

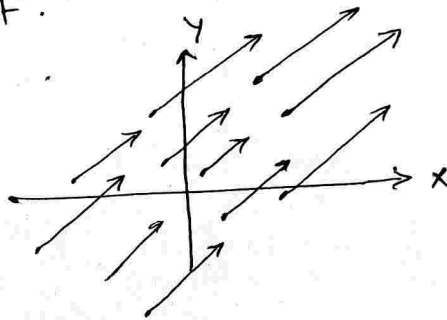
Lecture 19 Vector fields:

⊕ $\vec{F} = M\hat{i} + N\hat{j}$, M and N are f^n of x, y .

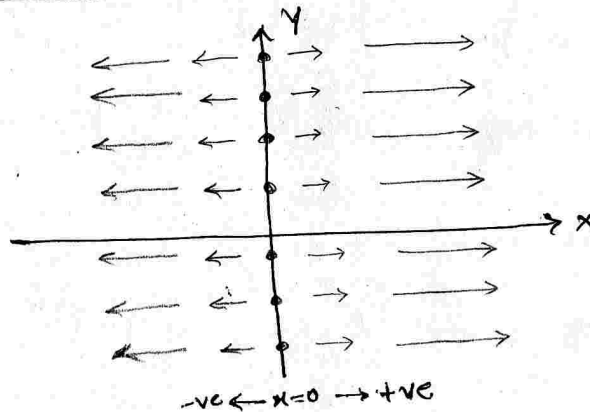
At each point (x, y) , \vec{F} a vector that depends on x & y .

Example: ① velocity in a fluid \vec{v}
② force field \vec{F} .

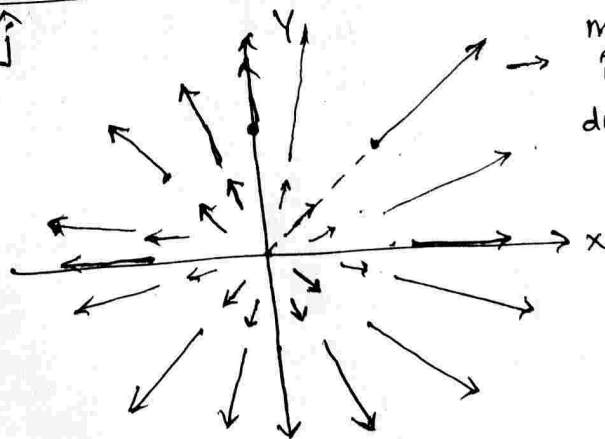
Example 6 $\vec{F} = 2\hat{i} + \hat{j}$



Example: $\vec{F} = x\hat{i}$



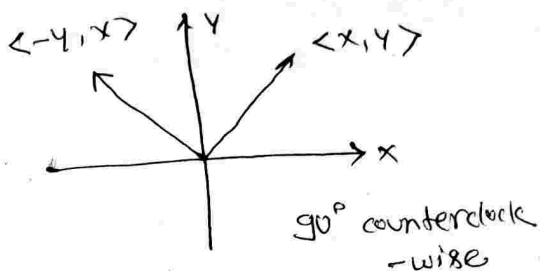
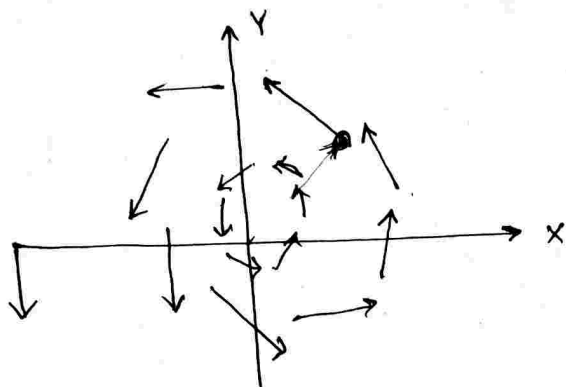
Example: $\vec{F} = x\hat{i} + y\hat{j}$



magnitude increases with distances from origin.

Example 6

$$\vec{F} = -y\hat{i} + x\hat{j}$$

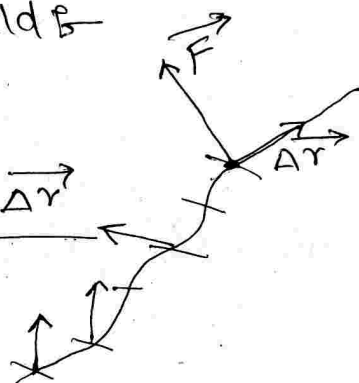


Velocity field for uniform rotation at unit angular velocity.

⊕ Compute Work done by vector field \vec{F}
Work & line integrals 6

$$W = (\text{Force}) \cdot (\text{distance}) = \vec{F} \cdot \Delta \vec{r}$$

Total work along some trajectory:
 (C)



work adds up to

$$W = \int_C \vec{F} \cdot d\vec{r}$$

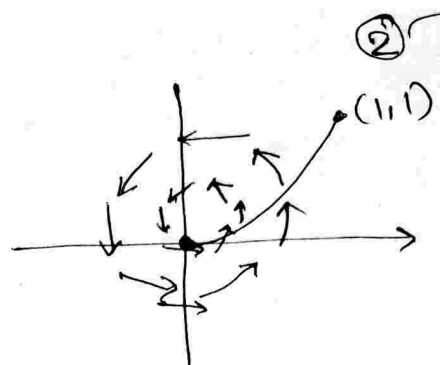
$$W = \int_{t_1}^{t_2} \vec{F} \cdot \frac{d\vec{r}}{dt} dt$$

$$\left(\begin{aligned} &= \lim_{\Delta r_i \rightarrow 0} \sum_i \vec{F} \cdot \Delta \vec{r}_i \\ &= \lim_{\Delta t \rightarrow 0} \sum_i \vec{F} \cdot \underbrace{\left(\frac{\Delta \vec{r}}{\Delta t} \Delta t \right)}_{\text{velocity vector}} \end{aligned} \right)$$

Example 5- $\vec{F} = -y\hat{i} + x\hat{j}$;

$$C; \begin{cases} x=t \\ y=t^2 \end{cases} \quad 0 \leq t \leq 1$$

Work = ?



Soln-

$$\int_C \vec{F} \cdot d\vec{r} = \int_0^1 \vec{F} \cdot \frac{d\vec{r}}{dt} \cdot dt = \int_0^1 \langle -t^2, t \rangle \cdot \langle 1, 2t \rangle dt$$

$$\begin{aligned} \therefore \vec{F} = \langle -y, x \rangle &= \langle -t^2, t \rangle \\ &\quad \begin{matrix} \uparrow \\ x=t \\ y=t^2 \end{matrix} \\ \therefore dx/dt &= 1; \quad dy/dt = 2t \end{aligned} \quad \left| \begin{aligned} &= \int_0^1 (-t^2 + 2t^2) dt \\ &= \int_0^1 t^2 dt = 1/3. \end{aligned} \right.$$

Another way:

$$\vec{F} = \langle M, N \rangle$$

$$d\vec{r} = \langle dx, dy \rangle$$

$$\vec{F} \cdot d\vec{r} = Mdx + Ndy$$

$$\boxed{\int_C \vec{F} \cdot d\vec{r} = \int_C Mdx + Ndy}$$

Method to evaluate express x, y in terms of a single variable & substitute it

$$\int_C \vec{F} \cdot d\vec{r} = \int_C -y dx + x dy = \text{in terms of } t$$

$$x=t$$

$$y=t^2$$

$$dx=dt$$

$$dy=2t dt$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C -t^2 dt + t \cdot 2t dt$$

$$= \int_0^1 t^2 dt = \frac{1}{3};$$

General Method If you are given a curve then you first have to figure out how do you express x & y in terms of the same thing.

Note: $\int_C \vec{F} \cdot d\vec{r}$ depends on the trajectory C but not on parametrization.

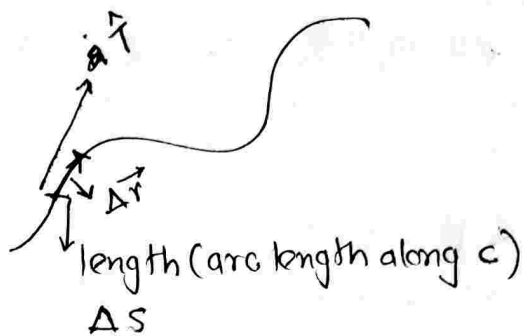
e.g. could be $\begin{cases} x = \sin \theta \\ y = \sin^2 \theta \end{cases} \quad 0 \leq \theta \leq \frac{\pi}{2}$
(NOT PRACTICAL)

③

Geometric Approach

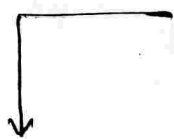
Arg

If I take a very small piece of trajectory then my vector $\Delta \vec{r}$ will be tangent to the trajectory.



→ It will be going in same direction as the unit tangent (\hat{t}). & its length, arc length along trajectory (Δs).
 $s \rightarrow$ distance along trajectory.

$$\boxed{d\vec{r} = \langle dx, dy \rangle = \hat{t} \cdot ds}$$



So,

(Note: $\frac{d\vec{r}}{dt} = \langle \frac{dx}{dt}, \frac{dy}{dt} \rangle = \hat{t} \cdot \frac{ds}{dt}$)

$$\boxed{\int_C \vec{F} \cdot d\vec{r} = \int_C M dx + N dy = \int_C \underbrace{\vec{F} \cdot \hat{t}}_{\text{scalar quantity}} ds}$$

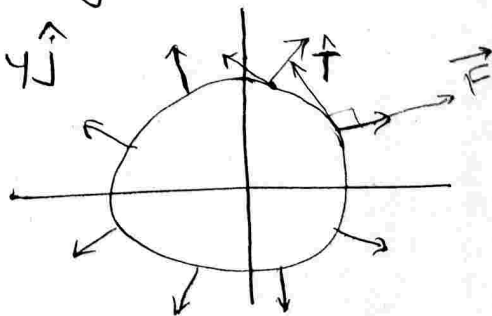
It is the tangent component of force.

Example C : circle of radius 'a' at origin; counterclockwise, $\vec{F} = x\hat{i} + y\hat{j}$

$\Rightarrow \hat{t} \perp$ to radial direction \vec{F}

Sol: $\vec{F} \perp \hat{t}$; so, $\vec{F} \cdot \hat{t} = 0$

$$\int_C \vec{F} \cdot \hat{t} ds = 0.$$

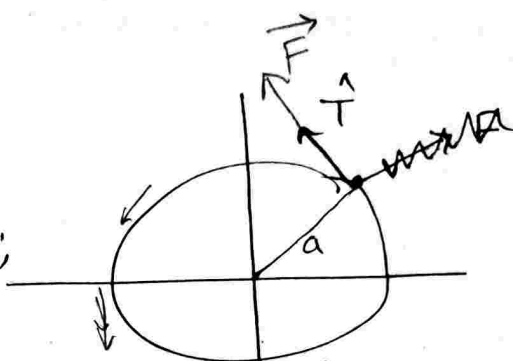


example 6

C: same

$$\vec{F} = -y\hat{i} + x\hat{j}$$

Sol: $\vec{F} \parallel \hat{T}; \vec{F} \cdot \hat{T} = |\vec{F}| = a;$



$$\int_C \vec{F} \cdot \hat{T} ds = \int_C a ds = a \int_C ds = a \cdot \text{length}(C) = 2\pi a^2$$

(or: computing: $\int_C -y dx + x dy = \int_C -(a \sin \theta)(-a \sin \theta) d\theta$

$$x = a \cos \theta$$

$$y = a \sin \theta$$

$$0 \leq \theta \leq 2\pi$$

$$+ (a \cos \theta)(a \cos \theta) d\theta) = \int_0^{2\pi} a^2 (\sin^2 \theta + \cos^2 \theta) d\theta$$

Lecture: 20

Path Independence and conservative fields.

