

Using one measurement to reproduce another

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arXiv: 2203.02593

EoC 2024
16th July '24



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CIFAR

Outline

- Main question & motivating example
- Main result & sketch of proof
 - two key subroutines
- outline briefly other results
- Current & future directions
- Conclusions

Main question

To what extent can we use one measuring device
to simulate (reproduce) another?

- simulate ideal measurement from noisy one
- Completely change the measurement

Motivating example

- Consider the noisy Z measurement

$$M_1 = (1-p)|0\rangle\langle 0| + q|1\rangle\langle 1|$$

$$M_{-1} = p|0\rangle\langle 0| + (1-q)|1\rangle\langle 1|$$

$p = q = 0$: ideal Z meas.

$p = q$: sym. noisy Z

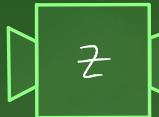
- Q: How well can this be used to simulate

ideal von Neumann measurement

i.e. simulate $Z = |0\rangle\langle 0| - |1\rangle\langle 1|$ measurement

The goal

Simulate as closely as possible statistics of ideal measurement

ideal $|\psi\rangle = \alpha|0\rangle + \beta|1\rangle \rightarrow$  $\Rightarrow a$ $\begin{aligned} \text{Prob}(+1) &= |\alpha|^2 \\ \text{Prob}(-1) &= |\beta|^2 \end{aligned}$

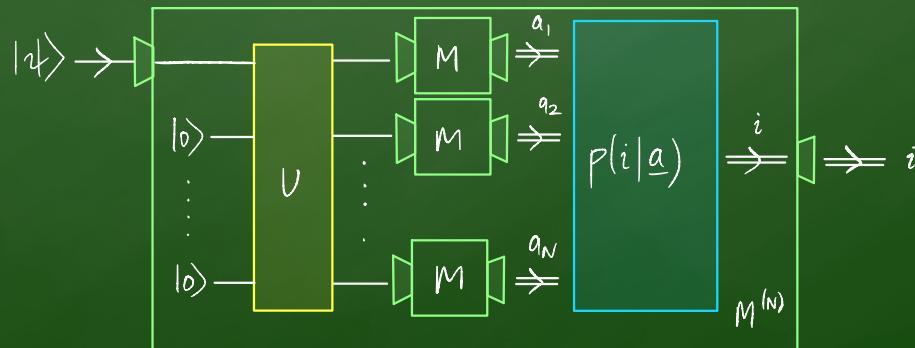
noisy Z $|\psi\rangle = \alpha|0\rangle + \beta|1\rangle \rightarrow$  $\Rightarrow a$ $\begin{aligned} \text{Prob}(+1) &= (1-p)|\alpha|^2 + q|\beta|^2 \\ \text{Prob}(-1) &= p|\alpha|^2 + (1-q)|\beta|^2 \end{aligned}$

+ correct post-measurement state too

Multi-copy approach

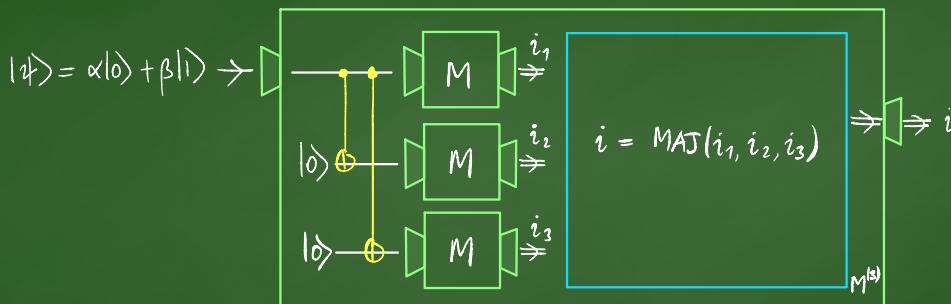
- Our approach is to allow ourselves multiple uses of the available measurement
(to simulate single use of target measurement)
 - Allow for preparation of arbitrary ancillary systems
 - + entangling pre-processing
 - Measure system + ancillary systems & collectively post-process string of outcomes

e.g.



