MACHINE LEARNING IN BIOINFORMATICS

FEATURE SELECTION

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MOTIVATION

Feature selection problem

$$\hat{\theta} = \begin{cases} \underset{\theta}{\text{arg min}} & \|y - X\theta\|_2^2 \\ & \text{subject to} & \|\theta\|_0 = m \end{cases} \text{ with } \binom{p}{m} \text{ possible subsets}$$

- Required are computationally efficient methods to approximate the feature selection problem
- Offline methods: Select features before estimating parameters
- Online methods: Features are selected during parameter estimation

FEATURE SELECTION METHODS

- Offline methods:
 - ► Safe and Strong rules
 - Sure independence screening (SIS)
 - ► Estimation of mutual information
- Online methods:
 - ► (Orthogonal) matching pursuit
 - Least angle regression (LARS) / Homotopy algorithm
 - ► Penalty methods

LINEAR REGRESSION - RECAP

$$\begin{aligned} y &= X\theta + \epsilon \\ \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} &= \begin{bmatrix} x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(p)} \\ x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(p)} \\ \vdots & \vdots & \ddots & \vdots \\ x_n^{(1)} & x_n^{(2)} & \dots & x_n^{(p)} \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_p \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix} \end{aligned}$$

response: $y \in \mathbb{R}^n$

covariates : $X \in \mathbb{R}^{n \times p}$

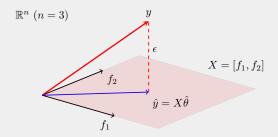
coefficients : $\theta \in \mathbb{R}^p$

residuals : $\epsilon \in \mathbb{R}^n$

LINEAR REGRESSION - RECAP

Geometric interpretation of ordinary least squares [Hastie et al., 2009]:

$$\begin{split} \hat{\theta} &= \operatorname*{arg\,min}_{\theta} \|\epsilon\|_2^2 \\ &= \operatorname*{arg\,min}_{\theta} \|y - X\theta\|_2^2 \end{split}$$



- Consider the case of ultrahigh-dimensional data, where the number of features *p* is much larger than the number of observations *n*
- Specifically, we assume that p is so large that we cannot compute an estimate of θ
- Assuming θ is sparse, we can first select a promising subset of q features M_q (called feature screening)
- lacktriangle The coefficients heta are estimated based on the subset M_q

■ Consider the solution of rigde regression:

$$\hat{\theta}(\lambda) = (X^{\top}X + \lambda I)^{-1}X^{\top}y$$

- For $\lambda \rightarrow$ 0 we obtain the OLS solution
- For $\lambda \to \infty$ it follows that $\lambda \hat{\theta}(\lambda)$ converges to the componentwise regression estimator

$$\hat{\theta}_k(\lambda) = \tilde{X}^{\top} y$$

where \widetilde{X} is the data matrix X with normalized columns f_j such that $f_i^{ op}f_j=$ 1

■ Traditionally, for very large p we would select λ large in order to decrease the variance of $\hat{\theta}$

- $\tilde{X}^{\top}y = (f_1^{\top}y, \dots, f_p^{\top}y)$ can be interpreted as the correlation of features f_i with y
- Sure independence screening (SIS) [Fan and Lv, 2008] selects a subset of features

$$\Omega = \left\{ j \mid |f_j^\top y| > t \right\} \tag{1}$$

based on their correlation with y, where t is a threshold such that $|\Omega| = q < p$

- The OLS estimate $\hat{\theta}$ is computed using only the selected features Ω
- All remaining components of $\hat{\theta}$ are set to zero

■ The same idea can be applied to more complex models [Fan and Song, 2010], such as logistic regression, where

$$\hat{\theta} = \arg\max_{\theta} \operatorname{pr}_{\theta}(\mathbf{y} \,|\, \mathbf{X})$$

Select a subset of features

$$\Omega = \{ j \mid \text{score}(f_j, y) > t \}$$
 (2)

