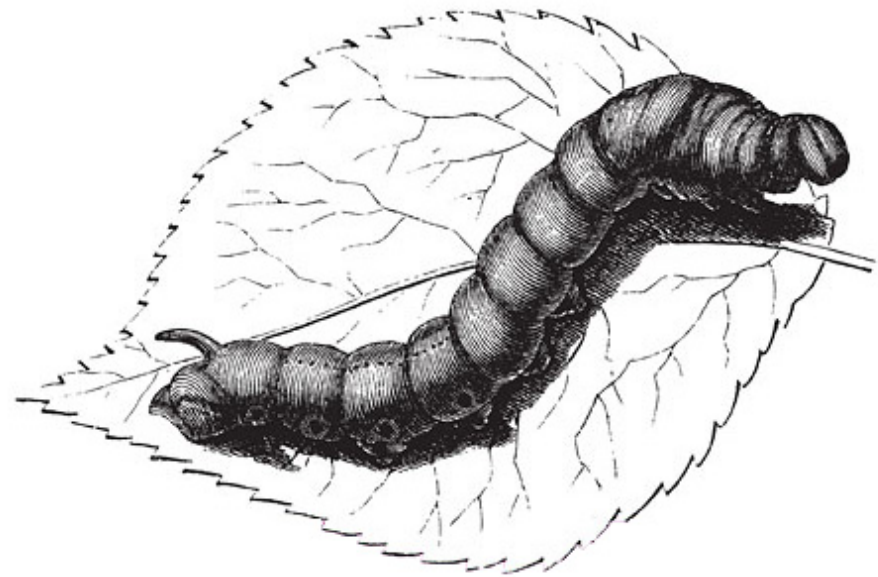


# POSIX Threads

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# CREATING AND DESTROYING THREADS

The **pthread\_create()** function is used to create a new thread. If successful, the **pthread\_create()** function returns zero. Otherwise, an error number is returned to indicate the error.

```
int pthread_create(pthread_t *thread, const pthread_attr_t *attr,  
void *(*start_routine)(void*), void *arg);
```

# CREATING AND DESTROYING THREADS

The **pthread\_cancel()** function requests that thread be canceled. The target threads cancelability state and type determines when the cancellation takes effect.

```
int pthread_cancel(pthread_t thread);
```

# CREATING AND DESTROYING THREADS

You should plan to collect the exit status of all the threads you create by calling **pthread\_join()** on each thread eventually. The **pthread\_join()** function suspends execution of the calling thread until the target thread terminates, unless the target thread has already terminated.

```
int pthread_join(pthread_t thread, void **value_ptr);
```

# CREATING AND DESTROYING THREADS

```
#include <pthread.h>

void * thread_function ( void * arg ) {
    int * incoming = ( int *) arg;
    // Do whatever is necessary using * incoming as the argument.
    return NULL;
}

int main ( void ) {
    pthread_t thread_ID;
    void * exit_status;
    int value = 42;
    pthread_create (&thread_ID , NULL, thread_function , &value );
    pthread_join ( thread_ID , &exit_status );
    return 0;
}
```

# RETURNING RESULTS FROM THREADS

```
void * thread_function ( void ) {  
    char * buffer = ( char *) malloc ( 64 );  
    // Fill up the buffer with something good.  
    return buffer;  
}
```

```
void * exit_status;  
pthread_join ( thread_ID, &exit_status );  
char * thread_result;  
thread_result = ( char * ) exit_status;  
printf ( "I got %s back from the thread .\n" , thread_result );  
free ( exit_status );
```

# THREAD SYNCHRONIZATION

The idea is to associate a **mutex** with each shared data object and then require every thread that wishes to use the shared data object to first lock the **mutex** before doing so.

1. Declare an object of type **pthread\_mutex\_t**.
2. Initialize the object by calling **pthread\_mutex\_init()**.
3. Call **pthread\_mutex\_lock()** to gain exclusive access to the shared data object.
4. Call **pthread\_mutex\_unlock()** to release the exclusive access and allow another thread to use the shared data object.
5. Get rid of the object by calling **pthread\_mutex\_destroy()**.

# THREAD SYNCHRONIZATION

```
#include <pthread.h>
#include <unistd.h>
pthread_mutex_t lock;
int shared_data = 0;

void * thread_function ( void * arg ) {
    int i;
    for ( i = 0 ; i < 10241024; ++i ) {
        // Access the shared data here.
        pthread_mutex_lock(&lock);
        shared_data++;
        pthread_mutex_unlock(&lock);
    }
    return NULL;
}
```



# THREAD SYNCHRONIZATION

```
int main ( void ) {  
    pthread_t thread_ID;  
    void * exit_status;  
    int i;  
    // Initialize the mutex before trying to use it.  
    pthread_mutex_init (&lock, NULL);  
    pthread_create (&thread_ID, NULL, thread_function, NULL);  
    // Try to use the shared data.  
    for ( i = 0 ; i < 10 ; ++i ) {  
        sleep ( 1 );  
        pthread_mutex_lock(&lock );  
        printf ( "rShared integer's value = %d\n" , shared_data );  
        pthread_mutex_unlock(&lock );  
    }  
    pthread_join ( thread_ID, &exit_status );  
    // Clean up the mutex when we are finished with it.  
    pthread_mutex_destroy(&lock );  
    return 0 ;  
}
```

# THREAD SYNCHRONIZATION

1. No thread should attempt to lock or unlock a **mutex** that has not been initialized.
2. The thread that locks a **mutex** must be the thread that unlocks it.
3. No thread should have the **mutex** locked when you destroy the **mutex**.
4. Any **mutex** that is initialized should eventually be destroyed, but only after any thread that uses it has either terminated or is no longer interesting in using it.

# ASSIGNMENT

Write a program that creates **10 threads**. Have each thread execute the same function and **pass each thread a unique number**.

Each thread should print “Hello, World (thread n)” five times where ‘n’ is replaced by the **thread's number**.

Use an array of **pthread\_t** objects to hold the various **thread IDs**. Be sure the program doesn't terminate **until all the threads are complete**.

Try running your program on more than one machine. Are there any differences in how it behaves?

# REFERENCES

- D. Buttlar, J. Farrell, B. Nichols, *PThreads Programming: A POSIX Standard for Better Multiprocessing*, O'Reilly Media, September 1996.
- Open Group's Online Manual for PThreads, available at <http://pubs.opengroup.org/onlinepubs/007908799/xsh/pthread.h.html>
- S. King, *pthread Examples*, University of Illinois, Lecture Notes.
- P. C. Chapin, *pthread Tutorial*, August 2008.