3-use CNOT protocol

- Apply CNOT w/ ancillary qubits to prepare $|i\rangle = \alpha|0\rangle|0\rangle + \beta|1\rangle|1\rangle$
 - Measure all qubits w/ noisy-Z
 - Output majority of results
- } "repetition code"



$$M_1^{(3)} = (1 - p^{(3)})|0\rangle\langle 0| + q^{(3)}|1\rangle\langle 1|$$

$$M_{-1}^{(3)} = p^{(3)}|0\rangle\langle 0| + (1 - q^{(3)})|1\rangle\langle 1|$$

$$p^{(3)} = 3p^2 - 2p^3$$

$$q^{(3)} = 3q^2 - 2q^3$$

i.e.

$$p \rightarrow O(p^2)$$

$$q \rightarrow O(q^2)$$

Any* measurement can simulate any other measurement

* non-trivial

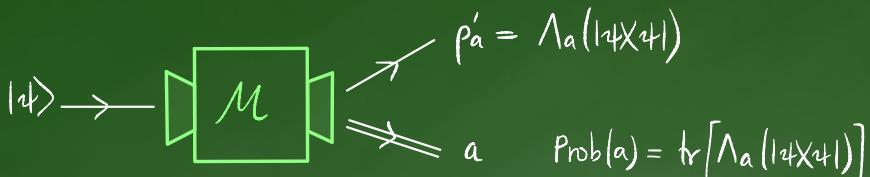
- Above result is not special to noisy- $\mathbb{Z}_2 \otimes \mathbb{Z}_2$
- In fact, this result holds in almost full generality:

Using any non-trivial measurement a sufficient number of times can simulate arbitrarily well any other measurement (instrument)

POVM elements not all proportional to identity $M_a \neq q(a)I$

Quantum Instruments

- Most general type of non-destructive measurement possible.



- $\Lambda_a(\cdot)$ completely positive trace non-increasing map.
- $\Lambda_a(\cdot) = \sum_i k_i^a(\cdot) k_i^{a\dagger}$ Kraus representation
- $\sum_a \Lambda_a(\cdot) = \Lambda(\cdot)$ q. channel.

- Previously: trivial to get post-measurement state correct
 - depends only upon meas. outcome & no memory of pre-meas. state $|\psi\rangle$
- Here: non-trivial dependence between pre-meas. & post-meas. state.

Two key subroutines

- Main result is proven by combining two key simulation sub routines:

Subroutine 1: post-measurement sub routine

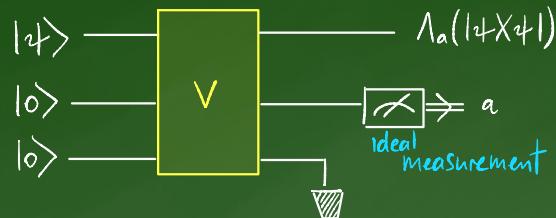
Given ability to perform (destructive) projective measurement
it is possible to simulate an arbitrary instrument

Subroutine 2: Generalised classical cloning sub routine

Given ability to perform any (non-trivial) instrument
it is possible to simulate arbitrarily well an ideal projective measurement

