Applied Algorithms CSCI-B505 / INFO-I500

Lecture 7.

Amortized Analysis - 2

- Dynamic Array Allocation
- Amortized Dictionary Data Structure

Dynamic Arrays

- Remember array is a contiguous block in memory.
- Thus, its size should be definite at the time of creation.
- However, the size of an array can change frequently!
- Therefore, the **dynamic arrays**, whose size can be altered at run time is of our interest. *Notice that many modern programming languages make use of it.*
- At the end we will see that, theoretically it is no different then static arrays!?

Main Question: What to do when array is full, in other words, all cells are occupied, and we need to add a new element to this full array.



Allocate a larger size in the memory

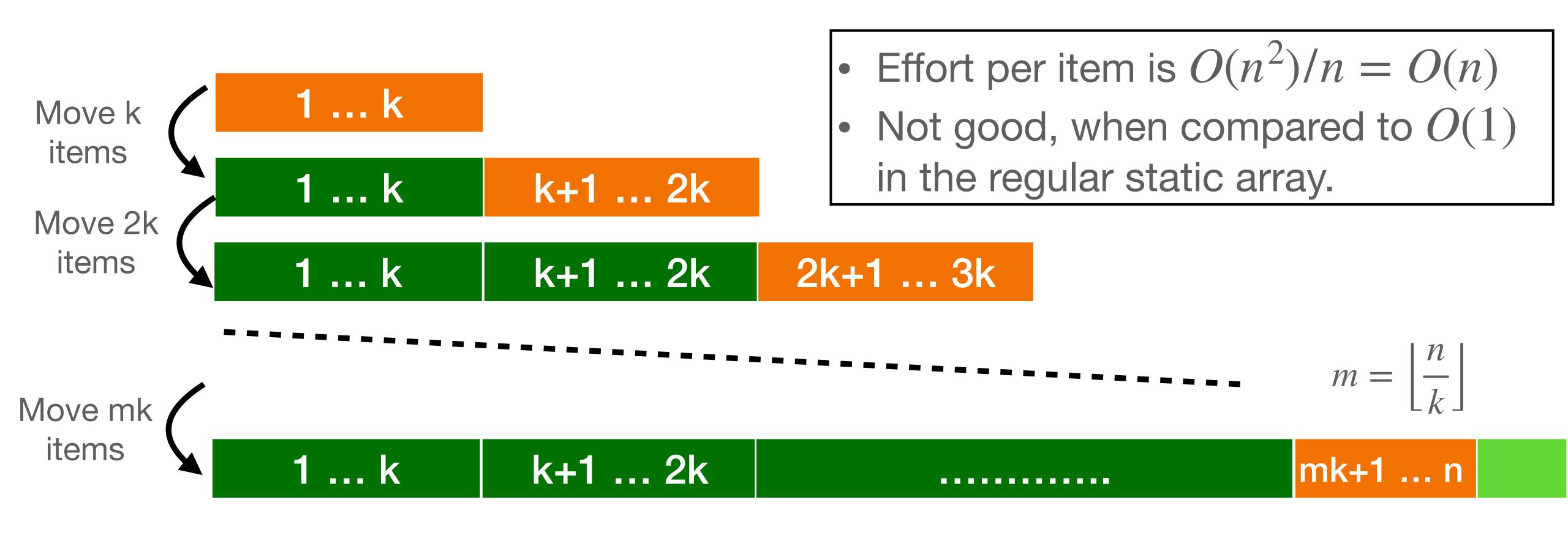
Move old elements to the new array



Append the **new** item to the new array



Let's consider incrementing the size by a fixed amount each time we need to resize.



$$k(1+2+...+m) = \frac{k \cdot m \cdot (m+1)}{2} \in O(k \cdot m^2) \to O(n^2)$$

Let's consider doubling the current size each time we need to resize.



- 1 2
- 1 2 3 4
- 1 2 3 4 5 6 7 8

- Now, effort per item is O(n)/n = O(1)
- Same with the regular static array
- But, where did our extra movements go?!
 - In the hidden constant of O(1), which is 3 on the dynamic case ?

