

Exercise 1: Problem 9.6

Note that the Taylor estimation is $f(x+c) = f(x) + f'(x)c + f''(x)c^2/2 + f'''(x)c^3/6 + O(c^4)$. We are asked to find the values of the constants in the equation $f''(x) \approx Af(x) + Bf(x+h) + Cf(x+2h)$ that give the maximal accuracy in terms of the magnitude of h . Note that using Taylor's approximation we get $f''(x) \approx Af(x) + B[f(x) + f'(x)h + f''(x)h^2/2 + f'''(x)h^3/6] + C[f(x) + 2f'(x)h + 2f''(x)h^2 + 4f'''(x)h^3/3] + O(h^4)$. We then get the equations $A + B + C = 0$ to link values, $Bh + 2Ch = 0$, $Bh^2/2 + 2Ch^2 = 1$. Solving we get $-B = 2C$, $Bh^2/2 - Bh^2 = 1$, $Bh^2(1/2 - 1) = -Bh^2/2 = 1$, $B = -2/h^2$, $C = 1/h^2$, $A = 1/h^2$. To determine order accuracy let's ask if we also happen to get $0f'''(x)$, $Bh^3/6 + C4h^3/3 = 0$, $B + 8C = 0$, clearly false, thus we get error of order $O(h^3/h^2) = O(h)$.

Exercise 2: Turn in the last problem from the worksheet on Richardson extrapolation.

```

1 function mintegral=traprule(f,a,b,nm)
2     mintegral=[];
3     for (n=nm)
4         w=(b-a)./n;
5         cent=linspace(a+w,b-w,n-1);
6         integral=w.*(1/2*f(a)+sum(f(cent))+1/2*f(b));
7         mintegral=[mintegral integral];
8     end
9 endfunction

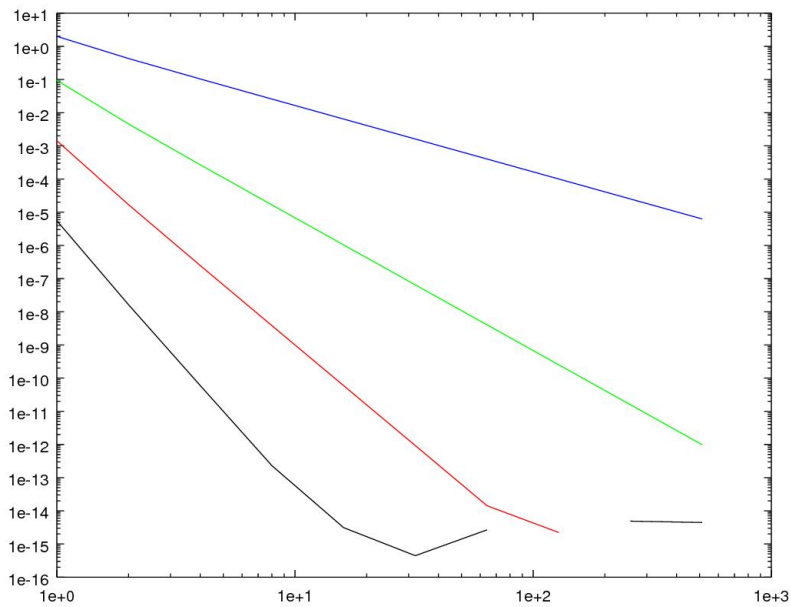
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```

1 I0=@(n) arrayfun( @(k) traprule(@(x) sin(x),0,pi,k), n);
2 I1=@(n) (I0(n*2)- 2^(-2).*I0(n)) ./ (1-2^(-2));
3 I2=@(n) (I1(n*2)- 2^(-4).*I1(n)) ./ (1-2^(-4));
4 I3=@(n) (I2(n*2)- 2^(-6).*I2(n)) ./ (1-2^(-6));
5 N=2.^[0:9];
6 loglog(N,abs(I0(N)-2),'b');
7 hold on;
8 loglog(N,abs(I1(N)-2),'g');
9 loglog(N,abs(I2(N)-2),'r');
10 loglog(N,abs(I3(N)-2),'k');
11 hold off;

```

This is a plot of the $I_k(N)$ lines for $k = [0 : 3]$ notice that there slopes are $-2, -4, -6, -8$ indicating that the error goes as $O(n^{-2}), O(n^{-4}), O(n^{-6}), O(n^{-8})$.



