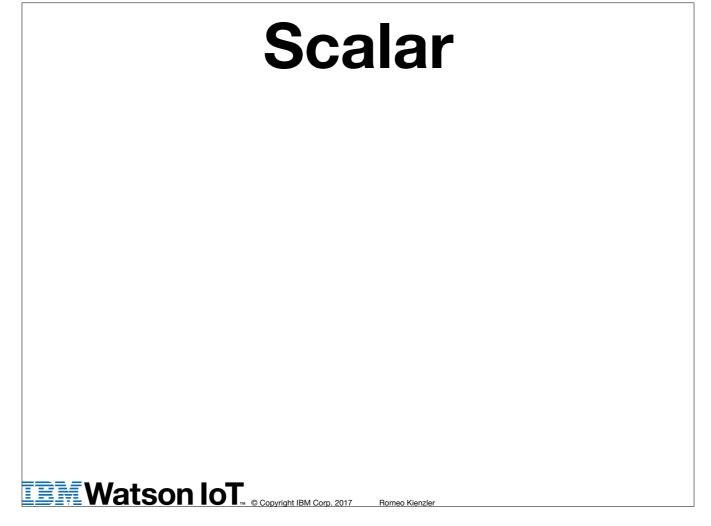
Linear Algebra

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Welcome to the lecture on linear algebra



So before we start with the math let's have a look at some important terms. Let's start with scalar.

Scalar

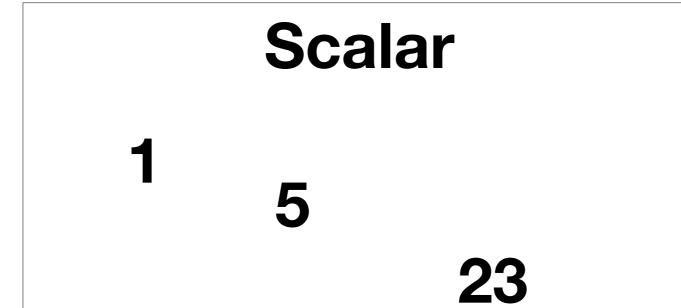


A scalar is basically any number ... like one...

Scalar

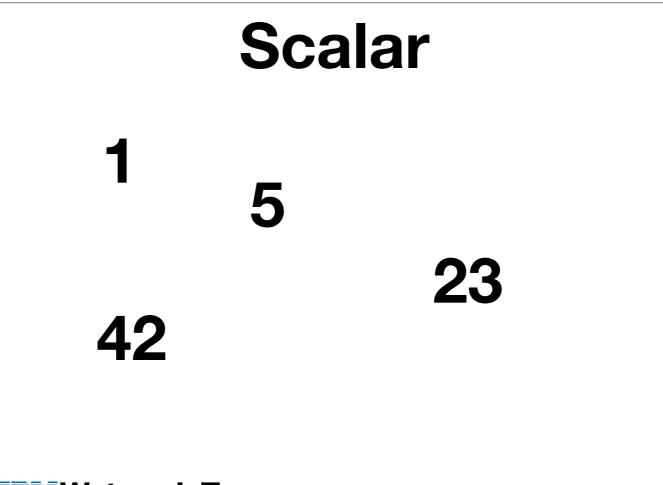
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..five..



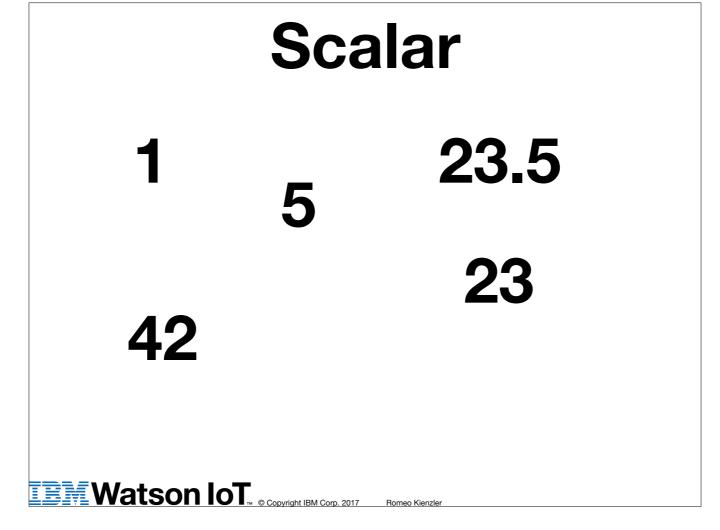
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..twenty-three...



