

# Processus stochastiques avec sauts sur arbre : application à l'évolution adaptative sur des phylogénies

Soutenance de thèse de Paul Bastide

19 Octobre 2017

Composition du Jury :

Elisabeth Gassiat	Professeure, <i>Université Paris Sud</i>	(Examinateuse)
Amaury Lambert	Professeur, <i>UPMC</i>	(Examinateur)
Philippe Lemey	Principal Investigator, <i>KU Leuven</i>	(Rapporteur)
Mahendra Mariadassou	Chargé de recherche, <i>INRA</i>	(Directeur de thèse)
Hélène Morlon	Chargée de recherche, <i>CNRS</i>	(Examinateuse)
Pierre Pudlo	Professeur, <i>Aix-Marseille Université</i>	(Rapporteur)
Stéphane Robin	Directeur de recherche, <i>INRA</i>	(Directeur de thèse)

# New World Monkeys

(Aristide et al., 2016)



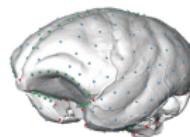
*Callithrix penicillata*

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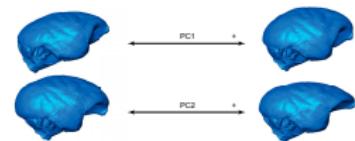
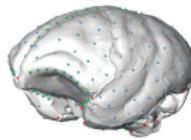


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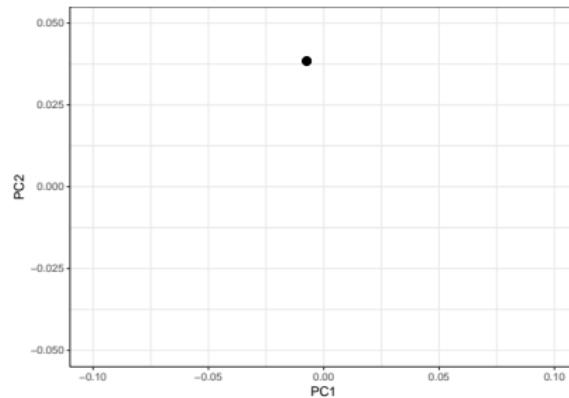


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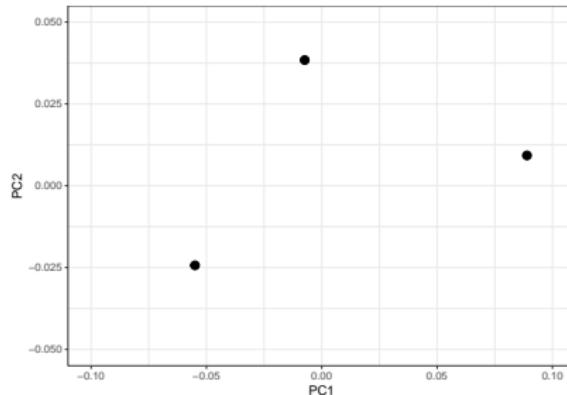


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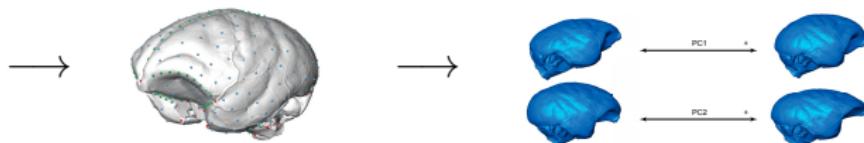
*Alouatta palliata*



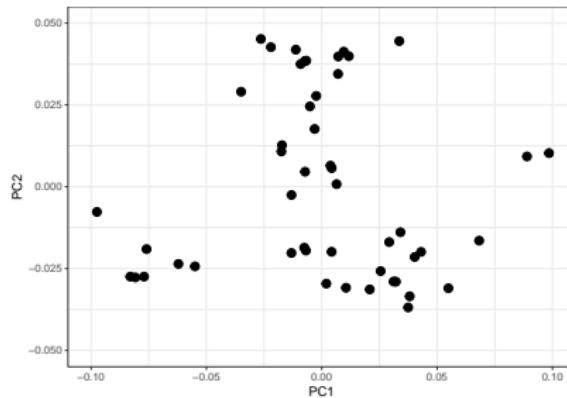
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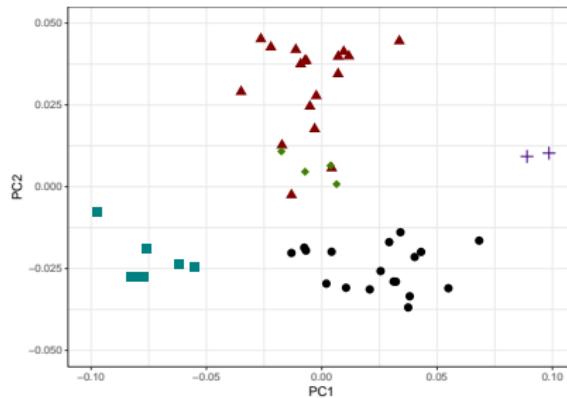
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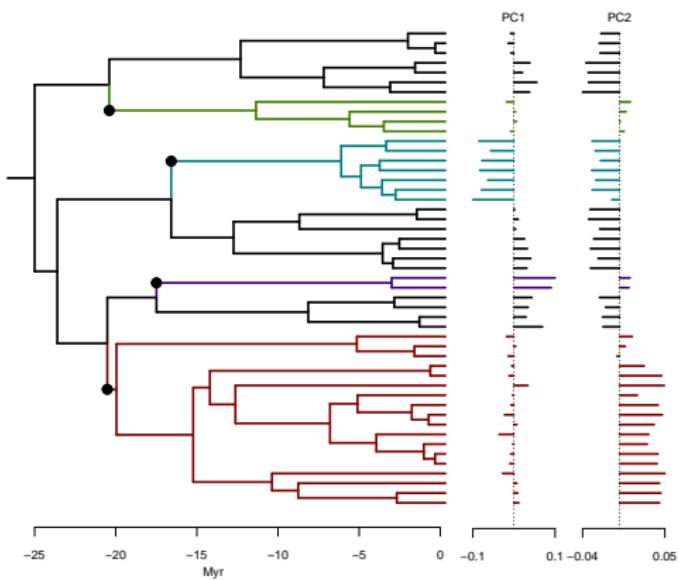
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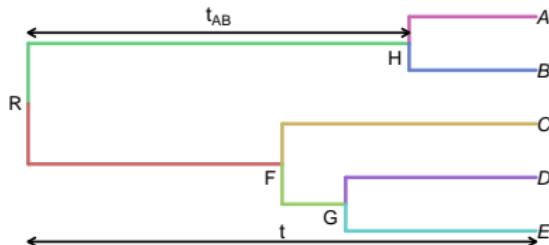
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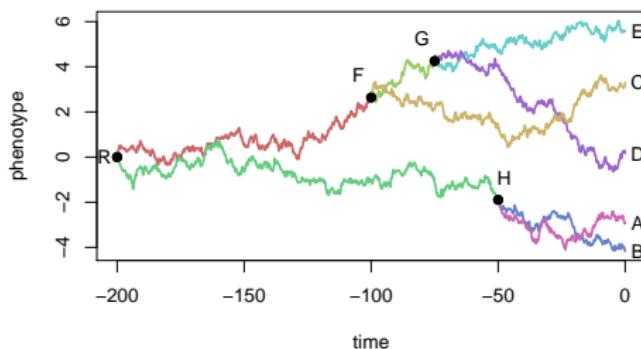
# Shifted BM on a Tree

(Felsenstein, 1985)



**Known** tree.

Only tip values observed.



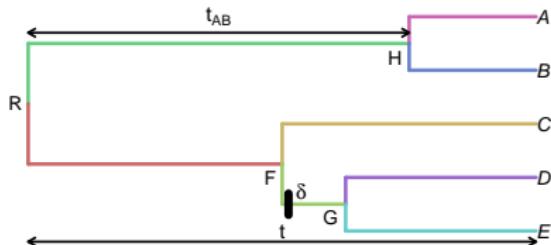
Brownian Motion:

$$\text{Var}[A | R] = \sigma^2 t$$

$$\text{Cov}[A; B | R] = \sigma^2 t_{AB}$$

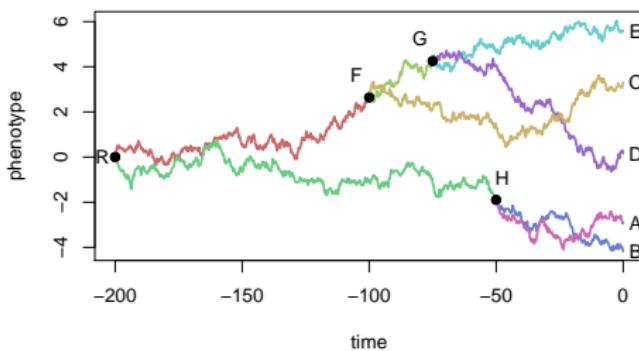
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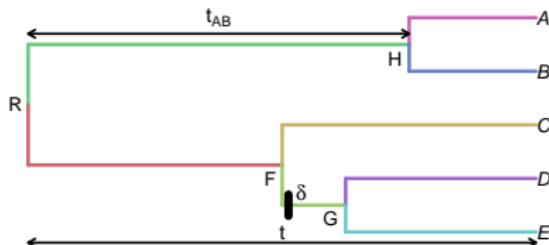
$$\text{Var}[A | R] = \sigma^2 t$$

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$$m_{\text{child}} = m_{\text{parent}} + \delta$$

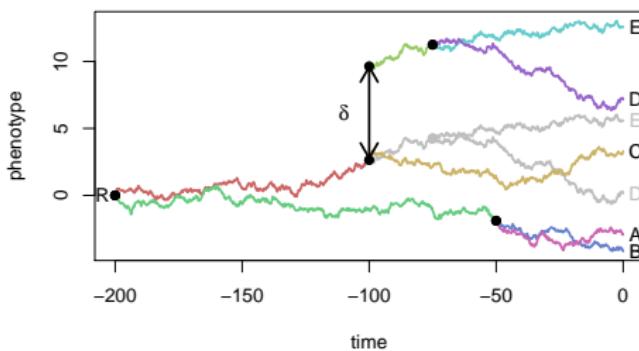
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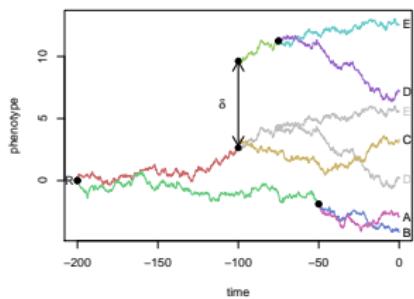
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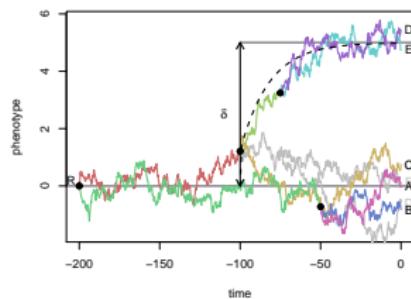
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# Outline

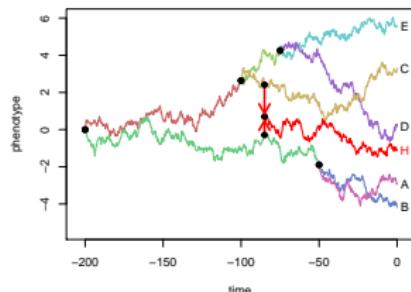
## ① Shifted BM on a Tree



## ② Shifted OU on a Tree



## ③ BM on a Network



# Outline

## ① Shifted BM on a Tree

- Identifiability
- Incomplete Data Model
- Linear Regression Model

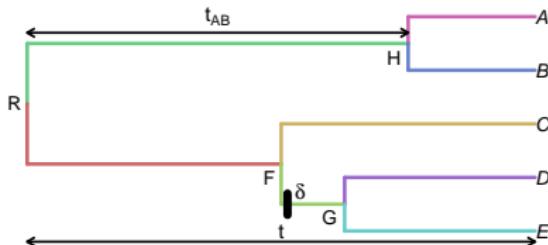
→ For univariate traits.

## ② Shifted OU on a Tree

## ③ BM on a Network

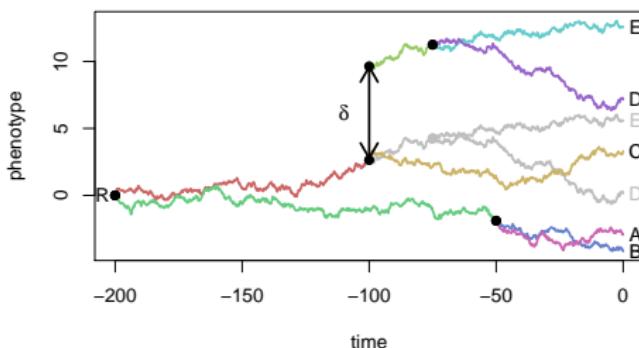
# Shifted BM on a Tree

(Felsenstein, 1985)



**Known** tree.

Only tip values observed.



Brownian Motion:

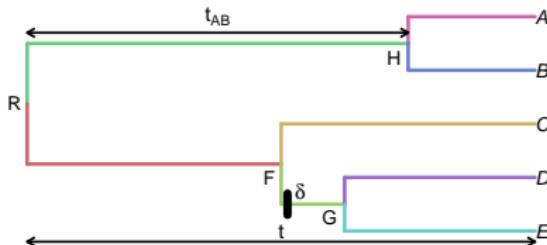
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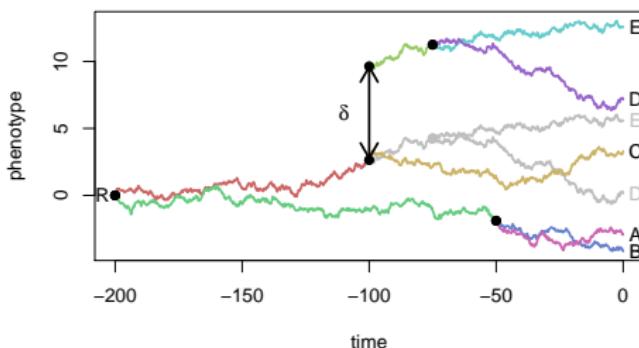
(Felsenstein, 1985)



**Known** tree.

Only tip values observed.

**Goal:** Find shifts position.



Brownian Motion:

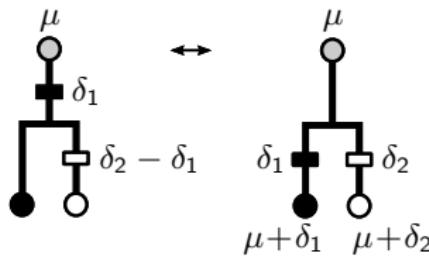
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# Equivalencies

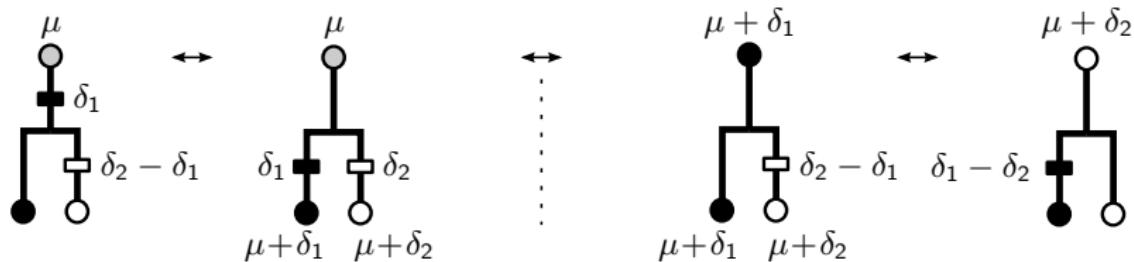
- Equivalent configurations:



- Over-parametrization: parsimonious configurations.

# Equivalencies

- Equivalent configurations:



- Over-parametrization: parsimonious configurations.

# Parsimonious Solution: Definition

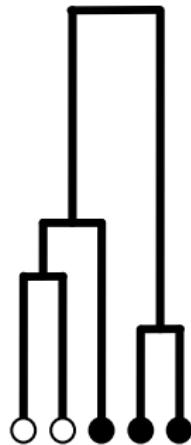
## Definition (Parsimonious Allocation)

A coloring of the tips being given, a *parsimonious* allocation of the shifts is such that it has a minimum number of shifts.

# Parsimonious Solution: Definition

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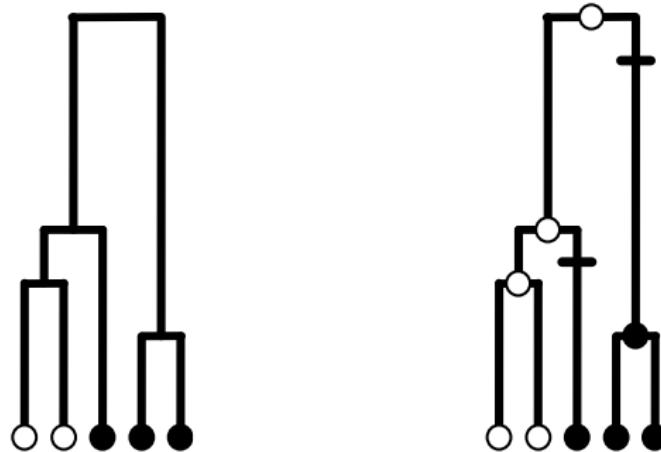
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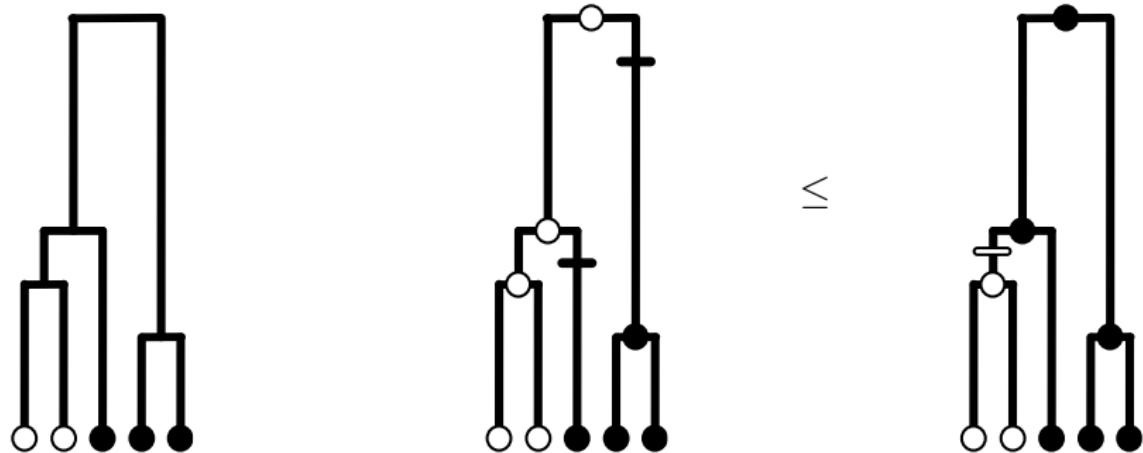
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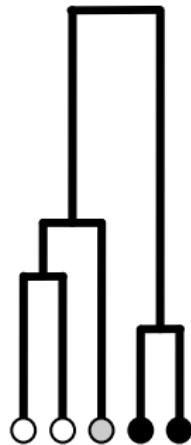
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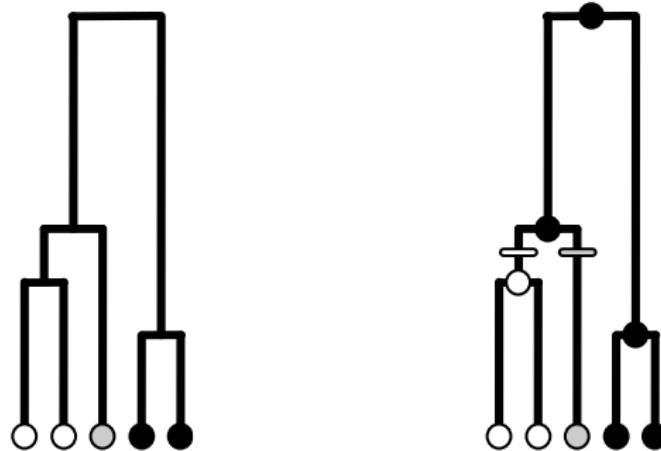
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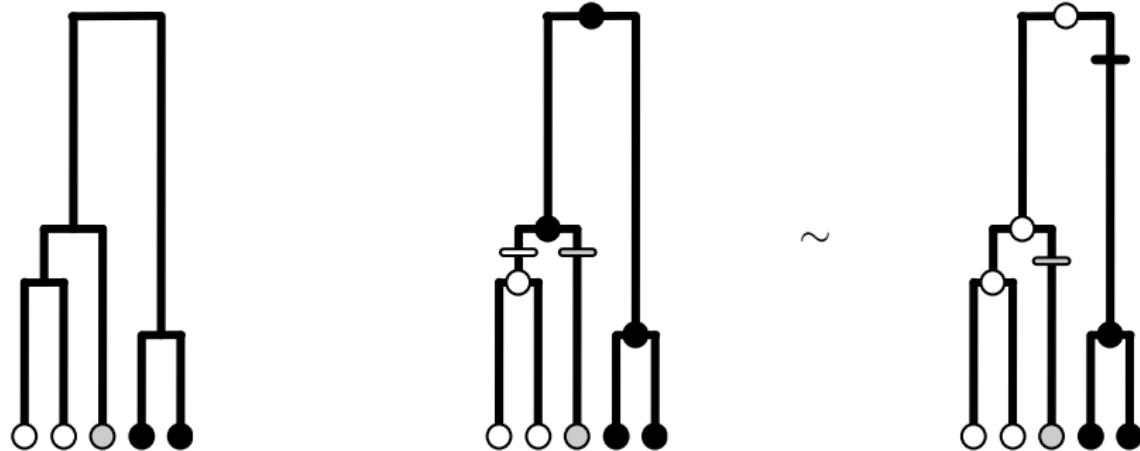
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# Parsimonious Solution: Definition

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# Equivalent Parsimonious Allocations

## Definition (Equivalency)

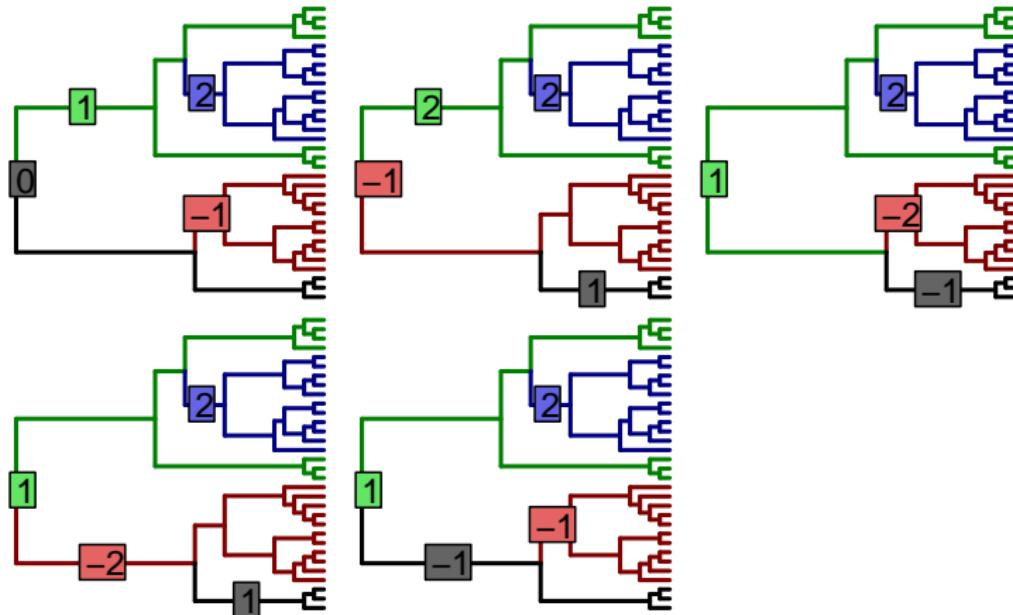
Two allocations are said to be *equivalent* (noted  $\sim$ ) if they are both parsimonious and give the same colors at the tips.