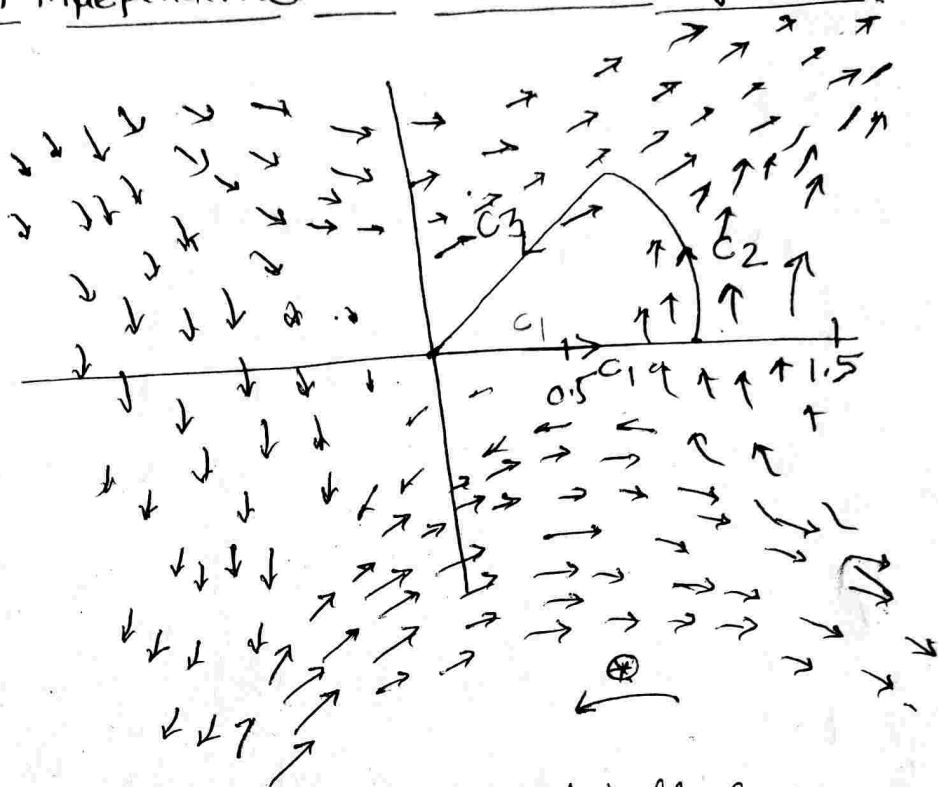
example vector field:

$$\vec{F} = \langle y, x \rangle$$

$$\int_C \vec{F} \cdot d\vec{r} \quad C = C_1 + C_2 + C_3$$

enclosing sector
of unit disk

$$0 \leq \theta \leq \frac{\pi}{4}$$



Need $\int_{C_1} y dx + x dy$

(a) x-axis &—

from (0,0) to (1,0):—

$$y=0; \quad dy=0;$$

$$\int_{C_1} y dx + x dy = \int_{C_1} 0 dx + 0 = 0;$$

(a) Geometrically &

Along the x-axis, vector field is pointing \uparrow vertically (y-direction)

Work done will be zero

$$\vec{F} \parallel \hat{j}; \quad \vec{F} \cdot \hat{i} = 0.$$

(b) C_2 : portion of unit circle &

$$x = \cos \theta$$

$$y = \sin \theta$$

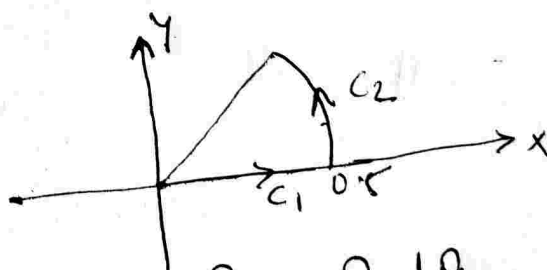
$$0 \leq \theta \leq \pi/4$$

$$dx = -\sin \theta d\theta$$

$$dy = \cos \theta d\theta$$

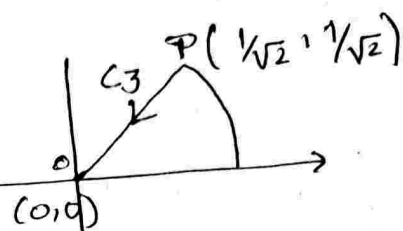
$$\int_C y dx + x dy = \int_0^{\pi/4} \sin \theta \cdot (-\sin \theta d\theta) + \cos \theta \cdot \cos \theta \cdot d\theta$$

$$= \int_0^{\pi/4} \underbrace{\cos^2 \theta - \sin^2 \theta}_{\cos(2\theta)} d\theta = \left[\frac{1}{2} \sin 2\theta \right]_0^{\pi/4} = 1/2$$



