# Venkatesh Desai

op Boston, MA | marketeshdesai99 | marketeshdesai9

#### **EDUCATION**

#### Northeastern University, Boston, MA - Khoury College of Computer Science

Expected Apr 2024

Candidate for Master of Science in Robotics - Computer Science concentration

Coursework – Deep Learning, Reinforcement Learning, Adv. Perception, Algorithms, Mobile Robotics, Robot Mechanics and Control

### Indian Institute of Information Technology, IND

Sep 2021

Bachelor of Technology in Mechanical Engineering with Specialization in Design and Manufacturing

Position of Responsibility – CODIGO club coordinator, Cultural Secretary, Placement Cell Secretary

## **SKILLS**

- Languages and OS: Python, C, MATLAB, Linux, SQL, Shell Script
- Applied CS: Data Science, Machine Learning, Deep Learning, Computer Vision, Natural Language Processing, AI
- Deep Learning Methodologies: CNN's, RNN's, Transformers, VAE's, DAE's, Self-Supervised Learning, Time-Series Analysis
- Tools and Frameworks: Pandas, NumPy, scikit-learn, Pytorch, OpenCV, Matplotlib, Seaborn, Docker, git, AWS, GCP

### **EXPERIENCE**

#### Graduate Teaching Assistant - CS 7150: Deep Learning

Aug 2023 – Present

- Assisting PhD course, focusing on Neural Network, Transformers, VAE's, Stable Diffusion, crucial in modern research
- Conducting TA hours and GAN, Image Transformer, and LLM discussions, increasing academic research engagement

<u>Co-Founder | iTorque</u> May 2021 – July 2022

- Designed 20% efficient hydrodynamic gear sets to replace traditional gear sets currently used in the market
- Utilized k-means clustering algorithms to segment customer base, this helped us to understand the product market fit

# **Summer Intern | Indian Institute of Information Technology**

May 2020 - Dec 2020

- Developed a gym assistant robot to guide users through workout routines and posture monitoring to prevent injuries
- Generated a gym layout map using Lidar cloud points and Hector-SLAM algorithm, enabling efficient navigation for the robot
- Detected 33 key human body points with an accuracy of 95%, facilitating real-time posture correction guidance for users

<u>ML Intern | Air India</u> Nov 2019 – Jan 2020

- Implemented a Decision Tree model, reducing restocking lead times by 15% and decreasing excess inventory levels by 10%, optimizing real-time inventory decisions in the airline's supply chain
- Leveraged Long Short-Term Memory (LSTM) networks, achieving a 90% accuracy rate in classifying user intents, including booking flights, checking flight status, and handling general inquiries, significantly improving user satisfaction

## **PROJECTS**

# Shadow Removal via Shadow Image Decomposition (SP-Net: VGGNet, ResNeXt; M-Net: U-Net)

Sep 2023 – Oct 2023

- Engineered a deep learning framework, fusing physics-based modeling with data-driven approaches, to predict illumination parameters using SP-Net and shadow mattes using M-Net for shadow-free image reconstruction
- Demonstrated a 40% error reduction (RMSE from 13.3 to 7.9) over prior methods on ISTD benchmark dataset

Automated Essay Grading (AES) (Transformers- BERT, DeBERTa, Distilbert, Roberta, GPT-2)

Mar 2023 - Apr 2023

- Created an AES system utilizing pre-trained transformer models, leading to improved essay grading efficiency
- Achieved higher QWK scores compared to the EASE model on 8 essay sets, demonstrating an average increase of 12%

### <u>Self-Driving Car</u> (Convolutional Neural Network, Raspberry Pi, Arduino)

May 2020 - Nov 2020

- Engineered an autonomous car trained on 17,500 images using fine-tuned NVIDIA End-to-End Deep Learning architecture
- Showcased model's 75% accuracy in steering angle prediction, highlighting autonomous navigation effectiveness

### **EXTRA-CURRICULAR ACTIVITIES**

- Awarded a full scholarship of worth \$1200 for Utility Patent by the director of IIIT institute during my undergraduate
- Lead team to Top 5 position among 180 Teams from INDIA, in NASA International Space Apps Challenge 2020
- <u>Certifications</u>: Coursera- Machine Learning, Deep Learning, Deep Learning for Computer Vision, Robotics
- Utility Patent: A Method and a System for Autonomous Training and Assessing the Gym Users (App. # 202141049354)