Find one solution Existing Dynamic Programming algorithms  
(Fitch, Sankoff, see Felsenstein, 2004).

Enumerate all solutions New adapted recursive algorithm  
(implemented in PhylogeneticEM).



# Equivalent Parsimonious Solutions



*Equivalent allocations and values of the shifts - BM.*

# Collection of Models

New Problem Number of Equivalence Classes:  $|\mathcal{S}_K^{PI}|$  ?

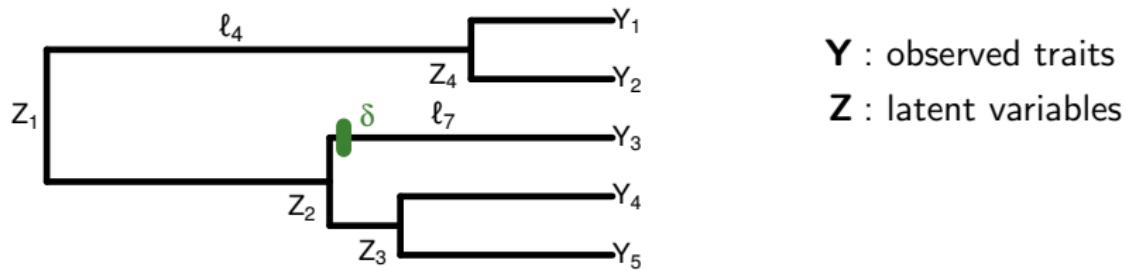
- $|\mathcal{S}_K^{PI}| \leq \binom{m+n-1}{K} = \binom{\text{\# of edges}}{\text{\# of shifts}}$
- Recursive algorithm to compute  $|\mathcal{S}_K^{PI}|$  (implemented in PhylogeneticEM).

→ Generally dependent on the topology of the tree.

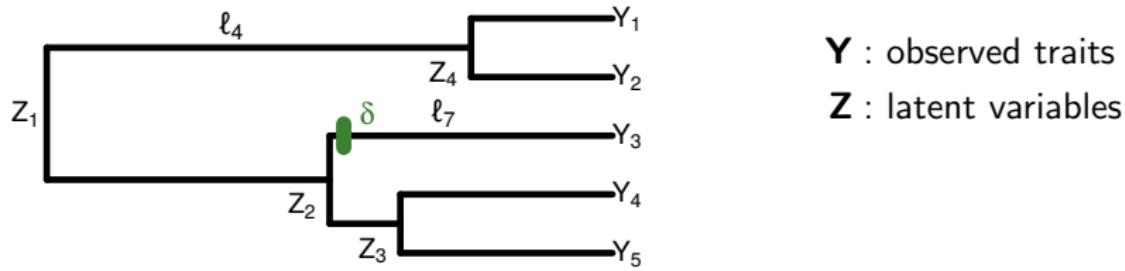
- Binary tree:  $|\mathcal{S}_K^{PI}| = \binom{2n-2-K}{K} = \binom{\text{\# of edges} - \text{\# of shifts}}{\text{\# of shifts}}$

→ See convex characters: Semple and Steel (2003)

# Incomplete Data Model

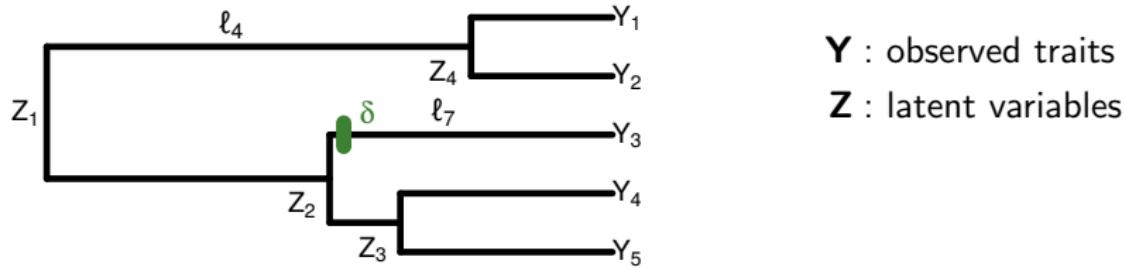


# Incomplete Data Model



$$\text{BM : } Z_4|Z_1 \sim \mathcal{N}\left(Z_1, \sigma^2 \ell_4\right)$$
$$Y_3|Z_2 \sim \mathcal{N}\left(Z_2 + \delta, \sigma^2 \ell_7\right)$$

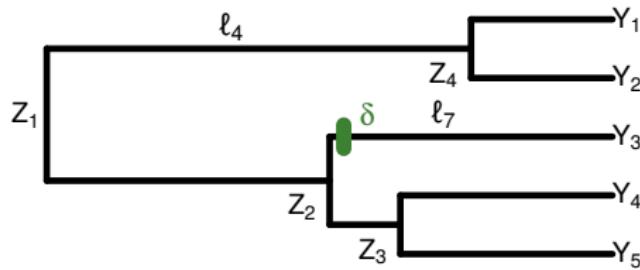
# Incomplete Data Model



$$\text{BM : } \begin{aligned} Z_4 | Z_1 &\sim \mathcal{N}\left(Z_1, \sigma^2 \ell_4\right) \\ Y_3 | Z_2 &\sim \mathcal{N}\left(Z_2 + \delta, \sigma^2 \ell_7\right) \end{aligned}$$

$$p_{\theta}(\mathbf{Z}, \mathbf{Y}) = p_{\theta}(Z_1) \prod_{1 \leq j \leq m} p_{\theta}(Z_j | Z_{\text{parent}(j)}) \prod_{1 \leq i \leq n} p_{\theta}(Y_i | Z_{\text{parent}(i)})$$

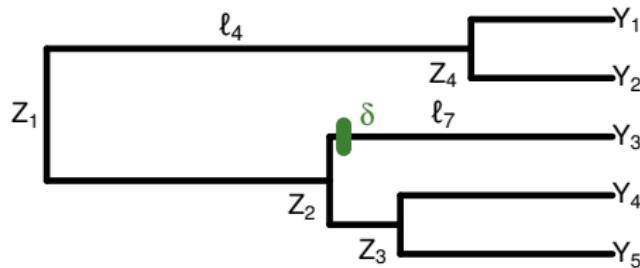
## EM Algorithm: K fixed



$$BM : \begin{aligned} Z_4 | Z_1 &\sim \mathcal{N}\left(Z_1, \sigma^2 \ell_4\right) \\ Y_3 | Z_2 &\sim \mathcal{N}\left(Z_2 + \delta, \sigma^2 \ell_7\right) \end{aligned}$$

Goal:  $\hat{\theta}_K = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmax}} p_{\hat{\theta}_\eta}(\mathbf{Y})$

## EM Algorithm: K fixed

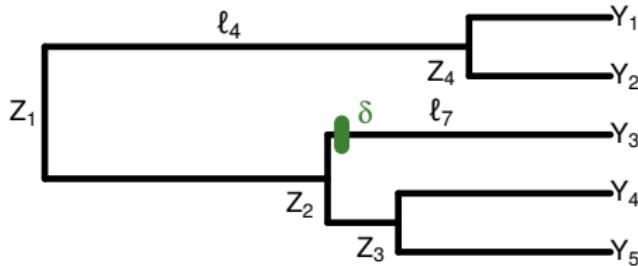


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$$\text{Goal: } \hat{\theta}_K = \underset{\eta \in S_K^{PI}}{\operatorname{argmax}} p_{\hat{\theta}_\eta}(\mathbf{Y})$$

EM Maximize  $\log p_\theta(\mathbf{Y})$  through  $\mathbb{E}_\theta[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]$ .

## EM Algorithm: K fixed



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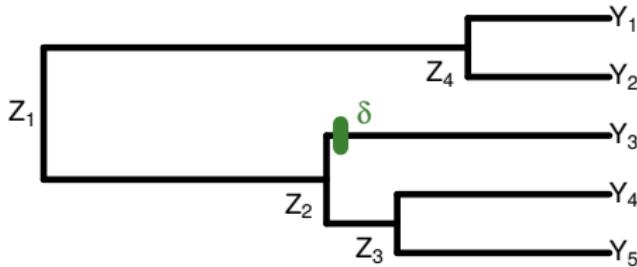
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EM Maximize  $\log p_\theta(\mathbf{Y})$  through  $\mathbb{E}_\theta[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]$ .

E step Given  $\theta^h$ , compute  $p_{\theta^h}(\mathbf{Z} | \mathbf{Y})$

M step  $\theta^{h+1} = \operatorname{argmax}_\theta \{\mathbb{E}_{\theta^h}[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]\}$

## E step



Compute the following quantities:

$$\mathbb{E}^{(h)}[Z_j | \mathbf{Y}], \text{Var}^{(h)}[Z_j | \mathbf{Y}], \text{Cov}^{(h)}[Z_j, Z_{\text{parent}(j)} | \mathbf{Y}]$$

- Gaussian properties:  $O(n^3)$ .
- Gaussian properties + Tree structure:  $O(n)$ .  
→ "Upward-Downward" algorithm.



# M Step

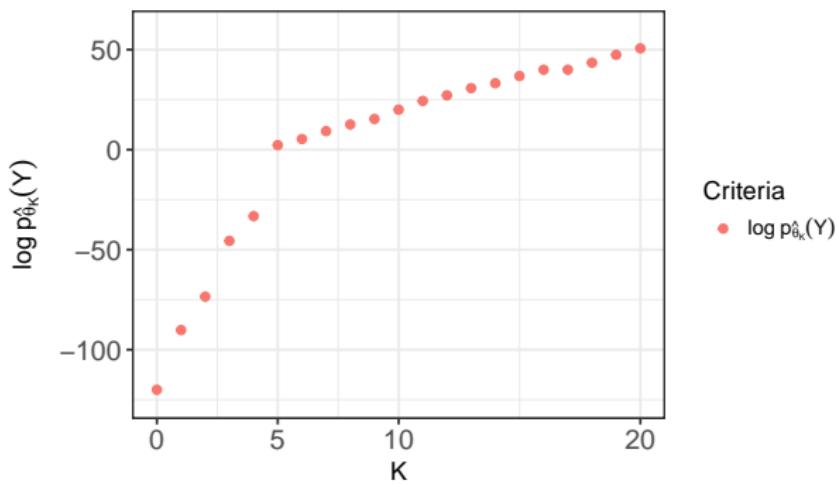
Maximize:

$$\mathbb{E} [\log p_\theta(\mathbf{Z}, \mathbf{Y}) \mid \mathbf{Y}] = - \sum_{j=2}^{m+n} C_j(\boldsymbol{\Delta}) + \mathcal{F}^{(h)}(\mu, \sigma^2)$$

- $\mu, \sigma^2$ : simple maximization
- Discrete location of  $K$  shifts
  - ↳ Exact and fast for the BM

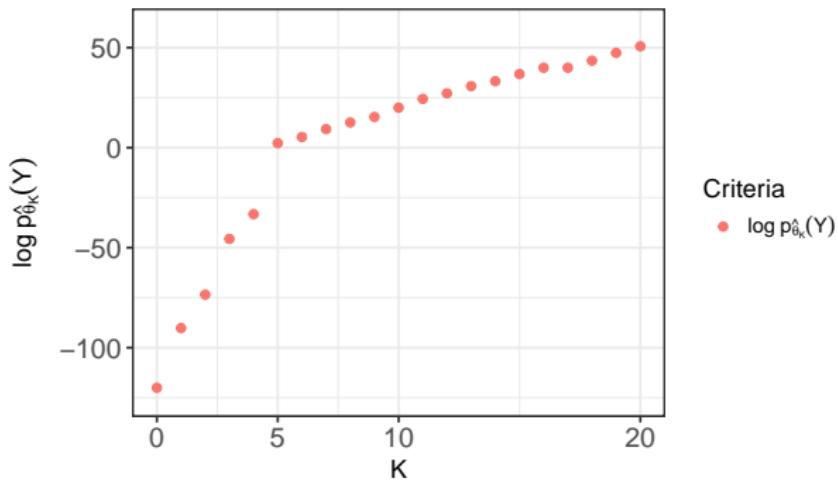


# Model Selection: Penalized Likelihood



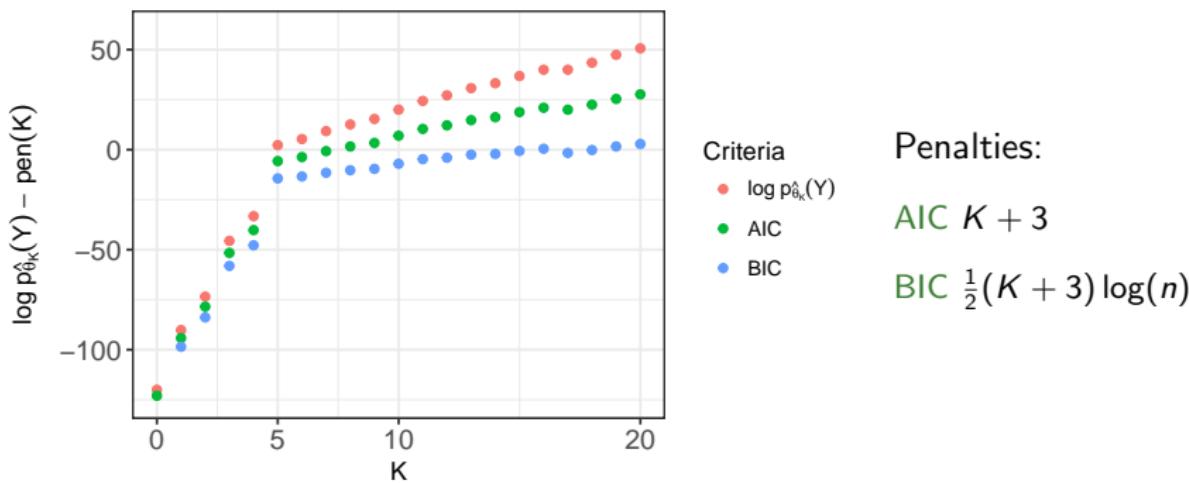
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Idea  $\hat{K} = \operatorname{argmax}_{0 \leq K \leq K_{\max}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\}$



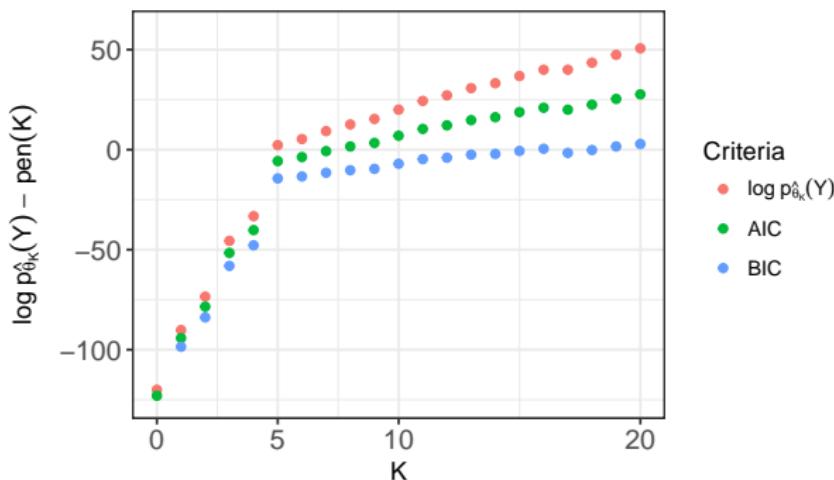
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Penalties:

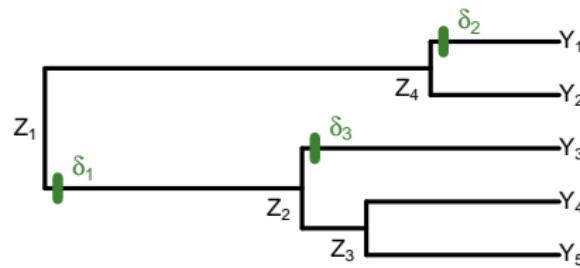
AIC  $K + 3$

BIC  $\frac{1}{2}(K + 3) \log(n)$

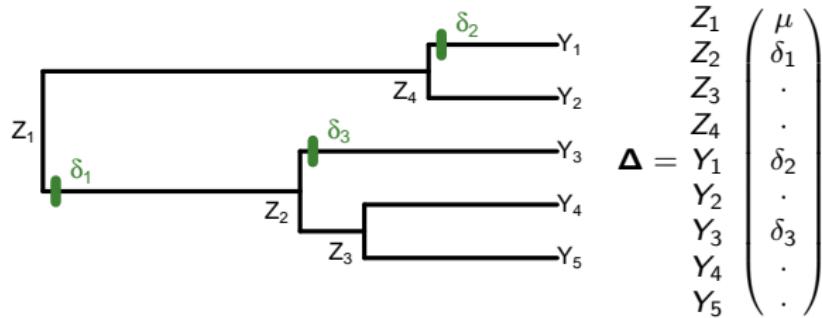
Solution

- Use  $|\mathcal{S}_K^{PI}|$ .
- Linear Regression Model.

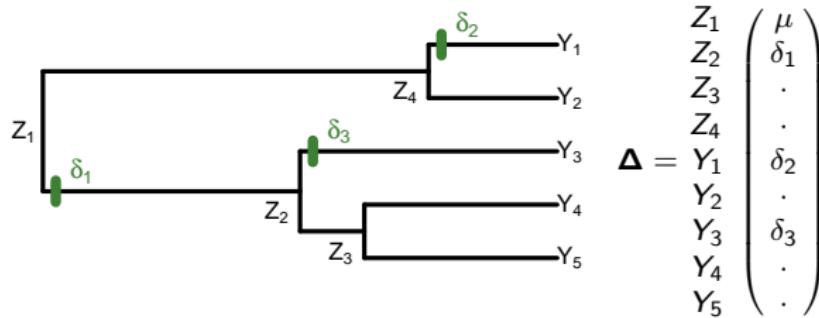
# Linear Regression Model



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$$T = \begin{pmatrix} Y_1 & Z_1 & Z_2 & Z_3 & Z_4 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 \\ Y_2 & 1 & \cdot & \cdot & 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

# Linear Regression Model

$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \delta_1 \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Y_1 & \delta_2 \\ Y_2 & \cdot \\ Y_3 & \delta_3 \\ Y_4 & \cdot \\ Y_5 & \cdot \end{pmatrix}$$
$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu + \delta_2 \\ Y_2 & \mu \\ Y_3 & \mu + \delta_1 + \delta_3 \\ Y_4 & \mu + \delta_1 \\ Y_5 & \mu + \delta_1 \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 \\ Y_1 & 1 & \cdot & \cdot & 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_3 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

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$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu + \delta_2 \\ Y_2 & \mu \\ Y_3 & \mu + \delta_1 + \delta_3 \\ Y_4 & \mu + \delta_1 \\ Y_5 & \mu + \delta_1 \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 \\ Y_1 & 1 & \cdot & \cdot & 1 & 1 & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot \\ Y_3 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_4 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

$$BM : \quad \mathbf{Y} = \mathbf{T}\Delta + \sigma \mathbf{E}^{BM}$$

$$\mathbf{E}^{BM} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$$

# Model Selection: LINselect

## Proposition (Form of the Penalty and guarantees)

Under our setting:  $\mathbf{Y} = \mathbf{T}\Delta + \sigma\mathbf{E}$  with  $E \sim \mathcal{N}(0, \mathbf{V})$ , define the penalty:

$$\text{pen}(K) = A \text{pen} \left( n, K, |\mathcal{S}_K^{PI}| \right).$$

Selecting

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmax}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\},$$

and under reasonable assumptions:

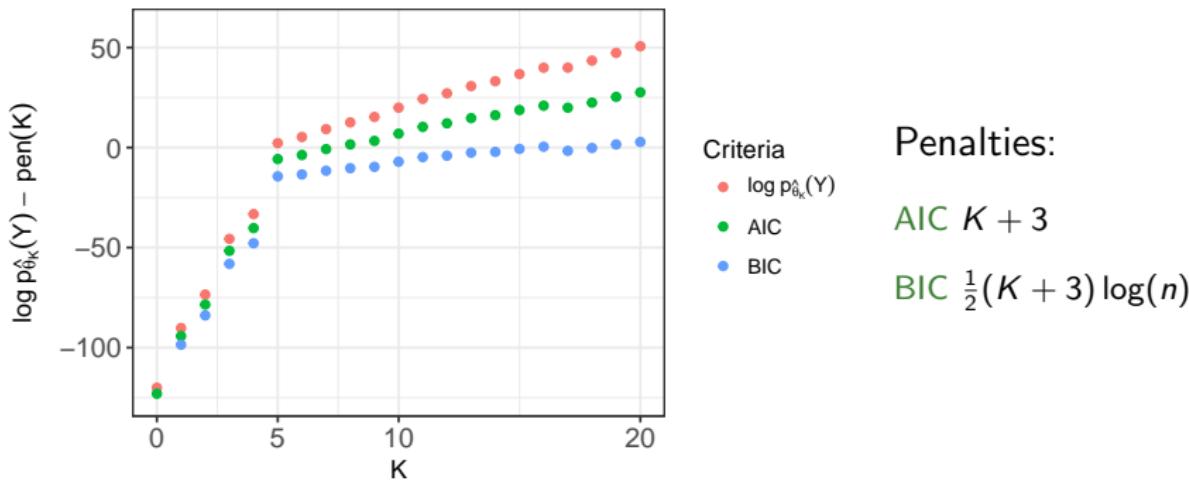
$$\mathbb{E} \left[ \frac{\|\mathbb{E}[\mathbf{Y}] - \hat{\mathbf{Y}}_{\hat{K}}\|_{\mathbf{V}^{-1}}^2}{\sigma^2} \right] \leq C(A, \kappa) \inf_{\eta \in \mathcal{M}} \left\{ \frac{\|\mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^*\|_{\mathbf{V}^{-1}}^2}{\sigma^2} + (K_{\eta} + 2)(3 + \log(n)) \right\}$$

with  $C(A)$  a constant.

