# CAS in Applied Data Science Muerren 2024



Géraldine Schaller-Conti

### Program of the week

12:30

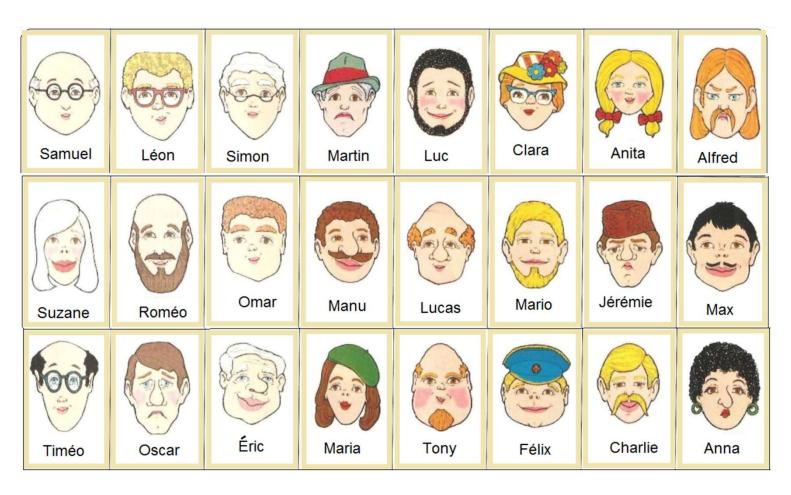
End

```
Convolutions
17:00 - 18:30 Tutorial (Geraldine)
19:00 - 20:00 Dinner at hotel Regina
20:30 - 21:00 Neural Style Transformations (an example on how to use deep ML to create art - Sigve)
Thursday (Geraldine)
                       Deep Forward Networks – optimization
08:15 - 09:00 Lecture
                       Transfer Learning
09:15 - 10:00 Tutorial
10:00 - 10:30 Coffee break
                      Transfer Learning
10:30 - 12:30 Tutorial
12:30 - 17:00 Skiing, work or whatever
17:00 - 18:15 Tutorial and project discussions Projects
19:00 - 22:00 Fondue and sledge ride back down to Regina in the dark
Everyone has to be READY OUTSIDE THE HOTEL at 18:45.
The train up departs at 19:00.
Friday (Geraldine)
                       Convolutional models and generative models
08:15 - 09:00 Lecture
                       Recurrent Neural Networks
09:15 - 10:00 Tutorial
10:00 - 10:30 Coffee break and Check Out
10:30 - 12:00 Tutorial / Discussion Session Recurrent Neural Networks
12:00 - 12:30 Wrap up (Sigve)
```

### About me ©

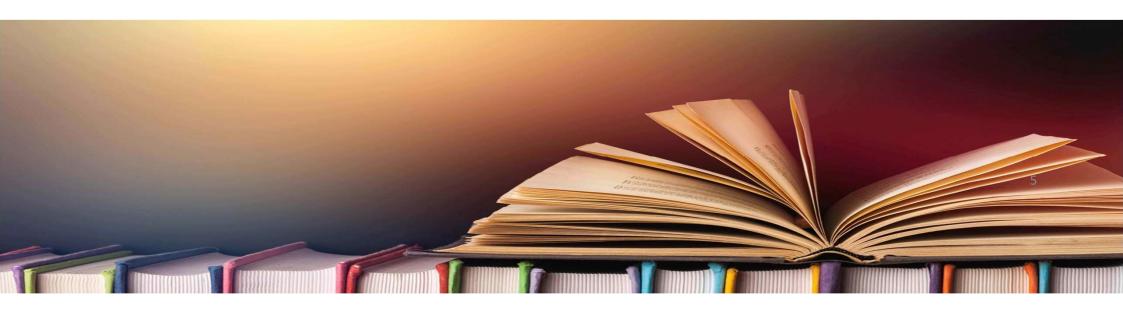


## About you ©



### Bibliography

- Deep Learning book (Goodfellow, Bengio, Courville)
- Machine Learning @ Stanford (Prof Andrew Ng)
- Hands-On Machine Learning with Scikit-Learn & Tensorflow (Aurélien Géron)



