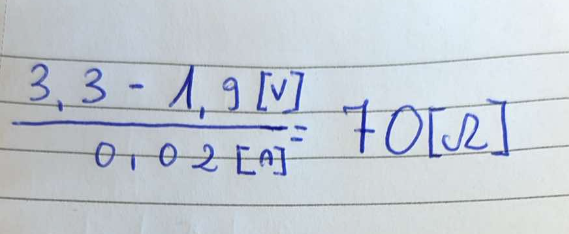
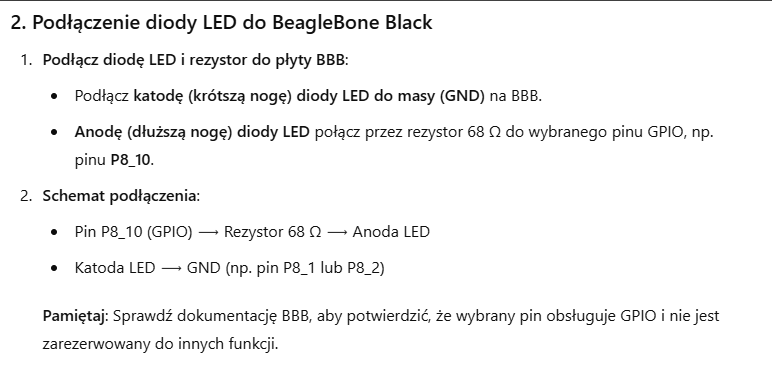
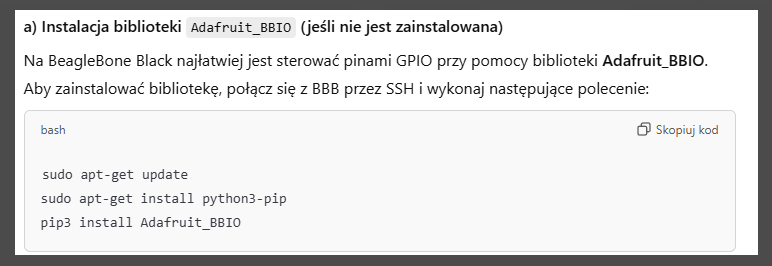


LUB PYCHARM !!!







import Adafruit\_BBIO.GPIO as GPIO

import time

LED\_PIN = "P8\_10"

GPIO.setup(LED\_PIN, GPIO.OUT)

def short\_blink():

GPIO.output(LED\_PIN, GPIO.HIGH)

time.sleep(0.25)

GPIO.output(LED\_PIN, GPIO.LOW)

time.sleep(0.25)

def long\_blink():

GPIO.output(LED\_PIN, GPIO.HIGH)

time.sleep(0.75)

GPIO.output(LED\_PIN, GPIO.LOW)

time.sleep(0.25)

try:

while True:

# Trzy krótkie mignięcia

for \_ in range(3):

short\_blink()

# Przerwa

time.sleep(0.5)

# Trzy długie mignięcia

for \_ in range(3):

long\_blink()

# Przerwa

time.sleep(0.5)

# Trzy krótkie mignięcia

for \_ in range(3):

short\_blink()

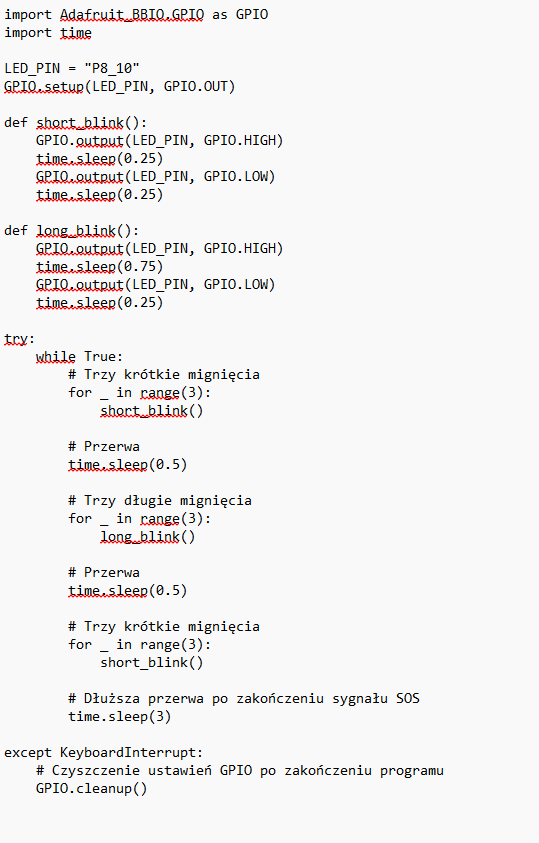
# Dłuższa przerwa po zakończeniu sygnału SOS

