

## 12. Support Vector Machines II

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**DaST**  
Data • (Systems+Theory)

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## Support Vector Machines: Story So Far

- Primal Formulation of SVM: Minimise the **hinge loss** with regularisation
- Slack variables  $\zeta_i$  for linearly (**non**-)separable data

$$\text{minimise: } \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \zeta_i$$

$$\text{subject to: } y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \geq 1 - \zeta_i$$

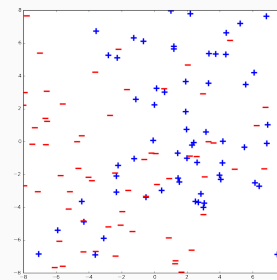
$$\zeta_i \geq 0$$

$$\text{for } 1 \leq i \leq N$$

Here  $y_i \in \{-1, 1\}$

For the optimal solution:

$$\zeta_i = \max\{0, 1 - y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0)\}$$



## Optimisation Background: Constrained Optimisation with Inequalities

### Primal Form

$$\begin{aligned} &\text{minimise} && F(\mathbf{z}) \\ &\text{subject to} && g_i(\mathbf{z}) \geq 0 && i = 1, \dots, m \\ &&& h_j(\mathbf{z}) = 0 && j = 1, \dots, \ell \end{aligned}$$

### Lagrange Function

$$\Lambda(\mathbf{z}; \alpha, \mu) = F(\mathbf{z}) - \sum_{i=1}^m \alpha_i g_i(\mathbf{z}) - \sum_{j=1}^{\ell} \mu_j h_j(\mathbf{z})$$

Primal variables:  $\mathbf{z}$ . Dual variables:  $\alpha, \mu$ .

## Karush-Kuhn-Tucker (KKT) Conditions

### Lagrange Function

$$\Lambda(\mathbf{z}; \alpha, \mu) = F(\mathbf{z}) - \sum_{i=1}^m \alpha_i g_i(\mathbf{z}) - \sum_{j=1}^{\ell} \mu_j h_j(\mathbf{z})$$

### Karush-Kuhn-Tucker (KKT) conditions

$$\text{Dual feasibility: } \alpha_i \geq 0 \quad \text{for } i = 1, \dots, m$$

$$\begin{aligned} \text{Primal feasibility: } &g_i(\mathbf{z}) \geq 0 && \text{for } i = 1, \dots, m \\ &h_j(\mathbf{z}) = 0 && \text{for } j = 1, \dots, \ell \end{aligned}$$

$$\text{Complementary slackness: } \alpha_i g_i(\mathbf{z}) = 0 \quad \text{for } i = 1, \dots, m$$

- For **convex** problems: KKT conditions are **necessary and sufficient** for a critical point of  $\Lambda$  to be the minimum of the original constrained optimisation
- For **non-convex** problems: KKT are **necessary but not sufficient**

## From Primal to Dual SVM Formulation: The Linearly Separable Case

$$\text{minimise: } \frac{1}{2} \|\mathbf{w}\|_2^2 \quad \text{subject to: } y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \geq 1 \quad \text{for } 1 \leq i \leq N$$

The Lagrange function and its gradients wrt the primal variables:

$$\Lambda(\mathbf{w}, w_0; \alpha) = \frac{1}{2} \|\mathbf{w}\|_2^2 - \sum_{i=1}^N \underbrace{\alpha_i}_{\text{dual variables}} \underbrace{(y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) - 1)}_{\text{constraints}}$$

$$\frac{\partial \Lambda}{\partial w_0} = - \sum_{i=1}^N \alpha_i y_i \quad \nabla_{\mathbf{w}} \Lambda = \mathbf{w} - \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

At optimality, these gradients are 0:

$$\sum_{i=1}^N \alpha_i y_i = 0 \quad \mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

## Computing $w_0$ using the Optimal Values for Variables $\mathbf{w}$ and $\alpha$

Optimal  $\mathbf{w}$  obtained as  $\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$

At optimality:  $y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) = 1$ , for all  $1 \leq i \leq N$

We can obtain  $w_0$  using the above equality constraint for any  $i$ :

$$y_i^2 \left( \left( \sum_{j=1}^N \alpha_j y_j \mathbf{x}_j \right) \cdot \mathbf{x}_i + w_0 \right) = y_i \Rightarrow w_0 = y_i - \sum_{j=1}^N \alpha_j y_j (\mathbf{x}_j \cdot \mathbf{x}_i)$$