Exercise 3: Problem 10.8. Note that Romberg integration is just Richardson extrapolation applied to the trapezoidal rule, as you did in the previous problem.

```

1 >> [q,cnt]=romberg(0,1,1e-12)
2      3.0000e+00    9.0266e-01    1.0000e-10
3      5.0000e+00    9.0462e-01    1.0000e-10
4      9.0000e+00    9.0452e-01    9.9983e-05
5      1.7000e+01    9.0452e-01    1.1338e-07
6      3.3000e+01    9.0452e-01    1.3115e-09
7      6.5000e+01    9.0452e-01    4.8783e-13
8 warning: Matlab-style short-circuit operation performed for operator &
9 warning: called from
10      romberg at line 52 column 1
11 q =    0.90452
12 cnt =    65

```

```

13 >> n=2.^[2:7;]
14 n =
15
16      4      8     16     32     64    128
17
18 >> I0=@(n) arrayfun (@(k) traprule (@(x) cos (x.^2), 0, 1, k), n)
19 I0 =
20
21 @(n) arrayfun (@(k) traprule (@(x) cos (x .^ 2), 0, 1, k), n)
22
23 >> abs(I0(n)-q).*n.^2
24 ans =
25
26      0.14025      0.14025      0.14025      0.14025      0.14025      0.14025
27
28 >> sqrt(0.14025/1e-12)
29 ans =      3.7450e+05
30 >> diary off

```

The trapazodal rule will take arround 300,000 steps to accheve the desired accuracy. This is because the error in the trapazoid rule goes as $O(n^2)$ where as the Romberg integration is just Richardson extrapolation and increases the order of convergence as the number of steps increases.

Exercise 4: Problem 11.1 (a,b)

Solve analitically

(a)

$$\frac{dy}{dt} = t^3$$

$$y = \int dy = \int t^3 dt = t^4/4 + C$$

$$y = t^4/4$$

(b)

$$\frac{dy}{dt} = 2y$$

$$\int \frac{1}{y} dy = \int 2 dt$$

$$\ln(y) = 2t + c$$

$$\ln(3) = 2 + c$$

$$\ln(y) = 2t + \ln(3) - 2$$

(c)

$$\frac{dy}{dt} = ay + b$$

$$\begin{aligned}\text{Ansatz: } y &= ce^{\alpha t} + \beta \\ \alpha ce^{\alpha t} &= ace^{\alpha t} + a\beta + b \\ \alpha &= a \text{ and } \beta = -b/a \\ y &= ce^{\alpha t} - b/a \\ y_0 &= ce^{\alpha 0} - b/a \\ y &= (y_0 + b/a)e^{\alpha t} - b/a\end{aligned}$$

Exercise 5: Problem 11.3

If $y = t^{3/2}$ then $y' = 3/2t^{1/2}$. Noting that $t^{1/2} = y^{1/3}$ we see $y' = 3/2y^{1/3}$ and note that $(0,0)$ is a solution to $y = t^{3/2}$. Clearly $y = t^{3/2}$ is a solution to the given ODE. As a demonstration I will use one step of euler method on this problem. Note that $y_1 = 0 + 0 * h$ and $t_1 = h$. By inspection euler method will give us $y = 0$ always. Note that $y = 0$ is actually a solution to the given ODE and initial conditions, this is the problem, there are multiple solutions to the ODE passing through $(0,0)$.