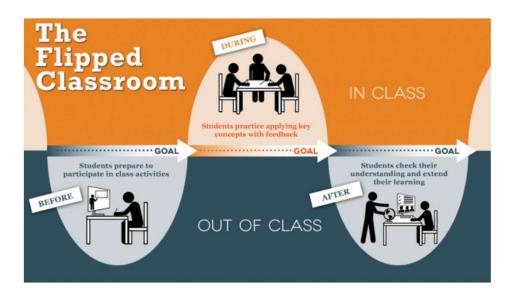
### Teaching method

#### Inverted classroom based

- Introduction lectures
- Real content you learn yourself with the notebooks. Either to put in practice your knowledge or to learn ahead of another lecture

#### Why

- Supposed to be better
- More fun
- Learning by doing



To give back sense to being present (Marcel Lebrun)



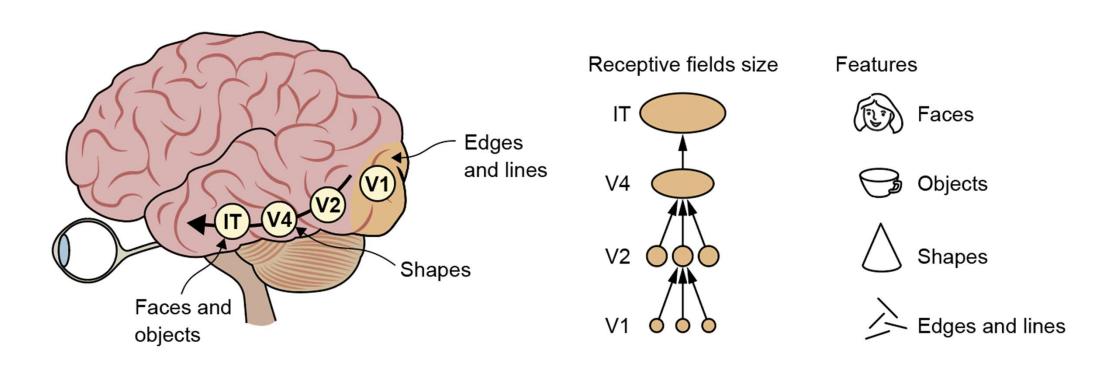
# Tutorial IV: Convolutions

### Introduction

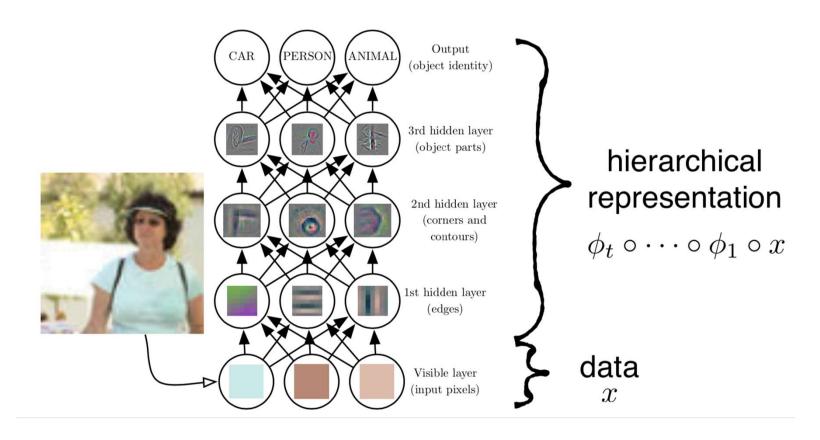
- Goal: basics to perform image recognition
- Program : inverted classroom style
  - Theory
  - Overview to get the big picture of the Notebook
  - Work alone (30 minutes)
  - Work in groups of 4 (30 minutes)
- Technical: Google Colab, Pytorch

