

# Change-point Detection on Phylogenetic Trees from Present-day Data

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<sup>4</sup> MIA-Paris, INRA - AgroParisTech, Paris, France

20 November 2017



# New World Monkeys

(Aristide et al., 2016)



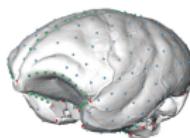
*Callithrix penicillata*

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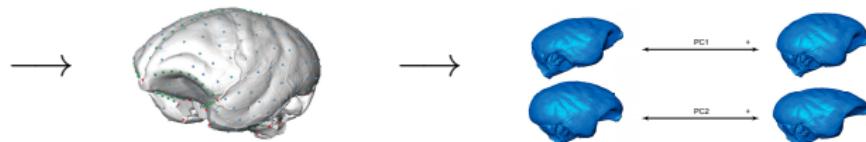


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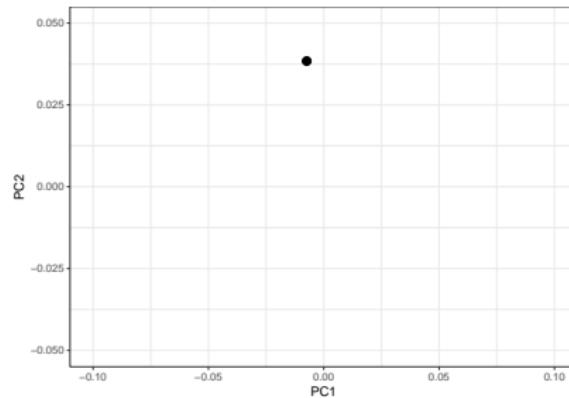
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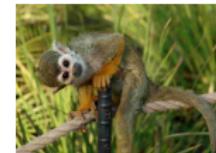
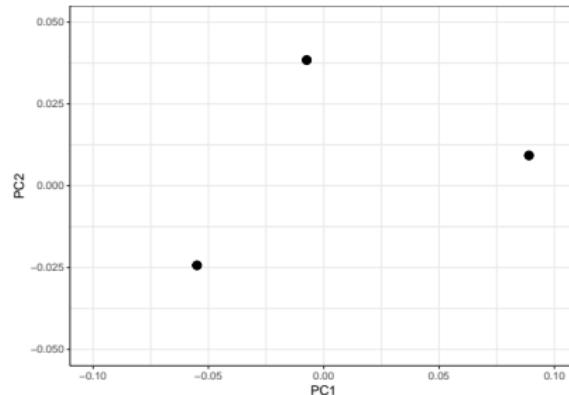


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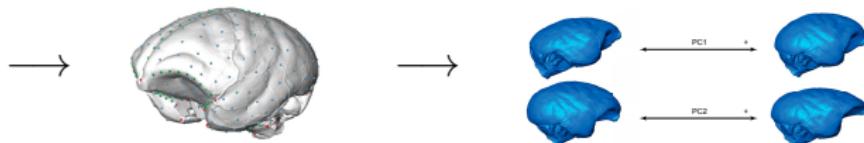
*Alouatta palliata*



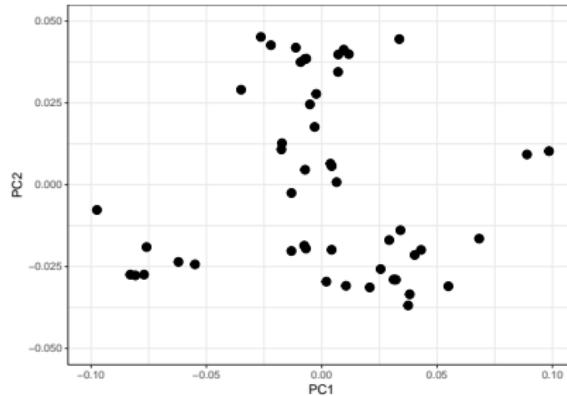
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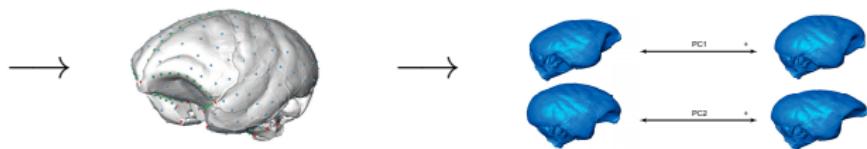
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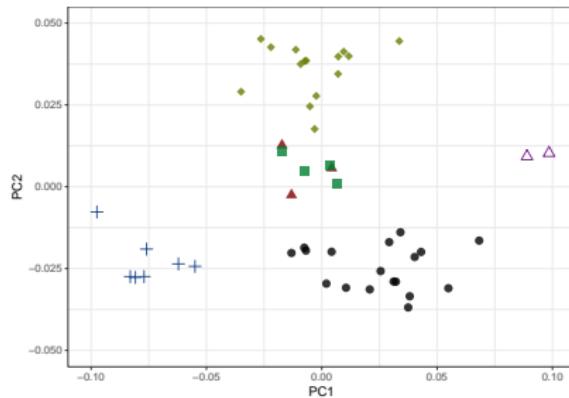
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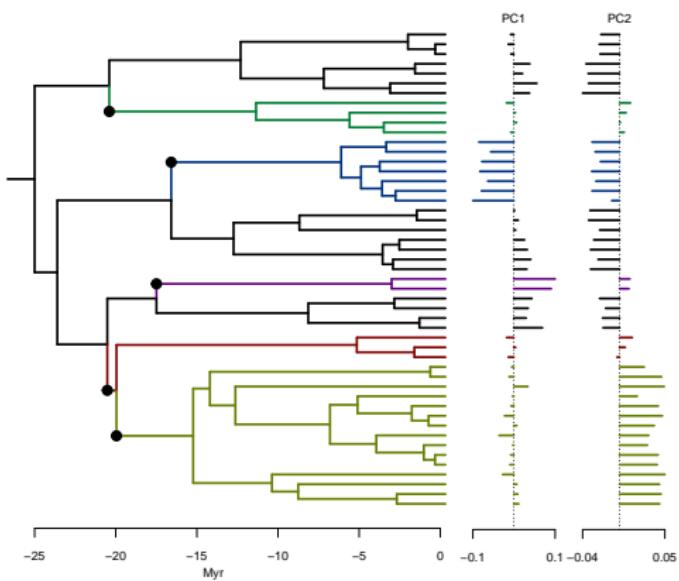
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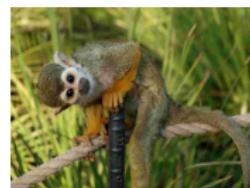
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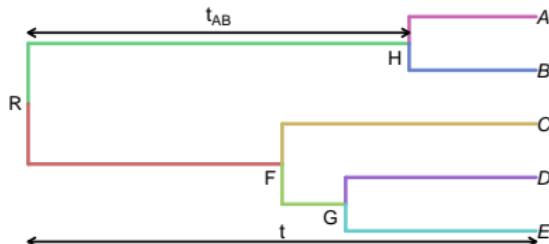
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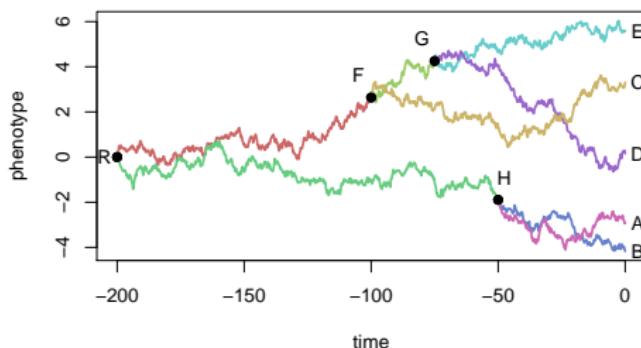
# Shifted BM on a Tree

(Felsenstein, 1985)



**Known** tree.

Only tip values observed.



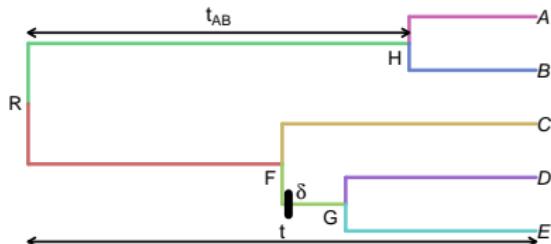
Brownian Motion:

$$\text{Var}[A | R] = \sigma^2 t$$

$$\text{Cov}[A; B | R] = \sigma^2 t_{AB}$$

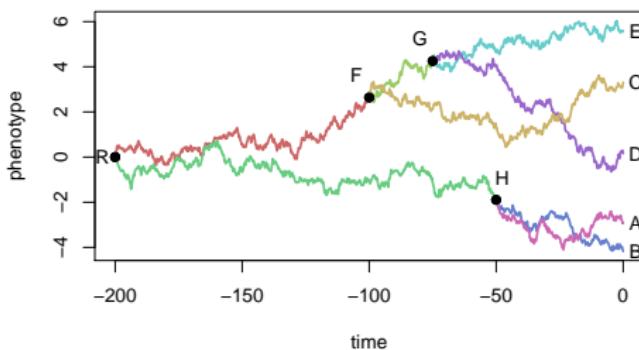
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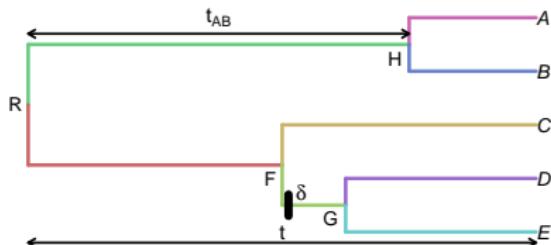
$$\text{Var}[A | R] = \sigma^2 t$$

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$$m_{\text{child}} = m_{\text{parent}} + \delta$$

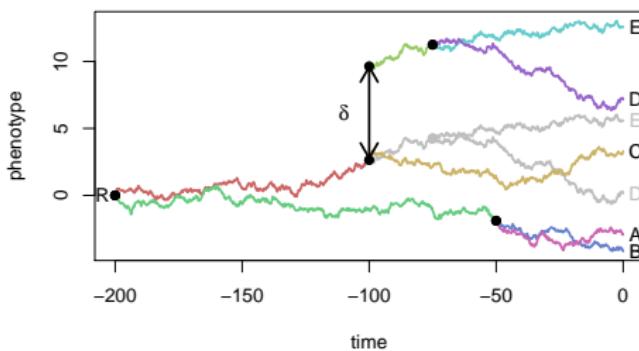
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# Outline

① Shifted BM on a Tree

② Shifted OU on a Tree

③ Multivariate Trait

# Outline

## ① Shifted BM on a Tree

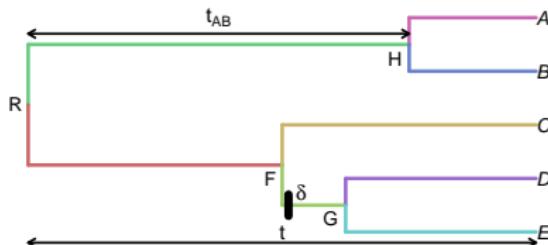
- Identifiability
- Incomplete Data Model
- Linear Regression Model

## ② Shifted OU on a Tree

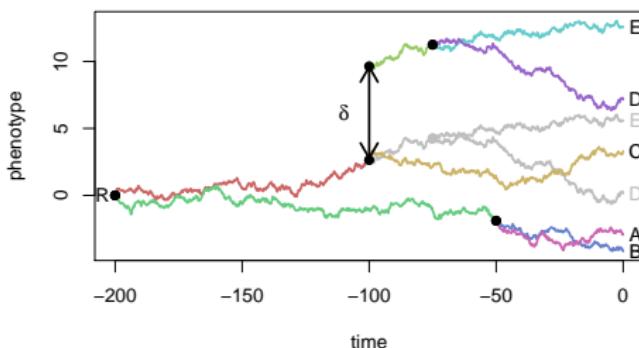
## ③ Multivariate Trait

## Shifted BM on a Tree

(Felsenstein, 1985)

**Known tree.**

Only tip values observed.



Brownian Motion:

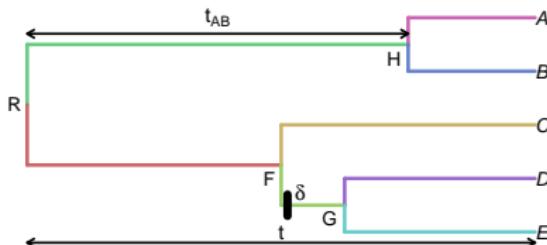
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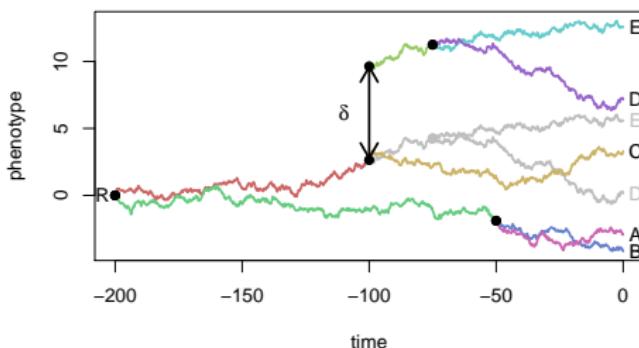
## Shifted BM on a Tree

(Felsenstein, 1985)

**Known** tree.

Only tip values observed.

Goal: Find shifts position.



Brownian Motion:

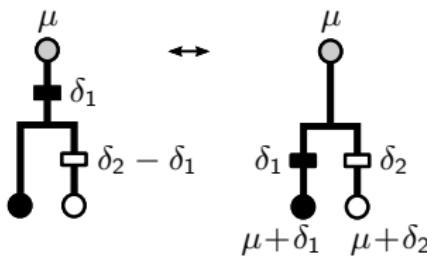
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# Equivalencies

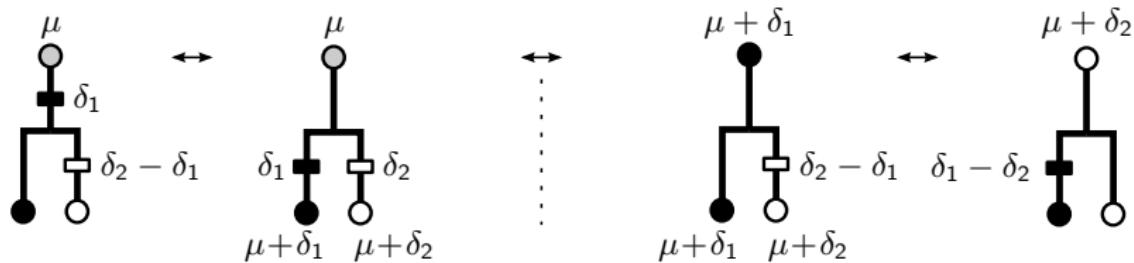
- Equivalent configurations:



- Over-parametrization: parsimonious configurations.

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- Over-parametrization: parsimonious configurations.

# Parsimonious Solution: Definition

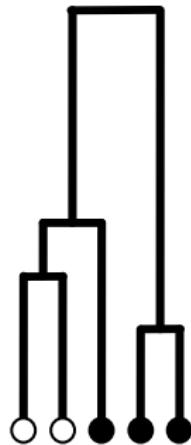
## Definition (Parsimonious Allocation)

A coloring of the tips being given, a *parsimonious* allocation of the shifts is such that it has a minimum number of shifts.

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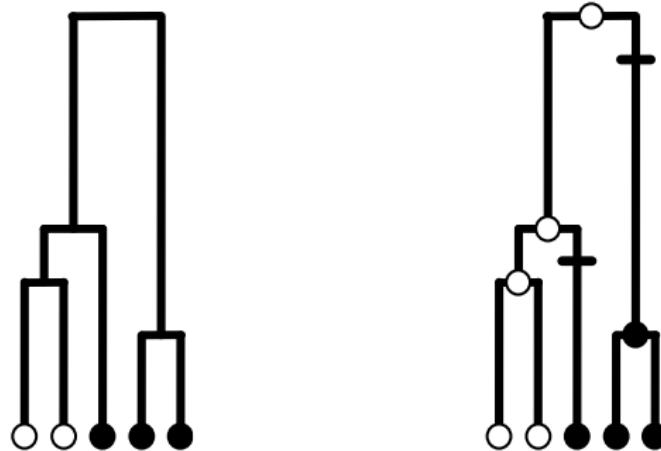
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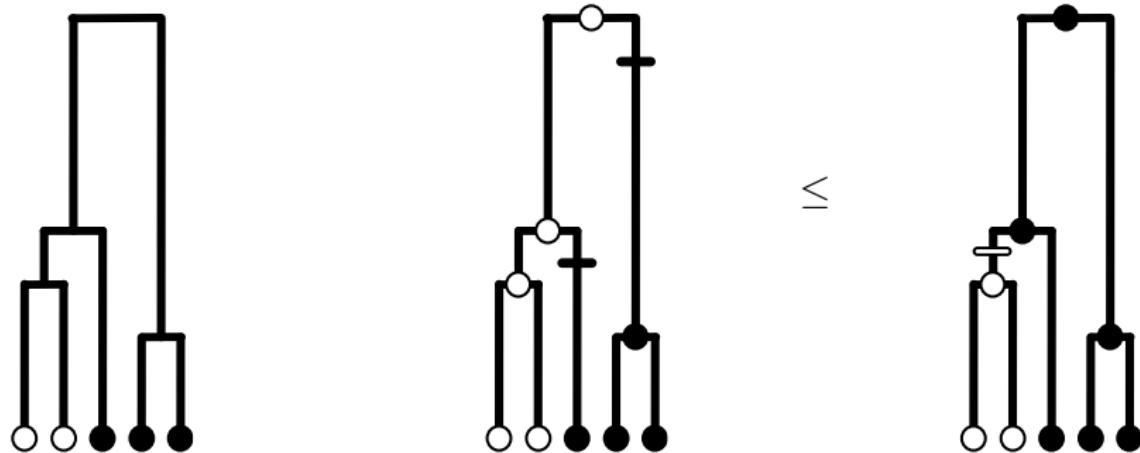
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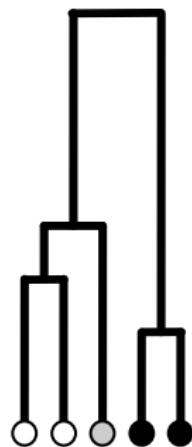
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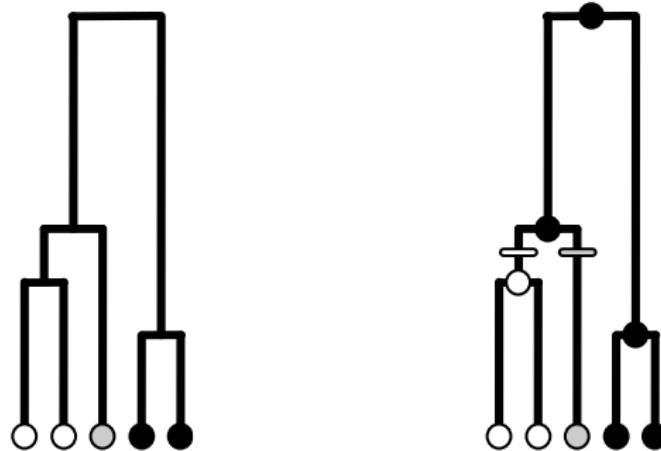
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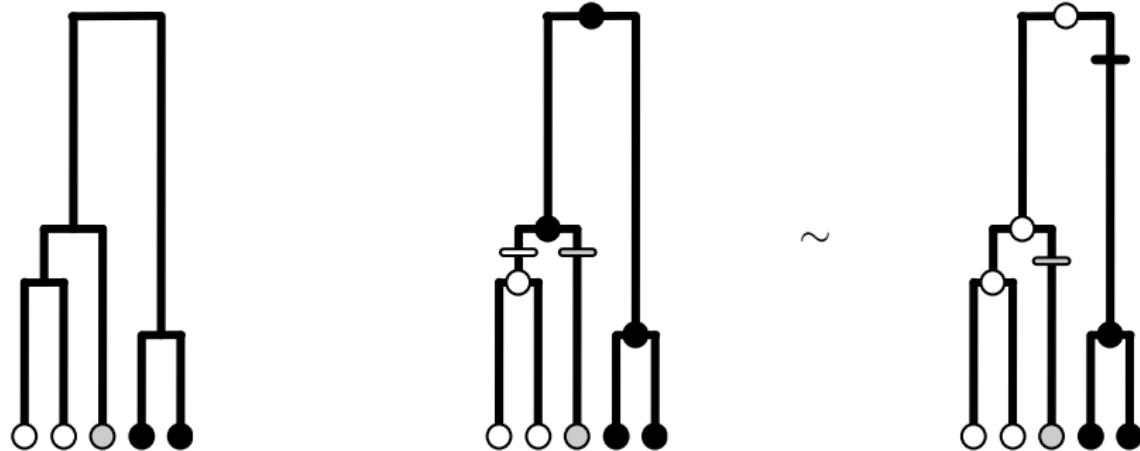
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# Equivalent Parsimonious Allocations

## Definition (Equivalency)

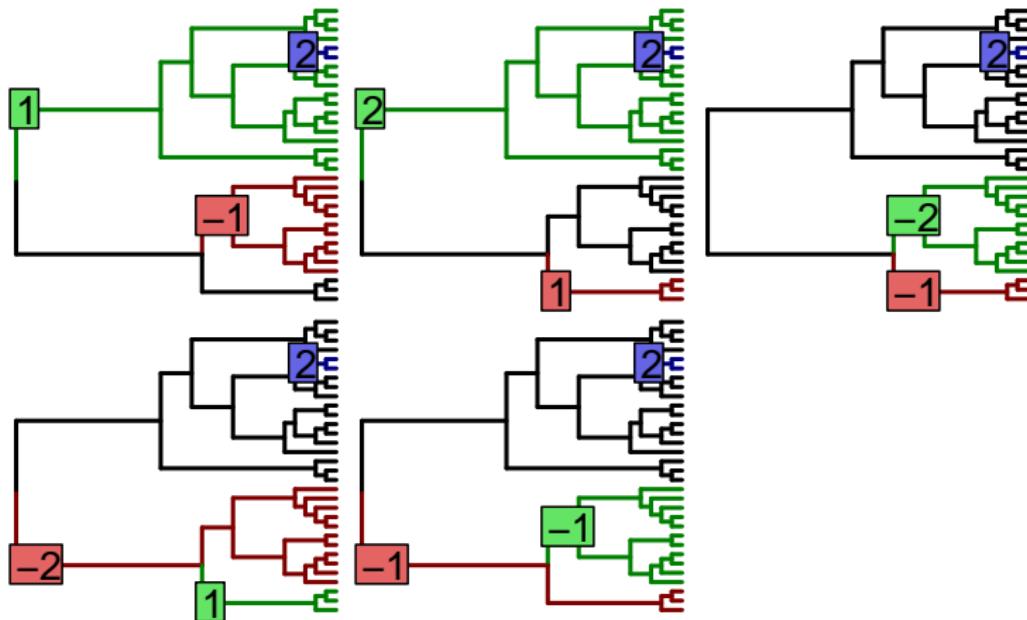
Two allocations are said to be *equivalent* (noted  $\sim$ ) if they are both parsimonious and give the same colors at the tips.

**Find one solution** Existing Dynamic Programming algorithms  
(Fitch, Sankoff, see Felsenstein, 2004).

**Enumerate all solutions** New adapted recursive algorithm  
(implemented in PhylogeneticEM).



# Equivalent Parsimonious Solutions



*Equivalent allocations and values of the shifts - BM.*

# Collection of Models

New Problem Number of Equivalence Classes:  $|\mathcal{S}_K^{PI}|$  ?