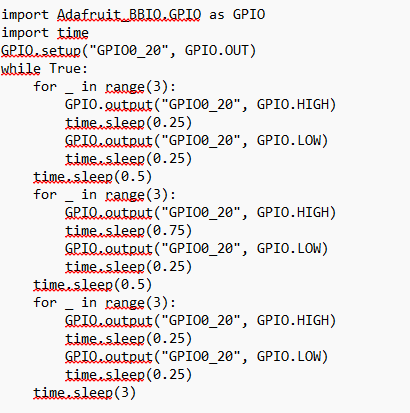
time.sleep(3)

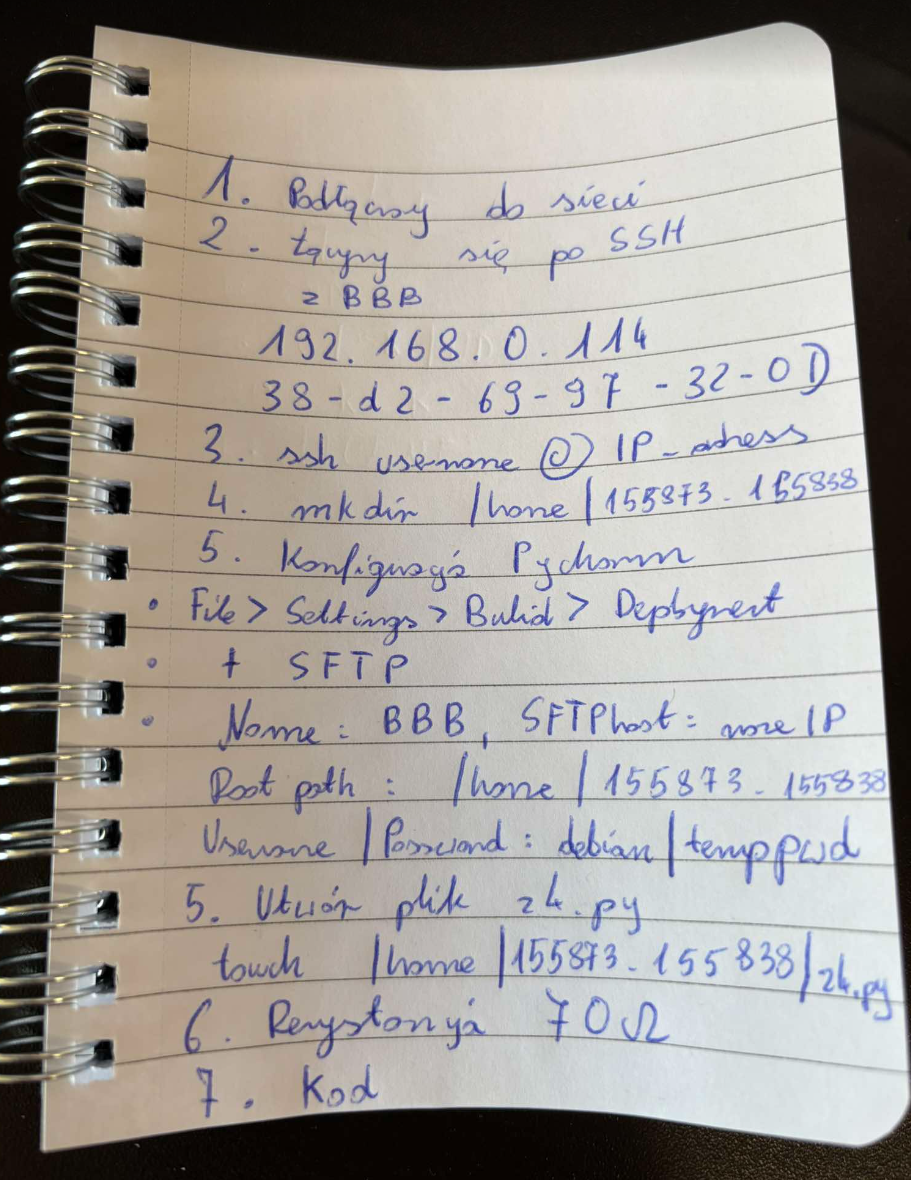
except KeyboardInterrupt:

# Czyszczenie ustawień GPIO po zakończeniu programu

GPIO.cleanup()







Sposób 2:

