 2.56 [2.56 - 2.55]
      VCCint
      VCCaux
      VCC1.8-INT
                           : 1.78
      VCC3.3-INT
                           : 3.18
      VCC5.0-VME
                           : 4.97
      VCC3.3-VME
                            : 3.30
XprsMon#1>
```

2.6 Script files

To avoid the burden of typing many times the same set of command, XprsMon is able to execute simple script files. Script files can include comments starting with the '#' character. When '#' is encountered by the line interpreter, all following characters are discarded.

If a line start with the '\$' character, the following string of character is interpreted as a Linux command. The following commands are supported:

- sleep
- usleep

It shall be noted that script files can contain references to other script files.

2.7 Reloading an FPGA bitstream

After a reset, the FPGA bitstream file is automatically loaded from the SFLASH device according to the identification number selected in the static options SW501 (see Error: Reference source not found). IOxOS Technologies provides binary files with a *.sfl* extention ready to be loaded in SFLASH. These files contains the FPGA bitstream, a register initialization code and a signature.

The XprsMon command *sflash* allows the user to perform a load operation in order to store a .sfl binary file in the PEV1100 SFLASH device.

```
[root@P2020RDB IPV1102]# ./XprsMon 1
initializing crate 1
       XprsMon - IPV1102 diagnostic tool
        IOxOS Technologies Copyright 2009-2012
        Version 4.06 - Mar 27 2012 10:23:52
Device driver: pev-linux
XprsMon>sflash load fpga#1 pev_041108.sfl
Loading SFLASH from file pev_101208a.sfl at offset 0x200000 [size 0x200000]
!! Programming the SFLASH device is done one bit at a time
!! It requires millions of physical accesses loading the CPU at 100%
!! During that process the system will be hanging for periods of 10 seconds
\verb|!!| This is the time needed to program one SFLASH sector
-> Just relax and sit back...
Writing device will take about 90 seconds.....00400000 -> done
Verifying device will take about 108 seconds...00400000 -> OK
XprsMon>
```

That operation takes two arguments

- an fpga identifier *fpga#i* (where i goes from 1 to 4)
- the file name of the .sfl file to be loaded

The sign operation displays the file signature

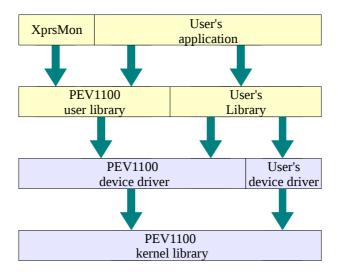
```
XprsMon>sflash sign fpga#1
FPGA#1 Signature at offset 0x3f0000
   + company: IOxOS Technologies
   + board:PEV1100
   + filename:pev_101208a.sfl
   + creation:Wed Dec 10 14:22:35 2008
   + mcs_file:pev1100_sw4_101208a.mcs
   + mcs devname:XC5VLX30T
   + mcs_devid:0x02a6e093
   + mcs offset:0x000000
   + mcs size:0x11dfc0
   + mcs_checksum:0x339e1638
   + mcs creation: Wed Dec 10 14:19:02 2008
   + fsm_file:pev_init.fsm
   + fsm_offset:0x1c0000
   + fsm size:0x000278
   + fsm_checksum:0xcc952770
   + fsm_creation:Wed Sep 17 15:43:36 2008
XprsMon>
```

3 Software Reference

3.1 Software Organization

The PEV1100 software for Linux is delivered on an Iso9660 CDROM labeled **PEV1100_x.y.z** together with an installation notice. The CDROM contains a README file and a compressed archive file labeled **PEV1100_xxyyzz.tgz** containing all delivered files including the documentation.

The **PEV1100_xxyyzz.tgz** can be extracted anywhere in the Linux file system and produce a directory tree labeled *PEV1100/* (see §2.2.1). All source code is written in C language and has been compiled with the gnu compiler (gcc version 4.2.1).



The core of the software organization is the PEV device driver (see §3.2). This is a Linux loadable module located in the *drivers*/ directory of the *PEV1100*/ directory tree.

A user library (see §3.5)interfacing applications with the driver is provided in the lib/ directory.

The code has been written and tested for a 64 bit little endian machine. Data size are declared as followed:

```
8 bit signed → char,
8 bit unsigned → uchar, u8
16 bit signed → short,
16 bit unsigned → ushort, u16
32 bit signed → int,
32 bit unsigned → uint, u32
64 bit signed → long,
64 bit unsigned → ulong, u64
```

3.2 PEV1100 Device Driver

The PEV1100 device driver is a Linux module acting as interface between an application and the PEV1100 interface. It relies on the PEV1100 kernel library. It implements the following functions:

```
pev_init()
pev_exit()
```

```
pev_probe()
pev_remove()
pev_open()
pev_release()
pev_read()
pev_write()
pev_llseek()
pev_ioctl()
pev_immap()
pev_irq()
```

All global data used by the driver and the kernel library are stored in the *pev_dev* control structure defined in the *pevdrvr.h* file.

3.2.1 Install/Remove

When the *pev* driver is installed in the kernel, the function *pev_init()* is automatically executed. That function performs the following operations:

- dynamically allocate a major device number
- scan the PCI device table to find all PLX8624 upstream ports present in the PCI tree
- register the device if at least one PLX8624 has been found.

For each PLX8624 PCI Express switch found it allocated a control structure in order to build a minor device whose number is equal to the node number selected by the rotary switch on the PEV1100 board. If it fails, it unregister the device and returns an error. Otherwise, it maps a 128 Kbytes address window in the PCI MEM space to access the PEC8624configuration registers.

It scan again the PCI device table behind each PLX8624 in order to find the FPGA PCIe end point and the PEX8112 PCI Express to PCI bridge. If found, both devices are mapped in kernel space and the FPGA Control and Status Registers are initialized.

3.2.2 Open/Close

open() select the PEV1100 control structure according to the minor device number. Return an error of minor number doesn't match any PEV1100 node number.

olose() release the PEV1100 control structure

3.3 Read/Write

read() and write() functions are not implemented in the pev driver.

3.3.1 **Ioctl**

The file *pevioctl.h* contains all declarations and definition to be used with the *ioctl()* system call. The file *pevioctl.c* implement all ioctl operations.

3.3.1.1 PEV1100 read/write operations

The **PEV_IOCTL_RDWR** command is a generic way to perform read and write access on any PEV1100 resource. The control structure has the following format:

```
char swap:
                       /* swap mode
    char as;
                       /* address size
                       /* transfer direction
   char dir;
                       /* remote crate identifier
   char crate:
   char am;
                       /* address modifier
                       /* remote space identifier
   char space;
   char rsv3:
  } mode:
  void *k addr;
};
```

The *buf* field is a pointer in the user's space to the data to be read or written.

The *offset* field is an address offset within the address space of the resource to be accessed. The resource is identified by the *space* fields in the *pev_rdwr_mode* data structure.

The field *len* defines the number of bytes to be transferred. For single access operations this field shall be set to zero.

The *pev_rdwr_mode* data structure holds the parameters defining the access type.

The *ds* field defines the data size to be used for each access. It can be 1 (byte), 2 (short), 4 (int) or 8 (long).

The as fields define the address size, It is used for VME accesses and can be 16, 24, 32, 48 or 64.

The *dir* field defines the transfer direction. It shall be 0 for a read and 1 for a write.

The *crate* field shall be set to the node number of the PEV1100 holding the targeted resource.

The *space* field shall be an identifier of the targeted resources. The following identifiers are valid:

```
RDWR_PCIE_CFG → PEV configuration register

RDWR_PCIE_IO → PEV PCI IO window (Control and status registers)

RDWR_PCIE_PMEM → PEV Prefetchable memory window

RDWR_PCIE_MEM → PEV Non Prefetchable memory window

RDWR_CSR → PEV Control and Status register through PCI MEM space

RDWR_PEX_MEM → PEX8624 Non Prefetchable memory window

RDWR_ELB → for P2020 host, provide access to ELB bus

RDWR_KMEM → Host kernel buffer
```

The *k_addr* field is used when **RDWR_KMEM** space is selected and shall hold the kernel base address of a data buffer allocated with **PEV_IOCTL_DMAC_ALLOC** (see §3.3.1.5).

3.3.1.2 PEV1100 address mapping operations

Some of the PEV1100 resources such the VME bus or the shared memory are accesses through an address translation table allowing to remap a local address to a remote address. Per example, the VME bus is seen by the CPU as a PCI memory resource. The address translation table defines the relationship between the PCI address used by the CPU and the VME cycle actually generated.

The **PEV_IOCTL_MAP_ALLOC** command allows to created an address translation window by allocating pages in the scatter/gather memory.

The PEV_IOCTL_MAP_FREE command allows to free previously allocated pages.

The **PEV_IOCTL_MAP_MODIFY** command allows to modify the mapping parameters of previously allocated pages.

All mapping operation are performed using the *pev_ioctl_map_pg* data structure as argument.

```
ulong rem addr;
                                         /* remote address to be mapped
                                                                                      */
  ulong loc addr;
                                         /* local address returned by mapper
                                                                                      */
  uint offset;
                                         /* offset of page containing local address
                                                                                      */
                                         /* size actually mapped
                                                                                      * /
  uint win size;
  ulong rem_base;
                                         /* remote address of window actually mapped */
                                        /* local address of window actually mapped
                                                                                      */
  ulong loc base;
  void *usr_addr;
                                         /* user address pointing to local address
                                                                                      */
                                         /* pci base address of SG window
  ulong pci_base;
};
```

The *rem_addr* and *size* parameters are used by the **PEV_IOCTL_MAP_ALLOC** command to define the window base address and size in bytes to be mapped in the destination space.

The *sg_id* parameter defines which address translation table shall be used for the mapping operation. Three tables are currently implemented in the PEV1100:

```
MAP_PCIE_MEM → FGA End Point PCI MEM mapper
MAP_PCIE_PMEM → FGA End Point PCI PMEM mapper
MAP_VME_SLAVE → VME slave mapper
```

The *mode* parameter defines the addressing mode and the destination space Its value shall be the logical or of the space,

```
MAP_SPACE_PCIE → destination space is PCI tree

MAP_SPACE_VME → destination space is VME bus

MAP_SPACE_SHM → destination space is shared memory

MAP_SPACE_SHM1 → destination space is shared memory #1

MAP_SPACE_SHM2 → destination space is shared memory #2

MAP_SPACE_USR → destination space is FPGA user area

MAP_SPACE_USR1 → destination space is FPGA user area #1

MAP_SPACE_USR2 → destination space is FPGA user area #2
```

swapping policy,

```
MAP_SWAP_NO → no swapping
MAP_SWAP_AUTO → auto swapping big → little endian
```

and address mode identifiers.

```
MAP_VME_SP → VME supervisor mode

MAP_VME_A16 → VME A16 (AM = 0x29 or 0x2d)

MAP_VME_A24 → VME A24 (AM = 0x39 or 0x3d)

MAP_VME_A32 → VME A32 (AM = 0x09 or 0x0d)

MAP_VME_BLT → VME A32 (AM = 0x0b or 0x0f)

MAP_VME_MBLT → VME A32 (AM = 0x0c)

MAP_VME_IACK → VME IACK
```

The *flaq* parameter holds information to allow to share address mapping among several applications.

The *loc_addr* parameter is filled by the driver after a successful allocation and contains the local address to be used to target the remote address. That address is an address offset within the mapping window and can be used as offset parameter by the PEV_IOCTL_RDWR command or by the mmap() function.

The other parameters are used internally by the driver mapping functions and should be left untouched.

3.3.1.3 PEV1100 SFLASH operations

The PEV_IOCTL_SFLASH_ID command returns the SFLASH hardware identifier.

SFLASH read/write operations are performed using the *pev_ioctl_sflash_rw* data structure as argument.

```
struct pev_ioctl_sfash_rw
{
  void *buf;
  uint offset;
  uint len;
};
```

The *buf* field is a pointer in the user's space to the data to be read or written.

The offset field is the SFLASH offset where data have to be read or written

The **len** field defines the number of bytes to be transferred.

The **PEV_IOCTL_SFLASH_RD** command shall be used to read an SFLASH address range and copy its content in the buffer provided by the application.

The **PEV_IOCTL_SFLASH_RW** command shall be used to copy a data buffer provided by the application in the SFLASH device. SFLASH sector boundaries are automatically handled by the driver, by first reading the entire sector, updating it and writing it back. SFLASH programming is done one bit at a time, thus overloading the CPU. The system seems to be hanging when that operation is performed.

3.3.1.4 PEV1100 local timer operation

All timer operation are performed using the *pev_ioctl_timer* data structure as argument.

The **PEV_IOCTL_TIMER_START** command starts the PEV1100 local timer. The *mode* field of the *pev_ioctl_timer* data structure is used to define in which mode the timer shall be started.

It shall be set to the bitwise OR of TIMER_FREQ_xxx, TIMER_BASE_xxx, TIMER_SYNC_xxx or TIMER_OUT_xxx.

The PEV_IOCTL_TIMER_STOP command stops the PEV1100 local timer

The **PEV_IOCTL_TIMER_READ** command reads the PEV1100 local timer and update the *time* and *utime* fields of the *pev_ioctl_timer* data structure with the current value of the main counter and the micro timer.

3.3.1.5 PEV1100 DMA operation

The **PEV_IOCTL_DMA_MOVE** request code allows to move data between a source and a destination space using the PEV1100 embedded DMA engines.

Data transfer operations using the DMA engines are performed using the *pev_ioctl_dma_req* data structure as argument.

```
struct pev_ioctl_dma_req
{
  ulong src_addr;
  ulong des_addr;
  uint size;
  uchar src_space; uchar src_mode; uchar des_space; uchar des_mode;
  uchar start_mode; uchar end_mode; uchar intr_mode; uchar wait_mode;
  uint dma_status;
};
```

The *src_addr* shall be initialized by the calling application with the bus address of the source buffer.

The *des_addr* shall be initialized by the calling application with the bus address of the destination buffer.

The *size* field shall be initialized by the calling application with the size of the requested transfer. For a block transfer (see *start_mode*), the size maximum is 0xff800. For a list transfer, the maximum number of element in the list is 63.