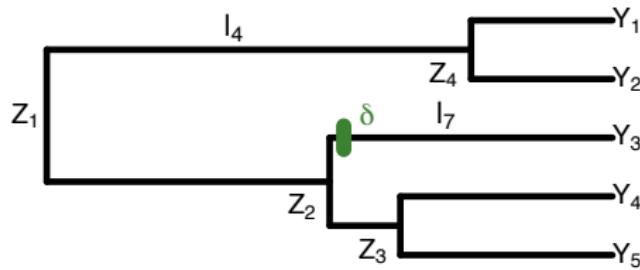
- $|\mathcal{S}_K^{PI}| \leq \binom{m+n-1}{K} = \binom{\text{\# of edges}}{\text{\# of shifts}}$
- Recursive algorithm to compute  $|\mathcal{S}_K^{PI}|$  (implemented in PhylogeneticEM).

→ Generally dependent on the topology of the tree.

- Binary tree:  $|\mathcal{S}_K^{PI}| = \binom{2n-2-K}{K} = \binom{\text{\# of edges} - \text{\# of shifts}}{\text{\# of shifts}}$

→ See convex characters: Semple and Steel (2003)

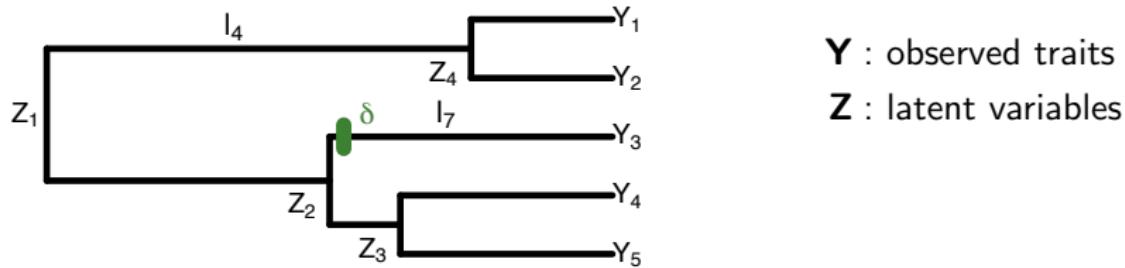
# Incomplete Data Model



**Y** : observed traits

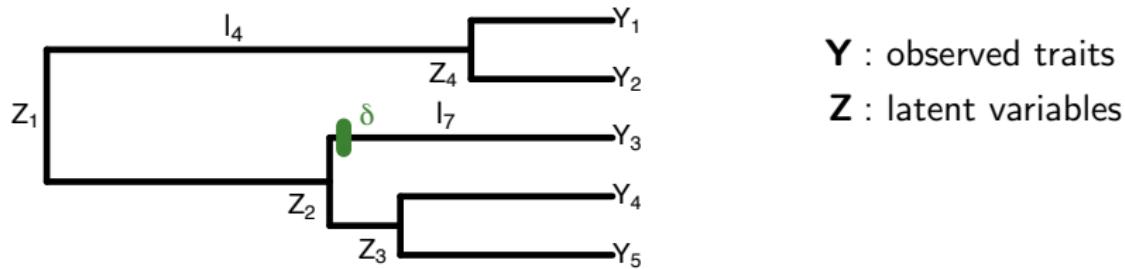
**Z** : latent variables

# Incomplete Data Model



$$\text{BM : } Z_4|Z_1 \sim \mathcal{N}(Z_1, \sigma^2 \ell_4)$$
$$Y_3|Z_2 \sim \mathcal{N}(Z_2 + \delta, \sigma^2 \ell_7)$$

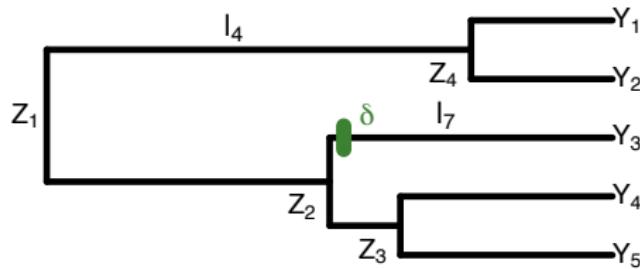
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$$p_{\theta}(\mathbf{Z}, \mathbf{Y}) = p_{\theta}(Z_1) \prod_{1 < j \leq m} p_{\theta}(Z_j | Z_{\text{parent}(j)}) \prod_{1 \leq i \leq n} p_{\theta}(Y_i | Z_{\text{parent}(i)})$$

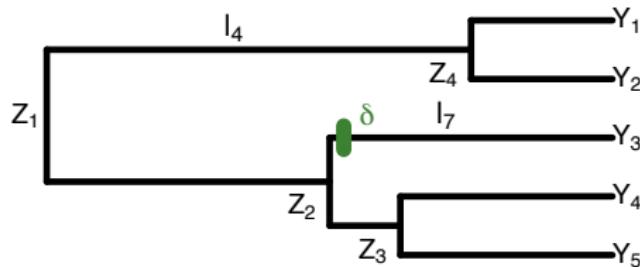
## EM Algorithm: K fixed



$$BM : Z_4 | Z_1 \sim \mathcal{N}(Z_1, \sigma^2 \ell_4)$$
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Goal:  $\hat{\theta}_K = \underset{\eta \in S_K^{PI}}{\operatorname{argmax}} p_{\hat{\theta}_\eta}(\mathbf{Y})$

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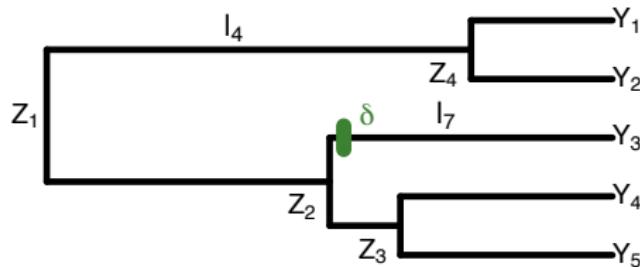


$$BM : \begin{aligned} Z_4 | Z_1 &\sim \mathcal{N}\left(Z_1, \sigma^2 \ell_4\right) \\ Y_3 | Z_2 &\sim \mathcal{N}\left(Z_2 + \delta, \sigma^2 \ell_7\right) \end{aligned}$$

Goal:  $\hat{\theta}_K = \underset{\eta \in S_K^{PI}}{\operatorname{argmax}} p_{\hat{\theta}_\eta}(\mathbf{Y})$

EM Maximize  $\log p_\theta(\mathbf{Y})$  through  $\mathbb{E}_\theta[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]$ .

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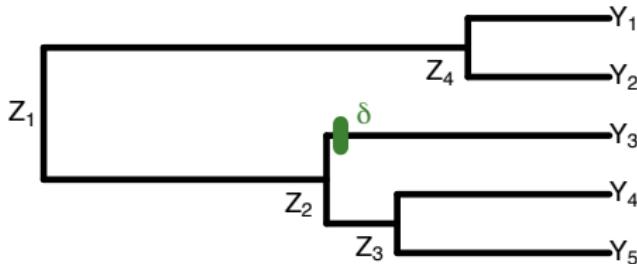
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EM Maximize  $\log p_\theta(\mathbf{Y})$  through  $\mathbb{E}_\theta[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]$ .

E step Given  $\theta^h$ , compute  $p_{\theta^h}(\mathbf{Z} | \mathbf{Y})$

M step  $\theta^{h+1} = \operatorname{argmax}_\theta \{\mathbb{E}_{\theta^h}[\log p_\theta(\mathbf{Z}, \mathbf{Y}) | \mathbf{Y}]\}$

## E step



Compute the following quantities:

$$\mathbb{E}^{(h)}[Z_j | \mathbf{Y}], \text{Var}^{(h)}[Z_j | \mathbf{Y}], \text{Cov}^{(h)}[Z_j, Z_{\text{parent}(j)} | \mathbf{Y}]$$

- Gaussian properties:  $O(n^3)$ .
- Gaussian properties + Tree structure:  $O(n)$ .  
↳ "Upward-Downward" algorithm.



# M Step

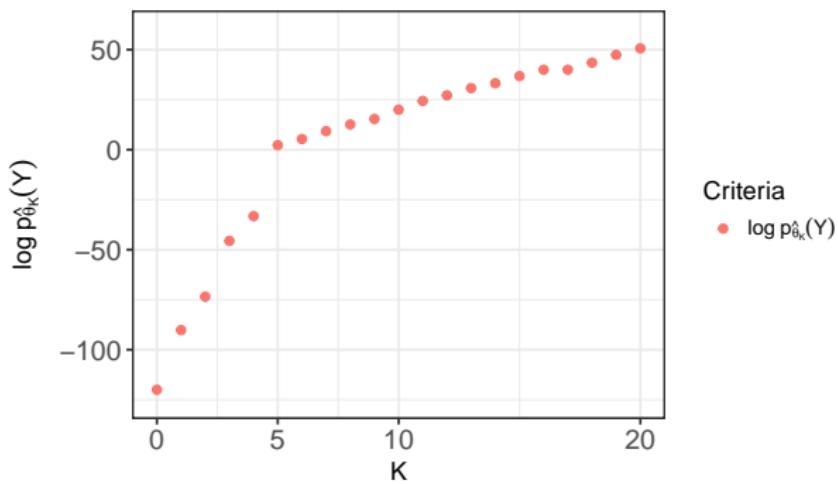
Maximize:

$$\mathbb{E} [\log p_\theta(\mathbf{Z}, \mathbf{Y}) \mid \mathbf{Y}] = - \sum_{j=2}^{m+n} C_j(\boldsymbol{\Delta}) + \mathcal{F}^{(h)}(\mu, \sigma^2)$$

- $\mu, \sigma^2$ : simple maximization
- Discrete location of  $K$  shifts
  - ↳ Exact and fast for the BM

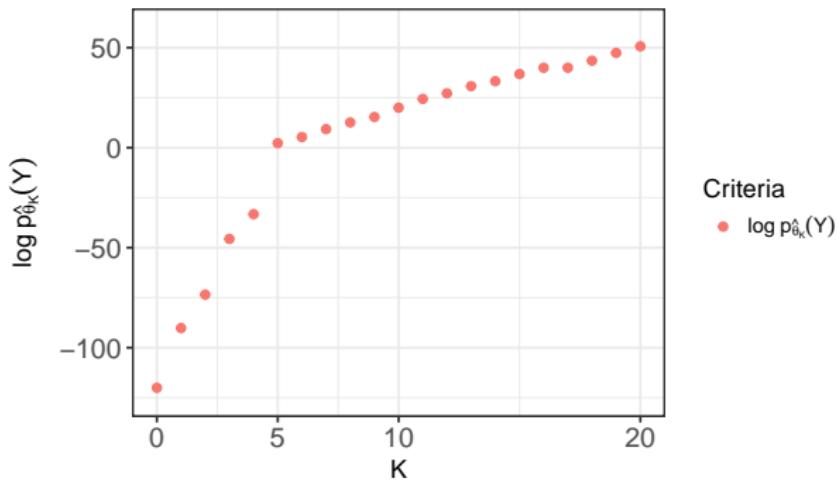


# Model Selection: Penalized Likelihood



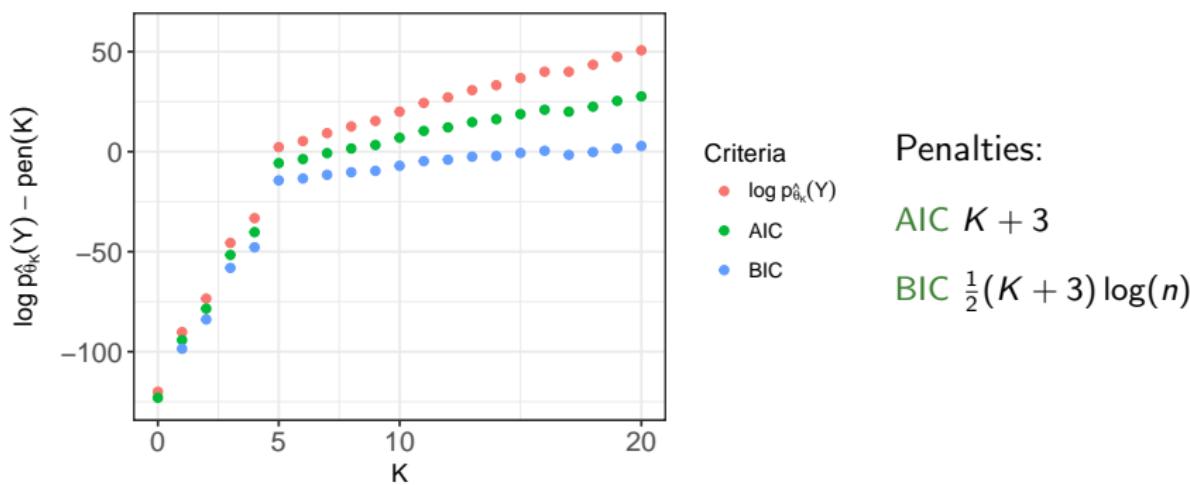
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Idea  $\hat{K} = \operatorname{argmax}_{0 \leq K \leq K_{\max}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\}$



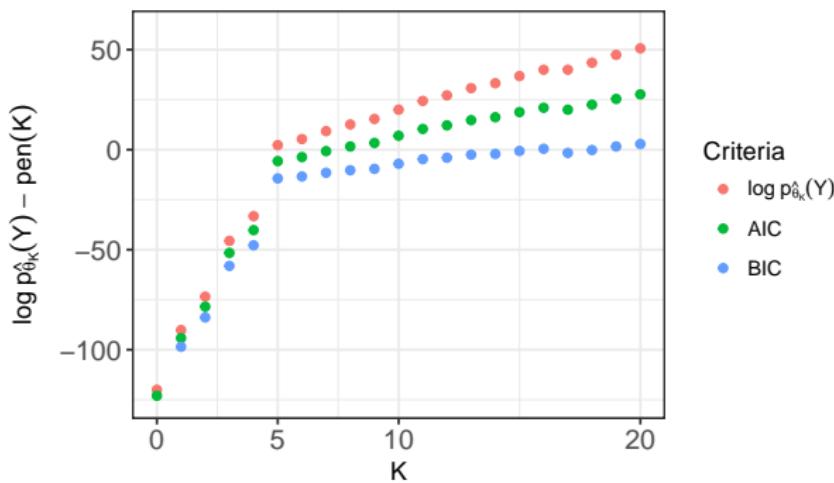
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Penalties:

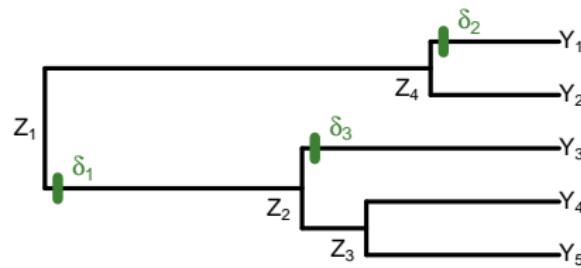
AIC  $K + 3$

BIC  $\frac{1}{2}(K + 3) \log(n)$

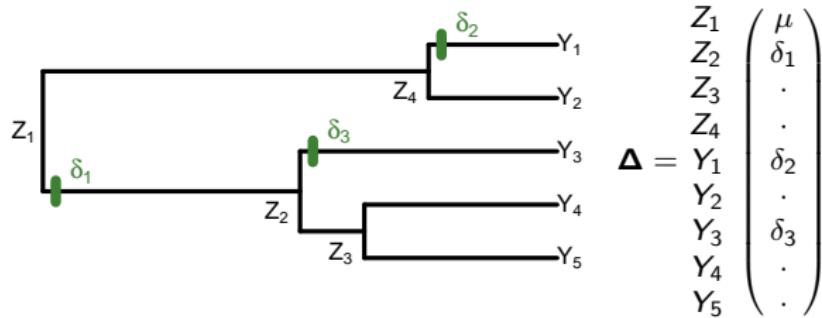
Solution

- Use  $|\mathcal{S}_K^{PI}|$ .
- Linear Regression Model.

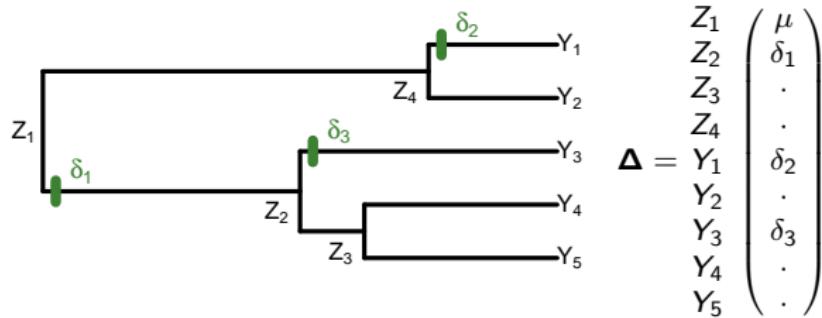
# Linear Regression Model



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$$T = \begin{pmatrix} Y_1 & Z_1 & Z_2 & Z_3 & Z_4 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 \\ Y_2 & 1 & \cdot & \cdot & 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

## Linear Regression Model

$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \delta_1 \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Y_1 & \delta_2 \\ Y_2 & \cdot \\ Y_3 & \delta_3 \\ Y_4 & \cdot \\ Y_5 & \cdot \end{pmatrix}$$
$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu + \delta_2 \\ Y_2 & \mu \\ Y_3 & \mu + \delta_1 + \delta_3 \\ Y_4 & \mu + \delta_1 \\ Y_5 & \mu + \delta_1 \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 \\ Y_1 & 1 & \cdot & \cdot & 1 & 1 & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot \\ Y_3 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_4 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

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$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu + \delta_2 \\ Y_2 & \mu \\ Y_3 & \mu + \delta_1 + \delta_3 \\ Y_4 & \mu + \delta_1 \\ Y_5 & \mu + \delta_1 \end{pmatrix}$$

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$$BM : \quad \mathbf{Y} = \mathbf{T}\Delta + \sigma \mathbf{E}^{BM}$$

$$\mathbf{E}^{BM} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$$

# Model Selection on $K$ : LINselect

## Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 + \hat{\sigma}_K^2 \operatorname{pen}(n, K, |\mathcal{S}_K^{PI}|) \right\}$$

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$$\hat{\sigma}_K^2 = \frac{\left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2}{n - K - 1}$$

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## Oracle

$$\inf_{\eta \in \bigcup_{K=0}^{p-1} \mathcal{S}_K^{PI}} \left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2$$

# Model Selection on $K$ : LINselect

## Goal

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## Oracle

$$\inf_{\eta \in \bigcup_{K=0}^{p-1} \mathcal{S}_K^{PI}} \left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2$$

### Definition (Baraud et al. (2009))

Let  $D, N > 0$ , and  $X_D \sim \chi^2(D)$ ,  $X_N \sim \chi^2(N)$ ,  $X_D \perp X_N$ .

$$\text{Dkhi}[D, N, x] = \frac{1}{\mathbb{E}[X_D]} \mathbb{E} \left[ \left( X_D - x \frac{X_N}{N} \right)_+ \right], \quad \forall x > 0$$

$$\text{Dkhi}[D, N, \text{EDkhi}[D, N, q]] = q, \quad \forall 0 < q \leq 1$$

# LINselect: Oracle Inequality

## Proposition (Form of the Penalty and guarantees)

Under our setting:  $\mathbf{Y} = \mathbf{T}\Delta + \sigma\mathbf{E}$  with  $E \sim \mathcal{N}(0, \mathbf{V})$ , define the penalty:

$$\text{pen}(K) = A \frac{n - K - 1}{n - K - 2} \text{EDkhi} \left[ K + 2, n - K - 2, \exp \left( -\log \left| S_K^{PI} \right| - 2 \log(K + 2) \right) \right]$$

If  $\kappa < 1$ , and  $p \leq \min \left( \frac{\kappa n}{2 + \log(2) + \log(n)}, n - 7 \right)$ , we get:

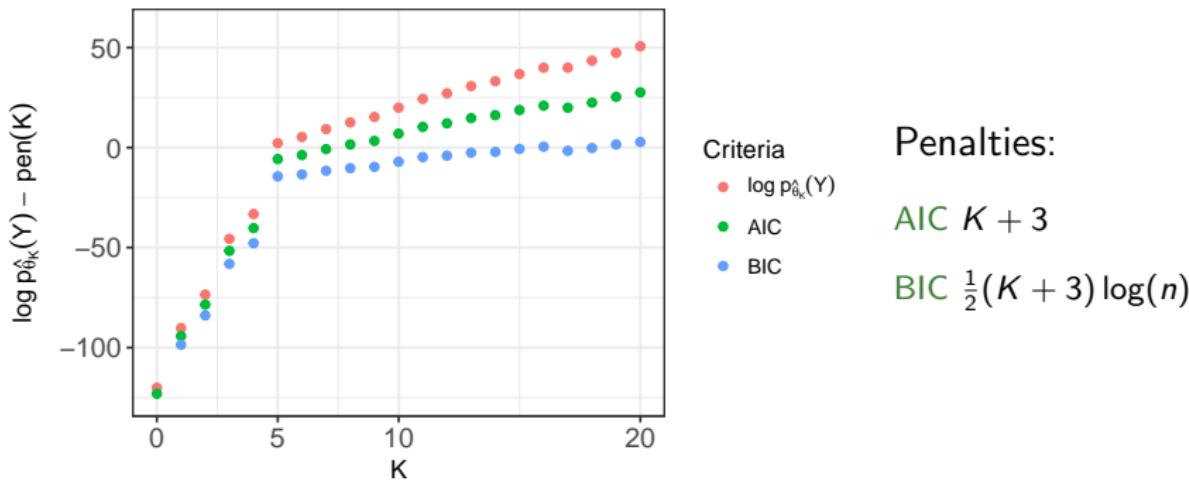
$$\mathbb{E} \left[ \frac{\left\| \mathbb{E}[\mathbf{Y}] - \hat{\mathbf{Y}}_{\hat{K}} \right\|_{\mathbf{V}^{-1}}^2}{\sigma^2} \right] \leq C(A, \kappa) \inf_{\eta \in \mathcal{M}} \left\{ \frac{\left\| \mathbb{E}[\mathbf{Y}] - \mathbf{Y}_{\eta}^* \right\|_{\mathbf{V}^{-1}}^2}{\sigma^2} + (K_{\eta} + 2)(3 + \log(n)) \right\}$$

with  $C(A, \kappa)$  a constant depending on  $A$  and  $\kappa$  only.