# Theory

### Human vision

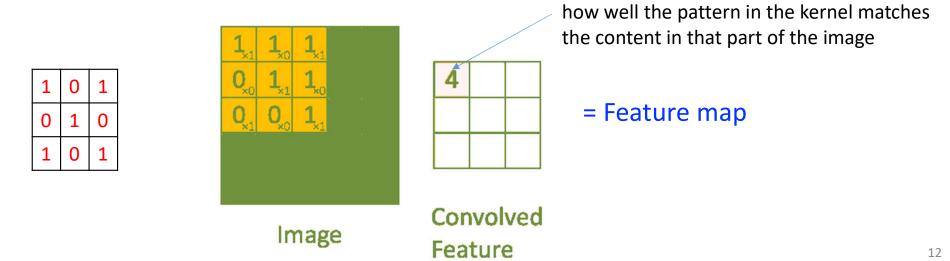


### Computer vision

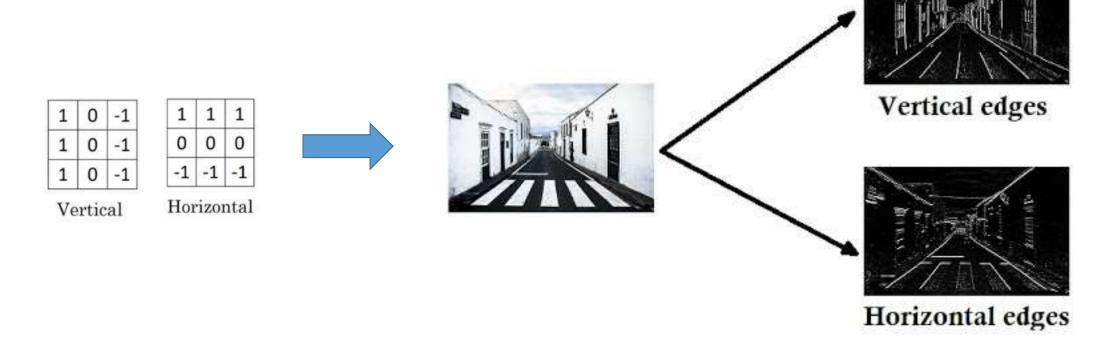


### Kernel (filter)

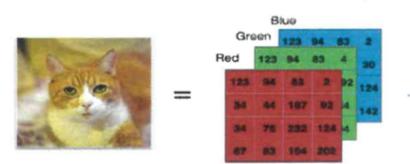
- Used to detect features (vertical/horizontal filter,...)
- Different kernels to create different feature maps → learn to see various patterns and details in images



## Kernel example



# Padding, Stride, Dilation



	ad	pa						
nad	0	0	0	0	0	0	0	0
pad	0	0	0	0	0	0	0	0
	0	0	2	83	94	133	0	0
	0	0	102	187	48	24	0	0
	0	0	126	222	79	24	0	0
	0	0	202	164	63	87	0	0
	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	0

	tO.	DE						
pad	0	0	0	0	0	0	0	O
Pac	0	0	0	0	0	0	0	0
	0	0	4	2	94	123	0	0
	0	0	192	22	3	11	0	0
	0	0	34	23		12	0	0
	0	0	94	12	83	194	0	0
	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	c

pad

1	2	3
4	5	6
7	8	9

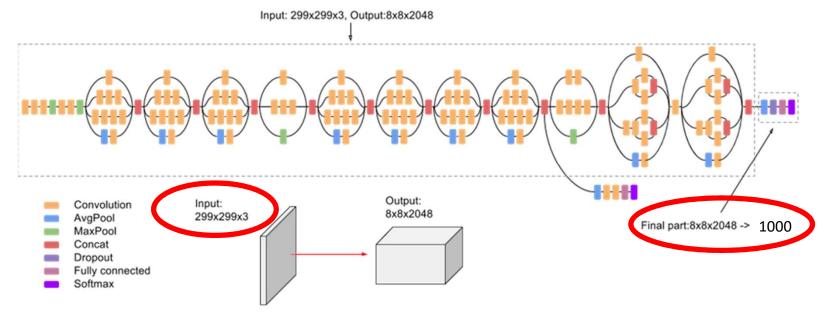


	1	2	3		
•		4	5	6	
			7	8	9

0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	123	94	81	2	0	0
0	0	34	44	37	30	0	0
0	0	94	114	224	124	0	0
9	0	69	10	204	143	0	0
a	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