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or fourth two....



but we are not limited to integers here...also a real number like twenty three dot five is a scalar...

Vector

(0,1,1,2)

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So if you group a bunch of scalars together you'll get a vector...so this is a vector of length four...

Vector

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...and this is one of length three...

Vector

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and this one of length five...





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So a vector can be easily confused with a tuple...

Tuple

(0,1,1,2)

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so this guy here can either be a vector or a tuple...

Tuple

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but this one is a tuple...can you see the difference? so in a vector, each element needs to have the same type, whereas in a tuple types can be mixed...





A matrix is the big brother of a vector

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it is basically a list of equal sized vectors

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note that the number of rows and columns can be different, but again, all elements need to have the same type

```
(0,1,1,2)
(1,5,1,2,7)
(1,5,1,2,7)
(0,1,1,4,2)
```

n - columns m - rows

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any matrix has n columns and m rows

```
(0,1,1,2)
(1,5,1,2,7)
(1,5,1,2,7)
(0,1,1,4,2)
```

n - columns m - rows m - by - n

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therefore we call those matrices m - by - n matrix

```
(0,1,1,2)
(1,5,1,2,7)
(1,5,1,2)
(0,1,1,4,2)
```

n - columns m - rows m - by - n

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so the left one is a three by four matrix

```
3 - by - 4

(0,1,1,2) 2 - by - 5

(1,5,1,2,7)

(1,5,1,2) (0,1,1,4,2)

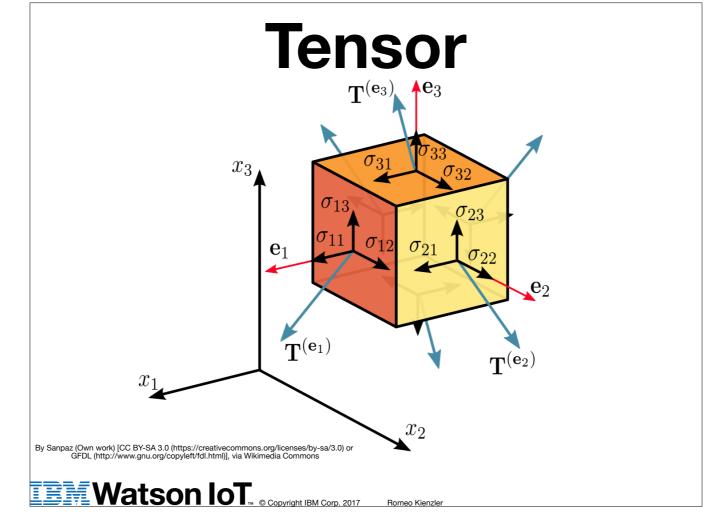
(0,1,1,4)
```