Based on Baraud et al. (2009) 

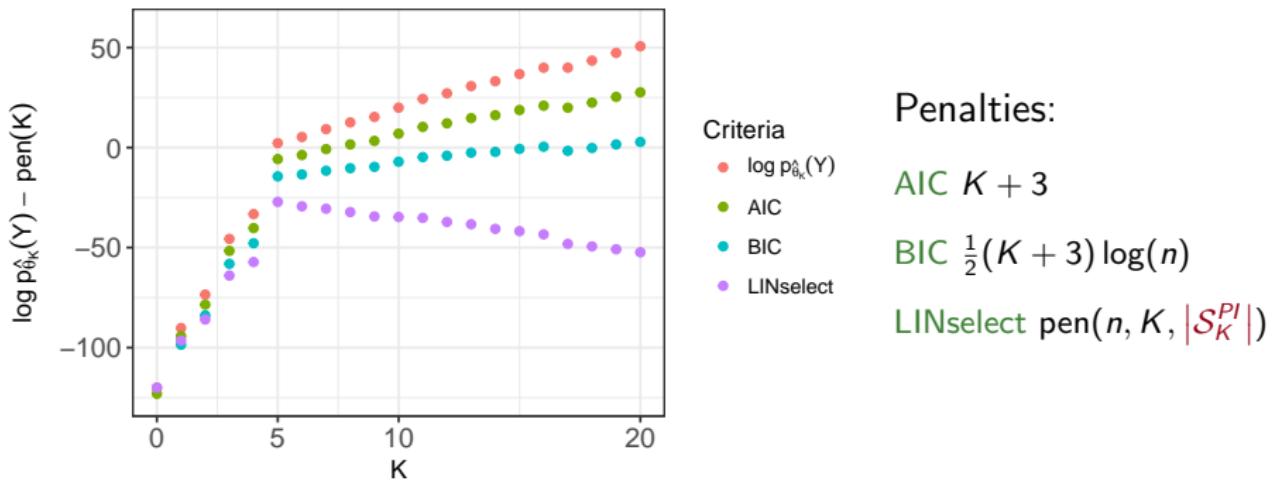
# Model Selection: Penalized Likelihood

Idea  $\hat{K} = \operatorname{argmax}_{0 \leq K \leq K_{\max}} \left\{ \log p_{\hat{\theta}_K}(\mathbf{Y}) - \text{pen}(K) \right\}$



## Model Selection: Penalized Likelihood

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## LINselect Model Selection: Important Points

Based on Baraud, Giraud, and Huet (2009)

- Non-asymptotic bound.
- Unknown variance.
- No constant to be calibrated.

Note

- Non iid variance.
- Penalty depends on the tree topology (through  $|\mathcal{S}_K^{PI}|$ ).

# LASSO Regression

Lasso regression:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y - T\Delta\|_{V^{-1}}^2 + \lambda \|\Delta\|_1 \right\}$$

# LASSO Regression

Lasso regression:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y - T\Delta\|_{V^{-1}}^2 + \lambda \|\Delta\|_1 \right\}$$

Initialization: For  $K$  fixed

- Choose  $\lambda$  to get  $K$  shifts
- Estimate  $\Delta$  with a Gauss Lasso



# New World Monkey Dataset



We have:

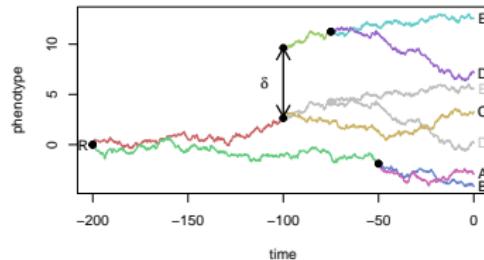
- A model of trait evolution
- A way to assess identifiability
- An inference strategy (EM + LINselect)

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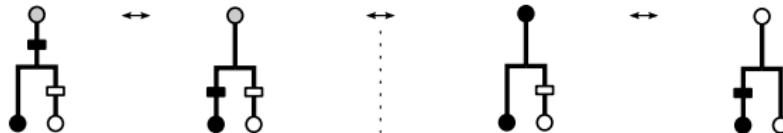


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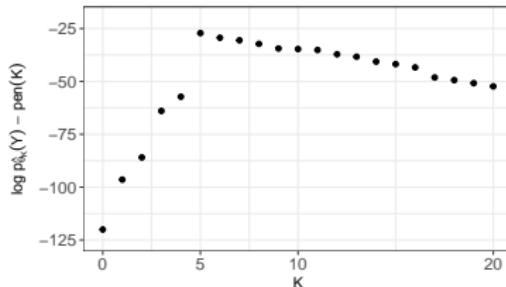


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But...

- The BM is not realistic in many cases.
  - No selection.
  - Unbounded variance.

↪ Use the Ornstein-Uhlenbeck instead.

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# Outline

① Shifted BM on a Tree

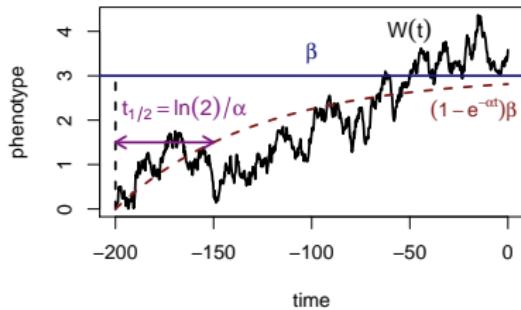
② Shifted OU on a Tree

- Ornstein-Uhlenbeck
- Re-scaling

③ Multivariate Trait

## Ornstein-Uhlenbeck Modeling

(Hansen, 1997)



$$dW(t) = \alpha[\beta - W(t)]dt + \sigma dB(t)$$

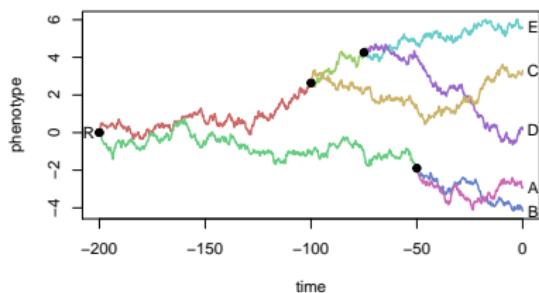
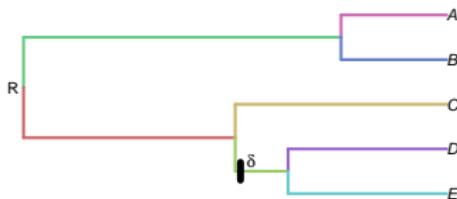
## Deterministic part:

- $\beta$ : primary optimum (mechanistically defined).
- $\ln(2)/\alpha$ : phylogenetic half live.

## Stochastic part:

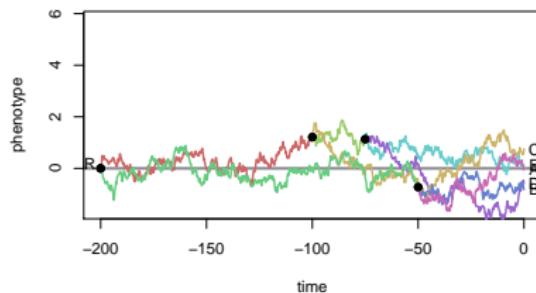
- $W(t)$ : trait value (actual optimum).
- $\sigma dB(t)$ : Brownian fluctuations.

# Shifts



**BM Shifts in the mean:**

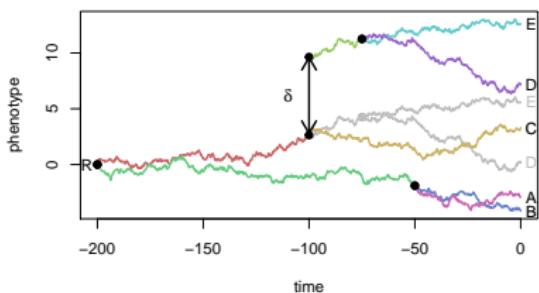
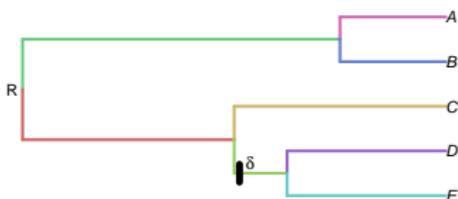
$$m_{\text{child}} = m_{\text{parent}} + \delta$$



**OU Shifts in the optimal value:**

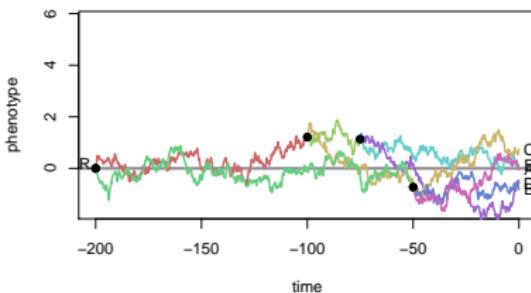
$$\beta_{\text{child}} = \beta_{\text{parent}} + \delta$$

# Shifts



## BM Shifts in the mean:

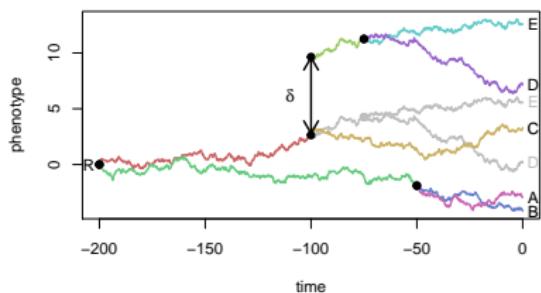
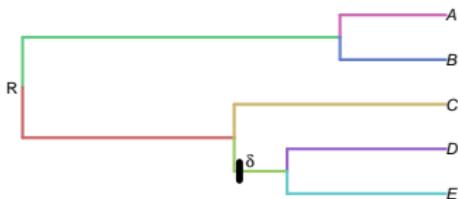
$$m_{\text{child}} = m_{\text{parent}} + \delta$$



### OU Shifts in the **optimal value**:

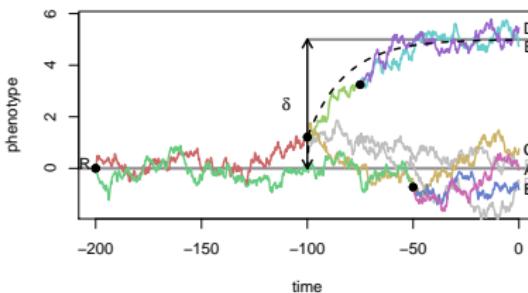
$$\beta_{\text{child}} = \beta_{\text{parent}} + \delta$$

# Shifts



**BM Shifts in the mean:**

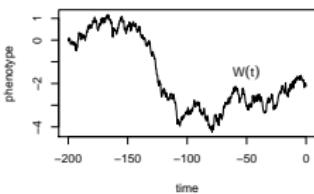
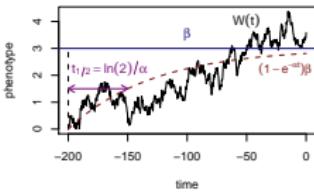
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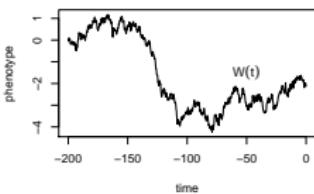
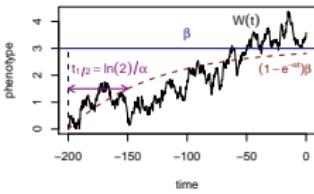
**OU Shifts in the optimal value:**

$$\beta_{\text{child}} = \beta_{\text{parent}} + \delta$$

## BM vs OU

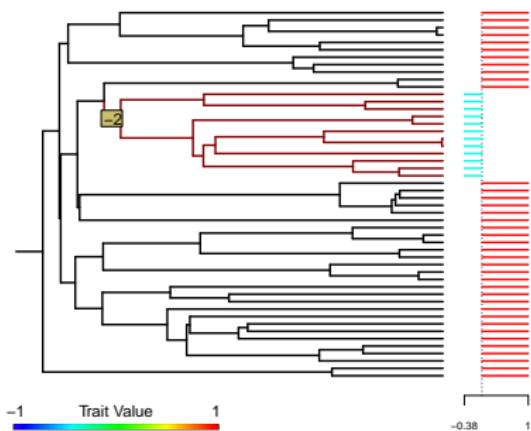
Equation	Stationary State	$\text{Cov}[Y_i; Y_j]$
	$dW(t) = \sigma dB(t)$	None.
	$dW(t) = \sigma dB(t) + \alpha[\beta - W(t)]dt$	$\begin{cases} \mu = \beta \\ \gamma^2 = \frac{\sigma^2}{2\alpha} \end{cases} \quad \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1) \times \sigma^2$

## BM vs OU

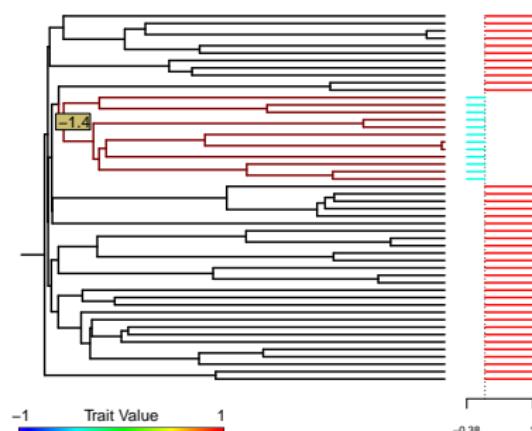
Equation	Stationary State	$\text{Cov}[Y_i; Y_j]$
 <p><math>dW(t) = \sigma dB(t)</math></p>	None.	$t_{ij} \times \sigma^2$
 <p><math>dW(t) = \sigma dB(t) + \alpha[\beta - W(t)]dt</math></p>	$\begin{cases} \mu = \beta \\ \gamma^2 = \frac{\sigma^2}{2\alpha} \end{cases}$ $\underbrace{\frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1)}_{t'_{ij}(\alpha)} \times \sigma^2$	

OU  $\iff$  BM

OU  $\iff$  BM on a re-scaled tree with  $t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$



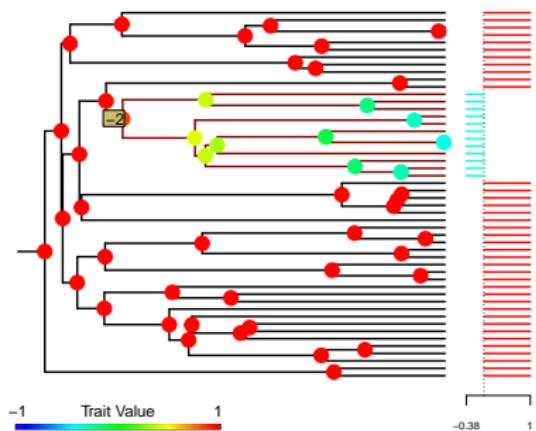
Original tree.



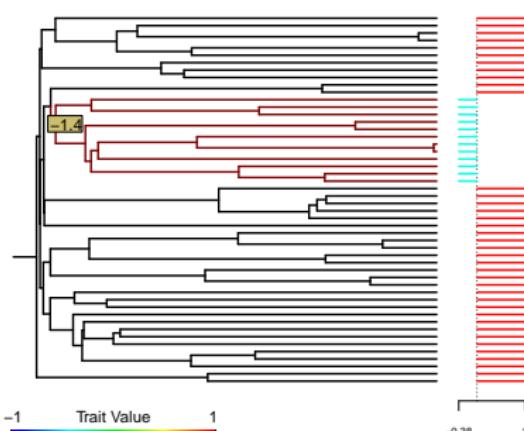
Re-scaled tree.

OU  $\iff$  BM

$$\text{OU} \iff \text{BM on a re-scaled tree with } t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$$



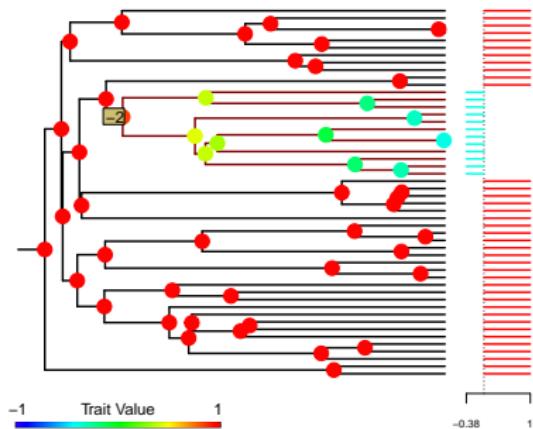
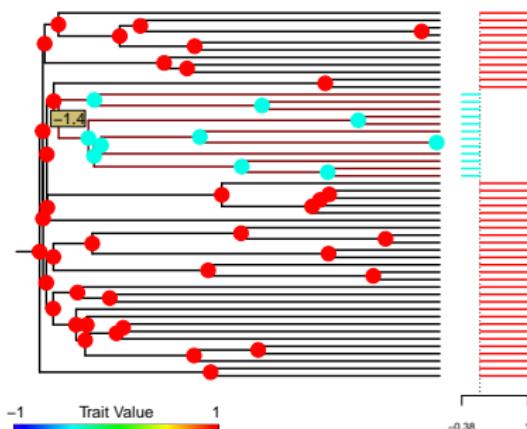
OU:  $\beta_0 = \mu = 1$  and  $t_{1/2} = 0.5$



Re-scaled tree.

OU  $\iff$  BM

OU  $\iff$  BM on a re-scaled tree with  $t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$

OU:  $\beta_0 = \mu = 1$  and  $t_{1/2} = 0.5$ 

Re-scaled tree, equivalent BM.

OU  $\iff$  BM

$$\text{OU} \iff \text{BM on a re-scaled tree with } t' = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t} - 1)$$

### Remarks:

- This only works for an *ultrametric* tree.
- The laws of the internal nodes is changed.
- This is **not** the following standard time transformation

$$X_t = X_0 e^{-\alpha t} + \beta(1 - e^{-\alpha t}) + \frac{\sigma}{\sqrt{2\alpha}} e^{-\alpha t} B_{e^{2\alpha t} - 1}$$

to get the BM solution of the OU.

# New World Monkey Dataset



We have:

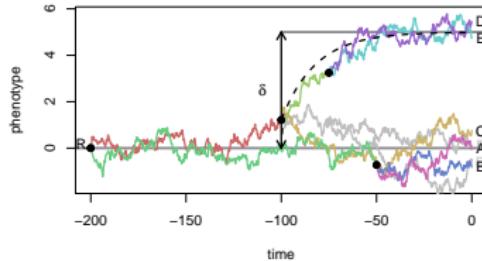
- A better model of trait evolution.
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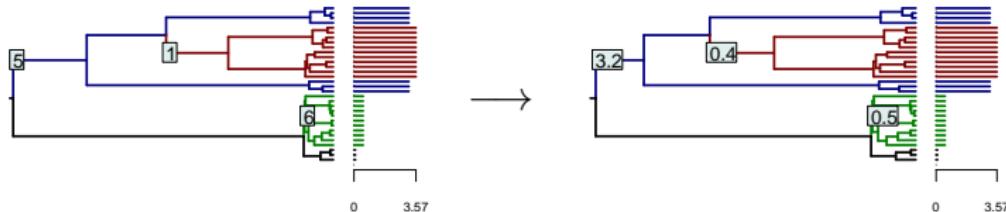


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OU Groups are means, not regimes

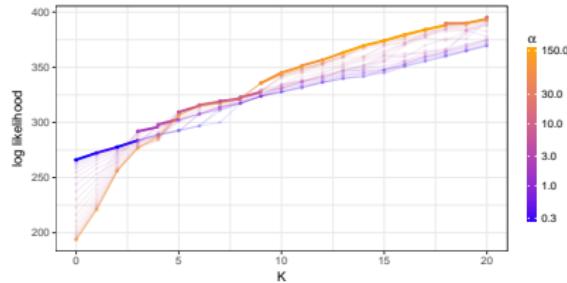
Defined from the equivalent BM

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# New World Monkey Dataset



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But...

- Brains are multivariate.

# Outline

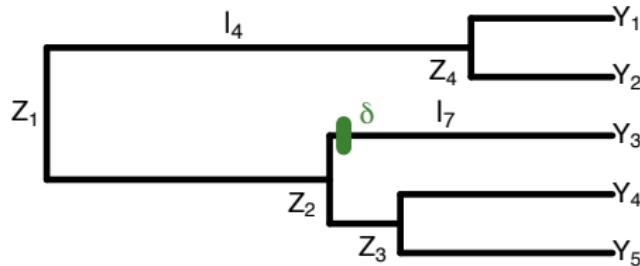
① Shifted BM on a Tree

② Shifted OU on a Tree

③ Multivariate Trait

- Multivariate BM
- Multivariate OU
- Results

# Multivariate BM



Data Vectors of  $p$  traits:

$$\mathbf{Y}_i^T = (Y_{i1}, \dots, Y_{ip})$$

Shifts  $\delta$  vector size  $p$ .

→ All traits shift together.

## Incomplete Data Representation

$$\mathbf{Y}_3 | \mathbf{Z}_2 \sim \mathcal{N}(\mathbf{Z}_2 + \delta, \ell_7 \mathbf{R})$$

## Linear Model Representation

$$\mathbf{Y} = \mathbf{T}\Delta + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{MN}_{n \times p}(\mathbf{0}, \mathbf{V}, \mathbf{R})$$

# Model Selection

$$\mathbf{Y} = \mathbf{T}\Delta + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{MN}_{n \times p}(\mathbf{0}, \mathbf{V}, \mathbf{R})$$

**Problem:** Can we do Model Selection when  $\mathbf{R}$  is unknown ?

# Model Selection

$$\mathbf{Y} = \mathbf{T}\Delta + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{MN}_{n \times p}(\mathbf{0}, \mathbf{V}, \mathbf{R})$$

**Problem:** Can we do Model Selection when  $\mathbf{R}$  is unknown ?

- Slope Heuristic based method

$$\text{vec}(\mathbf{Y}) = (\mathbf{I}_p \otimes \mathbf{T}) \text{vec}(\Delta) + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{R} \otimes \mathbf{V})$$

- Massart (2007)
  - oracle inequality with **known variance**
  - penalty up to a **multiplicative constant**
- Baudry et al. (2012)
  - Slope-heuristic method to **calibrate the constant**
  - Implemented in `capushe` (Brault et al., 2012)

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→ Does not work well in practice.

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  - ↪ Independant traits only.