### Inception V3 model

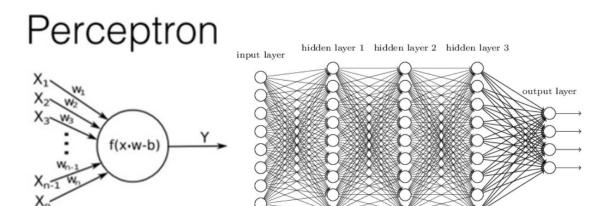
- Deep learning model based on Convolutional Neural Networks
- Used for image classification
- Released in year 2015
- It has 42 layers

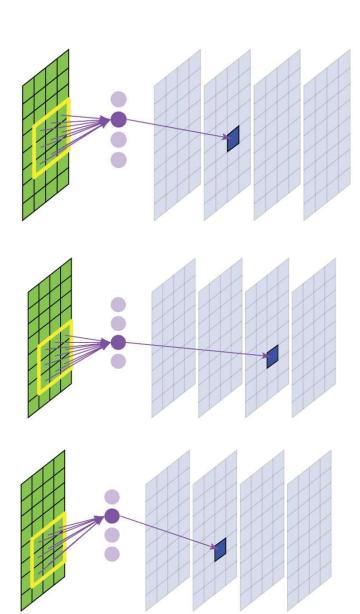


# Overview of the notebook

## Tutorial IV (1)

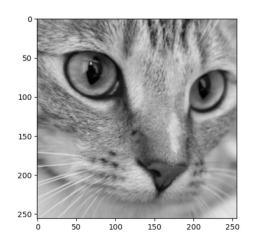
- 1) Load necessary libraries (common libraries and personal modules)
- 2) Images
- 3) Convolutions





### Tutorial IV (2)

- Pre-processing of the image
  - Gray-scale, cropping, float conversion, normalization
  - Add dimensions (batch, channel, height, width) (in get\_convolved)
  - Convert Numpy to pytorch (in get\_convolved)



- Define the convolution
  - Forward model (class Model)
  - Apply 4 convolutions one after each other (inside class Model, call conv\_2d function)
- Define the filter
  - Identity filter
  - Convert to np.array (in get\_convolved)
  - Add dimensions
  - Convert Numpy to pytorch

```
flt_mtx = [
     [ 0, 0, 0, 0, 0, ],
     [ 0, 0, 0, 0, 0, ],
     [ 0, 0, 1, 0, 0, ],
     [ 0, 0, 0, 0, 0, ],
     [ 0, 0, 0, 0, 0, ],
] # identity transformation
```

### Tutorial IV (3)

- Use it ! (ims\_convolved = get\_convolved(img\_raw, flt\_mtx))
  - You get back 5 figures

#### • Exercise :

- 1. experiment with different filters and understand what they do, e.g.:
- · identity transformation
- identity transformation with positive non-unit values
- identity transformation with negative unit value
- identity transformation off center
- · blurring with box filter
- edge detection with + and bands
- try whatever you like
- 2. experiment with convolution parameters:
- padding = 1, 2, 3
- stride = 2
- dilation = 2

0	0	0	0	0
0	0	0	0	0
0	0	30	0	0
0	0	0	0	0
0	0	0	0	0

0	0	0	0	0
0	0	0	0	0
0	0	-1	0	0
0	0	0	0	0
0	0	0	0	0

0	0	0	0	0
0	0	0	0	0
0	0	0	0	0
0	0	1	0	0
0	0	0	0	0

1	1	1	1	1
1	1	1	1	1
1	1	1	1	1
1	1	1	1	1
1	1	1	1	1

0	-1	1	0	0
0	-1	1	0	0
0	-1	1	0	0
0	-1	1	0	0
0	-1	1	0	0

### Tutorial IV (4)

filter type	effect
gaussian	bluring
first derivative of gaussian	detection of edges
second derivative of gaussian	detection of peaks

