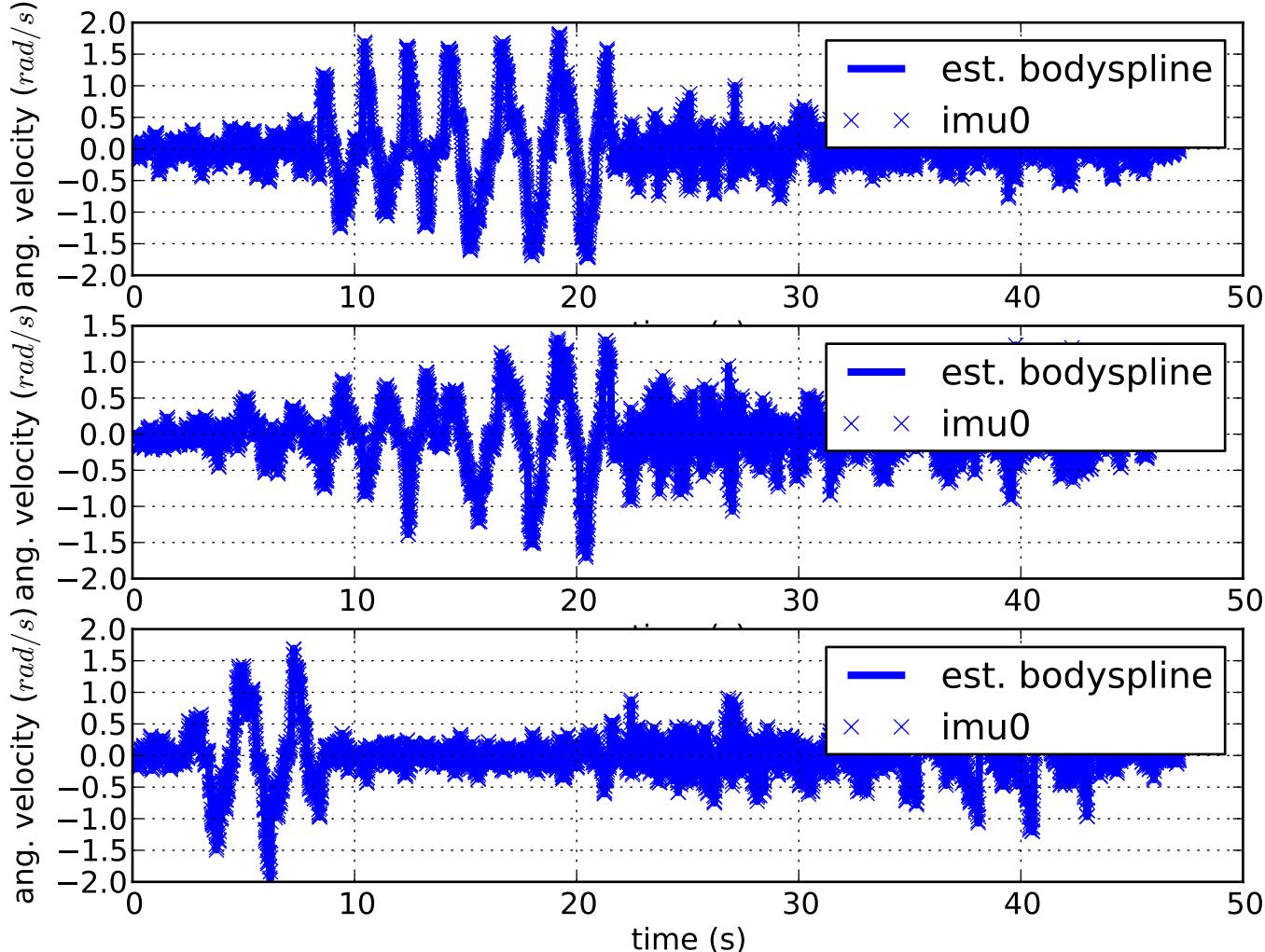
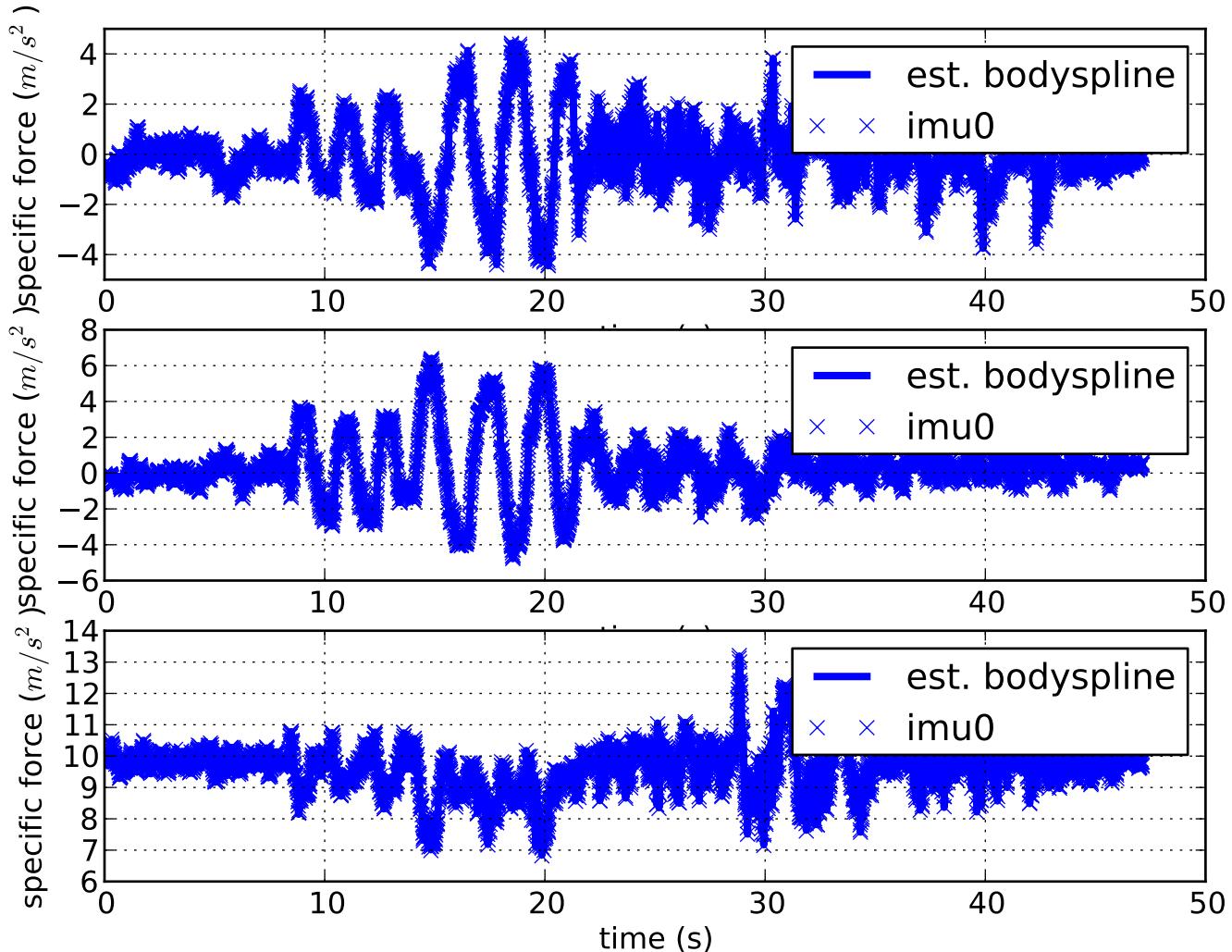