 2^k

n

 2^{k+1}

$$(1+2+\ldots+2^k)=2^{k+1}-1\in O(2^k)\to O(n)$$

$$k = \lfloor \log n \rfloor \to 2^k \approx n$$

Aggregate analysis

insert	old capacity	new capacity	insert cost	copy cost
1	0	1	1	_
2	1	2	1	1
3	2	4	1	2
4	4	4	1	_
5	4	8	1	4
6	8	8	1	_
7	8	8	1	_
8	8	8	1	_
9	8	16	1	8
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 $\lfloor \log n \rfloor$

 c_i is the cost of i^{th} insertion to the array

- If $i=2^k+1$, for some k>0, then $c_i=i$.
- Else, $c_i = 1$.

$$\sum_{i=1}^{n} c_i \le n + \sum_{j=0}^{\lfloor \log n \rfloor} 2^j$$

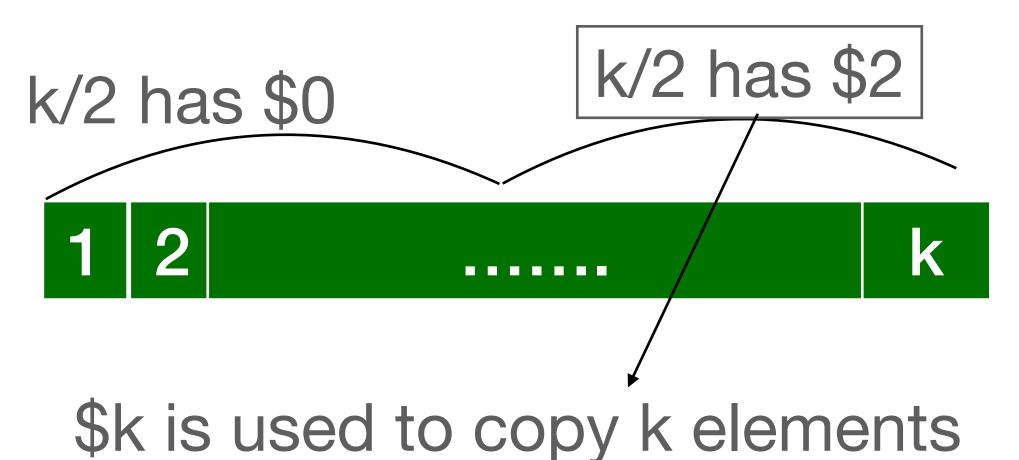
$$< n + 2n$$

$$< 3n$$

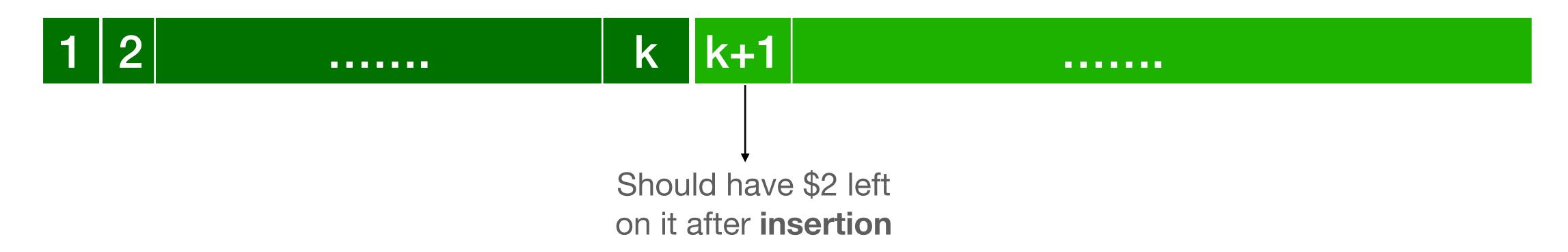
- . The cost per item is less than $\frac{3n}{n} = 3$
- Therefore, O(1).

Accounting Method

\$3 per each insert will guarantee to avoid bankruptcy.



If half of the elements have \$2 on them, it is enough to copy the old items. Since regular \$1 cost will be required per each, \$3 will surely avoid bankruptcy.



Potential Method

$$\phi(D_i) = 2 \cdot size(D_i) - capacity(D_i) \qquad \qquad \phi(D_0) = 0$$
 # of elements — Total space of the array

 $\forall i, \ \phi(D_i) \geq 0$, since after each resize capacity is 2 times the number of elements.

