

FileHandler logger : Logger, RootLogger, NoneType output\_dir : str output\_files : tuple

destination : tuple logger : RootLogger, Logger, NoneType start\_time : float parse(data: str): 'Instruction'

Instruction

Parser

logger : Logger, RootLogger, NoneType

parse\_input(string: str): dict parse\_output(dim: tuple, freq: float, cam\_positions: list[tuple], rope\_lengths: list[tuple]): tuple

## Plotter

cam\_positions : ndarray
dim : Optional[tuple]

freq : float

logger: RootLogger, Logger, NoneType name: Optional[str] output\_dir: Optional[str] rope\_lengths: ndarray

plot(): None

plot\_cam\_positions(): None plot\_rope\_lengths(): None