



# Most Diverse Near-Shortest Paths

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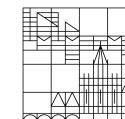
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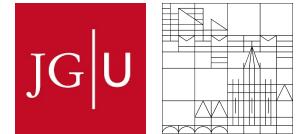


Universität  
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# Outline

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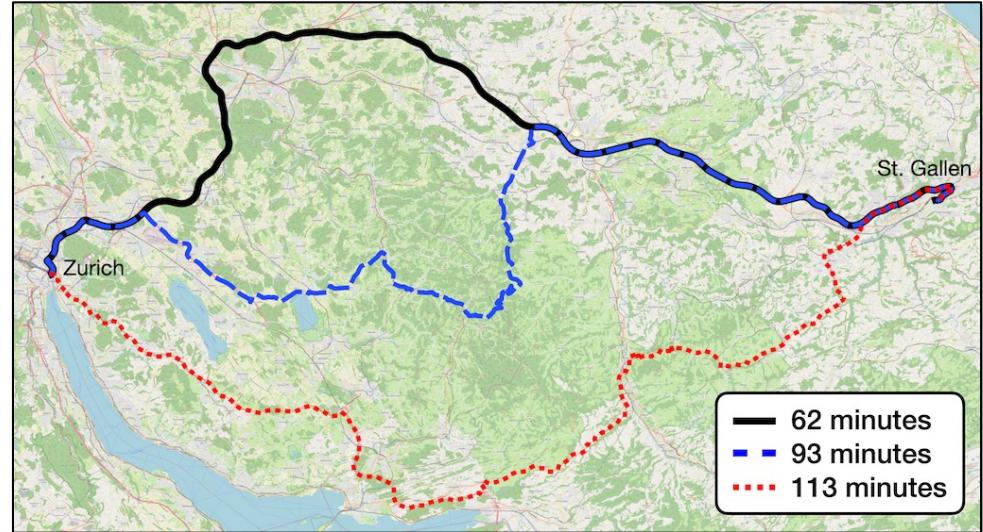


- Motivation
- Previous work
- Problem definition
- Evaluation methods
  - An exact approach
  - Heuristic-based approaches
- Experimental analysis
- Conclusions



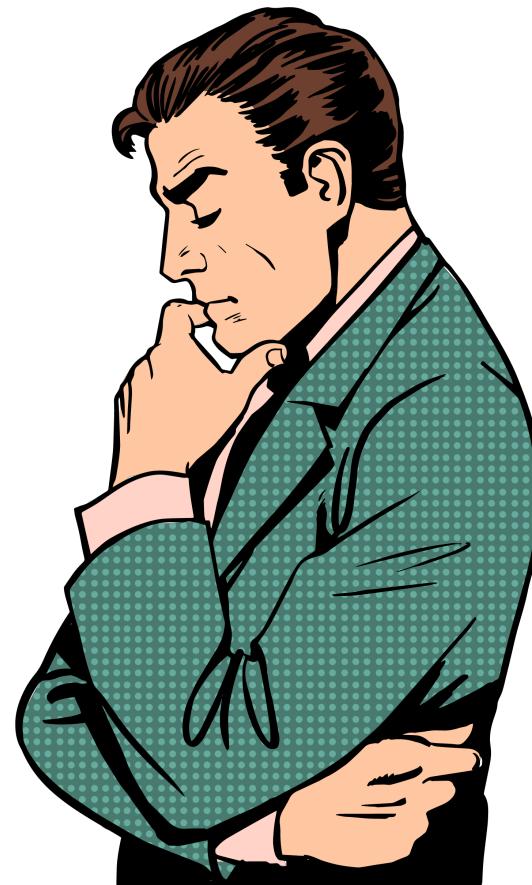
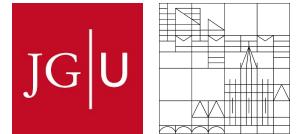
# Motivation

- Alternative routing
  - Need to recommend a set of diverse paths
- Existing works mainly consider
  - Path length as an optimization criterion
  - Path dissimilarity as a constraint
- But,
  - Recommended paths might be too long
  - Setting dissimilarity thresholds/constraints is counterintuitive
- Our proposal, to consider
  - Path length as a constraint => near-shortest paths
  - Dissimilarity as an optimization criterion => most diverse paths



