#### **ASSIGNMENT-1**

#### Er.Perumal Manimekalai College of Engineering Hosur

STUDENT NAME: N.NETHRAVATHI

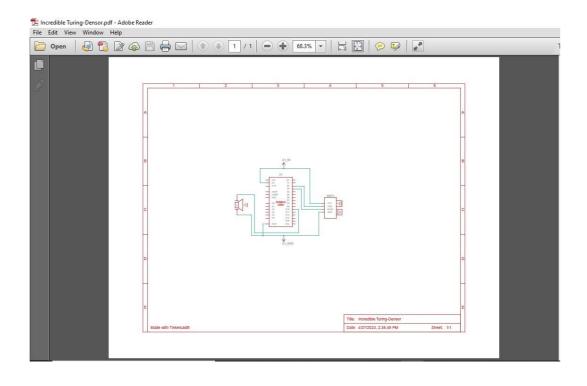
**DEPARTMENT** : ECE III YEAR

SUBJECT : IBM

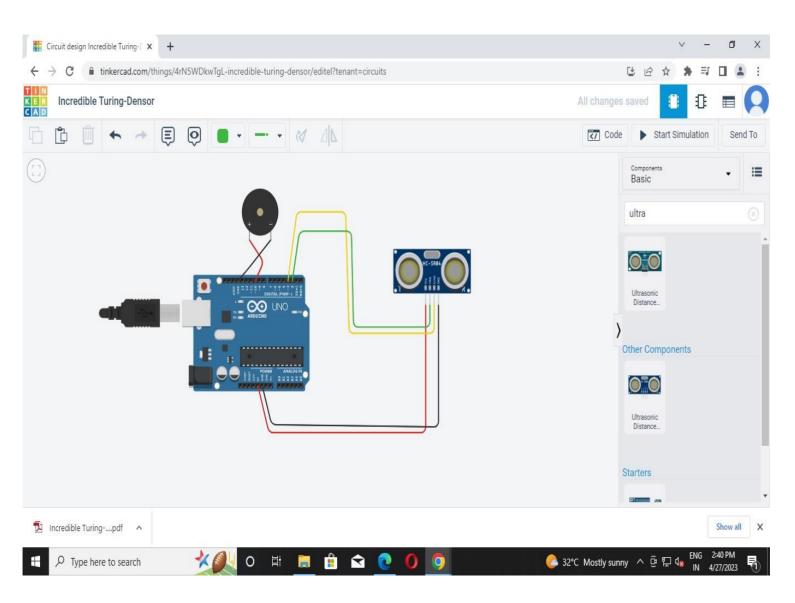
**REGISTER NO** :610820106034

# Build a smart home in wokwi with minimum 2 sensors, Led, buzzer

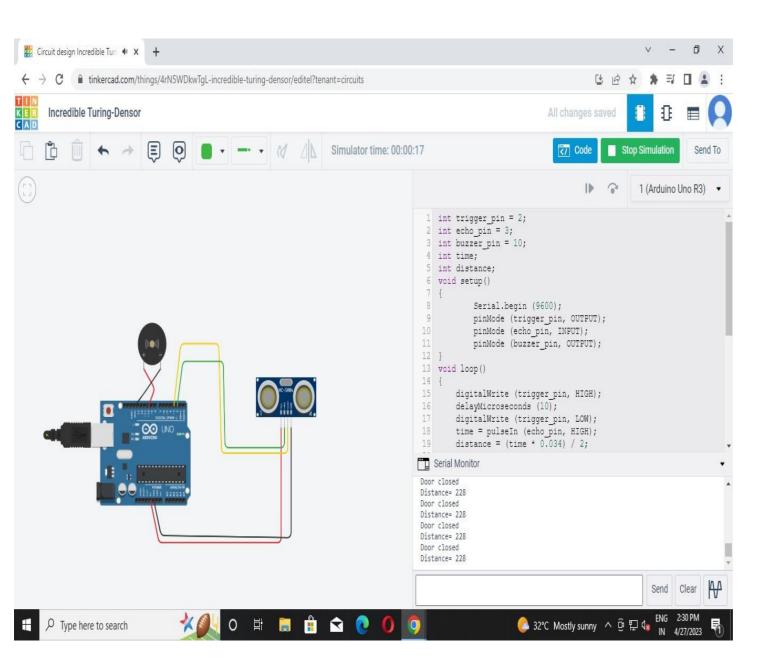
## PIN DIAGRAM



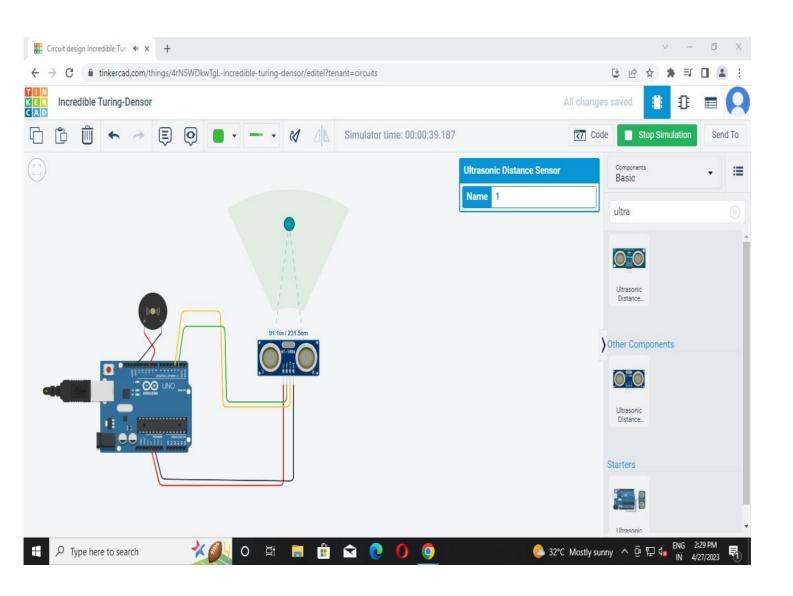
# **DESIGN PART**



# **BUZZER VIBRATING**



# **DISTANCE**



#### **CODING PART**

```
PROJECT CODE - Notepad
File Edit Format View Help
int trigger_pin = 2;
int echo_pin = 3;
int buzzer_pin = 10;
int distance;
            Serial.begin (9600);
            pinMode (trigger_pin, OUTPUT);
pinMode (echo_pin, INPUT);
pinMode (buzzer_pin, OUTPUT);
void loop()
      digitalWrite (trigger_pin, HIGH);
delayMicroseconds (10);
digitalWrite (trigger_pin, LOW);
      time = pulseIn (echo_pin, HIGH);
distance = (time * 0.034) / 2;
   if (distance <= 10)
            Serial.println (" Door Open ");
Serial.print (" Distance= ");
Serial.println (distance);
             digitalWrite (buzzer_pin, HIGH);
             delay (500);
            Serial.println (" Door closed ");
Serial.print (" Distance= ");
Serial.println (distance);
            digitalWrite (buzzer_pin, HIGH);
delay (500);
                                                                                                                                                                                                 C 32°C Mostly sunny ヘ 현 딮 ા LNG
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                                                                                                              ₹
```

```
int trigger_pin = 2;
int echo_pin = 3;
int buzzer_pin = 10;
int time;
int distance;
void setup()
{
        Serial.begin (9600);
        pinMode (trigger_pin, OUTPUT);
        pinMode (echo_pin, INPUT);
        pinMode (buzzer_pin, OUTPUT);
}
void loop()
{
        digitalWrite (trigger_pin, HIGH);
        delayMicroseconds (10);
        digitalWrite (trigger_pin, LOW);
```

```
time = pulseIn (echo_pin, HIGH);
distance = (time * 0.034) / 2;

if (distance <= 10)
    {
        Serial.println ("Door Open ");
        Serial.print ("Distance= ");
        Serial.println (distance);
        digitalWrite (buzzer_pin, HIGH);
        delay (500);
     }

else {
        Serial.println ("Door closed ");
        Serial.print ("Distance= ");
        Serial.println (distance);
        digitalWrite (buzzer_pin, HIGH);
        delay (500);
}</pre>
```

## SERIAL PORT

