# Correctness ("Hoare") Triples, pt. 1

## CS 536: Science of Programming, Fall 2022

Sep 26: Added q. 16, 17

## A. Why

• To specify a program's correctness, we need to know its precondition (what must be true before executing it) and its postcondition (what should be true after it).

## B. Objectives

At the end of this practice you should be able to

- Recognize syntactically correct correctness triples.
- Say whether a correctness triple is satisfied, given information about whether the current state satisfies the precondition, whether the statement terminates, and if it does, whether the terminating state satisfies the postcondition.

## C. Questions

For all the questions below, you can assume (unless otherwise said) that  $\sigma \in \Sigma$ , not  $\Sigma_{\perp}$ . (I.e., we're not trying to start run a program after an infinite loop or runtime failure.)

- 1. For a loop-free program without runtime errors, is there any difference between partial and total correctness?
- 2. Say we're given  $\sigma = \{x > 0\}$  S  $\{y > x\}$  for all  $\sigma$  and we're given a state  $\tau$  where  $\tau(x) = -3$ . Do we know what S will do if we run in  $\tau$ ? Must it terminate (without a runtime error)? Must it produce a runtime error? Must it diverge? Must y > x afterwards? How about  $y \le x$ ?
- 3. For which  $\sigma$  does  $\sigma \models \{x > 1\}$   $y := x*x \{y > x\}$  hold? Is this triple valid?
- 4. For which  $\sigma$  does  $\sigma = \{x > 0\}$   $y := x*x \{y > x\}$  hold? Is this triple valid?
- 5. Under partial correctness, does  $\models$  {F} S {q} hold for all  $\sigma$ , q, and S? What about  $\models$  {p} S {T}? Do these triples say anything interesting about *S*?
- 6. Repeat the previous question under total correctness: Does  $\models_{tot} \{F\} S \{q\}$  always hold? Does  $\models_{tot} \{p\} \ S \ \{T\}$ ? If they do, then do they say anything interesting about S?

For Problems 7 – 14, say for each statement whether it's true or false and give a brief explanation. (Just a sentence or two is fine.) Assume  $\sigma \in \Sigma$ . (Remember, if  $\sigma \models$  any predicate or triple, then  $\sigma \neq \bot$ .) In general, programs might be deterministic or nondeterministic.

- 7. If  $\sigma \vDash \{p\}$   $S \{q\}$ , then  $\sigma \vDash p$ .
- 8. If  $\sigma \not\models \{p\}$   $S \{q\}$ , then  $\sigma \not\models p$ .

- 9. If  $M(S, \sigma) \subseteq \{\perp_d, \perp_e\}$ , then  $\sigma \models \{p\} S \{q\}$ .
- 10. If  $\sigma \vDash p$  and  $M(S, \sigma) \cap \{\bot_d, \bot_e\} \neq \emptyset$ , then  $\sigma \nvDash_{tot} \{p\} S \{q\}$ .
- 11. If  $\sigma \models \{p\}$  S  $\{q\}$  and  $\sigma \models p$ , then every state in  $M(S, \sigma)$  either  $\{L_d, L_e\}$  or satisfies q.
- 12. If  $\sigma \models \{p\}$  S  $\{q\}$  and  $\sigma \not\models p$ , then every state in  $M(S, \sigma)$  is either  $\in \{\bot_d, \bot_e\}$  or satisfies  $\neg q$ .
- 13. For nondeterministic *S*, if  $\sigma \not\models \{p\}$  *S*  $\{q\}$ , then  $\tau \models \neg q$  for some  $\tau \in M(S, \sigma)$  but it's possible that for some other  $\xi \in M(S, \sigma)$ , we have  $\xi \models q$ .
- 14. For nondeterministic S, if  $\sigma \not\models_{tot} \{p\}$  S  $\{q\}$ , if  $\bot \not\in M(S, \sigma)$ , then  $\tau \models \neg q$  for some  $\tau \in M(S, \sigma)$  but it's possible that for other some other  $\xi \in M(S, \sigma)$ , we have  $\xi \models q$ .
- 15. Let S = x := x \* x; y := y \* y and let  $\sigma(x) = \alpha$  and  $\sigma(\xi) = \beta$ . Verify that  $\sigma \models_{tot} \{x > y > 0\}$   $S \{x > y > 0\}$ as follows. First assume  $\sigma$  satisfies the precondition, then calculate  $M(S, \sigma)$ , and then verify that  $M(S, \sigma) - \bot$  satisfies the postcondition.

#### [2022-09-26 - added]

- 16. What are the mostly trivial cases for partial and total correctness?
- 17. How do we symbolically write that total correctness is partial correctness plus termination?