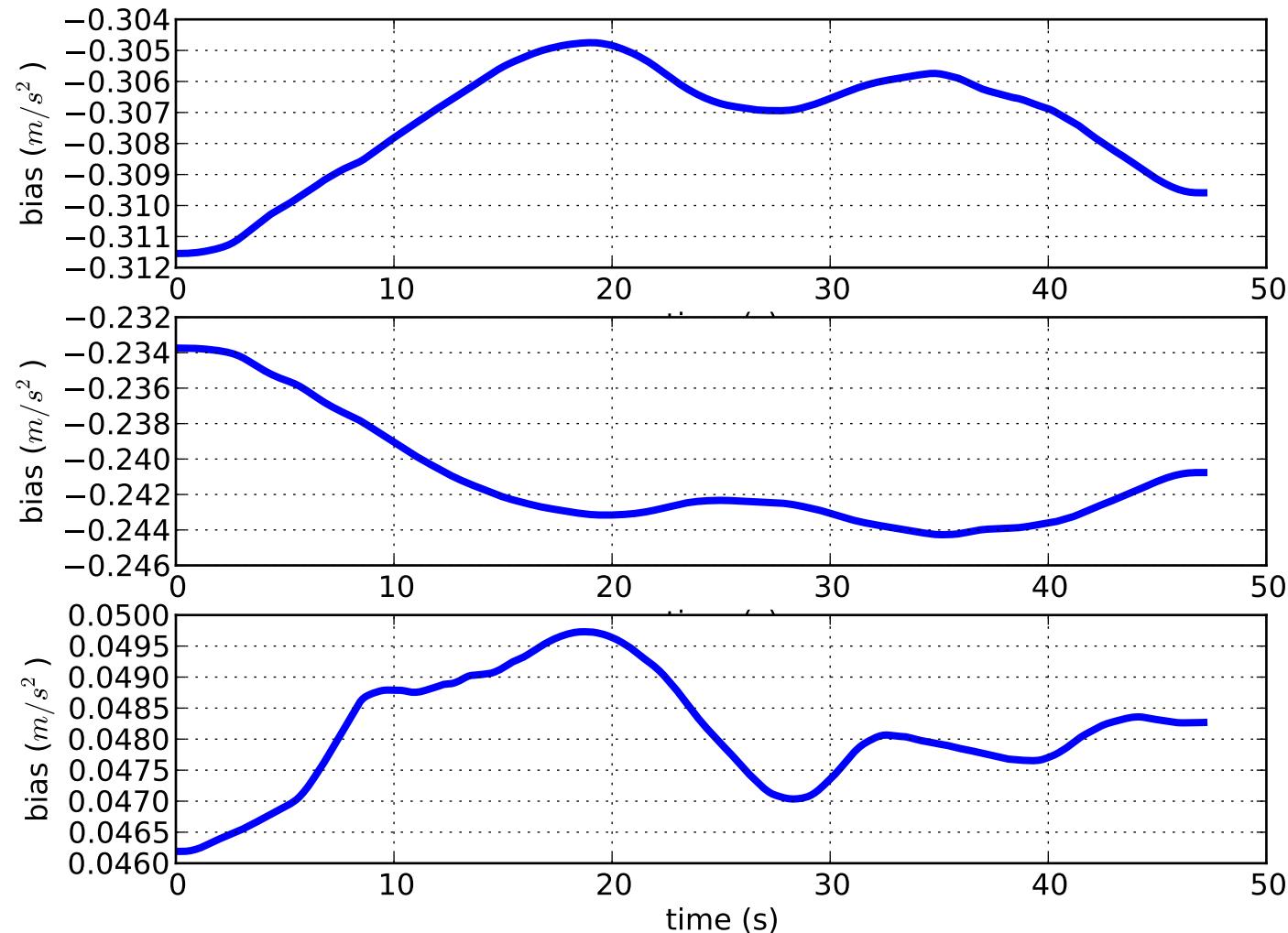
Comparison of predicted and measured angular velocities (body frame)