Based on Baraud et al. (2009)

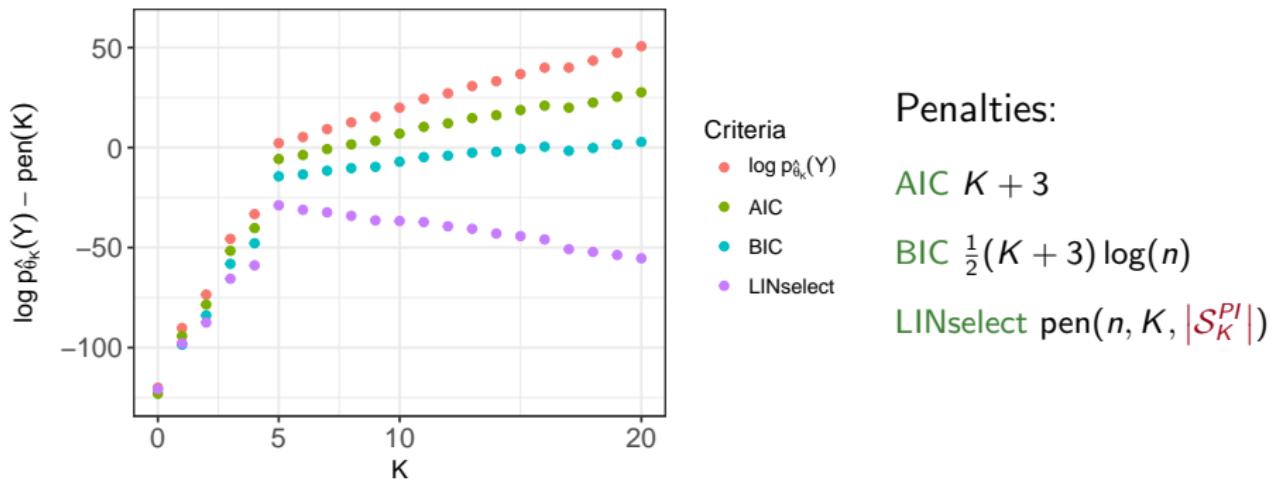
# Model Selection: Penalized Likelihood

Idea  $\hat{K} = \operatorname{argmax}_{0 \leq K \leq K_{\max}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\}$



## Model Selection: Penalized Likelihood

Idea  $\hat{K} = \operatorname{argmax}_{0 \leq K \leq K_{\max}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\}$



# Can we Deal with Georges?



We have:

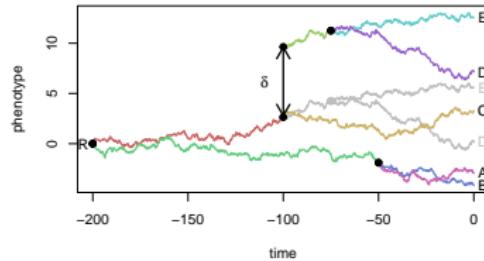
- A model of trait evolution
- A way to asses identifiability
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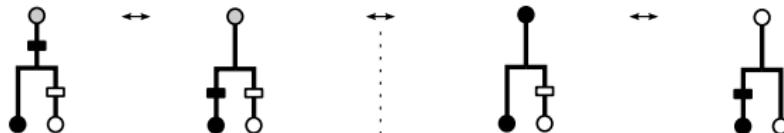


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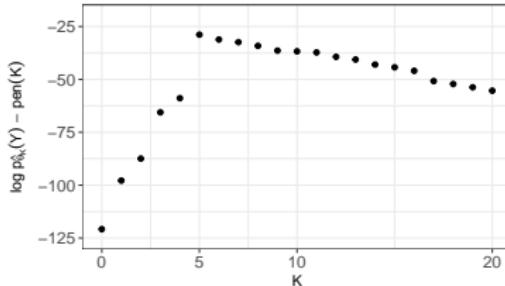


# Can we Deal with Georges?



We have:

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We have:

- A model of trait evolution
- A way to assess identifiability
- An inference strategy (EM + LINselect)

But...

- The BM is not realistic in many cases.
  - No selection.
  - Unbounded variance.

↪ Use the Ornstein-Uhlenbeck instead.

# Can we Deal with Georges?



We have:

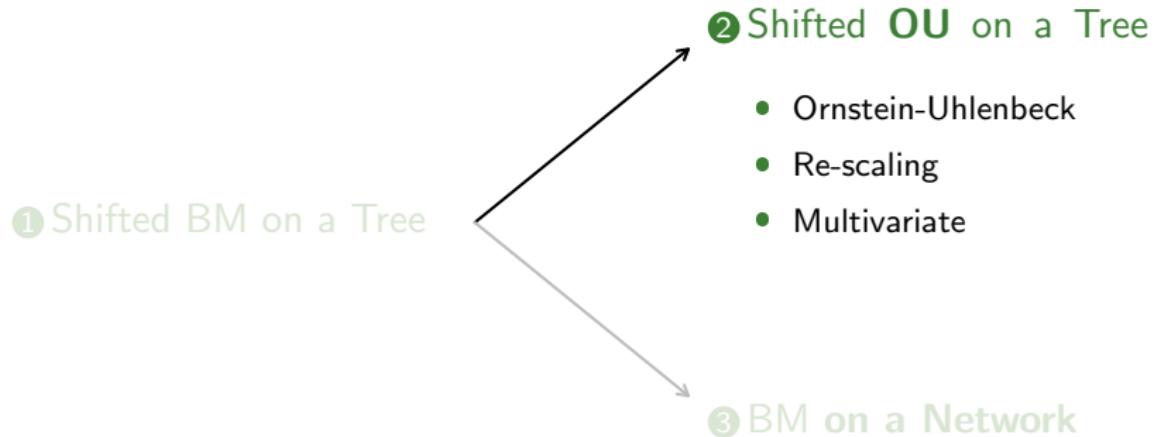
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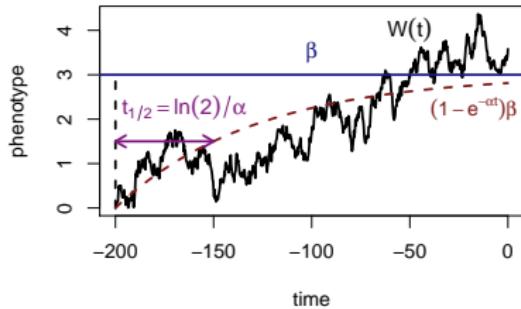
↪ Use the Ornstein-Uhlenbeck instead.

# Outline



## Ornstein-Uhlenbeck Modeling

(Hansen, 1997)



$$dW(t) = \alpha[\beta - W(t)]dt + \sigma dB(t)$$

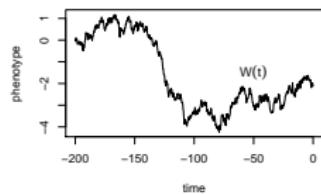
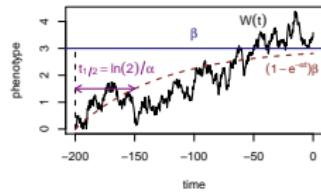
## Deterministic part:

- $\beta$ : primary optimum (mechanistically defined).
- $\ln(2)/\alpha$ : phylogenetic half live.

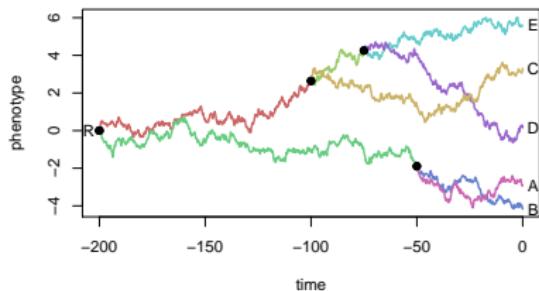
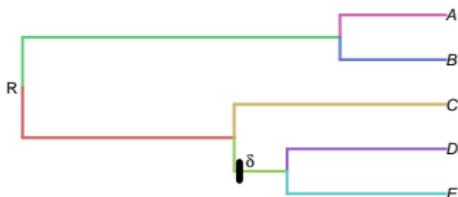
## Stochastic part:

- $W(t)$ : trait value (actual optimum).
- $\sigma dB(t)$ : Brownian fluctuations.

## BM vs OU

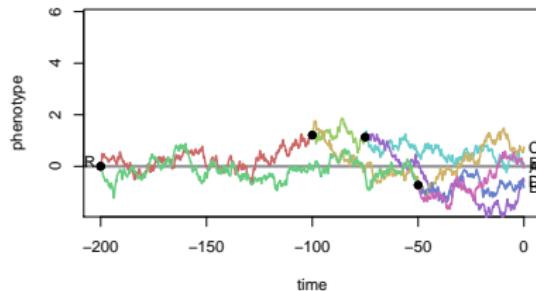
Equation	Stationary State	Variance
 <p><math>dW(t) = \sigma dB(t)</math></p>	None.	$\sigma_{ij} = \sigma^2 t_{ij}$
 <p><math>dW(t) = \sigma dB(t) + \alpha[\beta - W(t)]dt</math></p>	$\begin{cases} \mu = \beta \\ \gamma^2 = \frac{\sigma^2}{2\alpha} \end{cases}$	$\sigma_{ij} = \gamma^2 e^{-\alpha d_{ij}}$

# Shifts



**BM Shifts in the mean:**

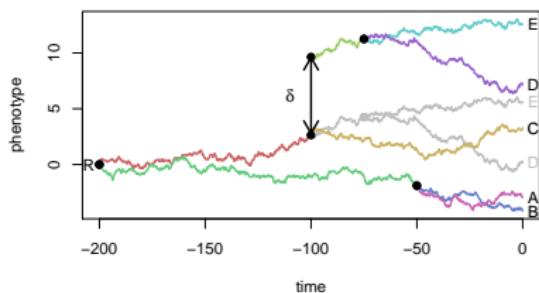
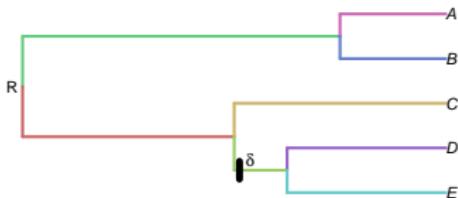
$$m_{\text{child}} = m_{\text{parent}} + \delta$$



**OU Shifts in the optimal value:**

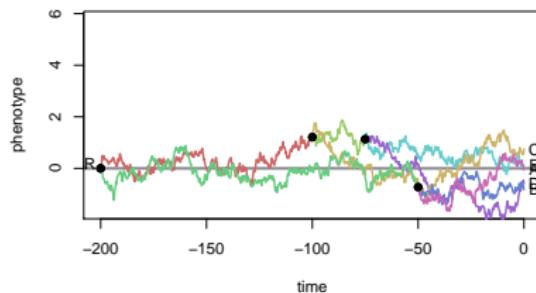
$$\beta_{\text{child}} = \beta_{\text{parent}} + \delta$$

## Shifts



**BM Shifts in the mean:**

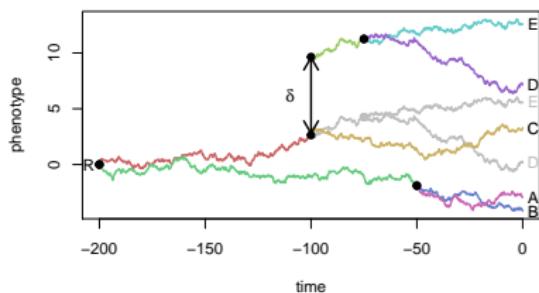
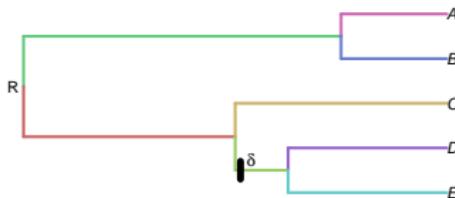
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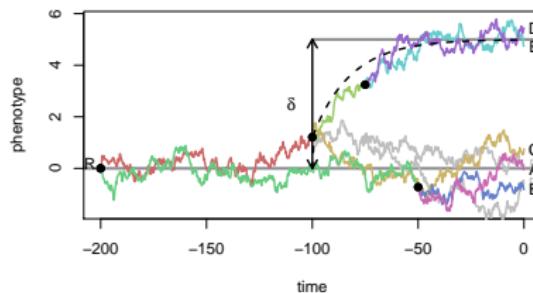
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## Shifts



BM Shifts in the mean:

$$m_{\text{child}} = m_{\text{parent}} + \delta$$

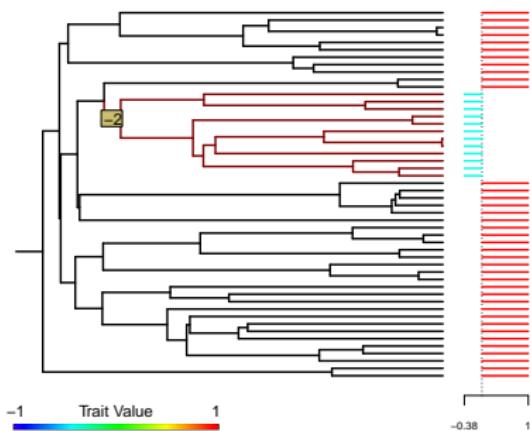


OU Shifts in the optimal value:

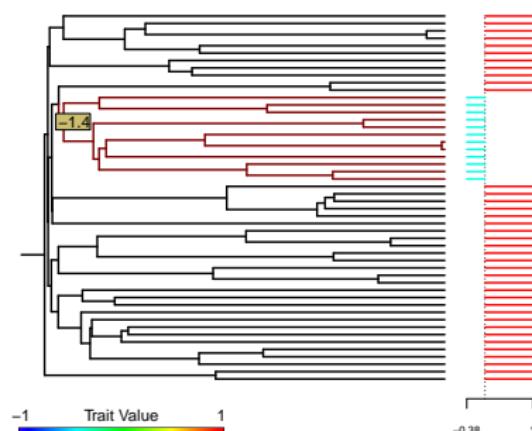
$$\beta_{\text{child}} = \beta_{\text{parent}} + \delta$$

OU  $\iff$  BM

$$\text{OU} \iff \text{BM on a re-scaled tree with } t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$$



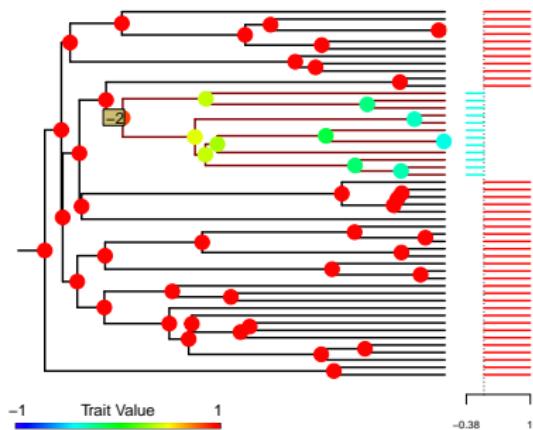
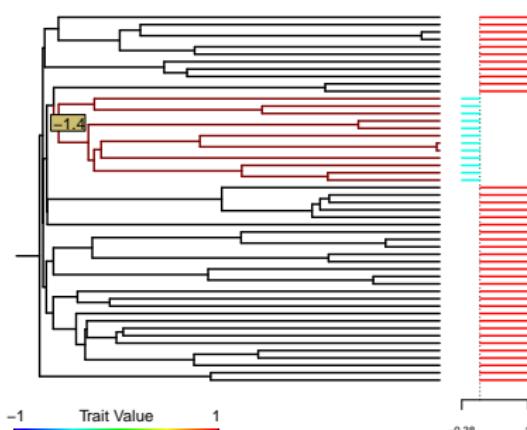
Original tree.



Re-scaled tree.

OU  $\iff$  BM

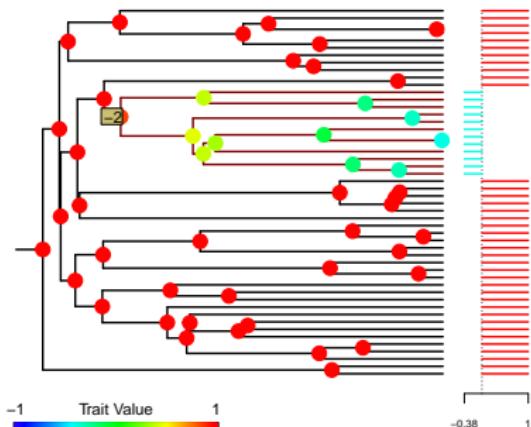
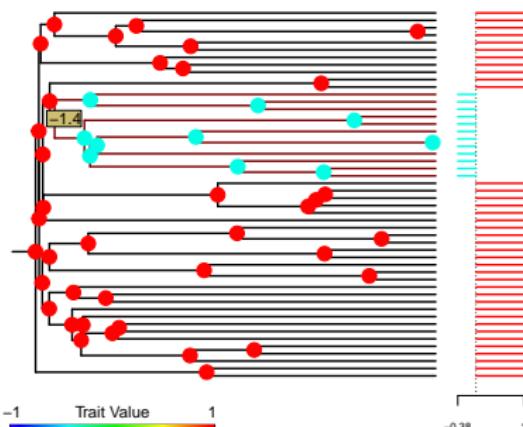
OU  $\iff$  BM on a re-scaled tree with  $t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$

OU:  $\beta_0 = \mu = 1$  and  $t_{1/2} = 0.5$ 

Re-scaled tree.

OU  $\iff$  BM

OU  $\iff$  BM on a re-scaled tree with  $t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$

OU:  $\beta_0 = \mu = 1$  and  $t_{1/2} = 0.5$ 

Re-scaled tree, equivalent BM.

OU  $\iff$  BM

$$\text{OU} \iff \text{BM on a re-scaled tree with } t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$$

### Remarks:

- This only works for an *ultrametric* tree.
- The laws of the internal nodes is changed.
- This is **not** the following standard time transformation

$$X_t = X_0 e^{-\alpha t} + \beta(1 - e^{-\alpha t}) + \frac{\sigma}{\sqrt{2\alpha}} e^{-\alpha t} B_{e^{2\alpha t} - 1}$$

to get the BM solution of the OU.

# Now, Can we Deal with Georges?



We have:

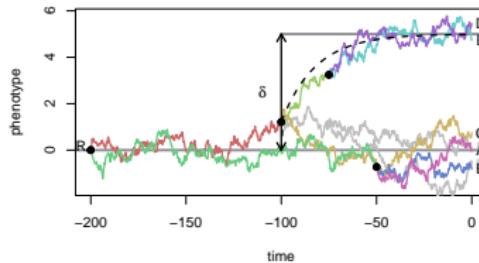
- A better model of trait evolution.
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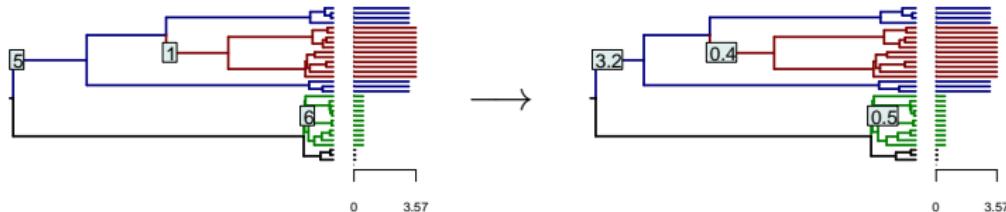


# Now, Can we Deal with Georges?



We have:

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OU Groups are means, not regimes

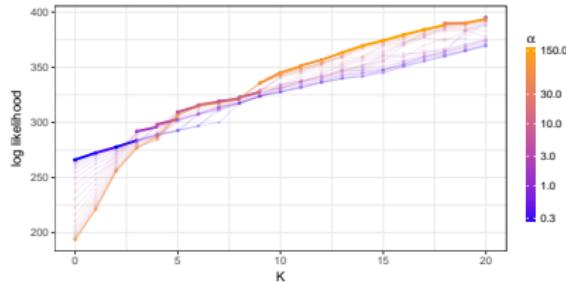
Defined from the equivalent BM

# Now, Can we Deal with Georges?



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# Now, Can we Deal with Georges?



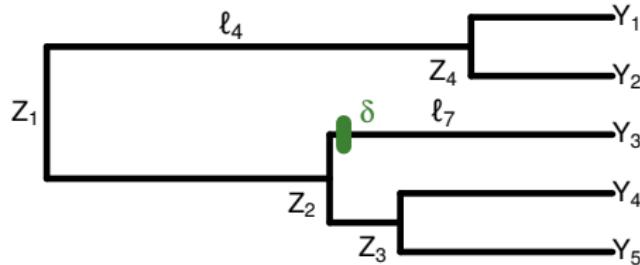
We have:

- A better model of trait evolution.
- A way to assess identifiability.
- An inference strategy (grid on  $\alpha$  + EM + LINselect).