Post-measurement sub routine

- Essentially Naimark's theorem



$$V|+\rangle|0\rangle|0\rangle = \sum_{a,j} k_j^a |+\rangle|0\rangle|j\rangle$$

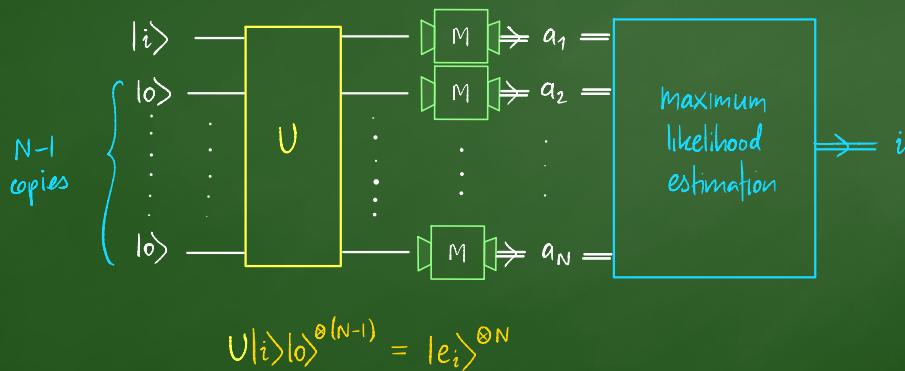
- projective measurement is **destructive** but measurement **steers** first system in desired post-measurement state.
- Routine shows that in order to simulate arbitrary instrument M it suffices to be able to simulate ideal projective measurement
this simplifies problem dramatically!

Generalised classical cloning sub routine

key observation 1: Ability to perform ideal projective measurement is equivalent*
being able to distinguish (perfectly) between a basis of states.

↳ we will focus on distinguishing a basis of states.

Generalised classical cloning sub-routine:

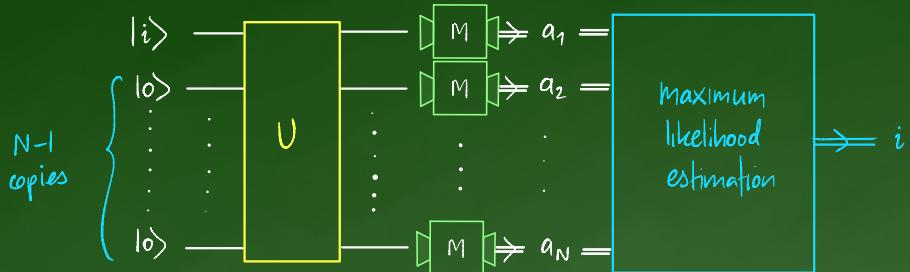


where $|e_i\rangle$ forms some
O.N.B.

- For large N this protocol will correctly identify the basis state $|i\rangle$
- Why?
 - $P(a|i) = \text{tr}(M_a |e_i\rangle\langle e_i|)$
 - ↳ $P^{(N)}(a|i) = \prod_{i=1}^N P(a_k|i)$
 - i.e. N i.i.d. samples from one of the distributions $\{P(a|i)\}_i$.
 - d-ary hypothesis testing
↳ all RVs can be distinguished asymptotically as $N \rightarrow \infty$, with error vanishing exponentially fast.

* up to trivial post-processing of measurement results.

Generalised classical cloning sub-routine:



$$U|i\rangle|0\rangle^{\otimes(N-1)} = |e_i\rangle^{\otimes N}$$

where $|e_i\rangle$ forms some

D.N.B

Subtlety: How do we know that distributions $P(a|i)$ are distinct for all i ?

i.e. what if $P(a|0) = P(a|1) \quad \forall a?$

$$\text{e.g. } M_0 = |0\rangle\langle 0| \quad M_1 = |1\rangle\langle 1| + |2\rangle\langle 2|$$

We can deal with this by considering running different U on different subsets. (leave details for offline).

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- Why?