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  - ↪ Independant traits only.
- LINselect-based method
  - ↪ Idea: ML = LSQ for  $\hat{\Delta}$

# Model Selection: LINselect

$$\mathbf{Y} = \mathbf{T}\Delta + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{V})$$

Projectors

$$\hat{\mathbf{Y}}_\eta = \text{Proj}_{S_\eta}^{\mathbf{V}}(\mathbf{Y})$$

EM Estimators

$$\hat{\mathbf{Y}}_K = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \left\| \mathbf{Y} - \hat{\mathbf{Y}}_\eta \right\|_{\mathbf{V}^{-1}}^2$$

Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

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## Projectors

$$\hat{\mathbf{Y}}_\eta = \left( \text{Proj}_{S_\eta}^{\mathbf{V}}(\mathbf{Y}_1) \cdots \text{Proj}_{S_\eta}^{\mathbf{V}}(\mathbf{Y}_p) \right) \quad \text{Independent !}$$

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## EM Estimators

$$\hat{\mathbf{Y}}_K = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \sum_{I=1}^p \left\| \mathbf{Y}_I - [\hat{\mathbf{Y}}_\eta]_I \right\|_{\mathbf{V}^{-1}}^2 = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \left\| \mathbf{Y} - \hat{\mathbf{Y}}_\eta \right\|_{F, \mathbf{V}^{-1}}^2$$

## Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{\mathbf{V}^{-1}}^2 \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

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$$\hat{\mathbf{Y}}_K = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \sum_{I=1}^p \left\| \mathbf{Y}_I - [\hat{\mathbf{Y}}_\eta]_I \right\|_{\mathbf{V}^{-1}}^2 = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \left\| \mathbf{Y} - \hat{\mathbf{Y}}_\eta \right\|_{F, \mathbf{V}^{-1}}^2$$

## Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \left\| \mathbf{Y} - \hat{\mathbf{Y}}_K \right\|_{F, \mathbf{V}^{-1}}^2 \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

# Model Selection: LINselect

$$\mathbf{Y} = \mathbf{T}\boldsymbol{\Delta} + \mathbf{E} \text{ with } \mathbf{E} \sim \mathcal{MN}_{n \times p}(\mathbf{0}, \mathbf{V}, \mathbf{R})$$

## Projectors

$$\hat{\mathbf{Y}}_\eta = \left( \text{Proj}_{S_\eta}^{\mathbf{V}}(\mathbf{Y}_1) \cdots \text{Proj}_{S_\eta}^{\mathbf{V}}(\mathbf{Y}_p) \right) \quad \text{Independent !}$$

## EM Estimators

$$\hat{\mathbf{Y}}_K = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \sum_{l=1}^p \left\| \mathbf{Y}_l - [\hat{\mathbf{Y}}_\eta]_l \right\|_{\mathbf{V}^{-1}}^2 = \underset{\eta \in \mathcal{S}_K^{PI}}{\operatorname{argmin}} \left\| \mathbf{Y} - \hat{\mathbf{Y}}_\eta \right\|_{F, \mathbf{V}^{-1}}^2$$

## Goal

$$\hat{K} = \underset{0 \leq K \leq K_{\max}}{\operatorname{argmin}} \left\{ \text{tr}(\hat{\mathbf{R}}_K) \left( 1 + \frac{\text{pen}(n, K, |\mathcal{S}_K^{PI}|)}{n - K - 1} \right) \right\}$$

# Multivariate OU

$$\text{SDE} \quad d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \boldsymbol{\beta}(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

Good Case  $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  must commute

- $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  diagonal  $\rightarrow$  independent traits
  - $\rightarrow$  Brownian motion (BM) for each trait
  - $\rightarrow$  no correlation between traits
  - $\rightarrow$  no shared information between traits
  - $\rightarrow$  no shared information between traits
- $\mathbf{A} = \alpha I_p$  scalar and  $\boldsymbol{\Sigma}$  full  $\rightarrow$  scOU
  - $\rightarrow$  Brownian motion with shared variance

# Multivariate OU

$$\text{SDE} \quad d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}dB_t$$

Good Case  $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  must commute

- $\mathbf{A}$  and  $\boldsymbol{\Sigma}$  diagonal  $\rightarrow$  independent traits
  - Ingram and Mahler (2013); Khabbazian et al. (2016)
  - Justification: de-correlate the traits with a pPCA
  - ✗ With shifts: not justified
- $\mathbf{A} = \alpha I_p$  scalar and  $\boldsymbol{\Sigma}$  full  $\rightarrow$  scOU
  - Same tree re-scaling trick  $\rightarrow$  BM

# Multivariate OU

SDE       $d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \Sigma dB_t$

Good Case  $\mathbf{A}$  and  $\Sigma$  must commute

- $\mathbf{A}$  and  $\Sigma$  diagonal  $\rightarrow$  independent traits
  - ↳ Ingram and Mahler (2013); Khabbazian et al. (2016)
  - ↳ Justification: de-correlate the traits with a pPCA
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- $\mathbf{A} = \alpha I_p$  scalar and  $\Sigma$  full  $\rightarrow$  scOU
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# Multivariate OU

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# Multivariate OU

SDE       $d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \Sigma dB_t$

Good Case  $\mathbf{A}$  and  $\Sigma$  must commute

- $\mathbf{A}$  and  $\Sigma$  diagonal  $\rightarrow$  independent traits
  - ↪ Ingram and Mahler (2013); Khabbazian et al. (2016)
  - ↪ Justification: de-correlate the traits with a pPCA
  - ✗ With shifts: not justified
- $\mathbf{A} = \alpha I_p$  scalar and  $\Sigma$  full  $\rightarrow$  scOU
  - ↪ Same tree re-scaling trick  $\rightarrow$  BM



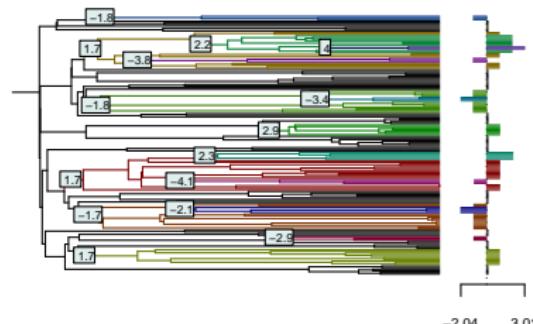
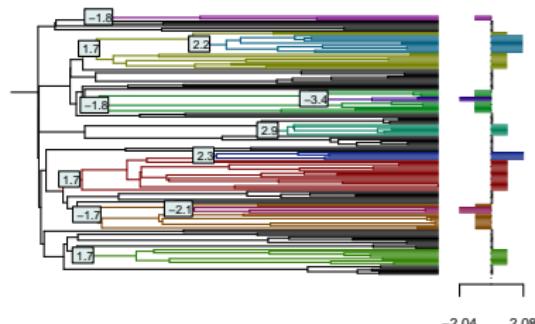
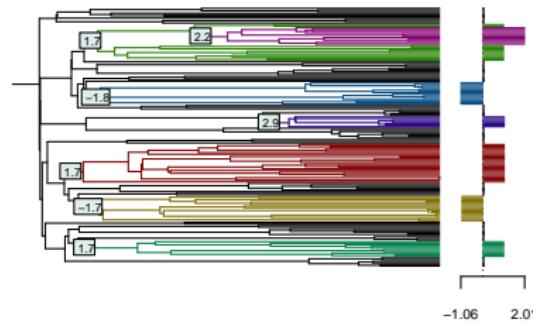
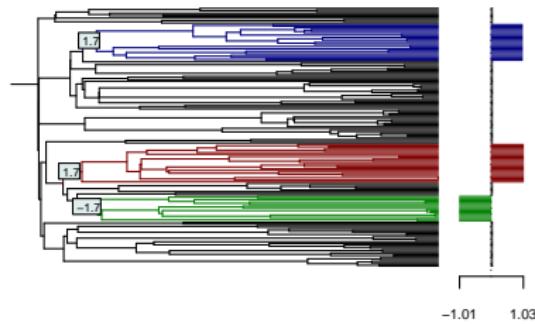
# Multivariate OU

SDE       $d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \Sigma dB_t$

Good Case  $\mathbf{A}$  and  $\Sigma$  must commute

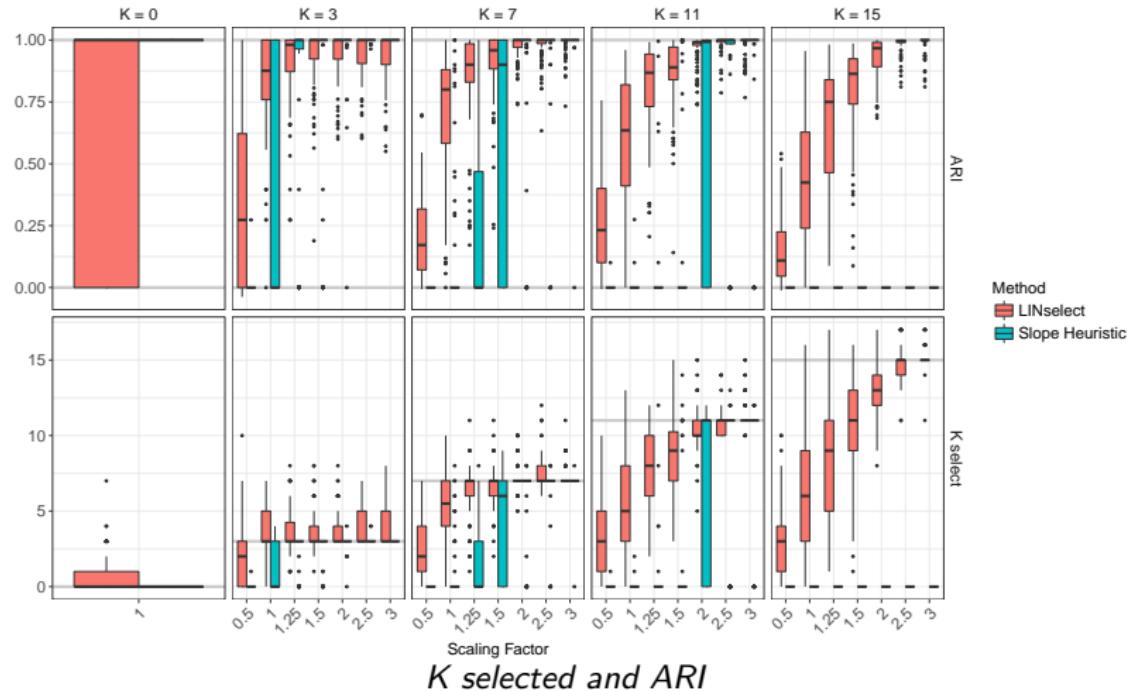
- $\mathbf{A}$  and  $\Sigma$  diagonal  $\rightarrow$  independent traits
  - ↳ Ingram and Mahler (2013); Khabbazian et al. (2016)
  - ↳ Justification: de-correlate the traits with a pPCA
  - ✗ With shifts: not justified
- $\mathbf{A} = \alpha I_p$  scalar and  $\Sigma$  full  $\rightarrow$  scOU
  - ↳ Same tree re-scaling trick  $\rightarrow$  BM

# Simulations: Experimental Design

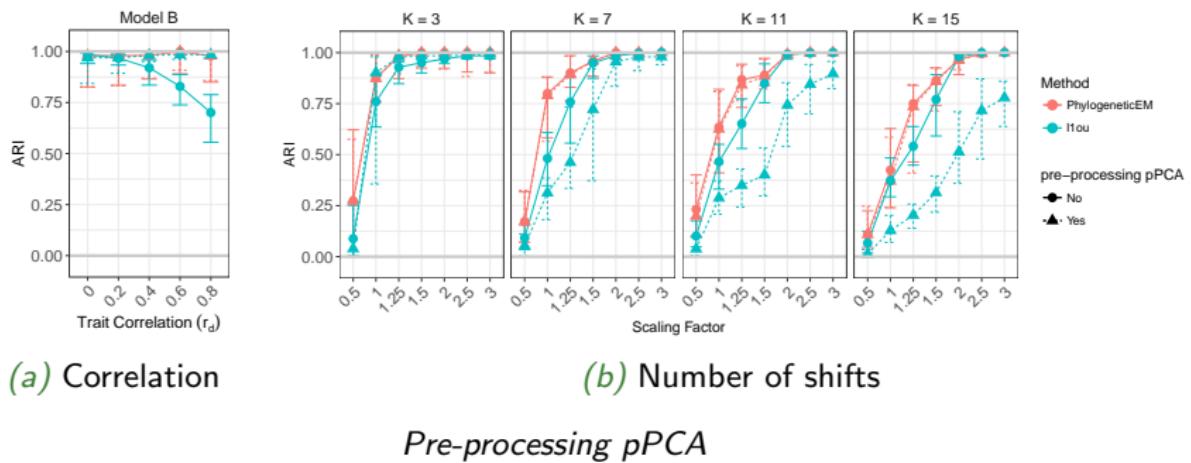


Tree Used

# Simulations: Model Selection

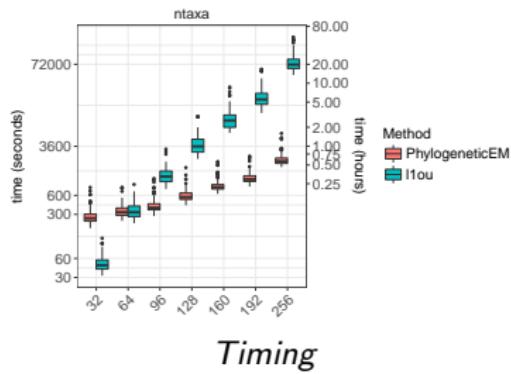
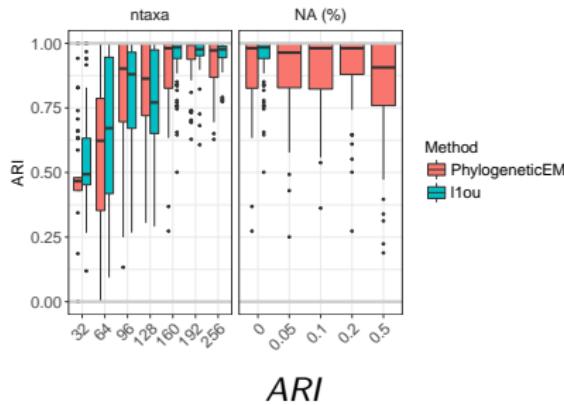


# Simulations: pPCA



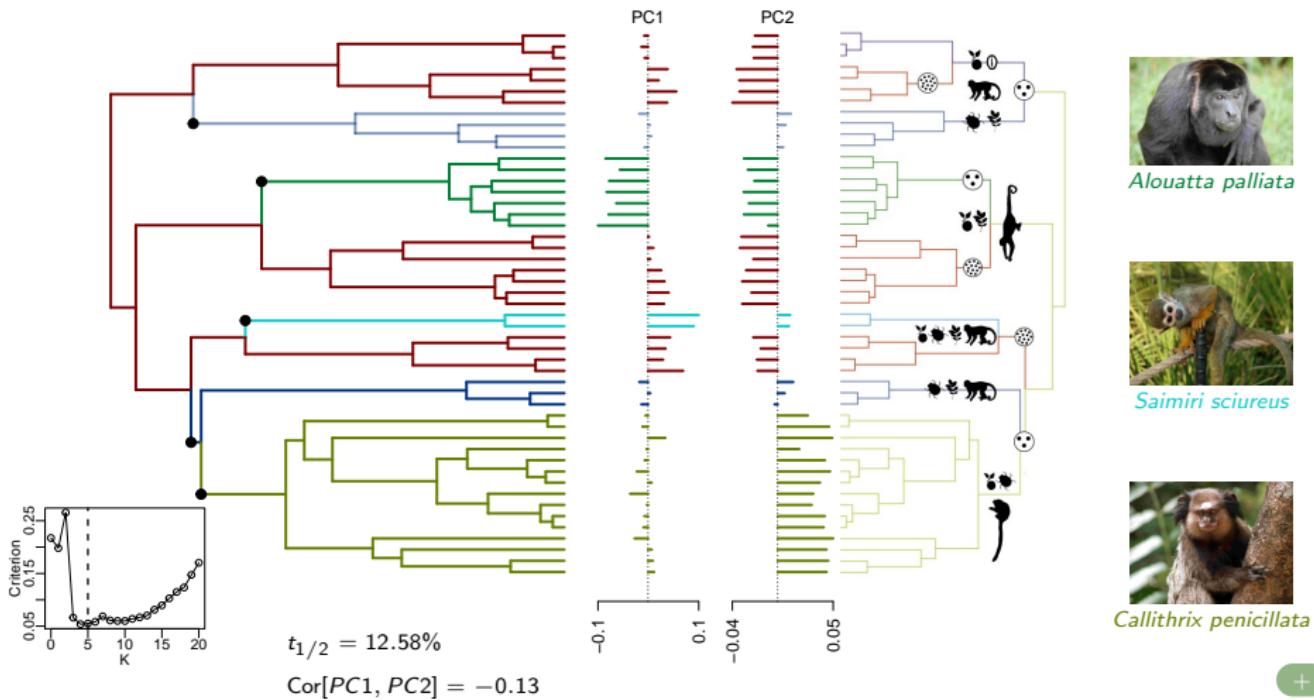
*Pre-processing pPCA*

# Simulations: Scalability



## New World Monkeys

(Aristide et al., 2016)



# Contributions

## Statistical Inference, Univariate

**Bastide**, Mariadassou, Robin (2017). Detection of adaptive shifts on phylogenies by using shifted stochastic processes on a tree. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 79(4), 1067–1093.

## Multivariate

**Bastide**, Ané, Robin, Mariadassou (2017). Inference of Adaptive Shifts for Multivariate Correlated Traits. *Systematic Biology, under minor revisions*.

## R package

- PhylogeneticEM, available on the CRAN.
  - ↳ Univariate and multivariate.
  - ↳ Rcpp, continuous integration, unitary tests, online doc.
  - ↳ GitHub: <https://github.com/pbastide/PhylogeneticEM>

# Conclusion and Perspectives

A general inference framework for trait evolution models.

## Literature

- **Model:** Felsenstein (1985); Butler and King (2004).
- **Shift detection:** Ingram and Mahler (2013); Uyeda and Harmon (2014); Khabbazian et al. (2016).

## Contributions

- **Univariate:** Identifiability, EM, Model selection.
- **Multivariate:** OU with correlations.

## Perspectives

- Deal with uncertainty (data, tree).
- Non-ultrametric trees (fossils).
- Patterns in missing data.
- Phylogenetic Networks.



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  - Braboowi at the English language Wikipedia, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=7069103>
  - Xiphophorus Genetic Stock Center, Texas State University, <http://www.xiphophorus.txstate.edu/resources/galleries/comprehensive.html>

Thank you for listening



[pbastide.github.io](https://pbastide.github.io)

# Appendices

## ④ BM on a Network

- Model
- Test for Transgressive Evolution (TE)
- Example

## ⑤ Identifiability Issues

- Cardinal of Equivalence Classes
- Number of Tree Compatible Clustering

## ⑥ Inference

- Initialization
- Upward-Downward Algorithm
- Segmentation Algorithms
- Model Selection

## ⑦ Multivariate Modeling

- Phylogenetic PCA
- Scalar OU

## ⑧ Tests for Transgressive Evolution

## ⑨ Simulations Univariate

## ⑩ Simulations Multivariate

## ⑪ Monkey Dataset

## ⑫ Extensions

- Measurement Error and Factor Analysis
- Tree Misspecification
- Non-Ultrametric Trees
- Patterns in Missing Data

# Xiphophorus Fish Dataset

(Cui et al., 2013)



*X. Montezumae*

# Xiphophorus Fish Dataset

(Cui et al., 2013)



*X. Montezumae*

## Two traits

- Sword index
- Female preference

# Xiphophorus Fish Dataset

(Cui et al., 2013)



*X. Montezumae*

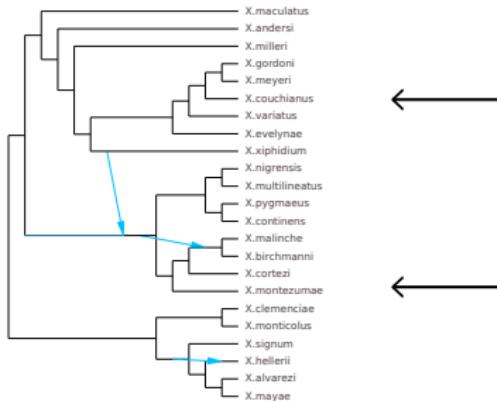
## Two traits

- Sword index
- Female preference

Problem There are hybrids !

# Phylogenetic “Networks”

(Solís-Lemus and Ané, 2016)



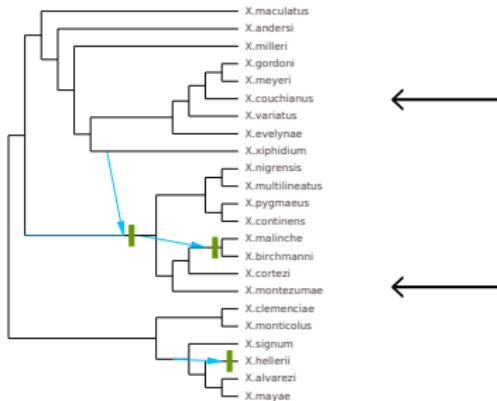
*X. Couchianus*



*X. Montezumae*

# Phylogenetic “Networks”

(Solís-Lemus and Ané, 2016)



*X. Couchianus*

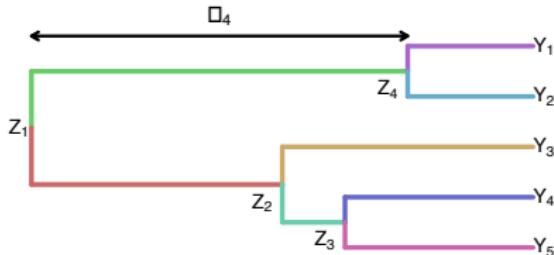


*X. Montezumae*

Question:

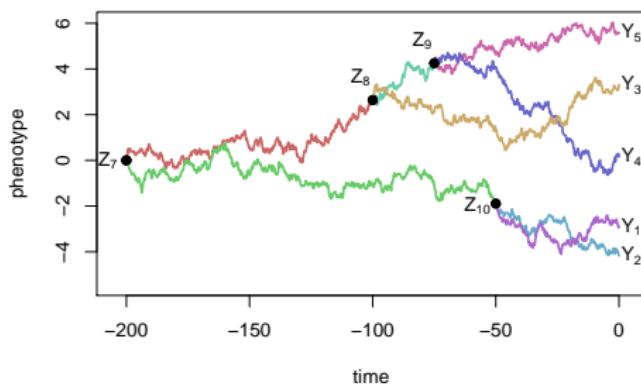
- Can we see the effects of ancestral transgressive evolution ?

# Shifted BM on a Network



Known network.

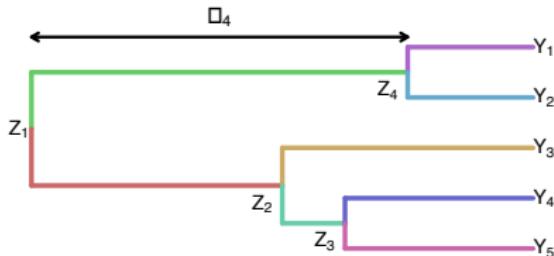
Only tip values observed.



Brownian Motion:

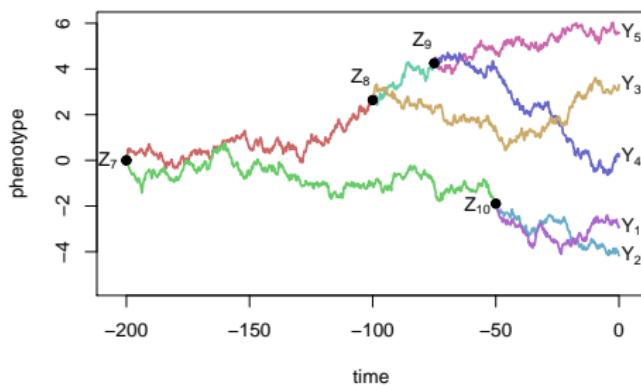
$$\text{Cov}[Y_1; Y_2] = \sigma^2 \ell_4$$

# Shifted BM on a Network



Known network.

Only tip values observed.

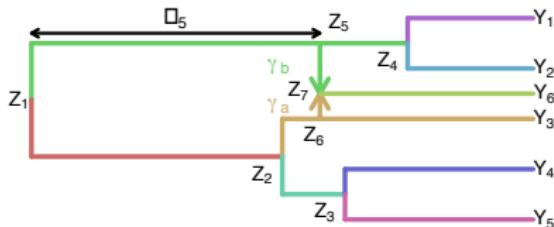


Brownian Motion:

$$V_{ij}^{\text{tree}} = \sum_{e \in p_i \cap p_j} \ell_e$$

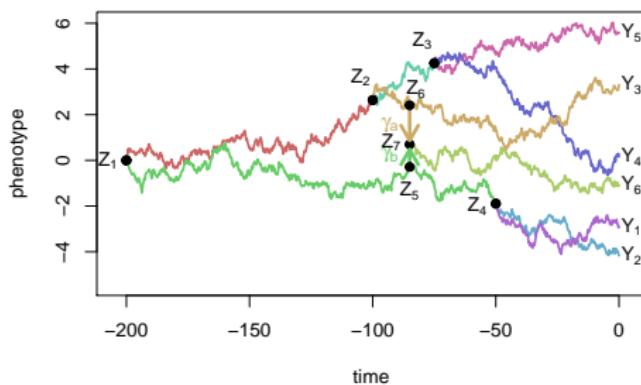
Sum over shared edges.  
 $p_i$ : path from root to tip  $i$

# Shifted BM on a Network



Known network.

