

Newtonovy zákony:

$$1) \frac{d\vec{v}}{dt} = 0 \rightarrow \vec{v} = \text{const.}$$

$$2) \vec{F} = m \cdot \frac{d\vec{v}}{dt} = m \cdot \vec{a}$$

$$\vec{a} = \frac{\vec{F}}{m}$$

$$3) \vec{F} = -F_s$$

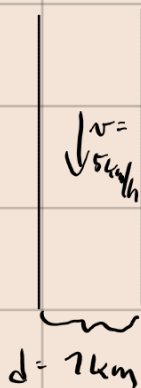


$$\vec{F} = m \cdot \vec{a}$$

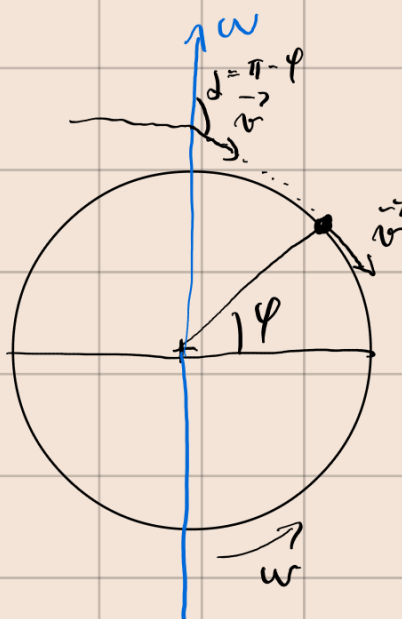
$$m \cdot \vec{a} = m \cdot \vec{a} - m \cdot \vec{A} - m \cdot \vec{\omega} \times (\vec{\omega} \times \vec{r}) - m \vec{\epsilon} \times \vec{r} - 2m \vec{\omega} \times \vec{v}$$

resting síla      díky zrychlení posunu soustavy      odstředivá      Eulerova      Coriolis

3.39 - Řeka



na 45. vlnoběžce  
 $\varphi = 45^\circ$



$$\vec{F}_C = -2m \vec{\omega} \times \vec{v}$$



$$\Delta h = z$$

$$10 \beta = \frac{F_c}{F_g} \approx \frac{\Delta h}{d}$$

$$F_c = 2m v^1 \omega \sin(\pi - \varphi) = 2m v^1 \omega \sin \varphi$$



$$\frac{F_c}{F_g} = \frac{\Delta h}{d}$$

$$\frac{2m v^1 \omega \sin \varphi}{m \cdot g} \approx \frac{\Delta h}{d}$$

$$\frac{2 d v^1 \omega \sin \varphi}{g} \approx \Delta h$$

$$\omega = \frac{2\pi}{T} = \frac{2\pi}{86400}$$

$$= 15 \text{ mm}$$

Energie

$$\vec{F} \cdot \vec{v} \approx m \cdot \frac{d\vec{v}}{dt} \cdot \vec{v} = m \cdot \frac{1}{2} \frac{d\vec{v}}{dt} (\vec{v} \cdot \vec{v}) = \frac{d}{dt} \left( \underbrace{\frac{1}{2} m \cdot v^2}_{\text{kinetische Energie}} \right) = \frac{dE_{kin}}{dt}$$

$$\vec{F} \cdot \vec{v} = \frac{dE_{kin}}{dt}$$

$$\int_A^B dE_{kin} = \int_{t=0}^t \vec{F} \cdot \vec{v} \cdot dt = \int_0^s \vec{F} \cdot d\vec{s}$$

$$E_{kin}(t) - E_{kin}(0) = \int_0^s \vec{F} \cdot d\vec{s} = A \dots \text{pro}^{\text{nce}}$$

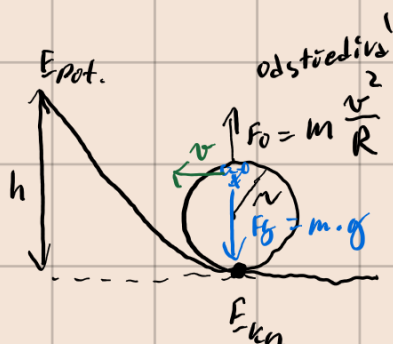
$$\vec{F} = -\text{Grad } E_{pot.} = -\text{Grad } U = -\vec{\nabla} U$$

$$\vec{\nabla} = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$E_{\text{pot.}} = m \cdot g \cdot z$$