```
DMA_SIZE_MAX_BLK → maximum block size
DMA_SIZE_MAX_LIST → maximum list size
```

The *src_space* and *des_space* shall be initialized by the calling application with the source and destination spaces. The following values are accepted:

```
DMA_SPACE_PCIE

DMA_SPACE_SHM

DMA_SPACE_VME | DMA_VME_A16

DMA_SPACE_VME | DMA_VME_A24

DMA_SPACE_VME | DMA_VME_A24

DMA_SPACE_VME | DMA_VME_A32

DMA_SPACE_VME | DMA_VME_A32

DMA_SPACE_VME | DMA_VME_SGL

DMA_SPACE_VME | DMA_VME_BLT

DMA_SPACE_VME | DMA_VME_BLT

DMA_SPACE_VME | DMA_VME_MBLT

DMA_SPACE_VME | DMA_VME_MBLT

DMA_SPACE_VME | DMA_VME_BLT

DMA_SPACE_VM
```

The *src_mode* and *des_mode* shall be used by the application to pass to the driver additional parameters associated to the source and destination spaces. For **DMA_PCIE_SPACE**, these fields allows to specify the traffic class and the number of outstanding read request:

```
DMA PCIE TCO
                 → Traffic Class 0
DMA PCIE TC1
                 → Traffic Class 1
DMA PCIE TC2
                 → Traffic Class 2
DMA PCIE TC3
                 → Traffic Class 3
DMA PCIE TC4
                 → Traffic Class 4
DMA PCIE TC5
                 → Traffic Class 5
                 → Traffic Class 6
DMA_PCIE_TC6
DMA PCIE TC7
                 → Traffic Class 7
DMA PCIE RR1
                 → 1 outstanding read request
DMA PCIE RR2
                 → 2 outstanding read request
DMA PCIE RR3
                 → 3 outstanding read request
```

The **start_mode** shall be set by the application to define the mode to be used for the data transfer. The following modes are supported:

```
DMA_MODE_BLOCK → move one block from src to des
DMA_MODE_LIST_RD → move a list of buffer pointed by src_addr to a destination buffer
```

If **DMA_MODE_LIST_RD** is selected, the *src_addr* parameter is expected to point on a list of *pev_ioctl_dma_list* data structure holding the transfer parameters:

```
struct pev_ioctl_dma_list
{
  ulong addr;
  uint size;
  uint mode;
};
```

In this case, the *size* parameter of the *pev_ioctl_dma_req* data structure shall be interpreted as the number of element in the transfer list (maximum 63). The exact meaning of the fields in the *pev_ioctl_dma_list* data structure depend on the value of the *src_space* parameter. For **DMA_VME_SPACE**, *addr* shall be the VME address, *size* the buffer size in byte and *mode*, the VME transfer mode (Address Modifier).

The *end_mode* shall be initialized to 0 by the calling application (reserved for future use)

The *intr_mode* shall be set to **DMA_INTR_ENA** if DMA interrupts must be enabled, else it shall be set to 0.

The *wait_mode* shall be set to **DMA_WAIT_INTR** if the system call must return when the DMA engine has stopped (at the end of transfer or in case of error). If set to 0, the driver return to the application after having started the DMA.

The *dma_status* field is updated by the driver before returning to the application.

The **PEV_IOCTL_BUF_ALLOC** request code allocates a data buffer in kernel space suitable for DMA access. It takes a **pev_ioctl_buf** data structure as argument.

```
struct pev_ioctl_buf
{
  int kmem_fd;
  uint size;
  void *b_addr;
  void *u_addr;
  void *k_addr;
};
```

The *size* field shall be initialized by the calling application with the size in byte of the requested buffer.

The driver updates the b_addr and k_addr fields with the bus and kernel addresses of the buffer actually allocated.

The bus address is the address used by the DMA engines to access the buffer.

The kernel address is used by the CPU while executing in kernel mode to access the buffer. That address shall be given in the *pev_ioctl_rdrw* data structure when using PEV_IOCTL_RDWR command to perform read/write access to that buffer.

The fields *kmem_fd* and *u_addr* are not used by the kernel but are provided to allow the application to perform a subsequent call to the mmap() function of the /dev/kmem device in order to map the buffer in user's space.

3.3.1.6 I2C

The PEV interface integrates an I2C controller to access I2C devices implemented on the board (PCIe switch, thermometers,...) or on carriers such XMC and FMC. The pev_ioctl_i2c data structure is used to exchange parameters and data between an application and the PEV device driver:

```
struct pev_ioctl_i2c
{
  uint device;
  uint cmd;
  uint data;
};
```

The I2C controller implement 4 hardware registers

- device register → select the target bus and address, access speed, data width, operation,...
 command register → command to be send to the device
- command register → command to be send to the device
 data read register → data received from the device
- data write register → data to be sent to the device

The **PEV_IOCTL_I2C_DEV_CMD** performs a command operation to the device identified in the *device* field. The command to be performed shall be loaded in the *cmd* field.

The **PEV_IOCTL_I2C_DEV_RD** performs a read operation to the device identified in the *device* field. The I2C register index shall be loaded in the *cmd* field. The data returned is loaded in the *data* field.

The **PEV_IOCTL_I2C_DEV_WR** performs a write operation to the device identified in the *device* field. The I2C register index shall be loaded in the *cmd* field. The data to be written shall be loaded in the *data* field.

3.3.1.7 FIFO

The PEV interface integrates 4 message passing FIFO for synchronization. FIFO operation are performed using the *pev_ioctl_fifo* data structure as argument.

The PEV_IOCTL_FIFO_INIT initialize and enable the 4 FIFOs. It does not take argument.

The **PEV_IOCTL_FIFO_STATUS** command shall be used to retreive the current status of the FIFO refered by the *idx* field (from 0 to 3) of the pev_ioctl_fifo data structure. After the call, the 32 bit *sts* field is updated with the current status of the FIFO:

```
    bit 0:7 → word count
    bit 8:15 → write index
    bit 16:13 → read index
    bit 24 → FIFO not empty
    bt 25 → FIFO full
    bit 31 → enable
```

The **PEV_IOCTL_FIFO_CLEAR** command shall be used to reset the FIFO refered by the *idx* field (from 0 to 3) of the pev_ioctl_fifo data structure.

The **PEV_IOCTL_FIFO_READ** command shall be used to read data from the FIFO refered by the *idx* field (from 0 to 3) of the pev_ioctl_fifo data structure. The data are copied in the buffer pointed by the *data* field. The *cnt* field defines the number of word to be read. If the number of word in the FIFO is less then *cnt*, all words are copied in the data buffer and the ioctl() call returns the number of word actually read. After the FIFO readout, the *sts* and *cnt* fields are updated.

The **PEV_IOCTL_FIFO_WRITE** command shall be used to write data to the FIFO referred by the *idx* field (from 0 to 3) of the pev_ioctl_fifo data structure. The data are taken from the buffer pointed by the *data* field.

The *cnt* field defines the number of word to write. If the number of word avialable in the FIFO is less then *cnt*, then words are copied until FIFO is full and the ioctl() call returns the number of word actually written in the FIFO. After the FIFO write, the *sts* and *cnt* fields are updated.

The **PEV_IOCTL_FIFO_WAIT_EF** command shall be used wait until the FIFO referred by the *idx* field (from 0 to 3) of the pev_ioctl_fifo data structure becomes not empty. A maximum wait time (in msec) can be given by the *tmo* field. If tmo is 0, the ioctl() call does not return until the FIFO contains at least one word. Before returning, the *sts* field is updated.

3.3.1.8 EVENT QUEUE

The PEV interface manages up to 64 interrupt sources handled by 4 interrupt controllers. These interrupts can be associated to "events" stored in an "event queue".

A user application can create dynamically an event queue to gather events it needs to manage. When a queue is created, the driver fills a *pev_iocrl_evt* data structue provided by the application. All data exchange between the application and the PEV device driver is done through that data structure. Each ioctl call takes a a pointer to that data structure as argument.

```
struct pev_ioctl_evt
{
  void evt_queue;    /* event queue handle */
  int src_id;    /* */
  int vec_id;    /* */
  int evt_cnt;    /* */
  int sig;    /* */
  int wait;    /* */
};
```

The **PEV_IOCTL_EVT_ALLOC** command creates an event queue. It takes a pointer to an empty pev_ioctl_evt data structure as argument. When the ioctl system call returns, the field *evt_queue* contains an handle to the event queue. That handle will be be the event queue reference for all subsequent ioctl calls.

A event queue can be associated to a Linux signal (usually SIGUSR or SIGUSR2). Each time the event queue becomes non-empty, the signal is sent to the task. When creating the queue, the field *sig* of the *pev_ioctl_evt* data structure shall be initialize with the signal number to be used. If it is set to 0, no signal mechanism is used. This mechanism is implemented to allow a task to us the sig_action system call to wake up a event handled every time an event is loaded in the queue.

Before exiting, the user application shall give back the queue to the driver using the **PEV_IOCTL_EVT_FREE** command.

When a queue has been creation, events can be registered to be stored in that queue using the **PEV_IOCTL_EVT_REGISTER** command. The field *src_id* shall be set to defined the interrupt source associated to the event the application needs to handle. If a interrupt source is register in one queue, it cannot be registered in another queue.

Event can be unregistered from the queue using the PEV_IOCTL_EVT_UNREGISTER command.

When a set of events have been registered in a queue, the queue should be "enabled" in order to start accepting registered events. This is done using the **PEV_IOCTL_EVT_ENABLE** command. As sson this command has been executed, when a registered event is generated, its source and vector identifier are stored in the queue.

When an interrupt has been detected and the corresponding event stored in the queue, the interrupt source stay masked until unmasked by the application using **PEV_IOCTL_EVT_UNMASK** command. After enabling, all registered events are unmasked by default.

At any time the application can mask an interrupt source using the **PEV_IOCTL_EVT_MASK** command. This can be done before enabling the queue if the application does not want to handle immediately some of the registered events.

The application can suspend event handling at any time using the **PEV_IOCTL_EVT_DISABLE** command.

The application can remove the "oldest" event from the queue using the **PEV_IOCTL_EVT_READ** command. If the queue is non empty, the src_id and vec_id fields of the pev_ioctl_evt data structure are update with the source and vector identifier of the event. The evt_cnt contains the number of event left in the queue after the current one has been removed. If the queue is empty, the wait field defines if the system call shall wait until an event or a timeout occurs. It shall contain a timeout value in msec. If the wait is equal to 0, the call returns immediately. It it is equal to -1 it waits forever until an event occurs. Otherwise if wait for a maximum time defined by the timeout value. If no event is present in the queue, src_id is set to 0.

3.3.2 **Mmap**

The mmap function allows to map the PEV1100 PCI MEM and PMEM address space in the application space.

3.3.3 Interrupt handling

The PEV1100 uses PCI Express Message Signaled Interrupts (MSI) to notify the host of the occurrence of asynchronous events.

3.4 PEV1100 Kernel Library

The PEV1100 kernel library implements a set of low levels functions used to handle the PEV1100. That library is part of the PEV1100 linux module. Each function takes as first argument a pointer to the pev_dev data structure.

```
void pev_irq_register(struct pev_dev *, int, void (*)( struct pev_dev*, int, void *),
int pev_rdwr(struct pev_dev *, struct pev_ioctl_rdwr *);
void pev_sflash_id(struct pev_dev *, unsigned char *, uint);
unsigned short pev_sflash_rdsr(struct pev_dev *, uint);
void pev sflash wrsr(struct pev dev *, unsigned short, uint);
int pev_sflash_read(struct pev_dev *, struct pev_ioctl_sflash_rw *);
int pev_sflash_write(struct pev_dev *, struct pev_ioctl_sflash_rw *);
int pev fpga load(struct pev dev *, struct pev ioctl sflash rw *);
int pev idt_eeprom_read(struct pev_dev *, struct pev_ioctl_rdwr *);
int pev_idt_eeprom_write(struct pev_dev *, struct pev_ioctl_rdwr *);
int pev map init(struct pev dev *, struct pev ioctl map ctl *);
int pev_map_alloc(struct pev_dev *, struct pev_ioctl_map_pg *);
int pev_map_free(struct pev_dev *, struct pev_ioctl_map_pg *);
int pev_map_modify(struct pev_dev *, struct pev_ioctl_map_pg *);
int pev_map_find(struct pev_dev *, struct pev_ioctl_map_pg *);
int pev_map_read(struct pev_dev *, struct pev_ioctl_map_ctl *);
int pev_map_clear(struct pev_dev *, struct pev_ioctl_map_ctl *);
int pev map set sg(struct pev dev *, struct pev ioctl map ctl *, uint);
int pev_map_clear_sg(struct pev_dev *, struct pev_ioctl_map_ctl *, uint);
void pev_sg_master_32_set(struct pev_dev *, uint, ulong,
void pev sg master 64 set(struct pev dev *, uint, ulong, uint);
void pev_sg_slave_vme_set(struct pev_dev *, uint, ulong,
void pev_i2c_dev_cmd(struct pev_dev *, struct pev_ioctl_i2c *);
void pev_i2c_dev_read(struct pev_dev *, struct pev_ioctl_i2c *);
void pev i2c dev write(struct pev dev *, struct pev ioctl i2c *);
void pev_i2c_pex_read(struct pev_dev *, struct pev_ioctl_i2c *);
void pev_i2c_pex_write(struct pev_dev *, struct pev_ioctl_i2c *);
void pev_vme_conf_read(struct pev_dev *, struct pev_ioctl_vme_conf *);
void pev_vme_conf_write(struct pev_dev *, struct pev_ioctl vme conf *);
uint pev_vme_crcsr(struct pev_dev *, struct pev_ioctl_vme_crcsr *);
uint pev vme crcsr(struct pev dev *, struct pev ioctl vme crcsr *);
uint pev vme rmw( struct pev dev *, struct pev ioctl vme rmw *);
uint pev_vme_lock( struct pev_dev *, struct pev_ioctl_vme_lock *);
uint pev_vme_unlock( struct pev_dev *);
uint pev vme slv init( struct pev dev *);
void pev_vme_irq( struct pev_dev *, int, void *);
uint pev_vme_irq_alloc( struct pev_dev *, struct pev_ioctl_vme_irq *);
uint pev vme irq arm( struct pev dev *, struct pev ioctl vme irq *);
```

```
uint pev_vme_irq_wait( struct pev_dev *, struct pev_ioctl_vme_irq *);
uint pev vme_irq_clear( struct pev_dev *, struct pev_ioctl_vme_irq *);
void pev vme irq init( struct pev dev *);
void pev_timer_irq( struct pev_dev *, int, void *);
void pev_timer_init( struct pev_dev *);
void pev_timer_read( struct pev_dev *, struct pev_ioctl_timer *);
int pev_timer_start( struct pev_dev *, struct pev_ioctl_timer *);
void pev_timer_restart( struct pev_dev *);
void pev timer stop( struct pev dev *);
void pev_timer_irq_ena( struct pev_dev *);
void pev_timer_irq_dis( struct pev_dev *);
void pev_fifo_irq(struct pev_dev *, int, void *);
void pev fifo init(struct pev dev *);
void pev_fifo_status( struct pev_dev *, struct pev_ioctl_fifo *);
void pev_fifo_clear( struct pev_dev *, struct pev_ioctl_fifo *);
int pev_fifo_wait_ef( struct pev_dev *, struct pev_ioctl_fifo *);
int pev_fifo_wait_ff( struct pev_dev *, struct pev_ioctl_fifo *);
int pev_fifo_read( struct pev_dev *, struct pev_ioctl_fifo *);
int pev_fifo_write( struct pev_dev *, struct pev_ioctl_fifo *);
void pev_dma_irq( struct pev_dev *, int, void *);
void pev_dma_init( struct pev_dev *);
void pev_dma_exit( struct pev_dev *);
int pev_dma_move( struct pev_dev *, struct pev_ioctl_dma_req *);
int pev_dma_status( struct pev_dev *, struct pev_ioctl_dma_sts *);
```

3.5 PEV1100 User's Library

The user library interfaces applications with the PEV device driver. It expects the device <code>/dev/pevX</code> (where X is the crate number) to be existing with with read/write access for the user executing the application linked to the library. Compatibility with previous release of the library (single crate version) is obtained by setting the crate number to 0.

A multicrate interface is also provided in which function takes the crate number as first parameter and are labeled *pevx_xxx_yyy(crate, ...)*. When the multicrate version of the function is invoked, it checks if the initialization function for that crate has been called and returns an error if not.

Basically the library functions re-package user's parameters in a data structure ready to be passed to the driver *ioctl()* functions. If not otherwise stated, library functions returns the value returned by the corresponding *ioctl()* call.

3.5.1 Initialization

To be allowed to call functions defined in pevulib.a, the application shall first call an initialization function performing the open of the driver and initializing the library private data structure.

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  struct pev node
   *pev init( int crate)
or
  *pevx_init( int crate)
Description
  That function must be called by the application before invoking any other
  function belonging to the PEV1100 user's library. Among other things, it
  performs an open of the /dev/pevX (where X is the crate number) device and
  return the file descriptor in the pev node data structure. This file
  descriptor can be used by the application for direct call to the pev device
  driver functions. When installing the driver, the script load in the
  modules directory creates automatically the /dev/pevX (X going from 0 to
  15) device nodes.
  Compatibility with older version of that library is obtained by choosing {\tt 0}
  as crate number.
<u>Parameters</u>
              crate number as set by the rotary switch located on the PEV1100
  crate
Return
          pointer to a pev node data structure
  pev
          pev->fd
                        pev file descriptor (returned by the open call)
          Cannot open PEV1100 device driver
  NULL
```

In multicrate configuration, the *pev_init(crate)* or *pevx_init(crate)* function shall be called for each crate to be accessed. If the single crate version of the library is used, the function *pev_set_crate(crate)* shall be called to make sure subsequent function calls will be targeted to the PEV1100 having *crate* as node number.