#### Most common filters

- Define 1D functions
- Create 2D filters by repeating the 1D filters along axis 0 (np.tile)
- Multiply by transpose() to get the horizontal dimension (filter size does not change)
- Use them ! (ims\_convolved = get\_convolved(img\_raw, flt\_mtx)

#### 4) Homework (leave it for now)

### Tutorial IV (5)

- 5) Load a pretrained model (inception V3) from torchhub
- 6) Test the model
- Preprocessing of the image (cropping, shuffle sizes, totensor, normalize adds batch size)  $\rightarrow$  [1,3,299,299]
- Desactivate the gradient (eval mode)
- Get the logits (1000 values), then the probabilities (applying softmax)
- Print out the 5 most probable classes
- Do the same with 100 classes

# Tutorial V: Transfer Learning

### Introduction

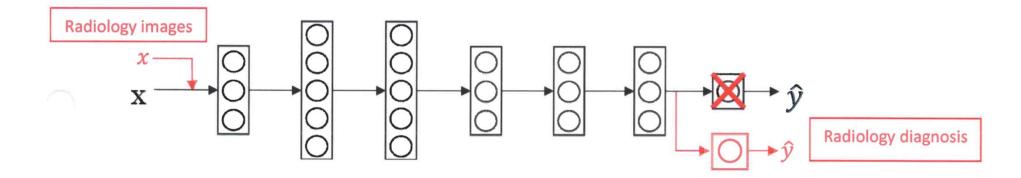
 Goal: use the Inception model to classify images of different nature, learn how to save a model

- Program : inverted classroom style
  - Theory
  - Overview to get the big picture of the notebook
  - Work alone ()
  - Work in groups of 4 (45 minutes, then 2 minute presentation)
- Technical: Google Colab, Pytorch

# Theory

### Transfer Learning

- Try to find an existing neural network that accomplishes a similar task to the one you are trying to tackle
- reuse the lower layers of this network
  - Output layer should usually be replaced
- Speeds up training and requires much fewer training data



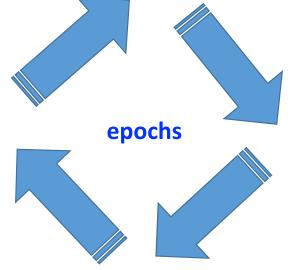
### Training Loop

• *Iterative* process

**Gradient descent**Parameter update

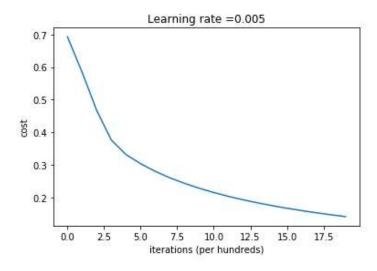
Forward propagation

Make a prediction



**Backward propagation** 

**Learning curve** 

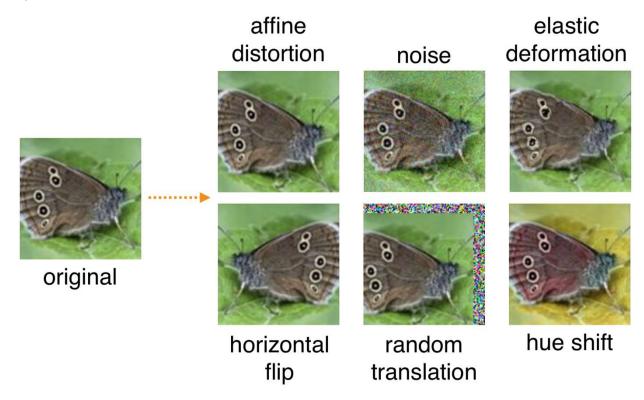


**Cost function** *Compute the error function* 

Measure the error contribution from each connection

### Dataset Augmentation

 Apply realistic transformations to data to create new synthetic samples, with same label