### Solution to Practice 8 (Hoare Triples, pt 1)

- 1. For a loop-free, failure-free program, there's no difference between partial and total correctness.
- 2. No to all the questions: The triple only tells us what will happen if the precondition is satisfied. Since  $\tau$  doesn't satisfy the precondition, the triple doesn't say anything about what will happen when you run S in  $\tau$ . S might diverge, it might cause an error. It might terminate in which case the final state might satisfy the postcondition or it might not.
- 3. All states satisfy the triple, so the triple is valid.
- 4. States with x > 1 set y appropriately and do satisfy the triple. States with x < 1 satisfy the triple trivially. But in states with x = 1 do not satisfy the triple. So, the triple is not valid, since it's not satisfied in all states.
- 5. Under partial correctness, for all S, both triples are valid:  $\models \{F\} S \{q\} \text{ and } \models \{p\} S \{T\}$ . But neither triple says anything useful about the program S.
- 6. Under total correctness, we again have validity:  $\models_{tot} \{F\} \ S \{q\}$ , but again it says nothing useful about S. However,  $\models_{tot} \{p\} S \{T\}$  says that if  $\sigma \models p$ , then running S in  $\sigma$  will terminate. We don't get any information about what the final state looks like, but at least there is one. As usual, if  $\sigma \not\models p$ , then we know nothing about what will happen if you run S in  $\sigma$ .
- 7. False;  $\sigma \vDash \{p\}$   $S \{q\}$  does not imply  $\sigma \vDash p$ . (It doesn't imply  $\sigma \not\vDash p$  either.)
- 8. False; if  $\sigma \in \Sigma$  and  $\sigma \not\models \{p\}$   $S \{q\}$ , then  $\sigma \models p$  (and  $M(S, \sigma) \bot \models \neg q$ ).
- 9. True.  $M(S, \sigma) \subseteq \{\perp_d, \perp_e\}$  says that S never terminates when run in  $\sigma$ . (It diverges or gets a runtime error.) Nontermination in  $\sigma$  implies partial correctness in  $\sigma$ .
- 10. True.  $M(S, \sigma) \cap \{\perp_d, \perp_e\} \neq \emptyset$  says that S might not terminate when run in  $\sigma$ . I.e., at least one execution path causes an error:  $\langle S, \sigma \rangle \rightarrow^* \langle E, \bot \rangle$ . That path causes total correctness to fail:  $\sigma \nvDash_{tot} \{p\} S \{q\}.$
- 11. True; if  $\{p\}$  S  $\{q\}$  is partially correct and we run S in a state satisfying p, then either S causes an error or terminates in a state satisfying q.
- 12. False; if a triple is satisfied in  $\sigma$  but  $\sigma$  doesn't satisfy the precondition, then all possibilities can happen: S might diverge, it might cause a runtime error, and even if it terminates, the final state might satisfy q but it doesn't have to.
- 13. True; if partial correctness fails, it's because (for some execution path), running S terminates satisfying  $\neg q$ . If S is nondeterministic, it's still possible for there to be an execution path in which S terminates satisfying q.
- 14. True; we assumed  $\bot \notin M(S, \sigma)$ , so if total correctness fails, it's because running S can terminate satisfying  $\neg q$ . If S is nondeterministic, it's still possible for there to be an execution path in which S terminates satisfying q.

15. We're given S = x := x \* x; y := y \* y and  $\sigma(x) = \alpha$  and  $\sigma(y) = \beta$ . For arbitrary  $\sigma$ ,

$$M(S, \sigma) = M(x := x * x; y := y * y, \sigma)$$

$$= M(y := y * y, M(x := x * x, \sigma))$$

$$= M(y := y * y, \sigma[x \mapsto \alpha^2]))$$

$$= \{ \sigma[x \mapsto \alpha^2][y \mapsto \beta^2] \}.$$

Since  $\sigma(x) = \alpha$  and  $\sigma(y) = \beta$ , we know  $\sigma = x > y > 0$  implies  $\alpha > \beta > 0$ , which implies  $\alpha^2 > \beta^2 > 0$ , which implies  $M(S, \sigma) = \{ \sigma[x \mapsto \alpha^2][y \mapsto \beta^2] \} \models x > y > 0.$ 

This gives us total correctness right away, but just for practice we can analyze the situation for both partial correctness and termination. For partial correctness, we have  $M(S, \sigma) - \bot =$  $\{ \sigma[x \mapsto \alpha^2][y \mapsto \beta^2] \} - \bot = \{ \sigma[x \mapsto \alpha^2][y \mapsto \beta^2] \}$ , which satisfies the postcondition, x > y > 0. For termination,  $M(S, \sigma) - \bot = M(S, \sigma)$ , so  $\bot \notin M(S, \sigma)$ , which means termination. Partial correctness plus termination gives us total correctness:  $\sigma \models_{tot} \{x > y > 0\}$   $S\{x > y > 0\}$ .

#### [2022-09-26 - added]

- 16. The truly trivial cases are  $\models \{p\}$   $S \{q\}$  and  $\models_{tot} \{p\}$   $S \{q\}$  when
  - *p* is a contradiction
  - S always doesn't terminate
  - (For partial correctness) *q* is a tautology.
  - For total correctness, if q is a tautology, then the correctness triple says that S always terminates when started in a state that satisfies p. (We know the final state exists but we don't know anything else about it.)

#### [2022-09-26 - added]

17.  $\vDash_{tot} \{p\} \ S \ \{q\} \ \text{iff} \vDash \{p\} \ S \ \{q\} \ \text{and} \vDash_{tot} \{p\} \ S \ \{T\}.$