Case 1: There is space in the capacity, so no resize is required.

- Actual cost: $c_i = 1$
- $\phi(D_i) \phi(D_{i-1}) = 2 \cdot size(D_i) capacity(D_i) 2 \cdot size(D_{i-1}) + capacity(D_{i-1}) = 2$, since

$$size(D_i) = size(D_{i-1}) + 1$$

$$capacity(D_i) = capacity(D_{i-1})$$

• Amortized cost : $\hat{c}_i = 1 + 2 = 3$

Potential Method

$$\phi(D_i) = 2 \cdot size(D_i) - capacity(D_i) \qquad \qquad \phi(D_0) = 0$$
 # of elements — Total space of the array

 $\forall i, \ \phi(D_i) \geq 0$, since after each resize capacity is 2 times the number of elements.

Case 2: There is NO space in the capacity, so resizing is required.

- Actual cost: $c_i = 1 + capacity(D_{i-1})$
- $\phi(D_i) \phi(D_{i-1}) = 2 \cdot size(D_i) capacity(D_i) 2 \cdot size(D_{i-1}) + capacity(D_{i-1})$ = $2 - capacity(D_{i-1})$,

since
$$size(D_i) = size(D_{i-1}) + 1$$
 and $capacity(D_i) = 2 \cdot capacity(D_{i-1})$

• Amortized cost : $\hat{c}_i = 1 + capacity(D_{i-1}) + 2 - capacity(D_{i-1}) = 3$

- What if we want to support resize on delete operation?
- When the number of items in the array become less, we shrink the array.
- What would be a good strategy?
 - Halve the array when items become 1/2 ???

Dictionary structures are always in the heart of computing. We have many alternatives. Here is one of those ...

Problem: Given n items, provide an efficient way to support search and update.

Main idea:

- Instead of a single list, maintain a collection of arrays, say $A_0, A_1, \ldots, A_{k-1}$
- Array A_i has either exactly 2^i elements or empty with zero elements.
- Each array is sorted.
- There is no relation or order between the arrays.

Depending on the number n, how will we decide on the number of arrays (k=?), and how will we decide which ones will be empty and full?

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Each integer can be written as the sum of the powers of 2. Actually, this is its binary representation!

$$(n = 11) \rightarrow n = 1011$$
 indicates n=8.1+4.0+2.1+1.1

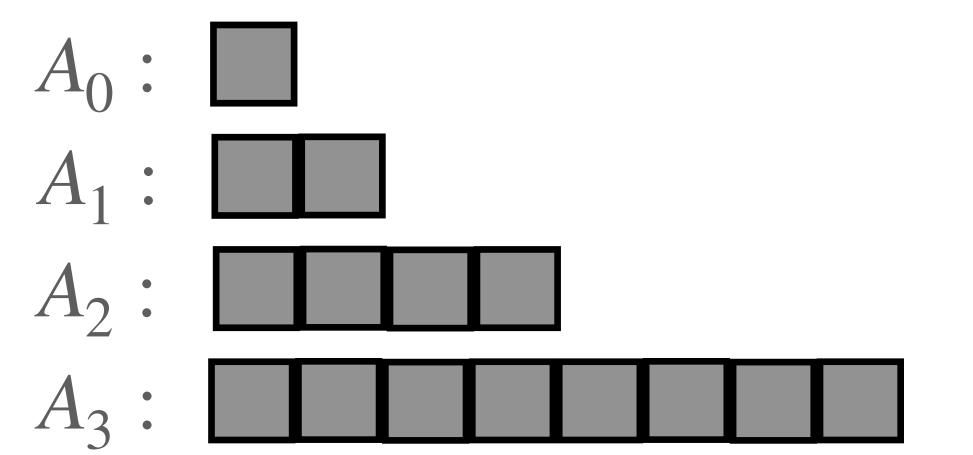
4 arrays A_3, A_2, A_1, A_0 with sizes 8,4,2,1, respectively. A_2 is empty.

- A_0 : 5
- A_1 : 1 9
- A_2 :
- A₃: 2 4 8 10 13 15 16 19

- Given n, we maintain $\lceil \log(n+1) \rceil$ arrays.
- Each has its corresponding size.
- The ones with a 1 bit are full, others empty

What do you think about the construction cost?