But...

- Georges' brain is multivariate.

# Multivariate BM



Data Vectors of  $p$  traits:

$$\mathbf{Y}_i^T = (Y_{i1}, \dots, Y_{ip})$$

Shifts  $\delta$  vector size  $p$ .

→ All traits shift together.

Incomplete Data Representation

$$\mathbf{Y}_3 | \mathbf{Z}_2 \sim \mathcal{N}(\mathbf{Z}_2 + \delta, \ell_7 \mathbf{R})$$

Linear Model Representation

$$\mathbf{Y} = \mathbf{T}\Delta + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{MN}_{n \times p}(\mathbf{0}, \mathbf{V}, \mathbf{R})$$

# Multivariate OU

$$\text{SDE} \quad d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \boldsymbol{\beta}(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

Good Case  $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  must commute

- $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  diagonal  $\rightarrow$  independent traits
  - $\rightarrow$  Brownian motion with different variances and drifts
  - $\rightarrow$  independent OU processes with different scales and drifts
  - $\rightarrow$  independent BM with different variances
- $\mathbf{A} = \alpha I_p$  scalar and  $\boldsymbol{\Sigma}$  full  $\rightarrow$  scOU
  - $\rightarrow$  Brownian motion with different variances and drifts

# Multivariate OU

SDE       $d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \Sigma dB_t$

Good Case **A** and **Σ** must commute

- **A** and **Σ** diagonal → independent traits
  - Ingram and Mahler (2013); Khabbazian et al. (2016)
  - Justification: de-correlate the traits with a pPCA
  - ✗ With shifts: not justified
- **A** =  $\alpha I_p$  scalar and **Σ** full → scOU
  - Same tree re-scaling trick → BM

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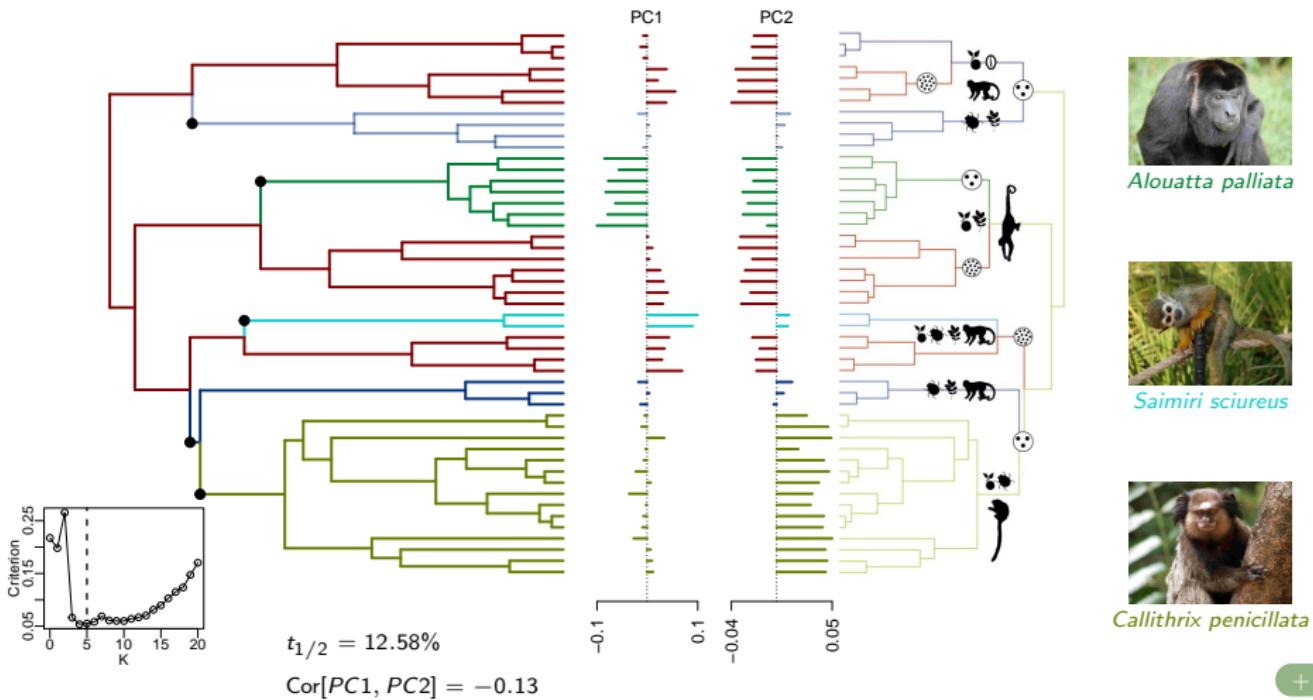
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Now we can study Georges !

# New World Monkeys

(Aristide et al., 2016)



# Contributions

## Statistical Inference, Univariate

**Bastide**, Mariadassou, Robin (2017). Detection of adaptive shifts on phylogenies by using shifted stochastic processes on a tree. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 79(4), 1067–1093.

## Multivariate

**Bastide**, Ané, Robin, Mariadassou (2017). Inference of Adaptive Shifts for Multivariate Correlated Traits. *Systematic Biology, under minor revisions*.

## R package

- PhylogeneticEM, available on the CRAN.
  - ↳ Univariate and multivariate.
  - ↳ Rcpp, continuous integration, unitary tests, online doc.
  - ↳ GitHub: <https://github.com/pbastide/PhylogeneticEM>

# What about Marcel ?

(Cui et al., 2013)



*X. Montezumae*

# What about Marcel ?

(Cui et al., 2013)



*X. Montezumae*

## Two traits

- Sword index
- Female preference

# What about Marcel ?

(Cui et al., 2013)



*X. Montezumae*

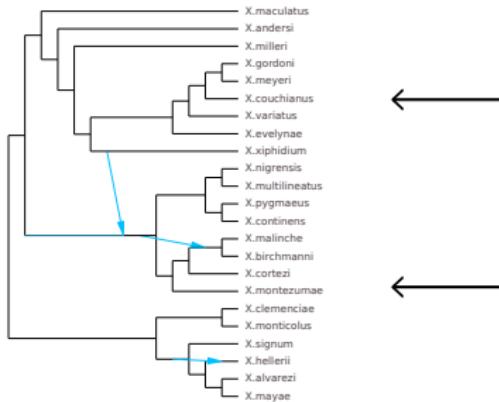
## Two traits

- Sword index
- Female preference

Problem There are hybrids !

# Phylogenetic “Networks”

(Solís-Lemus and Ané, 2016)



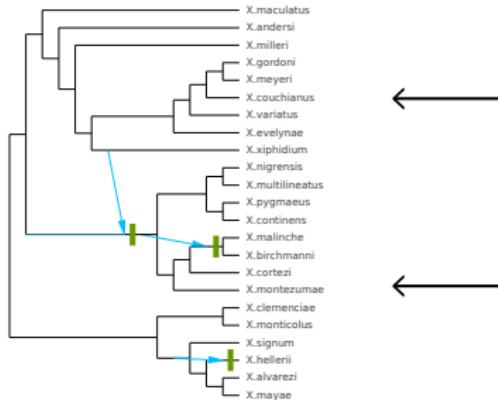
*X. Couchianus*



*X. Montezumae*

# Phylogenetic “Networks”

(Solís-Lemus and Ané, 2016)



*X. Couchianus*

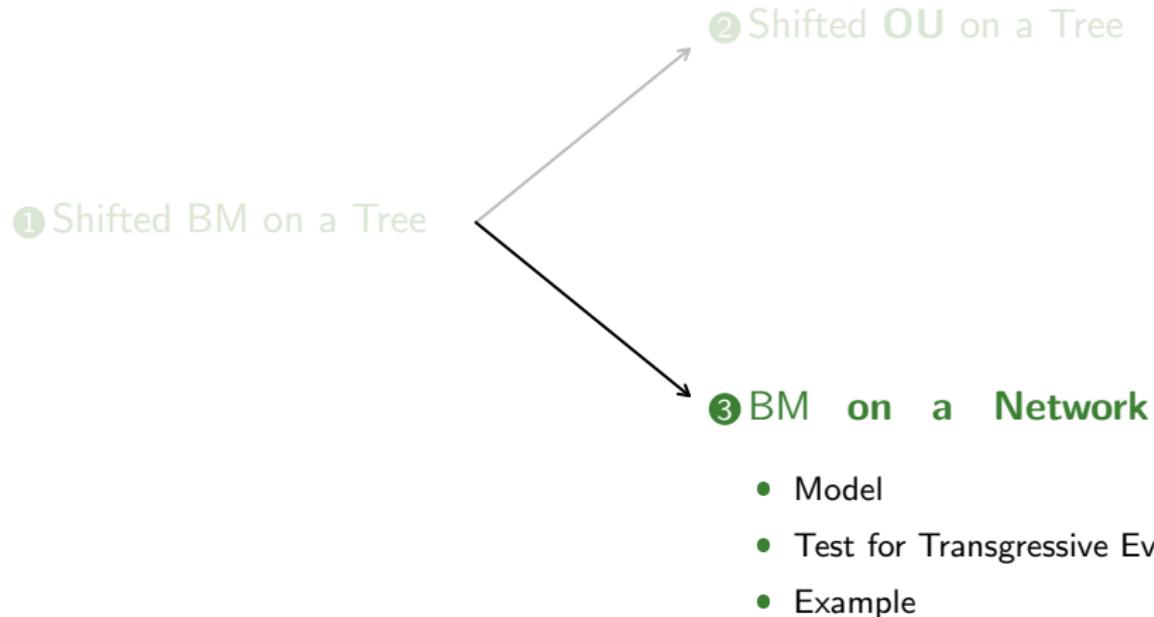


*X. Montezumae*

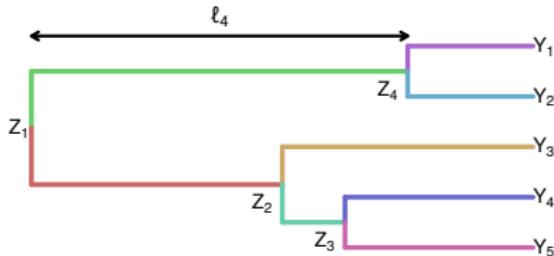
## Question:

- Can we see the effects of ancestral transgressive evolution ?

# Outline

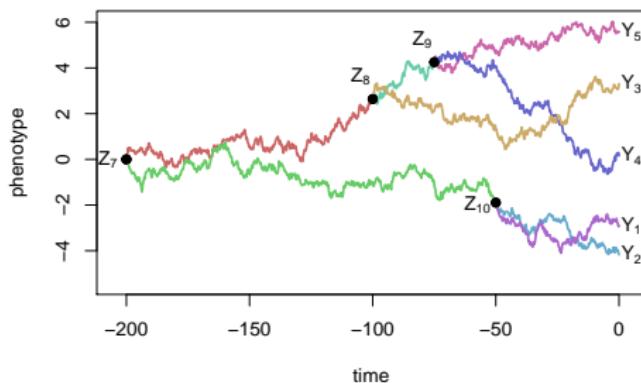


# Shifted BM on a Network



Known network.

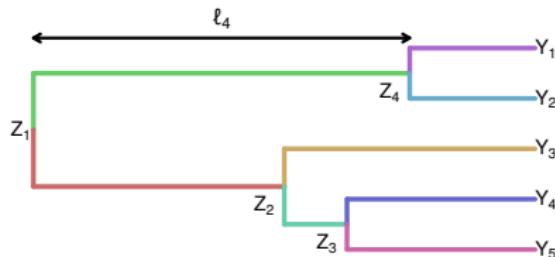
Only tip values observed.



Brownian Motion:

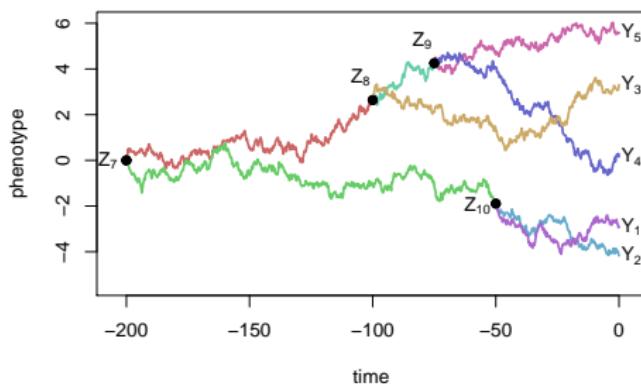
$$\text{Cov}[Y_1; Y_2] = \sigma^2 \ell_4$$

# Shifted BM on a Network



Known network.

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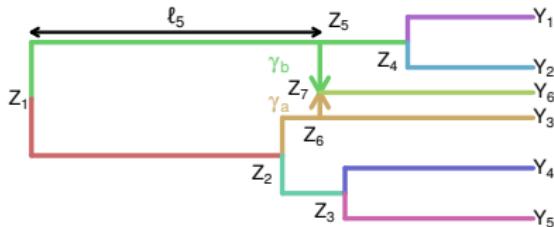


Brownian Motion:

$$V_{ij}^{\text{tree}} = \sum_{e \in p_i \cap p_j} \ell_e$$

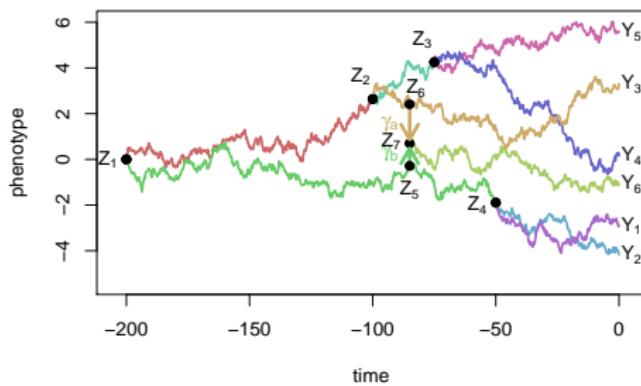
Sum over shared edges.  
 $p_i$ : path from root to tip  $i$

# Shifted BM on a Network



Known network.

Only tip values observed.

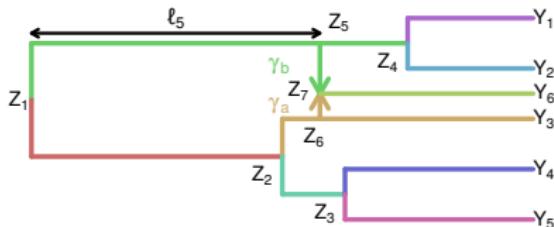


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5$$

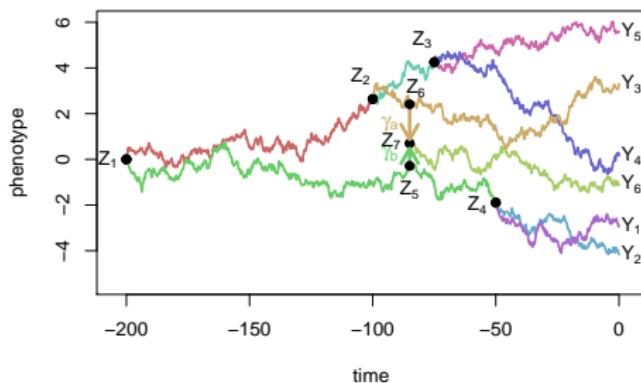
$$\gamma_a + \gamma_b = 1$$

# Shifted BM on a Network



Known network.

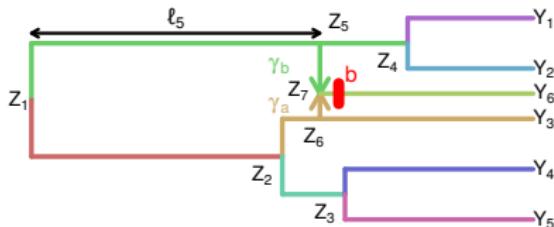
Only tip values observed.



Brownian Motion:

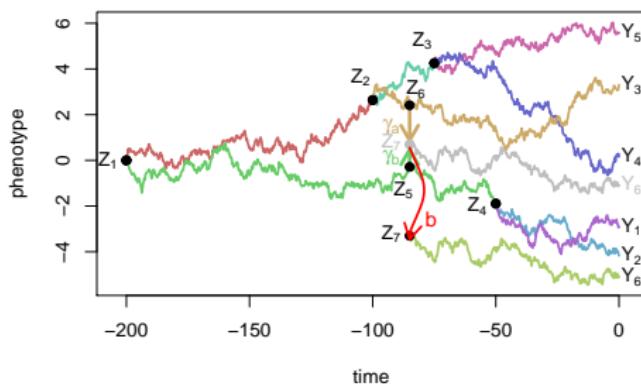
$$V_{ij}^{\text{net}} = \sum_{\substack{p_i \in \mathcal{P}_i \\ p_j \in \mathcal{P}_j}} \left( \prod_{e \in p_i} \gamma_e \right) \left( \prod_{e \in p_j} \gamma_e \right) \sum_{e \in p_i \cap p_j} \ell_e$$

# Shifted BM on a Network



Known network.

Only tip values observed.

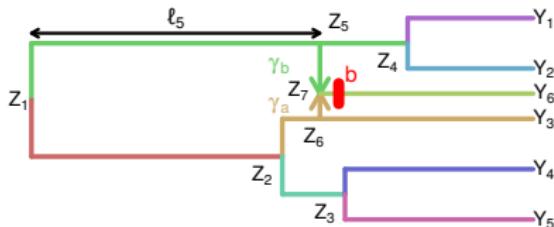


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5 + b$$

$b$  : Transgressive evolution.

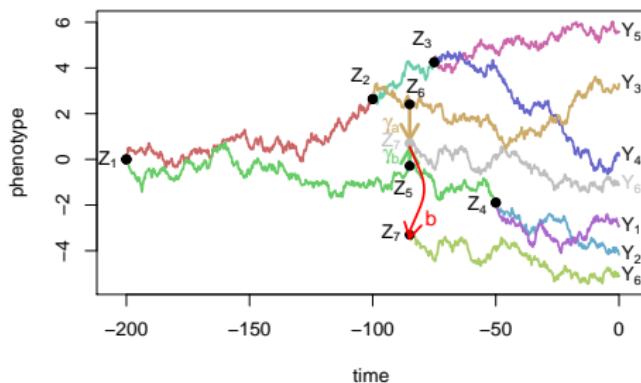
# Shifted BM on a Network



Known network.

Only tip values observed.

**Goal:** Test for transgressive evolution.

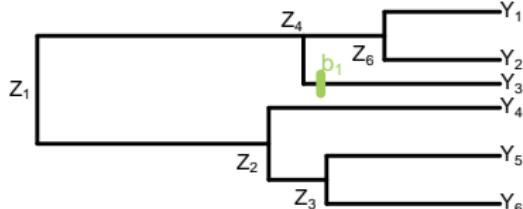


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5 + b$$

**b** : Transgressive evolution.

## Linear Regression Model

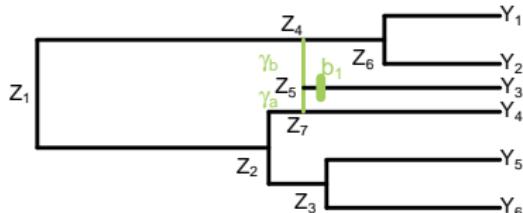


$$\Delta = \begin{pmatrix} Z_1 \\ Z_2 \\ Z_3 \\ Z_4 \\ Z_6 \\ Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \end{pmatrix} \quad T\Delta = \begin{pmatrix} Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \end{pmatrix} \begin{pmatrix} \mu \\ \mu \\ \mu + b_1 \\ \mu \\ \mu \\ \mu \end{pmatrix}$$

$$T = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_6 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \\ Y_6 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

$$\mathbf{Y} = T\Delta + \sigma \mathbf{E}^{\text{net}}$$

## Linear Regression Model



$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \cdot \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Z_5 & 0 \\ Z_6 & \cdot \\ Z_7 & \cdot \\ Y_1 & \cdot \\ Y_2 & \cdot \\ Y_3 & \cdot \\ Y_4 & \cdot \\ Y_5 & \cdot \\ Y_6 & \cdot \end{pmatrix}$$

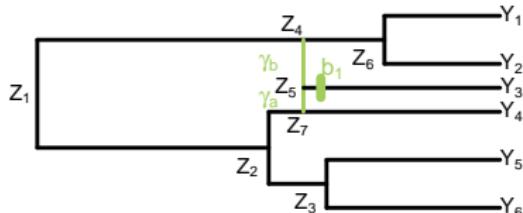
$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu \\ Y_2 & \mu \\ Y_3 & \mu + b_1 \\ Y_4 & \mu \\ Y_5 & \mu \\ Y_6 & \mu \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_5 & Z_6 & Z_7 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & \cdot & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & \gamma_b & 1 & \cdot & \gamma_a & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & 1 & \cdot \\ Y_6 & 1 & 1 & 1 & \cdot & 1 \end{pmatrix}$$

$$\mathbf{Y} = \mathbf{T}\Delta + \sigma \mathbf{E}^{\text{net}}$$

$$T_{ij} = \sum_{p \in \mathcal{P}_{j \rightarrow i}} \prod_{e \in p} \gamma_e$$

# Linear Regression Model



$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \cdot \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Z_5 & 0 \\ Z_6 & \cdot \\ Z_7 & \cdot \\ Y_1 & \cdot \\ Y_2 & \cdot \\ Y_3 & \cdot \\ Y_4 & \cdot \\ Y_5 & \cdot \\ Y_6 & \cdot \end{pmatrix}$$

$$T\Delta = \begin{pmatrix} Y_1 & \mu \\ Y_2 & \mu \\ Y_3 & \mu + b_1 \\ Y_4 & \mu \\ Y_5 & \mu \\ Y_6 & \mu \end{pmatrix}$$

$$T = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_5 & Z_6 & Z_7 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & \gamma_b & 1 & \cdot & \gamma_a & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & 1 & \cdot \\ Y_6 & 1 & 1 & 1 & \cdot & 1 \end{pmatrix}$$

$$\mathbf{Y} = \mu \mathbf{1} + \mathbf{N}\mathbf{b} + \sigma \mathbf{E}^{\text{net}}$$

$$T_{ij} = \sum_{p \in \mathcal{P}_{j \rightarrow i}} \prod_{e \in p} \gamma_e$$

# Transgressive Evolution: Testing Effect(s)

Model:

$$\mathbf{Y} = \mu \mathbf{1} + \mathbf{Nb} + \sigma^2 \mathbf{E} \quad , \quad \mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$$

- Tests:
- |   |                               |
|---|-------------------------------|
| $\mathcal{H}_0$ : No TE                         | $\mathbf{b} = \mathbf{0}$     |
| $\mathcal{H}_1$ : TE with one single effect     | $\mathbf{b} = b_1 \mathbf{1}$ |
| $\mathcal{H}_2$ : TE with heterogeneous effects | $\mathbf{b} \in \mathbb{R}^h$ |

Fisher:

$$F_{10} \sim \mathcal{F}_{1,n-2} (\Delta_{10}(b, \sigma^2))$$

$$F_{21} \sim \mathcal{F}_{h-1,n-h-1} (\Delta_{21}(\mathbf{b}, \sigma^2))$$



# Xiphophorus fishes

(Cui et al., 2013)



*X. Montezumae*

## Sword Index

No evidence for TE.