- $P(a|i) = \text{tr}(M_a |e_i\rangle\langle e_i|)$

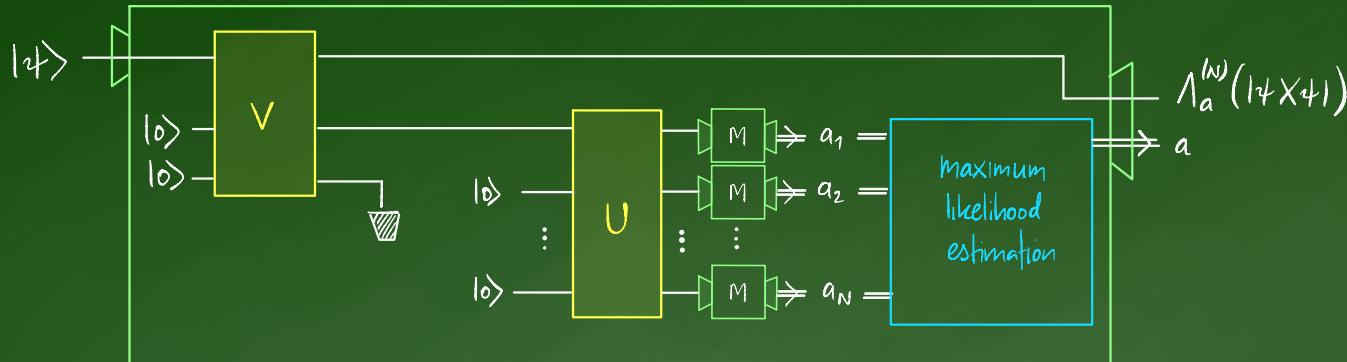
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Putting it all together



$$V|+\rangle|0\rangle|0\rangle = \sum_{a,j} k_j^a |+\rangle|a\rangle|j\rangle \quad U|i\rangle|0\rangle^{\otimes(N-1)} = |e_i\rangle^{\otimes N}$$

- Uses $N+1$ ancillary systems & N uses of available measurement.
- $\Lambda_a^{(N)}$ approaches target instrument as $N \rightarrow \infty$ (becomes physically indistinguishable)
- Not optimal but universal protocol

Other Results

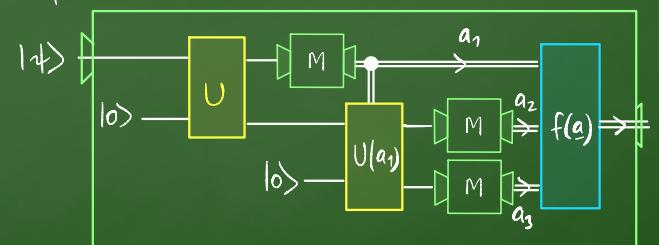
- In general optimal protocol minimising average TVD error $\langle \epsilon_{(N)} \rangle$ for fixed N will not be classical cloning (CNOT) protocol.
 - Optimal to apply unitaries that take $|0\rangle|0\rangle^{\otimes(N-1)}$ & $|1\rangle|0\rangle^{\otimes(N-1)}$ to non-orthogonal states.
 - Intuition: this performs worse for basis states but better for equatorial states $\frac{|0\rangle + e^{i\phi}|1\rangle}{\sqrt{2}}$
- Similarly optimal protocols sometimes involve probabilistic post-processing of measurement results.
 - Intuition: injecting randomness into simulation can again be useful (especially for equatorial states).
- Above protocol is zero rate: N uses of available measurement to simulate 1 use of target
 - Using ideas of (classical) block coding we can achieve finite rate protocols.
 - Given k -particle state & want to simulate k measurement results in parallel.
 - Rate lower bounded by classical capacity of classical channel $p(a|x) = \text{tr}(Ma|xX|)$.

Current & Future directions

- Practical question: What happens if unitaries & ancillary systems are noisy?
 - More general error correction ideas can be applied.
Not all noise is relevant e.g. dephasing irrelevant for \bar{z} meas.
 - Architecture specific analysis ions, Rydberg atoms, SC qubits etc.

- what is optimal protocol for a fixed number of uses?

- more general meas. protocols e.g.
- Don't have example of measurement where classical feed forward probably useful yet.



- what is the optimal rate of measurement simulation?
 - Analogue of coding theorem for measurements.

Conclusions

- Main result: Any non-trivial measurement can simulate arbitrarily well any other measurement given sufficient uses
 - Ability to perform projective meas. equivalent to ability to perform arbitrary instrument
 - Any measurement can distinguish a basis of states
≡ simulate a projective measurement
- Simple protocols & few uses improve measurements
→ lightweight measurement-error mitigation
- Lots of interesting future directions to explore.