## Weakest Preconditions, v.2

## Part 1: Definitions and Basic Properties

CS 536: Science of Programming, Fall 2022

#### A. Why

• Weakest liberal preconditions (*wlp*) and weakest preconditions (*wp*) are the most general requirements that a program must meet to be correct.

#### B. Objectives

At the end of today you should understand

• What wlp and wp are and how they are related to preconditions in general.

#### Part 1: The Deterministic Case

## C. Weakening the Precondition of $\models_{tot} \{p\} S \{q\}$

- Let's assume that S is deterministic. Figure 1 illustrates how  $\vDash_{tot} \{p\} S \{q\}$  works: If you take any state in p and follow the arrow by applying S, you end in a state that satisfies q.
  - (To illustrate partial correctness, we would add arrows from p to  $\neg q$  or to  $\bot$ .)
- The predicate r intersects p, so states within  $p \wedge r$  are guaranteed to lead (via S) to states in q.
- Now, states in  $\neg p \land r$  might lead via S to p or  $\neg p$  or to  $\bot$ , but if all of them lead to p, then we could extend our precondition p and we'd have  $\{p \lor \neg p \land r\} S \{q\}$ , which simplifies to  $\{p \lor r\} S \{q\}$ .
  - A shorter way to say this is if  $\vDash_{tot} \{p\} S \{q\}$  and  $\vDash_{tot} \{\neg p \land r\} S \{q\}$ , then  $\vDash_{tot} \{p \lor r\} S \{q\}$ .
  - Of course, in general, we don't know  $\models_{tot} \{ \neg p \land r \} S \{ q \}$ , but if we can prove it, we can weaken the precondition p to r, which provides the user with more flexibility for running S.
- **Definition:** w is the weakest precondition of S and q (we write w = wp(S, q)) if w is a precondition that can't be weakened. I.e.,  $\models_{tot} \{ w \} S \{ q \}$  and there is no r strictly stronger than w such that  $\models_{tot} \{ r \} S \{ q \}$ .
  - We already know the converse; we've been calling it precondition strengthening: If  $\vDash_{tot} \{ w \} S \{ q \}$ , then knowing  $r \to w$  lets us conclude (is **sufficient** for)  $\vDash_{tot} \{ r \} S \{ q \}$ .
  - Being the weakest precondition makes  $r \rightarrow w$  a **necessary** condition for  $\models_{tot} \{r\} S \{q\}$ .
  - So if w is the weakest precondition, then  $\{r\}$  S  $\{q\}$  iff  $w \rightarrow r$ .
  - In terms of states,  $wp(S, q) = \{ \sigma \in \Sigma \mid M(S, \sigma) \models q \}$

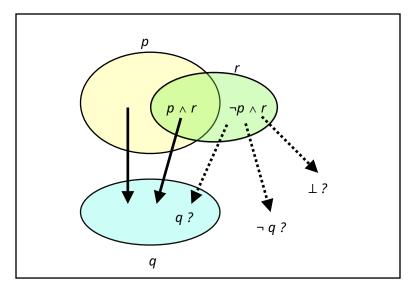


Figure 1: Extending Precondition of { p } S { q }

(Under total correctness)

- Recall that in general,  $\models_{tot} \{ p \} S \{ q \}$  doesn't tell us anything about  $M(S, \sigma)$  if  $\sigma \not\models p$ . But if p is weakest, we know  $M(S, \sigma) \not\models q$ .
  - For deterministic programs, we can state this using partial correctness: If w = wp(S, q) and S is deterministic then  $\models \{\neg w \} S \{\neg q \}$ . If  $\sigma \models \neg w$  then  $M(S, \sigma) = \{\tau\}$  where  $\tau = \bot$  or  $\tau \models \neg q$ .
- We'll write wp(S, q) as a predicate, but technically wp(S, q) is a set of states (the set of all states that are preconditions of S and q under total correctness). As sets, there are wp(S, q) that don't correspond well to writable predicates, and in those cases we'll have to write predicates that approximate wp(S, q).
- Usually, we talk about "the" wp(S, q), but as a predicate, a wp is unique only "up to logical equivalence": If  $u \Leftrightarrow w$ , then u is also a wp. So in general if we have that the wp(S, q) is x > 0, then  $x \ge 1$  and 0 < x, etc. are also wp's.
- But later, we'll see a syntactic algorithm that helps us calculate some *wp*'s; in those cases, we'll prefer the representation produced by the algorithm.

