

# Lecture 5

## Parametric equations for lines & curves

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### ## EQUATIONS OF LINES

We have seen line = intersection of 2 planes.

Another representation of line

(line is the trajectory of a point as time varies.)

line = trajectory of moving point = "parametric equation"

example -

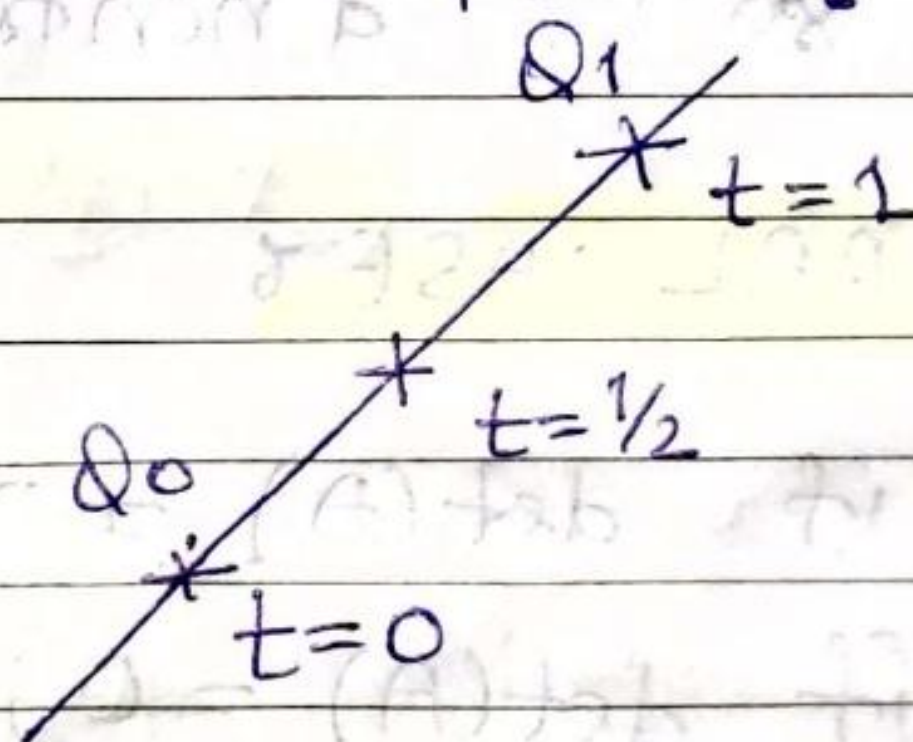
Line through

$$Q_0 = (-1, 2, 2) ; Q_1 = (1, 3, -1)$$

Now, how to find all the other points?

Solutions

Let's say  $Q(t)$  is moving point, and at  $t=0$ ; it is  $Q_0$  & moves at constant speed on the line



What is the position at time  $t=0$   $Q(t)$ ?

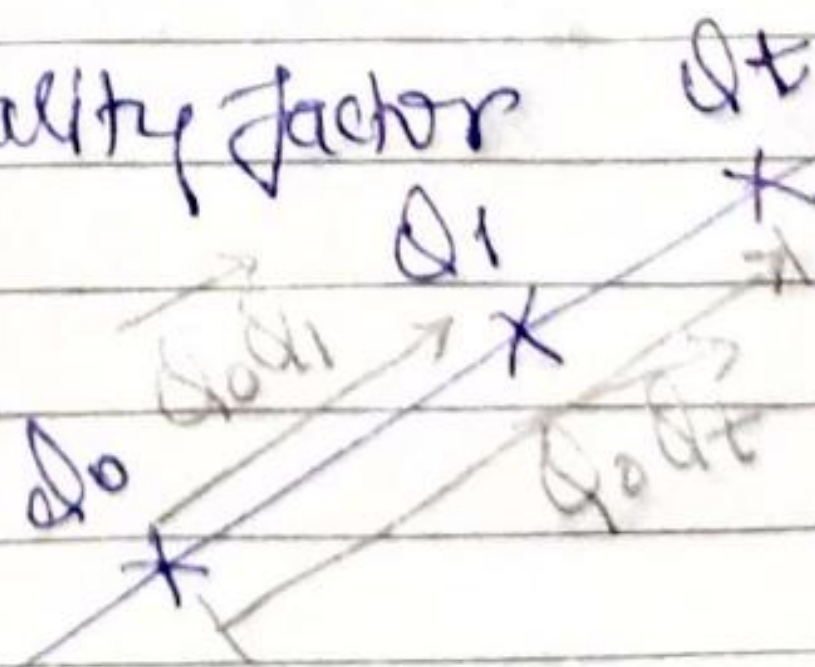
$$\overrightarrow{Q_0 Q(t)} = t \overrightarrow{Q_0 Q_1}$$

