

☑ philipp.becker@kit.edu | 🋠 pbecker93.github.io | 🗘 pbecker93 | 🛅 ph-becker | 🕿 Google Scholar

# **Key Research Expertise**

- Developed generative AI approaches for world modeling in reinforcement learning for robotics and image generation.
- Researched dynamics and representation learning for robotics from multimodal observations.
- · Proposed novel deep learning approaches to model continuous time series with structured and probabilistic state space models.
- Improved reinforcement and imitation learning in robotics contexts with information-theoretic methods.
- · Investigated how to quantify uncertainties in deep learning using Bayesian approaches and variational inference.

### Experience \_

#### Research Intern (6 months)

Cambridge, United Kingdom

SAMSUNG R&D INSTITUTE UK, AI CENTER - CAMBRIDGE, GEN AI TEAM

11/2024 - Present

- Trained large-scale generative AI methods for text-to-image using diffusion models across multiple GPUs.
- Explored structured state-space approaches and linear attention as efficient alternatives to self-attention in transformer architectures.

**Doctoral Researcher** Karlsruhe & Tübingen, Germany

KARLSRUHE INSTITUTE OF TECHNOLOGY (KIT), AUTONOMOUS LEARNING ROBOTS LAB (SINCE 01/2020) BOSCH CENTER FOR ARTIFICIAL INTELLIGENCE, ROBERT-BOSCH-GMBH (05/2019-12/2019)

05/2019 - Present

- · Published 4 first-author and 13 co-author publications at ICML, ICLR, NeurIPS, TMLR, RLC, RSS, CoRL, IROS, and ICRA.
- Supervised 25+ Bachelor and Master students, often in collaboration with other labs, leading to 8 co-author publications.
- Ensured robust compute availability for efficient research in the lab by setting up and maintaining local GPU resources (SLURM-based cluster, desktop pool), supervising the development of experiment deployment tools, and coordinating with public providers of large-scale compute.
- Demonstrated organizational and problem-solving skills by supporting the establishment of two research labs and ensuring operational continuity during challenges such as the shift to remote lectures during COVID-19 and lab closures and relocations due to infrastructure issues.
- Organized, designed exams and exercises, and presented solutions for "Machine Learning Foundations and Algorithms" (graduate level lecture, 150+ students) as the head teaching assistant for 3 years.
- Guest lectured on model-based reinforcement learning to 50+ students for "Reinforcement Learning" (graduate level lecture).

**Research Scientist** Karlsruhe, Germany

FZI RESEARCH CENTER FOR INFORMATION TECHNOLOGY, (FZI FORSCHUNGSZENTRUM INFORMATIK)

04/2023 - 07/2024

- Worked towards establishing a new research group under the direction of Prof. Gerhard Neumann.
- Contributed to securing funding for the EU Horizon project XSCAVE (€8M total, €950K to FZI from 2025 to 2028), aimed at advancing Al-driven planning and control for heavy machinery in industries like forestry and mining.
- Collaborated on research grant proposals with academic and industry partners, focusing on AI for production, energy, and heavy machinery.
- Successfully evaluated structured reinforcement learning approaches for control applications of an industry customer.

**Student Researcher** 

TECHNICAL UNIVERSITY OF DARMSTADT, INTELLIGENT AUTONOMOUS SYSTEMS

04/2016 - 04/2019

- Developed a software stack for point cloud-based active segmentation with real and simulated robots in C++ using ROS and PCL.
- · Collaborated on robotics projects, including a policy learning toolbox, feasibility studies on real robots, and setting up simulations.

Student Intern Munich, Germany

'DEEP LEARNING AND ROBOTICS CHALLENGE' AT VOLKSWAGEN GROUP, DATA LAB IN COLLABORATION WITH NVIDIA

09/2017

• Developed a Lego robot with control and deep learning perception stacks, for autonomous deployment on the Lego system and a NVIDIA Jetson.

### **Education**

#### Ph.D. in Computer Science, Machine Learning (Ongoing)

Karlsruhe, Germany

KARLSRUHE INSTITUTE OF TECHNOLOGY, AUTONOMOUS LEARNING ROBOTS LAB

01/2020 - 06/2025 (Expected)

- Thesis: Learning and Inference with Probabilistic World and Behavior Models for Decision Making and Control.
- · Advisor: Gerhard Neumann

TECHNICAL UNIVERSITY OF DARMSTADT,

#### Master of Science in Autonomous Systems (Computer Science), with Distinction

Darmstadt, Germany

11/2016 - 04/2019

- Thesis: Expected Information Maximization: Using the I-Projection for Mixture Density Estimation.
- · Honors: ECTS A Ranking, Deutschlandstipendium (Germany Scholarship), awarded for academic excellence (2016–2019).

