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IST 2018/2019

Processamento e Recuperação de Informação

Lab 04: Information Extraction (cont.)

The Python extension package named nltk¹ provides a set of tools that are useful for addressing information extraction problems such as Named Entity Recognition (NER). More specifically, you can use the following methods:

- nltk.sent_tokenize(d), which splits a document d into a list of sentences;
- nltk.word_tokenize(s), which splits a sentence s into a list of words;
- nltk.pos_tag(w), which leverages a sequence classification model to tag the words in list w according to their part-of-speech (i.e., tag words according to morphosyntactic classes such as noun, verb, adjective, ...);
- nltk.ne_chunk(p, binary=True), which tags the words in list p as named entities or not (where each word in p was previously tagged with a part-of-speech tag).

Note that the output of each of these tools can be used as input to the next tool. The nltk² documentation also presents several alternative models for parts-of-speech tagging and named entity recognition, leveraging different types of algorithms (e.g., structured perceptrons, CRFs, etc.)

1

Test the Senna³ POS tagger, NER Tagger and Chunk Tagger with a few sentences of your own, or extracted from Web sites. Try text from different contexts (e.g. news, blogs, etc.).

2

Using the above tools, print all named entities found in the documents of the 20 newsgroups collection⁴. This document collection can be conveniently accessed through the scikit-learn library, as shown in the previous lab class.

¹http://www.nltk.org

²https://www.nltk.org/api/nltk.tag.html

³https://www.nltk.org/api/nltk.tag.html#module-nltk.tag.senna

⁴ http://qwone.com/~jason/20Newsgroups/

3 Pen and Paper Exercise

Consider the Hidden Markov Model from the previous exercises, represented by the following probabilities. Remember that π corresponds to the initial probabilities of each state, B corresponds to the state emission probabilities, and A corresponds to the transition probabilities.

The symbols corresponding to each line in matrix B are a, b, and c.

$$\pi = \begin{pmatrix} 0.8 & 0.2 \end{pmatrix} B = \begin{pmatrix} 0.1 & 0.6 \\ 0.7 & 0.2 \\ 0.2 & 0.2 \end{pmatrix} A = \begin{pmatrix} 0.1 & 0.5 \\ 0.9 & 0.5 \end{pmatrix}$$

Consider now a structured perceptron in which the considered feature representations/scores correspond to restructuring the HMM probabilities as scores.

- (a) Consider the observation **acb** associated to the sequence of states **121**. Show how this observation would be represented in terms of binary features.
- (b) Consider a structured perceptron defined with feature weights corresponding to the logarithm of the HMM probabilities. What is the most likely sequence of states for the sequence of symbols **acbc**?
- (c) Starting from the structured perceptron model from the previous question, compute a new model using one iteration of the structured perceptron training method, assuming that you had only one observation available: **acb** associated to the sequence of states **121**.