■ The score is given by the independent estimate

$$score(f_j, y) = \arg\max_{\theta_j} \max_{\theta_j} (y \mid f_j)$$

for all $j = 1, \ldots, p$

MATCHING PURSUIT FOR LINEAR RE-

GRESSION

Feature selection problem

$$\hat{\theta} = \begin{cases} \arg\min & \|y - X\theta\|_2^2 \\ \theta & \text{with } \binom{p}{m} \text{ possible subsets} \end{cases}$$
subject to $\|\theta\|_0 = m$

Feature selection problem

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Matching Pursuit

Greedy approximation to feature selection problem.

Feature selection problem

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If we must represent y with only one feature, which one should we take?

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Greedy approximation to feature selection problem.

If we must represent y with only one feature, which one should we take?

$$j_1 = \mathop{\mathrm{arg\,min}}_j \left\| y - f_j \hat{ heta}_j
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$$\begin{split} j_1 &= \operatorname*{arg\,min}_j \left\| y - f_j \hat{\theta}_j \right\|_2^2 \,, \quad \text{where} \quad \hat{\theta}_j = \operatorname*{arg\,min}_{\theta_j} \left\| y - f_j \theta_j \right\|_2^2 \\ &= \operatorname*{arg\,max}_j \frac{(f_j^\top y)^2}{f_j^\top f_j} \\ &= \operatorname*{arg\,max}_j \left| f_j^\top y \right| \end{split}$$

[assuming normalized data, i.e. $f_j^{\top} f_j = 1$]

 \Rightarrow select feature j with maximal scalar projection of y onto f_j

$$\epsilon = y - X\theta$$

$$= \underbrace{y - f_{j_1}\theta_{j_1} - f_{j_2}\theta_{j_2}}_{r_0} - \dots - f_{j_p}\theta_{j_p}$$

$$j_{1} = \underset{j}{\operatorname{arg \, min}} \left\| y - f_{j} \hat{\theta}_{j} \right\|_{2}^{2} = \underset{j}{\operatorname{arg \, min}} \left\| r_{0} - f_{j} \hat{\theta}_{j} \right\|_{2}^{2}$$

$$= \underset{j}{\operatorname{arg \, max}} \left| f_{j}^{\top} r_{0} \right|$$

$$\epsilon = y - X\theta$$

$$= \underbrace{y - f_{j_1}\theta_{j_1} - f_{j_2}\theta_{j_2}}_{r_1} - \dots - f_{j_p}\theta_{j_p}$$

$$\begin{aligned} j_1 &= \arg\min_{j} \left\| \mathbf{y} - f_j \hat{\theta}_j \right\|_2^2 &= \arg\min_{j} \left\| \mathbf{r}_0 - f_j \hat{\theta}_j \right\|_2^2 \\ &= \arg\max_{j} \left| f_j^\top \mathbf{r}_0 \right| \\ j_2 &= \arg\min_{j} \left\| \mathbf{y} - f_{j_1} \hat{\theta}_{j_1} - f_j \hat{\theta}_j \right\|_2^2 &= \arg\min_{j} \left\| \mathbf{r}_1 - f_j \hat{\theta}_j \right\|_2^2 \\ &= \arg\max_{j} \left| f_j^\top \mathbf{r}_1 \right| \end{aligned}$$

Matching pusuit (MP) [Tropp et al., 2007]

The MP feature selection rule is given by

$$j_k = \arg\max_j \left| f_j^{\top} r_{k-1} \right| \qquad k = 1, \dots, m$$

where r_k are the residuals at step k:

$$\epsilon = y - X\theta$$

$$= \underbrace{y - f_{j_1}\theta_{j_1} - f_{j_2}\theta_{j_2}}_{r_0} - \dots - f_{j_p}\theta_{j_p}$$

Orthogonal Matching Pursuit

Orthogonal Matching Pursuit: Re-estimate parameters after every iteration.