# Xiphophorus fishes

(Cui et al., 2013)



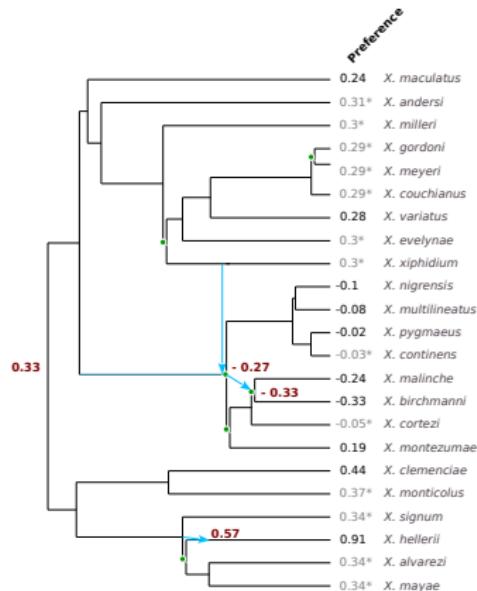
*X. Montezumae*

## Sword Index

No evidence for TE.

## Female Preference

Heterogeneous TE.



# Xiphophorus fishes

(Cui et al., 2013)



*X. Montezumae*

## Sword Index

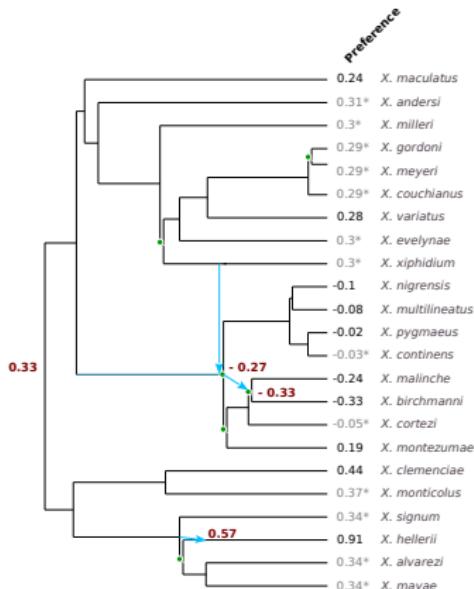
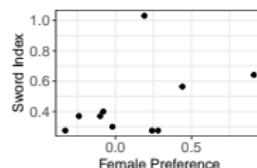
No evidence for TE.

## Female Preference

Heterogeneous TE.

## Regression

Positive correlation  
(Non-significant).



# Contributions

## Preprint

**Bastide**, Solís-Lemus, Kriebel, Sparks, Ané (submitted). Phylogenetic Comparative Methods for Phylogenetic Networks with Reticulations.

## Julia package

Solís-Lemus, **Bastide**, Ané (2017). PhyloNetworks: a package for phylogenetic networks. *Molecular Biology and Evolution*, msx235.

- Network inference and use.
- Continuous integration, unitary tests, online doc.

# Conclusion and Perspectives

A general inference framework for trait evolution models.

## Literature

- **Model:** Felsenstein (1985); Butler and King (2004).
- **Shift detection:** Ingram and Mahler (2013); Uyeda and Harmon (2014); Khabbazian et al. (2016).

## Contributions

- **Univariate:** Identifiability, EM, Model selection.
- **Multivariate:** OU with correlations.
- **Network:** Variance matrix, Transgressive Evolution.

## Perspectives

- Deal with uncertainty (data, tree).
- Non-ultrametric trees (fossils).
- Patterns in missing data.
- Go beyond BM for networks.

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- Uyeda JC, Harmon LJ. 2014. A Novel Bayesian Method for Inferring and Interpreting the Dynamics of Adaptive Landscapes from Phylogenetic Comparative Data. *Systematic Biology*. 63:902–918.

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- Braboowi at the English language Wikipedia, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=7069103> - Xiphophorus Genetic Stock Center, Texas State University, <http://www.xiphophorus.txstate.edu/resources/galleries/comprehensive.html> - "Lonesome George in profile" by Mike Weston - Flickr: Lonesome George 2. Licensed under CC BY 2.0 via Wikimedia Commons

# Contributions

## Shift Detection



- **Bastide**, Mariadassou, Robin (2017). Detection of adaptive shifts on phylogenies by using shifted stochastic processes on a tree. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 79(4), 1067–1093.
- **Bastide**, Ané, Robin, Mariadassou (2017). Inference of Adaptive Shifts for Multivariate Correlated Traits. *Systematic Biology*, *under minor revisions*.



## Networks



- **Bastide**, Solís-Lemus, Kriebel, Sparks, Ané (submitted). Phylogenetic Comparative Methods for Phylogenetic Networks with Reticulations.

## Softwares



- R package PhylogeneticEM, available on the CRAN.
- Contributions to the Julia package PhyloNetworks: Solís-Lemus, **Bastide**, Ané (2017). PhyloNetworks: a package for phylogenetic networks. *Molecular Biology and Evolution*, msx235.

# Appendices

## 4 Identifiability Issues

- Cardinal of Equivalence Classes
- Number of Tree Compatible Clustering

## 5 Inference

- Initialization
- Upward-Downward Algorithm
- Segmentation Algorithms
- Model Selection

## 6 Multivariate Modeling

- Phylogenetic PCA
- Scalar OU

## 7 Tests for Transgressive Evolution

## 8 Simulations Univariate

## 9 Simulations Multivariate

## 10 Monkey Dataset

## 11 Extensions

- Measurement Error and Factor Analysis
- Tree Misspecification
- Non-Ultrametric Trees
- Patterns in Missing Data

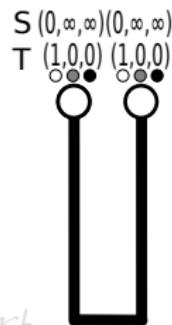
# Cardinal of Equivalence Classes

Initialization For tips  
Propagation

$$\mathcal{K}_k^l = \underset{1 \leq p \leq K}{\operatorname{argmin}} \left\{ S_{ij}(p) + \mathbb{I}\{p \neq k\} \right\}$$

$$S_i(k) = \sum_{l=1}^L S_{il}(p_l) + \mathbb{I}\{p_l \neq k\}, \quad \forall (p_1, \dots, p_L) \in \mathcal{K}_k^1 \times \dots \times \mathcal{K}_k^L$$

$$T_i(k) = \sum_{(p_1, \dots, p_L) \in \mathcal{K}_k^1 \times \dots \times \mathcal{K}_k^L} \prod_{l=1}^L T_{il}(p_l) = \prod_{l=1}^L \sum_{p_l \in \mathcal{K}_k^l} T_{il}(p_l)$$



Termination Sum on the root vector

[back](#)

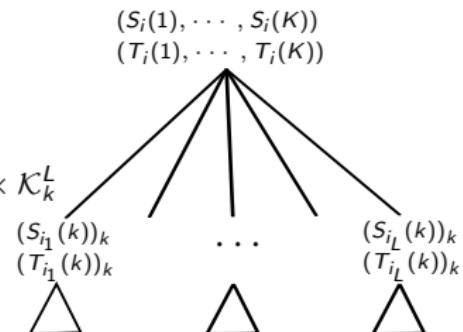
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**Termination** Sum on the root vector

[back](#)

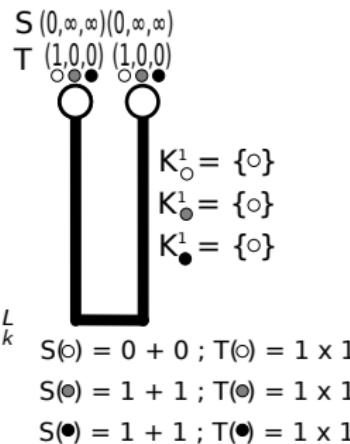
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Termination Sum on the root vector

back

# Cardinal of Equivalence Classes

**Initialization** For tips  
**Propagation**

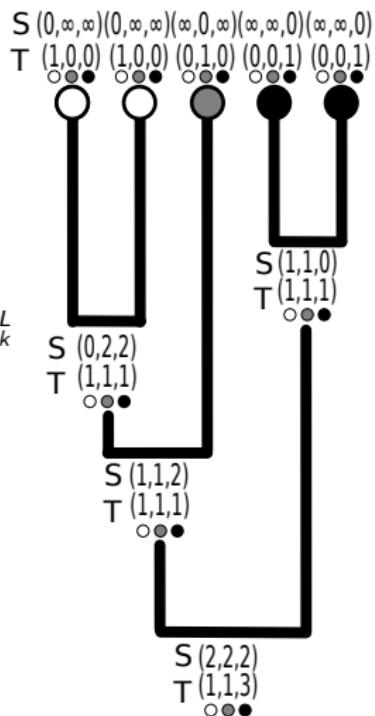
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$$T_i(k) = \sum_{(p_1, \dots, p_L) \in \mathcal{K}_k^1 \times \dots \times \mathcal{K}_k^L} \prod_{l=1}^L T_{i_l}(p_l) = \prod_{l=1}^L \sum_{p_l \in \mathcal{K}_k^l} T_{i_l}(p_l)$$

**Termination** Sum on the root vector

back



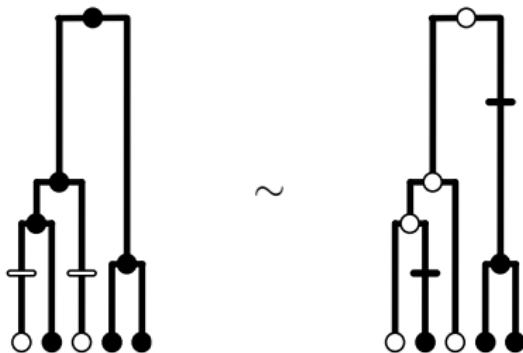
# Linking Shifts and Clustering

Assumption “No Homoplasy”: 1 shift = 1 new color

Proposition “ $K$  shifts  $\iff K + 1$  clusters”

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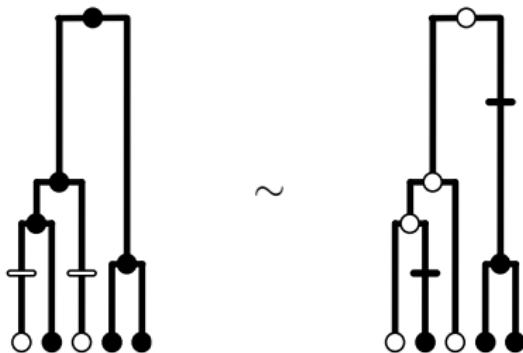


The No Homoplasy hypothesis is not respected.

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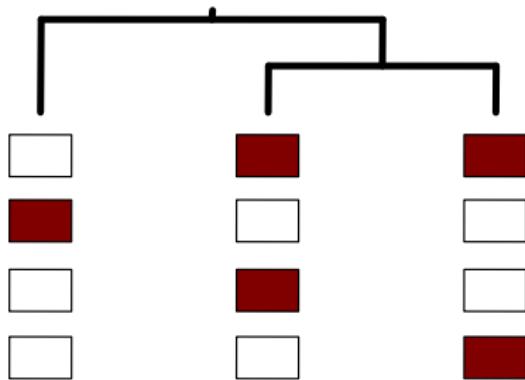


The No Homoplasy hypothesis is not respected.

Proposition “ $K$  shifts  $\iff K + 1$  clusters”

# Definitions

- $\mathcal{T}$  a rooted tree with  $n$  tips
- $N_K^{(\mathcal{T})} = |\mathcal{C}_K|$  the number of possible partitions of the tips in  $K$  clusters
- $A_K^{(\mathcal{T})}$  the number of possible *marked* partitions



Difference between  $N_2^{(\mathcal{T}_3)}$  and  $A_2^{(\mathcal{T}_3)}$ :

- $N_2^{(\mathcal{T}_3)} = 3$ : partitions 1 and 2 are equivalent
- $A_2^{(\mathcal{T}_3)} = 4$ : one marked color ("white = ancestral state")

*Partitions in two groups for a binary tree with 3 tips*

# General Formula (Binary Case)

If  $\mathcal{T}$  is a binary tree, consider  $T_\ell$  and  $T_r$  the left and right sub-trees of  $\mathcal{T}$ . Then:

$$\begin{cases} N_K^{(\mathcal{T})} = \sum_{k_1+k_2=K} N_{k_1}^{(\mathcal{T}_\ell)} N_{k_2}^{(\mathcal{T}_r)} + \sum_{k_1+k_2=K+1} A_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} \\ A_K^{(\mathcal{T})} = \sum_{k_1+k_2=K} A_{k_1}^{(\mathcal{T}_\ell)} N_{k_2}^{(\mathcal{T}_r)} + N_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} + \sum_{k_1+k_2=K+1} A_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} \end{cases}$$

We get:

$$N_{K+1}^{(\mathcal{T})} = N_{K+1}^{(n)} = \binom{2n-2-K}{K} \quad \text{and} \quad A_{K+1}^{(\mathcal{T})} = A_{K+1}^{(n)} = \binom{2n-1-K}{K}$$

# Recursion Formula (General Case)

If we are at a node defining a tree  $\mathcal{T}$  that has  $p$  daughters, with sub-trees  $\mathcal{T}_1, \dots, \mathcal{T}_p$ , then we get the following recursion formulas:

$$\left\{ \begin{array}{l} N_K^{(\mathcal{T})} = \sum_{\substack{k_1 + \dots + k_p = K \\ k_1, \dots, k_p \geq 1}} \prod_{i=1}^p N_{k_i}^{(\mathcal{T}_i)} + \sum_{\substack{I \subset [1, p] \\ |I| \geq 2}} \sum_{\substack{k_1 + \dots + k_p = K + |I| - 1 \\ k_1, \dots, k_p \geq 1}} \prod_{i \in I} A_{k_i}^{(\mathcal{T}_i)} \prod_{i \notin I} N_{k_i}^{(\mathcal{T}_i)} \\ A_K^{(\mathcal{T})} = \sum_{\substack{I \subset [1, p] \\ |I| \geq 1}} \sum_{\substack{k_1 + \dots + k_p = K + |I| - 1 \\ k_1, \dots, k_p \geq 1}} \prod_{i \in I} A_{k_i}^{(\mathcal{T}_i)} \prod_{i \notin I} N_{k_i}^{(\mathcal{T}_i)} \end{array} \right.$$

No general formula. The result depends on the topology of the tree.

back

# Initialization

Lasso regression:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y - T\Delta\|_{V^{-1}}^2 + \lambda \|\Delta\|_1 \right\}$$

For K fixed:

- Choose  $\lambda$  to get  $K$  shifts
- Estimate  $\Delta$  with a Gauss Lasso



# Cholesky Decomposition

The problem is:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y - T\Delta\|_V^2 + \lambda |\Delta|_1 \right\}$$

Cholesky decomposition of  $\Sigma_{YY}$ :

$$V = LL^T, \quad L \text{ a lower triangular matrix}$$

Then:

$$\|Y - T\Delta\|_V^2 = \|L^{-1}Y - L^{-1}T\Delta\|^2$$

And if  $Y' = L^{-1}Y$  and  $T' = L^{-1}T$ , the problem becomes:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y' - T'\Delta\|^2 + \lambda |\Delta|_1 \right\}$$

# Gauss Lasso

Let  $\hat{m}_\lambda$  be the set of selected variables (including the root). Then:

$$\hat{\Delta}^{\text{Gauss}} = \Pi_{\hat{F}_\lambda}(\mathbf{Y}') \text{ with } \hat{F}_\lambda = \text{Span}\{\mathbf{T}'_j : j \in \hat{m}_\lambda\}$$

back

# Goal and Notations

**Data** A process on a tree with the following structure:

$$\forall j > 1, \quad X_j | X_{\text{pa}(j)} \sim \mathcal{N} (m_j(X_{\text{pa}(j)}) = q_j X_{\text{pa}(j)} + r_j, \sigma_j^2)$$

$$\text{BM: } \begin{cases} q_j = 1 \\ r_j = \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k \\ \sigma_j^2 = \ell_j \sigma^2 \end{cases} \quad \text{OU: } \begin{cases} q_j = e^{-\alpha \ell_j} \\ r_j = \beta^{\text{pa}(j)} (1 - e^{-\alpha \ell_j}) + \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k (1 - e^{-\alpha(1-\nu_k) \ell_j}) \\ \sigma_j^2 = \frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha \ell_j}) \end{cases}$$

**Goal** Compute the following quantities, at every node  $j$ :

$$\mathbb{V}\text{ar}^{(h)} [Z_j | \mathbf{Y}], \mathbb{C}\text{ov}^{(h)} [Z_j, Z_{\text{pa}(j)} | \mathbf{Y}], \mathbb{E}^{(h)} [Z_j | \mathbf{Y}]$$

# Upward

**Goal** Compute for a vector of tips, given their common ancestor:

$$f_{\mathbf{Y}^j|X_j}(\mathbf{Y}^j; a) = A_j(\mathbf{Y}^j)\Phi_{M_j(\mathbf{Y}^j), S_j^2(\mathbf{Y}^j)}(a)$$

**Initialization** For tips:  $f_{Y_i|Y_i}(Y_i; a) = \Phi_{Y_i, 0}(a)$

**Propagation**

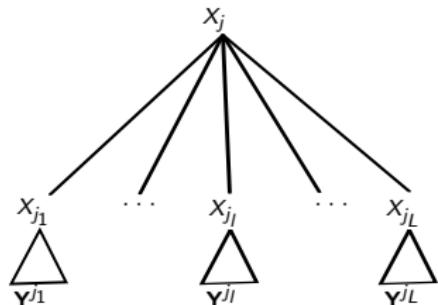
$$f_{\mathbf{Y}^j|X_j}(\mathbf{Y}^j; a) = \prod_{l=1}^L f_{\mathbf{Y}^{j_l}|X_j}(\mathbf{Y}^{j_l}; a)$$

$$f_{\mathbf{Y}^{j_l}|X_j}(\mathbf{Y}^{j_l}; a) = \int_{\mathbb{R}} f_{\mathbf{Y}^{j_l}|X_{j_l}}(\mathbf{Y}^{j_l}; b) f_{X_{j_l}|X_j}(b; a) db$$

**Root Node and Likelihood** At the root:

$$f_{X_1|\mathbf{Y}}(a; \mathbf{Y}) \propto f_{\mathbf{Y}|X_1}(\mathbf{Y}; a) f_{X_1}(a)$$

$$\left\{ \begin{array}{l} \text{Var}[X_1 | \mathbf{Y}] = \left( \frac{1}{\gamma^2} + \frac{1}{S_1^2(\mathbf{Y})} \right)^{-1} \\ \mathbb{E}[X_1 | \mathbf{Y}] = \text{Var}[X_1 | \mathbf{Y}] \left( \frac{\mu}{\gamma^2} + \frac{M_1(\mathbf{Y})}{S_1^2(\mathbf{Y})} \right) \end{array} \right.$$



# Downward

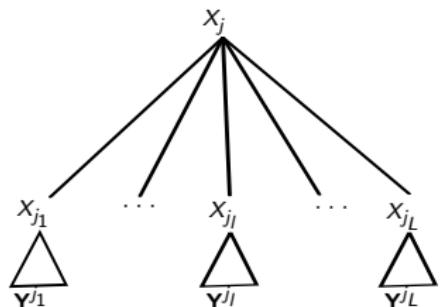
Compute  $E_j = \mathbb{E}[X_j | \mathbf{Y}]$  ,  $V_j^2 = \text{Var}[X_j | \mathbf{Y}]$  ,  $C_{j,\text{pa}(j)}^2 = \text{Cov}[X_j; X_{\text{pa}(j)} | \mathbf{Y}]$

**Initialization** Last step of Upward.

**Propagation**

$$f_{X_{\text{pa}(j)}, X_j | \mathbf{Y}}(a, b; \mathbf{Y}) = f_{X_{\text{pa}(j)} | \mathbf{Y}}(a; \mathbf{Y}) f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}}(b; a, \mathbf{Y})$$

$$\begin{aligned} f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}}(b; a, \mathbf{Y}) &= f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}^j}(b; a, \mathbf{Y}^j) \\ &\propto f_{X_j | X_{\text{pa}(j)}}(b; a) f_{\mathbf{Y}^j | X_j}(\mathbf{Y}^j; b) \end{aligned}$$



# Formulas

Upward

$$\left\{ \begin{array}{l} S_j^2(\mathbf{Y}^j) = \left( \sum_{l=1}^L \frac{q_{jl}^2}{S_{jl}^2(\mathbf{Y}^{j_l}) + \sigma_{jl}^2} \right)^{-1} \\ M_j(\mathbf{Y}^j) = S_j^2(\mathbf{Y}^j) \sum_{l=1}^L q_{jl} \frac{M_{jl}(\mathbf{Y}^{j_l}) - r_{jl}}{S_{jl}^2(\mathbf{Y}^{j_l}) + \sigma_{jl}^2} \end{array} \right.$$

Downward

$$\left\{ \begin{array}{l} C_{j,\text{pa}(j)}^2 = q_j \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} V_{\text{pa}(j)}^2 \\ E_j = \frac{S_j^2(\mathbf{Y}^j)(q_j E_{\text{pa}(j)} + r_j) + \sigma_j^2 M_j(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} \\ V_j^2 = \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} \left( \sigma_j^2 + p_j^2 \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} V_{\text{pa}(j)}^2 \right) \end{array} \right.$$

back

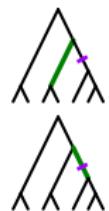
# M Step: Segmentation

$$C_j(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - r_j - s_j \Delta_j)^2$$

BM :  $r_j = 0$ , each cost is independent.

$$C_j^0 = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y])^2$$

$$C_j^1(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - s_j \Delta_j)^2$$



Algorithm:

- ① Find the  $K$  branches  $j_1, \dots, j_K$  with largest  $C_j^0$ ;
- ② Allocate one change point in the first  $K$  branches;
- ③ For each of these branches, set  $\delta_{j_k}^{(h+1)}$  so that  $C_j^1(\Delta) = 0$

[back](#)

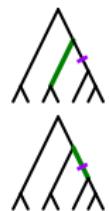
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[back](#)

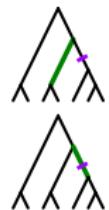
# M Step: Segmentation

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Algorithm:

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[back](#)

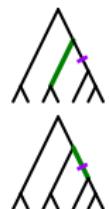
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$$C_j(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - r_j - s_j \Delta_j)^2$$

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$$C_j^1(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - s_j \Delta_j)^2$$



Algorithm:

- ① Find the  $K$  branches  $j_1, \dots, j_K$  with largest  $C_j^0$ ;
- ② Allocate one change point in the first  $K$  branches;
- ③ For each of these branches, set  $\delta_j^{(h+1)}$  so that  $C_j^1(\Delta) = 0$

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# M Step: Segmentation

$$C_j(\alpha, \tau, \delta) = \sigma_j^{-2} \left( \mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - r_j - s_j \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k \right)^2$$

OU :  $r_j = \beta^{\text{pa}(j)}$ , a cost depends on all its parents.