# Previous work

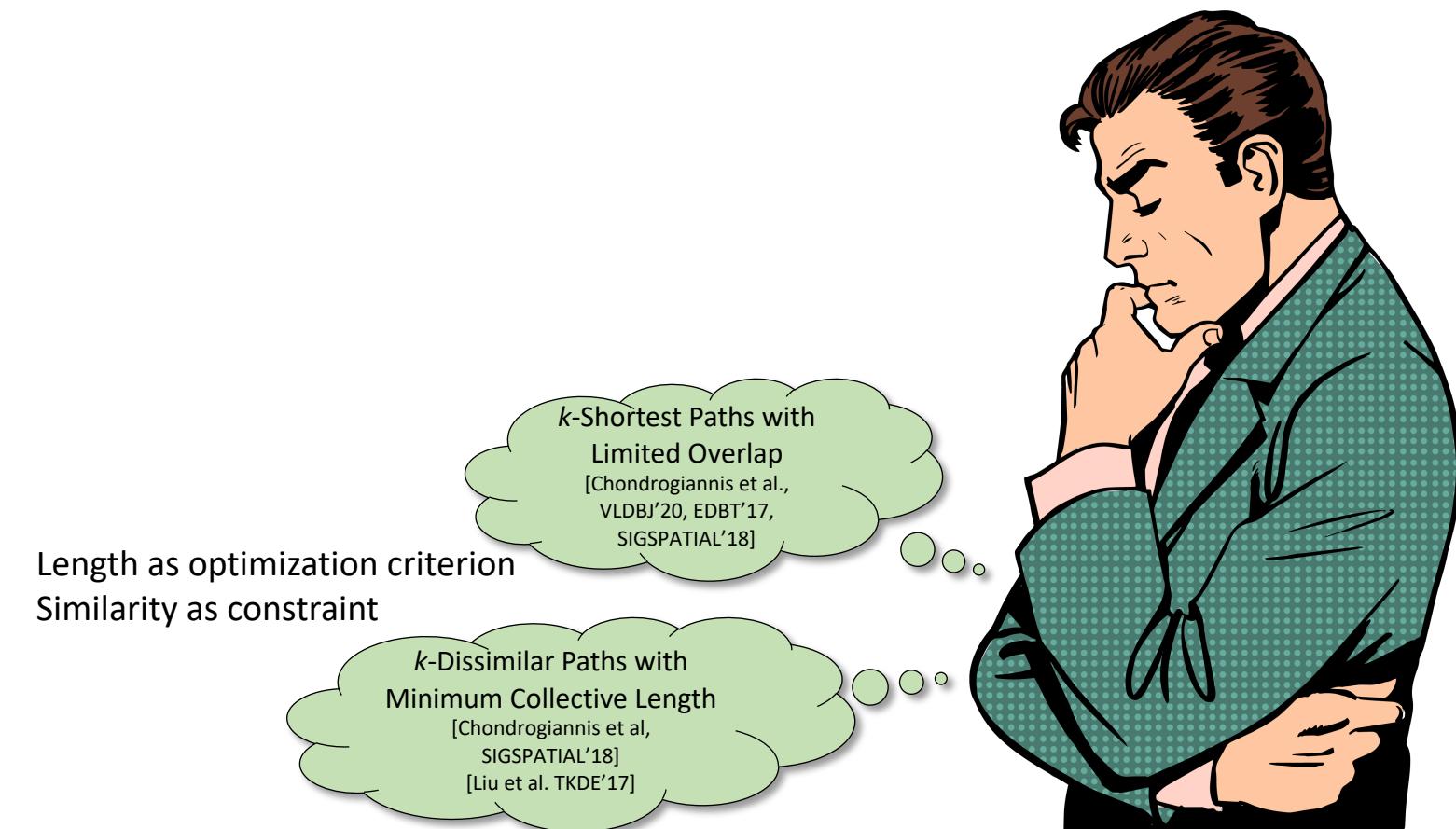
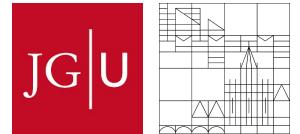
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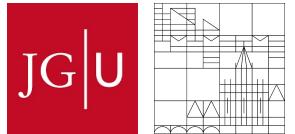
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# Previous work



