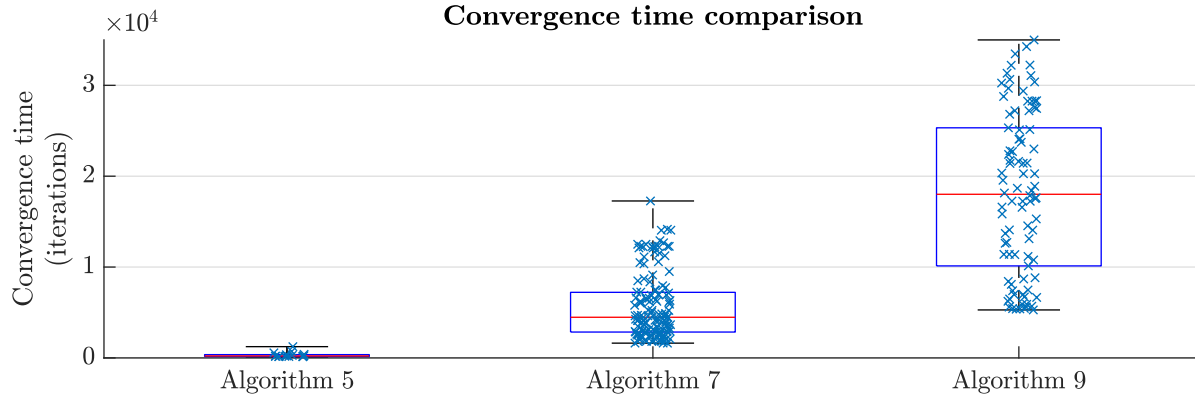
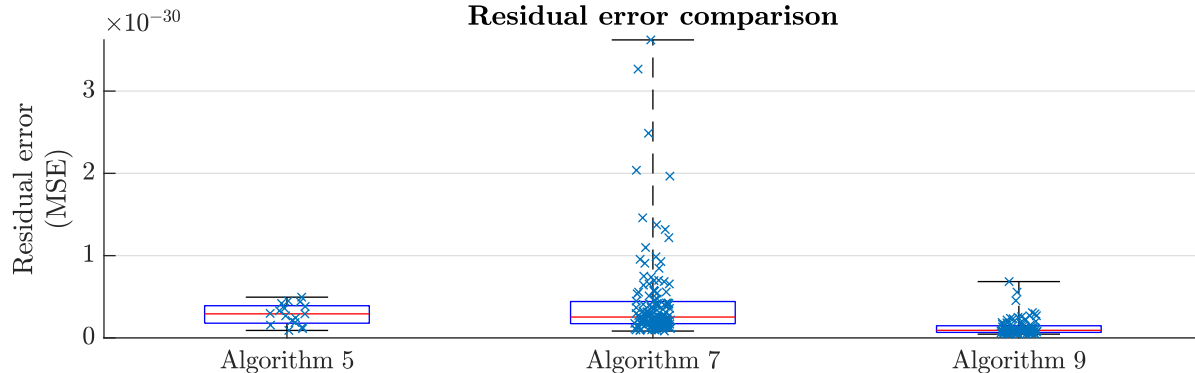


Pink noise
Convergence time comparison



Pink noise
Residual error comparison



Pink noise
Computing time comparison