↳ proportionality factor

$$\overrightarrow{Q_0 Q(t)} = t \langle 2, 1, -3 \rangle$$

$$Q(t) = (x(t), y(t), z(t))$$

↳ co-ordinate of moving point





$$\begin{cases} x(t)+1 = t \cdot 2 \\ y(t)-2 = t \\ z(t)-2 = -3t \end{cases} \quad \begin{matrix} (3-2) \\ (-1-2) \end{matrix}$$

$$\vec{Q_0 Q(t)} = t \vec{Q_0 Q_1}$$

$$(x(t)-(-1)) = t(2-(-1))$$

$$\begin{cases} x(t) = -1 + 2t \\ y(t) = 2 + t \\ z(t) = 2 - 3t \end{cases} \quad \begin{matrix} \text{where we are at } t=0 \\ \vec{Q_0 Q_1} \end{matrix}$$

$$Q(t) = Q_0 + t \vec{Q_0 Q_1}$$

### Application 6 Intersection with a plane?

Consider the plane  $x+2y+4z=7$

where does the line  $Q_0 Q_1$  intersect the plane?

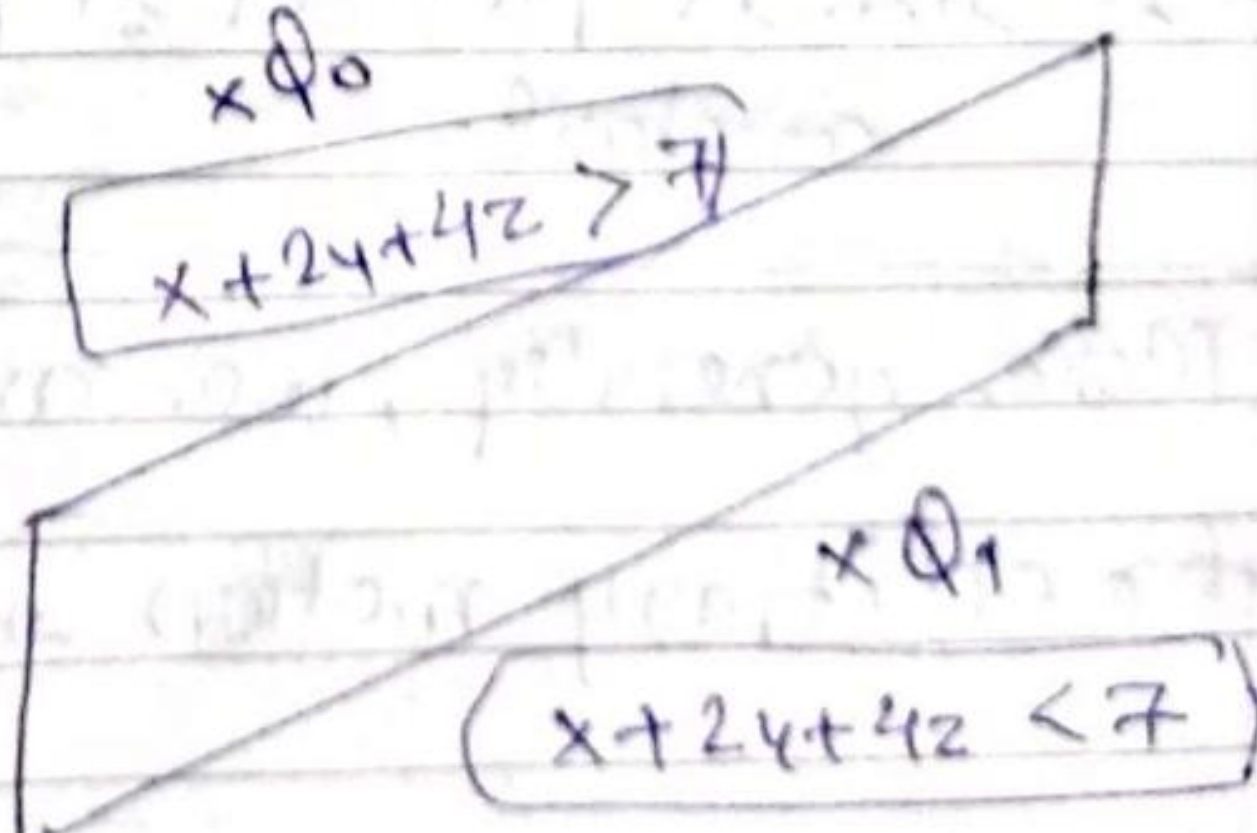
Q: Relative to  $x+2y+4z=7$ ;

