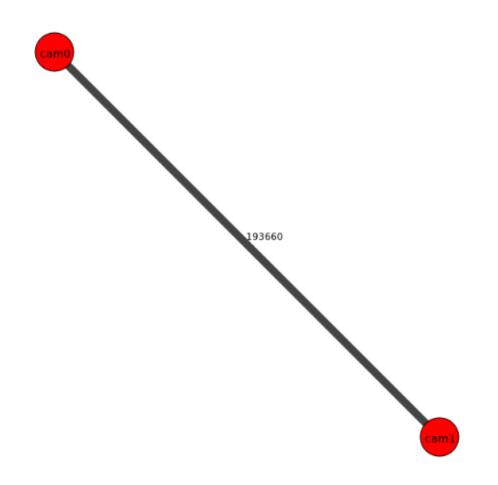
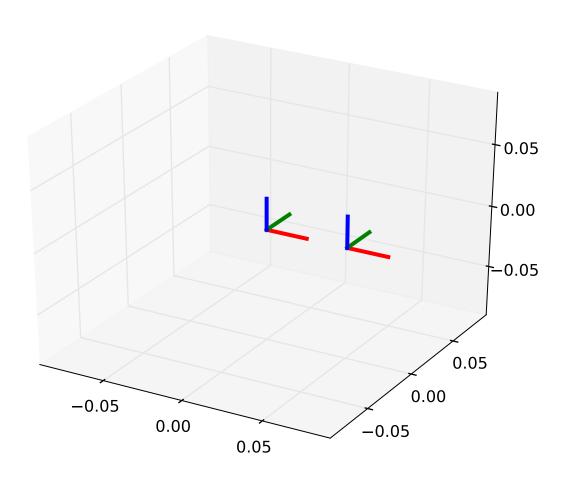
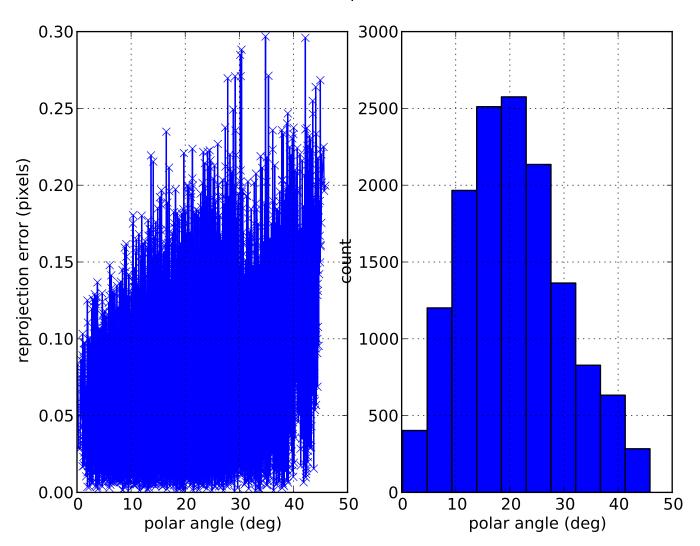
Inter-camera observations graph (edge weight=#mutual obs.)



