```
syms x;
y1 = inline('8 + 4*cos(x)')
y = @(x) 8 + 4*cos(x);
%int(y(x))
a = 0;
b = pi/2;
analytical_sol = double(int(y1(x),a,b))
%trapezoidal rule
c = (b-a)/2;
integ\_trape = c * (y(a) + y(b))
x = linspace(a,b,3);
x1 = linspace(a,b,5);
h = (b-a)/2;
integ_trap_2seg = h/2 * (y(x(1)) + 2*y(x(2)) + y(x(3)))
integ_trap_4seg = (h/4)*(y(x1(1)) + 2*(y(x1(2)) + y(x1(3)) +
y(x1(4))) + y(x1(5))
integ_sim13rd = (h/3) * (y(a) + 4*y(a+b/2) + y(b))
x2 = linspace(a,b,7); %% in Simpsons 3/8th rule we generally divide
 the interval into n segments where n is a multiple of 3 I take n = 6
 so 7 points
%and h will be (b-a)/6
integ_sim38 = (3*h/24)*(y(x2(1)) + y(x2(end)) + 2*(y(x2(4))) +
 3*(y(x2(2)) + y(x2(3)) + y(x2(5)) + y(x2(6)))
y1 =
     Inline function:
     y1(x) = 8 + 4*\cos(x)
analytical_sol =
   16.5664
integ_trape =
   15.7080
```

```
integ_trap_2seg =
    16.3586

integ_trap_4seg =
    16.5148

integ_sim13rd =
    16.5755

integ_sim38 =
    16.5666
```

composite simpson's rule with 4 segments

```
xn = linspace(a,b,5);  %%for composite simpson's rule with 4 th
  segments;
% where h is (b-a)/4 xj = a + j*h;
hn = (b-a)/4;
integ_compsimp_rule = (hn/3).*( y(xn(1)) + y(xn(5)) + 2*y(xn(3)) +
  4*(y(xn(2))+y(xn(4))) )

integ_compsimp_rule =

16.5669
```

Relative error calculations

```
relaerr_integ_trap = ((integ_trape-analytical_sol)/
analytical_sol)*100
relaerr_integ_trap_2seg = ((integ_trap_2seg-analytical_sol)/
analytical_sol)*100
relaerr_integ_trap_4seg = ((integ_trap_4seg-analytical_sol)/
analytical_sol)*100
relaerr_integ_sim13rd = (( integ_sim13rd- analytical_sol)/
analytical_sol)*100
relaerr_integ_sim38 = (( integ_sim38-analytical_sol )/
analytical_sol)*100
relaerr_integ_compsimp_rule = (( integ_compsimp_rule -analytical_sol)/
analytical_sol)*100
```

```
relaerr_integ_trap =
    -5.1816

relaerr_integ_trap_2seg =
    -1.2541

relaerr_integ_trap_4seg =
    -0.3111

relaerr_integ_sim13rd =
    0.0550

relaerr_integ_sim38 =
    0.0014

relaerr_integ_compsimp_rule =
    0.0032
```

Published with MATLAB® R2018b