It is numerically more stable to have  $w_0$  the average over all possible values:

$$w_0 = \frac{1}{N} \sum_{i=1}^N \left( y_i - \sum_{j=1}^N \alpha_j y_j (\mathbf{x}_j \cdot \mathbf{x}_i) \right)$$

We expressed optimal  $\mathbf{w}$  and  $w_0$  as functions of  $\alpha$ . **How can we compute  $\alpha$ ?**

## Reduced Expression of the Lagrange Function

Plug the optimal  $\mathbf{w}$  and constraint  $\sum_{i=1}^N \alpha_i y_i = 0$  into Lagrangian:

$$\begin{aligned} g(\alpha) &= \frac{1}{2} \left( \underbrace{\mathbf{w}}_{\sum_{i=1}^N \alpha_i y_i \mathbf{x}_i} \right)^T \underbrace{\mathbf{w}}_{\sum_{i=1}^N \alpha_i y_i \mathbf{x}_i} - \sum_{i=1}^N \alpha_i y_i \underbrace{\mathbf{w}}_{\sum_{i=1}^N \alpha_i y_i \mathbf{x}_i} \cdot \mathbf{x}_i - \underbrace{\sum_{i=1}^N \alpha_i y_i \mathbf{w}_0}_0 + \sum_{i=1}^N \alpha_i \\ &= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i y_i \alpha_j y_j (\mathbf{x}_i \cdot \mathbf{x}_j) - \sum_{i=1}^N \sum_{j=1}^N \alpha_i y_i \alpha_j y_j (\mathbf{x}_i \cdot \mathbf{x}_j) + \sum_{i=1}^N \alpha_i \\ &= \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i y_i \alpha_j y_j (\mathbf{x}_i \cdot \mathbf{x}_j) \end{aligned}$$

To find critical points of  $\Lambda$  satisfying the KKT conditions, it is sufficient to find the critical points of  $g$  that satisfy the constraints:  
 $\alpha_i \geq 0$  and  $\sum_{i=1}^N \alpha_i y_i = 0$

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## Primal and Dual SVM Formulations in the Linearly Separable Case

### Primal Form

minimise:  $\frac{1}{2} \|\mathbf{w}\|_2^2$

subject to:

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \geq 1$$

$$\text{for } 1 \leq i \leq N$$

- Quadratic convex problem
- $D + 1$  variables
- Constraints define a complex polytope

### Dual Form

maximise  $\sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)$

subject to:

$$\sum_{i=1}^N \alpha_i y_i = 0 \quad \text{and} \quad \alpha_i \geq 0$$

$$\text{for } 1 \leq i \leq N$$

- Quadratic concave problem
- $N$  variables
- Very simple box constraints + one zero-sum constraint

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## Why Prefer the SVM Dual Formulation?

**Reason 1:**  $D \approx N$  or  $D \gg N$ : Basis expansion to capture non-linear discriminating boundaries

**Reason 2:** Natural kernelisation: Replace dot product  $\mathbf{x}_i \cdot \mathbf{x}_j$  by kernel  $\kappa(\mathbf{x}_i, \mathbf{x}_j)$

**Reason 3:** The number of non-zero variables  $\alpha_i$  can be much smaller in practice!

Complementary slackness conditions:  $\alpha_i (y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) - 1) = 0$

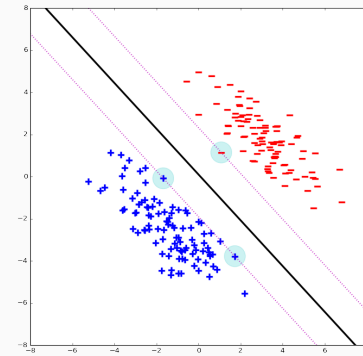
- $\alpha_i = 0$  OR  $y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) = 1$
- Only the points  $\mathbf{x}_i$  with  $\alpha_i > 0$  contribute to the solution  $\mathbf{w}$ :

$$\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

- Such vectors  $\mathbf{x}_i$  form the support of the solution  $\Rightarrow$  **support vectors**
- Such vectors  $\mathbf{x}_i$  are points with *least* margin

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## Support Vectors



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## SVM Dual Formulation in the Non-Linearly Separable Case