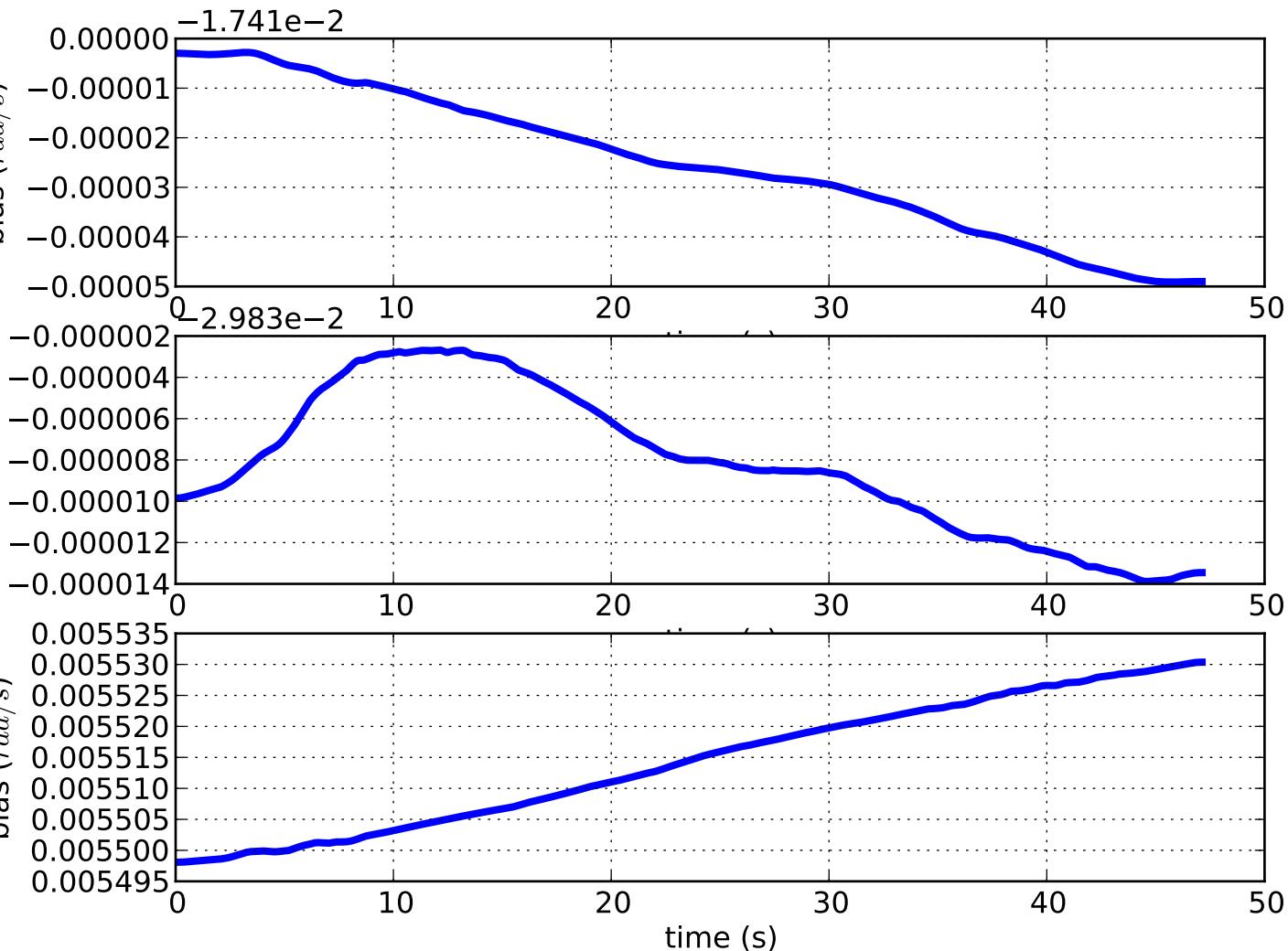
Comparison of predicted and measured specific force (imu0 frame)