Exercise 6: Problem 11.4

```

1 >> dy=@(y,t) (t+1)*e^(-y)
2 dy =
3
4 @(y, t) (t + 1) * e ^ (-y)
5
6 >> #euler
7 >> h=.1
8 h = 0.10000
9 >> y1=dy(0,0)*h
10 y1 = 0.10000
11 >> #midpoint
12 >> temp=dy(0,0)*h/2
13 temp = 0.050000
14 >> y1=dy(temp,h/2)*h
15 y1 = 0.099879
16 >> #now for Heun's method
17 >> temp=dy(0,0)*h
18 temp = 0.10000
19 >> y1=(dy(0,0)+dy(temp,h))/2*h
20 y1 = 0.099766
21 >> diary off

```

Exercise 7: Problem 11.6

For $y'(y) = \lambda y$ we know that the slopes needed for RK4 will be

$$s_1 = y'(y_k) = \lambda y_k$$

$$\begin{aligned}
s_2 &= y'(y_k + s_1 * h/2) = \lambda(y_k + \lambda y_k * h/2) = \lambda y_k + \lambda^2 y_k * h/2 \\
s_3 &= y'(y_k + s_2 * h/2) = \lambda(y_k + (\lambda y_k + \lambda^2 y_k * h/2) * h/2) = \lambda y_k + \lambda^2 y_k * h/2 + \lambda^3 y_k * (h/2)^2 \\
s_4 &= y'(y_k + s_3 * h) = \lambda(y_k + s_3 * h) = \lambda y_k + \lambda^2 y_k h + \lambda^3 y_k * h^2/2 + \lambda^4 y_k * h^3/4 \\
y_{k+1} &= y_k + h/6(s_1 + 2s_2 + 2s_3 + s_4) = y_k + h/6(6\lambda y_k + 3\lambda^2 y_k * h + \lambda^3 y_k * h^2 + \lambda^4 y_k * h^3/4) = \\
&\quad [1 + \lambda h + \lambda^2 h^2/2 + \lambda^3 h^3/6 + \lambda^4 h^4/24]y_k
\end{aligned}$$

Exercise 8: Problem 11.14 (a,b)

(a) The new system of equations would be

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} z \\ w \\ \frac{-x}{(x^2+y^2)^{2/3}} \\ \frac{-y}{(x^2+y^2)^{2/3}} \end{bmatrix}$$

(b) This is my general orbit evaluator

```

1 function out=orbit(pos,dt,t,m);
2 #pos=[x,y,dx,dy]
3 distance=@(pos) sqrt(pos(1)^2+pos(2)^2);
4 dpos=@(pos,t) [pos(3),pos(4),-pos(1)/distance(pos)^3,-pos(2)/distance(pos)^3];
5 n=ceil(t/dt);
6 px=zeros(1,n);
7 py=zeros(1,n);
8 for i=1:n
9     px(i)=pos(1);
10    py(i)=pos(2);
11    pos=m(pos,dpos,dt,t);
12 end
13 plot(px,py);
14 axis('equal');

```

and here are euler and RK4

```

1 function out=euler(pos,dpos,dt,t)
2     out=pos+dpos(pos,t)*dt;
3 endfunction

```

```

1 function out=RK4(pos,dpos,dt,t)
2     s1=dpos(pos,t);
3     s2=dpos(pos+s1*dt/2,t+dt/2);
4     s3=dpos(pos+s2*dt/2,t+dt/2);
5     s4=dpos(pos+s3*dt,t);
6     out=pos+(s1+2*s2+2*s3+s4)*dt/6;
7 endfunction