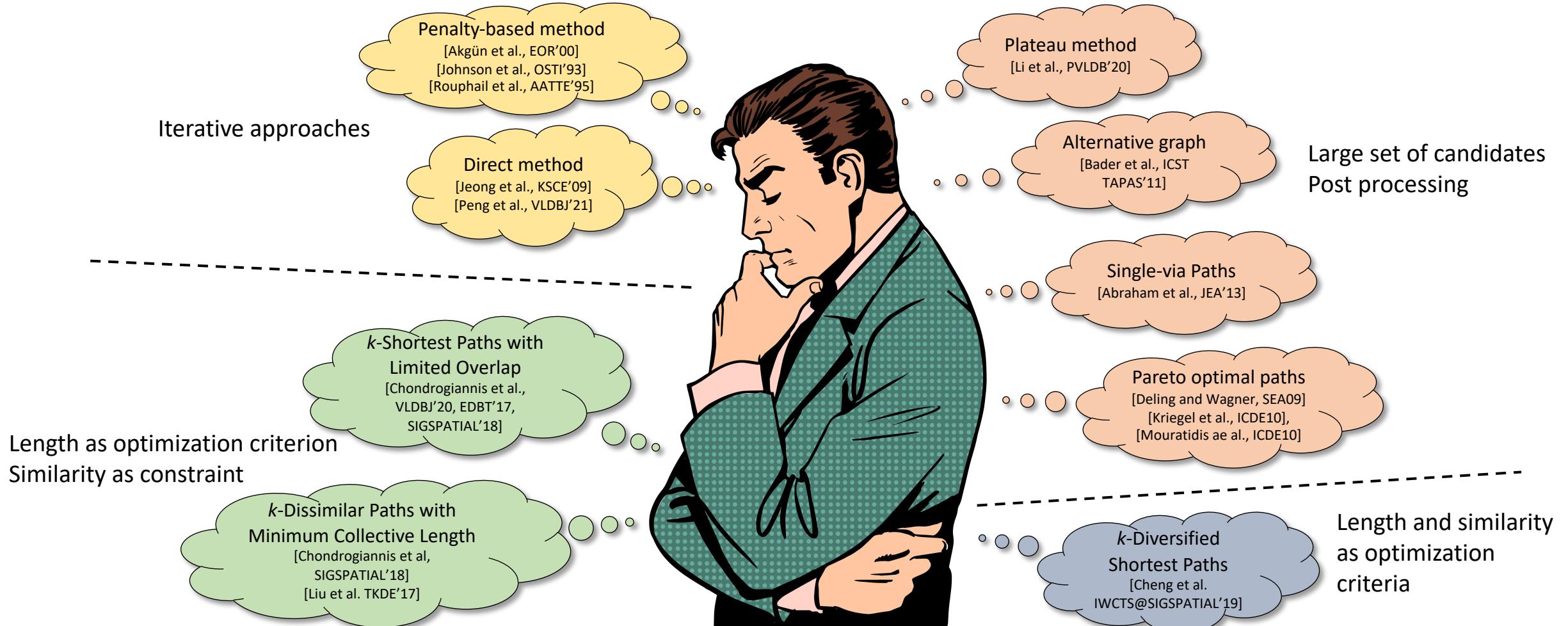
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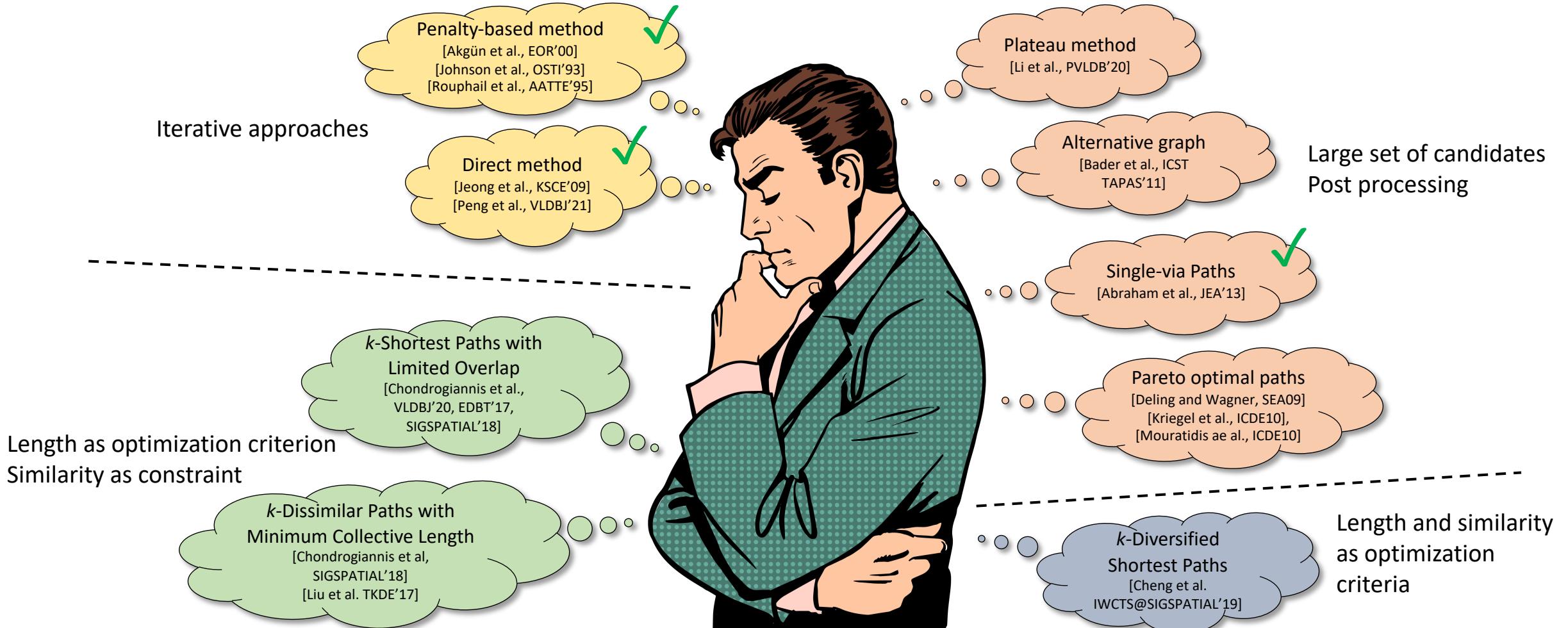
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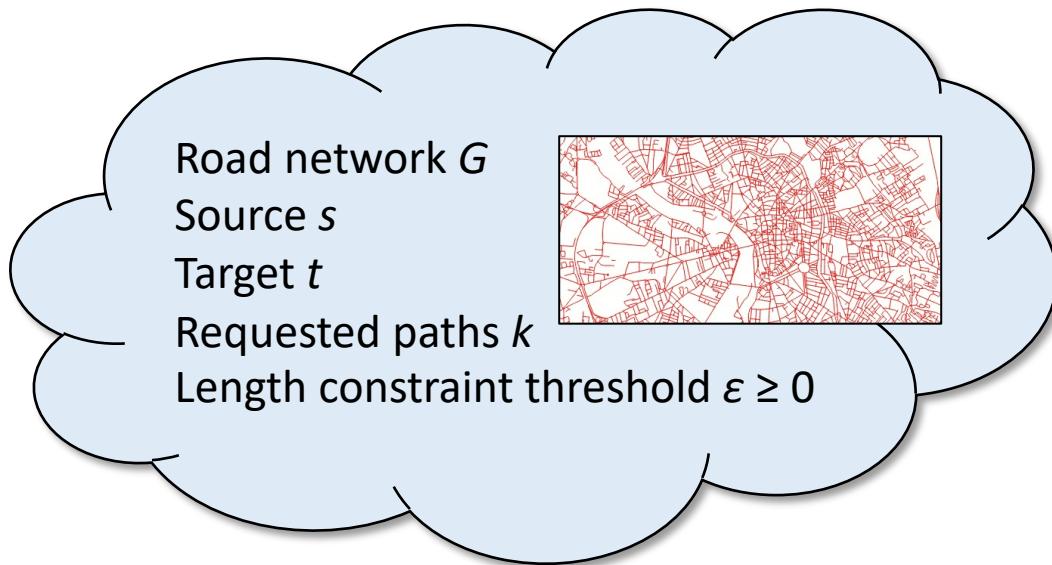