②

figure out a way to express x & y as a same parameter.



$$\int_{C_3} y dx + x dy$$

Could do:

$$y = \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} t$$

$$x = \frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} t$$

start from P at $t=0$
end at point O at $t=1$

$$0 \leq t \leq 1$$

Better

$x=t$
 $y=t$ + from 0 to $1/\sqrt{2}$ gives us $(-C_3)$ (C_3 backwards)

paramaterization

$$dx=dt; dy=dt$$

$$\int_{-C_3} y dx + x dy = \int_0^{1/\sqrt{2}} t dt + t dt = \int_0^{1/\sqrt{2}} 2t dt = \left[t^2 \right]_0^{1/\sqrt{2}} = \underline{\underline{1/2}}$$

$$\boxed{\int_{C_3} y dx + x dy = -1/2}$$

$$\text{Total work } \int_C = \int_{C_1} + \int_{C_2} + \int_{C_3} = 0 + \frac{1}{2} - \frac{1}{2} = 0.$$

⊕ Special Cases

Say that \vec{F} is gradient of some function so it's a gradient field $\boxed{\vec{F} = \nabla f}$ ($f(x, y)$ is called potential)

Then we can simplify evaluation of $\int_C \vec{F} \cdot d\vec{r}$.

⊕ Fundamental theorem of calculus for line integrals

$$\int_C \vec{F} \cdot d\vec{r} \quad \left| \quad \int_C \nabla f \cdot d\vec{r} = f(P_1) - f(P_0) \right.$$

for gradient

$$\int_C f_x dx + f_y dy = \int_C df = f(P_1) - f(P_0)$$

Proof! $\int_C \nabla f \cdot d\vec{r} = \int_C f_x dx + f_y dy$

C: $x = x(t)$
 $y = y(t)$
 $t_0 \leq t \leq t_1$

Sol! $x = x(t), \quad dx = x'(t) dt$
 $y = y(t), \quad dy = y'(t) dt$

$$\int_C \nabla f \cdot d\vec{r} = \int_C \left(f_x \frac{dx}{dt} + f_y \frac{dy}{dt} \right) dt$$

$$= \int_{t_0}^{t_1} \frac{df}{dt} dt = \left[f(x(t), y(t)) \right]_{t_0}^{t_1} = f(P_1) - f(P_0)$$

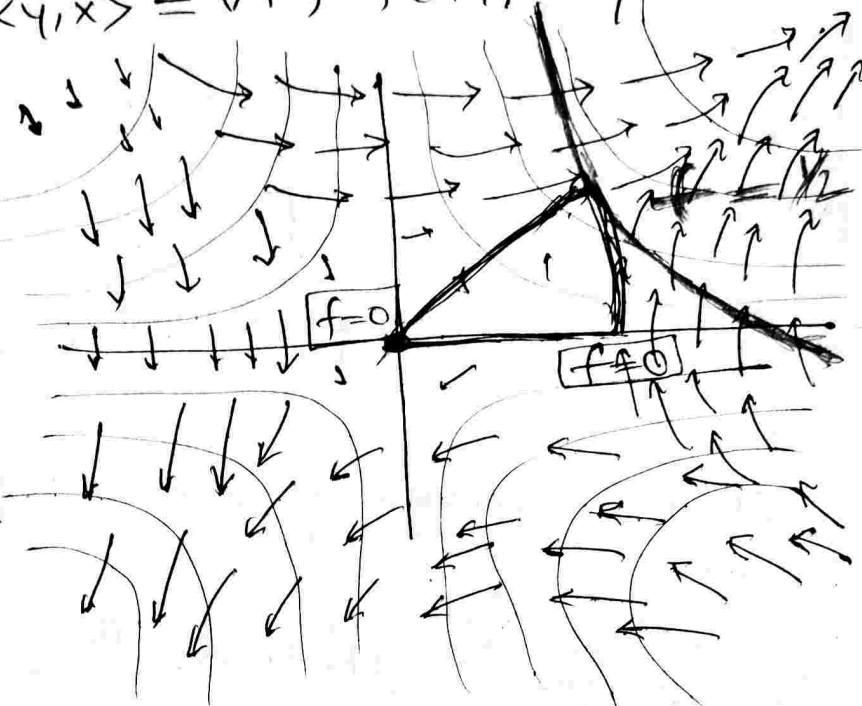
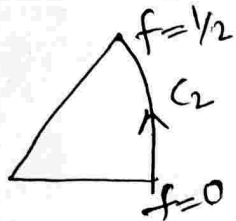
$$\boxed{\int_C \nabla f \cdot d\vec{r} = f(P_1) - f(P_0)}$$