- Exact minimization: too costly.
- Need of an heuristic.
- Idea: rewrite as a least square:

$$\|D - AU\Delta\|^2$$

with  $D$  a vector of size  $n + m$ ,  $A$  a diagonal matrix of size  $n + m$ ,  $\Delta$  the vector of shifts and  $U$  the incidence matrix of the tree.

- Then use Stepwise selection or LASSO.
- Other idea: binary segmentation.

back

# Model Selection on $K$ : LINselect

Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 + \hat{\sigma}_K^2 \operatorname{pen}(n, K, |\mathcal{S}_K^{PI}|) \right\}$$

# Model Selection on $K$ : LINselect

Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 + \hat{\sigma}_K^2 \operatorname{pen}(n, K, |\mathcal{S}_K^{PI}|) \right\}$$

$$\hat{\sigma}_K^2 = \frac{\left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2}{n - K - 1}$$

# Model Selection on $K$ : LINselect

Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 \left( 1 + \frac{\operatorname{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

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Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

Oracle

$$\inf_{\eta \in \bigcup_{K=0}^{p-1} \mathcal{S}_K^{PI}} \left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2$$

# Model Selection on $K$ : LINselect

## Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

## Oracle

$$\inf_{\eta \in \bigcup_{K=0}^{p-1} \mathcal{S}_K^{PI}} \left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2$$

## Definition (Baraud et al. (2009))

Let  $D, N > 0$ , and  $X_D \sim \chi^2(D)$ ,  $X_N \sim \chi^2(N)$ ,  $X_D \perp X_N$ .

$$\text{Dkhi}[D, N, x] = \frac{1}{\mathbb{E}[X_D]} \mathbb{E} \left[ \left( X_D - x \frac{X_N}{N} \right)_+ \right], \quad \forall x > 0$$

$$\text{Dkhi}[D, N, \text{EDkhi}[D, N, q]] = q, \quad \forall 0 < q \leq 1$$

# LINselect: Oracle Inequality

## Proposition (Form of the Penalty and guarantees)

*Under our setting:  $\mathbf{Y} = \mathbf{T}\Delta + \sigma\mathbf{E}$  with  $E \sim \mathcal{N}(0, \mathbf{V})$ , define the penalty:*

$$\text{pen}(K) = A \frac{n - K - 1}{n - K - 2} \text{EDkhi} \left[ K + 2, n - K - 2, \exp \left( -\log \left| S_K^{PI} \right| - 2 \log(K + 2) \right) \right]$$

If  $\kappa < 1$ , and  $p \leq \min \left( \frac{\kappa n}{2 + \log(2) + \log(n)}, n - 7 \right)$ , we get:

$$\mathbb{E} \left[ \frac{\left\| \mathbb{E}[\mathbf{Y}] - \hat{\mathbf{Y}}_{\hat{K}} \right\|_{\mathbf{V}^{-1}}^2}{\sigma^2} \right] \leq C(A, \kappa) \inf_{\eta \in \mathcal{M}} \left\{ \frac{\left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2}{\sigma^2} + (K_{\eta} + 2)(3 + \log(n)) \right\}$$

with  $C(A, \kappa)$  a constant depending on  $A$  and  $\kappa$  only.

Based on Baraud et al. (2009) 

# LINselect Model Selection: Important Points

Based on Baraud, Giraud, and Huet (2009)

- Non-asymptotic bound.
- Unknown variance.
- No constant to be calibrated.

Note

- Non iid variance.
- Penalty depends on the tree topology (through  $|\mathcal{S}_K^{PI}|$ ).

back?

# Model Selection with Unknown Variance

Theorem (Baraud et al. (2009))

*Under the following setting:*

$$Y' = \mathbb{E}[Y'] + \gamma E' \quad \text{with} \quad E' \sim \mathcal{N}(0, I_n) \quad \text{and} \quad \mathcal{S}' = \{S'_\eta, \eta \in \mathcal{M}\}$$

If  $D_\eta = \text{Dim}(S'_\eta)$ ,  $N_\eta = n - D_\eta \geq 7$ ,  $\max(L_\eta, D_\eta) \leq \kappa n$ , with  $\kappa < 1$ , and:

$$\Omega' = \sum_{\eta \in \mathcal{M}} (D_\eta + 1) e^{-L_\eta} < +\infty$$

$$\text{If: } \hat{\eta} = \operatorname{argmin}_{\eta \in \mathcal{M}} \|Y' - \hat{Y}'_\eta\|^2 \left(1 + \frac{\text{pen}(\eta)}{N_\eta}\right)$$

$$\text{with: } \text{pen}(\eta) = \text{pen}_{A, L}(\eta) = A \frac{N_\eta}{N_\eta - 1} \text{EDkhi}[D_\eta + 1, N_\eta - 1, e^{-L_\eta}] \quad , \quad A > 1$$

$$\text{Then: } \mathbb{E} \left[ \frac{\|\mathbb{E}[Y'] - \hat{Y}'_{\hat{\eta}}\|^2}{\gamma^2} \right] \leq C(A, \kappa) \left[ \inf_{\eta \in \mathcal{M}} \left\{ \frac{\|\mathbb{E}[Y'] - Y'_\eta\|^2}{\gamma^2} + \max(L_\eta, D_\eta) \right\} + \Omega' \right]$$

# IID Framework ( $\alpha = 0$ )

Assume  $K_\eta = D_\eta - 1 \leq p - 1 \leq n - 8$ ,  $\forall \eta \in \mathcal{M}$

Then:

$$\begin{aligned}\Omega' &= \sum_{\eta \in \mathcal{M}} (D_\eta + 1)e^{-L_\eta} = \sum_{\eta \in \mathcal{M}} (K_\eta + 2)e^{-L_\eta} \\ &= \sum_{K=0}^{p-1} |\mathcal{S}_K^{PI}| (K+2)e^{-L_K} = \sum_{K=0}^{p-1} |\mathcal{S}_K^{PI}| (K+2)e^{-(\log|\mathcal{S}_K^{PI}| + 2\log(K+2))} \\ &= \sum_{K=0}^{p-1} \frac{1}{K+2} \leq \log(p) \leq \log(n)\end{aligned}$$

And:

$$L_K \leq \log \binom{n+m-1}{K} + 2\log(K+2) \leq K\log(n+m-1) + 2(K+1) \leq p(2 + \log(2n-2))$$

Hence, if  $p \leq \min\left(\frac{\kappa n}{2 + \log(2) + \log(n)}, n - 7\right)$ , then  $\max(L_\eta, D_\eta) \leq \kappa n$  for any  $\eta \in \mathcal{M}$ .

# Non-IID Framework ( $\alpha \neq 0$ )

Cholesky decomposition:  $V = LL^T$     $Y' = L^{-1}Y$     $s' = L^{-1}s$     $E' = L^{-1}E$

$$Y' = \mathbb{E}[Y'] + \gamma E', \text{ with: } E' \sim \mathcal{N}(0, I_n)$$

$$S'_\eta = L^{-1}S_\eta, \quad \hat{Y}'_\eta = \text{Proj}_{S'_\eta} Y' = \underset{a' \in S'_\eta}{\operatorname{argmin}} \|Y - La'\|_V^2 = L^{-1}\hat{Y}_\eta$$

$$\|\mathbb{E}[Y] - \hat{Y}_{\hat{\eta}}\|_V^2 = \|\mathbb{E}[Y'] - \hat{Y}'_{\hat{\eta}}\|_V^2, \quad \|Y - \hat{Y}_\eta\|_V^2 = \|Y' - \hat{Y}'_\eta\|_V^2$$

$$\text{Crit}_{MC}(\eta) = \|Y' - \hat{Y}'_\eta\|_V^2 \left(1 + \frac{\text{pen}_{A,\mathcal{L}}(\eta)}{N_\eta}\right) = \|Y - \hat{Y}_\eta\|_V^2 \left(1 + \frac{\text{pen}_{A,\mathcal{L}}(\eta)}{N_\eta}\right)$$

back

# Phylogenetic PCA with shifts

Model  $\mathbf{Y}$  size  $n \times p$  ( $n$  observations,  $p$  traits), Brownian

$$\mathbf{Y} = \boldsymbol{\mu} + \mathbf{E} \quad \text{vec}(\mathbf{E}) \sim \mathcal{N}(\mathbf{0}, \mathbf{R} \otimes \mathbf{C})$$

## Empirical Mean and Variance

$$\bar{\mathbf{Y}}^T = \tilde{\mathbf{C}}\mathbf{Y} \quad \bar{\boldsymbol{\mu}}^T = \mathbb{E}[\bar{\mathbf{Y}}^T] = \tilde{\mathbf{C}}\boldsymbol{\mu} \quad \text{with} \quad \tilde{\mathbf{C}} = (\mathbf{1}_n^T \mathbf{C}^{-1} \mathbf{1}_n)^{-1} \mathbf{1}_n^T \mathbf{C}^{-1}$$

$$\hat{\mathbf{R}} = \frac{1}{n-1}(\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T)^T \mathbf{C}^{-1} (\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T)$$

## Bias on $\hat{\mathbf{R}}$

$$\mathbb{E}[\hat{\mathbf{R}}] = \mathbf{R} + \frac{1}{n-1} \mathbf{G}^T \mathbf{C}^{-1} \mathbf{G} \quad \text{with} \quad \mathbf{G} = (\boldsymbol{\mu} - \mathbf{1}_n \bar{\boldsymbol{\mu}}^T)$$

# Phylogenetic PCA : Scores

## Rotation

$$\hat{\mathbf{R}} = \frac{1}{n-1} \hat{\mathbf{V}} \hat{\mathbf{D}}^2 \hat{\mathbf{V}}^T$$

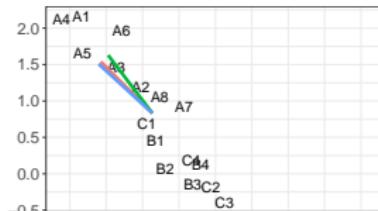
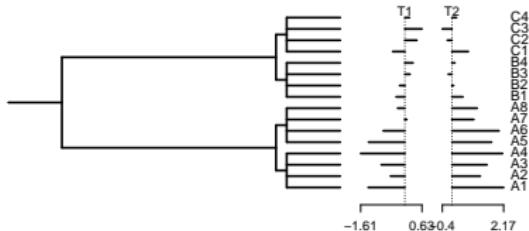
→ If  $\hat{\mathbf{R}}$  is biased, then  $\hat{\mathbf{V}}$  is the wrong rotation.

## Scores

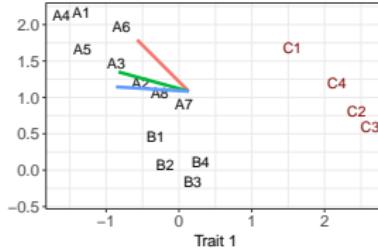
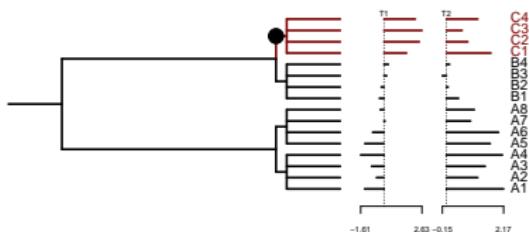
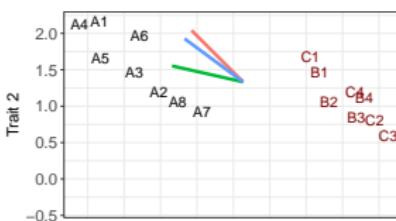
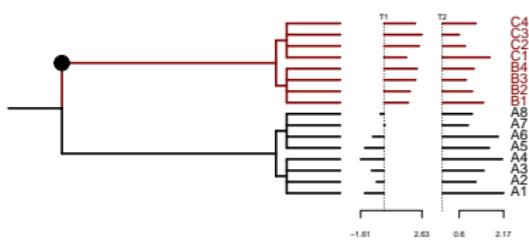
$$\mathbf{S} = (\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T) \hat{\mathbf{V}}$$

→ The scores are not decorrelated.

# Phylogenetic PCA : Examples



First eigenvector from  
 — red variance R  
 — green PCA  
 — blue pPCA



back

# OU Model

SDE **A** ( $p \times p$ ) selection strength

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

# OU Model

SDE  $\mathbf{A}$  ( $p \times p$ ) selection strength

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

## Covariances

$$\begin{aligned}\mathbb{C}\text{ov} [\mathbf{X}_i; \mathbf{X}_j] &= e^{-\mathbf{A}t_i} \boldsymbol{\Gamma} e^{-\mathbf{A}^T t_j} \\ &+ e^{-\mathbf{A}(t_i - t_{ij})} \left( \int_0^{t_{ij}} e^{-\mathbf{A}v} \boldsymbol{\Sigma} \boldsymbol{\Sigma}^T e^{-\mathbf{A}^T v} dv \right) e^{-\mathbf{A}^T (t_j - t_{ij})}\end{aligned}$$

# OU Model

SDE  $\mathbf{A}$  ( $p \times p$ ) selection strength  $\in \mathcal{S}_n^{++}$

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$$\begin{aligned} \text{Cov} [\mathbf{X}_i; \mathbf{X}_j] &= e^{-\mathbf{A}t_i} \boldsymbol{\Gamma} e^{-\mathbf{A}^T t_j} \\ &+ e^{-\mathbf{A}(t_i - t_{ij})} \left( \int_0^{t_{ij}} e^{-\mathbf{A}v} \boldsymbol{\Sigma} \boldsymbol{\Sigma}^T e^{-\mathbf{A}^T v} dv \right) e^{-\mathbf{A}^T (t_j - t_{ij})} \end{aligned}$$

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$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

## Stationary Variance

$$\mathbf{S} = \mathbf{P} \left( \left[ \frac{1}{\lambda_q + \lambda_r} \right]_{1 \leq q, r \leq p} \odot \mathbf{P}^{-1} \mathbf{R} \mathbf{P}^{-T} \right) \mathbf{P}^T$$

# OU Model

SDE  $\mathbf{A}$  ( $p \times p$ ) selection strength  $\in \mathcal{S}_n^{++}$

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

## Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

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## Incomplete Data Representation

$$\mathbf{X}_j \mid \mathbf{X}_{\text{pa}(j)} \sim \mathcal{N} \left( e^{-\mathbf{A}\ell_j} \mathbf{X}_{\text{pa}(j)} + (\mathbf{I}_p - e^{-\mathbf{A}\ell_j})\beta_j, \boldsymbol{\Upsilon}_i = \mathbf{S} - e^{-\mathbf{A}\ell_j}\mathbf{S}e^{-\mathbf{A}^T\ell_j} \right)$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma} d\mathbf{B}_t$$

## Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

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$$\mathbf{S} = \mathbf{P} \left( \left[ \frac{1}{\lambda_q + \lambda_r} \right]_{1 \leq q, r \leq p} \odot \mathbf{P}^{-1} \mathbf{R} \mathbf{P}^{-T} \right) \mathbf{P}^T$$

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$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

Stationary Variance

$$\mathbf{S} = \mathbf{P} \left( \left[ \frac{1}{\lambda_q + \lambda_r} \right]_{1 \leq q, r \leq p} \odot \mathbf{P}^{-1} \mathbf{R} \mathbf{P}^{-T} \right) \mathbf{P}^T$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\Gamma e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha}\mathbf{R}$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1) \mathbf{R}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha} \mathbf{R}$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1) \mathbf{R}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha} \mathbf{R}$$

↳ Re-scaling trick.

back

## TE: Single Effect

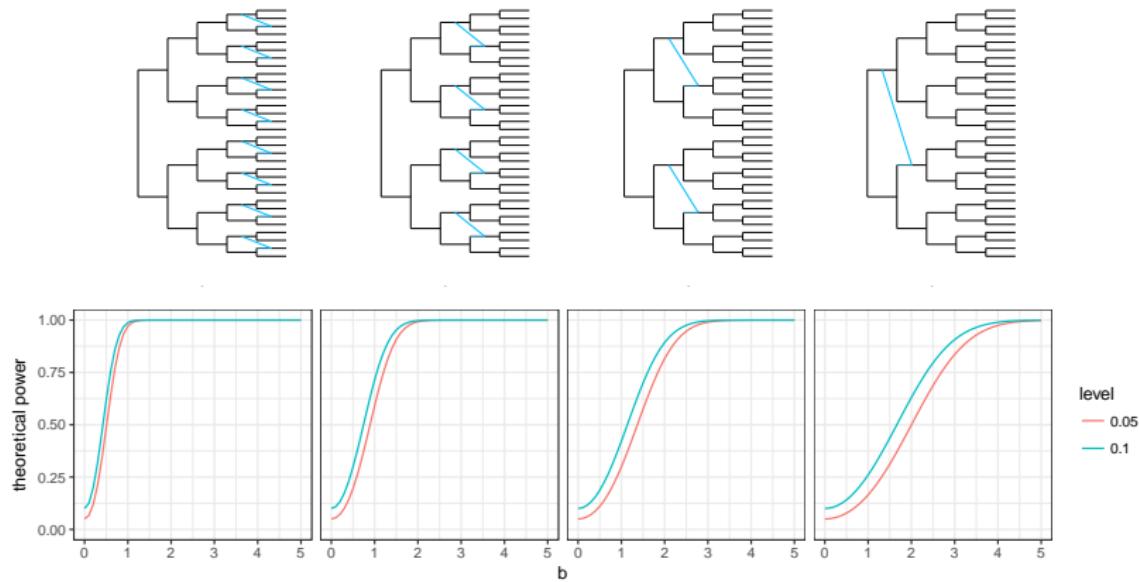
Model:  $\mathbf{Y} = \mu \mathbf{1} + b \bar{\mathbf{N}} + \sigma^2 \mathbf{E}$  ,  $\mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$

Test:  $\mathcal{H}_0 : b = 0$

Stat.:  $F_{10} = \frac{\|\mathbf{Y} - \text{Proj}_{\mathbf{1}} \mathbf{Y}\|_{\mathbf{V}^{-1}}^2 - \left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2}{\left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2} \frac{n - r_{[\mathbf{1} \ \bar{\mathbf{N}}]}}{r_{[\mathbf{1} \ \bar{\mathbf{N}}]} - r_{\mathbf{1}}}$

$$\sim \mathcal{F} \left( 1, n - 2, \frac{b^2}{2\sigma^2} \left\| (\mathbf{I} - \text{Proj}_{\mathbf{1}}) \bar{\mathbf{N}} \right\|_{\mathbf{V}^{-1}}^2 \right)$$

## TE: Single Effect



*Detection Power ( $\sigma^2 = 1$ )*

# TE: Several Effects

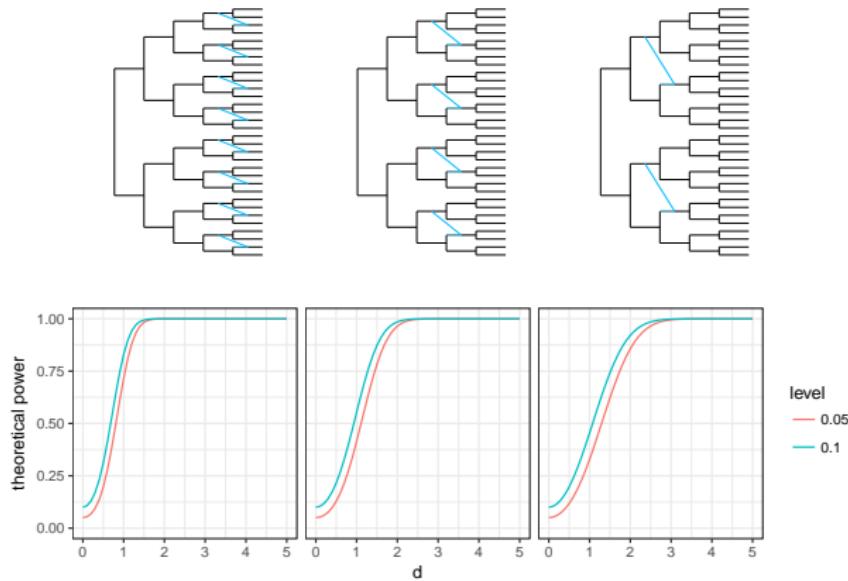
Model:  $\mathbf{Y} = \mu \mathbf{1} + b \bar{\mathbf{N}} + \mathbf{Nd} + \sigma^2 \mathbf{E}$  ,  $\mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$

Test:  $\mathcal{H}_1: d_1 = \dots = d_h = 0$

Stat.:  $F_{21} = \frac{\left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2 - \left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \mathbf{N}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2}{\left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \mathbf{N}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2} \frac{n - r_{[\mathbf{1} \ \mathbf{N}]}}{r_{[\mathbf{1} \ \mathbf{N}]} - r_{[\mathbf{1} \ \bar{\mathbf{N}}]}}$

$$\sim \mathcal{F} \left( h - 1, n - h - 1, \frac{1}{2\sigma^2} \left\| (\mathbf{I} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]}) \mathbf{Nd} \right\|_{\mathbf{V}^{-1}}^2 \right)$$

# TE: Several Effects



*Detection Power ( $\sigma^2 = 1$ )*

back

# Simulations Design

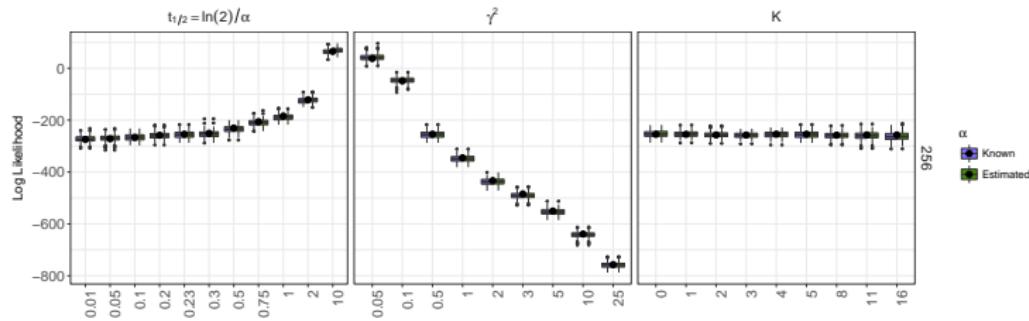
(Uyeda and Harmon, 2014)

- Topology of the tree fixed (unit height,  $\lambda = 0.1$ , with 64, 128, 256 taxa).
- Initial optimal value fixed:  $\beta_0 = 0$
- One "base" scenario  $\alpha_b = 3$ ,  $\gamma_b^2 = 0.5$ ,  $K_b = 5$ .
- $\alpha \in \log(2)/\{0.01, 0.05, 0.1, 0.2, 0.23, 0.3, 0.5, 0.75, 1, 2, 10\}$ .
- $\gamma^2 \in \{0.3, 0.6, 3, 6, 12, 18, 30, 60, 150\}/(2\alpha_b)$ .
- $K \in \{0, 1, 2, 3, 4, 5, 8, 11, 16\}$ .
- Shifts values  $\sim \frac{1}{2}\mathcal{N}(4, 1) + \frac{1}{2}\mathcal{N}(-4, 1)$
- Shifts randomly placed at regular intervals separated by 0.1 unit length.
- $n = 200$  repetitions: 16200 configurations.