After every iteration t, update all θ_{Ω_t} entries, where $\Omega_t = \{j_1, j_2, \dots, j_t\}$, i.e. compute

$$\theta_{\Omega_t} = \operatorname*{arg\,min}_{\theta} \left\| y_{\Omega_t} - X_{\Omega_t} \theta \right\|_2^2.$$

This update changes the residuals

$$r_t = y - f_{j_1}\theta_{j_1} - f_{j_2}\theta_{j_2} - \cdots - f_{j_t}\theta_{j_t}$$

used in the next iteration of the algorithm.

MATCHING PURSUIT FOR LOGISTIC RE-

GRESSION





LOGISTIC REGRESSION

$$\begin{bmatrix} \operatorname{pr}_{\theta}(y_{1} = 1) \\ \operatorname{pr}_{\theta}(y_{2} = 1) \\ \vdots \\ \operatorname{pr}_{\theta}(y_{n} = 1) \end{bmatrix} = \sigma \begin{pmatrix} \begin{bmatrix} x_{1}^{(1)} & x_{1}^{(2)} & \dots & x_{1}^{(p)} \\ x_{2}^{(1)} & x_{2}^{(2)} & \dots & x_{2}^{(p)} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n}^{(1)} & x_{n}^{(2)} & \dots & x_{n}^{(p)} \end{bmatrix} \begin{bmatrix} \theta_{1} \\ \theta_{2} \\ \vdots \\ \theta_{p} \end{bmatrix} \end{pmatrix}$$

class labels: $y \in \{0,1\}^n$

covariates : $X \in \mathbb{R}^{n \times p}$

coefficients : $\theta \in \mathbb{R}^p$

LOGISTIC REGRESSION

Parameter estimation for logistic regression:

$$\begin{split} \hat{\theta} &= \arg\max_{\theta} \operatorname{pr}_{\theta}(y) \approx \arg\min_{\theta} \|y - \sigma(X\theta)\|_{2}^{2} \quad \text{[but not convex]} \\ &= \arg\max_{\theta} \sum_{i=1}^{n} \log \operatorname{pr}_{\theta}(y_{i}) \\ &= \arg\max_{\theta} \sum_{i=1}^{n} \left\{ y_{i} \log \sigma(x_{i}\theta) + (1 - y_{i}) \log(-x_{i}\theta) \right\} \\ &= \arg\max_{\theta} \sum_{i=1}^{n} \log \sigma(\tilde{y}_{i}x_{i}\theta) \,, \end{split}$$

where $\tilde{y}_i = 2y_i - 1 \in \{-1, 1\}$

Pseudo-residuals

$$r_k = y - \sigma(f_{j_1}\theta_{j_1} + f_{j_2}\theta_{j_2} + \dots + f_{j_k}\theta_{j_k})$$
$$X^{\top}r_p = \nabla \log \operatorname{pr}_{\theta}(y)$$

Pseudo-residuals

$$\begin{aligned} r_k &= y - \sigma(f_{j_1}\theta_{j_1} + f_{j_2}\theta_{j_2} + \dots + f_{j_k}\theta_{j_k}) \\ X^\top r_p &= \nabla \log \operatorname{pr}_{\theta}(y) \end{aligned}$$

$$j_1 = \underset{j}{\operatorname{arg \, min}} \left\| y - \sigma(f_j \hat{\theta}_j) \right\|_2^2$$

$$\approx \underset{j}{\operatorname{arg \, max}} \left| f_j^{\top} r_0 \right|$$

Pseudo-residuals

$$\begin{aligned} r_k &= y - \sigma(f_{j_1}\theta_{j_1} + f_{j_2}\theta_{j_2} + \dots + f_{j_k}\theta_{j_k}) \\ X^\top r_p &= \nabla \log \operatorname{pr}_{\theta}(y) \end{aligned}$$

$$\begin{aligned} j_1 &= \arg\min_{j} \left\| y - \sigma(f_j \hat{\theta}_j) \right\|_2^2 \\ &\approx \arg\max_{j} \left| f_j^\top r_0 \right| \\ j_2 &= \arg\min_{j} \left\| y - \sigma(f_{j_1} \hat{\theta}_{j_1} - f_j \hat{\theta}_j) \right\|_2^2 \\ &\approx \arg\max_{j} \left| f_j^\top r_1 \right| \end{aligned}$$