$Q_0 = (-1, 2, 2)$  &  $Q_1 = (1, 3, -1)$  are on

Ans:  $\hookrightarrow Q_0 = (-1, 2, 2)$ ;  $x+2y+4z = (-1)+2 \times 2+4 \times 2 = 11 > 7$   
(so  $Q_0$  not in the plane)

$Q_1 = (1, 3, -1)$ ;  $x+2y+4z = 1+2 \times 3-4 = 3 < 7$   
(not in plane)

$Q_0$  &  $Q_1$  are opposite sides of the plane





↳ What about moving point  $Q(t)$ ?

$$x(t) + 2y(t) + 4z(t)$$

$$= (-1+2t) + 2(2+t) + 4(2-3t)$$

$$= -8t + 11 = 7$$

↳  $Q(t)$  is the plane when

$$-8t + 11 = 7$$

$$\Leftrightarrow t = \frac{1}{2}$$

Then  $Q\left(\frac{1}{2}\right) = \left(0, \frac{5}{2}, \frac{1}{2}\right)$

(Plug the values

into  $(-1+2t) + 2(2+t) + 4(2-3t)$

$= 7$  ✓  
 $Q_0 + t(Q_1 - Q_0)$

→ this is the line where the plane intersects.  $\left(0, \frac{5}{2}, \frac{1}{2}\right)$  ✓

Note If a line in the plane then plugging  $(x(t), y(t), z(t))$  into eq<sup>n</sup> always gives 7!

↳ If line is parallel to plane, we get another constant.

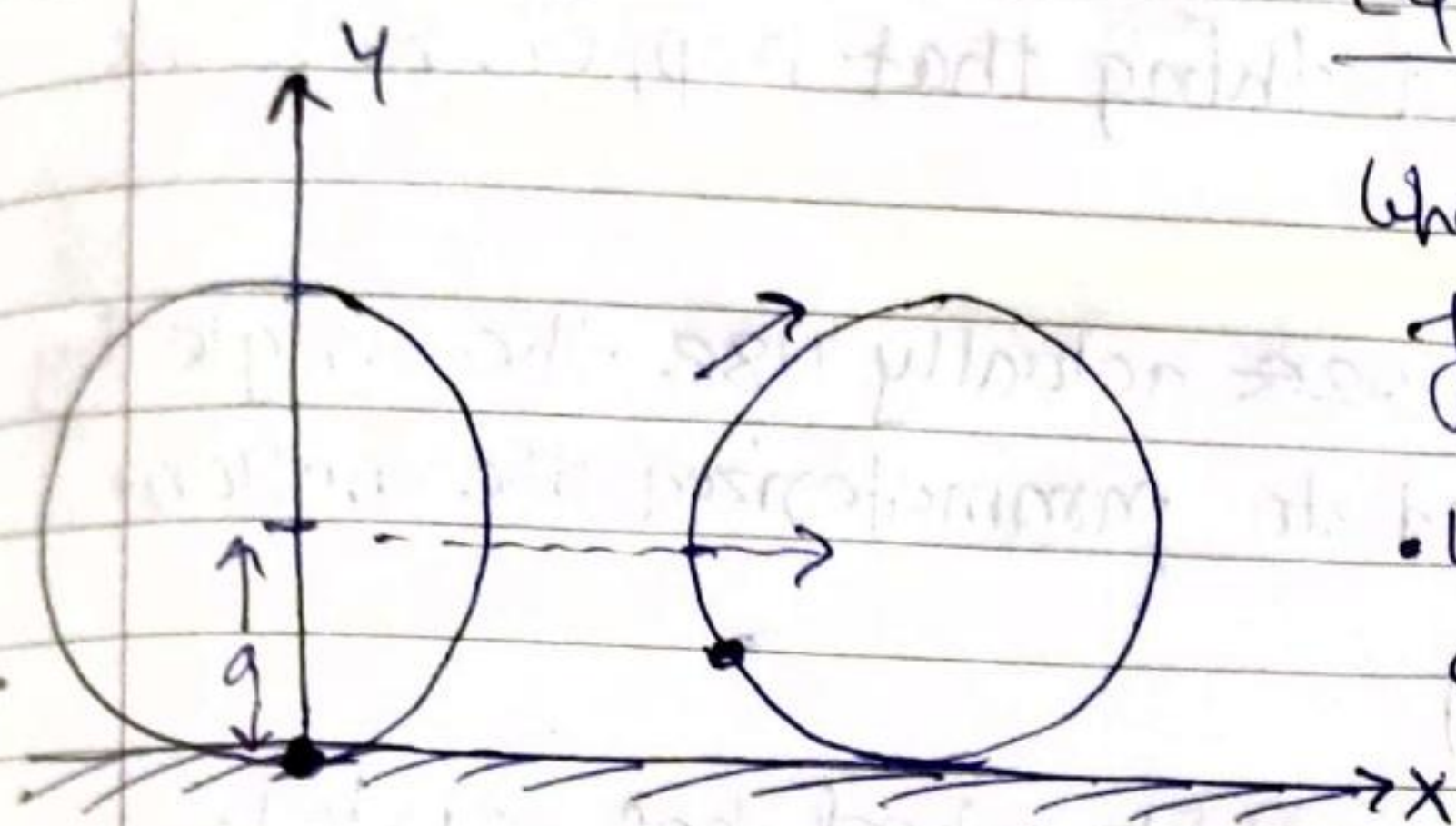
↳ More generally, we can use parametric eq<sup>n</sup> for arbitrary motion in the plane or in space!

