

Controller

anchors : list
cam_positions : list
dim : tuple
freq : float
instructions : Optional[list[spidercam_simulator.Instruction]]
logger : Logger, RootLogger, NoneType
rope_lengths : list
spidercam : Spidercam

from_dict(data: dict): 'Controller'
get_rope_lengths(position: tuple): list[tuple]
run(): tuple[list[tuple], list[tuple]]
store_anchors(): None