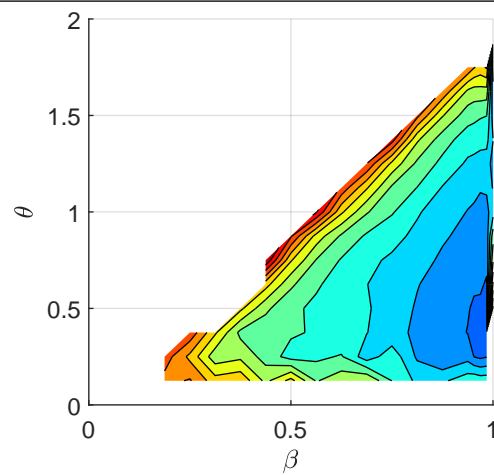
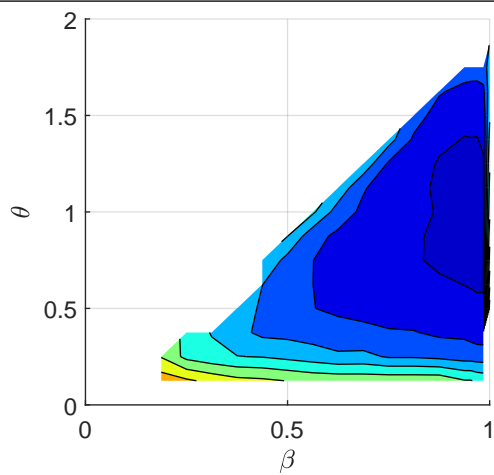
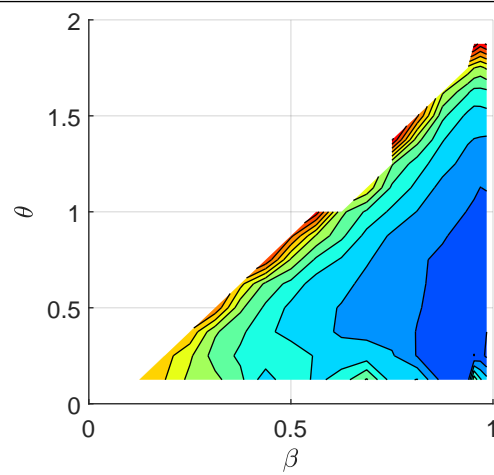
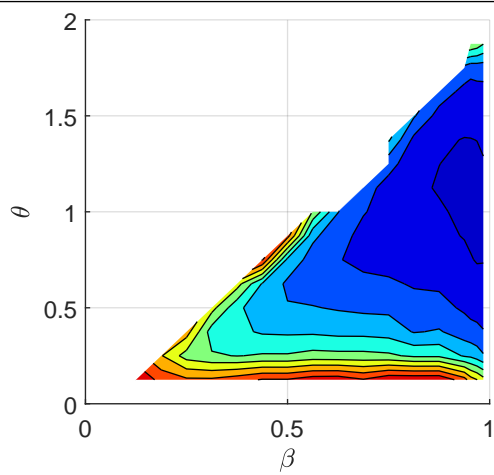


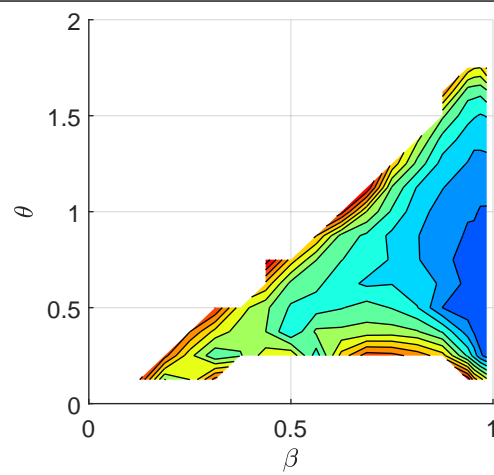
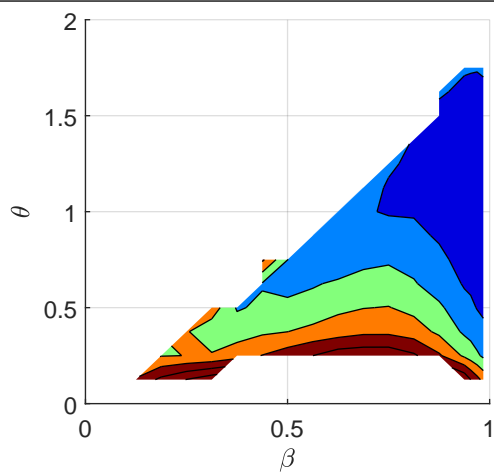
DCTLMS — White noise



DCTLMS — Pink noise



DCTLMS — UAV noise



0 0.5 1 1.5 2
Convergence time (iterations) $\times 10^4$

0 0.5 1 1.5
Residual error (RMSE) $\times 10^{-15}$