Searching for a key on this dictionary which maintains n keys in total?



$$A_{k-1}$$
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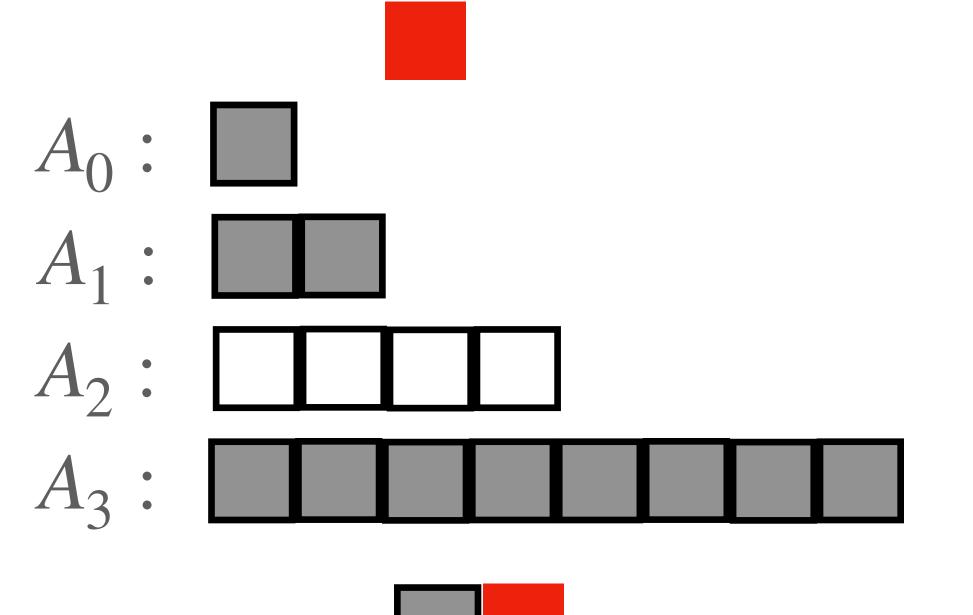
$$k = \lceil \log(n+1) \rceil$$

- Investigate each array one-by-one.
- We have $k = \lceil \log(n+1) \rceil$ arrays.
- Search on a sorted array of t elements is $O(\log t)$ via binary search.
- Longest array size $\leq n$.
- At most k arrays will be searched.
- Each search is $O(\log n)$ time.