# Overview of the notebook

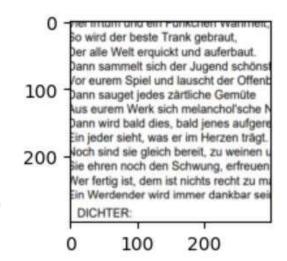
### Tutorial V (1)

- 1) Load necessary libraries (common libraries and personal modules)
- 2) Transfer Learning
- Load the inception model (base\_model)
- Build new model using the base\_model (model)
  - Define a head function (in\_features, n\_classes=2) : use of sigmoid
- Optimization: define the loss function (criterion) and the optimizer
- Helper functions to get the prediction (get\_predictions) and to compute the batch accuracy (calculate accuracy batch)

### Tutorial V (2)

#### 3) Dataset

- Images :
  - Get them from ML3 folder
  - Preprocessing using transforms.Compose (resize, tensor, normalize)
  - Shape [3,299,299]
  - Transform to numpy array for display (im\_numpy)
- Labels
- Split dataset into train/test samples
  - Torch.utils.data.random\_split
  - Train\_test\_split with stratify enabled from scikit-learn
- Create data loaders for training/val (beware shuffle param)
- Example: batch of 10 images, plot them, print logits and output classes (res)



### Tutorial V (3)

#### 4) Training

- Train\_model function
  - Contains the loop on epochs
  - Calls the train and validate functions (beware the params)
  - Save history (loss, accuracy) and model for a given epoch
  - Train function: reset gradients, compute logits and loss, compute gradients (backward prop), update parameters, calculate accuracy of the batch (helper functions), returns train loss and train accuracy
  - Validate function: structure BUT (no optimizer, no backward, no update of the params), returns test loss and test accuracy
- Plot\_history function
- Run it ! history = train\_model(...) using 70 epochs

### Tutorial V (4)

- 5) Load trained variables from checkpoint
  - Choose epochs values
  - Load corresponding models
  - Call validate function to get the validation loss and validation accuracy (see how it evolves)
- 6) Save final model for inference

### 7) Inference:

- Load the model, eval() mode
- Get an image, preprocess (convert to tensor, add batch dimension)
- Get the logits and associated class

### Tutorial V (4)

- 8) Improve the results: data augmentation
  - Load images from ML3 folder
  - Preprocess (resize, Randomcrop, tensor, normalize)
  - Convert to Numpy for plotting purposes (im\_numpy)
  - The rest of the code is similar to previous code
- 9) Exercise (groups of 4) (35 min), 2min presentation

# Tutorial VI: Transfer Learning

### Introduction

 Goal: use Recurrent Neural Networks to predict and generate text sequence

- Program : inverted classroom style
  - Theory
  - Overview to get the big picture of the notebook
  - Work alone
  - Work in groups of 4
- Technical: Google Colab, Pytorch

# Theory

# Overview of the notebook

### Tutorial VI (1)

- 1) Load necessary libraries (common libraries and personal modules)
- 2) Text data
  - Read the data (rnn.txt), print the first 100 words
- 3) Build the dataset
  - 2 dictionaries: word → id (dictionary) and id → word (reverse\_dictionary)
    - Build\_dictionaries function
  - Vocabulary size = 493 (0=most common word)
  - Helper functions to get sequences of int or words (text\_to\_ints, ints\_to\_text)
  - Print example : first 100 words (or int), length of input data=2118 (words\_as\_int)

### Tutorial VI (2)

#### 4) Data streaming

- Create dataset using WordDataSet class to create blocks of text
  - Block length = n\_input+1 = 3+1 = 4
- Create DataLoader with batch size=50, preprocess data (separate input and target sequences, stack data and convert Numpy > tensors, put them to GPU)
  - Length of dataset = Number of blocks in sequence = Total length/Block length = 2118/4=529
- Example: print the 50 samples that are in the 1st batch

# Back-up slides

• https://www.tensorflow.org/api\_docs/python/tf/keras/applications