examples $\vec{F} = \langle y, x \rangle = \nabla f$, $f(x, y) = xy$

So:

$$\int_{C_2} \vec{F} \cdot d\vec{r} = f\left(\frac{1}{2}, \frac{1}{\sqrt{2}}\right) - f(0, 0)$$

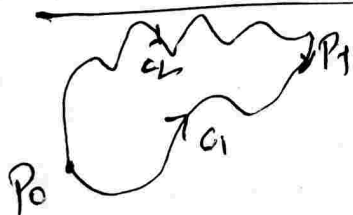
$$= \frac{1}{2} - 0 = \frac{1}{2}$$



WARNING: Everything today only applies if \vec{F} is a gradient field! Not true otherwise!

⊕ Consequences of fundamental theorem
IF \vec{F} is a gradient field

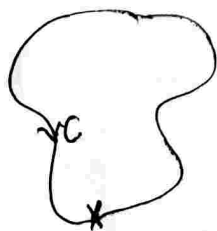
→ Path-Independence



$$\int_{c_1} \vec{F} \cdot d\vec{r} = \int_{c_2} \vec{F} \cdot d\vec{r}$$

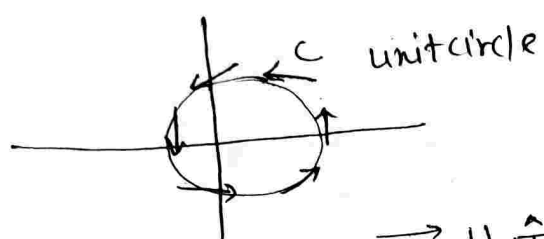
if c_1, c_2 have same start & end point.

→ $\vec{F} = \nabla f$ is conservative.



⇒ if 'C' is closed curve $\Rightarrow \int_C \vec{F} \cdot d\vec{r} = 0$
Work = 0

Remark: $\vec{F} = \langle -y, x \rangle$;



$$\int_C \vec{F} \cdot \hat{T} ds = \int_C 1 ds = 2\pi \neq 0.$$

On unit circle, $\vec{F} \parallel \hat{T}$

$$\vec{F} \cdot \hat{T} = |\vec{F}| = 1$$

NOT CONSERVATIVE.

SO ITS NOT A GRADIENT VECTOR.

NOT PATH INDEPENDENT

⊕ Physics: If force \vec{F} is gradient of a potential

$$\boxed{\vec{F} = \nabla f}$$

→ work of \vec{F} = change in value of potential

(E.g: gravitational field vs. gravitational electrical field vs. electrical potential.)

→ conservativeness means no energy can be extracted from the field "for free".

— total energy is conserved.

→ EQUIVALENT PROPERTIES

① \vec{F} is conservative: $\int_C \vec{F} \cdot d\vec{r} = 0$ along all closed curves C .



② $\int_C \vec{F} \cdot d\vec{r}$ is path independent.

③ \vec{F} is a gradient field $\vec{F} = \langle f_x, f_y \rangle$

④ $Mdx + Ndy$ is an exact differential $= df$.