Prototype

*pev_set_crate(int crate)

Description

Set the default node number used by library function calls to crate.

<u>Parameters</u>

crate crate number as set by the rotary switch located on the PEV1100

Return

pointer to the pev_node data structure if pev_init() has been successfully called previously.

NULL in case of error (non initialized node).

3.5.2 Register access

A set of functions allows applications to perform read and write access on the PEV1100 control and status registers mapped in the PCI IO space.

3.5.2.1 CSR Read

Prototype

```
#include <pevulib.h>
or
    #include <pevxulib.h>
    int
    pev_csr_rd( int idx)
or
    pevx csr rd( int crate, int idx)
```

<u>Description</u>

Perform a 32 bit read cycle in the PEV PCI IO space in order to return the current value of the control and status register whose offset is equal to bit 0:12 of the idx parameter.

If bit 31 of the idx parameter is set, the PCI MEM space window, if available, is used to access de register. This is useful when the PCI IO window is configured in short addressing mode and not all registers are directly accessible through that window.

<u>Parameters</u>

idx register index (address offset in PCI IO window)

Return

register current value

3.5.2.2 CSR Write

Prototype

```
#include <pevulib.h>
  #include <pevxulib.h>
  void
  pev csr wr( int idx,
              int data);
  pevx csr wr( int crate
               int idx,
               int data);
Description
  Perform a 32 bit write cycle in the PEV1100 PCI IO space in order to set
  the current value of the control and status register whose offset is equal
  to the idx parameter.
  If bit 31 of the idx parameter is set, the PCI MEM space window, if
  available, is used to access de register. This is useful when the PCI IO
  window is configured in short addressing mode and not all registers are
  directly accessible through that window.
Parameters
  idx register index (address offset in PCI IO window)
  data 32 bit value to write in register
Return
  None
```

3.5.2.3 **CSR Set**

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  void
  pev_csr_set( int idx,
               int data);
  pevx_csr_set( int crate,
                int idx,
                int data);
Description
  Perform a 32 bit read cycle followed by a 32 bit write cycle in the PEV1100
  PCI IO space in order to set the value of the control and status register
  whose offset is equal to the idx parameter. The value written in the
  register is the bitwise OR between the result of the read cycle and the
  data parameter. This is equivalent to perform the following operation:
  pev_csr_wr( idx, data | pev_csr_rd( idx)).
  That function is useful to reset status bit in registers where they have to
  be overwritten to be cleared.
  If bit 31 of the idx parameter is set, the PCI MEM space window, if
  available, is used to access de register. This is useful when the PCI IO
  window is configured in short addressing mode and not all registers are
```

```
Parameters

idx register index (address offset in PCI IO window)
data bit field (32 bit) holding the bit to be set in the register

Return

none
```

3.5.3 Generic read/write

The generic read/write function allows to move data between the application address space and the physical resources located on the PEV1100.

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
or
  #include <pevioctl.h>
  pev rdwr( struct pev ioctl rdwr *rdwr p)
  pevx rdwr( struct pev ioctl rdwr *rdwr p)
  That function allows to move data between a buffer allocated in the
  application space and a PEV1100 physical resource. Basically it performs an
  ioctl() call with the PEV IOCTL RDWR request code (see §3.3.1.1). The
  argument shall be a pointer to an pev_ioctl_rdwr data structure initialized
  with the transfer parameters.
Parameters
  rdwr_p pointer to a pev_ioctl_rdwr data structure initialized with the
          transfer parameters.
                             pointer to the data buffer in user's space
          rdwr p->buf
                              offset in the PEV1100 resource address space
          rdwr_p->offset
          rdwr p->len
                              size in byte of the data transfer
          rdwr p->mode.ds
                              data size
                RDWR BYTE → 8 bit access (byte)
                RDWR SHORT → 16 bit access (short)
                RDWR INT → 32 bit access (int)
                RDWR LONG → 64 bit access (long)
                              swapping mode
          rdwr p->mode.swap
                 RDWR NOSWAP → no swapping
                 RDWR SWAP → swapping
          rdwr p->mode.dir
                              transfer direction
                 RDWR READ → from PEV1100 to local memory (read)
                 RDWR_WRITE → from PEV1100 to local memory (write)
```

```
rdwr p->mode.space PEV1100 address space
                RDWR PCIE CFG → FPGA End point PCI configuration space
                RDWR_PCIE_IO → FPGA End point PCI IO window (BAR#4)
                RDWR PCIE MEM → FPGA End point PCI MEM window (BAR#2)
                RDWR PCIE PMEM → FPGA End point PCI PMEM window (BAR#0)
                RDWR CSR
                           → FPGA End point PCI CSR window (BAR#3)
                RDWR PEX MEM → PEX8624 PCI MEM window (BAR#2)
                RDWR KMEM
                              → HOST kernel space (DMA buffer)
                              Kernel address of DMA buffer (if RDWR KMEM)
          rdwr_p->k_addr
Return
  0
          Data transfer successful
  < 0
          See ioctl() error codes
```

3.5.4 PEV1100 Resource Mapping

Basically the PEV1100 acts as a bridge between the following address space

- · PCI tree
- VME bus
- · Shared Memory
- · FPGA user's area

Going from one space to another implies the initialization of address translation tables in order to map source addresses to destination addresses. A set of functions allows application to dynamically create, modify, and destroy these address translation windows.

The PEV1100 hardware offers three address translation tables. The first two allows the local host to perform data cycles from the PCI MEM and PMEM spaces targeted to the VME bus, shared memory and FPGA user's space. The third one allows a VME master to perform data cycle from the VME bus (through the PEV1100 A32 slave port) targeted to the PCI tree, shared memory and FPGA user's area. Each table can contain multiple translation windows. The address allocator in the pev device driver uses a search algorithm designed to maximize the number of windows one can create and allows to share the same window among different applications.

3.5.4.1 Allocating a new address translation window

```
#include <pevulib.h>
or
    #include <pevxulib.h>
#include <pevioctl.h>

void
    pev_map_alloc( struct pev_ioctl_map_pg *map_p)
or
    pevx_map_alloc( int crate, struct pev_ioctl_map_pg *map_p)

Description
That function allows to create an address window in a local space pointing to a remote area in a destination space specified in the mode field of the
```

```
mapping data structure given as parameter.
Parameters
  map p
          pointer to a pev_ioctl_map_pg data structure initialized with the
           mapping parameters.
                               base address of remote area to be mapped
          map p->rem addr
          map_p->size
                                Size (in bytes) of remote area to be mapped
                                Identifier of mapping table to be used
          map p->sg id
                 MAP MASTER 32 → mapper for PCI MEM window in FPGA End Point
                 MAP_MASTER_64 → mapper for PCI PMEM window in FPGA End Point
                 MAP SLAVE VME → mapper for VME slave A32 window
           map p->mode
                                Mapping mode (16 bit)
                 {\it MAP SPACE PCIE} \rightarrow {\it PCI} Express tree is the destination space
                 MAP SPACE VME → VME bus is the destination space
                 MAP SPACE SHM → Shared Memory is the destination space
                 MAP SPACE SHM1 → Shared Memory #1 is the destination space
                 MAP SPACE SHM2 → Shared Memory #2 is the destination space
                 MAP SPACE USR → FPGA user space is the destination
                 MAP_SPACE_USR1 → FPGA user space #1 is the destination
                 MAP SPACE USR2 → FPGA user space #2 is the destination
                 MAP ENABLE
                                 → Enable address translation
                 MAP ENABLE WR → Enable write accesses
                MAP_VME_USR
                                 \rightarrow if VME space perform user access
                 MAP VME SP
                                 \rightarrow if VME space perform supervisor access
                 MAP VME A16
                                 → if VME space perform A16 address cycles
                 MAP VME A24
                                 → if VME space perform A24 address cycles
                 MAP_VME_BLT → if VME space perform BLT address cycles
MAP_VME_MBLT → if VME space perform MDT.
                                 → if VME space perform MBLT address cycles
                 MAP VME 2eSST → if VME space perform A16 address cycles
Return
  0
          Mapping successful
          pev ioctl map pg data structure has been updated with the mapping
          parameters.
          map_p->loc addr
                                Address offset in local space mapping rem addr
                                Page offset in translation table used to create
          map p->offset
                                the address mapping
                                Actual window size (in bytes) allocated for the
          map p->win size
                                mapping
                                Remote address of window base
          map p->rem base
                                Local address of window base
          map p->loc base
          Mapping not successful
```

3.5.4.2 Freeing a previously allocated address translation window

Prototype

```
#include <pevulib.h>
  #include <pevxulib.h>
  #include <pevioctl.h>
  void
  pev_map_free( struct pev_ioctl_map_pg *map_p)
  pevx map free( int crate, struct pev ioctl map pg *map p)
Description
  That function free a mapping window previously allocated by a call to
  pev_map_alloc(). The field sg_id and offset of the pev_ioctl_map_pg data
  structure are used by the pev driver to identify the window to be freed.
Parameters
          pointer to a pev ioctl map pg data structure initialized with the
  map p
          mapping parameters.
          map p->offset
                           Offset (as returned by pev map alloc()) of mapping
                           window to be freed
                          Identifier of mapping table to be used
          map_p->sg_id
<u>Return</u>
  0
          Mapping window successfully freed
  -1
          Invalid mapping window parameters
```

3.5.4.3 Modifying a previously allocated address translation window

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
   #include <pevioctl.h>
  pev_map_modify( struct pev_ioctl_map_pg *map_p)
  pevx_map_modify( int crate, struct pev_ioctl_map_pg *map_p)
<u>Description</u>
  That function modifies a mapping window previously allocated by a call to
  {\tt pev\_map\_alloc()}. The field {\tt sg\_id} and offset of the {\tt pev\_ioctl\_map\_pg} data
  structure are used by the pev driver to identify the window to be modified.
Parameters
  map_p
         pointer to a pev_ioctl_map_pg data structure initialized with the
           mapping parameters.
                            Offset (as returned by pev_map_alloc()) of mapping
           map p->offset
```

3.5.4.4 Getting a list of all allocated address translation windows

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  #include <pevioctl.h>
  int
  pev_map_read( struct pev_ioctl_map_ctl *ctl_p)
  pevx_map_read( int crate, struct pev_ioctl_map_ctl *ctl_p)
Description
  That function updates the pev_ioctl_map_ctl data structure with the
  control parameters of the translation table identified by the sg id field.
<u>Parameters</u>
  ctl p
          pointer to a pev_ioctl_map_ctl data structure.
           ctl p->sg id
                           Identifier of mapping table
                           Pointer to a pev\_map\_blk[] data structure big enough
           ctl p->map
                           to hold a full image of the address translation
                           table. The size of that table shall be equal to
                           ctl p->pg num * ctl p->pg size
                           If that pointer is set to NULL, only control fields
                           in the pev_ioctl_map_ctl data structure are
                           updated.
Return
  0
          pev_ioctl_map_pg data structure pointed by ctl_p parameter has been
           updated with the table control parameters.
                           Number of pages in the address translation table
           ctl p->pg num
           ctl p->pg size Page size
          ctl p->loc addr Local address of the first address translation
                           window in the table.
          If table identifier is invalid
  -1
```

3.5.4.5 Clearing all allocated address translation windows

3.5.4.6 Mapping an allocated address translation window in user's space

```
#include <pevulib.h>
or
    #include <pevulib.h>
    #include <pevxulib.h>
    #include <pevioctl.h>

void
    *pev_mmap( struct pev_ioctl_map_pg *map_p)
or
    *pevx_mmap( int crate, struct pev_ioctl_map_pg *map_p)

Description
    That function maps in user's space an address translation window previously allocated by a call to pev_map_alloc(). The mmap() sytem call is performed with map_p->rem_addr as offset parameter and map_p->size as length parameter. The prot and flags parameter are set to PROT_READ | PROT_WRITE and MAP_SHARED.
```

3.5.5 DMA operations

Buffer suitable for DMA access shall be allocated using special kernel function to make sure they are locked in memory and visible from the PCI Express. This operation is done by the device driver using the PEV_IOCTL_BUF_ALLOC ioctl() command.

Once a buffer has been allocated, its kernel address can be used to map it in user's space using the /dev/kmem device. That operation can only be done in superuser mode.