n - columns m - rows m - by - n

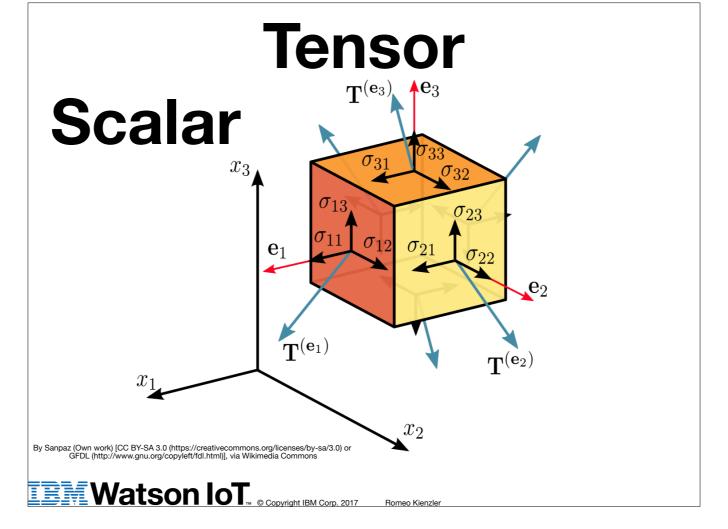
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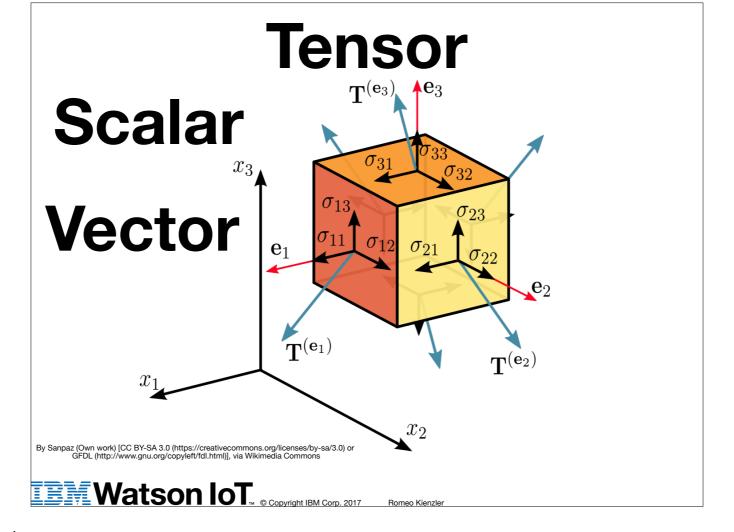
whereas the right one is a two by five matrix



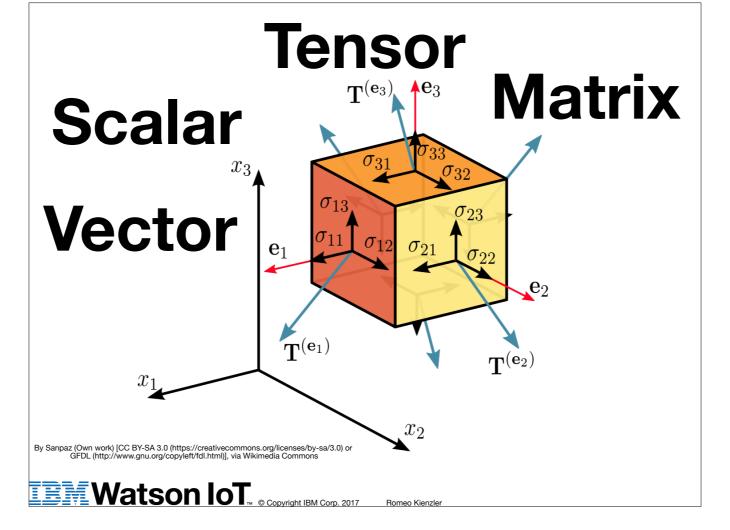
finally, the coolest guy is called a tensor. here you see a three dee tensor which is basically nothing else than a matrix with three instead of two dimension. three dee tensors are quite handy for image processing since beside two dimensional pixel information also colour, alpha and focus information can be expressed. tensor is a more general term for specials cases



 \ldots so for example a zero dimensional tensor is called scalar \ldots



a one dimensional tensor is called vector...



..and a two dimensional tensor is called matrix...so you can really show off in front of your colleagues by knowing all those terms :) so let's start with some math...

Multiplication



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the most important mathematical operation on tensors used in this course is multiplication