Que

Soln

Ma



example cycloidcycloid:

Wheel of radius  $a$  rolling on floor =  $x$ -axis

• We have point 'P', painted on the wheel.

• Initially, it's at the origin

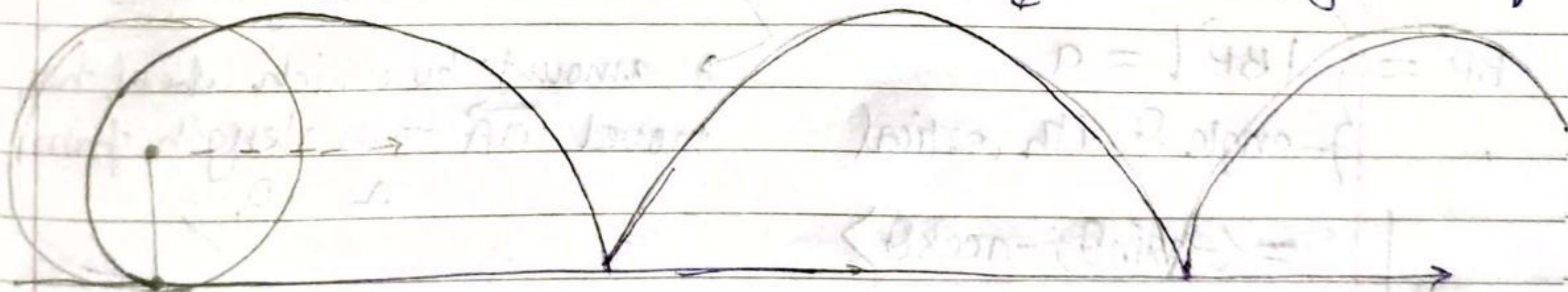
But as time goes by, it moves on the wheel.

⇒ P is the point on the rim of wheel, starts at origin

In particular, can we find the position of this point,  $x(t)$ ,  $y(t)$ , as a function of time?

trajectory of cycloid-

trajectory of cycloid



Question:- position  $(x(t), y(t))$  of the point P?

Soln I am expressing the position in terms of time. Let's see, is time going to be a good thing to do? Well, suddenly, the position changes over time. But doesn't actually matter how fast the wheel is rolling? No; because trajectory ~~to~~ will be same.

So, In fact, time is not most relevant thing here.