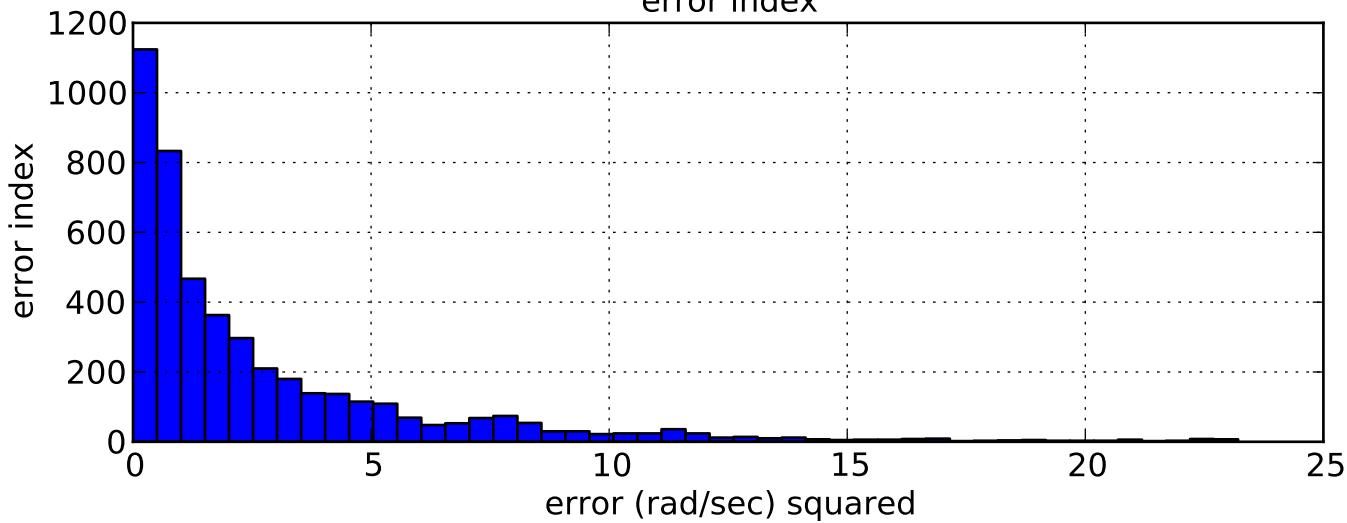
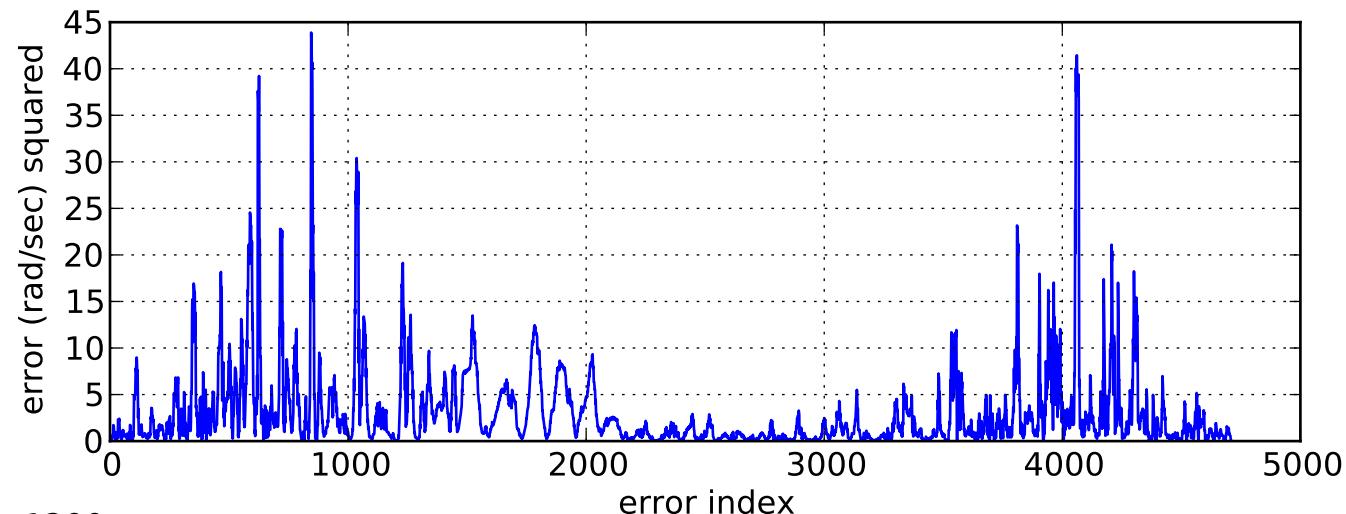
# imu0: estimated