## D. The Weakest Liberal Precondition, wlp

- The *weakest liberal precondition* is analogous to the *wp* but for partial correctness instead of total correctness.
- **Definition**: The **weakest liberal precondition** for S and q, written wlp(S, q), is a valid precondition for q under partial correctness where no strictly weaker valid precondition exists.
  - In symbols, w = wlp(S, q) iff  $\models \{w\}$  S  $\{q\}$  and for all  $u, \models \{u\}$  S  $\{q\}$  if and only if  $\models u \rightarrow w$ .
  - In terms of states,  $wlp(S, q) = \{ \sigma \in \Sigma \mid M(S, \sigma) \bot \models q \}.$

$$wlp(S, q) \begin{cases} \sigma \in wp(S, q) & \text{iff} \quad M(S, \sigma) = \{\tau\} \vDash q \\ M(S, \sigma) = \{\bot\} \\ \sigma \in wp(S, \neg q) & \text{iff} \quad M(S, \sigma) = \{\tau\} \vDash \neg q \end{cases}$$
 
$$wlp(S, \neg q)$$

Figure 2: The Weakest Liberal Precondition for Deterministic S

#### Relationships Between wp and wlp

- Figure 2 illustrates the relationships between wp and wlp for deterministic programs.
- The top third shows the states in wp(S, q): For them,  $M(S, \sigma)$  satisfies q.
- The bottom third shows the states in  $wp(S, \neg q)$ : For them,  $M(S, \sigma)$  satisfies  $\neg q$ .
- The middle third shows that states that cause nontermination.
  - Adding the nonterminating states to wp(S, q) gives wlp(S, q).
  - Adding the nonterminating states to  $wp(S, \neg q)$  gives  $wlp(S, \neg q)$ .
  - Subsequently,  $\neg wp(S, \neg q) \Leftrightarrow wlp(S, q)$  and  $\neg wp(S, q) \Leftrightarrow wlp(S, \neg q)$ .
- And one more relationship:  $wlp(S, q) \wedge wlp(S, \neg q)$  describes the states that cause nontermination.

#### Why Are wp and wlp Important?

- The reason wp and wlp are important is that if you have a precondition and can show that it's the
  weakest precondition, you have the most general solution to "What states can I start in and
  successfully end in q?
  - With wp, "successfully end" means "terminates satisfying q". With wlp, it means "if we terminate, we terminate satisfying q".
- The solution is most general in the sense that any state not satisfying the *wp* or *wlp* is guaranteed to *not* successfully end in *q*.
- Compare with non-weakest preconditions, where starting in a state not satisfying the precondition might end successfully or end not successfully (satisfying  $\neg q$ ) or not terminate.

## E. Examples of wp and wlp

- **Example 1**: The assignment y := x\*x always terminates, so wp and wlp behave identically on it.  $wp(y := x*x, x \ge 0 \land y \ge 4) \Leftrightarrow wlp(y := x*x, x \ge 0 \land y \ge 4) \Leftrightarrow x \ge 2$ .
- **Example 2**: The wp and wlp of if  $y \le x$  then m := x else skip fi and m = max(x, y) are  $(y > x \rightarrow m = y)$ .
  - Later, we'll see an algorithm for calculating the wp in this instance, but for now, intuitively, the true branch sets up the postcondition when  $y \le x$ . The false branch (implicitly *else skip*) runs when y > x but it does nothing, we need to already be in a state that satisfies the postcondition, namely m = y.
- **Example 3**: The weakest precondition of while  $x \ne 0$  do x := x-1 od and x = 0 is  $x \ge 0$ . Starting with  $x \ge 0$  terminates with x = 0, and starting with x < 0 doesn't terminate.