3.5.5.1 Allocating a buffer in system memory suitable for DMA

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  #include <pevioctl.h>
  pev buf alloc( struct pev ioctl buf *buf p)
or
  pevx buf alloc( int crate, struct pev ioctl buf *buf p)
Description
  That function updates the {\it pev\_ioctl\_buf} data structure with the parameters
  of the buffer allocated by the kernel in system memory.
<u>Parameters</u>
  buf p pointer to a pev ioctl buf data structure.
          buf p->size
                           Size of the buffer to be allocated
Return
  0
          pev ioctl buf data structure pointed by buf p parameter has been
          updated with the buffer parameters.
          buf p->k addr
                           Buffer kernel address (suitable for subsequent call
                            to mmap() function using /dev/kmem device)
          buf p->b addr
                           Buffer bus address (suitable for DMA parameters)
```

```
-1 Buffer was not allocated
```

3.5.5.2 Freeing an allocated buffer

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  #include <pevioctl.h>
  void
  pev buf free( struct pev ioctl buf *buf p)
  pevx buf free( int crate, struct pev ioctl buf *buf p)
Description
  That function free a buffer previously allocated by a call to
  pev_buf_alloc().
<u>Parameters</u>
  buf p
          pointer to a pev ioctl buf data structure initialized with the
          buffer parameters.
          buf p->k addr
                           Kernel address (as returned by pev buf alloc()) of
                           the buffer to be freed
                           Bus address (as returned by pev_buf_alloc()) of the
          buf_p->b_addr
                           buffer to be freed
          buf p->size
                           Size (as returned by pev buf alloc()) of the buffer
                           to be freed
Return
  0
          Buffer successfully freed
          Invalid buffer parameters
  -1
```

3.5.5.3 Performing a DMA transfer

```
#include <pevulib.h>
or
    #include <pevxulib.h>
    #include <pevxulib.h>
    #include <pevioctl.h>

void
    pev_dma_move( struct pev_ioctl_dma_req *req_p)
or
```

```
pevx_dma_move( int crate, struct pev_ioctl_dma_req *req_p)
  This is the generic function to perform DMA transfers. Transfer parameters
  shall be loaded in the pev_ioctl_dma_req data structure.
Parameters
           pointer to a pev ioctl dma req data structure initialized with the
  req_p
           transfer parameters.
                               DMA transfer destination address
           req p->des addr
           req p->des space DMA transfer destination space
                  DMA_SPACE_PCIE → PCI Express
                  DMA SPACE VME → VME bus
                  DMA SPACE SHM → shared memory
                  DMA SPACE WS → 16 bit byte swapping (OR with DMA SPACE XXX)
                  DMA SPACE DS → 32 bit byte swapping (OR with DMA SPACE XXX)
                  DMA_SPACE_QS \rightarrow 64 bit byte swapping (OR with DMA_SPACE_XXX)
                  DMA_VME_A16 \rightarrow VME A32 single transfer DMA_VME_A24 \rightarrow VME A32 single transfer
                  DMA VME A32 → VME A32 single transfer
                  DMA VME BLT → VME block transfer
                  DMA VME MBLT → VME MBLT
                  DMA VME 2eVME → VME 2eVME
                  DMA\_VME\_2eFAST \rightarrow VME\ 2eVME\ fast
                  DMA_VME_2e160 \rightarrow VME 2eSST 160 MBytes/sec DMA_VME_2e233 \rightarrow VME 2eSST 233 MBytes/sec DMA_VME_2e320 \rightarrow VME 2eSST 320 MBytes/sec
           req p->des mode
                              DMA transfer destination mode
                  DMA PCIE TCO → PCI Express Traffic Class O
                  DMA PCIE TC1 → PCI Express Traffic Class 1
                  DMA_PCIE_TC2 → PCI Express Traffic Class 2
                  DMA PCIE TC3 → PCI Express Traffic Class 3
                  DMA PCIE TC4 → PCI Express Traffic Class 4
                  DMA PCIE TC5 → PCI Express Traffic Class 5
                  DMA PCIE TC6 → PCI Express Traffic Class 6
                  DMA PCIE TC7 → PCI Express Traffic Class 7
                  DMA PCIE RR1 → PCI Express 1 outstanding request
                  DMA_PCIE_RR2 → PCI Express 2 outstanding request
                  DMA_PCIE_RR3 → PCI Express 3 outstanding request
                  DMA VME SWAP \rightarrow big/little endian byte swapping
           req p->src addr
                              DMA transfer source address
           req p->src space DMA transfer source space
                               DMA transfer source mode
           req p->src mode
           req p->size
                               DMA transfer size (in bytes)
           req p->start mode DMA starting mode
                  DMA MODE BLOCK → block transfer
                  DMA MODE PIPE
                                   → read/write are pipelined (only for VME)
           req p->intr mode Interrupt mode
                  DMA INTR ENA
                                   → enable interrupt
           req p->wait mode Wait mode
                   DMA WAIT INTR → wait for interrupt
Return
```

```
    0 DMA transfer ended
    -1 Invalid transfer parameters
```

3.5.5.4 Reading a list of buffer from VME using DMA

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  #include <pevioctl.h>
  pev dma vme list rd( void *uaddr,
                       struct pev ioctl dma list *list p,
                       int size)
or
  pevx dma vme list rd( int crate,
                        void *uaddr,
                        struct pev_ioctl_dma_list *list p,
                        int list size)
Description
  That function takes as input a list of VME read transfer to be executed by
  the DMA engine. Data collected are pushed sequentially in a buffer
  provided by the application.
  Any VME address boundary and size are supported in the list parameters.
  However, physical transfers on the VME are always performed with 64 bits (8
  bytes) alignment. Unrequested data are then trowed away before filling the
  user's buffer.
  The function returns when all requested data have been copied in the user's
  buffer.
Parameters
  uaddr
            Pointer (void *) to the destination address (buffer address in
            user's space)
            pointer to a list of pev_ioctl_dma_list data structures
  list p
            initialized with the VME transfer parameters.
            list p->addr
                            DMA transfer source address (VME address)
            list p->size
                           DMA transfer size (in bytes)
            list_p->mode
                           DMA transfer mode (VME Address Modifier)
                   DMA VME A16 → VME A32 single transfer
                   DMA VME A24 → VME A32 single transfer
                   DMA_VME_A32 → VME A32 single transfer
                   DMA VME BLT
                                 → VME block transfer
                   DMA VME MBLT \rightarrow VME MBLT
                   DMA VME 2eVME → VME 2eVME
                   DMA VME 2eFAST → VME 2eVME fast
                   DMA VME 2e160 → VME 2eSST 160 MBytes/sec
                   DMA_VME_2e233 → VME 2eSST 233 MBytes/sec
                   DMA_VME_2e320 → VME 2eSST 320 Mbytes/sec
  list size VME list size (number of elements in the list pointed by list p)
```

Return 0 DMA transfer ended -1 Invalid transfer parameters

3.5.6 VME Interface Configuration

3.5.6.1 Reading the VME current configuration

```
Prototype
  #include <pevulib.h>
or
  #include <pevxulib.h>
  void
  pev_vme_conf_read( struct pev_ioctl_vme_conf *vc_p)
  pevx_vme_conf_read( int crate, struct pev_ioctl_vme_conf *vc_p)
Description
  Read the PEV1100 VME interface current configuration.
  All hardware registers related to the VME interface configuration are read
  and the data structure pointed by vc p is updated accordingly.
Parameters
          Pointer to a pev ioctl vme conf data structure
  vc p
Return
  0
           The pev ioctl vme conf data structure pointed by parameter vc p has
          been updated with the current status of vme interface
          vc p->a24 base VME base address of A24 slave window (CR/CSR)
          vc p->a24 size
                            Size of A24 slave window (CR/CSR)
          vc p->a32 base
                            VME base address of A32 slave window
          vc p->a32 size
                            Size of A32 slave window
          vc p->x64
                            Set to 1 if VME64x enabled, else 0
                            Set to 1 if System Controller enabled, else 0
          vc p->slot1
          vc_p->sysrst
                            Set to 1 if SYSRST transmission enabled, else 0
          vc p->rto
                            Retry time out in usec (512 usec or disabled)
          vc p->arb
                            VME arbitration mode (valid if Slot 1)
          vc p->bto
                            VME bus time out in usec (valid if Slot 1)
                            VME request mode
          vc p->req
                            VME request level
          vc p->level
                            Set to 1 if VME master enabled, else 0
           vc p->mas ena
```

```
vc_p->slv_ena Set to 1 if VME slave enabled, else 0
vc_p->slv_retry If set to 1, do not use VME Slave Retry
vc_p->burst Write postin burst size (VME slave)
```

3.5.6.2 Setting a new VME Configuration

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  pev_vme_conf_read( struct pev_ioctl_vme_conf *vc_p)
  pevx_vme_conf_read( int crate, struct pev_ioctl_vme_conf *vc_p)
Description
  Sets the hardware registers controlling the VME interface according to the
  parameters found in the pev ioctl vme conf data structure. To change only
  a subset of the configuration parameters, first call pev_vme_conf_read() to
  fill the data structure with the current configuration, modify it and call
  pev vme conf write().
  To map the VME slave window with a 1 Mbytes granularity, bit 3 of the
  slv ena field shall be set to 1.
Parameters
          vc p shall point to a pev ioctl vme conf data structure used to
  vc_p
          update the hardware registers controlling the VME interface
          vc p->a32 base
                            VME base address of A32 slave window
          vc p->a32 size
                            Size of A32 slave window
                            Retry time out in usec (512 usec or disabled)
          vc p->rto
                            VME arbitration mode (valid if Slot 1)
          vc p->arb
                            VME bus time out in usec (valid if Slot 1)
          vc_p->bto
                            VME request mode
          vc p->req
          vc p->level
                            VME request level
                            Set to 1 if VME master enabled, else 0
          vc p->mas ena
                            Set bit 0 to 1 to enable VME slave, else set to 0
          vc_p->slv_ena
                            Set bit 3 to 1 to enable 1 Mbyte granularity
                           If set to 1, do not use VME Slave Retry
          vc p->slv retry
                            Write posting burst size (VME slave)
          vc p->burst
Return
```

3.5.6.3 VME interrupt initialization

```
#include <pevulib.h>
or
#include <pevulib.h>

void
pev_vme_irq_init()
or
pevx_vme_irq_init( int crate)

Description
That function initialize the interrupt handling mechanism for VME interrupts. The interrupt handler associated to 16 potential VME interrupt sources are installed and enabled.

Parameters
none

Return
none
```

3.5.6.4 VME CRCSR operation

```
set data to be used for the VME_CRCSR_SET operation
clear data to be used for the VME_CRCSR_CLEAR operation
operation operation to be performedmbitwise OR of:
VME_CRCSR_GET, VME_CRCSR_SET, VME_CRCSR_CLEAR

Return

0 if OK
-1 if error
```

3.5.6.5 VME Read/Modify/Write

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
  void
  pev_vme_rmw( struct pev_ioctl_vme_rmw *rmw_p)
or
  pevx_vme_rmw( int crate, struct pev_ioctl_vme_rmw *rmw_p)
<u>Description</u>
  That function performs a read/modify/write operation. It takes a pointer to
  a pev ioctl vme rmw data structure as argument. The application shall fill
  that structure with
  - the VME address (addr) and access mode (ds and am)
  - the value to be used for update (up)
  - the compare value (cmp)
<u>Parameters</u>
          pointer to a pev ioctl vme rmw data structure
  rmw_p
           status
                   status of the operation (updated by the driver)
           addr
                    VME address
           cmp
                    compare value
                    update value
           up
                    data size (1,2 or 4)
           ds
                    VME address modifier
Return
  none
```

3.5.6.6 VME Lock/Unlock

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  pev_vme_irq_lock( struct pev_ioctl_vme_lock *lock_p)
 pev_vme_irq_unlock( struct pev_ioctl_vme_lock *lock_p)
  pevx_vme_irq_unlock( int crate, struct pev_ioctl_vme_lock *lock_p)
Description
  That function .
<u>Parameters</u>
  lock_p pointer to a pev_ioctl_vme_lock data structure
         status
         addr
         mode
Return
  none
```

3.5.6.7 VME interrupt controller enable

```
Prototype

#include <pevulib.h>
or

#include <pevxulib.h>

void
    pev_vme_irq_enable()
or
    pevx_vme_irq_enable( int crate)

Description
    That function enable the interrupt handling mechanism for VME interrupts.

Parameters
    none
```

```
Return none
```

3.5.6.8 VME interrupt mask/unmask

```
Prototype
   #include <pevulib.h>
or
   #include <pevxulib.h>
  void
  pev_vme_irq_mask( uint im)
  pev_vme_irq_unmask( uint im)
  pevx_vme_irq_mask( int crate, uint im)
  pevx_vme_irq_unmask( int crate, uint im)
Description
  The function pev_vme_irq_mask() enable the interrupt sources associated to
  bit set in the im parameter.
  The function pev_vme_irq_unmask() disable the interrupt sources associated
  to bit set in the im parameter.
  These functions perform a direct write in the hardware interrupt mask
  registers.
Parameters
  im
         interrupt mask
Return
  none
```

3.5.6.9 VME interrupt allocate

```
#include <pevulib.h>
or
    #include <pevxulib.h>

struct pev_ioctl_vme_irq
    pev_vme_irq_allocate( uint is)
or
    pevx_vme_irq_allocate( int crate, uint is)
```

Description

The function $pev_vme_irq_allocate()$ allocates a control structure to allow the application to wait on a set of VME interrupts.

That function takes as argument a bit set representing the interrupt sources to be managed by the application.

If one of the interrupt source in the set is already manage by another application, the function returns an error.

The function returns a pointer to the control structure. That pointer shall be given as argument to other VME interrupt control functions

Parameters

is interrupt set

Return

3.5.6.10 VME interrupt free

Prototype

```
#include <pevulib.h>
or
    #include <pevxulib.h>

int
    pev_vme_irq_free( struct pev_ioctl_vme_irq)
or
    pevx_vme_irq_free( int crate, struct pev_ioctl_vme_irq)
```

Description

The function <code>pev_vme_irq_free()</code> frees a data structure previously allocated by <code>pev_vme_irq_allocate()</code>. The corresponding interrupt set is desactivated. Interrupts sources are disabled and made available for other applications. That function takes as argument a pointer to the allocated data structure. If the data structure contains invalid parameters, the function returns an error.

Parameters

<u>Return</u>

0 if OK

-1 if datat structure does not contain valid parameters

3.5.6.11 VME interrupt arm

```
Prototype
  #include <pevulib.h>
or
  #include <pevxulib.h>
  int
  pev_vme_irq_arm( struct pev_ioctl_vme_irq *irq)
  pevx_vme_irq_arm( int crate, struct pev_ioctl_vme_irq *irq)
  The function pev_vme_irq_arm() takes as argument a pointer to a control
  structure previously allocated by pev vme irq allocate(). The corresponding
  interrupt set is activated. Interrupts sources are enabled.
Parameters
         pointer to the allocated control structure (fields shall not be
          directly modified by the application)
Return
  0
          if OK
          if datat structure does not contain valid parameters
  -1
```

3.5.6.12 VME interrupt wait

```
#include <pevulib.h>
or
    #include <pevulib.h>
int
    pev_vme_irq_wait( struct pev_ioctl_vme_irq *irq, uint tmo, uint *vector)
or
    pevx_vme_irq_wait( int crate, struct pev_ioctl_vme_irq *irq, uint tmo, uint *vector)

Description
The function pev_vme_irq_wait() returns when an interrupt belonging to the set associated to irq has fired.
If tmo is non 0, the function return after tmo msec if no interrupt sources
```

has fired. In this case **vector** is loaded with <code>0xffffffff</code>. If one of the 7 VME IRQ has fired, the VME IACK cycle is generated and the interrupt vector is loaded in the 32 bit integer pointed by vector.