accelerometer bias (imu frame)



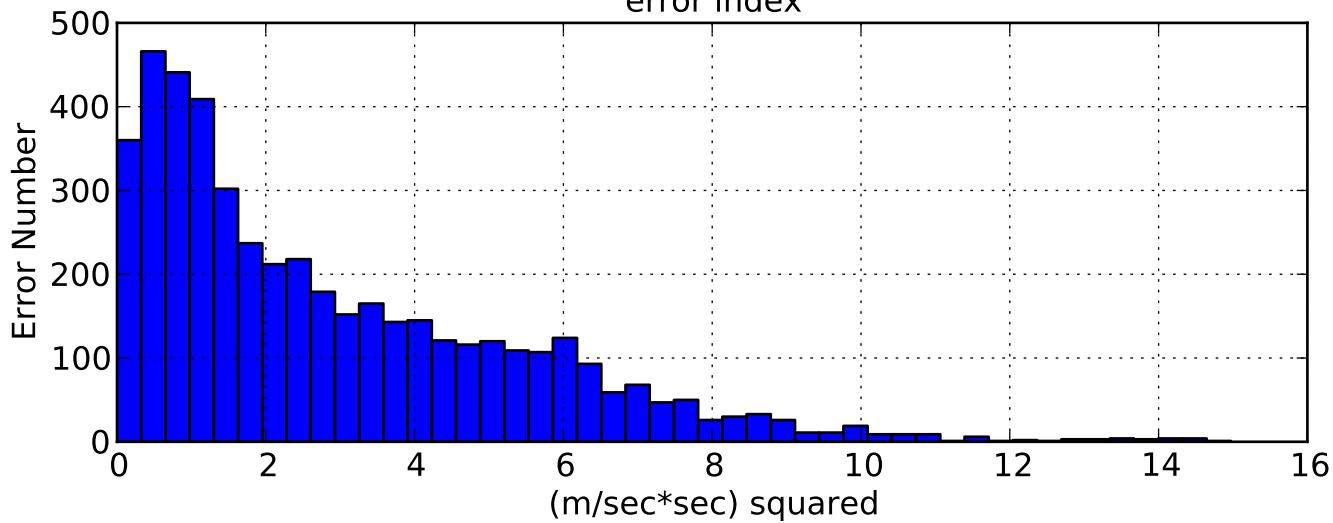
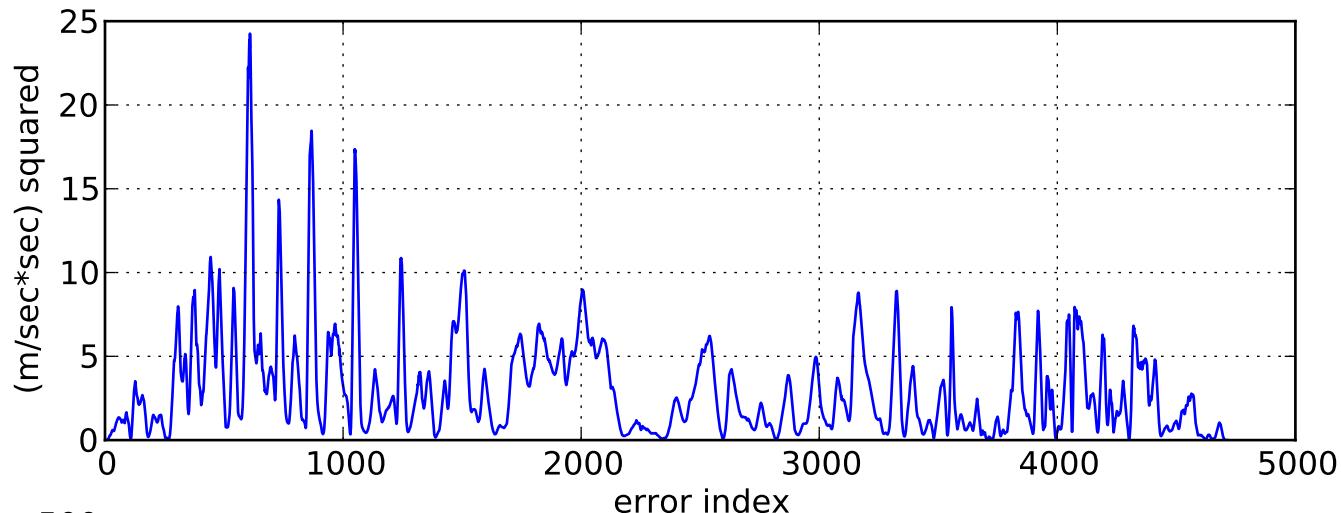