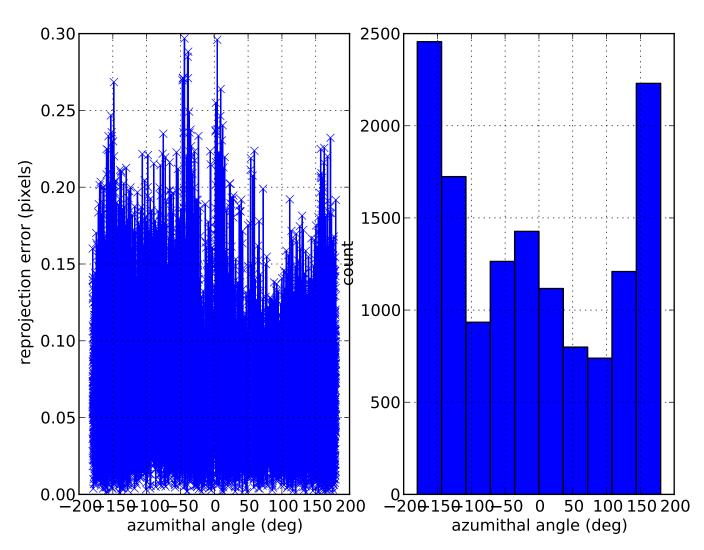
camera system



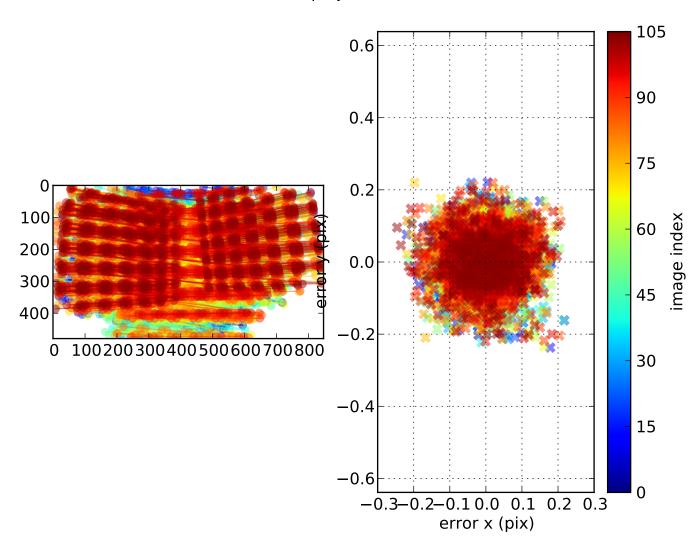
cam0: polar error



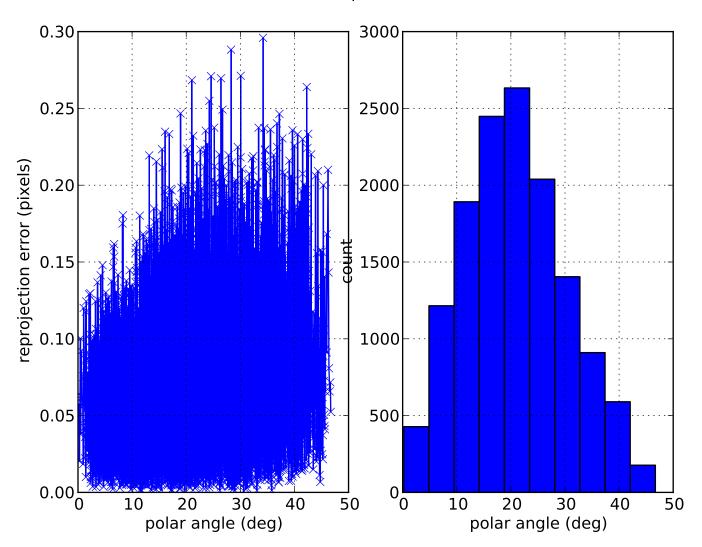
cam0: azimutal error



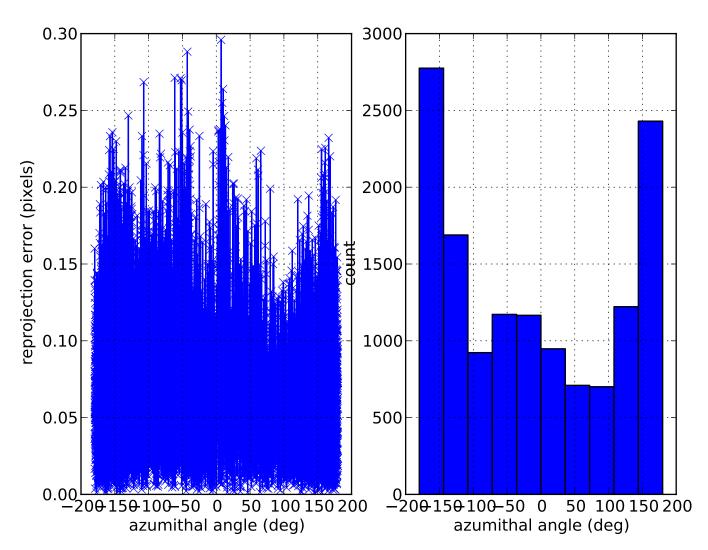
cam0: reprojection errors



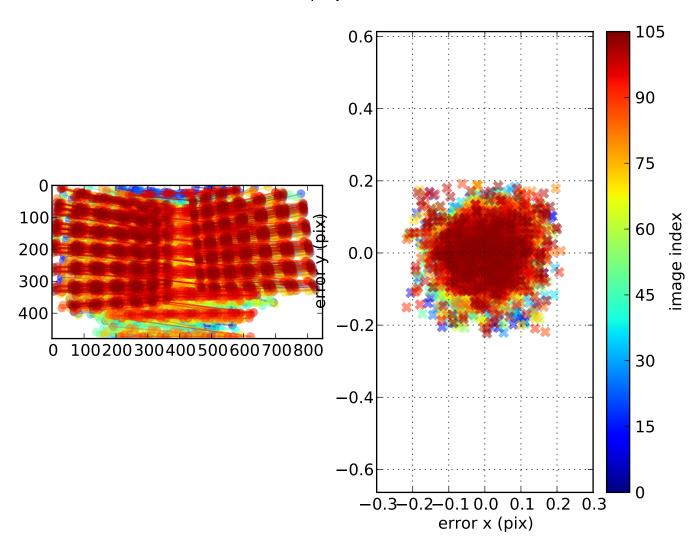
cam1: polar error



cam1: azimutal error



cam1: reprojection errors



Location of removed outlier corners