Matching pursuit feature selection rule [Lozano et al., 2011]

Assuming normalized data, i.e. $f_i^{\top} f_j = 1$, the OMP rule is given by

$$j_{k} = \arg\max_{j} \left| f_{j}^{\top} r_{k-1} \right|$$

where r_k are the kth pseudo-residuals

$$r_k = y - \sigma(f_{j_1}\theta_{j_1} + f_{j_2}\theta_{j_2} + \dots + f_{j_k}\theta_{j_k})$$
$$X^{\top}r_p = \nabla \log \operatorname{pr}_{\theta}(y)$$

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$$X^{\top}r_p = \nabla \log \operatorname{pr}_{\theta}(y)$$

OMP Performance

Greedy strategy causes poor performance of Orthogonal Matching Pursuit in practice

 \blacksquare Consider ℓ_1 -penalized linear regression (LASSO) where

$$\hat{\theta}(\lambda) = \operatorname*{arg\,min}_{\theta} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|_{\mathbf{2}}^{2} + \lambda \|\boldsymbol{\theta}\|_{\mathbf{1}}$$

- There exists a regularization strength $\lambda = \lambda_{max}$ for which all estimated coefficients are zero
- Least Angle Regression (LARS) [Efron et al., 2004] is a method to efficiently compute $\hat{\theta}(\lambda)$ for all $0 \le \lambda \le \lambda_{\max}$
- LARS computes breakpoints λ_k at which individual coefficients $\hat{\theta}_i(\lambda_k) \in \mathbb{R}$ change its value from
 - ► zero to non-zero, or from
 - non-zero to zero
- Between breakpoints the values of coefficients can be linearly interpolated

■ Remember that the OLS solution $\hat{\theta}(o)$ for $\lambda = o$ requires that

$$\nabla_{\theta} \| \mathbf{y} - \mathbf{X} \mathbf{\theta} \|_{2}^{2} = 2 \mathbf{X}^{\top} (\mathbf{y} - \mathbf{X} \mathbf{\theta}) = 0$$

■ For λ > 0 the solution requires

$$X^{\top}(y - X\theta) \in \frac{\lambda}{2} \partial \|\theta\|_{1}$$

where $\partial \|\theta\|_1$ is the subgradient with respect to θ

■ We define

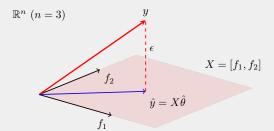
$$c(\theta) = X^{\top}(y - X\theta)$$

which is interpreted as the correlation of features $X = [f_1, f_2, \dots, f_p]$ with the residuals $\epsilon = y - X\theta$

■ The correlation $\hat{c}(\lambda) = c(\hat{\theta}(\lambda))$ varies with λ as follows:

$$ightharpoonup \hat{c}(\lambda) = c_{\max} \text{ for } \lambda = \lambda_{\max}$$

$$ightharpoonup$$
 $\hat{c}(\lambda) = o$ for $\lambda = o$



- LARS maintains a set of active features $\Omega \subset \{1, \dots, p\}$ all equally correlated with the residuals $y X\hat{\theta}(\lambda)$ for the current estimate $\hat{\theta}(\lambda)$
- Let $X_{\Omega} = (f_j)_{j \in \Omega}$ denote the covariate matrix and $\theta_{\Omega} = (\theta_j)_{j \in \Omega}$ the coefficients restricted to the features in the active set Ω
- \blacksquare In each iteration, the coefficients θ are updated

$$\theta \leftarrow \theta + \gamma^* \mathbf{V}$$
,

where γ^* is the amount by which the correlation $c_{\Omega}(\theta)$ is reduced and $v \in \mathbb{R}^p$ defines the direction and relative size of the update