Matter, is how far wheel has gone. So we can use



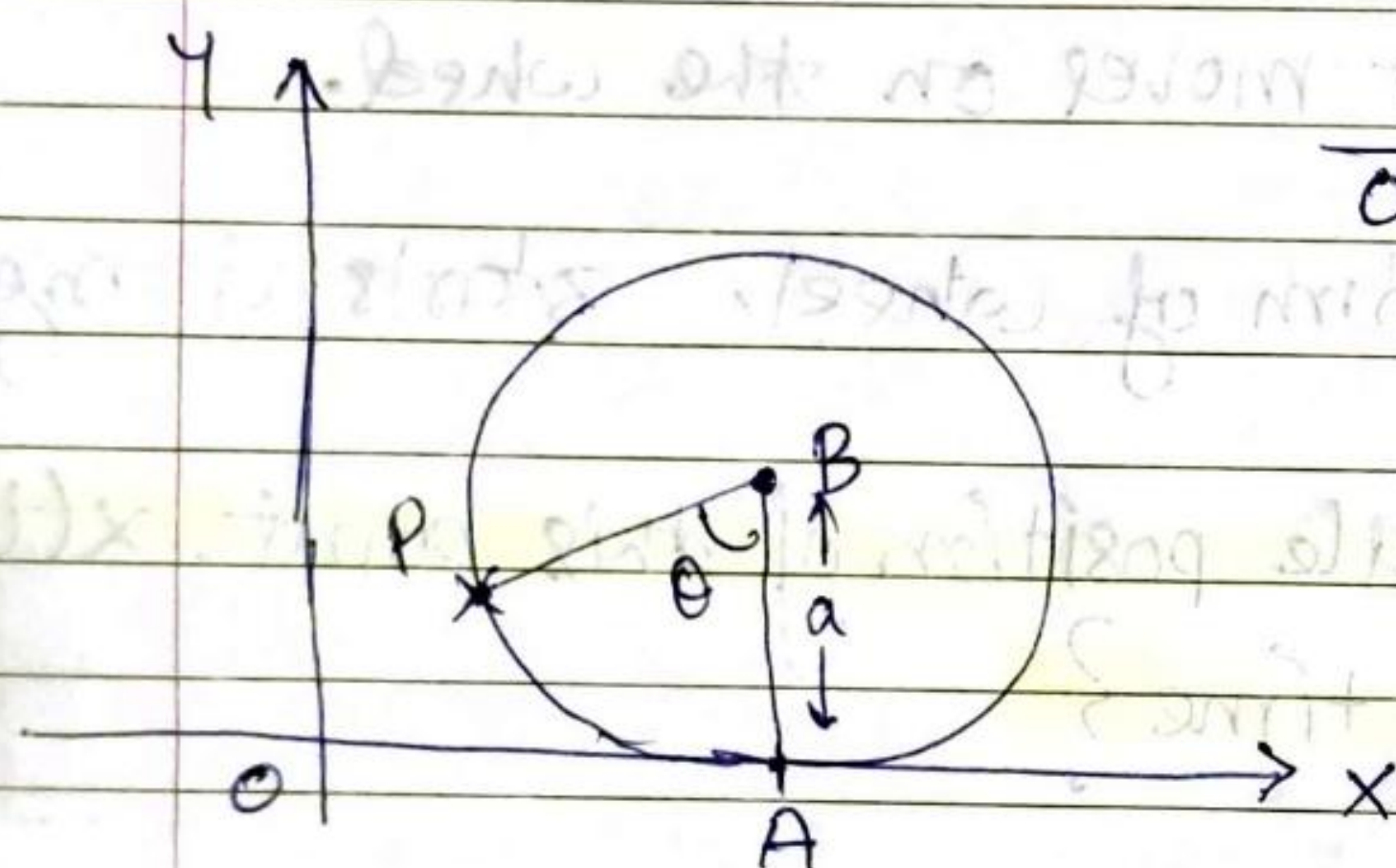
→ parameter, for example, the distance by which the wheel has moved.

We can even do even better because we see that, really, the most complicated thing that happens here is really the rotation.