Parameters

irq pointer to the allocated control structure (fields shall not be

directly modified by the application)

tmo timeout in msec

vector pointer to a 32 bit integer to hold VME IVEC

<u>Return</u>

0 if OK

-1 if datat structure does not contain valid parameters

3.5.6.13 VME interrupt armwait

Prototype

#include <pevulib.h>

or

#include <pevxulib.h>

int

pev_vme_irq_armwait(struct pev_ioctl_vme_irq *irq, uint tmo, uint *vector)

 $\label{eq:pevx_vme_irq_armwait} \textit{(int crate, struct pev_ioctl_vme_irq *irq, , uint tmo, uint *vector)}$

Description

The function <code>pev_vme_irq_armwait()</code> takes as argument a pointer to a control structure previously allocated by <code>pev_vme_irq_allocate()</code>. The corresponding interrupt set is activated and interrupts sources are enabled.

The function return when one of the interrupt belonging to the set has fired.

If **tmo** is non 0, the function return after **tmo** msec if no interrupt sources has fired. In this case **vector** is loaded with 0xffffffff.

If one of the 7 VME IRQ has fired, the VME IACK cycle is generated and the interrupt vector is loaded in the 32 bit integer pointed by vector.

Parameters

irq pointer to the allocated control structure (fields shall not be

directly modified by the application)

tmo timeout in msec

vector pointer to a 32 bit integer to hold VME IVEC

Return

0 if OK

```
-1 if datat structure does not contain valid parameters
```

3.5.7 PEV1100 SFLASH Access

The <code>pev_sflash_xxx()</code> set of functions allows to read/write from/to the SFLASH device. Be aware that the SFLASH device is accessed bit per bit from the CPU through a serial link. Operations are then very slow and consume all CPU resources. This means that during SFLASH operation the linux system will be almost frozen. Programing one sector (256 kbytes) takes about 15 seconds.

3.5.7.1 SFLASH identification

```
#include <pevulib.h>
or
    #include <pevulib.h>
int
    pev_sflash_id( char *id)
or
    pevx_sflash_id( int crate, char *id)

Description
    Fill the string pointed by id with the SFLASH 3 bytes hardware identifier

Parameters
    id    pointer to a 4 bytes string

Return
    0    if OK
    -1    if error
```

3.5.7.2 SFLASH read

```
Description

Copy len byte from a data buffer pointed by addr in SFLASH at offset offset.

Parameters

offset offset in SFLASH where the data are to be read from addr address of the buffer where the data are to be copied len number of bytes to by copied

Return

0 in case of success
-1 in case of error
```

3.5.7.3 SFLASH write

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
  void
  pev_sflash_write( uint offset,
                     void *addr,
                     uint len)
or
  pevx_sflash_write( int crate,
                      uint offset,
                      void *addr,
                     uint len)
Description
  Copy {\it len} byte from a data buffer pointed by {\it addr} in SFLASH at offset
  offset.
Parameters
  offset offset in SFLASH where the data are to be copied
  addr
           address of the buffer containing the data to be copied
           number of bytes to by copied
  len
Return
  0
         in case of success
  -1
         in case of error
```

3.5.8 PEV1100 timer functions

The PEV1100 FPGA implements a local timer driven by one of the following synchronization sources:

- a 1 KHz local clock
- VME SYSFAIL
- VME IRQ1
- VME IRQ2

The main counter is incremented by the selected synchronization source giving the main tick. The occurrence

of the tick can generate an interrupt to the local host.

A free running micro timer driven by a local clock (programmable frequency from 1 MHz to 125 MHz) is reset to 0 at each occurrence of the the main tick .

When the main counter is read, the current value of the micro timer is catch in order to provide an accurate (up to 8 nsec resolution) timing measurement.

3.5.8.1 Starting the timer

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
   void
  pev timer start( int mode,
                     int msec)
  pevx_timer_start( int crate,
                       int mode,
                      int msec)
Description
  Start the PEV1100 local timer in an operating mode defined by the mode
  parameter. The main counter is preloaded with the value of msec parameter.
Parameters
  mode
           Timer mode of operation. Allow to set the synchronization source,
           frequency and output mode.
                                 → micro timer frequency set to 1 MHz
              TMR FREQ 1MHZ
              TMR FREO 5MHZ → micro timer frequency set to 5 MHz
              TMR FREQ 25MHZ → micro timer frequency set to 25 MHz
              TMR_FREQ_100MHZ → micro timer frequency set to 100 MHz
              TMR SRC LOC \rightarrow main timer sync source is 1 KHz local clock
              TMR SRC SYSFAIL -> main timer sync source is VME SYSFAIL
              TMR_SRC_IRQ1  → main timer sync source is VME IRQ1
TMR SRC_IRQ2  → main timer sync source is VME IRQ2
              TMR SRC IRQ2
              TMR_OUT_SYSFAIL -> timer output drives VME SYSFAIL
              TMR_OUT_IRQ1 → timer output drives VME IRQ1
TMR_OUT_IRQ2 → timer output drives VME IRQ2
              TMR OUT IRQ2
           Main timer initial value
  msec
Return
  None
```

3.5.8.2 Stopping the timer

```
Prototype
#include <pevulib.h>
or
```

```
#include <pevxulib.h>

void
pev_timer_stop( void)
or
pevx_timer_stop( int crate)

Description
Stop the PEV1100 local timer.

Parameters
None

Return
None
```

3.5.8.3 Reading the timer

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  pev_timer_read( struct pev_time *tm_p)
  pevx timer read( int crate, struct pev time *tm p)
Description
  Read the PEV1100 local timer current value. The current value of the two
  counters (msec and usec) are returned in the time and utime fields of the
  pev_time data structure.
<u>Parameters</u>
         Pointer to a pev time data structure
  tm p
Return
          The pev_time data structure pointed by parameter tm\_p has been
  time
          updated with the current value of timer counters. The current value
          of the main counter is returned.
           tm_p->time
                            Current value of the main counter
           tm p->utime
                            Current value of the micro counter
```

3.5.9 FIFO operations

The *pev_fifo_xxx()* set of functions allows to control and read/write from/to the communication FIFOs.

3.5.9.1 FIFO initialization

```
Prototype
   #include <pevulib.h>
or
   #include <pevxulib.h>
  void
  pev_fifo_init()
  pevx_fifo_init( int crate)
Description
  That function resets and enable all FIFOs implemented on the board. The
  interrupt handler associated to the non empty/full flags are installed and
  corresponding interrupts ready to be enabled.
Parameters
  none
<u>Return</u>
  0
           if OK
           if FIFOs not accessible (i.e. wrong board type)
```

3.5.9.2 FIFO status

```
#include <pevulib.h>
or
    #include <pevulib.h>
int
    pev_fifo_status( int idx, uint *sts)
or
    pevx_fifo_status( int crate, int idx, uint *sts)

Description
    That function read the control register of the FIFO referred by idx and returns its current value in an unsigned integer (32 bit) pointed by sts.

Parameters
    idx    FIFO index (from 0 to 3)
    sts    pointer to an integer to hold the FIFO status

Return
```

```
sts FIFO current status
-1 if error (wrong board type or FIFO index)
```

3.5.9.3 FIFO clear

```
Prototype
   #include <pevulib.h>
or
   #include <pevxulib.h>
  pev_fifo_clear( int idx, uint *sts)
  pevx_fifo_clear( int crate, int idx, uint *sts)
Description
  That function resets the FIFO referred by idx and returns its current
  status in an unsigned integer (32 bit) pointed by sts.
<u>Parameters</u>
          FIFO index (from 0 to 3)
  idx
  sts
          pointer to an integer to hold the FIFO status
Return
  sts
          FIFO current status
  -1
          if error (wrong board type or FIFO index)
```

3.5.9.4 FIFO read

```
#include <pevulib.h>
or
    #include <pevxulib.h>

int
    pev_fifo_read( int idx, uint *data, int cnt, uint *sts)
or
    pevx_fifo_read( int crate, int idx, uint *data, int cnt, uint *sts)
```

Description

That function tries to read at most cnt data (32 bit integer) from the FIFO referred by idx. Data are copied in the buffer pointed by data. At the end of the FIFO readout, the FIFO control register is read and its current value copied in an unsigned integer (32 bit) pointed by sts. The number of data actually copied in the data buffer is returned by the function.

If the FIFO is empty, no data are copied in the buffer and 0 is returned by the function call.

Parameters

```
idx
          FIFO index (from 0 to 3)
          pointer ta a data buffer ready to receive the FIFO data
  data
          number of word (32 bit integers) to read
  cnt
          pointer to a 32 bit integer to hold the FIFO status
  sts
Return
```

cnt number of word (32 bit integers) copied in the data buffer -1 if error (wrong board type or FIFO index)

3.5.9.5 FIFO write

Prototype #include <pevulib.h> #include <pevxulib.h> pev_fifo_write(int idx, uint *data, int cnt, uint *sts) pevx fifo write(int crate, int idx, uint *data, int cnt, uint *sts) Description That function tries to write at most cnt data (32 bit integer) to the FIFO referred by idx. Data are taken from the buffer pointed by data. At the end of the FIFO wrizing, the FIFO control register is read and its current value copied in an unsigned integer (32 bit) pointed by sts. When the FIFO is full, writing is stopped. The number of data actually copied in the FIFO is returned by the function. If the FIFO is full, no data are written and 0 is returned by the function. call. **Parameters** idx FIFO index (from 0 to 3) data pointer ta a data buffer ready to receive the FIFO data number of word (32 bit integers) to read cnt pointer to a 32 bit integer to hold the FIFO status sts

```
Return
cnt number of word (32 bit integers) copied in the data buffer
-1 if error (wrong board type or FIFO index)
```

3.5.10 EEPROM Access

The *pev_eeprom_xxx()* set of functions allows to read/write from/to the EEPROM device attached to the PCIe switches.

3.5.10.1 EEPROM read

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  void
  pev_eeprom_rd( uint offset,
                 char *addr,
                 uint cnt)
  pevx eeprom rd( int crate,
                   uint offset,
                   char *addr,
                  uint cnt)
Description
  Copy cnt byte from a data buffer pointed by addr in EEPROM at offset
  offset.
<u>Parameters</u>
  offset \, offset in EEPROM where the data are to be read from
  addr address of the buffer where the data are to be copied
  cnt
          number of bytes to by copied
<u>Return</u>
        in case of success
  0
       in case of error
```

3.5.10.2 EEPROM write

```
Prototype

#include <pevulib.h>
or
#include <pevxulib.h>
void
```

```
pev_eeprom_wr( uint offset,
                 char *addr,
                 uint cnt)
or
  pevx_eeprom_wr( int crate,
                  uint offset,
                  char *addr,
                  uint cnt)
Description
  Copy cnt byte from a data buffer pointed by addr in EEPROM at offset
  offset.
Parameters
  offset offset in SFLASH where the data are to be copied
  addr address of the buffer containing the data to be copied
         number of bytes to by copied
  len
Return
        in case of success
  0
       in case of error
  -1
```

3.5.11 Event Handling

3.5.11.1 Create an event queue

```
Prototype
  #include <pevulib.h>
or
  #include <pevxulib.h>
  struct pev ioctl*
  pev_evt_queue_alloc( int sig)
  pevx_evt_queue_alloc( int crate,
                        int sig)
Description
  Create an event queue by allocating a control structure and calling the
  ioctl system call with PEV IOCTL EVT ALLOC command.
  When returning, the field evt queue of control structure contains an handle
  allowing the driver to access the event queue.
  If the sig field is non 0, a Linux signal equal to sig field will be
  generated by the driver each time the event queue becomes non empty
Parameters
          Linux signal number to be generated
  sig
Return
  evt
         pointer to event queue control structure
  NULL in case of error
```

3.5.11.2 Free event queue

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  pev evt free( struct pev ioctl evt *evt)
  pevx_evt_free( int crate,
                 struct pev_ioctl_evt *evt)
Description
  That function return to the OS an event queue previously allocated with
  pev_evt_queue_alloc().
<u>Parameters</u>
          pointer to event queue control structure
  evt
Return
  0
         in case of success
  -1
         in case of error (non existing event queue)
```

3.5.11.3 Register event in queue

```
Prototype
   #include <pevulib.h>
or
   #include <pevxulib.h>
  pev_evt_register( struct pev_ioctl_evt *evt,
                     uint src_id)
  pevx_evt_register( int crate,
                      struct pev_ioctl_evt *evt,
                      int src_id)
<u>Description</u>
  That function register event associated to interrupt source identified by
  src id in queue identified by evt.
<u>Parameters</u>
           handle to event control structure
  evt
   src id interrupt source identifier
Return
         in case of success
  -1
         in case of error
```

3.5.11.4 Unregister event in queue

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
  pev evt unregister( struct pev ioctl evt *evt,
                       uint src id)
or
  pevx_evt_unregister( int crate,
                        struct pev ioctl evt *evt,
                        int src id)
Description
  That function unregister the previously registered event associated to
  interrupt source identified by src id from queue identified by evt.
<u>Parameters</u>
          handle to event control structure
  src id interrupt source identifier
<u>Return</u>
         in case of success
   -1
        in case of error
```

3.5.11.5 Enable event queue

3.5.11.6 Disable event queue

3.5.11.7 Mask interrupt source associated to an event

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
  pev_evt_mask( struct pev_ioctl_evt *evt,
                int src_id)
or
  pevx_evt_mask( int crate,
                  struct pev_ioctl_evt *evt,
                 int src id)
Description
<u>Parameters</u>
           handle to event control structure
  evt
  src_id interrupt source identifier
<u>Return</u>
         in case of success
  0
        in case of error
  -1
```

3.5.11.8 Unmask interrupt source associated to an event

```
Prototype
   #include <pevulib.h>
   #include <pevxulib.h>
  pev evt unmask( struct pev ioctl evt *evt,
                   int src id)
or
  pevx_evt_unmask( int crate,
                    struct pev ioctl evt *evt,
                    int src id)
Description
<u>Parameters</u>
          handle to event control structure
  src id interrupt source identifier
Return
         in case of success
  0
   -1
         in case of error
```

3.5.11.9 Read event from queue

```
Prototype
  #include <pevulib.h>
  #include <pevxulib.h>
  pev_evt_read( struct pev_ioctl_evt *evt,
               int wait)
  pevx evt read( int crate,
                 struct pev_ioctl_evt *evt,
                 int wait)
Description
  Calling that function remove the "oldest" event from the queue identified
  by evt. If the queue is non empty, the src_id and vec_id fields of the
  pev ioctl evt data structure are update with the source and vector
  identifier of the event. The evt cnt contains the number of event left in
  the queue after the current one has been removed.
  If the queue is empty, the wait parameter defines if the system call shall
  wait until an event or a timeout occurs. It shall contain a timeout value
  in msec. If the wait is equal to 0, the call returns immediately. It it is
  equal to -1 it waits forever until an event occurs. Otherwise if wait for a
  maximum time defined by the timeout value. If no event is present in the
```

```
queue, src_id is set to 0

Parameters
evt handle to event control structure
wait timeout in msec

Return
(src_id << 8) | vec_id
```

3.6 Examples

3.6.1 Accessing a VME device from the host

The following examples performs a kind of VME loopback test by accessing the PEV1100 shared memory from its VME master port through its VME slave port. All physical accesses to the shared memory are performed by the application in user's mode.