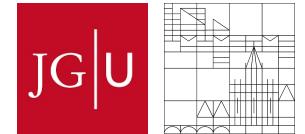
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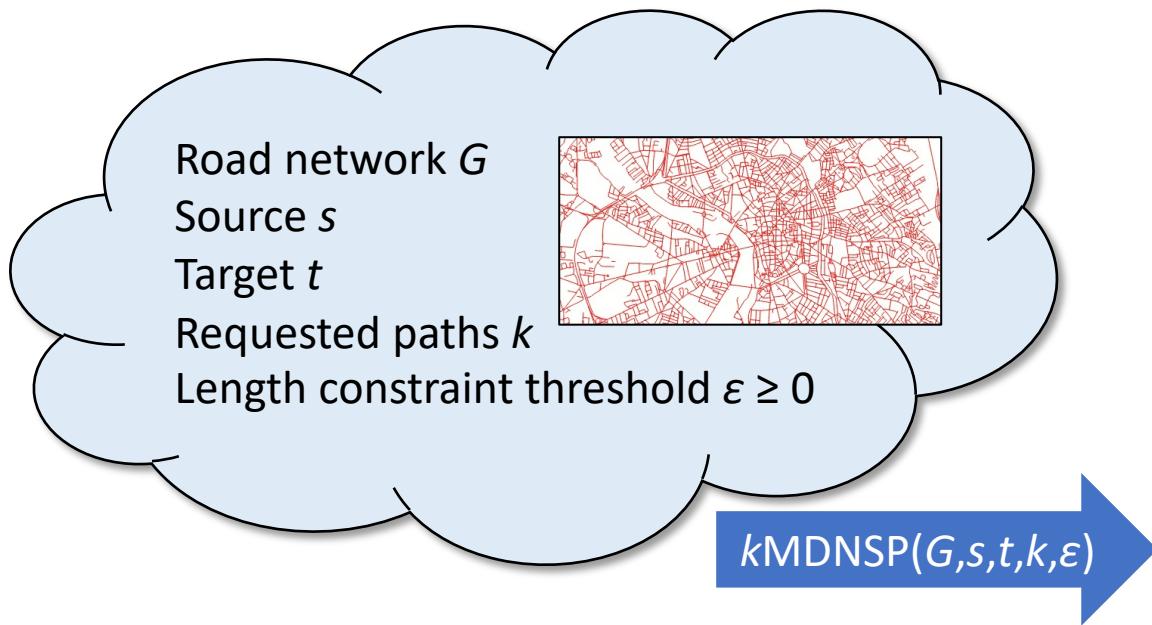
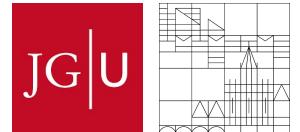
# Previous work