imu0: estimated gyro bias (imu frame)



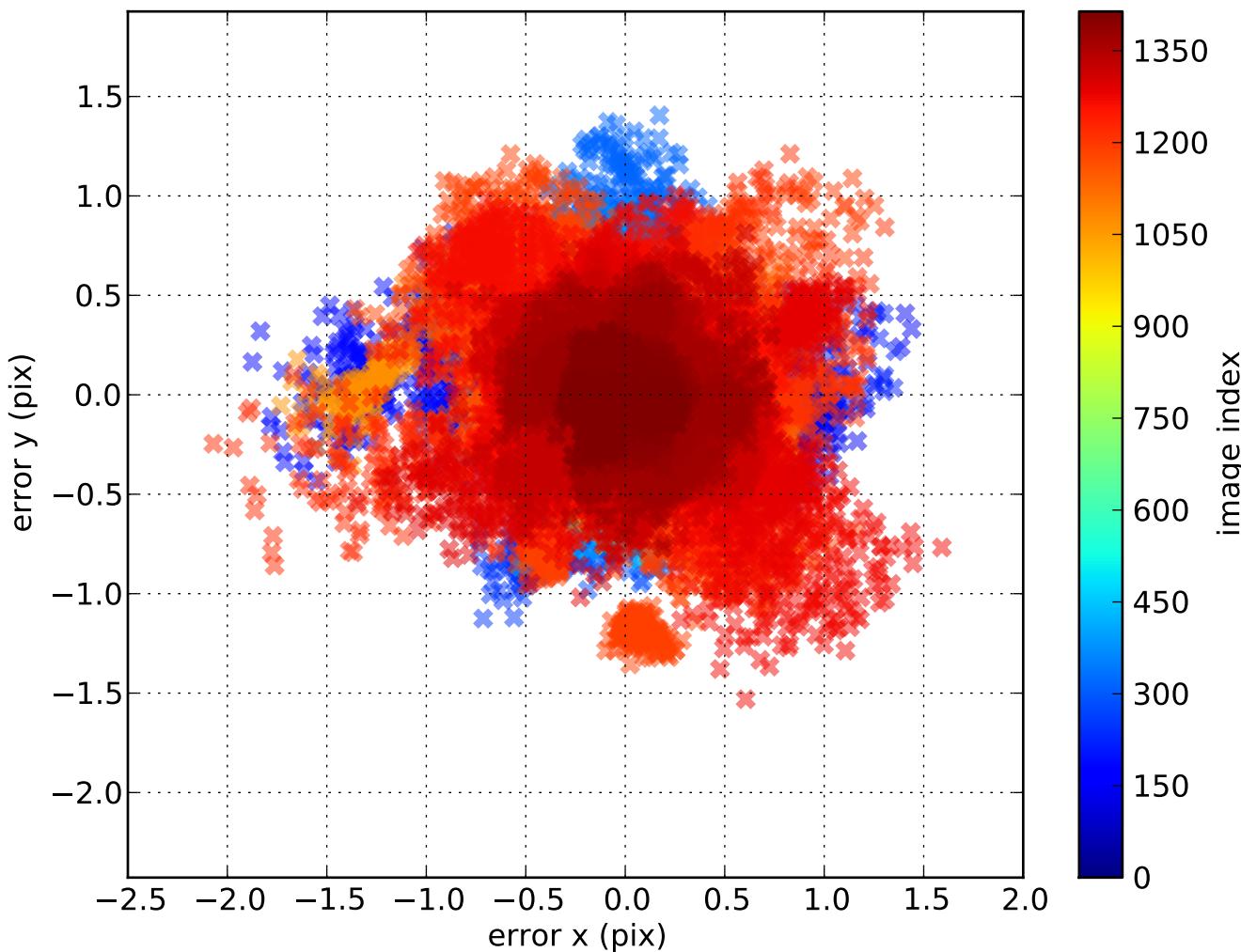
imu0: angular velocities error



imu0: acceleration error



cam0: reprojection errors



cam1: reprojection errors