$$-\nabla E_{\text{pot.}} = -(0, 0, m \cdot g) = -m \vec{g}$$

### 3.17 - Artista



$$F_0 = F_g$$

$$m \cdot \frac{v^2}{R} = m \cdot g \rightarrow v^2 \geq R \cdot g$$

$$\frac{1}{2} m \cdot v^2 + m \cdot g \cdot 2R = m \cdot g \cdot h$$

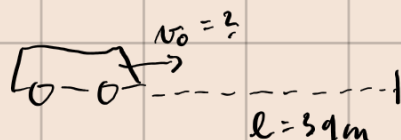
$$\frac{1}{2} v^2 + g \cdot 2R = g \cdot h$$

$$\frac{1}{2} Rg + g \cdot 2R = g \cdot h$$

$$\frac{1}{2} R + 2R = h$$

$$h = 2R + \frac{R}{2} = \frac{5}{2} R$$

### 3.22 - šlepiče



koeff. smyk. tření o vozovku:

$$\mu = 0,5$$

$$\frac{1}{2} m v_0^2 = A_t \quad \begin{array}{l} \text{všechna energie} \\ \text{se dá do tření} \end{array}$$

$$F_t = \mu \cdot m \cdot g$$

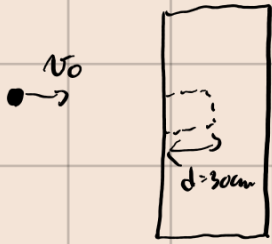
$$A_t = \int F_t \cdot dl = F_t \cdot l = \mu \cdot m \cdot g \cdot l$$

$$\frac{1}{2} m \cdot g \cdot v_0^2 = \mu \cdot m \cdot g \cdot l$$

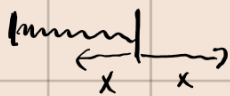
$$\frac{1}{2} g v_0^2 = \mu \cdot g \cdot l$$

$$v_0 = \sqrt{2 g l \cdot \mu} = 30,6 \text{ km/h}$$

## Ukol 3.24 - Stiel

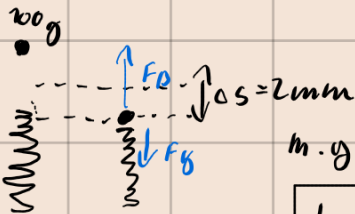


## 3.20 - Pružinový kvačín



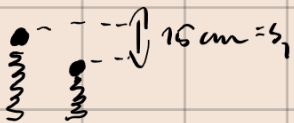
$$F = -k \cdot \vec{x}$$

$k$ ... tuhost pružiny



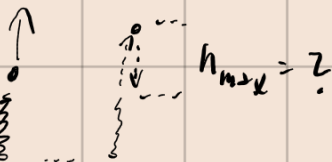
$$m \cdot g = k \cdot \Delta s$$

$$k = \frac{m \cdot g}{\Delta s}$$



$$E_{\text{pot.}} = \frac{1}{2} k x^2$$

$$= \frac{1}{2} k \cdot s_1^2$$



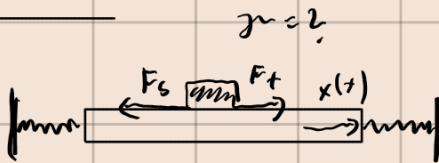
$$E_{\text{kin}} = 0$$

$$E_{\text{pot}} = m \cdot g \cdot h_{\text{max}}$$

$$\frac{1}{2} k s_1^2 = m \cdot g \cdot h_{\text{max}}$$

$$h_{\text{max}} = \frac{\frac{1}{2} k s_1^2}{m \cdot g} = \frac{\frac{1}{2} \frac{m \cdot g}{\Delta s} \cdot s_1^2}{m \cdot g} = \frac{s_1^2}{2 \Delta s}$$

3.32



harm. kmités!

$$T = 5s$$

objekt se zväčšie sľužet, kľuč  $x_0 = 0,5m$

$$F_{s_{max}} \geq F_t$$

Harm. kmit:

$$x(t) = x_0 \sin(\omega t + \varphi_0), \quad \omega = \frac{2\pi}{T}$$

$$v(t) = \dot{x} = \omega x_0 \cos(\omega t + \varphi_0)$$

$$a(t) = \ddot{x} = -\omega^2 x_0 \sin(\omega t + \varphi_0)$$

$$\vec{F} = m \cdot \ddot{x} \Rightarrow F_s = -m \cdot \ddot{x}$$

$$| -m a |_{max} \geq \gamma \cdot m \cdot g$$

$$m x_0 \omega^2 = \gamma \cdot m \cdot g$$

$$\gamma = \frac{x_0 \omega^2}{g} = \frac{x}{g} \left( \frac{2\pi}{T} \right)^2 = 0,08$$

$$\gamma \leq 0,08$$