■ The vector \mathbf{v} is selected so that for features in Ω the difference in correlation $c_{\Omega}(\theta) - c_{\Omega}(\theta + \gamma \mathbf{v})$ shrinks uniformly towards zero with rate γ , i.e.

$$\begin{split} c_{\Omega}\left(\theta\right) - c_{\Omega}\left(\theta + \gamma \mathbf{v}\right) &= \gamma \operatorname{sign} c_{\Omega}(\theta)\,, \quad \text{while} \\ c_{\Omega^{c}}(\theta) - c_{\Omega^{c}}(\theta + \gamma \mathbf{v}) &= \mathbf{0}\,. \end{split}$$

■ Both conditions can be combined into

$$c(\theta) - c(\theta + \gamma v) = \gamma \operatorname{sign} c(\theta),$$

since $\operatorname{sign} c_{\Omega^c}(\theta) = \mathsf{O}$

■ It follows that

$$\mathbf{v}_{\Omega} = [\mathbf{X}_{\Omega}^{\top} \mathbf{X}_{\Omega}]^{-1} \operatorname{sign} \mathbf{c}_{\Omega}(\theta)$$

and $v_{\Omega^c} = 0$

- LARS stop shrinking the correlations whenever:
 - Case 1: A non-active feature becomes equally correlated with the residuals
 - ► Case 2: A coefficient of an active feature becomes zero¹
- Case 1: More formally, γ is increased until some feature $j' \in \Omega^c$ outside the active group satisfies

$$|c_{j'}(\theta + \gamma \mathbf{v})| = |c_j(\theta + \gamma \mathbf{v})|$$

= $\lambda - \gamma$,

where $j \in \Omega$, and $\lambda = |c_j(\theta)|$ is the absolute correlation of the active features

¹This case was not part of the initial LARS algorithm but was later on added in order to ensure equivalence with the LASSO (see also Homotopy algorithm [Osborne et al., 2000])

LEAST ANGLE REGRESSION (LARS)

■ The solution is given by

$$\gamma^{+} = \min_{j \in \Omega^{c}}^{+} \left\{ \frac{\lambda - c_{j}(\theta)}{1 - f_{j}^{\top} X v}, \frac{\lambda + c_{j}(\theta)}{1 + f_{j}^{\top} X v} \right\} ,$$

where \min^+ is the minimum over positive elements and note that $f_i^\top X v = f_i^\top X_\Omega v_\Omega$

 \blacksquare Case 2: The algorithm also removes a feature \emph{j} from the active set when for some γ

$$\theta_{\it j} + \gamma {\rm V}_{\it j} = {\rm O}$$

so that $\gamma^- = \min_{j \in \Omega} \{-\theta_j/\mathbf{v}_j\}$

■ The subsequent breakpoint is given by $\gamma^* = \min\{\gamma^+, \gamma^-\}$

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SAFE AND STRONG RULES

ℓ_1 -PENALIZED REGRESSION

Penalized regression

$$\omega(\theta) = -\log \mathrm{pr}_{\theta}(y)$$
 (logistic regression), or $\omega(\theta) = \|y - X\theta\|_2^2$ (linear regression)

$$\hat{\theta} = egin{cases} \arg\min & \omega(\theta) \\ \theta \\ \mathrm{subject\ to} & \|\theta\|_{1} = \Lambda \end{cases}$$

Basic idea: Select Λ such that $\|\theta\|_{\Omega} = m$

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ℓ_1 -PENALIZED REGRESSION

Numerical solution of penalized regression

Identify saddle points of Lagrangian

$$\mathcal{L}(\theta, \lambda) = \omega(\theta) + \lambda(\|\theta\|_{1} - \Lambda)$$