Then, overall cost of search is

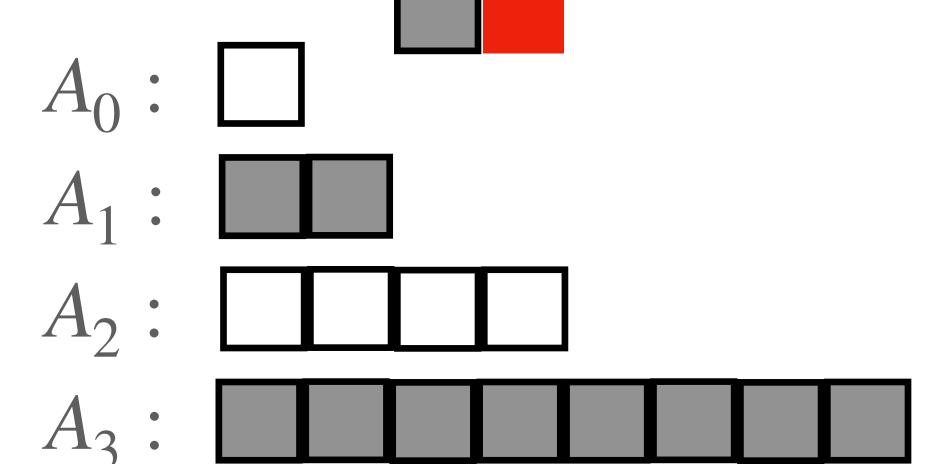
$$k \cdot \log n \in O(\log^2 n)$$

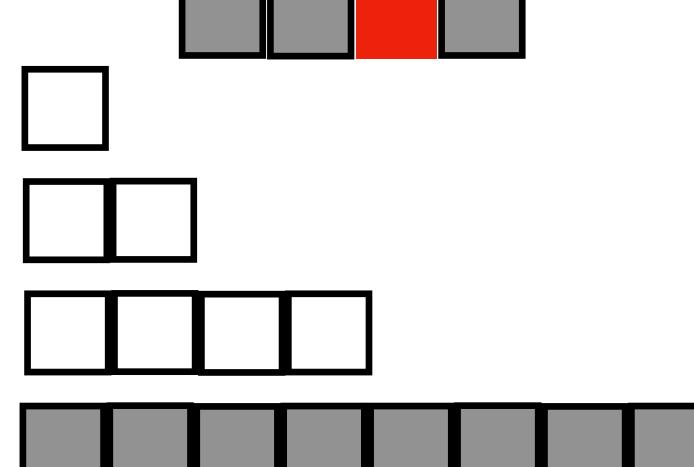
INSERTING a new key

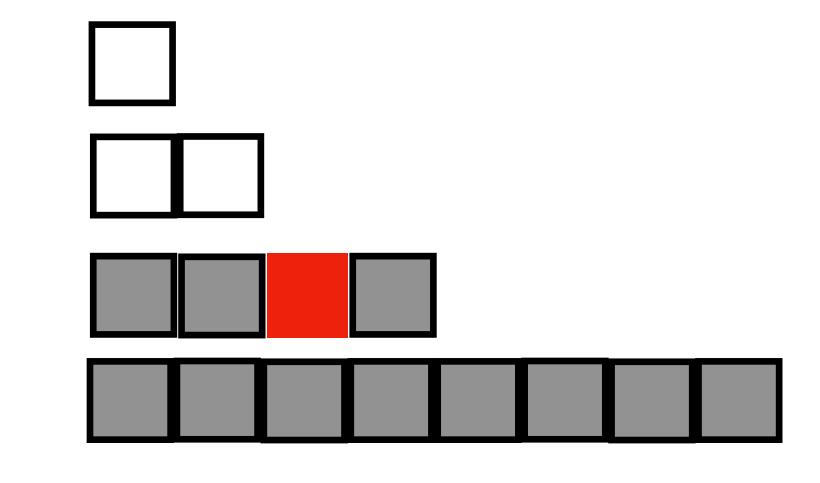


- Put new element into array H of size 1.
- i = 0
- Check A_i . If empty, copy H to A_i and stop. Else,

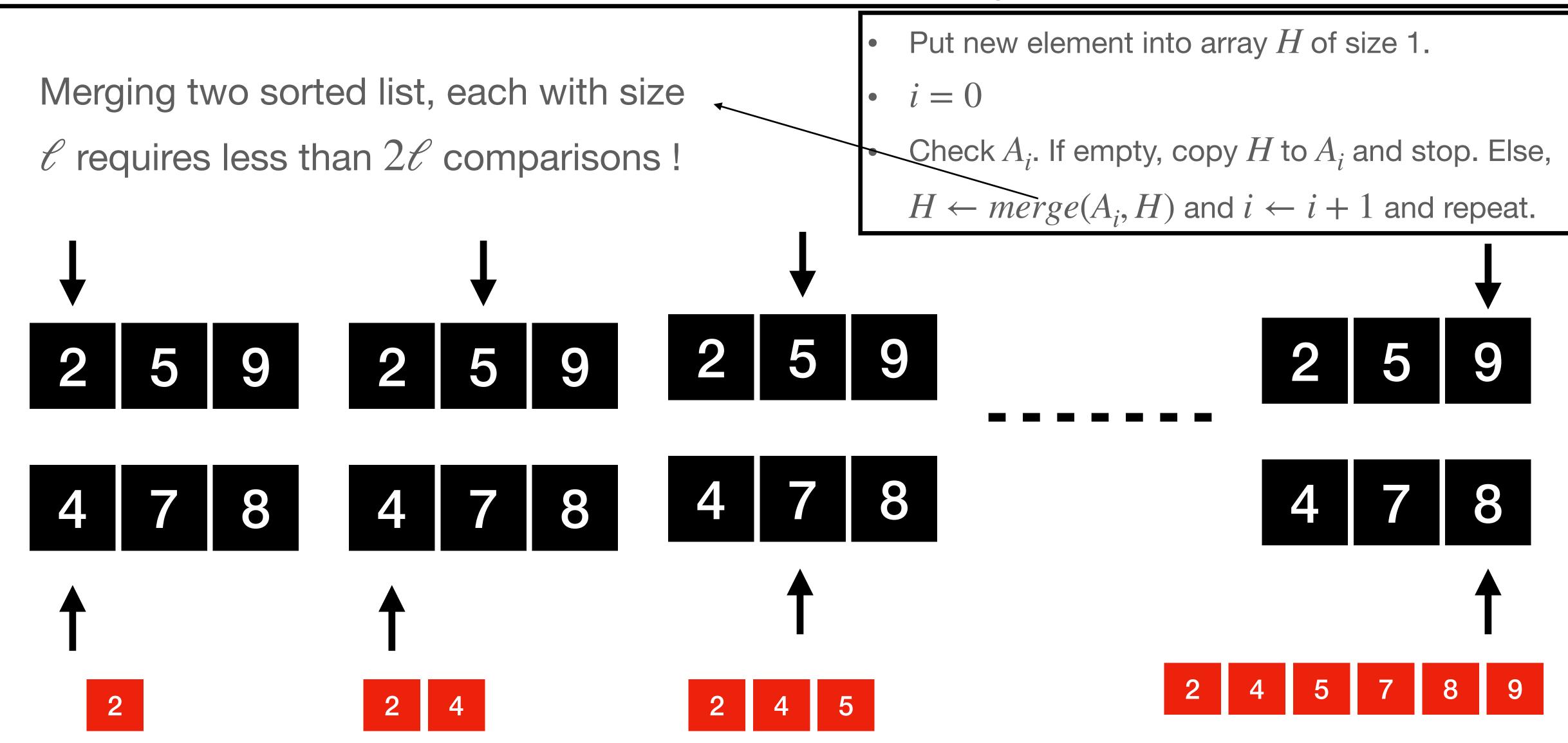
 $H \leftarrow merge(A_i, H)$ and $i \leftarrow i + 1$ and repeat.