- The *wlp* of the loop and postcondition is simply *T*. Since we're ignoring termination, the body of the loop doesn't affect the fact that for *while*  $x \ne 0$  ... to exit, x must be zero.
- Our loop terminates iff run with  $x \ge 0$ , so if W is our loop, then  $wp(W, T) \Leftrightarrow x \ge 0$ .
- We can verify  $x \ge 0 \Leftrightarrow wp(W, x = 0) \Leftrightarrow wlp(W, x = 0) \land wp(W, T) \Leftrightarrow T \land x \ge 0 \Leftrightarrow x \ge 0$ .
- **Example 4**: The weakest precondition of  $W = while \, x > 0 \, do \, x := x-1 \, od \, and \, x \le 0 \, is \, T$  (true). Again, starting with  $x \ge 0$  terminates with x = 0, and if we want to terminate with some particular value of x < 0, we can just start with x = 0 that value because the loop terminates immediately.
  - Since  $T \Leftrightarrow wp(W, x \le 0) \Leftrightarrow wlp(W, x \le 0) \land wp(W, T)$ , both  $wlp(W, x \le 0)$  and  $wp(W, T) \Leftrightarrow T$ . Semantically, we can also justify this by arguing that  $while \ x > 0$  ... terminates immediately iff  $x \le 0$ .
- **Example 5**: For any S and  $\sigma$ , either we terminate (in a state satisfying true) or we don't terminate. Therefore  $wlp(S, T) \Leftrightarrow T$ . Also, since  $wlp(S, T) \Leftrightarrow \neg wp(S, \neg T) \Leftrightarrow T$ , we see  $wp(S, F) \Leftrightarrow F$ . (In Figure 2 terms, the bottom third of the diagram is empty because running S in  $\sigma$  never terminates in a state satisfying false.)

#### Part 2: The Nondeterministic Case

- With nondeterministic programs, *wp* and *wlp* are more complicated (of course). The basic definitions are the same:
  - $\sigma \in wp(S, q)$  iff  $M(S, \sigma) \models q$  or equivalently  $\models_{tot} \{p\} S \{q\}$  iff  $\models wp(S, q) \rightarrow p$
  - $\sigma \in wlp(S, q)$  iff  $M(S, \sigma) \bot \models q$  or equivalently  $\models \{p\} S \{q\}$  iff  $\models wlp(S, q) \rightarrow p$
- Let  $\Sigma_0 = M(S, \sigma)$  or  $M(S, \sigma) \bot$  depending on whether we're discussing wp or wlp.
- Since  $\Sigma_0$  satisfies q iff every individual state in  $\Sigma_0$  satisfies q, nonsatisfaction only requires one counterexample state:
  - $\sigma \notin wp(S, q)$  iff for some  $\tau \in M(S, \sigma)$ , we have  $\tau = \bot$  or  $\tau \not\models q$  (and since  $\tau$  is a state,  $\tau \models \neg q$ ).
  - $\sigma \notin wlp(S, q)$  iff for some  $\tau \in M(S, \sigma)$ , we have  $\tau \not\models q$  (and since  $\tau$  is a state,  $\tau \models \neg q$ ).
- But there are no constraints on other members of  $\Sigma_0$ , so  $\sigma \notin wp(S, q)$  and  $\sigma \notin wlp(S, q)$  are both compatible with having  $\tau \in M(S, \sigma)$  with  $\tau \vDash q$ .