# Problem definition



# Problem definition

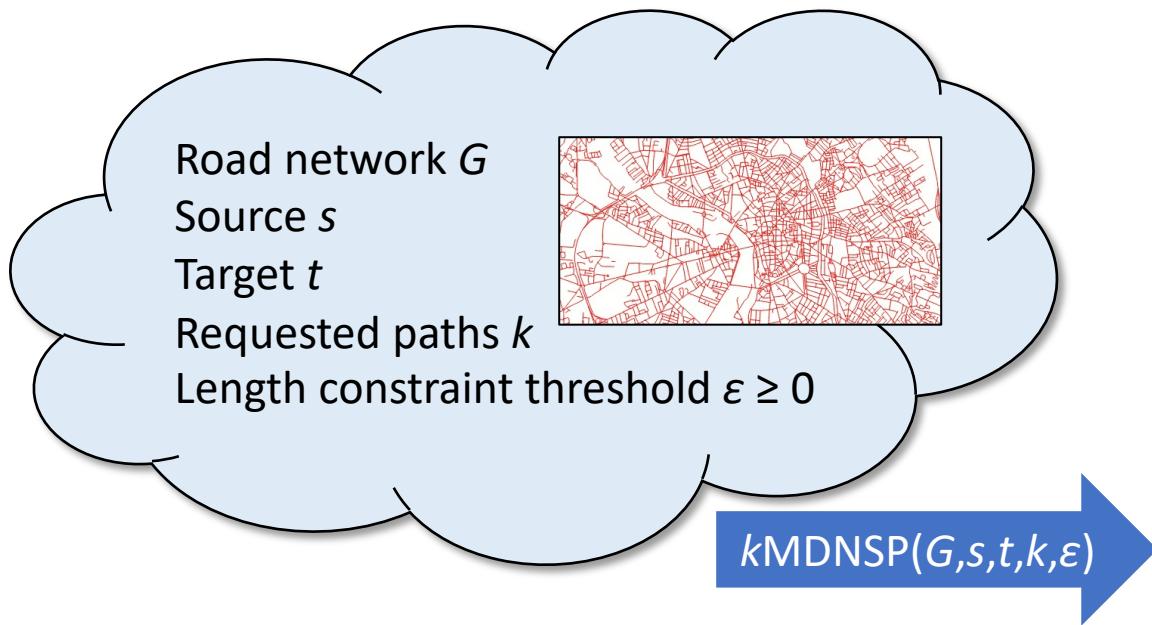
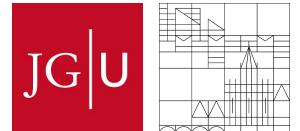