```
#include <stdlib.h>
#include <stdio.h>
#include <sys/types.h>
#include <sys/mman.h>
#include <sys/time.h>

typedef unsigned int u32;
#include <pevioctl.h>
#include <pevilib.h>
```

pevulib.h contains the function declaration of the PEV1100 user's library and pevioctl.h the declaration of the data structure used to perform the address mapping operations.

```
static float tst_read( void *);
static float tst_write( void *);
```

Declare two local functions to perform VME read and write test

```
struct pev_node *pev;
struct pev_ioctl_map_pg shm_mas_map;
struct pev_ioctl_map_pg vme_mas_map;
struct pev_ioctl_map_pg vme_slv_map;
struct pev_ioctl_vme_conf vme_conf;
struct timeval ti, to;
struct timezone tz;
```

The *pev* pointer holds the return value of the *pev_init()* call.

Three data structure are defined to hold address mapping information

- *shm_mas_map* → direct mapping to the Shared Memory
- *vme_slv_map* → VME slave mapping to the Shared Memory
- *vme_mas_map* → master mapping to the VME slave address pointing the Shared Memory

The *vme_conf* data structure holds the PEV1100 VME interface current configuration.

```
main( int argc,
      void *argv[])
{
```

```
void *shm_loc_addr, *shm_vme_addr;
int i, data, *p;
long vme_addr;
long dt, dt1, dt2;
float usec;
uint crate;

printf("Entering VME test program\n");

/* call PEV1100 user library initialization function */
crate = 0;
pev = pev_init( crate);
if( !pev)
{
   printf("Cannot allocate data structures to control PEV1100\n");
   exit( -1);
}
/* verify if the PEV1100 is accessible */
if( pev->fd < 0)
{
   printf("Cannot find PEV1100 interface\n");
   exit( -1);
}</pre>
```

The first call to be performed is *pev_init()* in order to allow the user's library to access the PEV1100 device driver.

```
/* get the current VME configuration */
pev_vme_conf_read( &vme_conf);
printf("VME A32 base address = 0x*08x [0x*x]", vme_conf.a32_base, vme_conf.a32_size);
if( vme_conf.mas_ena)
{
   printf(" -> enabled\n");
}
else
{
   printf(" -> disabled\n");
}
```

```
/* create an address translation window in the VME slave port */
/* pointing to the PEV1100 Shared Memory */

vme_slv_map.rem_addr = 0x0000000; /* shared memory base address */
vme_slv_map.mode = MAP_ENABLE | MAP_ENABLE_WR | MAP_SPACE_SHM;
vme_slv_map.flag = 0x0;
vme_slv_map.sg_id = MAP_SLAVE_VME;
vme_slv_map.size = 0x100000;
pev_map_alloc( &vme_slv_map);

/* calculate the VME base address at which the Shared Memory has been mapped */
vme_addr = vme_conf.a32_base + vme_slv_map.loc_addr;
printf("shared Memory is visible at VME A32 address 0x%08x\n", vme_addr);
```

```
/* create an address translation window in the PCIe End Point */
/* pointing to the VME address at which the Shared Memory has been mapped */
vme_mas_map.rem_addr = vme_addr;
vme_mas_map.mode = MAP_ENABLE | MAP_ENABLE_WR | MAP_SPACE_VME | MAP_VME_A32;
vme_mas_map.flag = 0x0;
vme_mas_map.sg_id = MAP_MASTER_32;
vme_mas_map.size = 0x100000;
pev_map_alloc( &vme_mas_map);
```

```
printf("offset in PCI MEM window to access SHM throug VME : %p\n",
vme_mas_map.loc_addr);

printf("perform the mapping in user's space");
shm_vme_addr = pev_mmap( &vme_mas_map);
printf("%p\n", shm_vme_addr);
if( shm_vme_addr == MAP_FAILED)
{
    printf("Failed\n");
    goto VmeTst_exit;
}
printf("Done\n");
```

```
/* create an address translation window in the PCIe End Point */
/* pointing to the PEV1100 local address of the Shared Memory */
shm mas map.rem addr = 0x000000; /* shared memory base address */
shm_mas_map.mode = MAP_ENABLE | MAP_ENABLE_WR | MAP_SPACE_SHM;
shm mas map.flag = 0x0;
shm mas map.sg id = MAP MASTER 32;
shm_mas_map.size = 0x100000;
pev_map_alloc( &shm_mas_map);
printf("local address = %p\n", shm_mas_map.loc_addr);
printf("offset in PCI MEM window to access SHM locally : %p\n", shm_mas_map.loc_addr);
printf("perform the mapping in user's space : ");
shm_loc_addr = pev_mmap( &shm_mas_map);
printf("%p", shm_loc_addr);
if( shm_loc_addr == MAP_FAILED)
 printf(" ->Failed\n");
 goto VmeTst exit;
printf(" -> Done\n");
```

```
usec = tst_read( shm_vme_addr);
printf("VME read cycle %4f usec\n", usec);
usec = tst_write( shm_vme_addr);
printf("VME write cycle %4f usec\n", usec);
usec = tst_read( shm_loc_addr);
printf("SHM read cycle %4f usec\n", usec);
usec = tst_write( shm_loc_addr);
printf("SHM write cycle %4f usec\n", usec);
```

```
VmeTst_exit:
   pev_munmap( &shm_mas_map);
   pev_map_free( &shm_mas_map);
   pev_munmap( &vme_mas_map);
   pev_map_free( &vme_mas_map);
   pev_map_free( &vme_slv_map);

   pev_exit( pev);
   exit(0);
}
```

```
float
tst_read( void *addr)
  int i, data;
  int *s, *d;
  long dt1, dt2;
  gettimeofday( &ti, &tz);
  s = (int *)addr;
  for(i = 0; i < 0x10000; i++)
    data = *s++;
  gettimeofday( &to, &tz);
  dt1 = ((to.tv_sec - ti.tv_sec) * 1000000) + ( to.tv_usec - ti.tv_usec);
gettimeofday( &ti, &tz);
  s = (int *)addr;
  for( i = 0; i < 0x20000; i++)
    data = *s++;
  gettimeofday( &to, &tz);
  dt2 = ((to.tv_sec - ti.tv_sec) * 1000000) + ( to.tv_usec - ti.tv_usec);
  return( (float)(dt2-dt1)/0x10000);
```

```
tst write( void *addr)
  int i, data;
  int *s, *d;
  long dt1, dt2;
  data = 0xa5a5a5a5;
  gettimeofday( &ti, &tz);
  d = (int *)addr;
  for( i = 0; i < 0x10000; i++)
   *d++ = data;
  gettimeofday( &to, &tz);
  dt1 = ((to.tv_sec - ti.tv_sec) * 1000000) + ( to.tv_usec - ti.tv_usec);
  gettimeofday( &ti, &tz);
  d = (int *)addr;
  for( i = 0; i < 0x20000; i++)
    *d++ = data;
  gettimeofday( &to, &tz);
  dt2 = ((to.tv_sec - ti.tv_sec) * 1000000) + ( to.tv_usec - ti.tv_usec);
  return( (float)(dt2-dt1)/0x10000);
```

3.7 PEV1100 Command Interpreter

3.7.1 Introduction

XprsMon is a Linux application linked with the PEV1100 user's library. It allows the user to perform interactively a set of command to operate the PEV1100 interface. Once the **pev** driver has been inserted in the kernel, **XprsMon** is very useful to setup and debug a VME configuration.

XprsMon command syntax is as follow:

cmd.ext para#1:m#1 para#2:m#2 ...

where

- **cmd** is the command name
- ext is a command extension (optional)
- para#i are the command parameters
- m#i are the parameter modifiers (optional)

The *help* command displays a list of all allowed command names.

XprsMon parameters can be strings, integers, ranges or data set. By default integers are interpreted and displayed as hexadecimal numbers.

Some commands takes address range and data set parameters. Ranges shall be in the form of

```
start..end
```

or

start..end:space

where

- start and end are integers
- space is an address space identifier

Data set parameter shall be in the form of

```
c:data..para
```

where

- c is a ascii character identifying the set
- data and para are integers

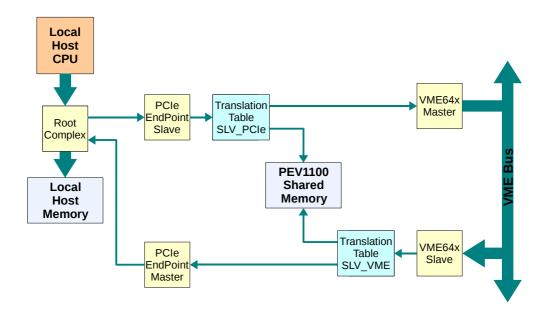
XprsMon is started by invoking the **XprsMon** binary file from the Linux shell with the node number as parameter.

During its initialization phase, **XprsMon** tries to opens the device /*dev/pev* in order to access the PEV1100. If the open system call fails, **XprsMon** exits.

In case of success, the following operations are performed:

- allocate a 1 Mbyte window in the PCI MEM space to access the PEV1100 Shared Memory
- allocate a 1 Mbyte window in the PCI MEM space to access the VME bus
- allocate a 1 Mbyte data buffer in kernel space for DMA access to the Local Host Memory
- allocate a 1 Mbyte window in the VME A32 slave to access the PEV1100 shared memory
- allocate a 1 Mbyte window in the VME A32 slave to access the Local Host Memory (data buffer

XprsMon provides a set of command to perform CPU read/write accesses from/to these spaces



3.7.2 Command List

Command	Description	Reference
conf	show PEV1100 configuration	\$3.7.2.1
dm	PEV1100 address mapping operations	\$3.7.2.2
dma	data transfer using DMA	\$3.7.2.3
dp	display data buffer from PEV1100 PCI MEM window	\$3.7.2.4
ds	display data buffer from PEV1100 shared memory	\$3.7.2.5
dv	display data buffer from VME address space	\$3.7.2.6
fm	fill data buffer in system memory	\$3.7.2.7
fp	fill data buffer in PEV1100 PCI MEM space	\$3.7.2.8
fs	fill data buffer in PEV1100 shared memory	\$3.7.2.9
fv	fill data buffer in VME address space	\$3.7.2.10
help	display list of commands or syntax of command <cmd></cmd>	\$
i2c	"perform i2c command	\$
ls	read/write loop from/to PEV1100 shared memory	\$
lv	read/write loop from/to VME address space	\$
map	PEV1100 address mapping operations	\$3.7.2.11
рс	read/write data from/to PEV1100 PCI configuration space	\$3.7.2.12
pio	read/write data from/to PEV1100 PCI IO space	\$3.7.2.13
pm	read/write data from/to PEV1100 system memory	\$
pp	read/write data from/to PEV1100 PCI MEM space	\$3.7.2.14
pr	read/write data from/to PEV1100 register	\$
ps	read/write data from/to PEV1100 shared memory	\$
pv	read/write single data from/to VME address space	\$3.7.2.15
px	read/write data from/to PEX86XX registers	\$3.7.2.16
lql		\$
sflash	sflash operation	\$
ts	perform read/write test on shared memory	\$
tv	perform read/write test on VME bus	\$
timer	perform operation on PEV1100 internal timer	\$3.7.2.18
tinit	launch test suite	\$3.7.2.19
tkill	kill test suite	\$
tlist	display a list of existing test	\$
tset	set test control parameter	\$
tstart	start execution of a test or a chain of tests	\$
tstop	stop current test execution	\$
tty	send string to ttyUSB0	\$3.7.2.21
vme	configure vme interface	\$3.7.2.20

Table 3: XprsMon Command List

3.7.2.1 Show board configuration

```
Command
   conf → display board hardware configuration
Synopsis
   conf <operation> <resource>
      where <operation> operation to be perform
                show → display resource current configuration
             <re>ource> string identifying the PEV1100 internal resource</ri>
                         → all avialable resources
                        → FPGA
                shm
                        → on board shared memory
                         → FPGA system monitoring
                smon
                switch → Front End PCIe switch (PEX8624)
                static \rightarrow static options (switches and jumpers)
                        → VME64x interface
Description
   The conf command allows to display the current configuration of all
   hardware resources available on the PEV1100 board.
Examples
   XprsMon#2>conf show all
   PEV1100 Configuration
      Static Options [0x002612d2]
         VME Interface
             A24 Base Address : d00000
             System Controller: 64x-Slot1+SysRstEna-
         PLX8624 Switch
            Port0 [P3] : Upstream : Externorm Port1 [P4] : Non Transparent Port5 [FPGA] : Downstream Port6 [PCI] : Downstream Port8 [XMC#1] : Downstream Port9 [XMC#2] : Downstream
                                 : Upstream : External Clock
         FPGA
            Bit Stream : 1
PON FSM : D
                                 : Disabled
                                : 128 MBytes
             MEM size
             PMEM size
                                : 128 MBytes
            PMEM mode
                                : A32
      PCIe SWITCH Status
         Identifier
                                : 0x862410b5
      FPGA Status
         Identifier : 0x06050901
Bit stream loaded : 1
      Shared Memory
         Size
                                : 512 MBytes
      VME Interface
         System Controller : Enabled
Arbtration mode : PRI not pipelined
            Arbtration

Bus Timeout : 16 usec
: Enabled
         Master
             Request Mode : Release On Request
             Request Level
                               : 0
         Slave
                                 : Enabled
             A24 base address : 0xd00000
A32 base address : 0x20000000
             A32 window size
                                 : 0x10000000
             CR/CSR
                                 : Berr- SlvEna+ SysFail- SysFailEna- Reset-
          Interrupt Generator
```

```
: 00
           Vector
           Level
                             : 0
                             : Register
           Mode
           Status
                             : Cleared
     FPGA System Monitor
        Temperature
                            : 50.20 [50.20 - 28.05]
        VCCint
                            : 1.00 [1.00 - 1.00]
        VCCaux
                            : 2.52 [2.52 - 2.51]
        VCC1.8-INT
                            : 1.79
        VCC3.3-INT
                            : 3.26
        VCC5.0-VME
                            : 5.02
        VCC3.3-VME
                             : 3.36
XprsMon#2>
```

3.7.2.2 Display address range from system memory