```

here is the evaluation

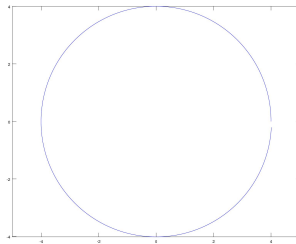
```

1 >> orbit([4,0,0,.5],.0025,50,@(pos,dpos,dt,t) euler(pos,dpos,dt,t))
2 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
3 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
4 >> diary off
5 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
6 >> orbit([4,0,0,.6],.5,150,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
7 >> orbit([4,0,0,.8],.5,200,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
8 >> orbit([4,0,0,.4],.25,35,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
9 >> orbit([4,0,0,.2],.25,30,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
10 >> orbit([4,0,0,.2],.05,30,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
11 >> diary off

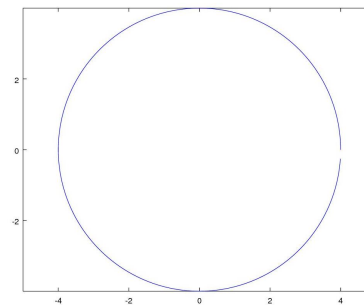
```

and the figures

euler

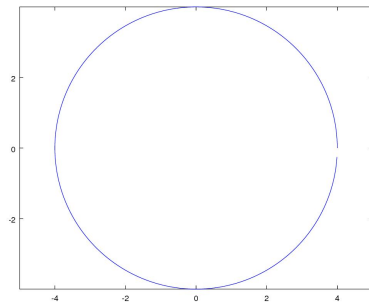


RK4

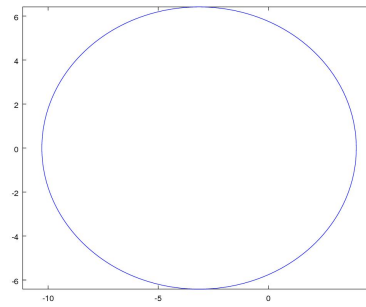


And here ar the requested runs notation is $[w(0),h,tmax]$

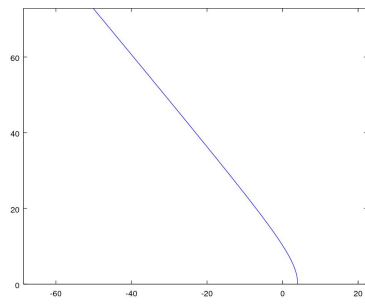
[0.5, 0.25, 50]



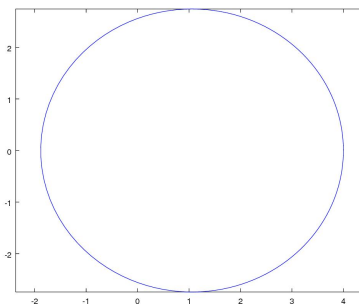
[0.6, 0.5, 150]



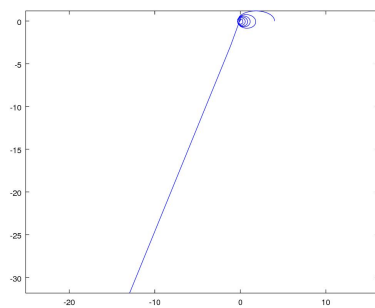
[0.8, 0.5, 200]



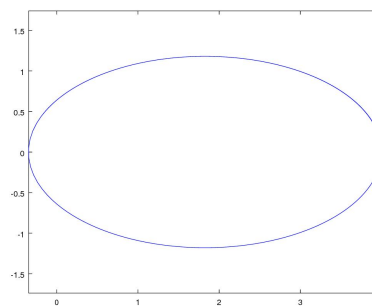
[0.4, 0.25, 35]



[0.2, 0.25, 30]



[0.2, 0.05, 30]



this is my command line

```

1 >> orbit([4,0,0,.5],.0025,50,@(pos,dpos,dt,t) euler(pos,dpos,dt,t))
2 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
3 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
4 >> diary off
5 >> orbit([4,0,0,.5],.25,50,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
6 >> orbit([4,0,0,.6],.5,150,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
7 >> orbit([4,0,0,.8],.5,200,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
8 >> orbit([4,0,0,.4],.25,35,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
9 >> orbit([4,0,0,.2],.25,30,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
10 >> orbit([4,0,0,.2],.05,30,@(pos,dpos,dt,t) RK4(pos,dpos,dt,t))
11 >> diary off

```