## Most Diverse Near-Shortest Paths

Set  $P_{k\text{MDNSP}}$ :

- of  $k$  near-shortest paths
$$\forall p \in P_{k\text{MDNSP}} : \ell(p) \leq (1 + \epsilon) \cdot \ell(p_s)$$
- with the highest diversity among all path sets  $P_A$  that satisfy Condition A
$$P_{k\text{MDNSP}} = \arg \max_{\forall P \subseteq P_A} \{Div(P)\}$$

# Problem definition



## Most Diverse Near-Shortest Paths

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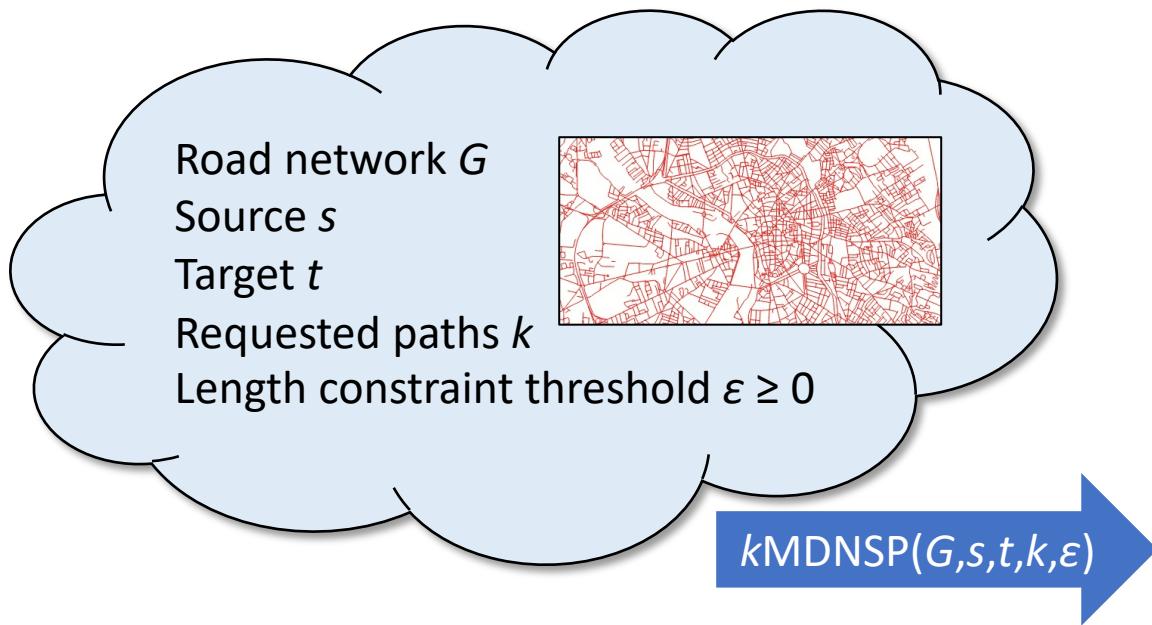
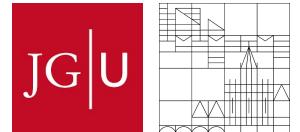
### Path set diversity

$$Div(P) = \min_{\forall p, p' \in P} Dis(p, p')$$

### Path dissimilarity

$$Dis(p, p') = 1 - \frac{\sum_{\forall (n_i, n_j) \in p \cap p'} w(n_i, n_j)}{\sum_{\forall (n_i, n_j) \in p \cup p'} w(n_i, n_j)}$$