Only tip values observed.

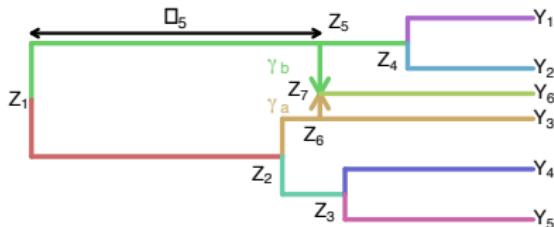


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5$$

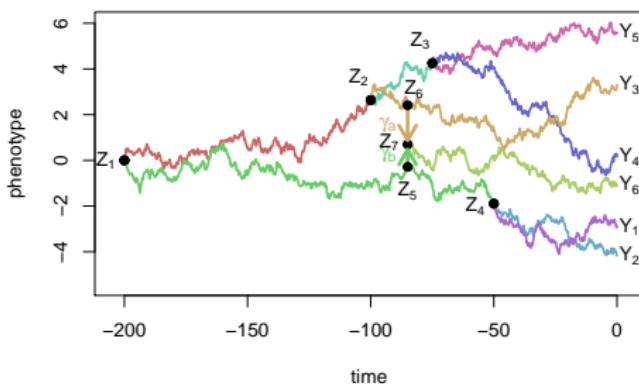
$$\gamma_a + \gamma_b = 1$$

# Shifted BM on a Network



Known network.

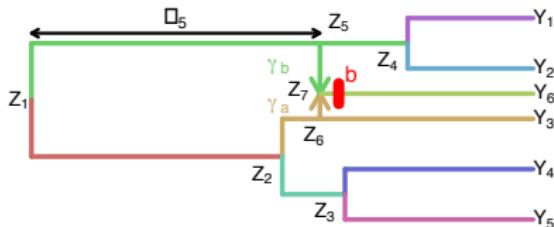
Only tip values observed.



Brownian Motion:

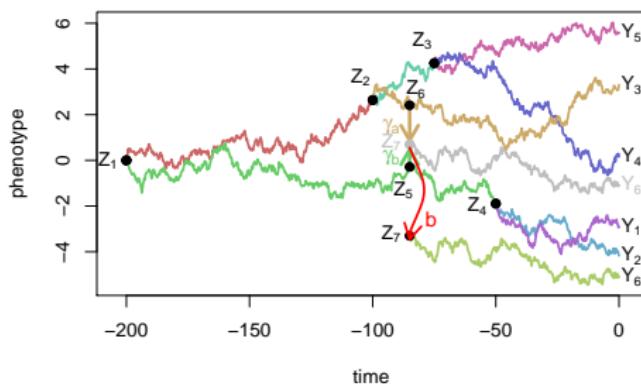
$$V_{ij}^{\text{net}} = \sum_{\substack{p_i \in \mathcal{P}_i \\ p_j \in \mathcal{P}_j}} \left( \prod_{e \in p_i} \gamma_e \right) \left( \prod_{e \in p_j} \gamma_e \right) \sum_{e \in p_i \cap p_j} \ell_e$$

# Shifted BM on a Network



Known network.

Only tip values observed.

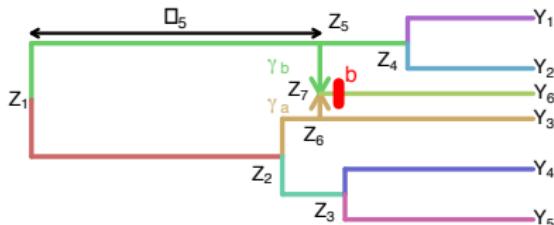


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5 + b$$

**b** : Transgressive evolution.

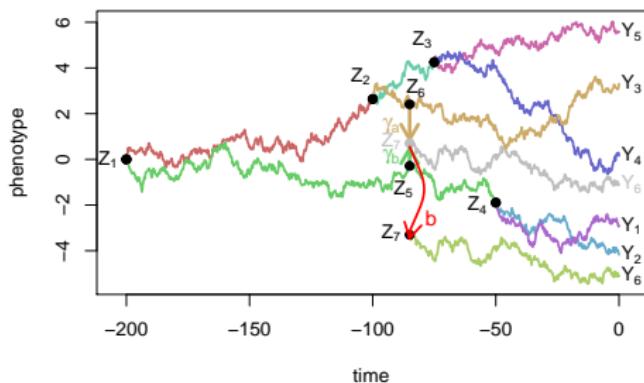
# Shifted BM on a Network



Known network.

Only tip values observed.

**Goal:** Test for transgressive evolution.

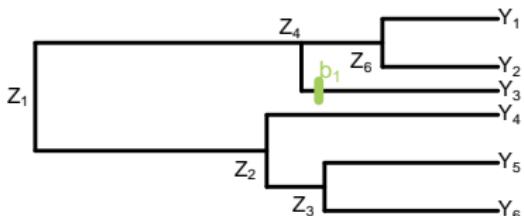


Brownian Motion:

$$Z_7 = \gamma_a Z_6 + \gamma_b Z_5 + b$$

**b** : Transgressive evolution.

# Linear Regression Model

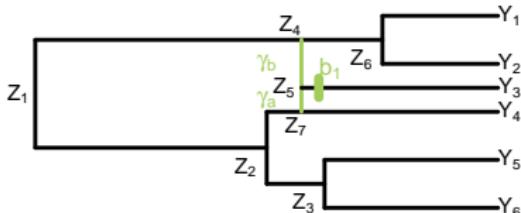


$$\Delta = \begin{pmatrix} Z_1 \\ Z_2 \\ Z_3 \\ Z_4 \\ Z_6 \\ Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \end{pmatrix} \quad T\Delta = \begin{pmatrix} Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \end{pmatrix} \begin{pmatrix} \mu \\ \mu \\ \mu + b_1 \\ \mu \\ \mu \\ \mu \end{pmatrix}$$

$$T = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_6 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \\ Y_6 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 \end{pmatrix}$$

$$Y = T\Delta + \sigma E^{\text{net}}$$

# Linear Regression Model



$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \cdot \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Z_5 & 0 \\ Z_6 & \cdot \\ Z_7 & \cdot \\ Y_1 & \cdot \\ Y_2 & \cdot \\ Y_3 & \cdot \\ Y_4 & b_1 \\ Y_5 & \cdot \\ Y_6 & \cdot \end{pmatrix}$$

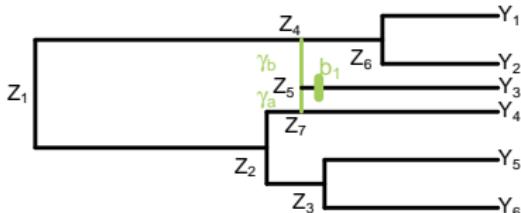
$$\mathbf{T}\Delta = \begin{pmatrix} Y_1 & \mu \\ Y_2 & \mu \\ Y_3 & \mu + b_1 \\ Y_4 & \mu \\ Y_5 & \mu \\ Y_6 & \mu \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_5 & Z_6 & Z_7 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & \cdot & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & \gamma_b & 1 & \cdot & \gamma_a & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & 1 & \cdot \\ Y_6 & 1 & 1 & 1 & \cdot & 1 \end{pmatrix}$$

$$\mathbf{Y} = \mathbf{T}\Delta + \sigma \mathbf{E}^{\text{net}}$$

$$T_{ij} = \sum_{p \in \mathcal{P}_{j \rightarrow i}} \prod_{e \in p} \gamma_e$$

# Linear Regression Model



$$\Delta = \begin{pmatrix} Z_1 & \mu \\ Z_2 & \cdot \\ Z_3 & \cdot \\ Z_4 & \cdot \\ Z_5 & 0 \\ Z_6 & \cdot \\ Z_7 & \cdot \\ Y_1 & \cdot \\ Y_2 & \cdot \\ Y_3 & \cdot \\ Y_4 & \cdot \\ Y_5 & \cdot \\ Y_6 & \cdot \end{pmatrix}$$

$$T\Delta = \begin{pmatrix} Y_1 & \mu \\ Y_2 & \mu \\ Y_3 & \mu + b_1 \\ Y_4 & \mu \\ Y_5 & \mu \\ Y_6 & \mu \end{pmatrix}$$

$$T = \begin{pmatrix} Z_1 & Z_2 & Z_3 & Z_4 & Z_5 & Z_6 & Z_7 & Y_1 & Y_2 & Y_3 & Y_4 & Y_5 & Y_6 \\ Y_1 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & 1 & \cdot & \cdot & \cdot & \cdot \\ Y_2 & 1 & \cdot & \cdot & 1 & \cdot & 1 & \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ Y_3 & 1 & \cdot & \cdot & \gamma_b & 1 & \cdot & \gamma_a & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_4 & 1 & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ Y_5 & 1 & 1 & 1 & \cdot & 1 & \cdot \\ Y_6 & 1 & 1 & 1 & \cdot & 1 \end{pmatrix}$$

$$\mathbf{Y} = \mu \mathbf{1} + \mathbf{N} \mathbf{b} + \sigma \mathbf{E}^{\text{net}}$$

$$T_{ij} = \sum_{p \in \mathcal{P}_{j \rightarrow i}} \prod_{e \in p} \gamma_e$$

# Transgressive Evolution: Testing Effect(s)

Model:

$$\mathbf{Y} = \mu \mathbf{1} + \mathbf{Nb} + \sigma^2 \mathbf{E} \quad , \quad \mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$$

Tests:	$\mathcal{H}_0$ : No TE	$\mathbf{b} = \mathbf{0}$
	$\mathcal{H}_1$ : TE with one single effect	$\mathbf{b} = b_1$
	$\mathcal{H}_2$ : TE with heterogeneous effects	$\mathbf{b} \in \mathbb{R}^h$

Fisher:

$$F_{10} \sim \mathcal{F}_{1,n-2} (\Delta_{10}(b, \sigma^2))$$

$$F_{21} \sim \mathcal{F}_{h-1,n-h-1} (\Delta_{21}(\mathbf{b}, \sigma^2))$$



# *Xiphophorus* fishes

(Cui et al., 2013)



*X. Montezumae*

## Sword Index

No evidence for TE.

# *Xiphophorus* fishes

(Cui et al., 2013)



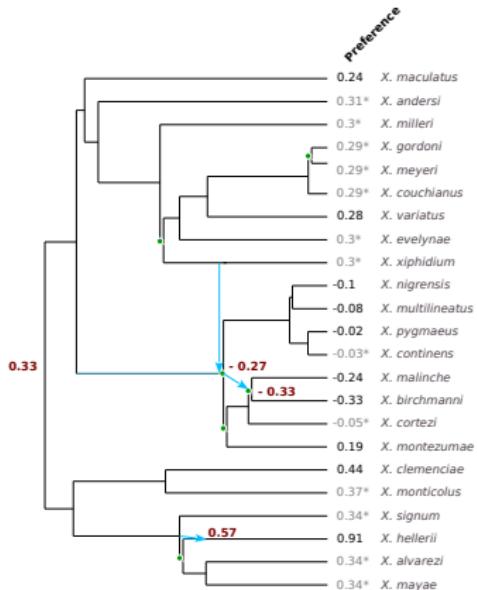
*X. Montezumae*

## Sword Index

No evidence for TE.

## Female Preference

Heterogeneous TE.



# Xiphophorus fishes

(Cui et al., 2013)



*X. Montezumae*

## Sword Index

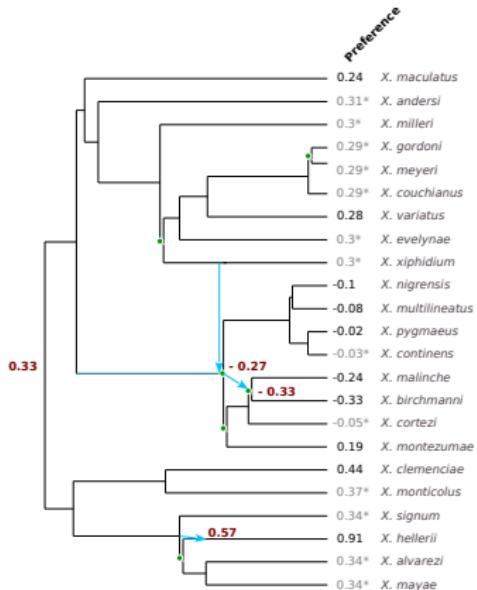
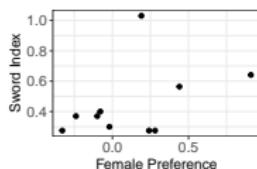
No evidence for TE.

## Female Preference

Heterogeneous TE.

## Regression

Positive correlation  
(Non-significant).



# Contributions

## Preprint

**Bastide**, Solís-Lemus, Kriebel, Sparks, Ané (submitted). Phylogenetic Comparative Methods for Phylogenetic Networks with Reticulations.

## Julia package

Solís-Lemus, **Bastide**, Ané (2017). PhyloNetworks: a package for phylogenetic networks. *Molecular Biology and Evolution*, msx235.

- ↳ Network inference and use.
- ↳ Continuous integration, unitary tests, online doc.

back

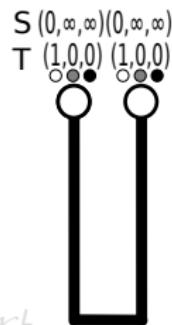
# Cardinal of Equivalence Classes

**Initialization** For tips  
**Propagation**

$$\mathcal{K}_k^l = \underset{1 \leq p \leq K}{\operatorname{argmin}} \left\{ S_{ij}(p) + \mathbb{I}\{p \neq k\} \right\}$$

$$S_i(k) = \sum_{l=1}^L S_{il}(p_l) + \mathbb{I}\{p_l \neq k\}, \quad \forall (p_1, \dots, p_L) \in \mathcal{K}_k^1 \times \dots \times \mathcal{K}_k^L$$

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**Termination** Sum on the root vector

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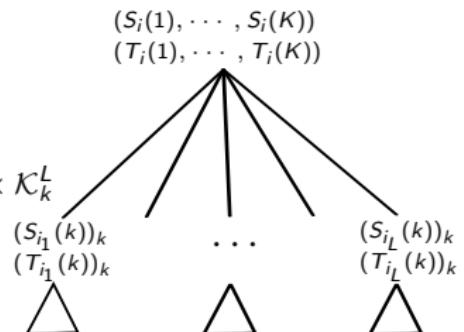
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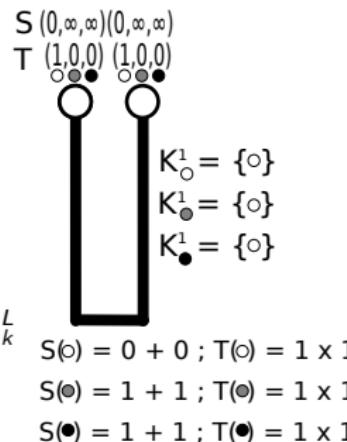
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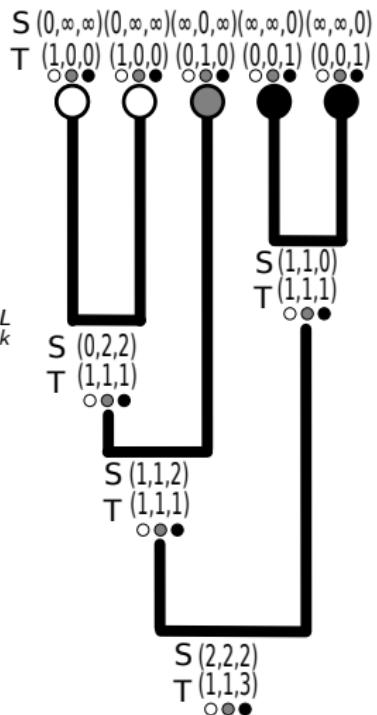
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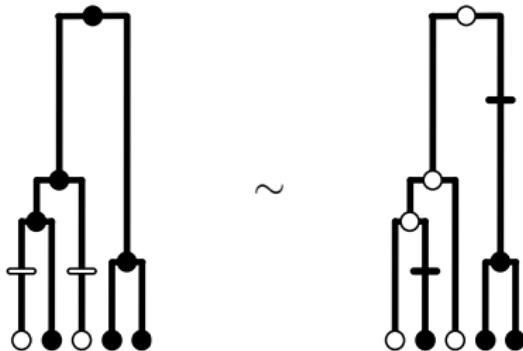
# Linking Shifts and Clustering

Assumption “No Homoplasy”: 1 shift = 1 new color

Proposition “ $K$  shifts  $\iff K + 1$  clusters”

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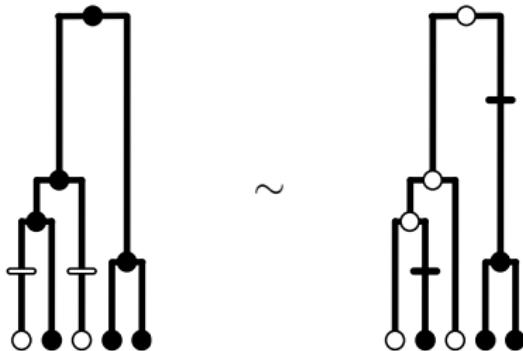


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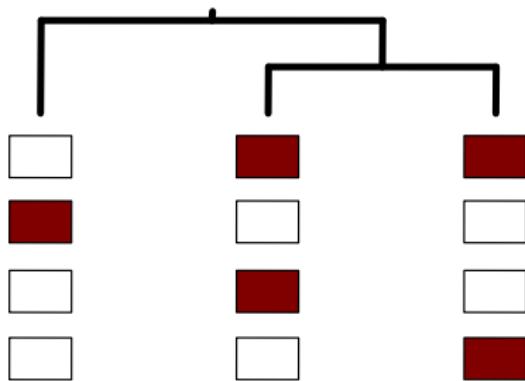
~

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Proposition “ $K$  shifts  $\iff K + 1$  clusters”

# Definitions

- $\mathcal{T}$  a rooted tree with  $n$  tips
- $N_K^{(\mathcal{T})} = |\mathcal{C}_K|$  the number of possible partitions of the tips in  $K$  clusters
- $A_K^{(\mathcal{T})}$  the number of possible *marked* partitions



Difference between  $N_2^{(\mathcal{T}_3)}$  and  $A_2^{(\mathcal{T}_3)}$ :

- $N_2^{(\mathcal{T}_3)} = 3$ : partitions 1 and 2 are equivalent
- $A_2^{(\mathcal{T}_3)} = 4$ : one marked color ("white = ancestral state")

*Partitions in two groups for a binary tree with 3 tips*

# General Formula (Binary Case)

If  $\mathcal{T}$  is a binary tree, consider  $T_\ell$  and  $T_r$  the left and right sub-trees of  $\mathcal{T}$ . Then:

$$\begin{cases} N_K^{(\mathcal{T})} = \sum_{k_1+k_2=K} N_{k_1}^{(\mathcal{T}_\ell)} N_{k_2}^{(\mathcal{T}_r)} + \sum_{k_1+k_2=K+1} A_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} \\ A_K^{(\mathcal{T})} = \sum_{k_1+k_2=K} A_{k_1}^{(\mathcal{T}_\ell)} N_{k_2}^{(\mathcal{T}_r)} + N_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} + \sum_{k_1+k_2=K+1} A_{k_1}^{(\mathcal{T}_\ell)} A_{k_2}^{(\mathcal{T}_r)} \end{cases}$$

We get:

$$N_{K+1}^{(\mathcal{T})} = N_{K+1}^{(n)} = \binom{2n-2-K}{K} \quad \text{and} \quad A_{K+1}^{(\mathcal{T})} = A_{K+1}^{(n)} = \binom{2n-1-K}{K}$$

# Recursion Formula (General Case)

If we are at a node defining a tree  $\mathcal{T}$  that has  $p$  daughters, with sub-trees  $\mathcal{T}_1, \dots, \mathcal{T}_p$ , then we get the following recursion formulas:

$$\begin{cases} N_K^{(\mathcal{T})} = \sum_{\substack{k_1 + \dots + k_p = K \\ k_1, \dots, k_p \geq 1}} \prod_{i=1}^p N_{k_i}^{(\mathcal{T}_i)} + \sum_{\substack{I \subset [1, p] \\ |I| \geq 2}} \sum_{\substack{k_1 + \dots + k_p = K + |I| - 1 \\ k_1, \dots, k_p \geq 1}} \prod_{i \in I} A_{k_i}^{(\mathcal{T}_i)} \prod_{i \notin I} N_{k_i}^{(\mathcal{T}_i)} \\ A_K^{(\mathcal{T})} = \sum_{\substack{I \subset [1, p] \\ |I| \geq 1}} \sum_{\substack{k_1 + \dots + k_p = K + |I| - 1 \\ k_1, \dots, k_p \geq 1}} \prod_{i \in I} A_{k_i}^{(\mathcal{T}_i)} \prod_{i \notin I} N_{k_i}^{(\mathcal{T}_i)} \end{cases}$$

No general formula. The result depends on the topology of the tree.