So, maybe we can ~~use~~ actually use the angle by which the wheel has turned to parameterized the motion.

$$(x(\theta), y(\theta))$$

as a f<sup>n</sup> of the angle by which wheel has rotated.



$$\vec{OP} = \vec{OA} + \vec{AB} + \vec{BP}$$

$$\vec{OA} = \langle a\theta, 0 \rangle$$

two components

→ y will be 0,

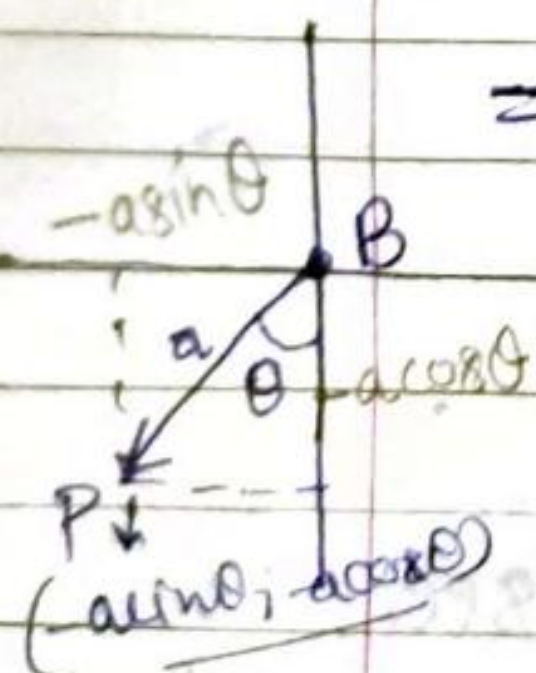
because it's directed along x-axis

amount by which wheel has moved  $\vec{OA}$  = arclength from A to P.

$$\vec{AB} = \langle 0, a \rangle$$

$$\vec{BP} = \begin{cases} |\vec{BP}| = a \\ \text{- angle } \theta \text{ with vertical} \end{cases}$$

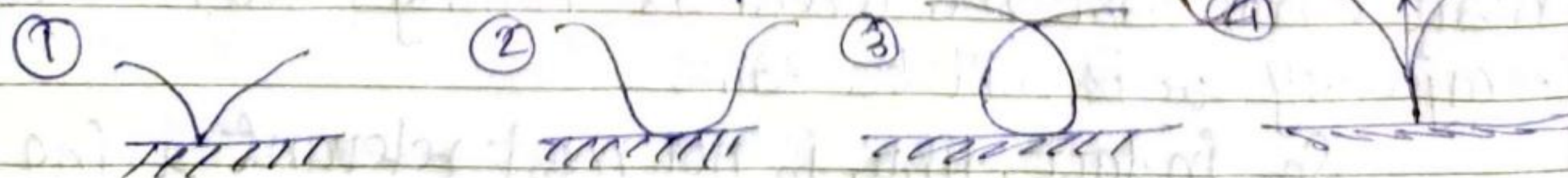
$$= \langle -a\sin\theta, -a\cos\theta \rangle$$



$$\vec{OP} = \langle \underbrace{a\theta - a\sin\theta}_{x(\theta)}, \underbrace{a - a\cos\theta}_{y(\theta)} \rangle$$

Question:   
 Note:

Near the bottom point =





let's try to figure out from formula



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$$\vec{OP} = \langle \underbrace{(a\theta - a\sin\theta)}_{x(\theta)}, \underbrace{(a - a\cos\theta)}_{y(\theta)} \rangle$$

Q: what happens near the bottom point?

A:

take length unit = radius  $\therefore a=1$

$$\begin{cases} x(\theta) = \theta - \sin\theta \\ y(\theta) = 1 - \cos\theta \end{cases}$$

$$\sin(\theta) \approx \theta$$

↓ very small angle.

$$\cos(\theta) \approx 1$$

↑ for very small

Better approximation?

Taylor's expansion

for if  $t$  is small, then value of  $f^n$

$$f(t) \approx f(0) + t f'(0) + \frac{t^2}{2} f''(0) + \frac{t^3}{6} f'''(0)$$

→ to be more precise.

$$\sin(\theta) \approx \theta - \frac{\theta^3}{6}$$

$$\cos(\theta) \approx 1 - \frac{\theta^2}{2}$$

$$x(\theta) \approx \theta - \left(\theta - \frac{\theta^3}{6}\right) \approx \frac{\theta^3}{6}$$

$$y(\theta) \approx 1 - \left(1 - \frac{\theta^2}{2}\right) \approx \frac{\theta^2}{2} \quad \checkmark \text{ is large}$$

$$|x| \ll |y|$$

$$\frac{y}{x} \approx \frac{\theta^2/2}{\theta^3/6} = \frac{3}{\theta} \rightarrow \infty \quad \text{when } \theta \rightarrow 0$$

Slope at origin is  $\infty$ .