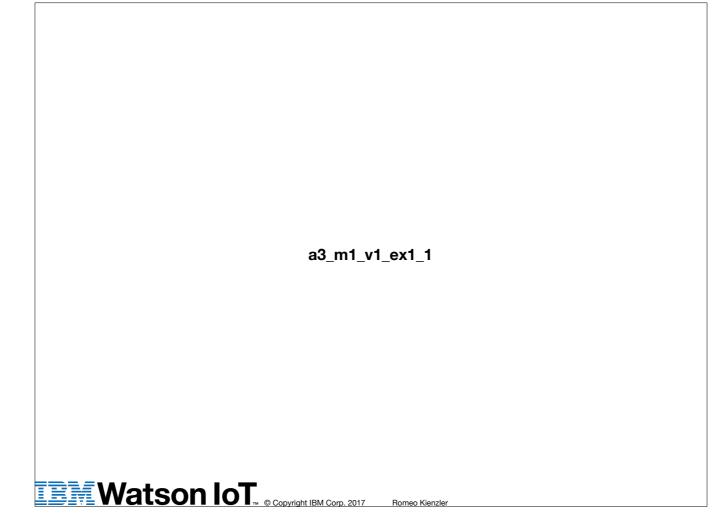
Scalar Multiplication

2 * 3 = 6

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we can multiply two scalars



So let start with two integers three and two. If we multiply them we get six as expected.

Scalar Multiplication

$$\begin{bmatrix} 0 \\ 1 \\ 3 \\ 6 \end{bmatrix} * \begin{bmatrix} 2 \\ 7 \\ 13 \\ 20 \end{bmatrix}$$

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but we can also multiply two vectors. note that the column wise notation is the most common in math. this multiplication is called dot product or scalar product because it returns a scalar. we won't cover the cross product or vector product here.

$$\begin{bmatrix} 0\\1\\3\\6 \end{bmatrix} * \begin{bmatrix} 2\\7\\13\\20 \end{bmatrix} = 0 * 2$$

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so the vector product simply takes the first element of the first vector and multiplies it with the first element of the second vector

$$\begin{bmatrix} 0 \\ 1 \\ 3 \\ 6 \end{bmatrix} * \begin{bmatrix} 2 \\ 7 \\ 13 \\ 20 \end{bmatrix} = 0 * 2 \quad 1 * 7$$

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then it does the same for the second elements of the two vectors

$$\begin{bmatrix} 0 \\ 1 \\ 3 \\ 6 \end{bmatrix} * \begin{bmatrix} 2 \\ 7 \\ 13 \\ 20 \end{bmatrix} = 0 * 2 \quad 1 * 7 \quad 3 * 13 \quad 6 * 20$$

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and finally for the rest

$$\begin{bmatrix} 0 \\ 1 \\ 3 \\ 6 \end{bmatrix} * \begin{bmatrix} 2 \\ 7 \\ 13 \\ 20 \end{bmatrix} = 0 * 2 + 1 * 7 + 3 * 13 + 6 * 20$$

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now all these intermediate products are summed up

$$\begin{bmatrix} 0 \\ 1 \\ 3 \\ 6 \end{bmatrix} * \begin{bmatrix} 2 \\ 7 \\ 13 \\ 20 \end{bmatrix} = 0 * 2 + 1 * 7 + 3 * 13 + 6 * 20 = 166$$

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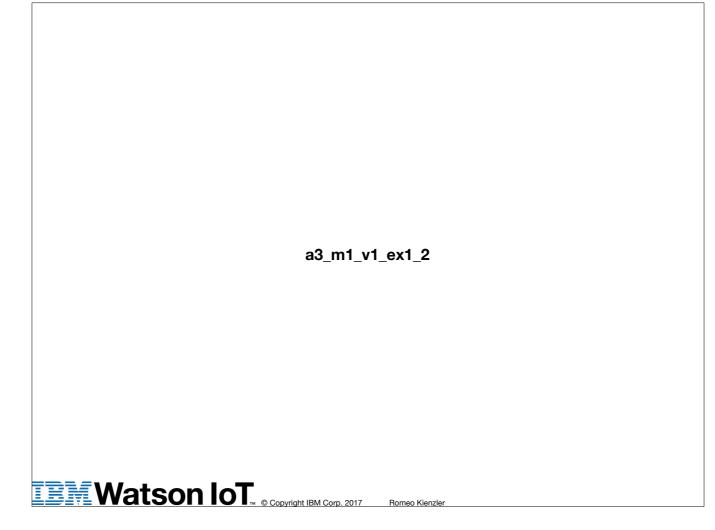
and the resulting sum is the solution to the vector dot product

$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} * \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} = a_1 * x_1 + a_2 * x_2 + a_3 * x_3 + a_4 * x_4$$

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more generally speaking, the vector dot product is the linear combination of those two vectors. and this notation is very handy in neural networks which we will see later because often one vector represents the data and one vectors the parameters to the neural network. also using this notation we can make use of accelerators like SIMD or GPUs. Note that both vectors need to be of the same size



We will use numpy as central library for linear algebra in python. So let's import it. Now we create two vectors a and b. Note that in python those are implemented as one dimensional numpy arrays. Now we can use the dot method of the numpy array object in order to get the dot product of those two vectors.