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# Cholesky Decomposition

The problem is:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y - T\Delta\|_{V^{-1}}^2 + \lambda |\Delta|_1 \right\}$$

Cholesky decomposition of  $V$ :

$$V = LL^T, \quad L \text{ a lower triangular matrix}$$

Then:

$$\|Y - T\Delta\|_{V^{-1}}^2 = \|L^{-1}Y - L^{-1}T\Delta\|^2$$

And if  $Y' = L^{-1}Y$  and  $T' = L^{-1}T$ , the problem becomes:

$$\hat{\Delta} = \operatorname{argmin}_{\Delta} \left\{ \|Y' - T'\Delta\|^2 + \lambda |\Delta|_1 \right\}$$

# Gauss Lasso

Let  $\hat{m}_\lambda$  be the set of selected variables (including the root). Then:

$$\hat{\Delta}^{\text{Gauss}} = \Pi_{\hat{F}_\lambda}(\mathbf{Y}') \text{ with } \hat{F}_\lambda = \text{Span}\{\mathbf{T}'_j : j \in \hat{m}_\lambda\}$$

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# Goal and Notations

**Data** A process on a tree with the following structure:

$$\forall j > 1, \quad X_j | X_{\text{pa}(j)} \sim \mathcal{N} (m_j(X_{\text{pa}(j)}) = q_j X_{\text{pa}(j)} + r_j, \sigma_j^2)$$

$$\text{BM: } \begin{cases} q_j = 1 \\ r_j = \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k \\ \sigma_j^2 = \ell_j \sigma^2 \end{cases} \quad \text{OU: } \begin{cases} q_j = e^{-\alpha \ell_j} \\ r_j = \beta^{\text{pa}(j)} (1 - e^{-\alpha \ell_j}) + \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k (1 - e^{-\alpha(1-\nu_k) \ell_j}) \\ \sigma_j^2 = \frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha \ell_j}) \end{cases}$$

**Goal** Compute the following quantities, at every node  $j$ :

$$\text{Var}^{(h)}[Z_j | \mathbf{Y}], \text{Cov}^{(h)}[Z_j, Z_{\text{pa}(j)} | \mathbf{Y}], \mathbb{E}^{(h)}[Z_j | \mathbf{Y}]$$

# Upward

**Goal** Compute for a vector of tips, given their common ancestor:

$$f_{\mathbf{Y}^j|X_j}(\mathbf{Y}^j; a) = A_j(\mathbf{Y}^j)\Phi_{M_j(\mathbf{Y}^j), S_j^2(\mathbf{Y}^j)}(a)$$

**Initialization** For tips:  $f_{Y_i|Y_i}(Y_i; a) = \Phi_{Y_i, 0}(a)$

**Propagation**

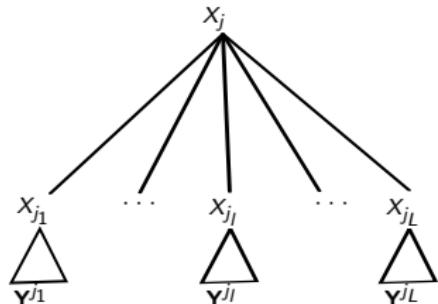
$$f_{\mathbf{Y}^j|X_j}(\mathbf{Y}^j; a) = \prod_{l=1}^L f_{\mathbf{Y}^{j_l}|X_j}(\mathbf{Y}^{j_l}; a)$$

$$f_{\mathbf{Y}^{j_l}|X_j}(\mathbf{Y}^{j_l}; a) = \int_{\mathbb{R}} f_{\mathbf{Y}^{j_l}|X_{j_l}}(\mathbf{Y}^{j_l}; b) f_{X_{j_l}|X_j}(b; a) db$$

**Root Node and Likelihood** At the root:

$$f_{X_1|\mathbf{Y}}(a; \mathbf{Y}) \propto f_{\mathbf{Y}|X_1}(\mathbf{Y}; a) f_{X_1}(a)$$

$$\begin{cases} \mathbb{V}\text{ar}[X_1 | \mathbf{Y}] = \left(\frac{1}{\gamma^2} + \frac{1}{S_1^2(\mathbf{Y})}\right)^{-1} \\ \mathbb{E}[X_1 | \mathbf{Y}] = \mathbb{V}\text{ar}[X_1 | \mathbf{Y}] \left(\frac{\mu}{\gamma^2} + \frac{M_1(\mathbf{Y})}{S_1^2(\mathbf{Y})}\right) \end{cases}$$



# Downward

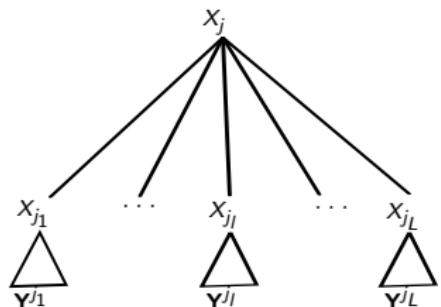
Compute  $E_j = \mathbb{E}[X_j | \mathbf{Y}]$  ,  $V_j^2 = \text{Var}[X_j | \mathbf{Y}]$  ,  $C_{j,\text{pa}(j)}^2 = \text{Cov}[X_j; X_{\text{pa}(j)} | \mathbf{Y}]$

**Initialization** Last step of Upward.

**Propagation**

$$f_{X_{\text{pa}(j)}, X_j | \mathbf{Y}}(a, b; \mathbf{Y}) = f_{X_{\text{pa}(j)} | \mathbf{Y}}(a; \mathbf{Y}) f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}}(b; a, \mathbf{Y})$$

$$\begin{aligned} f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}}(b; a, \mathbf{Y}) &= f_{X_j | X_{\text{pa}(j)}, \mathbf{Y}^j}(b; a, \mathbf{Y}^j) \\ &\propto f_{X_j | X_{\text{pa}(j)}}(b; a) f_{\mathbf{Y}^j | X_j}(\mathbf{Y}^j; b) \end{aligned}$$



# Formulas

Upward

$$\begin{cases} S_j^2(\mathbf{Y}^j) = \left( \sum_{l=1}^L \frac{q_{jl}^2}{S_{jl}^2(\mathbf{Y}^{j_l}) + \sigma_{jl}^2} \right)^{-1} \\ M_j(\mathbf{Y}^j) = S_j^2(\mathbf{Y}^j) \sum_{l=1}^L q_{jl} \frac{M_{j_l}(\mathbf{Y}^{j_l}) - r_{j_l}}{S_{jl}^2(\mathbf{Y}^{j_l}) + \sigma_{jl}^2} \end{cases}$$

Downward

$$\begin{cases} C_{j,\text{pa}(j)}^2 = q_j \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} V_{\text{pa}(j)}^2 \\ E_j = \frac{S_j^2(\mathbf{Y}^j)(q_j E_{\text{pa}(j)} + r_j) + \sigma_j^2 M_j(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} \\ V_j^2 = \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} \left( \sigma_j^2 + p_j^2 \frac{S_j^2(\mathbf{Y}^j)}{S_j^2(\mathbf{Y}^j) + \sigma_j^2} V_{\text{pa}(j)}^2 \right) \end{cases}$$

back

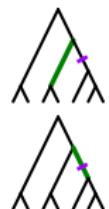
# M Step: Segmentation

$$C_j(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - r_j - s_j \Delta_j)^2$$

BM :  $r_j = 0$ , each cost is independent.

$$C_j^0 = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y])^2$$

$$C_j^1(\Delta) = \sigma_j^{-2} (\mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - s_j \Delta_j)^2$$



Algorithm:

- ① Find the  $K$  branches  $j_1, \dots, j_K$  with largest  $C_j^0$ ;
- ② Allocate one change point in the first  $K$  branches;
- ③ For each of these branches, set  $\delta_{j_k}^{(h+1)}$  so that  $C_j^1(\Delta) = 0$

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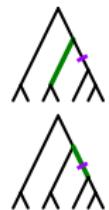
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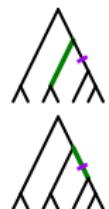
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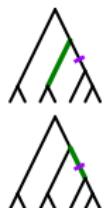
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# M Step: Segmentation

$$C_j(\alpha, \tau, \delta) = \sigma_j^{-2} \left( \mathbb{E}[X_j | Y] - q_j \mathbb{E}[X_{\text{pa}(j)} | Y] - r_j - s_j \sum_k \mathbb{I}\{\tau_k = b_j\} \delta_k \right)^2$$

OU :  $r_j = \beta^{\text{pa}(j)}$ , a cost depends on all its parents.

- Exact minimization: too costly.
- Need of an heuristic.
- Idea: rewrite as a least square:

$$\|D - AU\Delta\|^2$$

with  $D$  a vector of size  $n + m$ ,  $A$  a diagonal matrix of size  $n + m$ ,  $\Delta$  the vector of shifts and  $U$  the incidence matrix of the tree.

- Then use Stepwise selection or LASSO.
- Other idea: binary segmentation.

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# Model Selection with Unknown Variance

Theorem (Baraud et al. (2009))

*Under the following setting:*

$$Y' = \mathbb{E}[Y'] + \gamma E' \quad \text{with} \quad E' \sim \mathcal{N}(0, I_n) \quad \text{and} \quad \mathcal{S}' = \{S'_\eta, \eta \in \mathcal{M}\}$$

If  $D_\eta = \text{Dim}(S'_\eta)$ ,  $N_\eta = n - D_\eta \geq 7$ ,  $\max(L_\eta, D_\eta) \leq \kappa n$ , with  $\kappa < 1$ , and:

$$\Omega' = \sum_{\eta \in \mathcal{M}} (D_\eta + 1) e^{-L_\eta} < +\infty$$

$$\text{If: } \hat{\eta} = \operatorname{argmin}_{\eta \in \mathcal{M}} \|Y' - \hat{Y}'_\eta\|^2 \left(1 + \frac{\text{pen}(\eta)}{N_\eta}\right)$$

$$\text{with: } \text{pen}(\eta) = \text{pen}_{A, L}(\eta) = A \frac{N_\eta}{N_\eta - 1} \text{EDkhi}[D_\eta + 1, N_\eta - 1, e^{-L_\eta}] \quad , \quad A > 1$$

$$\text{Then: } \mathbb{E} \left[ \frac{\|\mathbb{E}[Y'] - \hat{Y}'_{\hat{\eta}}\|^2}{\gamma^2} \right] \leq C(A, \kappa) \left[ \inf_{\eta \in \mathcal{M}} \left\{ \frac{\|\mathbb{E}[Y'] - Y'_\eta\|^2}{\gamma^2} + \max(L_\eta, D_\eta) \right\} + \Omega' \right]$$

# IID Framework ( $\alpha = 0$ )

Assume  $K_\eta = D_\eta - 1 \leq p - 1 \leq n - 8$ ,  $\forall \eta \in \mathcal{M}$

Then:

$$\begin{aligned}
 \Omega' &= \sum_{\eta \in \mathcal{M}} (D_\eta + 1)e^{-L_\eta} = \sum_{\eta \in \mathcal{M}} (K_\eta + 2)e^{-L_\eta} \\
 &= \sum_{K=0}^{p-1} |\mathcal{S}_K^{PI}| (K+2)e^{-L_K} = \sum_{K=0}^{p-1} |\mathcal{S}_K^{PI}| (K+2)e^{-(\log|\mathcal{S}_K^{PI}| + 2\log(K+2))} \\
 &= \sum_{K=0}^{p-1} \frac{1}{K+2} \leq \log(p) \leq \log(n)
 \end{aligned}$$

And:

$$L_K \leq \log \binom{n+m-1}{K} + 2\log(K+2) \leq K\log(n+m-1) + 2(K+1) \leq p(2 + \log(2n-2))$$

Hence, if  $p \leq \min\left(\frac{\kappa n}{2 + \log(2) + \log(n)}, n - 7\right)$ , then  $\max(L_\eta, D_\eta) \leq \kappa n$  for any  $\eta \in \mathcal{M}$ .

# Non-IID Framework ( $\alpha \neq 0$ )

Cholesky decomposition:  $V = LL^T$     $Y' = L^{-1}Y$     $s' = L^{-1}s$     $E' = L^{-1}E$

$$Y' = \mathbb{E}[Y'] + \gamma E', \text{ with: } E' \sim \mathcal{N}(0, I_n)$$

$$S'_\eta = L^{-1}S_\eta, \quad \hat{Y}'_\eta = \text{Proj}_{S'_\eta} Y' = \underset{a' \in S'_\eta}{\operatorname{argmin}} \|Y - La'\|_V^2 = L^{-1}\hat{Y}_\eta$$

$$\|\mathbb{E}[Y] - \hat{Y}_{\hat{\eta}}\|_V^2 = \|\mathbb{E}[Y'] - \hat{Y}'_{\hat{\eta}}\|_V^2, \quad \|Y - \hat{Y}_\eta\|_V^2 = \|Y' - \hat{Y}'_\eta\|_V^2$$

$$\text{Crit}_{MC}(\eta) = \|Y' - \hat{Y}'_\eta\|_V^2 \left(1 + \frac{\text{pen}_{A,\mathcal{L}}(\eta)}{N_\eta}\right) = \|Y - \hat{Y}_\eta\|_V^2 \left(1 + \frac{\text{pen}_{A,\mathcal{L}}(\eta)}{N_\eta}\right)$$

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# Phylogenetic PCA with shifts

Model  $\mathbf{Y}$  size  $n \times p$  ( $n$  observations,  $p$  traits), Brownian

$$\mathbf{Y} = \boldsymbol{\mu} + \mathbf{E} \quad \text{vec}(\mathbf{E}) \sim \mathcal{N}(\mathbf{0}, \mathbf{R} \otimes \mathbf{C})$$

## Empirical Mean and Variance

$$\bar{\mathbf{Y}}^T = \tilde{\mathbf{C}}\mathbf{Y} \quad \bar{\boldsymbol{\mu}}^T = \mathbb{E}[\bar{\mathbf{Y}}^T] = \tilde{\mathbf{C}}\boldsymbol{\mu} \quad \text{with} \quad \tilde{\mathbf{C}} = (\mathbf{1}_n^T \mathbf{C}^{-1} \mathbf{1}_n)^{-1} \mathbf{1}_n^T \mathbf{C}^{-1}$$

$$\hat{\mathbf{R}} = \frac{1}{n-1}(\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T)^T \mathbf{C}^{-1} (\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T)$$

## Bias on $\hat{\mathbf{R}}$

$$\mathbb{E}[\hat{\mathbf{R}}] = \mathbf{R} + \frac{1}{n-1} \mathbf{G}^T \mathbf{C}^{-1} \mathbf{G} \quad \text{with} \quad \mathbf{G} = (\boldsymbol{\mu} - \mathbf{1}_n \bar{\boldsymbol{\mu}}^T)$$

# Phylogenetic PCA : Scores

## Rotation

$$\hat{\mathbf{R}} = \frac{1}{n-1} \hat{\mathbf{V}} \hat{\mathbf{D}}^2 \hat{\mathbf{V}}^T$$

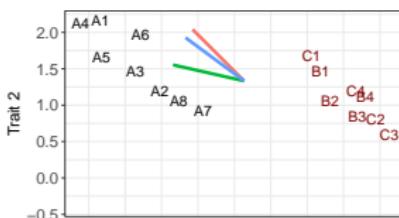
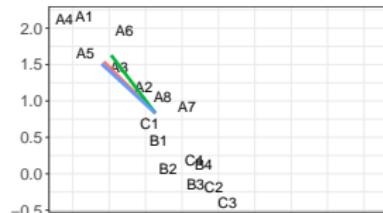
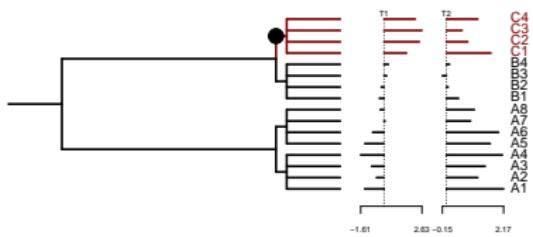
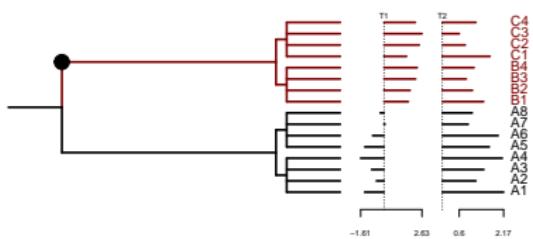
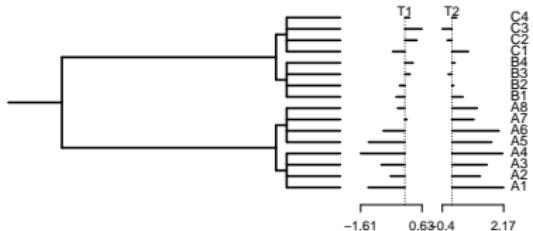
→ If  $\hat{\mathbf{R}}$  is biased, then  $\hat{\mathbf{V}}$  is the wrong rotation.

## Scores

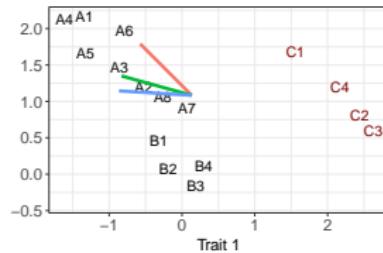
$$\mathbf{S} = (\mathbf{Y} - \mathbf{1}_n \bar{\mathbf{Y}}^T) \hat{\mathbf{V}}$$

→ The scores are not decorrelated.

# Phylogenetic PCA : Examples



First eigenvector from  
 — red variance R  
 — green PCA  
 — blue pPCA



back

# OU Model

SDE **A** ( $p \times p$ ) selection strength

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

# OU Model

SDE  $\mathbf{A}$  ( $p \times p$ ) selection strength

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma}d\mathbf{B}_t$$

## Covariances

$$\begin{aligned}\text{Cov} [\mathbf{X}_i; \mathbf{X}_j] &= e^{-\mathbf{A}t_i} \boldsymbol{\Gamma} e^{-\mathbf{A}^T t_j} \\ &+ e^{-\mathbf{A}(t_i - t_{ij})} \left( \int_0^{t_{ij}} e^{-\mathbf{A}v} \boldsymbol{\Sigma} \boldsymbol{\Sigma}^T e^{-\mathbf{A}^T v} dv \right) e^{-\mathbf{A}^T (t_j - t_{ij})}\end{aligned}$$

# OU Model

SDE  $\mathbf{A}$  ( $p \times p$ ) selection strength  $\in \mathcal{S}_n^{++}$

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## Covariances

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## Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

## Stationary Variance

$$\mathbf{S} = \mathbf{P} \left( \left[ \frac{1}{\lambda_q + \lambda_r} \right]_{1 \leq q, r \leq p} \odot \mathbf{P}^{-1} \mathbf{R} \mathbf{P}^{-T} \right) \mathbf{P}^T$$

# OU Model

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## Incomplete Data Representation

$$\mathbf{X}_j \mid \mathbf{X}_{\text{pa}(j)} \sim \mathcal{N} \left( e^{-\mathbf{A}\ell_j} \mathbf{X}_{\text{pa}(j)} + (\mathbf{I}_p - e^{-\mathbf{A}\ell_j})\beta_j, \mathbf{\Gamma}_i = \mathbf{S} - e^{-\mathbf{A}\ell_j}\mathbf{S}e^{-\mathbf{A}^T\ell_j} \right)$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\mathbf{A}(\mathbf{W}(t) - \beta(t))dt + \boldsymbol{\Sigma} d\mathbf{B}_t$$

## Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

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$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

Stationary Variance

$$\mathbf{S} = \mathbf{P} \left( \left[ \frac{1}{\lambda_q + \lambda_r} \right]_{1 \leq q, r \leq p} \odot \mathbf{P}^{-1} \mathbf{R} \mathbf{P}^{-T} \right) \mathbf{P}^T$$

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SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

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$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = e^{-\mathbf{A}t_i}\mathbf{\Gamma}e^{-\mathbf{A}^T t_j} - e^{-\mathbf{A}t_i}\mathbf{S}e^{-\mathbf{A}^T t_j} + e^{-\mathbf{A}(t_i - t_{ij})}\mathbf{S}e^{-\mathbf{A}^T(t_j - t_{ij})}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha}\mathbf{R}$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1) \mathbf{R}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha} \mathbf{R}$$

# OU Model

SDE  $\mathbf{A} = \alpha I_p$  scalar

$$d\mathbf{W}(t) = -\alpha(\mathbf{W}(t) - \beta(t))dt + \Sigma d\mathbf{B}_t$$

Covariances

$$\text{Cov}[\mathbf{X}_i; \mathbf{X}_j] = \frac{1}{2\alpha} e^{-2\alpha h} (e^{2\alpha t_{ij}} - 1) \mathbf{R}$$

Stationary Variance

$$\mathbf{S} = \frac{1}{2\alpha} \mathbf{R}$$

↳ Re-scaling trick.

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## TE: Single Effect

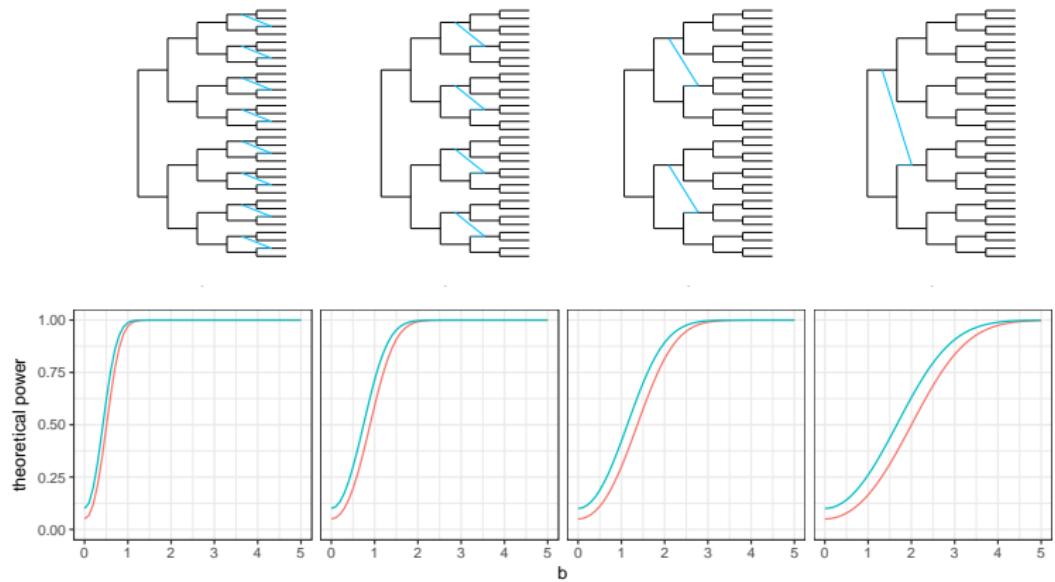
Model:  $\mathbf{Y} = \mu \mathbf{1} + b \bar{\mathbf{N}} + \sigma^2 \mathbf{E}$  ,  $\mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$

Test:  $\mathcal{H}_0 : b = 0$

Stat.:  $F_{10} = \frac{\|\mathbf{Y} - \text{Proj}_{\mathbf{1}} \mathbf{Y}\|_{\mathbf{V}^{-1}}^2 - \left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2}{\left\| \mathbf{Y} - \text{Proj}_{[\mathbf{1} \ \bar{\mathbf{N}}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2} \frac{n - r_{[\mathbf{1} \ \bar{\mathbf{N}}]}}{r_{[\mathbf{1} \ \bar{\mathbf{N}}]} - r_{\mathbf{1}}}$

$$\sim \mathcal{F} \left( 1, n - 2, \frac{b^2}{2\sigma^2} \left\| (\mathbf{I} - \text{Proj}_{\mathbf{1}}) \bar{\mathbf{N}} \right\|_{\mathbf{V}^{-1}}^2 \right)$$

## TE: Single Effect



*Detection Power ( $\sigma^2 = 1$ )*

# TE: Several Effects

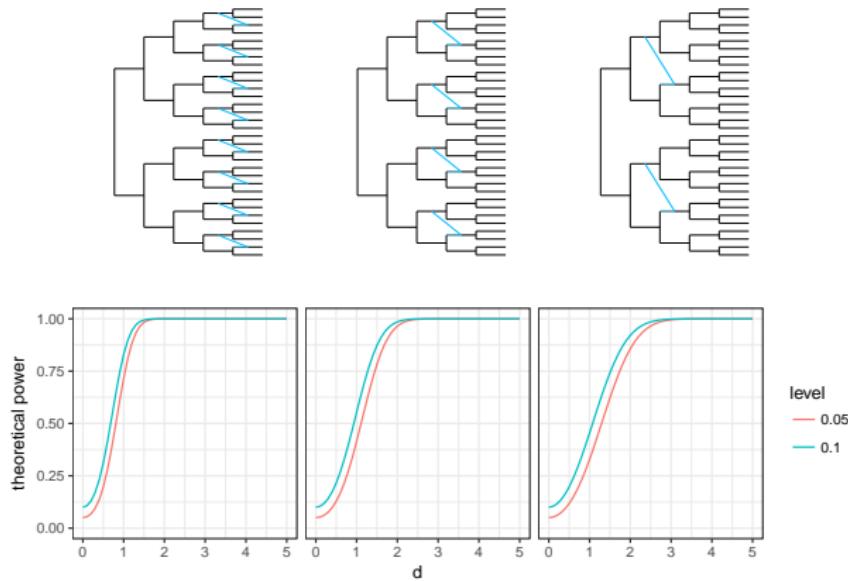
Model:  $\mathbf{Y} = \mu \mathbf{1} + b \bar{\mathbf{N}} + \mathbf{Nd} + \sigma^2 \mathbf{E}$  ,  $\mathbf{E} \sim \mathcal{N}(\mathbf{0}, \mathbf{V})$

Test:  $\mathcal{H}_1 : d_1 = \dots = d_h = 0$

Stat.:  $F_{21} = \frac{\left\| \mathbf{Y} - \text{Proj}_{[1 \ N]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2 - \left\| \mathbf{Y} - \text{Proj}_{[1 \ \bar{N}]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2}{\left\| \mathbf{Y} - \text{Proj}_{[1 \ N]} \mathbf{Y} \right\|_{\mathbf{V}^{-1}}^2} \frac{n - r_{[1 \ N]}}{r_{[1 \ N]} - r_{[1 \ \bar{N}]}}$

$$\sim \mathcal{F} \left( h - 1, n - h - 1, \frac{1}{2\sigma^2} \left\| (\mathbf{I} - \text{Proj}_{[1 \ \bar{N}]}) \mathbf{Nd} \right\|_{\mathbf{V}^{-1}}^2 \right)$$

# TE: Several Effects



*Detection Power ( $\sigma^2 = 1$ )*

back

# Simulations Design

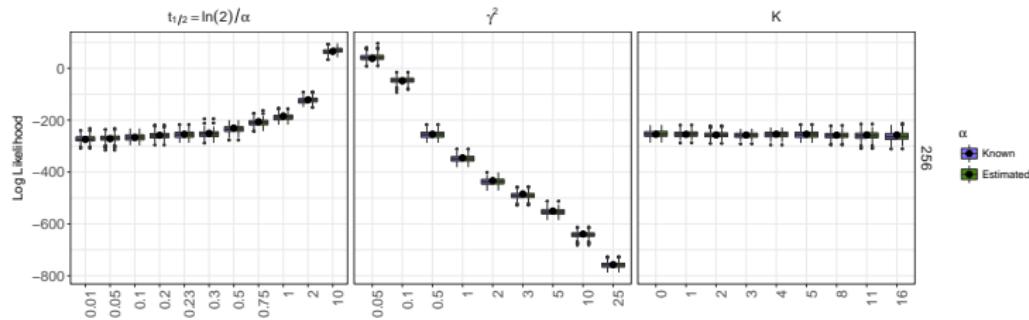
(Uyeda and Harmon, 2014)

- Topology of the tree fixed (unit height,  $\lambda = 0.1$ , with 64, 128, 256 taxa).
- Initial optimal value fixed:  $\beta_0 = 0$
- One "base" scenario  $\alpha_b = 3$ ,  $\gamma_b^2 = 0.5$ ,  $K_b = 5$ .
- $\alpha \in \log(2)/\{0.01, 0.05, 0.1, 0.2, 0.23, 0.3, 0.5, 0.75, 1, 2, 10\}$ .
- $\gamma^2 \in \{0.3, 0.6, 3, 6, 12, 18, 30, 60, 150\}/(2\alpha_b)$ .
- $K \in \{0, 1, 2, 3, 4, 5, 8, 11, 16\}$ .
- Shifts values  $\sim \frac{1}{2}\mathcal{N}(4, 1) + \frac{1}{2}\mathcal{N}(-4, 1)$
- Shifts randomly placed at regular intervals separated by 0.1 unit length.
- $n = 200$  repetitions: 16200 configurations.