SVM primal formulation

$$\begin{aligned} \text{minimise: } & \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \zeta_i \\ \text{subject to: } & y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \geq 1 - \zeta_i \quad \text{for } 1 \leq i \leq N \\ & \zeta_i \geq 0 \quad \text{for } 1 \leq i \leq N \end{aligned}$$

### Lagrange Function

$$\Lambda(\mathbf{w}, w_0, \zeta; \alpha, \mu) = \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \zeta_i - \sum_{i=1}^N \alpha_i (y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) - (1 - \zeta_i)) - \sum_{i=1}^N \mu_i \zeta_i$$

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## Gradient of Lagrange Function

### Lagrange Function

$$\Lambda(\mathbf{w}, w_0, \zeta; \alpha, \mu) = \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \zeta_i - \sum_{i=1}^N \alpha_i (y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) - (1 - \zeta_i)) - \sum_{i=1}^N \mu_i \zeta_i$$

We write derivatives with respect to  $\mathbf{w}$ ,  $w_0$  and  $\zeta_i$ :

$$\frac{\partial \Lambda}{\partial w_0} = - \sum_{i=1}^N \alpha_i y_i$$

$$\frac{\partial \Lambda}{\partial \zeta_i} = C - \alpha_i - \mu_i$$

$$\nabla_{\mathbf{w}} \Lambda = \mathbf{w} - \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

For (KKT) dual feasibility constraints, we require  $\alpha_i \geq 0$ ,  $\mu_i \geq 0$

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## SVM Dual Formulation in the Non-Linearly Separable Case

Setting the derivatives to 0, substituting the resulting expressions in  $\Lambda$  (and simplifying), we get a function  $g(\alpha)$  and some constraints

$$g(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j \mathbf{x}_i \cdot \mathbf{x}_j$$

Constraints

$$0 \leq \alpha_i \leq C \quad 1 \leq i \leq N$$

$$\sum_{i=1}^N \alpha_i y_i = 0$$

Finding critical points of  $\Lambda$  satisfying the KKT conditions corresponds to finding the maximum of  $g(\alpha)$  subject to the above constraints

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## Primal and Dual SVM Formulations in the Non-Linearly Separable Case

### Primal Form

$$\text{minimise: } \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \zeta_i$$

subject to:

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \geq 1 - \zeta_i$$

$$\zeta_i \geq 0$$

$$\text{for } 1 \leq i \leq N$$

- Quadratic convex problem
- $D + N + 1$  variables
- Constraints define a complex polytope

### Dual Form

$$\text{maximise } \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)$$

subject to:

$$\sum_{i=1}^N \alpha_i y_i = 0$$

$$0 \leq \alpha_i \leq C$$

$$\text{for } 1 \leq i \leq N$$

- Quadratic concave problem
- $N$  variables
- Very simple box constraints + one zero-sum constraint

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## Making Predictions using SVM Dual

Recall the optimal solution for  $\mathbf{w}$  expressed using the dual variables  $\alpha$ :

$$\mathbf{w} = \sum_{i=1}^N \alpha_i y_i \mathbf{x}_i$$

The bias  $w_0$  is also expressible using  $\alpha$ .

Prediction on a new point  $\mathbf{x}_{\text{new}}$  requires inner products with the support vectors:

$$\mathbf{w} \cdot \mathbf{x}_{\text{new}} = \sum_{i=1}^N \alpha_i y_i (\mathbf{x}_i \cdot \mathbf{x}_{\text{new}})$$

We can as well using blackbox access to a function  $\kappa(\cdot, \cdot)$  that maps two inputs  $\mathbf{x}, \mathbf{x}'$  to their inner product  $\mathbf{x} \cdot \mathbf{x}'$ . This is a **kernel** function.

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## Mercer Kernels

A function  $\kappa$  is a kernel that computes the dot product for some expansion  $\phi$

$$\kappa(\mathbf{x}', \mathbf{x}) : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}, \quad \kappa(\mathbf{x}', \mathbf{x}) = \phi(\mathbf{x}') \cdot \phi(\mathbf{x})$$

$\kappa(\mathbf{x}, \mathbf{x}')$  is some measure of **similarity** between  $\mathbf{x}$  and  $\mathbf{x}'$

