DWTLMS algorithm
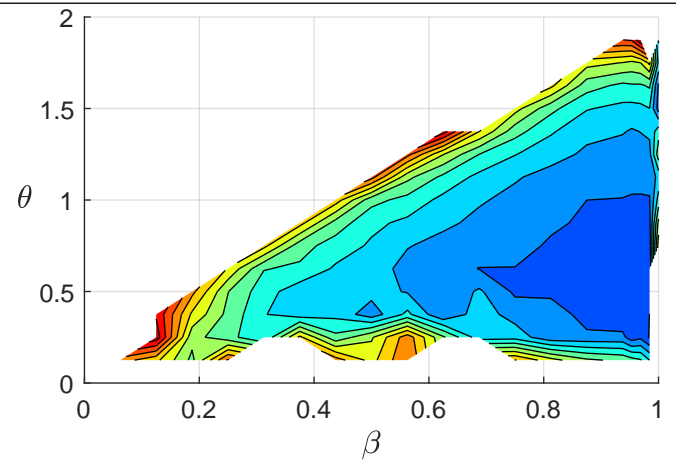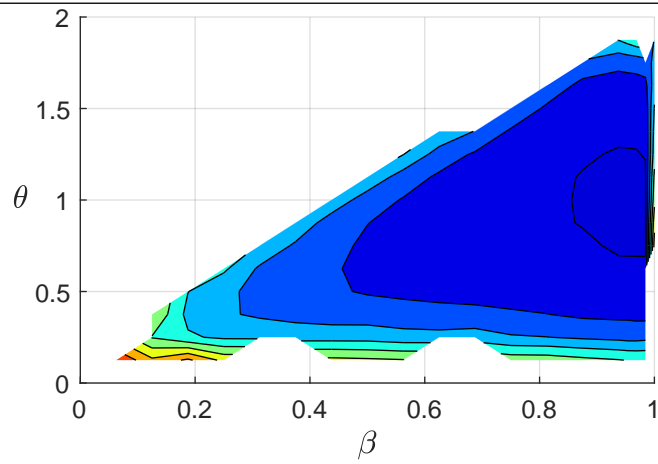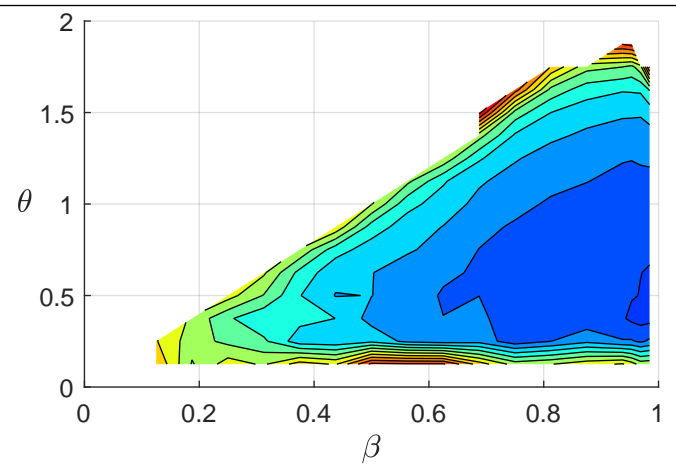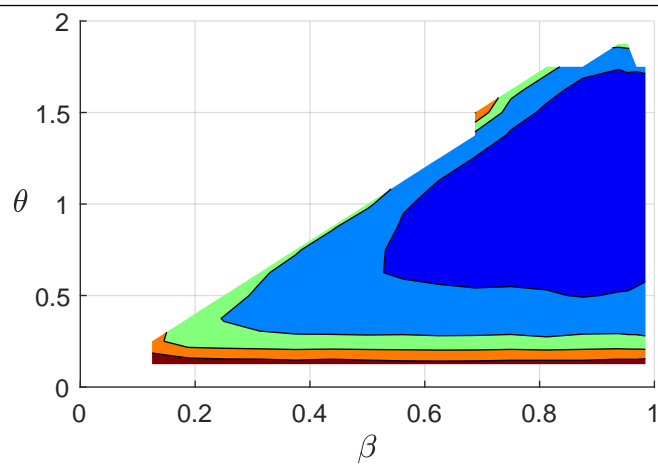
Convergence time (iterations) — Residual error (RMSE)

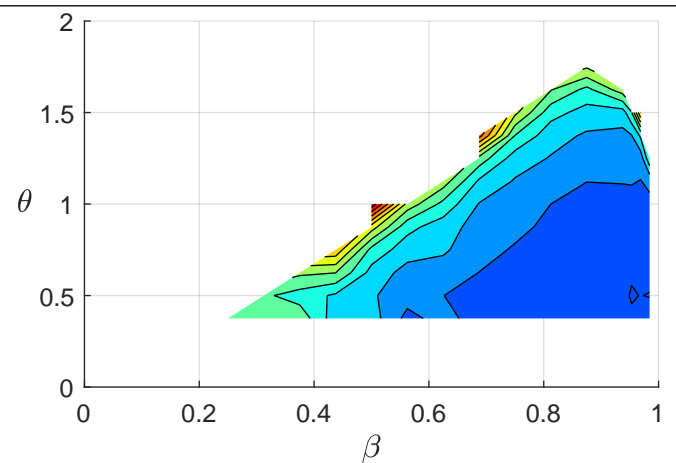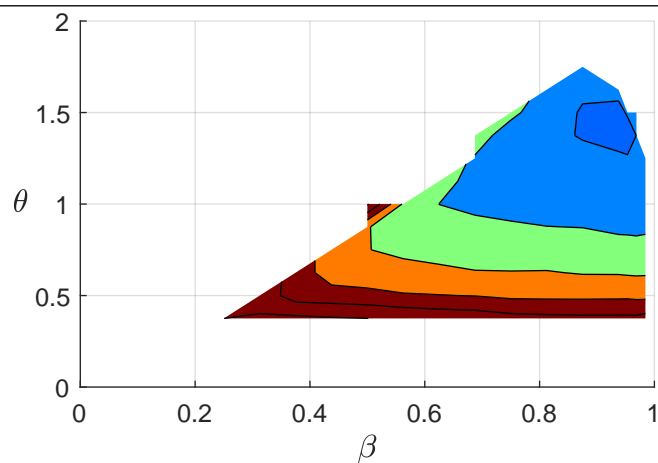White noise input signal

Pink noise input signal

UAV noise input signal