

## Scheduling

1. `sched_setscheduler` - [Link 1](#)
  - `int sched_setscheduler(pid_t pid, int policy, const struct sched_param *param);`
  - The `sched_setscheduler()` system call sets both the scheduling policy and parameters for the thread whose ID is specified in `pid`. If `pid` equals zero, the scheduling policy and parameters of the calling thread will be set.
2. `sched_getscheduler` - [Link 1](#)
  - `int sched_getscheduler(pid_t pid);`
  - The `sched_getscheduler()` function shall return the scheduling policy of the process specified by `pid`. If the value of `pid` is negative, the behavior of the `sched_getscheduler()` function is unspecified.
3. `sched_setparam` - [Link 1](#)
  - `int sched_setparam(pid_t pid, const struct sched_param *param);`
  - `sched_setparam()` sets the scheduling parameters associated with the scheduling policy for the thread whose thread ID is specified in `pid`.
4. `sched_getparam` - [Link 1](#)
  - `int sched_getparam(pid_t pid, struct sched_param *param);`
  - The `sched_getparam()` function shall return the scheduling parameters of a process specified by `pid` in the `sched_param` structure pointed to by `param`.
5. `sched_get_priority_max` - [Link 1](#)
  - `int sched_get_priority_max(int policy);`
  - `sched_get_priority_max()` returns the maximum priority value that can be used with the scheduling algorithm identified by `policy`.
6. `sched_get_priority_min` - [Link 1](#)
  - `int sched_get_priority_min(int policy);`
  - `sched_get_priority_min()` returns the minimum priority value that can be used with the scheduling algorithm identified by `policy`.
7. `pthread_attr_setschedparam` - [Link 1](#)
  - `int pthread_attr_setschedparam(pthread_attr_t *attr, struct sched_param *param);`
  - The `pthread_attr_setschedparam()` function sets the scheduling parameter attributes of the thread attributes object referred to by `attr` to the values specified in the buffer pointed to by `param`.
8. `pthread_attr_getschedparam` - [Link 1](#)
  - `int pthread_attr_getschedparam(pthread_attr_t *attr, struct sched_param *param);`
  - The `pthread_attr_getschedparam()` returns the scheduling parameter attributes of the thread attributes object `attr` in the buffer pointed to by `param`.
9. `pthread_attr_init` - [Link 1](#)

- `int pthread_attr_init(pthread_attr_t *attr);`
- The `pthread_attr_init()` function initializes the thread attributes object pointed to by `attr` with default attribute values.

#### 10. `pthread_attr_setschedpolicy` - [Link 1](#)

- `int pthread_attr_setschedpolicy(pthread_attr_t *attr, int policy);`
- The `pthread_attr_setschedpolicy()` function sets the scheduling policy attribute of the thread attributes object referred to by `attr` to the value specified in `policy`.

#### 11. `pthread_attr_getschedpolicy` - [Link 1](#)

- `int pthread_attr_getschedpolicy(const pthread_attr_t *attr, int *policy);`
- The `pthread_attr_getschedpolicy()` returns the scheduling policy attribute of the thread attributes object `attr` in the buffer pointed to by `policy`.

### Some useful struct definitions:

```
struct sched_param {
    int sched_priority;
};

struct timespec {
    time_t tv_sec; // seconds
    long tv_nsec; // nanoseconds
}
```

### Some important commands:

`chrt -m` - Lists the maximum and minimum valid priorities for all scheduling policies

`chrt -p pid` - Shows what the current scheduling policy and priority are for the process with process id = `pid`

`chrt [policy flag] -p priority pid` - Changes the scheduling policy of the process with process id = `pid`, with a priority value = `priority`, to the scheduling policy represented by `policy flag` (-o for SCHED\_OTHER, -f for SCHED\_FIFO, -r for SCHED\_RR, -b for SCHED\_BATCH, -i for SCHED\_IDLE).

Eg. `chrt -f -p 34 22885` - Changes the scheduling policy of the process with process id 22885 to SCHED\_FIFO, with a priority value of 34.

Refer [this](#) for more details on the `chrt` command and for the valid range of `priority`. You might also need to use `sudo` if you are using `chrt` with SCHED\_FIFO and SCHED\_RR.

Now we will look into the concept of **nice** values. When you use the **chrt -m** command to find the maximum and minimum values of priority values for SCHED\_OTHER, SCHED\_BATCH and SCHED\_IDLE, you will notice that they are 0 and 0. These are all non-realtime scheduling policies and it means all of these processes have the same 'priority' and their only difference is in their **nice** value. **nice** value ranges from -20 to 19. Bigger is the **nice** value of a process, lower is its priority and the 'nicer' it is to other processes. Refer [this](#) for more details.

**nice -n <nice\_value> <command>** - Replace <nice\_value> with the priority level and <command> with the actual command or process you want to execute with that priority

**renice -n <nice\_value> -p <process\_id>** - Replace <nice\_value> with the new priority level you want to assign and <process\_id> with the ID of the running process you wish to modify.

Eg. **renice -n 43 -p 59036** - Changes the nice value of process with process id 59036 to 43

Note: Use **ps ax -o pid,ni** to find the **nice** values of available processes.

## Problem 0

Use the **chrt** command to find out the valid priorities of the different scheduling policies. Also use the command to find out the priority and the policy of the **bash** process.

Use the **nice** command to launch a process with any priority. Now, use the **renice** command to change the priority.