Gram matrix

$$\mathbf{K} = \begin{bmatrix} \kappa(\mathbf{x}_1, \mathbf{x}_1) & \kappa(\mathbf{x}_1, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_1, \mathbf{x}_N) \\ \kappa(\mathbf{x}_2, \mathbf{x}_1) & \kappa(\mathbf{x}_2, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_2, \mathbf{x}_N) \\ \vdots & \vdots & \ddots & \vdots \\ \kappa(\mathbf{x}_N, \mathbf{x}_1) & \kappa(\mathbf{x}_N, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_N, \mathbf{x}_N) \end{bmatrix}$$

**Mercer** or **positive definite** kernel: The Gram matrix is always positive semi-definite

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## SVM Dual Formulation using Mercer Kernel

$$\text{maximise } \sum_{i=1}^N \alpha_i - \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j y_i y_j \mathbf{K}_{i,j} \quad \text{s.t.: } 0 \leq \alpha_i \leq C \text{ and } \sum_{i=1}^N \alpha_i y_i = 0$$

where the Gram matrix  $\mathbf{K}$  is

$$\mathbf{K} = \begin{bmatrix} \kappa(\mathbf{x}_1, \mathbf{x}_1) & \kappa(\mathbf{x}_1, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_1, \mathbf{x}_N) \\ \kappa(\mathbf{x}_2, \mathbf{x}_1) & \kappa(\mathbf{x}_2, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_2, \mathbf{x}_N) \\ \vdots & \vdots & \ddots & \vdots \\ \kappa(\mathbf{x}_N, \mathbf{x}_1) & \kappa(\mathbf{x}_N, \mathbf{x}_2) & \cdots & \kappa(\mathbf{x}_N, \mathbf{x}_N) \end{bmatrix}$$

To make prediction on new  $\mathbf{x}_{\text{new}}$ , we compute  $\kappa(\mathbf{x}_i, \mathbf{x}_{\text{new}})$  for support vectors  $\mathbf{x}_i$

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## Which Function Constitutes a Kernel?

**Kernel engineering:** We can build kernels using simpler kernels as building blocks

Given kernels  $\kappa_1, \kappa_2$ , the following are kernels:

1.  $\kappa(\mathbf{x}, \mathbf{x}') = c \kappa_1(\mathbf{x}, \mathbf{x}')$   $c > 0$
2.  $\kappa(\mathbf{x}, \mathbf{x}') = f(\mathbf{x}) \kappa_1(\mathbf{x}, \mathbf{x}') f(\mathbf{x}')$   $f$  is a function
3.  $\kappa(\mathbf{x}, \mathbf{x}') = q(\kappa_1(\mathbf{x}, \mathbf{x}'))$   $q$  is a polynomial with non-negative coefficients
4.  $\kappa(\mathbf{x}, \mathbf{x}') = \exp(\kappa_1(\mathbf{x}, \mathbf{x}'))$
5.  $\kappa(\mathbf{x}, \mathbf{x}') = \kappa_1(\mathbf{x}, \mathbf{x}') \kappa_2(\mathbf{x}, \mathbf{x}')$
6.  $\kappa(\mathbf{x}, \mathbf{x}') = \kappa_a(\mathbf{x}_a, \mathbf{x}'_a) \kappa_b(\mathbf{x}_b, \mathbf{x}'_b)$   $\mathbf{x} = (\mathbf{x}_a, \mathbf{x}_b), \mathbf{x}' = (\mathbf{x}'_a, \mathbf{x}'_b), \kappa_a, \kappa_b$  are kernels
7.  $\kappa(\mathbf{x}, \mathbf{x}') = \kappa_a(\mathbf{x}_a, \mathbf{x}'_a) + \kappa_b(\mathbf{x}_b, \mathbf{x}'_b)$
8.  $\kappa(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{A} \mathbf{x}'$   $\mathbf{A}$  is a symmetric positive semi-definite matrix

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### Example: Kernel Engineering

Recall the Gaussian/RBF kernel:  $\kappa_{\text{RBF}}(\mathbf{x}, \mathbf{x}') = \exp(-\|\mathbf{x} - \mathbf{x}'\|^2 / 2\sigma^2)$

We can show that  $\kappa_{\text{RBF}}$  is a kernel as follows:

$$\|\mathbf{x} - \mathbf{x}'\|^2 = \mathbf{x}^\top \mathbf{x} - 2\mathbf{x}^\top \mathbf{x}' + (\mathbf{x}')^\top \mathbf{x}'$$

$$\kappa_{\text{RBF}}(\mathbf{x}, \mathbf{x}') = \underbrace{\exp(-\mathbf{x}^\top \mathbf{x} / 2\sigma^2)}_{f(\mathbf{x})} \underbrace{\exp(\mathbf{x}^\top \mathbf{x}' / \sigma^2)}_{\exp(\langle \mathbf{x}, \mathbf{x}' \rangle)} \underbrace{\exp(-(\mathbf{x}')^\top \mathbf{x}' / 2\sigma^2)}_{f(\mathbf{x}')}$$