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$\ell_{ extsf{1}} extsf{-}\mathsf{PENALIZED}$ REGRESSION

Numerical solution of penalized regression

Identify saddle points of Lagrangian

$$\mathcal{L}(\theta, \lambda) = \omega(\theta) + \lambda(\|\theta\|_{1} - \Lambda)$$

In practice the constraint $\|\theta\|_1 = \Lambda$ is ignored, but λ is chosen such that classification performance is optimal:

Penalized regression in practice

$$\hat{\theta}(\lambda) = \operatorname*{arg\,min}_{\theta} \omega(\theta) + \lambda \left\|\theta\right\|_{1}$$

SAFE RULE FOR LINEAR REGRESSION

SAFE rule: What features can we neglect for a fixed λ ?

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SAFE rule [Ghaoui et al., 2010, Kim et al., 2007] for ℓ_1 -penalized linear regression

jth component of $\hat{\theta}$ must be zero if

$$\begin{aligned} |f_j^\top y| &< \lambda - \left\| f_j \right\|_2 \left\| y \right\|_2 \frac{\lambda_{\max} - \lambda}{\lambda_{\max}} \\ \lambda_{\max} &= \max_j |f_j^\top y| \end{aligned}$$

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$$|f_j^{\top}(y - \underbrace{\chi_{\theta=0}})| < \lambda - \|f_j\|_2 \|y\|_2 \frac{\lambda_{\max} - \lambda}{\lambda_{\max}}$$

STRONG RULE FOR LINEAR REGRESSION

SAFE rule for linear regression: jth component of $\hat{\theta}$ must be zero if

$$\begin{aligned} |f_j^\top y| &< \lambda - \left\| f_j \right\|_2 \|y\|_2 \, \frac{\lambda_{\max} - \lambda}{\lambda_{\max}} \\ \lambda_{\max} &= \max_j |f_j^\top y| \end{aligned}$$

Strong rule for ℓ_1 -penalized linear regression [Tibshirani et al., 2012]

Discard jth component if

$$|f_j^\top y| < \lambda - (\lambda_{max} - \lambda) = 2\lambda - \lambda_{max}$$
$$\lambda_{max} = \max_j |f_j^\top y|$$

STRONG RULE FOR LINEAR REGRESSION

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Remark

Strong rule may drop features that should not be discarded \Rightarrow KKT conditions must be checked, i.e.

$$X^{\top}(y - X\hat{\theta}) \in \lambda \partial_{\theta = \hat{\theta}} \|\theta\|_{1}$$

STRONG SEQUENTIAL RULE FOR LINEAR REGRESSION

Strong rule for ℓ_1 -penalized linear regression [Tibshirani et al.. 2012]

Discard jth component if

$$\begin{split} |f_j^\top y| &< \lambda - \left(\lambda_{\max} - \lambda\right) = \mathbf{2}\lambda - \lambda_{\max} \\ \lambda_{\max} &= \max_j |f_j^\top y| \end{split}$$

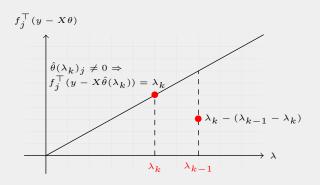
Strong sequential rule for ℓ_1 -penalized linear regression[Tibshirani et al., 2012]

Discard *i*th feature if

$$|f_j^{\top}\{y - \sigma(X\hat{\theta}(\lambda_{k-1}))\}| < 2\lambda_k - \lambda_{k-1}$$

STRONG SEQUENTIAL RULE FOR LINEAR REGRESSION

Compute $\hat{\theta}(\lambda_k)$ for all $\lambda_1 > \cdots > \lambda_k > \cdots > \lambda_K$



Assumption :
$$|f_j^{\top}(y - X\hat{\theta}(\lambda_{k-1} - \epsilon)) - f_j^{\top}(y - X\hat{\theta}(\lambda_{k-1}))| \le \epsilon$$

$$\Rightarrow |f_j^{\top}(y - X\hat{\theta}(\lambda_{k-1}))| < 2\lambda_k - \lambda_{k-1}$$