```
Command
  dm → display content of System Memory
Synopsis
  dm.<ds>[<swap>] <start>[..<end>]
     where \langle ds \rangle = b, s, w, (data size 1,2,4)
           <swap> = s if swapping is reqired
           <start> = start address in hexadecimal
           <end> = end address in hexadecimal
Description
  The dm command shall be used to display the content of the kernel buffer
  allocated in system memory during the XprsMon initialization phase. This
  buffer is provided to perform test with the VME slave interface and to
  offer DMA engines an access to the system memory.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
    1 → for 64 bit access
  The second character (optional) shall be {\bf s} if the data are to be displayed
  byte swapped (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of address offsets whose content are
  to be displayed according to the data size chosen. Address offsets are
  offset related to the base address of the allocated buffer.
Examples
  XprsMon#2>dm.b 0
  0x00000000 : 00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f
  0x00000010: 10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f
  0x00000020 : 20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f
  0x00000030 : 30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f
                                                                  01234567
  XprsMon#2>
```

3.7.2.3 Perform DMA operation

```
Command
dma → perform a data transfer using DMA engines
```

Description

The **dma** command allows to move data from a source address space identified by <src_space> to a destination address space identified by <des_space>. Allowed address space identifiers are:

```
0 → PCI memory space
2 → Shared Memory
```

3 → FPGA user's space

 $31 \rightarrow VME A32$

 $41 \rightarrow \text{VME BLT}$

51 → VME MBLT

61 → 2eVME

71 → 2eVME Fast

 $81 \rightarrow 2eSST 160$

91 → 2eSST 233

a1 \rightarrow 2eSST 320

The <src_addr> and <des_addr> parameters are the address offsets in the source and destination spaces.

Examples

Move 64 Kbytes from the VME address 0x80000000 to the kernel buffer allocated by XprsMon using VME MBLT transfer mode.

XprsMon>dma start 0:0 80000000:51 10000

3.7.2.4 Display PCI MEM address range

```
Command
```

dp → display content of PCI addresses (MEM space)

Synopsis

Description

The dp command shall be used to perform address cycle through the PCI MEM space window of the PEV1100 FPGA PCIe End Point. It takes an address offset range as parameter. The actual location from where the data will be read depends on the initialization of the address translation table associated to the FPGA PCI MEM window. That command is useful to display the content of address ranges in resources mapped by other application. The map command (see §3.7.2.11) shall be used to check the actual address mapping. The command extensions is made of 1 or 2 characters. The first character can be:

```
b → for byte access
c → for 16 bit access
```

 $\mathbf{w} \rightarrow \text{for 32 bit access}$

1 → for 64 bit access

The second character (optional) shall be ${\bf s}$ if the data are to be displayed byte swapped (meaningful only for 16, 32 and 64 bits accesses).

The first parameter shall be a range of address offsets whose content shall be displayed. Address offsets are offset related to the PCI base address of the FPGA PCI MEM window. Physical cycles are performed according to the data size chosen.

Basically that command allows to display content of remote addresses already mapped (by other application) through the mas_32 mapping table. The map show command shall be used to display existing mapping and address offsets to be used.

Examples

```
XprsMon#2>dp.w 100000
```

```
      0x00100000 :
      00000000 0000004 0000008 0000000c

      0x00100010 :
      00000010 0000014 00000018 0000001c

      0x00100020 :
      00000020 0000024 00000028 0000002c

      0x00100030 :
      00000030 0000034 0000038 000003c

      0xprsMon#2>
```

3.7.2.5 Display Shared Memory address range

Command

ds → display content of Shared Memory

Synopsis

```
ds.<ds>[<swap>] <start>[..<end>]
```

Description

The **ds** command shall be used to display the content of shared memory address ranges.

The command extensions is made of 1 or 2 characters. The first character can be:

- **b** → for byte access
- c → for 16 bit access
- w → for 32 bit access
- 1 → for 64 bit access

The second character (optional) shall be ${\bf s}$ if the data are to be displayed byte swapped (meaningful only for 16, 32 and 64 bits accesses).

The first parameter shall be a range of address offsets whose content shall be displayed according to the data size chosen. Address offsets are offset related to the base address of the PEV1100 on board shared memory.

Examples

```
XprsMon#2>ds.b 0
```

```
      0x000000000 :
      00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f

      0x000000010 :
      10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f

      0x000000020 :
      20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f

      0x000000030 :
      30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f

      0xprsMon#2>
```

3.7.2.6 Display VME address range

```
Command
  dv → display content of VME addresses
Synopsis
  dv.<ds>[<swap>] <start>[..<end>] m:<mode>
     where \langle ds \rangle = b, s, w, (data size 1,2,4)
           <swap> = s if swapping is required
           <start> = start address in hexadecimal
           <end> = end address in hexadecimal
           <mode> = address mode
Description
  The dv command shall be used to perform PCI configuration cycles targeted
  to the PEV1100 FPGA PCIe End Point. It takes an address range as parameter.
  The command extensions is made of 1 or 2 characters. The first character
    b → for byte access
    c → for 16 bit access
    \mathbf{w} \rightarrow \text{for } 32 \text{ bit access}
    1 → for 64 bit access
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of VME address whose content shall be
  displayed according to the data size chosen. XprsMon creates dynamically
  the address mapping in order to perform the requested VME cycles.
  The second parameter shall be a string defining the VME access mode:
    crcsr → generate address modifier for VME64x CR/CSR (0x2f)
           → generate A16 data access address modifier (0x29/0x2d)
    a16
           → generate A24 data access address modifier (0x39/0x3d)
           → generate A32 data access address modifier (0x09/0x0d)
    a32
           → generate address modifier A32/D32 block transfer (0x0b/0x0f)
    blt
    mblt → generate address modifier A32/D64 block transfer (0x08/0x0c)
           → generate A24 address only cycle
    ao24
           → generate A32 address only cycle
    iack → generate VME IACK cycle
  If the access mode parameter is missing the one used in the last cycle is
  kept. When XprsMon is launched, a32 is selected by default.
  If the address range parameter is missing, the display continues from the
  the address used in the last VME cycle executed.
Examples
  XprsMon#2>dv.s 40000000..40000020
  0x40000000 : 0100 0302 0504 0706 0908 0b0a 0d0c 0f0e ......
  0x40000010 : 1110 1312 1514 1716 1918 1b1a 1d1c 1f1e ......
  XprsMon#2>dv.ss 40000000..40000020
  0x40000000 : 0001 0203 0405 0607 0809 0a0b 0c0d 0e0f
  0x40000010 : 1011 1213 1415 1617 1819 1a1b 1c1d 1e1f
  XprsMon#2>dv
  0x40000020 : 2021 2223 2425 2627 2829 2a2b 2c2d 2e2f ! #"%$'&)(+*-,/.
  0x40000030 : 3031 3233 3435 3637 3839 3a3b 3c3d 3e3f 1032547698;:=<?>
  XprsMon#2>
```

3.7.2.7 Fill System Memory address range

```
Command
fs → fill an address range in shared memory with a data set
```

```
Synopsis
  fs.<ds>[<swap>] <start>[..<end>] data
     where <ds>
                   = b, s, w, (data size 1, 2, 4)
           <swap> = s if swapping is required
            <start> = start offset in hexadecimal
           <end> = end offset in hexadecimal
<data> = data set
Description
  The fs command shall be used to fill a range of address in shared memory
  with a data set.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c \rightarrow for 16 bit access
    \mathbf{w} \rightarrow \text{for } 32 \text{ bit access}
    1 → for 64 bit access
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of address offsets (relative to the
  shared memory base address) whose content shall be initialized according to
  the data size chosen. XprsMon creates dynamically the address mapping in
  order to access the shared memory.
  The second parameters defines the data set to be used to fill the address
  range. The syntax is made of a set identifier followed by a semi colon and
  one or more arguments. If the set identifier is missing, the address range
  is filled with a constant data.
                      → fill data set with a constant data
    <data>
  else it is filled with a data set
    r:<seed>
                       → fill with pseudo random data
    s:<start>..<inc> → fill with a ramp
    w:<data>..<mask> → fill with a walking pattern
  For random data set, the Linux rand() function is used with <seed>
  parameter as seed for the random generator. The first data of the set is
  the <seed> parameter
  The ramp data set starts with the <start> parameter and <inc> parameter is
  used as increment to generate the next data in the set.
  The walking pattern data set is calculated according to the following
  formula:
      <data> XOR <mask>
  To calculate the next data in the set, the mask is left rotated by 1 over
  the data size. This allows to generate a 32 bit walking 1 with
    w:ffffffff..fffffffe
  and a walking 0 with
    w:ffffffff..1
Examples
  XprsMon#2>fs.w 0..10000 w:ffffffff..1
  XprsMon#2>ds.w 0
  0x00000000 : fffffffe fffffffd ffffffff ......
  0x00000010 : ffffffef ffffffdf ffffffbf ffffff7f
  0x00000020 : fffffeff fffffdff fffffbff ffffffff
  0x00000030 : ffffefff ffffdfff ffffbfff ffff7fff ......
  XprsMon#2>
```

3.7.2.8 Fill PCI address range

```
Command
  fp \rightarrow fill an address range in FPGA PCI MEM space with a data set
Synopsis
  fp.<ds>[<swap>] <start>[..<end>] data
                    = b,s,w, (data size 1,2,4)
            <swap> = s if swapping is required
            <start> = start offset in hexadecimal
            <end> = end offset in hexadecimal
            <data> = data set
Description
  The fp command shall be used to fill a range of address in in the FPGA PCI
  MEM window with a data set. The actual location where the data will be
  written depends on the initialization of the address translation table
  associated to the FPGA PCI MEM window. That command is useful to initialize
  address ranges in resources mapped by other application. The map command
  (see §3.7.2.11) shall be used to check the actual address mapping.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
    1 → for 64 bit access
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of address offsets (relative to the
  FPGA PCI MEM window base address) whose content shall be initialized
  according to the data size chosen.
  The second parameters defines the data set to be used to fill the address
  range. The syntax is made of a set identifier followed by a semi colon and
  one or more arguments. If the set identifier is missing, the address range
  is filled with a constant data.
    <data>
                       → fill data set with a constant data
  else it is filled with a data set
                        → fill with pseudo random data
     s:<start>..<inc> → fill with a ramp
    w:<data>..<mask> → fill with a walking pattern
  For random data set, the Linux rand() function is used with <seed>
  parameter as seed for the random generator. The first data of the set is
  the <seed> parameter
  The ramp data set starts with the <start> parameter and <inc> parameter is
  used as increment to generate the next data in the set.
  The walking pattern data set is calculated according to the following
  formula:
       <data> XOR <mask>
  To calculate the next data in the set, the mask is left rotated by 1 over
  the data size. This allows to generate a 32 bit walking 1 with
    w:ffffffff..fffffffe
   and a walking 0 with
    w:ffffffff..1
Examples
  XprsMon#2>fp.w 100000..110000 r:12345678
  XprsMon#2>dp.w 100000
  0x00100000 : 12345678 c1da14f0 623d80e6 f0cba6c2 xV4.....=b...
0x00100010 : fe38c547 7bf64f5d 1c6df870 3473d32f G.8.]0.{p.m./.s4
0x00100020 : 397915d9 a23accf0 fc887b38 7abe7811 ...y9...8{...x.z}
   0x00100030 : 314a695b 8e0f2fdc 5e104039 f0307802 [iJ1./..9@.^.x0.
```

XprsMon#2>

3.7.2.9 Fill address range in shared memory

```
Command
  fs \rightarrow fill an address range in shared memory with a data set
Synopsis
  fs.<ds>[<swap>] <start>[..<end>] data
     where <ds>
                   = b,s,w, (data size 1,2,4)
           <swap> = s if swapping is required
           <start> = start offset in hexadecimal
           <end> = end offset in hexadecimal
           <data> = data set
Description
  The fs command shall be used to fill a range of address in shared memory
  with a data set.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
    1 → for 64 bit access
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of address offsets (relative to the
  shared memory base address) whose content shall be initialized according to
  the data size chosen. XprsMon creates dynamically the address mapping in
  order to access the shared memory.
  The second parameters defines the data set to be used to fill the address
  range. The syntax is made of a set identifier followed by a semi colon and
  one or more arguments. If the set identifier is missing, the address range
  is filled with a constant data.
                      → fill data set with a constant data
    <data>
  else it is filled with a data set
    r:<seed>
                     → fill with pseudo random data
    s:<start>..<inc> → fill with a ramp
    w:<data>..<mask> → fill with a walking pattern
  For random data set, the Linux rand() function is used with <seed>
  parameter as seed for the random generator. The first data of the set is
  the <seed> parameter
  The ramp data set starts with the <start> parameter and <inc> parameter is
  used as increment to generate the next data in the set.
  The walking pattern data set is calculated according to the following
  formula:
      <data> XOR <mask>
  To calculate the next data in the set, the mask is left rotated by 1 over
  the data size. This allows to generate a 32 bit walking 1 with
    w:ffffffff..fffffffe
  and a walking 0 with
    w:ffffffff..1
Examples
  XprsMon#2>fs.s 0..10000 s:0..2
  XprsMon#2>ds.s 0
```

```
      0x00000000 : 0000 0002 0004 0006 0008 000a 000c 000e

      0x00000010 : 0010 0012 0014 0016 0018 001a 001c 001e

      0x00000020 : 0020 0022 0024 0026 0028 002a 002c 002e
      ".$.&.(.*.,...

      0x00000030 : 0030 0032 0034 0036 0038 003a 003c 003e
      0.2.4.6.8.:.<.>.

