

HPC for numerical methods and data analysis

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Prof. Laura Grigori

Assistant: Tommaso Vanzan

Prepared by: Mariana Martinez Aguilar

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Communication in Python and MPI

Exercise I Reminder of a simple MPI code in Python

Given two vectors, b, c we want to compute d = 2b + c. Execute the following simple code on 2 processors several times.

```
from mpi4py import MPI
import numpy as np
b = np.array([1, 2, 3, 4])
c = np.array([5, 6, 7, 8])
a = np.zeros_like(b)
d = np.zeros_like(b)
comm = MPI.COMM_WORLD
rank = comm.Get_rank()
if rank == 0:
    for i in range(4):
        a[i] = b[i] + c[i]
    comm.Send(a, dest = 1, tag = 77)
else:
    comm.Recv(a, source = 0, tag = 77)
    for i in range(4):
        d[i] = a[i] + b[i]
print("I am rank = ", rank )
print("d: ", d)
```

Observe the order in which the prints take place and the value of d at the end.

Exercise II Point to point communication - blocking and non-blocking communication

- a) Provide a brief definition of MPI. What is a communicator?
- b) Execute the following simple code on 4 processors.

```
from mpi4py import MPI
import numpy as np
# Initialize MPI
comm = MPI.COMM_WORLD
rank = comm.Get_rank()
if rank == 0:
    data = {'a': 7, 'b': 3.14}
    print("From process: ", rank, "\n data sent:", data, "\n")
    comm.send(data, dest=1, tag=11)
elif rank == 1:
    data = comm.recv(source=0, tag=11)
    print("From process: ", rank, "\n data received:", data, "\n")
elif rank == 2:
    data = np.array([1, 1, 1, 1, 1])
    print("From process: ", rank, "\n data sent:", data, "\n")
    comm.send(data, dest=3, tag = 66)
else:
    data = comm.recv(source = 2, tag = 66)
    print("From process: ", rank, "\n data received:", data, "\n")
```

In this case, why do we need to be careful when specifying the dest and tag parameters on both comm.send and comm.recv?

c) Describe the difference between blocking communication and non-blocking communication in MPI. Modify the code above such that it uses comm.isend instead of comm.send and comm.irecv instead of comm.recv while ensuring the messages are passed correctly.

Exercise III Collective communication - scattering and broadcasting

a) Run the following script on 4 processors:

```
from mpi4py import MPI
import numpy as np

# Initialize MPI
comm = MPI.COMM_WORLD
rank = comm.Get_rank()
```

```
size = comm.Get_size()

# Define the vector
if rank == 0:
    vector = np.array([16, 62, 97, 25])
else:
    vector = None

data1 = comm.bcast(vector, root = 0)
data2 = comm.scatter(vector, root = 0)

print("rank: ", rank, " data1: ", data1, " data2: ", data2)
```

What is the difference in MPI between scattering and broadcasting?

- b) Consider the multiplication of a matrix $A \in \mathbb{R}^{m \times n}$ with a vector $v \in \mathbb{R}^n$. Write a Python file containing a script that:
 - Creates a matrix of dimension $m \times n$
 - \bullet Creates a vector of dimension n
 - ullet Makes sure that the dimensions of the matrix and the vector agree in such way that we can compute Av
 - Computes Av using MPI's scattering, make sure you execute your code on the right amount of processors (*Hints: you'll need to use* comm.gather. What are the entries of Av?)

Exercise IV Collective communication - all-to-all and reduce

• Run the following code on 4 processors:

```
from mpi4py import MPI
import numpy as np

comm = MPI.COMM_WORLD
size = comm.Get_size()
rank = comm.Get_rank()

senddata = rank*np.ones(size, dtype = int)

recvdata = comm.alltoall(senddata)

print(" process ", rank, " sending ", senddata, " receiving ", recvdata )

What is comm.alltoall doing? Compare it to comm.scatter.
```

• In this exercise we are going to use reduction operations on MPI. Run the following code on 4 processors:

What is a reduction operation? What is the difference between this and comm.gather?

• In the previous code, change comm.reduce to comm.allreduce. What is the difference between the two? (Note, comm.allreduce doesn't use the argument root).

Exercise V Deciding what to use - Mid point rule

Numerical integration describes a family of algorithms for calculating the value of definite integrals. One of the simplest algorithms to do so is called the Mid Point Rule. Assume that f(x) is continous on [a, b]. Let n be a positive integer and h = (b - a)/n. If [a, b] is divided into n subintervals, $\{x_0, x_1, ..., x_{n-1}\}$, then if $m_i = (x_i + x_{i+1})/2$ is the midpoint of the i-th subinterval, set:

$$M_n = \sum_{i=1}^n f(m_i)h.$$

Then:

$$\lim_{n \to \infty} M_n = \int_a^b f(x) dx.$$

Thus, for a fixed n, we can approximate this integral as:

$$\int_{a}^{b} f(x)dx \approx \sum_{i=1}^{n} f(m_i)h$$

Set n = s * 500, $f(x) = \cos(x)$, a = 0, $b = \pi/2$. Write a Python script such that:

- Defines a function that given x_i, h, n first calculates 500 mid points on a subinterval $[x_i, x_{i+1}]$ and returns the approximation of the integral on this subinterval.
- ullet Using MPI approximates the integral of f on [a,b]
- \bullet Run your script on s processors

to approximate the integral of f. (Hints: there are many ways of doing this, one approach is using comm.bcast and comm.reduce).