CPU time on cluster MIGALE (Jouy-en-Josas):

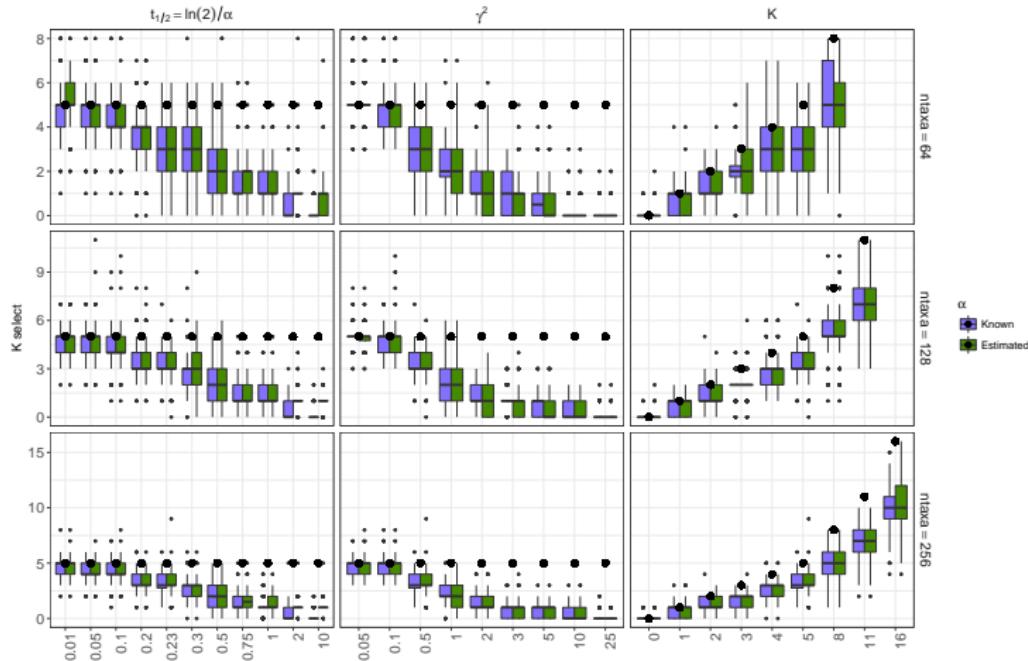
- $\alpha$  known: 6 minutes per estimation (66 days in total).
- $\alpha$  unknown: 52 minutes per estimation (570 days in total).

# Log-Likelihood

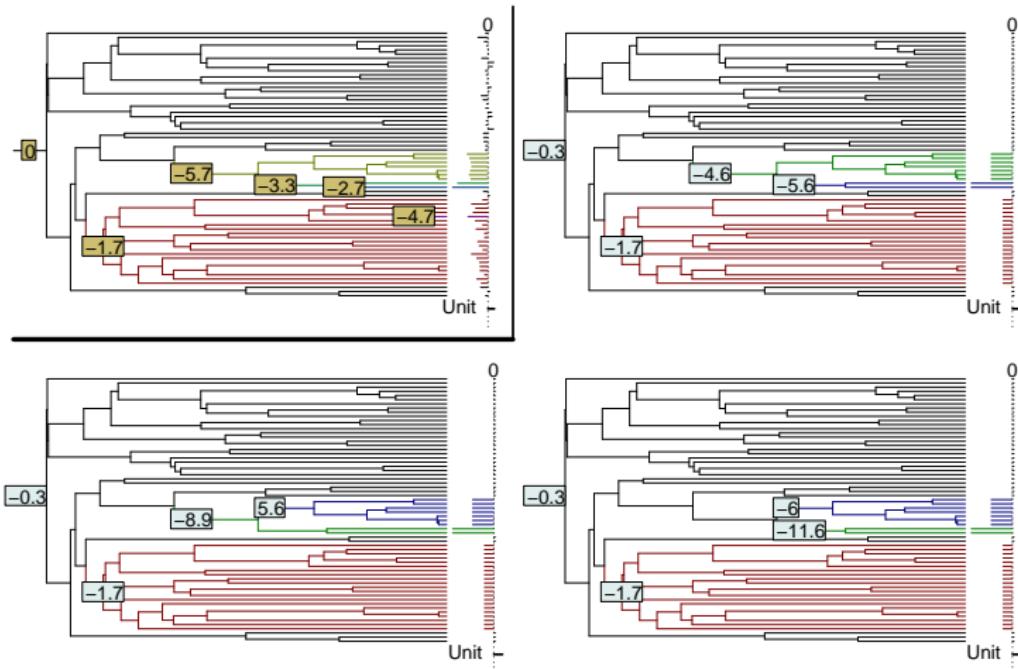


*Log likelihood for a tree with 256 tips. Solid black dots are the median of the log likelihood for the true parameters.*

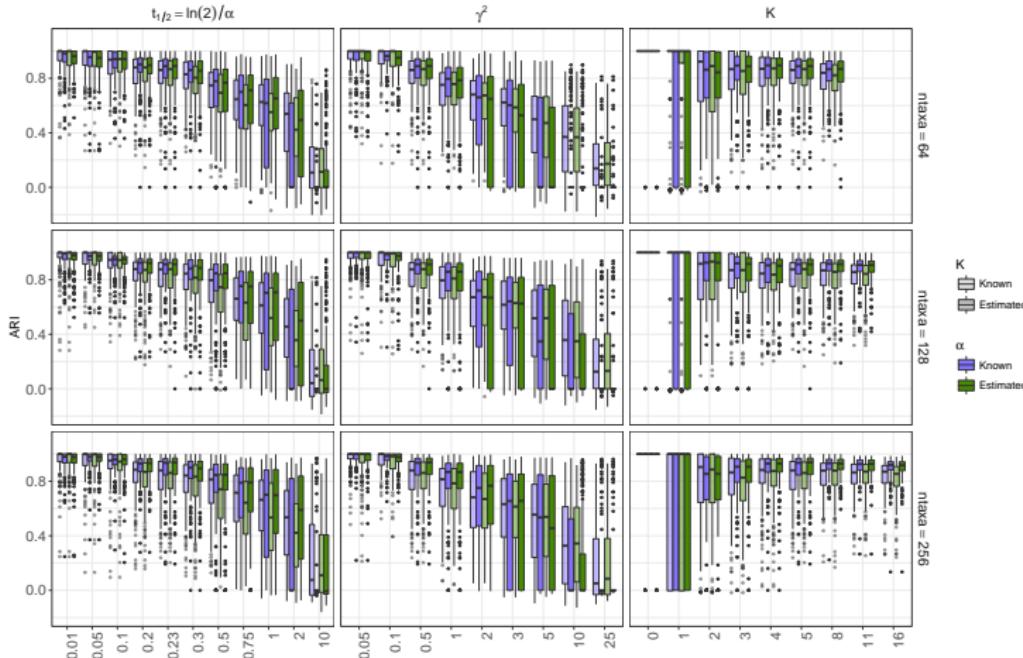
# Number of Shifts

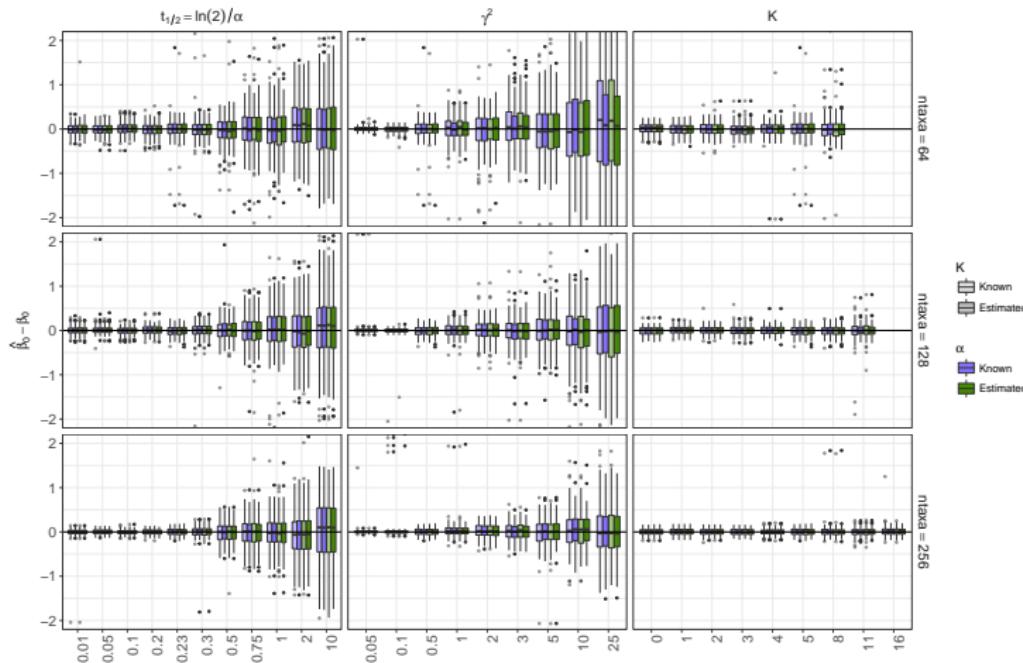


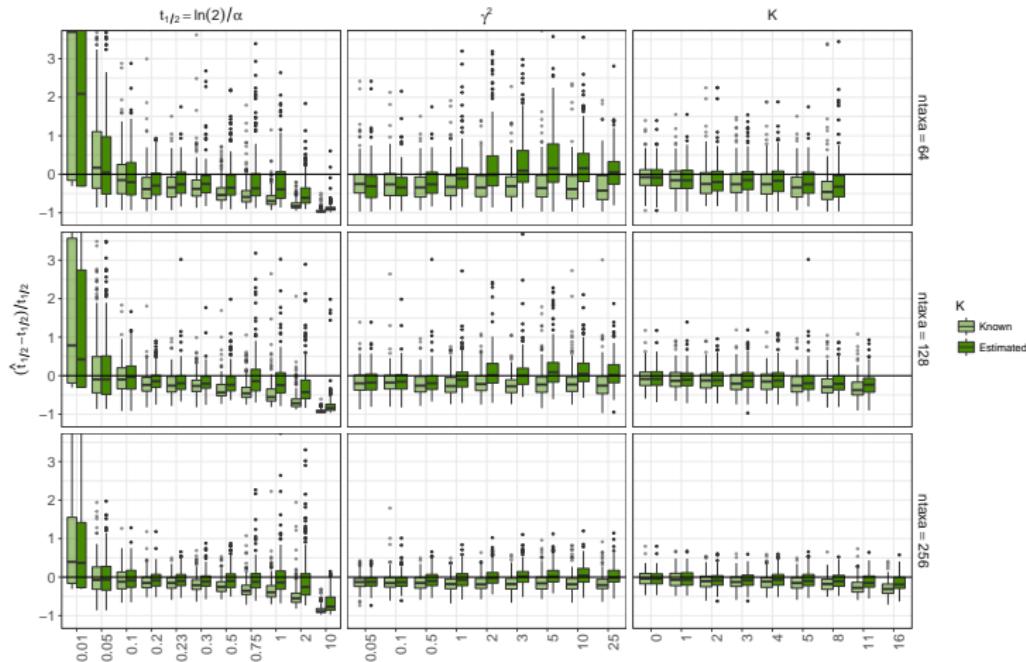
# One Example

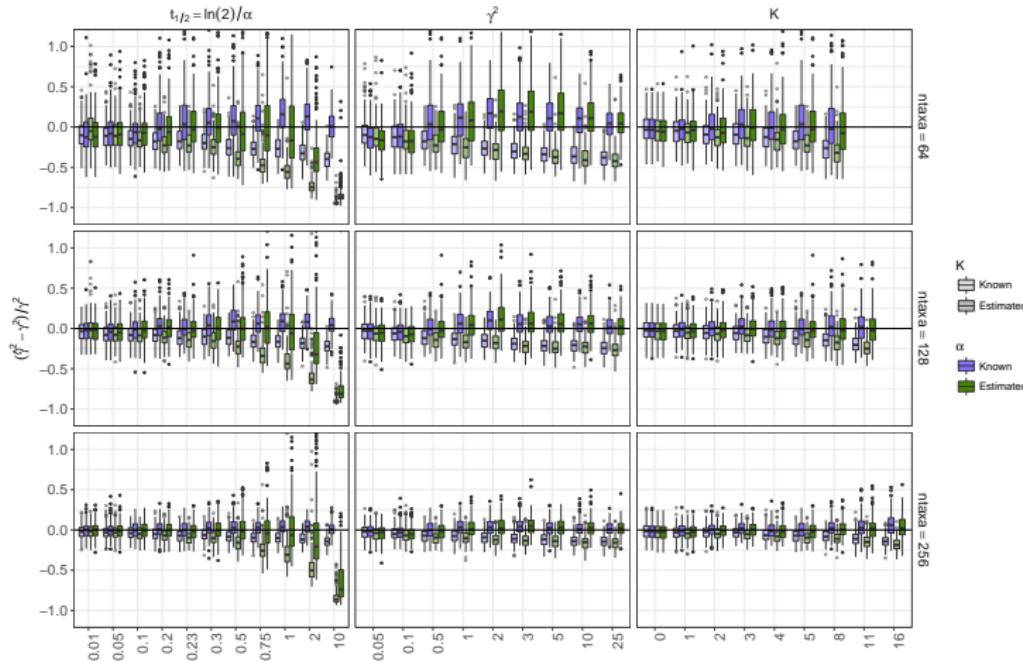


# Adjusted Rand Index

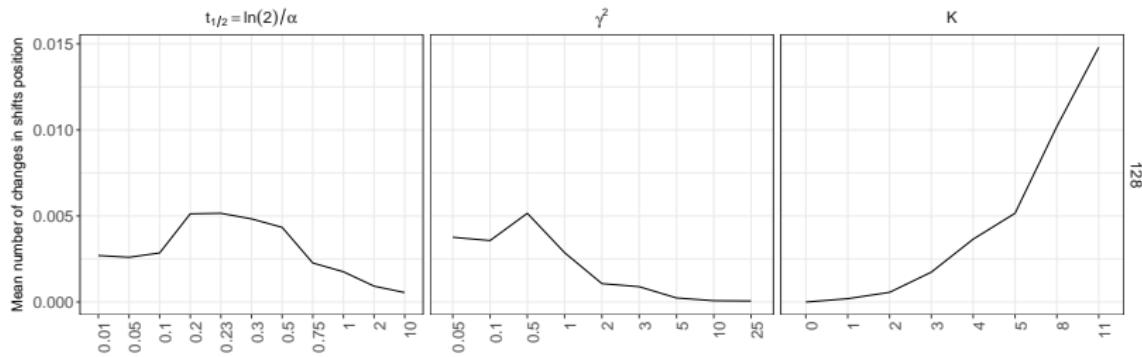


Parameters:  $\beta_0$ 

Parameters:  $\alpha$ 

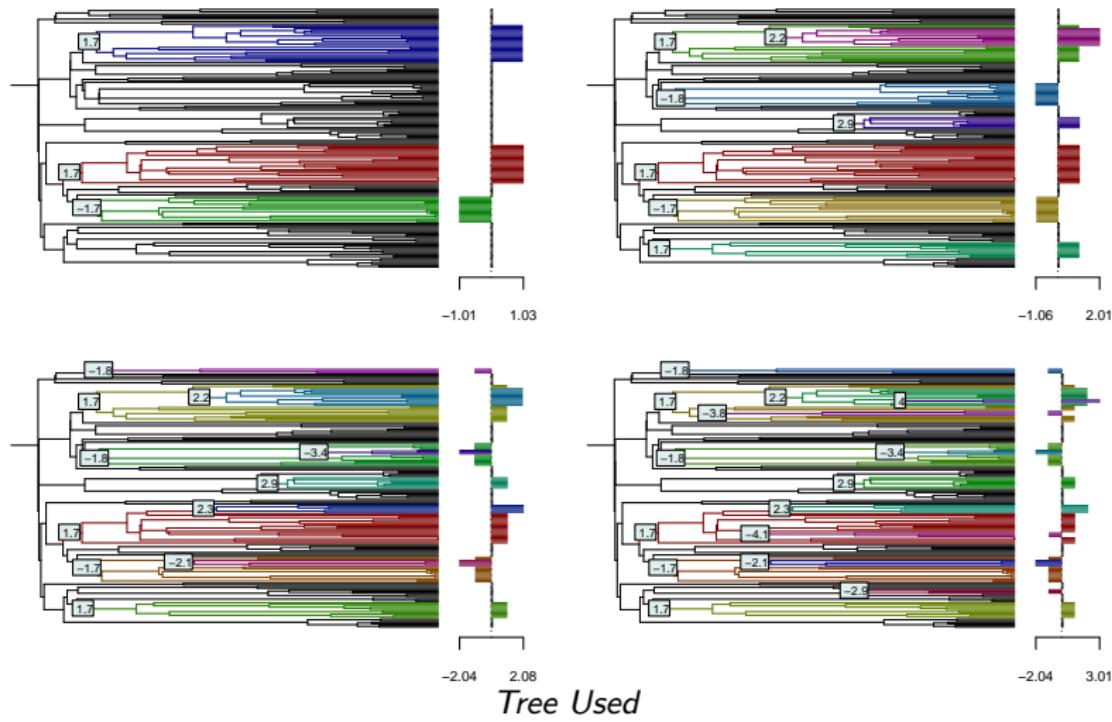
Parameters:  $\gamma^2$ 

# Exploration

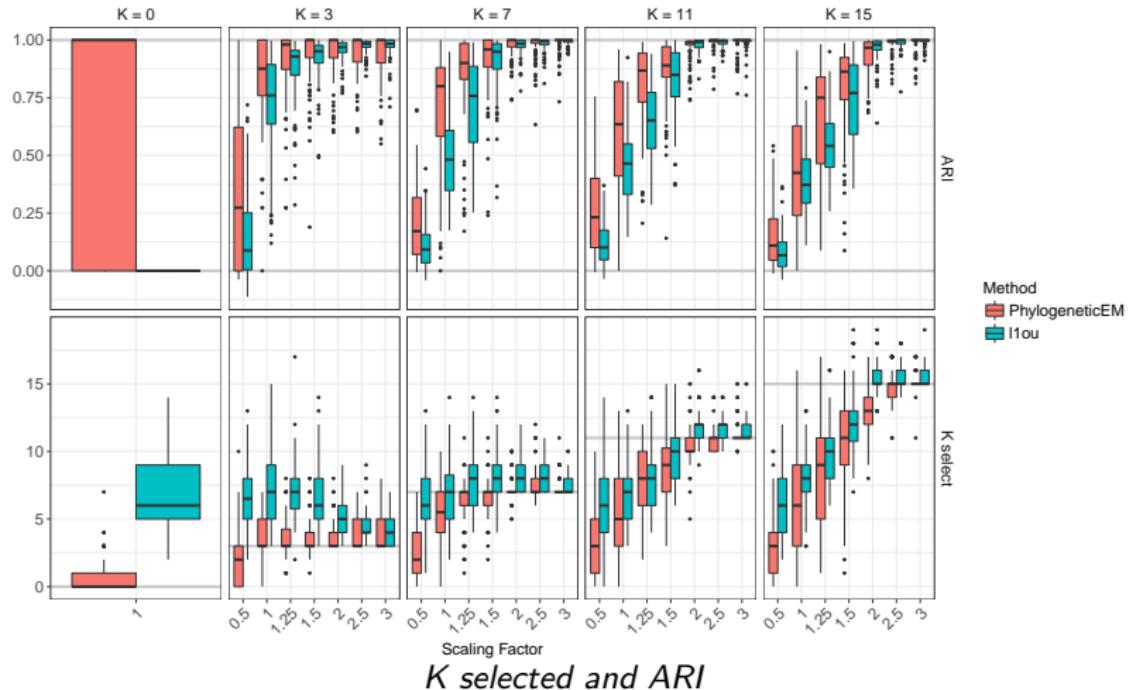


*Figure: Mean number changes in the shifts positions during the EM algorithm. Null means that the initial shifts were kept all along.*