INSERTING a new key



INSERTING a new key

- Worst case: We visit and merge all arrays in the dictionary, e.g. $n = 2^k 1$ elements in the dictionary for some k, and we are adding the 2^k th element
- What will be the cost of this worst case?
- Merging two sorted list, each with size ℓ requires less than 2ℓ comparisons!
- Therefore, $C = 2 + 4 + 8 + ... + 2^k = 2^{k+1} 1$. Since $k \in O(\log n)$, $C \in O(n)$.

Once such a worst case happens, can it appear repeatedly?

NO!

So, regular worst case analysis is not tight! We can try an amortized approach by computing the cost of , say t, consecutive insert operations.

INSERTING a new key has $O(\log n)$ amortized complexity.

The merge cost of A_i is at most $2 \cdot 2^i$ as merging two list each with ℓ costs 2ℓ .

During n insertion operations,

- A_0 will be subject to merge n/2 times with a cost of 2.
- A_1 will be subject to merge n/4 times with a cost of 4.
- A_2 will be subject to merge n/8 times with a cost of 8.
- Totally $O(\log n)$ arrays will be subject to merge each with O(n) cost.
- Therefore, this makes total cost $O(n \log n)$ for n insertions, which makes amortized cost of insertion $O(\log n)$.

This is exactly the same with the binary counter amortized analysis with one difference as the cost of flipping k^{th} bit is 2^k instead of a constant 1 unit.

DELETING a key

- Assume we will be deleting an item from the array ${\cal A}_i$ that includes 2^i elements.
- Split A_i into small arrays of length $1,2,4,...,2^{i-1}$. Notice that $1+2+4+...+2^{i-1}=2^i-1$, which is exactly the number of remaining elements in A_i . Delete all items from A_i .
- For each of these small arrays, insert it into the dictionary again. Insert operation starts with the corresponding list length, i.e., small array of size 1, start with A_0 , size 2 start with A_1 , and continue accordingly.

There can be at most $\log n$ small arrays after deleting an element. The amortized cost of insertion process is $O(\log n)$ as we showed previously. So the cost of deleting an element in the worst case is $O(\log^2 n)$ with the proposed method.

There might be other ways of deletion as well?

Reading assignment

 Read chapter 17 Amortized Analysis from Cormen and also related chapters from other text books or resources on the internet.

Next week we will study recursions and divide-and-conquer type algorithms.