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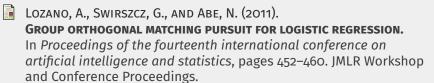
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DERIVATION OF THE SAFE RULE FOR LINEAR REGRESSION

$$\hat{\theta} = \operatorname*{arg\,min}_{\theta} \left\| y - X\theta \right\|_{2}^{2} + \lambda \left\| \theta \right\|_{1}$$

Define

$$\beta = y - X\theta$$

Equivalent optimization problem

$$\hat{\theta} = \begin{cases} \underset{\theta}{\text{arg min}} & \beta^{\top}\beta + \lambda \|\theta\|_{1} \\ \text{subject to} & \beta = y - X\theta \end{cases}$$

DERIVATION OF THE SAFE RULE FOR LINEAR REGRESSION

Lagrangian

$$\mathcal{L}(\theta, \beta, \nu) = \beta^{\top} \beta + \lambda \|\theta\|_{1} + \nu^{\top} (\mathbf{y} - \mathbf{X}\theta - \beta)$$

Dual function

$$\inf_{\theta,\beta} \mathcal{L}(\theta,\beta,\nu) = \begin{cases} \mathsf{G}(\nu) & \text{if } |f_j^\top \nu| \leq \lambda \,, \, j = 1,\dots,p \\ -\infty & \text{otherwise} \end{cases}$$

where $G(\nu) = -\frac{1}{4}\nu^{\top}\nu + \nu^{\top}y$. Lagrange dual

$$\hat{ heta}^* = egin{cases} {\sf arg\,max} & {\it G}(
u) \ {\sf subject\,to} & |f_j^{ op}
u| \leq \lambda \,, \, j=1,\dots,p \end{cases}$$

DERIVATION OF THE SAFE RULE FOR LINEAR REGRESSION

Side note: Since the primal problem satisfies Slater's condition, we know that the duality gap $\gamma=\hat{\theta}-\hat{\theta}^*$ is zero, i.e.

$$\hat{\theta} = \hat{\theta}^*$$

For a dual feasible point ν_0 , we solve for each $j=1,\ldots,p$

$$\begin{aligned} \xi_j(\nu_{\mathsf{O}}) &= \begin{cases} \arg\max & |f_j^\top \nu| \\ \text{subject to} & \textit{G}(\nu) \geq \textit{G}(\nu_{\mathsf{O}}) \end{cases} \\ &= |f_j^\top y| + \sqrt{(y^\top y - 2\textit{G}(\nu_{\mathsf{O}}))f_j^\top f_j} \end{aligned}$$

If $\xi_j(\nu_0)<\lambda$ we know that $\hat{\theta}_j=$ o. A simple dual feasible point is $\nu_0=y\lambda/\lambda_{max}$. The SAFE rule is obtained from

$$\xi_j(y\lambda/\lambda_{max}) < \lambda$$

LOGISTIC REGRESSION CLASSIFIER

SAGA algorithm [Defazio et al., 2014]: select $j \in \{1, \dots, n\}$ at random

$$\begin{split} &\vartheta_{j,t+1} = \theta_t \\ &\vartheta_{i,t+1} = \vartheta_{i,t+1} \text{ for all } i \neq j \\ &\theta_{t+1}^* = \theta_t - \gamma \left[\nabla \ell_j(\vartheta_{j,t+1}) - \nabla \ell_j(\vartheta_{j,t}) + \frac{1}{n} \sum_{i=1}^n \nabla \ell_i(\vartheta_{i,t}) \right] \\ &\theta_{t+1} = \arg\min_{\theta} \left\{ \lambda \|\theta\|_1 + \frac{1}{2\gamma} \|\theta - \theta_{t+1}^*\|_2^2 \right\} \end{split}$$