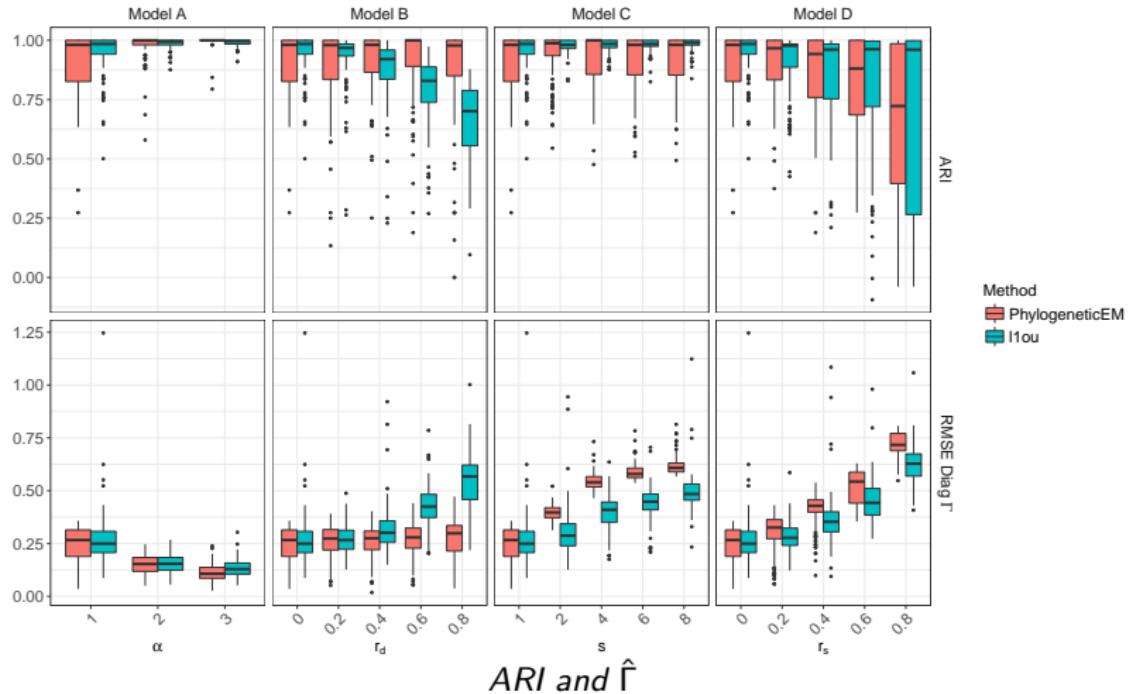
# Simulations: Experimental Design



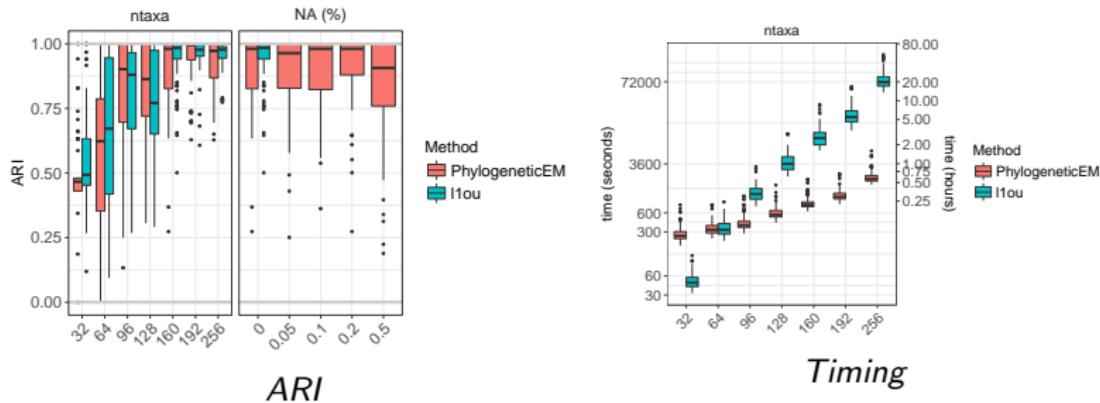
# Simulations: Model Selection

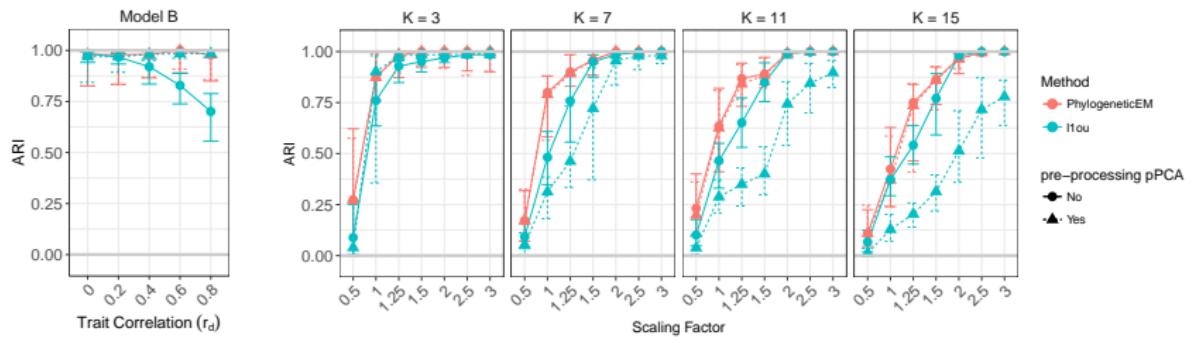


# Simulations: Model Selection and Estimation



# Simulations: Scalability



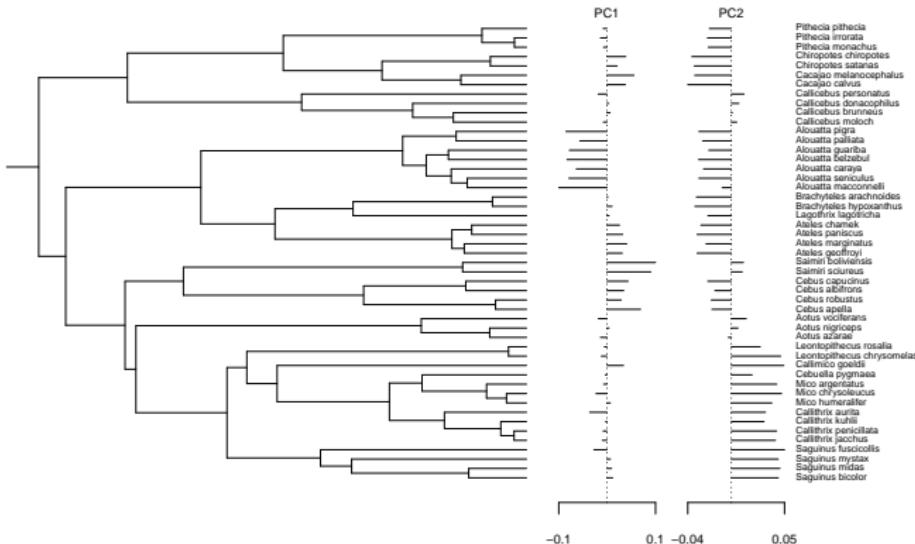


# Monkey Dataset

(Aristide et al., 2016)

```
data(monkeys)

plot(params_BM(p=2), data = monkeys$dat, phylo = monkeys$phy, show.tip.label = TRUE)
```



# Analysis

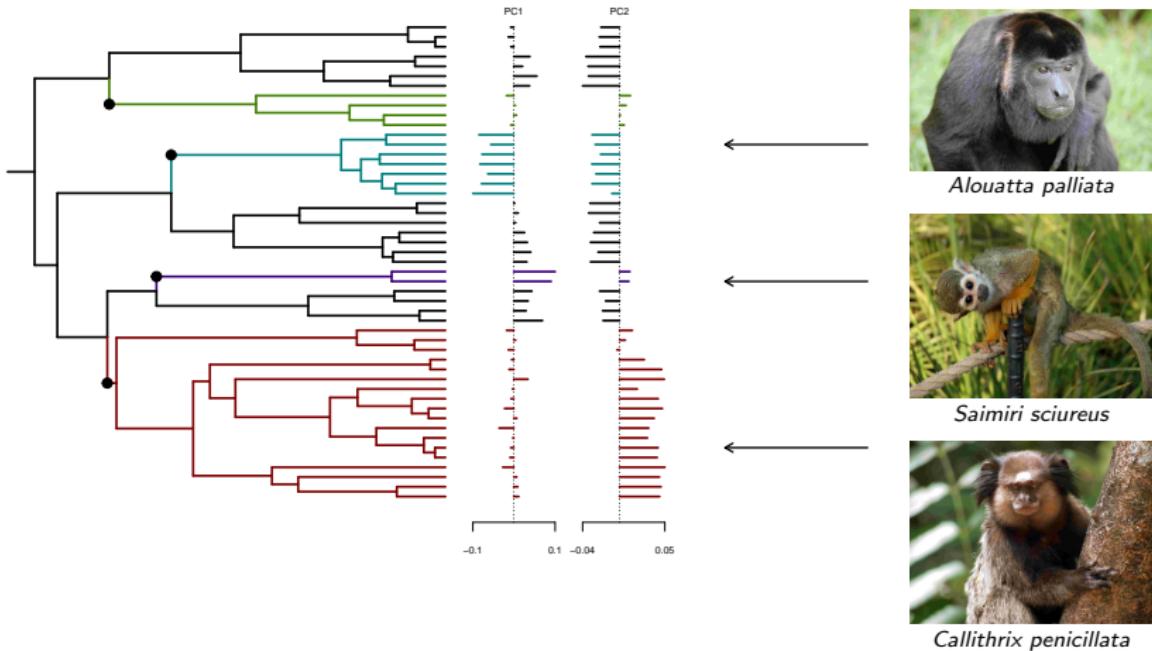
We use function PhyloEM:

```
res <- PhyloEM(Y_data = monkeys$dat,          ## data
                 phylo = monkeys$phy,       ## phylogeny
                 process = "scOU",        ## scalar OU
                 K_max = 10,              ## maximal number of shifts
                 nbr_alpha = 4,           ## number of alpha values
                 parallel_alpha = TRUE,   ## parallelize on alpha values
                 Ncores = 2)
```

Then plot the solution selected by the default method:

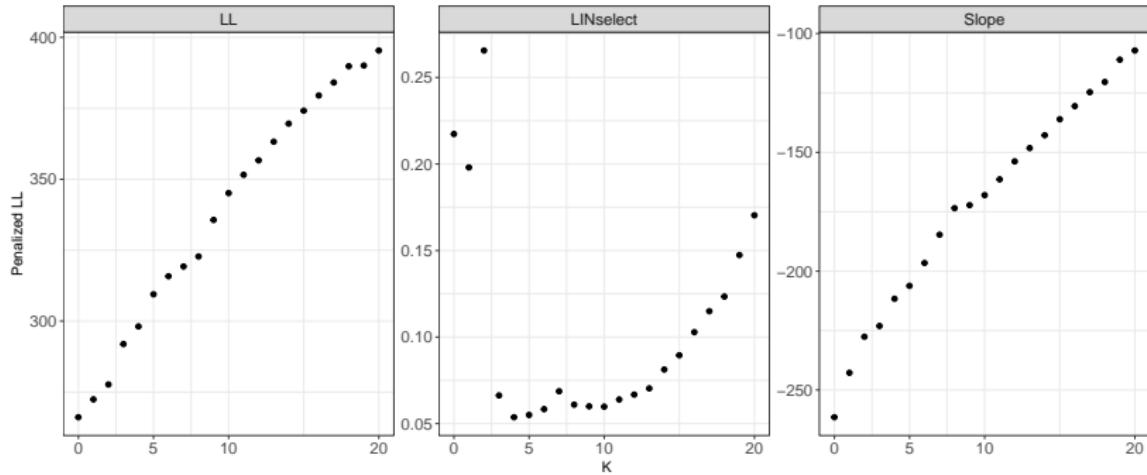
```
plot(res, edge.width = 2)
```

# Result



# Model Selection

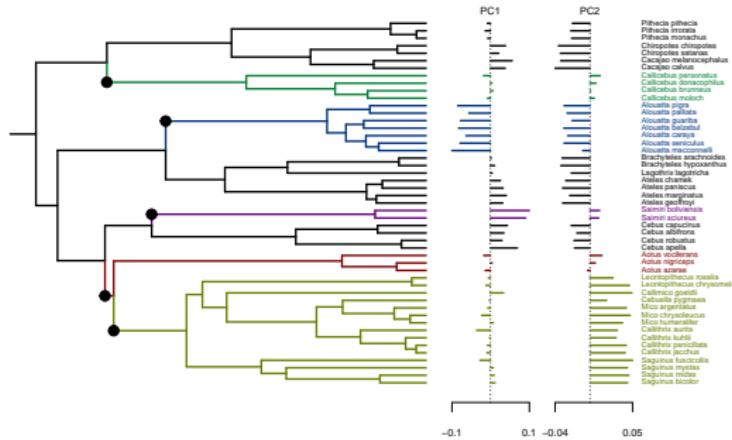
Solution with  $K = 5$  seems to be a good solution too.



## Solution for $K = 5$

```
plot(res, params = params_process(res, K = 5), edge.width = 2, show.tip.label = TRUE)
```

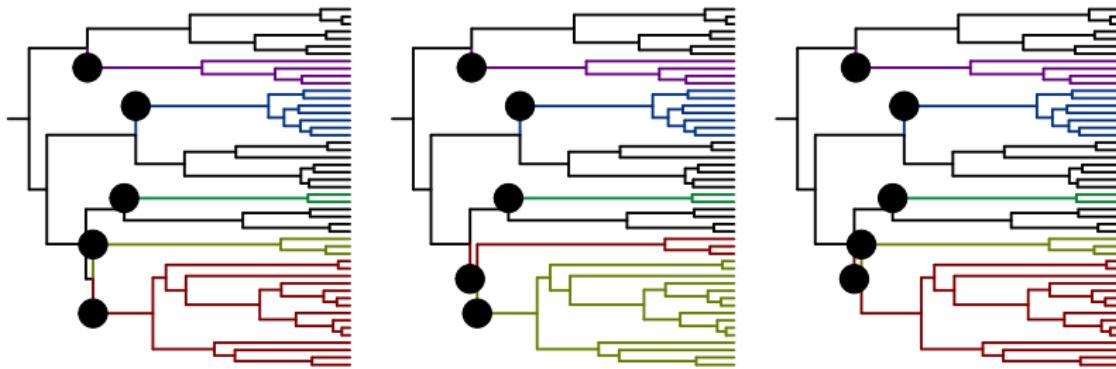
## Warning in params\_process.PhyloEM(res, K = 5): There are several equivalent solutions for this shift position.



# Solution for $K = 5$

```
params_5 <- params_process(res, K = 5)
eq_shifts <- equivalent_shifts(monkeys$phy, params_5)
```

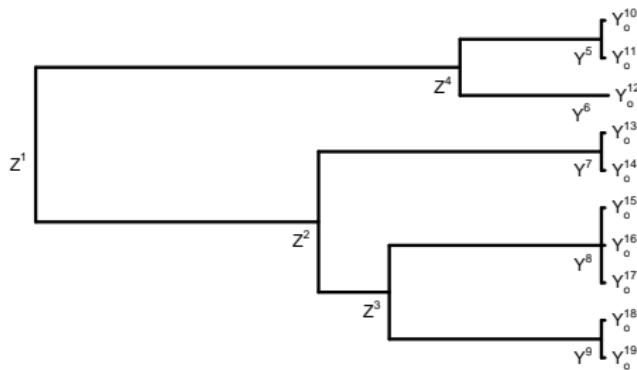
```
plot(eq_shifts)
```



back

## Measurement Error

(Felsenstein, 2008)



$$\mathbf{X} = \begin{cases} \mathbf{Y}_o & : \text{observed traits} \\ \mathbf{Y} & : \text{latent tips} \\ \mathbf{Z} & : \text{latent nodes} \end{cases}$$

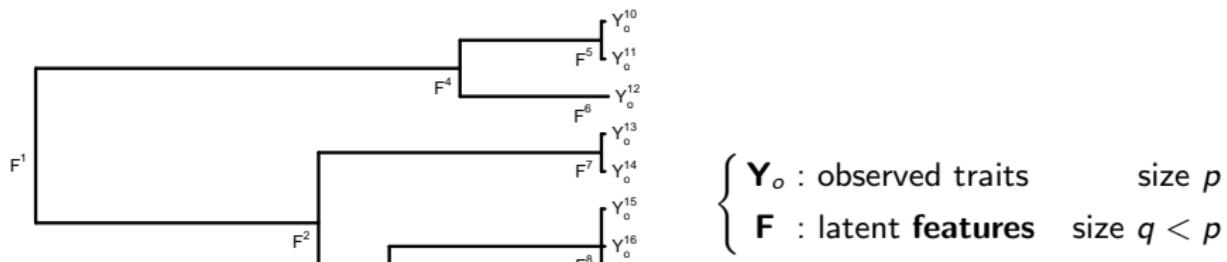
$$\mathbf{X}^1 \sim \mathcal{N}(\mu, \Gamma) \quad \text{root}$$

$$\mathbf{X}^j \mid \mathbf{X}^{\text{pa}(j)} \sim \mathcal{N} \left( \mathbf{X}^{\text{pa}(j)} + \boldsymbol{\Delta}^j, \ell_j \mathbf{R} \right) \quad \text{nodes } 2 \leq j \leq m+n$$

$$\mathbf{Y}_o^i \mid \mathbf{Y}^{\text{pa}(i)} \sim \mathcal{N} \left( \mathbf{Y}^{\text{pa}(i)}, \mathbf{P} \right) \quad \text{observations } m+n+1 \leq i \leq m+n+n_o.$$

# Factor Analysis

(Tolkoff et al., 2017)

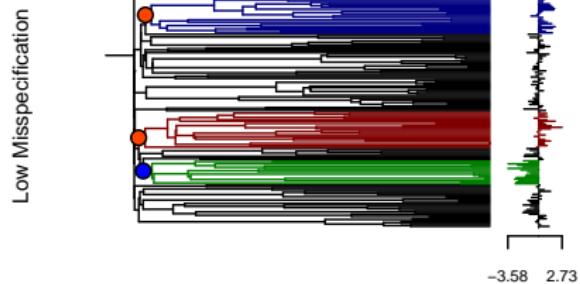


observations

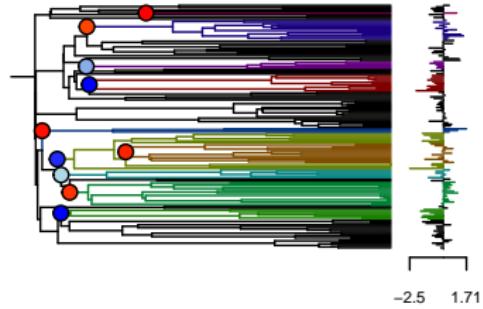
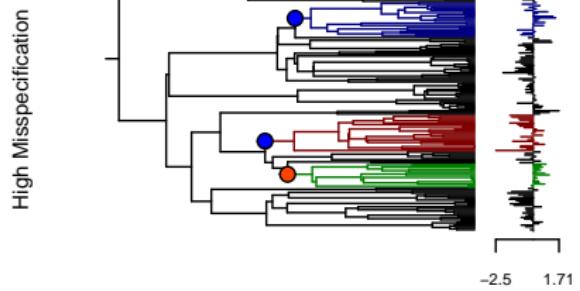
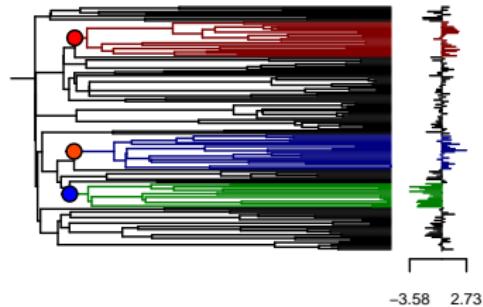
 $m + n + 1 \leq i \leq m + n + n_o$ .

# Tree Misspecification

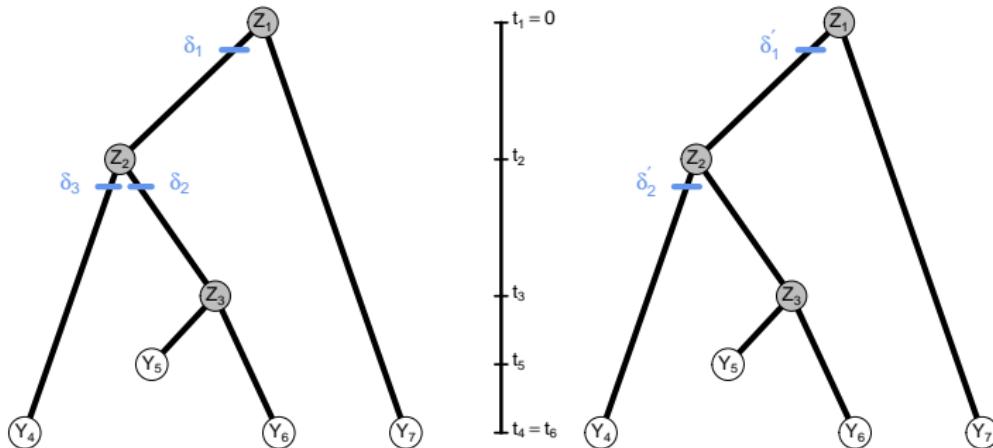
Simulation Tree and Shifts



Estimation Tree and Shifts



# Identifiability



*Figure: A non-ultrametric tree, with a “non parsimonious” solution on the left that cannot be reduced to the “parsimonious” one on the right for an OU.*

# M Step: Segmentation

See [here](#)

# Patterns in Missing Data

(Rubin, 1976)

 $\mathbf{Y}(n \times p)$  data $\mathbf{M}(n \times p)$  missing data indicator $p_\psi(\mathbf{M} | \mathbf{Y})$  sampling law

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EM:

$$\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

$$= \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

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MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$

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$$\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

$$= \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$

MAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}})$

# Patterns in Missing Data

(Rubin, 1976)

 $\mathbf{Y}(n \times p)$  data $\mathbf{M}(n \times p)$  missing data indicator $p_\psi(\mathbf{M} | \mathbf{Y})$  sampling law

EM:

$$\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

$$= \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$ MAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}})$ NMAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}})$