CPU time on cluster MIGALE (Jouy-en-Josas):

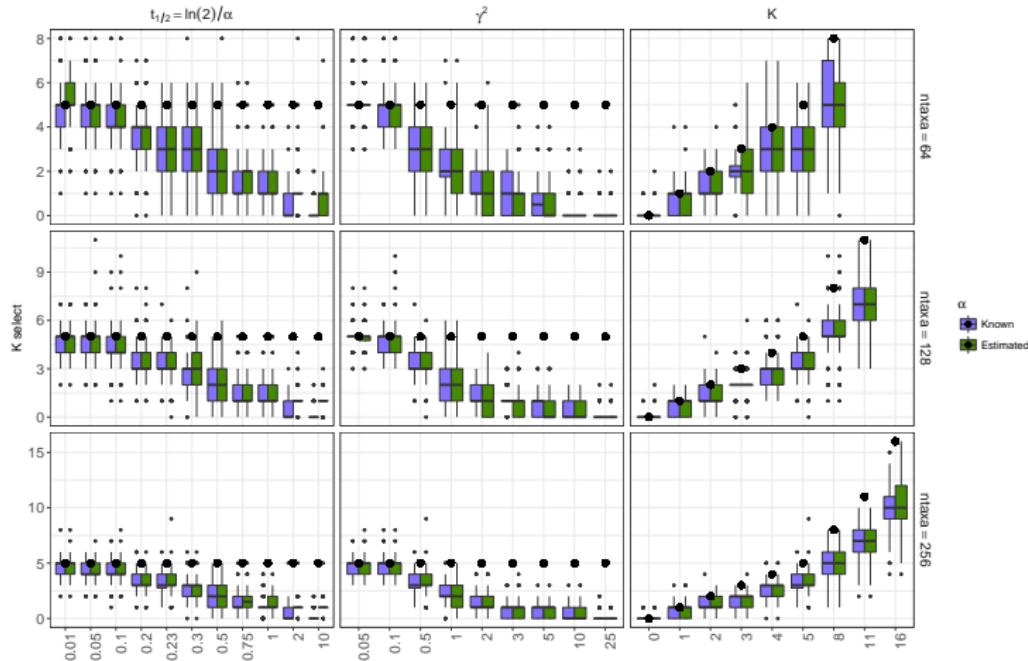
- $\alpha$  known: 6 minutes per estimation (66 days in total).
- $\alpha$  unknown: 52 minutes per estimation (570 days in total).

# Log-Likelihood

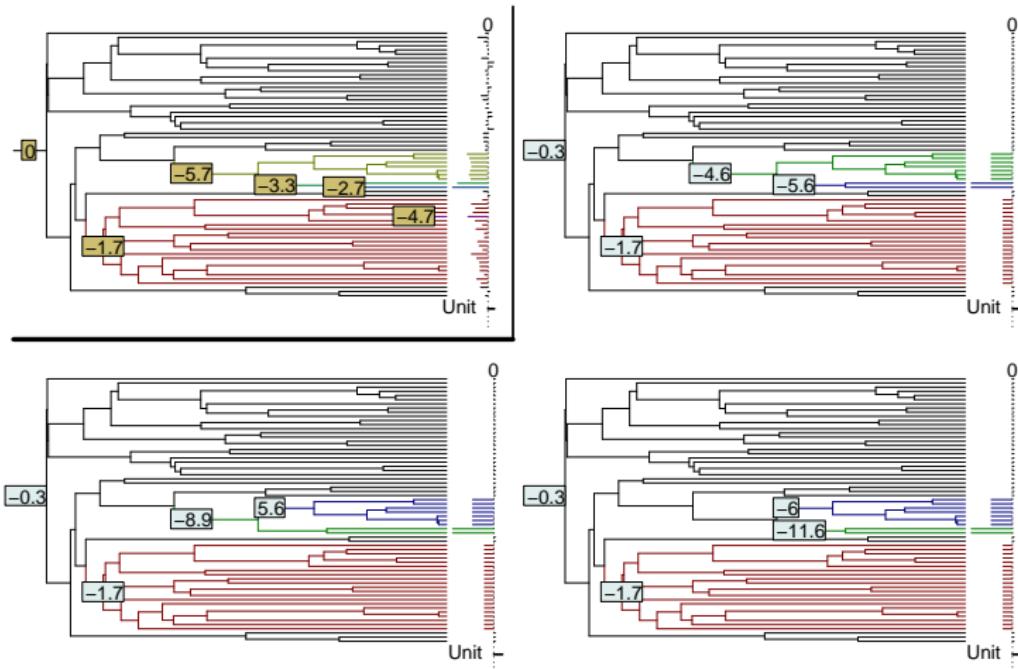


*Log likelihood for a tree with 256 tips. Solid black dots are the median of the log likelihood for the true parameters.*

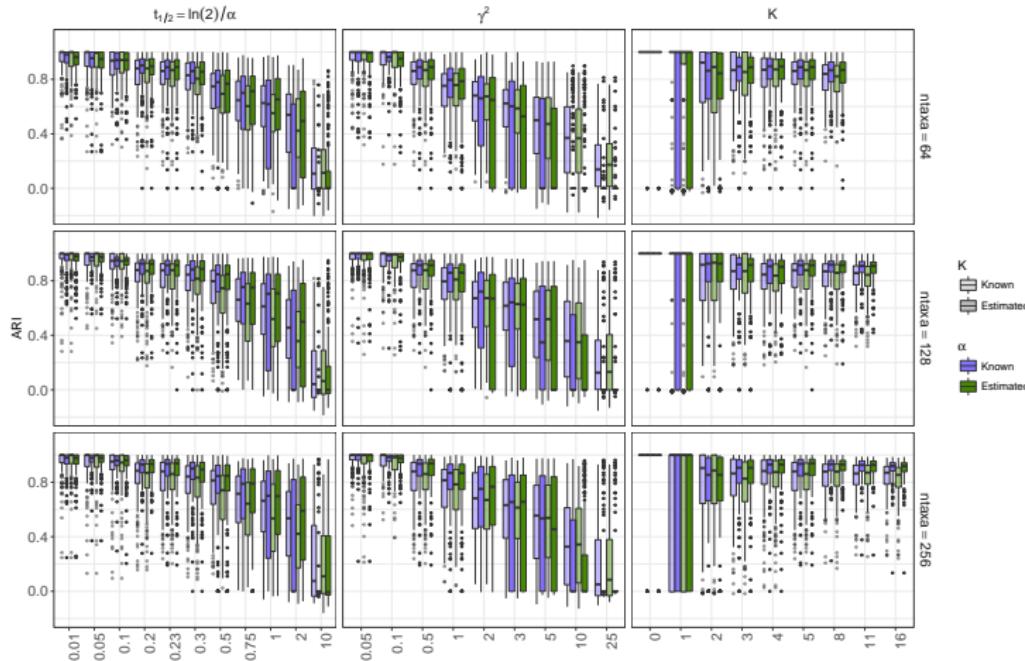
# Number of Shifts

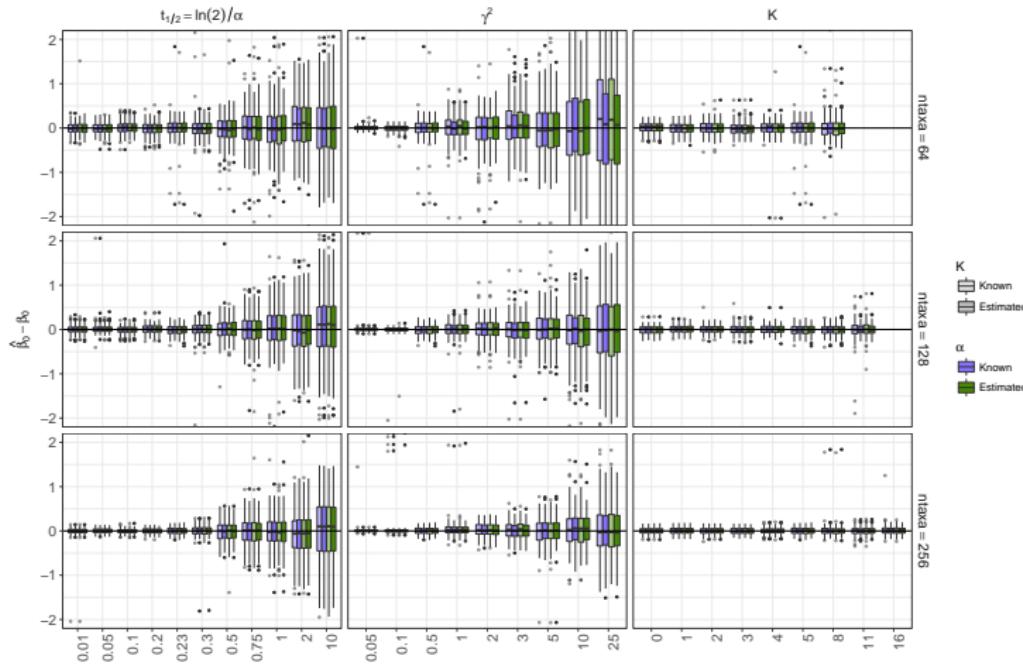


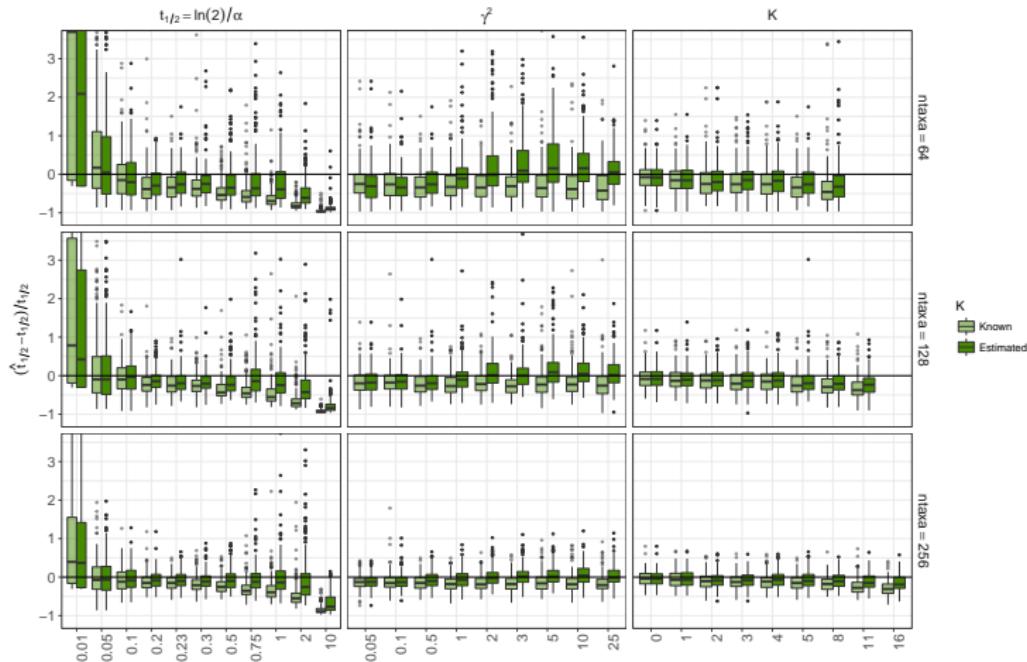
# One Example

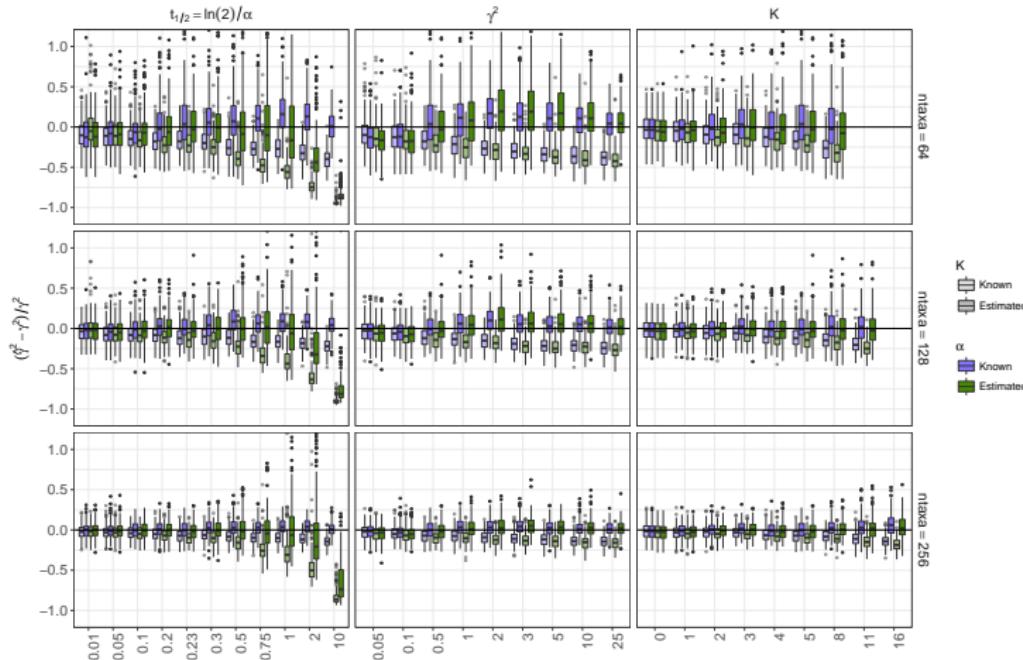


# Adjusted Rand Index

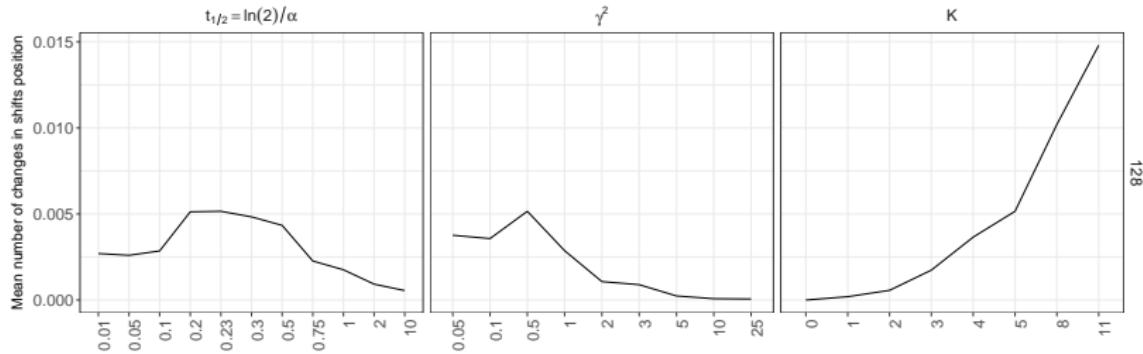


Parameters:  $\beta_0$ 

Parameters:  $\alpha$ 

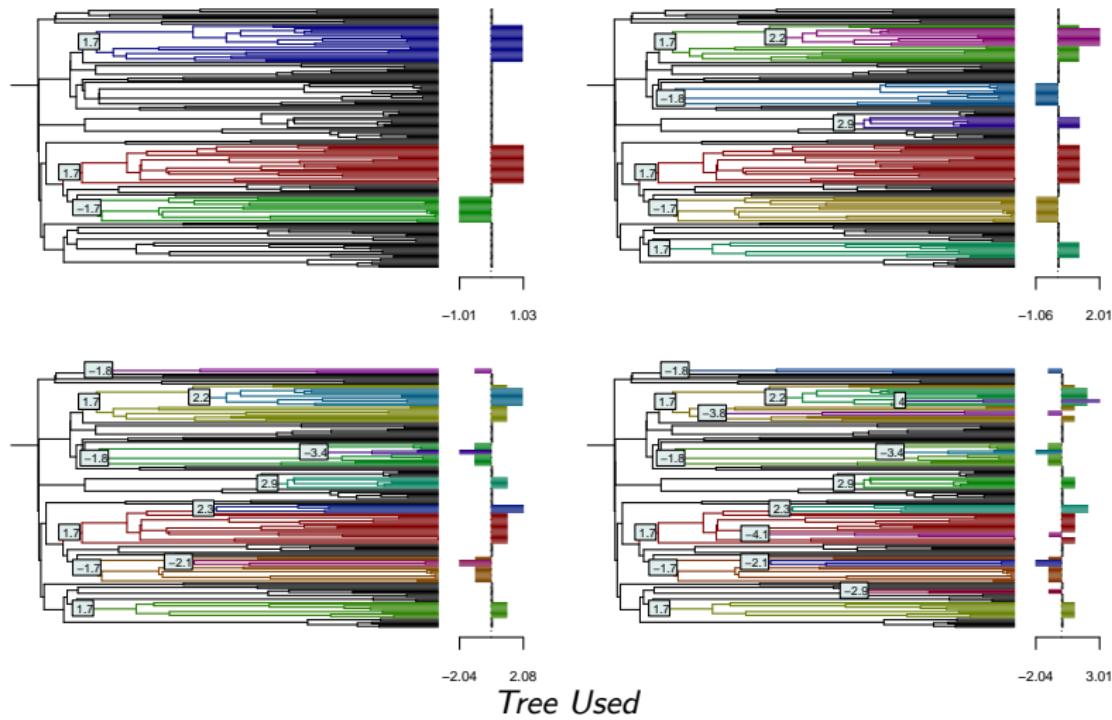
Parameters:  $\gamma^2$ 

# Exploration

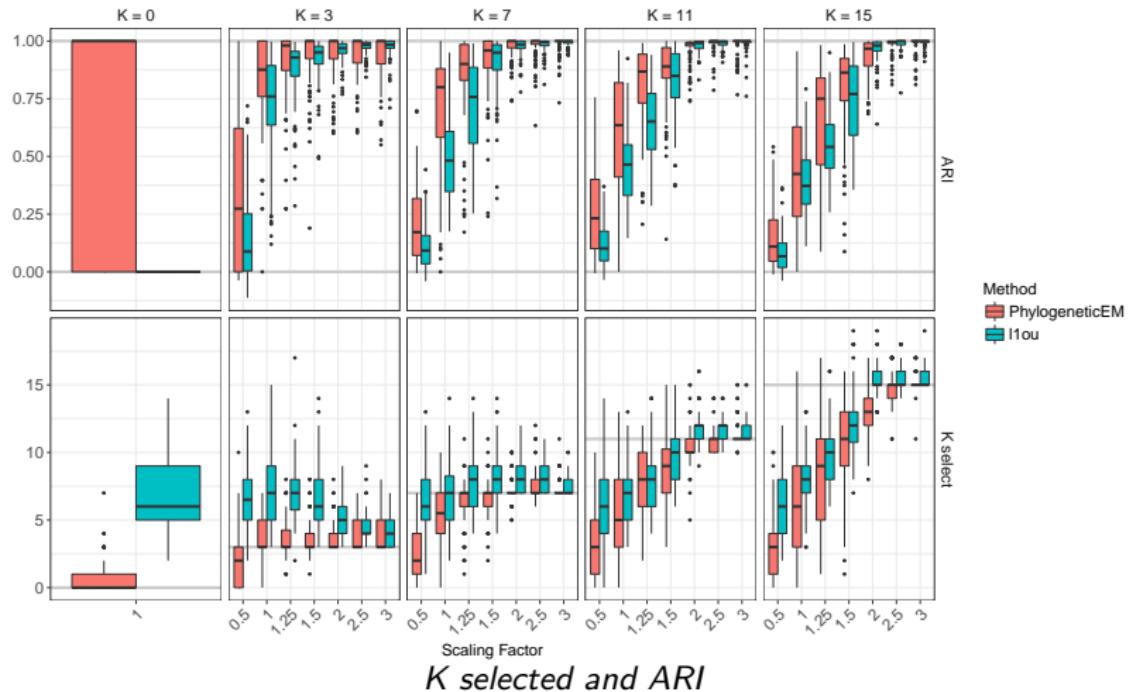


*Figure: Mean number changes in the shifts positions during the EM algorithm. Null means that the initial shifts were kept all along.*