TECHNICAL UNIVERSITY OF DARMSTADT

#### **Summer Schools**

ML Frameworks
ML Infrastructure

Robotics

- Nordic Probabilistic Al School, Trondheim, Norway, June 2023
- Machine Learning Summer School, Virtual (Tübingen, Germany), July 2020

## First Author Publications \_\_\_\_\_

Combining Reconstruction and Contrastive Methods for Multimodal Representations in RL	RLC
BECKER, P., MOSSBURGER, S., OTTO, F., NEUMANN, G.	2024
KalMamba: Towards Efficient Probabilistic State Space Models for RL under Uncertainty	Workshop, ICML & RLC
BECKER, P., FREYMUTH N., NEUMANN, G.	2024
On Uncertainty in Deep State Space Models for Model-Based Reinforcement Learning	TMLR
BECKER, P., NEUMANN, G.	2022
Expected Information Maximization: Using the I-Projection for Mixture Density Estimation	ICLR
BECKER, P., ARENZ, O., NEUMANN, G.	2020
Recurrent Kalman Networks: Factorized Inference in High-Dimensional Deep Feature Spaces	ICML
BECKER, P., PANDYA, H., GEBHARDT, G., ZHAO, C., TAYLOR, J., NEUMANN, G.	2019
Co-Author Publications (Selected, see 🖘)	
Geometry-aware RL for Manipulation of Varying Shapes and Deformable Objects	ICLR
Hoang, T., Le, H., <b>Becker, P.</b> , Anh Ngo, V., Neumann, G.	2025
Efficient Off-Policy Learning for High-Dimensional Action Spaces	ICLR
Otto, F., <b>Becker, P.</b> , Anh Ngo, V., Neumann, G.	2025
PointPatchRL - Masked Reconstruction Improves Reinforcement Learning on Point Clouds	CoRL
Gyenes, B., Franke, N., <b>Becker, P.</b> , Neumann G.	2024
MuTT: A Multimodal Trajectory Transformer for Robot Skills	IROS
Kienle C., Alt B., Celik O., <b>Becker P.</b> , Katic D., Jäkel R., Neumann G.	2024
Beyond Deep Ensembles: A Large-Scale Evaluation of Bayesian Deep Learning under Distribution S	Shift NeurIPS
Seligmann, F., <b>Becker, P.</b> , Volpp, M., Neumann, G.	2023
Accurate Bayesian Meta-Learning by Accurate Task Posterior Inference	ICLR
Volpp, M., Dahlinger, P., <b>Becker, P.</b> , Daniel, C., Neumann, G.	2023
Hidden Parameter Recurrent State Space Models For Changing Dynamics Scenarios	ICLR
Shaj, V., Büchler, D., Sonker, R., <b>Becker, P.</b> , Neumann, G.	2022
Specializing Versatile Skill Libraries using Local Mixture of Experts	CoRL
CELIK, O., ZHOU, D., LI, G., BECKER, P., NEUMANN, G.	2021
Differentiable Trust Region Layers for Deep Reinforcement Learning	ICLR
OTTO, F., BECKER, P., ANH NGO, V., ZIESCHE, H, NEUMANN, G.	2021
Action-Conditional Recurrent Kalman Networks For Forward and Inverse Dynamics Learning	CORL
Shaj, V., Becker, P., Buchler, D., Pandya, H., van Duijkeren, N., Taylor, J., Hanheide M., Neumann, G.	2020
Reviewing	
Machine Learning TMLR, NeurIPS, ICLR, ICML, CoRL, RLC  Robotics RA-L, IROS, ICRA	
Skills	
Programming Python, Java, C++, C, Matlab, Bash/Shell Scripting  MI Frameworks Di Tarch Tarcorflow, Jav. Korse Di Tarch Lightning multi CDI /multi node model training	

PyTorch, Tensorflow, Jax, Keras, PyTorch Lightning, multi-GPU/multi-node model training

Git, Slurm, Docker, WandB, TensorBoard, Matplotlib, Pandas, Hydra, Optuna

MuJoCo, Mitsubishi PA10, KUKA LBR iiwa, Franka Emika Panda