# Problem definition



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NP-hard

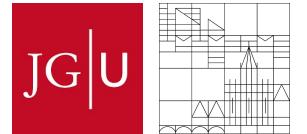
Path set diversity

$$\text{Div}(P) = \min_{\forall p, p' \in P} \text{Dis}(p, p')$$

Path dissimilarity

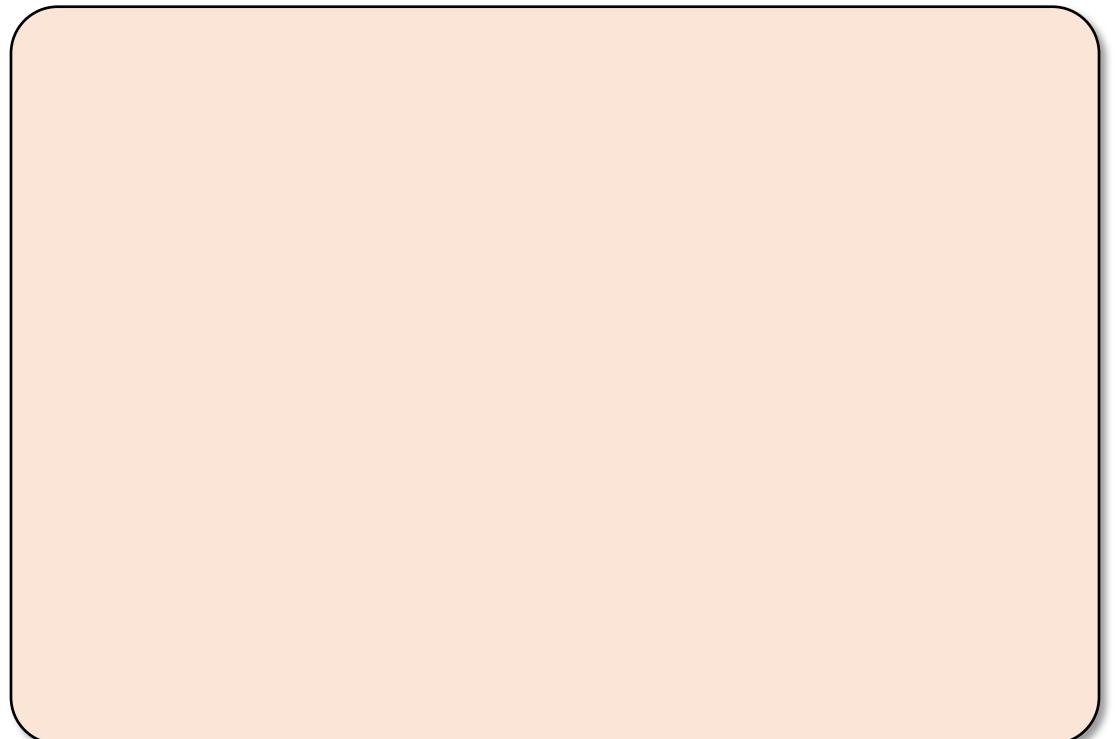
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# Exact approach

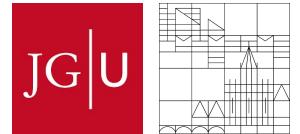


**Compute all Near-Shortest Paths**

**Generate Candidate  $k$ -Subsets**



# Exact approach



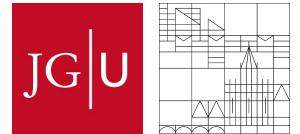
## Compute all Near-Shortest Paths

- Path enumeration
  - [Carlyle and Wood, Networks'05]
  - Traverse the network in depth-first fashion
  - Filter out subpaths that violate the near-shortest path constraint w.r.t.  $\epsilon$
- Optimization
  - Estimate lower bounds for path extensions
  - Compute shortest path tree  $T_{N \rightsquigarrow t}$

## Generate Candidate $k$ -Subsets



# Exact approach



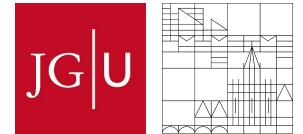
## Compute all Near-Shortest Paths

- Path **enumeration**
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## Generate Candidate $k$ -Subsets

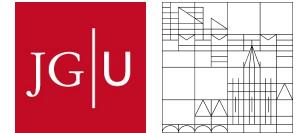
- **Dynamic programming**
  - “Filling a rucksack” algorithm [Knuth’05]
  - **Incrementally build a binomial tree of height  $k$**
  - Represent **all subsets with up to  $k$  near-shortest paths**
- **Optimization**
  - Upon adding a new path, **diversity of subsets can only drop**
  - **Prune unpromising subsets**

# Exact approach – critique



- Pros
  - Simple, straightforward
- Cons
  - Large number of near-shortest paths
  - Exponential cost
  - Impractical for real-world networks
- Solution
  - Heuristic-based methods
  - Reduce number of computed paths
  - Trade quality of the result for performance