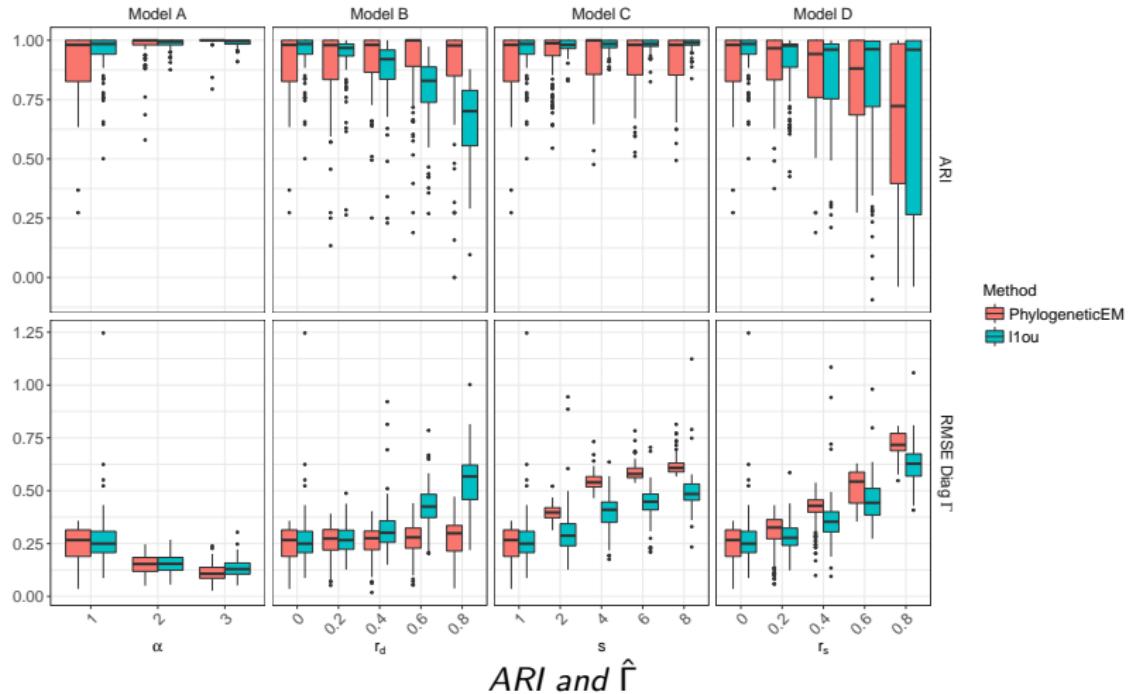
# Simulations: Experimental Design



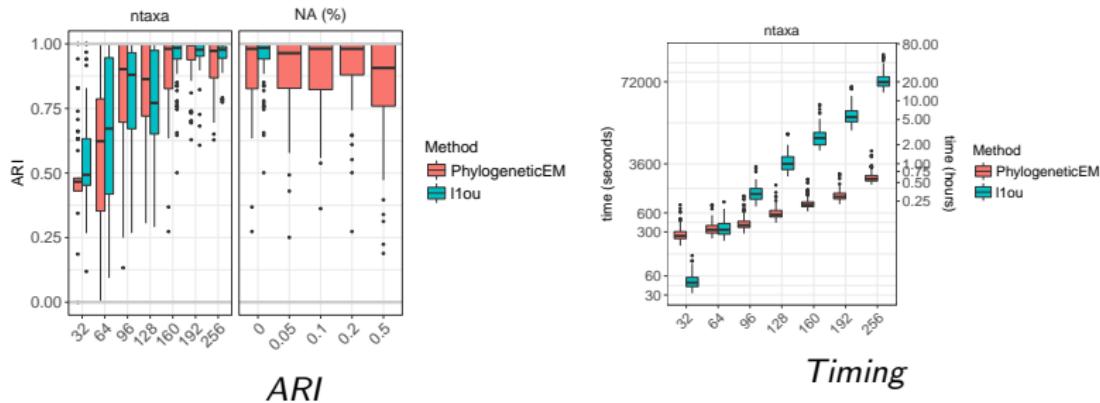
## Simulations: Model Selection

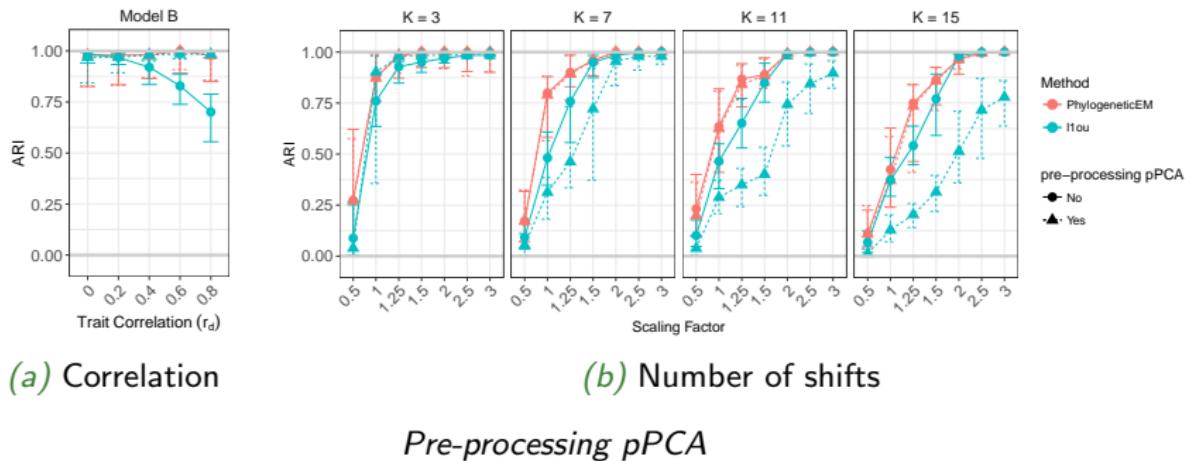


# Simulations: Model Selection and Estimation



# Simulations: Scalability





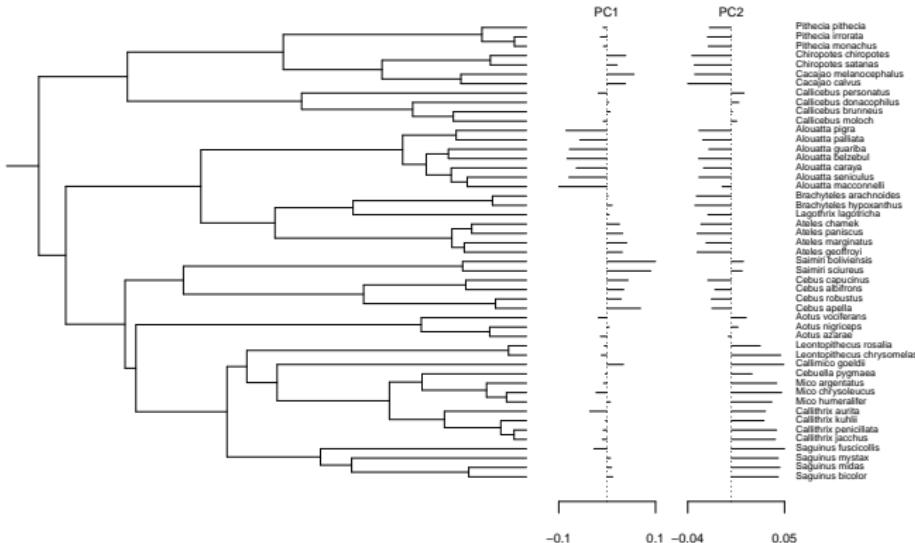
back

# Monkey Dataset

(Aristide et al., 2016)

```
data(monkeys)

plot(params_BM(p=2), data = monkeys$dat, phylo = monkeys$phy, show.tip.label = TRUE)
```



# Analysis

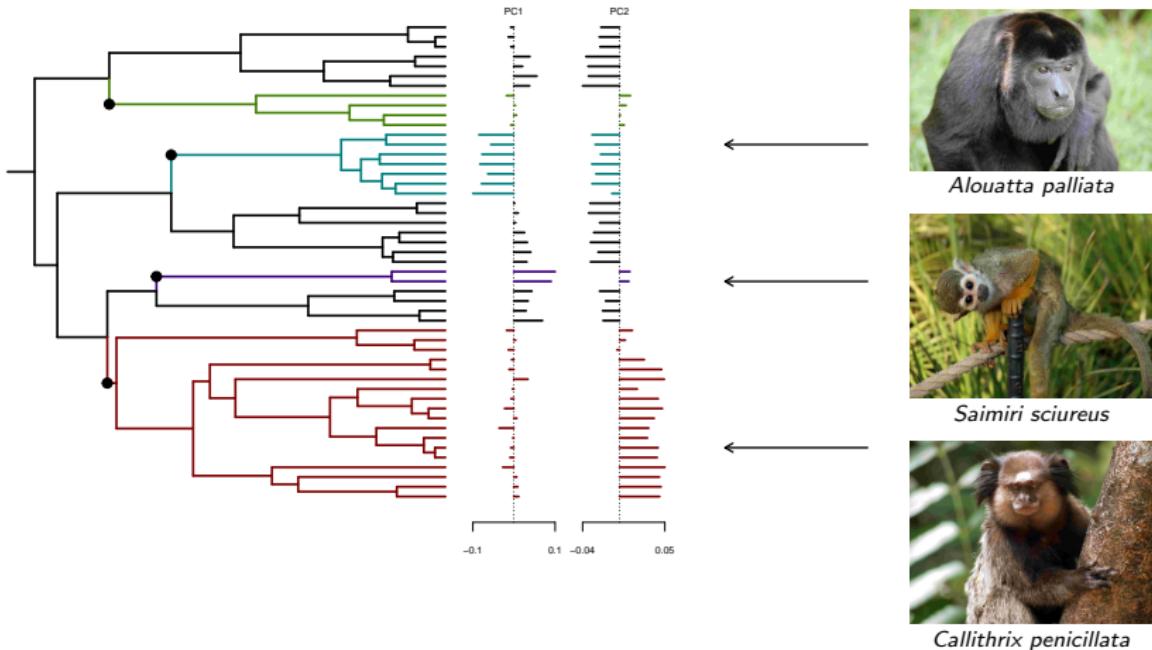
We use function PhyloEM:

```
res <- PhyloEM(Y_data = monkeys$dat,          ## data
                 phylo = monkeys$phy,       ## phylogeny
                 process = "scOU",        ## scalar OU
                 K_max = 10,              ## maximal number of shifts
                 nbr_alpha = 4,            ## number of alpha values
                 parallel_alpha = TRUE,   ## parallelize on alpha values
                 Ncores = 2)
```

Then plot the solution selected by the default method:

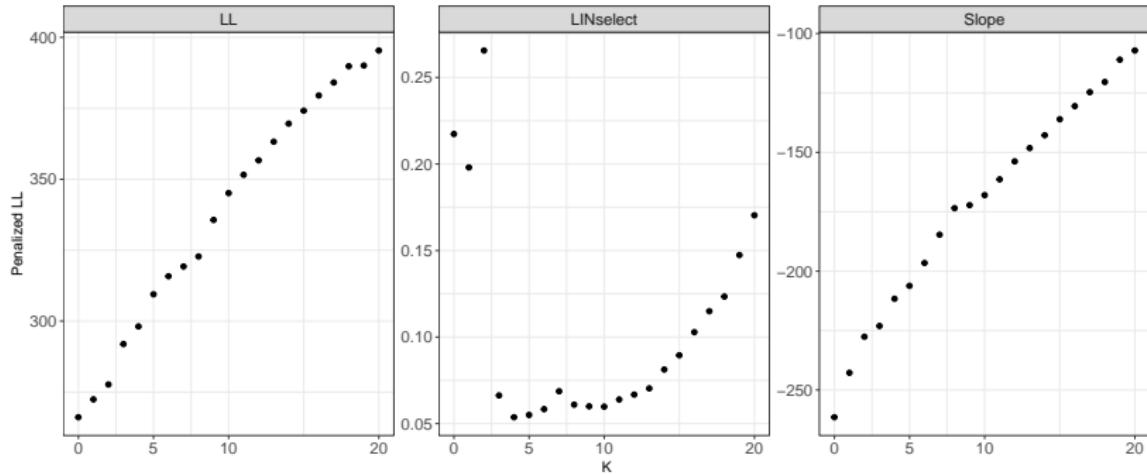
```
plot(res, edge.width = 2)
```

# Result



# Model Selection

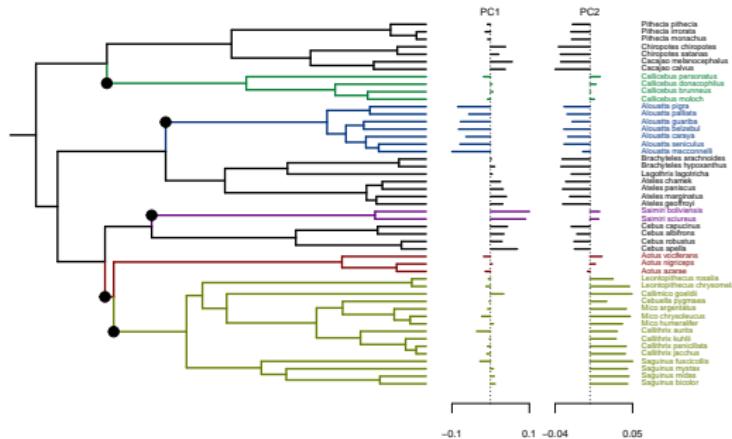
Solution with  $K = 5$  seems to be a good solution too.



# Solution for $K = 5$

```
plot(res, params = params_process(res, K = 5), edge.width = 2, show.tip.label = TRUE)
```

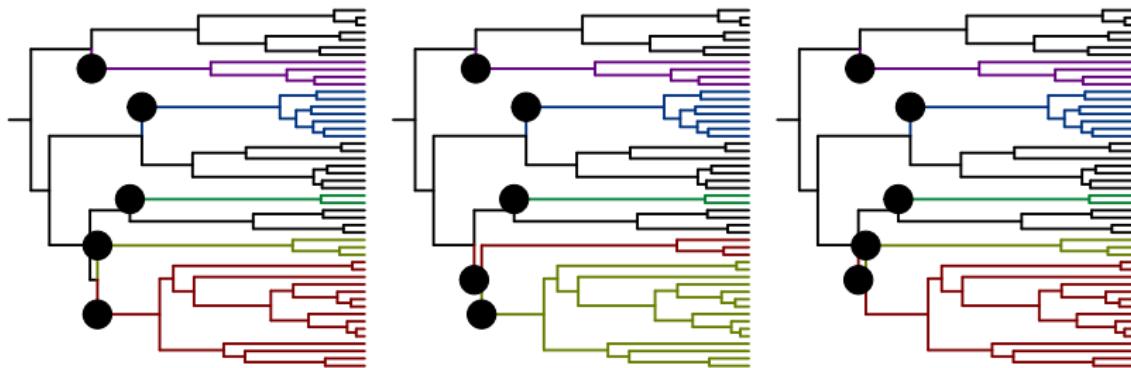
```
## Warning in params_process.PhyloEM(res, K = 5): There are several equivalent solutions for  
this shift position.
```



# Solution for $K = 5$

```
params_5 <- params_process(res, K = 5)
eq_shifts <- equivalent_shifts(monkeys$phy, params_5)
```

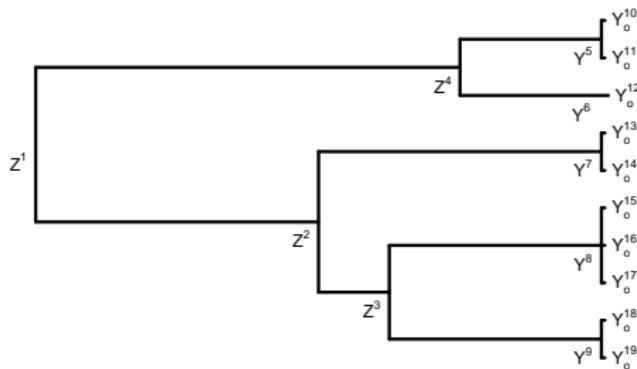
```
plot(eq_shifts)
```



back

## Measurement Error

(Felsenstein, 2008)



$$\mathbf{X} = \begin{cases} \mathbf{Y}_o & : \text{observed traits} \\ \mathbf{Y} & : \text{latent tips} \\ \mathbf{Z} & : \text{latent nodes} \end{cases}$$

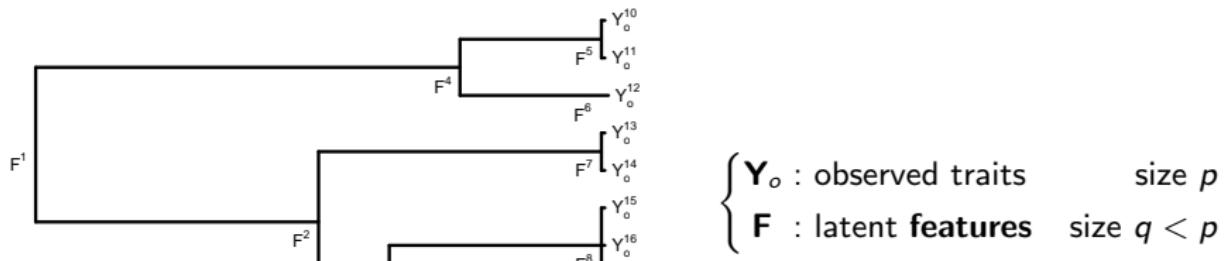
$$\mathbf{X}^1 \sim \mathcal{N}(\mu, \Gamma) \quad \text{root}$$

$$\mathbf{X}^j \mid \mathbf{X}^{\text{pa}(j)} \sim \mathcal{N}\left(\mathbf{X}^{\text{pa}(j)} + \boldsymbol{\Delta}^j, \ell_j \mathbf{R}\right) \quad \text{nodes } 2 \leq j \leq m+n$$

$$\mathbf{Y}_o^i \mid \mathbf{Y}^{\text{pa}(i)} \sim \mathcal{N}\left(\mathbf{Y}^{\text{pa}(i)}, \mathbf{P}\right) \quad \text{observations } m+n+1 \leq i \leq m+n+n_o.$$

# Factor Analysis

(Tolkoff et al., 2017)



$\mathbf{Y}_o$  : observed traits size  $p$   
 $\mathbf{F}$  : latent features size  $q < p$

$$\mathbf{F}^1 \sim \mathcal{N}(\mu_{\mathbf{F}}, \Gamma_{\mathbf{F}}) \quad \text{root}$$

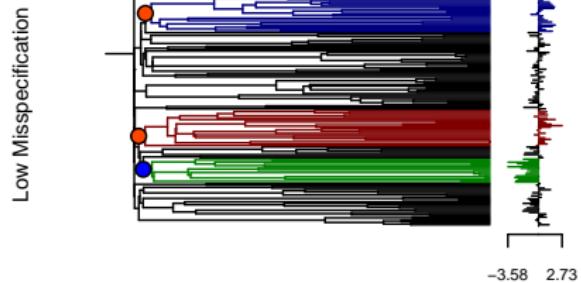
$$\mathbf{F}^j \mid \mathbf{F}^{\text{pa}(j)} \sim \mathcal{N}\left(\mathbf{X}^{\text{pa}(j)} + \boldsymbol{\Delta}^j, \ell_j \mathbf{I}_q\right) \quad \text{nodes } 2 \leq j \leq m+n$$

$$\mathbf{Y}_o^i \mid \mathbf{F}^{\text{pa}(i)} \sim \mathcal{N}\left(\mathbf{F}^{\text{pa}(i)} \mathbf{L}, \mathbf{P}\right) \quad \text{observations } m+n+1 \leq i \leq m+n+n_o.$$

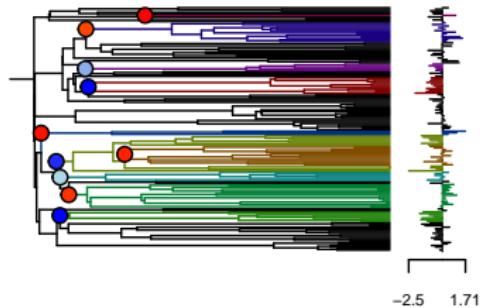
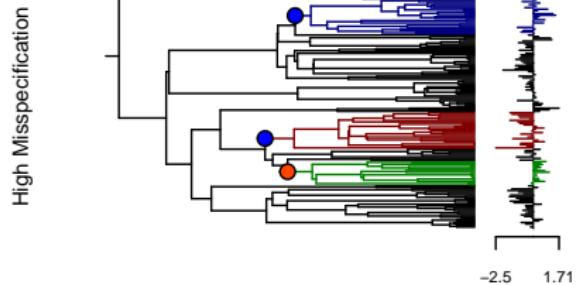
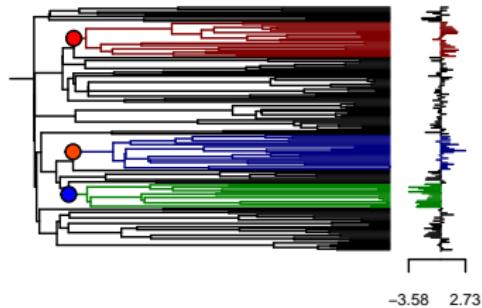
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# Tree Misspecification

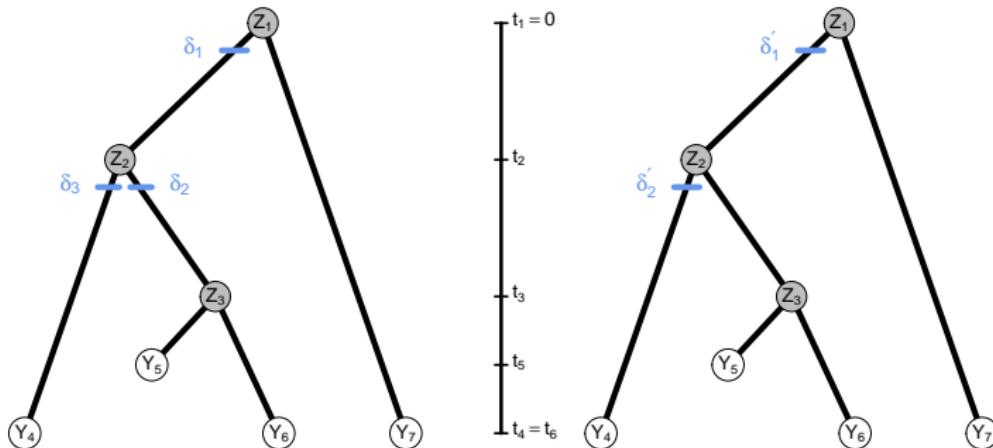
Simulation Tree and Shifts



Estimation Tree and Shifts



# Identifiability



*Figure: A non-ultrametric tree, with a “non parsimonious” solution on the left that cannot be reduced to the “parsimonious” one on the right for an OU.*

# Patterns in Missing Data

(Rubin, 1976)

 $\mathbf{Y}(n \times p)$  data $\mathbf{M}(n \times p)$  missing data indicator $p_\psi(\mathbf{M} | \mathbf{Y})$  sampling law

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(Rubin, 1976)

 $\mathbf{Y}(n \times p)$  data $\mathbf{M}(n \times p)$  missing data indicator $p_\psi(\mathbf{M} | \mathbf{Y})$  sampling law

EM:

$$\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

$$= \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

# Patterns in Missing Data

(Rubin, 1976)

 $\mathbf{Y}(n \times p)$  data $\mathbf{M}(n \times p)$  missing data indicator $p_\psi(\mathbf{M} | \mathbf{Y})$  sampling law

EM:

$$\begin{aligned}\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] \\ = \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]\end{aligned}$$

MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$

# Patterns in Missing Data

(Rubin, 1976)

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$$\mathbb{E} [\log p_{\theta, \psi}(\mathbf{Y}_{\text{obs}}, \mathbf{M}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

$$= \mathbb{E} [\log p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}] + \mathbb{E} [\log p_\theta(\mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}}, \mathbf{Z}) | \mathbf{Y}_{\text{obs}}, \mathbf{M}]$$

MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$

MAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}})$

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MCAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M})$ MAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}})$ NMAR:  $p_\psi(\mathbf{M} | \mathbf{Y}) = p_\psi(\mathbf{M} | \mathbf{Y}_{\text{obs}}, \mathbf{Y}_{\text{miss}})$ 

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