We can replace  $\kappa_1(\mathbf{x}, \mathbf{x}')$  with a non-linear kernel, so RBF is not restricted to Euclidean distance:

$$\kappa(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{1}{2\sigma^2}(-2\kappa_1(\mathbf{x}, \mathbf{x}') + \kappa_1(\mathbf{x}, \mathbf{x}) + \kappa_1(\mathbf{x}', \mathbf{x}'))\right)$$

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### Recall: Expansion Function for RBF Kernel

What is  $\phi_{\text{RBF}}$  such that  $\kappa_{\text{RBF}}(\mathbf{x}', \mathbf{x}) = \exp(-\gamma\|\mathbf{x} - \mathbf{x}'\|^2) = \phi_{\text{RBF}}(\mathbf{x}) \cdot \phi_{\text{RBF}}(\mathbf{x}')$ ?

We use the following:

$$\|\mathbf{x} - \mathbf{x}'\|^2 = \langle \mathbf{x} - \mathbf{x}', \mathbf{x} - \mathbf{x}' \rangle = \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}', \mathbf{x}' \rangle - 2\langle \mathbf{x}, \mathbf{x}' \rangle = \|\mathbf{x}\|^2 + \|\mathbf{x}'\|^2 - 2\mathbf{x} \cdot \mathbf{x}'$$

$$\exp(\mathbf{x} \cdot \mathbf{x}') = \sum_{k=0}^{\infty} \frac{1}{k!} \underbrace{(\mathbf{x} \cdot \mathbf{x}')^k}_{\phi_{\text{poly}}(\mathbf{x}) \cdot \phi_{\text{poly}}(\mathbf{x}')} \quad \text{Taylor expansion: } \exp(z) = \sum_{k=0}^{\infty} \frac{z^k}{k!}$$

Without loss of generality, assume  $\gamma = 1$ . Then,

$$\exp(-\gamma\|\mathbf{x} - \mathbf{x}'\|^2) = \sum_{k=0}^{\infty} \underbrace{\left(\sqrt{\frac{1}{k!}} \exp(-\|\mathbf{x}\|^2) \phi_{\text{poly}}(\mathbf{x})\right)}_{\text{row } k \text{ in } \phi_{\text{RBF}}(\mathbf{x})} \cdot \underbrace{\left(\sqrt{\frac{1}{k!}} \exp(-\|\mathbf{x}'\|^2) \phi_{\text{poly}}(\mathbf{x}')\right)}_{\text{row } k \text{ in } \phi_{\text{RBF}}(\mathbf{x}')}$$

$\phi_{\text{RBF}} : \mathbb{R}^d \rightarrow \mathbb{R}^{\infty}$  projects vectors into an infinite dimensional space!

- Not feasible to compute  $\kappa_{\text{RBF}}(\mathbf{x}', \mathbf{x})$  using  $\phi_{\text{RBF}}$ !

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### Recall: Expansion Function for Polynomial Kernel

Find expansion function for kernel  $\kappa_{\text{poly}}(\mathbf{x}', \mathbf{x}) = (\mathbf{x} \cdot \mathbf{x}')^d$ , where  $\mathbf{x}, \mathbf{x}' \in \mathbb{R}^k$

We use  $(z_1 + \dots + z_k)^d = \sum_{n_1 \geq 0, \dots, n_k \geq 0, \sum_i n_i = d} \underbrace{\frac{d!}{n_1! \dots n_k!}}_{\text{multinomial coeff. } C(d; n_1, \dots, n_k)} z_1^{n_1} \dots z_k^{n_k}$

C = # of ways to distribute  $d$  balls into  $k$  bins, where the  $j$ -th bin holds  $n_j \geq 0$  balls

Now assume  $z_j = x_j x'_j$  in the above formula. Then,

$$(\mathbf{x} \cdot \mathbf{x}')^d = \sum_{\substack{n_1 \geq 0, \dots, n_k \geq 0 \\ \sum_i n_i = d}} \underbrace{\sqrt{C(d; n_1, \dots, n_k)} x_1^{n_1} \dots x_k^{n_k}}_{\text{one row in } \phi_{\text{poly}}(\mathbf{x})} \underbrace{\sqrt{C(d; n_1, \dots, n_k)} (x'_1)^{n_1} \dots (x'_k)^{n_k}}_{\text{one row in } \phi_{\text{poly}}(\mathbf{x}')}$$

The dimension of the vectors  $\phi_{\text{poly}}(\mathbf{x})$  and  $\phi_{\text{poly}}(\mathbf{x}')$  is  $O(k^d)$ .

