

Movement
logger : RootLogger, NoneType, Logger phases : list spidercam : Spidercam start_time : float
calculate_phases(start: tuple, destination: tuple): None destination(): tuple distance(): float duration(): float end_time(): float get_phase(time: float): spidercam_simulator.Phase get_position(time: float): tuple start(): tuple start_deceleration(time: float): None