      XprsMon#2>
```

3.7.2.10 Fill VME address range

```
Command
  fv → fill a VME address range with a data set
  fv.<ds>[<swap>] <start>[..<end>] data [m:<mode>]
     where <ds>
                   = b,s,w, (data size 1,2,4)
            <swap> = s if swapping is required
            <start> = start address in hexadecimal
            <end> = end address in hexadecimal
            <data> = data set
            <mode> = address mode
Description
  The fv command shall be used to fill a range of VME address with a data
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b \rightarrow for byte access
    c → for 16 bit access
    \mathbf{w} \rightarrow \text{for } 32 \text{ bit access}
    1 → for 64 bit access
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16, 32 and 64 bits accesses).
  The first parameter shall be a range of VME address whose content shall be
  initialized according to the data size chosen. XprsMon creates dynamically
  the address mapping in order to perform the requested VME cycles.
  The second parameters defines the data set to be used to fill the address
  range. The syntax is made of a set identifier followed by a semi colon and
  one or more arguments. If the set identifier is missing, the address range
  is filled with a constant data.
                       → fill data set with a constant data
    <data>
  else it is filled with a data set
                      → fill with pseudo random data
    s:<start>..<inc> → fill with a ramp
    w:<data>..<mask> → fill with a walking pattern
  For random data set, the Linux rand() function is used with <seed>
  parameter as seed for the random generator. The first data of the set is
  the <seed> parameter
  The ramp data set starts with the <start> parameter and <inc> parameter is
  used as increment to generate the next data in the set.
  The walking pattern data set is calculated according to the following
  formula:
      <data> XOR <mask>
  To calculate the next data in the set, the mask is left rotated by 1 over
  the data size. This allows to generate a 32 bit walking 1 with
    w:ffffffff..ffffffe
  and a walking 0 with
    w:fffffff..1
  The third parameter shall be a string defining the VME access mode:
```

```
crcsr → generate address modifier for VME64x CR/CSR (0x2f)
           → generate A16 data access address modifier (0x29/0x2d)
    a24
           → generate A24 data access address modifier (0x39/0x3d)
           → generate A32 data access address modifier (0x09/0x0d)
    a32
           → generate address modifier A32/D32 block transfer (0x0b/0x0f)
    blt
    mblt → generate address modifier A32/D64 block transfer (0x08/0x0c)
    ao24 → generate A24 address only cycle
    ao32 → generate A32 address only cycle
    iack → generate VME IACK cycle
  If the access mode parameter is missing the one used in the last VME cycle
  is kept. When XprsMon is launched, a32 is selected by default.
Examples
  XprsMon#2>fv.w 40000000..40010000 w:ffffffff..ffffffe
  XprsMon#2>dv.w 40000000
  0x40000000 : 00000001 00000002 00000004 00000008 .....
  0x40000010 : 00000010 00000020 00000040 00000080 ....@.....
  0x40000020 : 00000100 00000200 00000400 00000800 .....0.....0x40000030 : 00001000 00002000 00004000 00008000 .....@....
  XprsMon#2>
```

3.7.2.11 Managing address mapping

```
Command
 map → handle address mapping
Synopsis
 map <operation> <map identifier>
    where <operation> operation to be perform
        <map identifier> string identifying the mapping
Description
 The map command shall be used to handle the PEV1100 address mapping tables.
 The show operation displays the PEV1100 current mapping information for the
 table identified by the <map identifier> parameter:
   mas 32 → mapping in PCI MEM space
   mas 64 → mapping in PCI PMEM space
   slv vme → mapping in VME slave interface
 If no map identifier is given, all maps are shown.
 The clear operation resets all pages in the translation table identified by
 the <map identifier> parameter. This destroy all mapping previously
 performed by any application and should be used only as a last resort
 operation.
Examples
 XprsMon#2>map show
 +-----+
 + Map Name : mas 32
  +----+
  offset | flag | usr | size | remote address | mode |
  +============++
  + Map Name : mas 64
  +----+
  offset | flag | usr | size | remote address | mode |
```

```
+----+
+ Map Name : slv vme
+----+
offset | flag | usr | size | remote address | mode |
+----+---+---+
XprsMon#2>map show mas 32
+ Map Name : mas 32
+----+
offset | flag | usr | size | remote address | mode |
+----+---+---+
XprsMon#2>
```

3.7.2.12 Patch PCI configuration register

```
Command
  pc → read/write data from/to PEV1100 PCI configuration space
Synopsis
  pc.<ds>[<swap>] <req> [<data>]
      where \langle ds \rangle = b, s, w, (data size 1,2,4)
            <swap> = s if swapping is required
            <reg> = register offset in hexadecimal
            <data> = data in hexadecimal [write cycle]
Description
  The pc command shall be used to perform PCI configuration cycles targeted
  to the PEV1100 FPGA PCIe End Point. It takes up to 2 parameters.
  The command extensions is made of 1\ \mathrm{or}\ 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
  The second character (optional) shall be {\bf s} if the data are to be byte
```

The second character (optional) shall be ${\bf s}$ if the data are to be byte swapped before being written or displayed (meaningful only for 16, 32 and 64 bits accesses).

The first parameter shall be the address offset of the configuration register to be accessed.

The second parameter shall be the data to write in the register. If it is missing, XprsMon performs a read cycle on the register, displays the data and prompt for a new data to overwrite the register. To return to the command interpreter enter the "." character. If you enter CR (Carriage Return), XprsMon will read the register at <rey>+<ds> and display it current value.

Examples

```
XprsMon#2>pc.s 0
0x000000000 : 7357 ->
0x000000002 : 1100 -> .
XprsMon#2>
```

3.7.2.13 Patch PCI address in the FPGA End Point IO space

```
Command
  pio → read/write data from/to PEV1100 PCI IO space
  pio.<ds>[<swap>] <offset> [<data>]
     where \langle ds \rangle = b, s, w, (data size 1,2,4)
            <swap> = s if swapping is required
            <offset> = address offset in hexadecimal
            <data> = data in hexadecimal [write cycle]
Description
  The pio command shall be used to perform PCI IO cycles targeted to the
  PEV1100 FPGA PCIe End Point. It takes up to 2 parameters.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    \mathbf{w} \rightarrow \text{for } 32 \text{ bit access}
  The second character (optional) shall be {\bf s} if the data are to be byte
  swapped before being written or displayed (meaningful only for 16, 32 and
  64 bits accesses).
  The second character is optional and shall be {\bf s} if byte swapping is
  required (meaningful only for 16 and 32 bits accesses).
  The first parameter shall be the address offset in PCI MEM space to be
  accessed.
  The second parameter shall be the data to write in the address offset. If
  it is missing, XprsMon performs a read cycle on the register, displays the
  data and prompt for a new data to overwrite the register. To return to the
  command interpreter enter the "." character. If you enter CR (Carriage
  Return), XprsMon will read the register at <reg>+<ds> and display it
  current value.
Examples
  XprsMon>
```

3.7.2.14 Patch PCI address in the FPGA End Point MEM space (BAR#2)

```
The command extensions is made of 1 or 2 characters. The first character
  can be:
   b → for byte access
   c → for 16 bit access
    w → for 32 bit access
  The second character (optional) shall be s if the data are to be byte
  swapped before being written or displayed (meaningful only for 16, 32 and
  64 bits accesses).
  The second character is optional and shall be s if byte swapping is
  required (meaningful only for 16 and 32 bits accesses).

The first parameter shall be the address offset in PCI MEM space to be
  accessed.
  The second parameter shall be the data to write in the address offset. If
  it is missing, XprsMon performs a read cycle on the register, displays the
  data and prompt for a new data to overwrite the register. To return to the
  command interpreter enter the "." character. If you enter CR (Carriage
  Return), XprsMon will read the register at <reg>+<ds> and display it
  current value.
Examples
   XprsMon#2>map show mas_32
  + Map Name : mas 32
  +----+---+---+
  | offset |flag| usr| size | remote address | mode |
   | 00100000 | 01 | 01 | 00100000 | 000000040000000 | 1303 | VME A32
  XprsMon#2>pp.w 100000
  0 \times 001000000 : 00000001 \rightarrow 12345678.
  0x00100004 : 00000002 \rightarrow .
  XprsMon#2>pp.w 100000
  0x00100000 : 12345678 ->
  0x00100004 : 00000002 \rightarrow .
  XprsMon#2>
```

3.7.2.15 Patch an address on the VME bus

```
Command
  pv → read/write data from/to VME bus
  pv.<ds>[<swap>] <vme addr> [<data>] [m:<mode>]
     where \langle ds \rangle = b, s, w, (data size 1,2,4)
            <swap> = s if swapping is required
            <vme addr> = VME address in hexadecimal
            <data> = data in hexadecimal [write cycle]
            <mode> = VME access mode
Description
  The pv command shall be used to perform VME cycles through the PEV1100. It
  takes up to 3 parameters.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
```

```
The second character (optional) shall be \mathbf{s} if the data are to be byte
  swapped before being written or displayed (meaningful only for 16, 32 and
  64 bits accesses).
  The second character is optional and shall be \mathbf{s} if byte swapping is
  required (meaningful only for 16 and 32 bits accesses).
  The first parameter shall be the VME address.
  The second parameter shall be the data to write in the VME address. If it
  is missing or equal to '?', XprsMon performs a read cycle on the register,
  displays the data and prompt for a new data to overwrite the register. To
  return to the command interpreter enter the "." character. If you enter CR
  (Carriage Return), XprsMon will read the register at <reg>+<ds> and display
  it current value.
  The third parameter shall be a string defining the VME access mode:
    {\tt crcsr} \rightarrow generate address modifier for VME64x CR/CSR (0x2f)
           → generate A16 data access address modifier (0x29/0x2d)
    a24
            → generate A24 data access address modifier (0x39/0x3d)
    a32
            → generate A32 data access address modifier (0x09/0x0d)
    blt
           → generate address modifier A32/D32 block transfer (0x0b/0x0f)
           → generate address modifier A32/D64 block transfer (0x08/0x0c)
    mblt.
    ao24 → generate A24 address only cycle
    ao32 → generate A32 address only cycle
    iack → generate VME IACK cycle
  If the access mode parameter is missing the one used the last time a VME
  cycle was executed is kept. When XprsMon is launched, a32 is selected by
  default.
Examples
  XprsMon#2>pv.w 40000000 ? m:a32
  0x40000000 : 12345678 \rightarrow 0
  0x40000004 : 00000002 \rightarrow .
  XprsMon#2>pv.w 40000000
  0x40000000 : 00000000 ->
  0x40000004 : 00000002 \rightarrow.
  XprsMon#2>
```

3.7.2.16 Patch PEX8624 registers

```
Command
  px → read/write data from/to PEV1100 PCI MEM space
Synopsis
  px.<ds>[<swap>] <offset> [<data>]
     where \langle ds \rangle = b, s, w, (data size 1,2,4)
            <swap> = s if swapping is required
            <offset> = address offset in hexadecimal
            <data> = data in hexadecimal [write cycle]
Description
  The px command allow to access the PEX8624 internal registers by performing
  PCI MEM cycles in its address space. It takes up to 2 parameters.
  The command extensions is made of 1 or 2 characters. The first character
  can be:
    b → for byte access
    c → for 16 bit access
    w → for 32 bit access
  The second character (optional) shall be {\bf s} if the data are to be byte
  swapped before being written or displayed (meaningful only for 16, 32 and
  64 bits accesses).
```

The second character is optional and shall be ${\bf s}$ if byte swapping is required (meaningful only for 16 and 32 bits accesses). The first parameter shall be the address offset in PCI MEM space to be accessed.

The second parameter shall be the data to write at the address offset. If it is missing, XprsMon performs a read cycle on the register, displays the data and prompt for a new data to overwrite the register. To return to the command interpreter enter the "." character. If you enter CR (Carriage Return), XprsMon will read the register at <reg>+<ds> and display it current value.

Examples

```
XprsMon#2>px.s 0
0x000000000 : 10b5 ->
0x00000002 : 8624 -> .
XprsMon#2>
```

3.7.2.17 SFLASH operations

```
Command
  sflash → perform SFLASH operation
Synopsis
  sflash <operation> [<para#1>][<para#2>][<para#3>]
     where <operation> is the operation to be performed
                   → shows the SFLASH identifier
             load \rightarrow loads an FPGA bitstream file in SFLASH
             sign → shows signature of FPGA loaded in SFLASH
             read → read SFLASH content
Description
  The sflash command allows to manage the PEV1100 SFLASH.
  The id operation displays the SFLASH device hardware identifier
  The load operation reads a file from the file system and writes it in the
  SFLASH device according to the following syntax:
  sflash load offset filename
  The read operation displays the timer current value in msec amd usec.
Examples
  XprsMon#2>sflash id
  SFLASH identifier 20:20:18
  XprsMon#2>sflash sign fpga#1
  FPGA#1 Signature at offset 0x3f0000
     + company: IOxOS Technologies
     + board:PEV1100
     + filename:pev1100 070509a.sfl
     + creation:Fri Aug 28 15:07:37 2009
     + mcs_file:pev1100 070509a.mcs
     + mcs_devname:XC5VLX30T
     + mcs devid:0x02a6e093
     + mcs offset:0x000000
     + mcs size:0x11dfc0
     + mcs_checksum:0xcbde562a
     + mcs creation:Fri Aug 28 15:06:01 2009
```

```
+ fsm_file:pev_init.fsm
+ fsm_offset:0x1c0000
+ fsm_size:0x000278
+ fsm_checksum:0xcc952770
+ fsm_creation:Wed Sep 17 15:43:36 2008
XprsMon#2>
```

3.7.2.18 Local Timer operations

```
timer → perform timer operation
Synopsis
  timer <operation>]
     where <operation> is the operation to be performed
              start → starts the timer
              stop → stops the timer
read → read the timer current value
Description
  The timer command allows to manage the PEV1100 local timer.
  The start operation starts the timer.
  The stop operation stops the timer.
  The read operation displays the timer current value in msec amd usec.
Examples
  XprsMon#2>timer start
  XprsMon#2>timer read
  current timer value : 3520.834500 msec
  XprsMon#2>timer read
  current timer value : 5648.904840 msec
  XprsMon#2>timer stop
  XprsMon#2>timer read
  current timer value : 8352.000000 msec
  XprsMon#2>timer read
  current timer value : 8352.000000 msec
  XprsMon#2>
```

3.7.2.19 Test Control

```
Command
  tinit → launch test program

Synopsis
  tinit [<testfile>]
  where <testfile> is the test program to be launched

Description
```

```
The tinit command launches the test program testfile in a xterm window. If no testfile is given, the "./PevTst" is used as test program.. When the test program is launched, a bidirectional pipe is created by XprsMon to establish a communication channel. This channel is used by XprsMon to pass the commands tlist, tset, tstart and tkill to the test program.
```

Examples

```
XprsMon#2>tinit ./PevTst
XprsTst->Launching:./PevTst XprsTst.cfg 5 8->Done:./PevTst 8594
XprsMon#2>
```

3.7.2.20 VME interface configuration

```
Command
  vme → handle VME interface
Synopsis
  vme <operation>)
     where <operation> is the operation to be performed
             conf → configure interface parameters
Description
  The conf operation allows to configure the following parameters on the VME
  interface:
    a32 base address
    a32 window size
  If bit 0 of a32 size is set, the slave interface is enabled with a 1 Mbytes
  granularity. Otherwise a 16 Mbytes granularity is used. That operation
  updates the hardware registers controlling the VME slave interface.
  If granularity mode is changed, the init command shall be used to re-
  initialize the VME slave interface according to the current setting of the
  hardware registers. That command destroys all existing address mapping.
Examples
  XprsMon#2>vme conf
  VME configuration
  a32 base [20000000] ->
  a32_size [10000000] -> 8000000
  XprsMon#2>vme conf
  VME configuration
  a32 base [20000000] ->
  a32 size [08000000] ->
  XprsMon#1>vme init
  VME INIT...
  XprsMon#2>
```

3.7.2.21 TTY operations

```
Command
   tty → allow to send a string of characters on /dev/ttyUSB0

Synopsis
   tty <operation> [<string>]
```

where <operation> is the operation to be performed <string> is a string of character

Description

The **tty** command allows to synchronize external devices with XprsMon using a USB to serial line converter. This can be very useful to perform automated test involving CPUs in the VME crate

The ${\bf open}$ operation opens the /dev/ttyUSB0 device

The close operation closes the /dev/ttyUSBO device

The ${\bf send}$ operation sends a character string <string> to the /dev/ttyUSB0 device

Examples

XprsMon>

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