Complexity of computing  $\kappa(\mathbf{x}', \mathbf{x})$ :  $O(k^d)$  using  $\phi_{\text{poly}}$  vs.  $O(k \log d)$  using  $(\mathbf{x} \cdot \mathbf{x}')^d$ !

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### Examples: Expansion Function for Polynomial Kernel

For  $\mathbf{x} = [x_1 \ x_2]^\top$  and  $\mathbf{x}' = [x'_1 \ x'_2]^\top$  find  $\phi$  such that  $\kappa(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x}) \cdot \phi(\mathbf{x}')$

$$\kappa(\mathbf{x}, \mathbf{x}') = (\mathbf{x} \cdot \mathbf{x}')^2 = (x_1 x'_1 + x_2 x'_2)^2 = x_1^2 (x'_1)^2 + 2x_1 x'_1 x_2 x'_2 + x_2^2 (x'_2)^2 = \phi(\mathbf{x}) \cdot \phi(\mathbf{x}')$$

$$\phi(\mathbf{x}) = \begin{bmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2} x_1 x_2 \end{bmatrix} \quad \phi(\mathbf{x}') = \begin{bmatrix} (x'_1)^2 \\ (x'_2)^2 \\ \sqrt{2} x'_1 x'_2 \end{bmatrix}$$

$$\begin{aligned} \kappa(\mathbf{x}, \mathbf{x}') &= (\mathbf{x} \cdot \mathbf{x}' + \theta)^2 \\ &= (x_1 x'_1 + x_2 x'_2 + \theta)^2 = x_1^2 (x'_1)^2 + 2x_1 x'_1 x_2 x'_2 + x_2^2 (x'_2)^2 + 2x_1 x'_1 \theta + 2x_2 x'_2 \theta + \theta^2 \end{aligned}$$

$$\phi(\mathbf{x}) = \begin{bmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2} x_1 x_2 \\ \sqrt{2} \theta x_1 \\ \sqrt{2} \theta x_2 \\ \theta \end{bmatrix} \quad \phi(\mathbf{x}') = \begin{bmatrix} (x'_1)^2 \\ (x'_2)^2 \\ \sqrt{2} x'_1 x'_2 \\ \sqrt{2} \theta x'_1 \\ \sqrt{2} \theta x'_2 \\ \theta \end{bmatrix}$$

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### Kernels on Discrete Data: String Kernel

Let alphabet  $\mathcal{A} = \{A, R, N, D, C, E, Q, G, H, I, L, K, M, F, P, S, T, W, Y, V\}$

Each letter denotes one of the 20 aminoacids

Let  $\mathbf{x}$  and  $\mathbf{x}'$  be strings over  $\mathcal{A}$ :

IPTSALVKETLALLSTHRTLLIANETLRIPVPVHKNHQLCTEEIFQGIGTLESQTVQGQGV  
ERLPKNLSLIKYYIDGGKKKCGEERRRVNQFLDYLQEFGLGVMTIEWI

PHRRDLCSRSIWLARKIRSDLTALTSEYVKHQLWSELTEAERLQENLQAYRTFHVLLA  
RLLEDQVHFPTTEGDFHQAIHTLLQVAFAFYIEELMILLEVKIPRNEADGMLFEKK  
LWGLKVLQELSQTWRVRSIHDLRFISSHQTGIP

These strings encode proteins. They have the string **LQE** in common.

The kernel defines similarities on strings:  $\kappa(\mathbf{x}, \mathbf{x}') = \sum_s w_s \phi_s(\mathbf{x}) \phi_s(\mathbf{x}')$

$\phi_s(\mathbf{x})$  is the number of times  $s$  appears in  $\mathbf{x}$  as substring

$w_s$  is the weight associated with substring  $s$

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