# F. Properties of wp and wlp for Deterministic and Nondeterministic Programs

- There are a number of properties connecting the wp, wlp,  $\neg wp$ , and  $\neg wlp$  of q and  $\neg q$ .
- Some properties are common to both deterministic and nondeterministic programs:
  - 1.  $M(S, \sigma) = \{\bot\} \Rightarrow wlp(S, q) \land wlp(S, \neg q)$ 
    - $M(S, \sigma) \bot = \emptyset$ , so it  $\models q$  and  $\models \neg q$ , so  $\sigma \models wlp(S, q) \land wlp(S, \neg q)$ .
  - 2.  $M(S, \sigma) = \{\bot\} \Rightarrow \neg wp(S, q) \land \neg wp(S, \neg q)$ 
    - $M(S, \sigma) = \{\bot\} \not\models q \text{ and } \not\models \neg q, \text{ so } \sigma \models \neg wp(S, q) \land \neg wp(S, \neg q).$

- 3.  $wlp(S, q) \land wlp(S, \neg q) \Rightarrow M(S, \sigma) = \{\bot\}$ 
  - For  $\sigma \vDash wlp(S, q) \land wlp(S, \neg q)$ , we must have  $M(S, \sigma) \bot \vDash q \land \neg q$ . So,  $M(S, \sigma) \bot \equiv \emptyset$ , so  $M(S, \sigma) = \{\bot\}.$
- 4.  $wp(S, q) \Rightarrow wlp(S, q)$ 
  - If  $\sigma \models wp(S, q)$ , then  $M(S, \sigma) \models q$ , so  $M(S, \sigma) \bot \models q$ , and so  $\sigma \models wlp(S, q)$ .
- 5.  $wlp(S, q) \Rightarrow \neg wp(S, \neg q)$ 
  - If  $\sigma \models wlp(S, q)$ , then  $M(S, \sigma) \bot \models q$ , so for all  $\tau \in M(S, \sigma) \bot$ ,  $\tau \not\models \neg q$ . If  $\bot \in M(S, \sigma)$  then it  $\not\models \neg q$ , so  $\tau \not\models \neg q$ .
- 6.  $wp(S, q) \Rightarrow \neg wlp(S, \neg q)$ 
  - If  $\sigma$  is in wp(S, q) then  $M(S, \sigma) \models q$ . For  $\sigma$  to be in  $wlp(S, \neg q)$ , we need every  $\tau \in M(S, \sigma)$  to be either  $\bot$  or to satisfy  $\neg q$ . But every  $\tau \in M(S, \sigma)$  satisfies q, so it's neither  $\bot$  nor satisfies  $\neg q$ . So if  $\sigma$  is in wp(S, q), it's not in  $wlp(S, \neg q)$ , it's in  $\neg wlp(S, \neg q)$ .
- There are also properties that hold for deterministic programs but not nondeterministic programs.
  - 7a. If S is deterministic, then  $\neg wp(S, q) \land \neg wp(S, \neg q) \Rightarrow M(S, \sigma) = \{\bot\}$ .
    - For deterministic *S*,  $M(S, \sigma) = \text{some } \{\tau\}$ , where either  $\tau = \bot$ ,  $\tau \models q$ , or  $\tau \models \neg q$ . But  $\sigma \models$  $\neg wp(S, q) \land \neg wp(S, \neg q)$  implies that  $M(S, \sigma) \not\models q$  and  $M(S, \sigma) \not\models \neg q$ , which leaves  $M(S, \sigma) =$  $\{\bot\}$  as the only possibility.
  - 7b. If S is nondeterministic, then  $\neg wp(S, q) \land \neg wp(S, \neg q)$  doesn't imply  $M(S, \sigma) = \{\bot\}$ .
    - For a nondeterministic program, if  $M(S, \sigma) \not\models g$  and  $M(S, \sigma) \not\models \neg g$ , it's still possible for  $M(S, \sigma)$  to contain non- $\bot$  states. A simple counterexample is  $M(S, \sigma) = \{\tau_1, \tau_2\}$  where  $\tau_1 = q$ and  $\tau_2 \models \neg q$ . Note it's possible that  $\bot \notin M(S, \sigma)$ , which definitely makes  $M(S, \sigma) \neq \{\bot\}$ .
  - 8a. If S is deterministic, then  $\neg wp(S, q) \Rightarrow wlp(S, \neg q)$ 
    - $M(S, \sigma) = \{t\}$  where  $\tau = \bot$ ,  $\tau \models q$ , or  $\tau \models \neg q$ . If  $\sigma \models \neg wp(S, q)$ , then  $\tau \models q$  fails, which leaves  $\tau = \bot$  or  $\tau \models \neg q$ , in which case  $M(S, \sigma) - \bot \models \neg q$ , so  $\sigma \models wlp(S, \neg q)$ .
  - 8b. If S is nondeterministic, then  $\neg wp(S, q)$  doesn't imply  $wlp(S, \neg q)$ 
    - When  $M(S, \sigma) \not\models q$ , there can still be a  $\tau_1 \in M(S, \sigma)$  with  $\tau_1 \models q$ , in which case  $\sigma \not\models wlp(S, \neg q)$ .