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$$

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Not only the multiplication of two vectors is defined, but also the multiplication of a matrix with a vector.

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 \end{bmatrix}$$

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So just take the element of the first row and column of the matrix..

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 \\ \end{bmatrix}$$

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...and multiply it with the first element of the vector...

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 \end{bmatrix}$$

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...and put it to the first element of the resulting vector

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 * 1 * 3 \end{bmatrix}$$

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then repeat the steps for the second column first row of the matrix with the second element of the vector

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 & 1 * 3 & 13 * 5 \\ 5 \end{bmatrix}$$

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finally repeat the steps for the third column first row of the matrix with the third element of the vector

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finally we repeat the same steps for the second row of the matrix

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 + 1 * 3 + 13 * 5 \\ 6 * 2 + 1 * 3 + 17 * 5 \end{bmatrix}$$

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then we sum up all those components

$$\begin{bmatrix} 1 & 1 & 13 \\ 6 & 1 & 17 \end{bmatrix} * \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 * 2 + 1 * 3 + 13 * 5 \\ 6 * 2 + 1 * 3 + 17 * 5 \end{bmatrix} = \begin{bmatrix} 70 \\ 100 \end{bmatrix}$$

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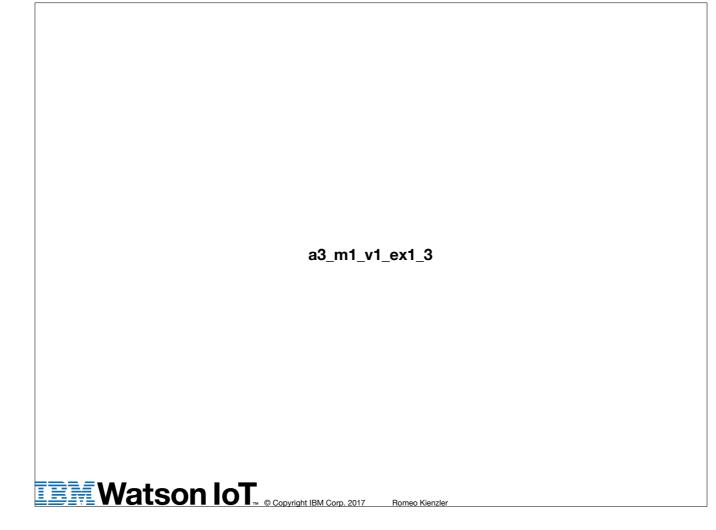
and the result is a two element vector. so this is nothing else than two vector dot products calculated in one go, where the first vector is encoded in the first row of the matrix and the second vector is encoded in the second row of the matrix. this is also very handy because SIMD and GPU accelerators can speed up things dramatically. also notation becomes far more concise

$$\begin{bmatrix} a & b & c \\ \vdots & & \\ d & e & f \end{bmatrix} * \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a*x+b*y+c*z \\ \vdots \\ d*x+e*y+f*z \end{bmatrix}$$

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as long as the number of columns matches the number of elements in the vector we can apply this multiplication to arbitrary factors. Vector Matrix multiplication is just a special case of Matrix Matrix multiplication, but we do not need to cover this now



So let's implement a vector matrix multiplication using numpy. We start with the same vector a and b and turn a into a matrix by using a two dimensional numpy array. Now we can use the same overloaded dot method in order to execute the matrix vector multiplication. Note that the result is the same as two sequential vector vector dot products. But now this computation is expressed in a single method call which can easily parallelized by SIMD instructions on CPUs or by GPUs.

Deep Feedforward Networks



Romeo Kienzle

so this was enough math for now and should enough to understand most of neural networks math, so let's get started with our first neural network