### G. Disjunctive Postconditions Behave Differently Under Nondeterminism

- For deterministic and nondeterministic both, the wp/wlp of a conjunction is the same as the conjunction of the *wp/wlp*'s.
  - $wp(S, q_1) \land wp(S, q_2) \Leftrightarrow wp(S, q_1 \land q_2)$
  - $wlp(S, q_1) \wedge wlp(S, q_2) \Leftrightarrow wlp(S, q_1 \wedge q_2)$
- Also, the disjunction of the *wp/wlp*'s implies the *wp/wlp* of the disjunction:
  - $wp(S, q_1) \vee wp(S, q_2) \Rightarrow wp(S, q_1 \vee q_2)$
  - $wlp(S, q_1) \vee wlp(S, q_2) \Rightarrow wlp(S, q_1 \vee q_2)$

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- However, the other direction only works for deterministic programs:
  - For deterministic S only,
    - $wp(S, q_1 \vee q_2) \Rightarrow wp(S, q_1) \vee wp(S, q_2)$
    - $wlp(S, q_1 \vee q_2) \Rightarrow wlp(S, q_1) \vee wlp(S, q_2)$
- But for nondeterministic programs,  $wp(S, q_1 \lor q_2) \Rightarrow wp(S, q_1) \lor wp(S, q_2)$  doesn't have to hold.
- The standard example for this property is a coin-flip program.
- **Example 11**: Let  $flip = if T \rightarrow x := 0 \square T \rightarrow x := 1 fi$ .
  - Let heads = x = 0 as and tails = x = 1, then  $M(flip, \emptyset) = \{\{x = 0\}, \{x = 1\}\}$ , which  $\models heads \lor tails$  but  $\not\models heads$  and  $\not\models tails$ . So  $wp(flip, heads \lor tails) = T$  but wp(flip, heads) = wp(flip, tails)
- In general, let  $M(S, \sigma) = \Sigma_1 \cup \Sigma_2$  where  $\Sigma_1 \vDash q_1$  and  $\Sigma_2 \vDash q_2$ . If  $q_1$  and  $q_2$  are not  $\Leftrightarrow$  under  $\sigma$ . then  $\Sigma_1 \neq \Sigma_2$ . Also, assume  $\Sigma_1$  and  $\Sigma_2$  are not  $\varnothing$ . Then  $\Sigma_1 \cup \Sigma_2 \vDash q_1 \vee q_2$ , but since  $\Sigma_1 \cup \Sigma_2$  includes elements that satisfy  $q_1$  and  $q_2$ , we don't have  $\Sigma_1 \cup \Sigma_2 \vDash q_1$  or  $\Sigma_1 \cup \Sigma_2 \vDash q_2$ . separately.