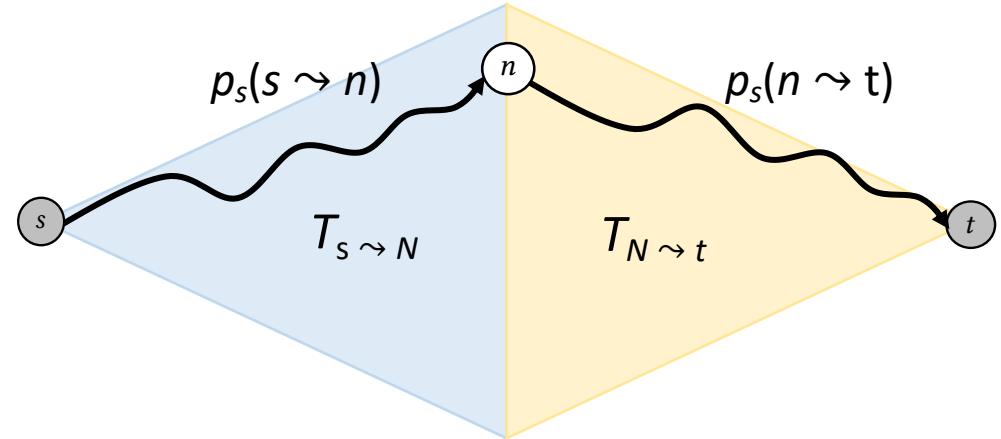
# (Simple) single-via paths



- Single-via paths (SVP)
  - [Abraham et al., JEA'13]
  - Reverse shortest path tree  $T_{s \rightarrow N}$
  - Shortest path tree  $T_{N \rightarrow t}$
  - $p_{sv}(n) = p_s(s \rightarrow n) \circ p_s(n \rightarrow t)$

- Simple single-via paths (SSVP)

$$- p_{ssv}(n) \begin{cases} p_{sv}(n), & \text{if simple} \\ p_s(s \rightarrow n) \circ \text{Dijkstra}(G', n, t) \text{ or } \text{Dijkstra}(G'', s, n) \circ p_s(n \rightarrow t), & \text{otherwise} \end{cases}$$



## ~~Compute all Near Shortest Paths~~

## Generate Candidate $k$ -Subsets

- Dynamic programming
  - “Filling a rucksack” algorithm [Knuth’05]
  - Incrementally build a binomial tree of height  $k$
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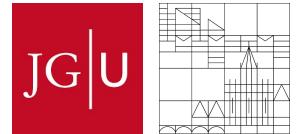
## Compute all Near-Shortest SSVPs

- Path enumeration
  - Compute shortest path tree  $T_{s \sim N}$
  - Compute reverse shortest path tree  $T_{N \sim t}$
  - Construct  $p_{ssv}(n)$  for each node  $n \in N$

## Generate Candidate $k$ -Subsets

- Dynamic programming
  - “Filling a rucksack” algorithm [Knuth’05]
  - Incrementally build a binomial tree of height  $k$
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# Penalty-based approach



Built upon [Johnson et al., OSTI'93], [Rouphail et al., AATTE'95]

~~Compute all Near Shortest Paths~~

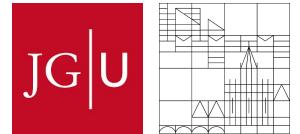
~~Compute all Near Shortest SSVPs~~

**Generate Candidate  $k$ -Subsets**

- **Dynamic programming**
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# Penalty-based approach



Built upon [Johnson et al., OSTI'93], [Rouphail et al., AATTE'95]

## Compute Near-Shortest Paths set

- Path computation
  - Iterative approach
    - Compute a near-shortest path  $p$
    - Penalize all edges on  $p$
    - Repeat
- Optimization
  - Dynamically adjusted penalties

## Generate Candidate $k$ -Subsets

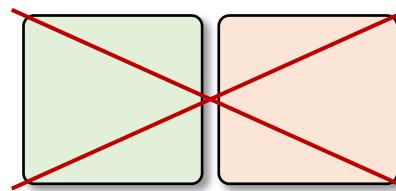
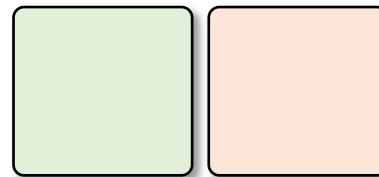
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# Direct approach

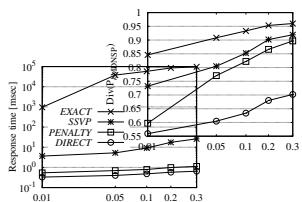
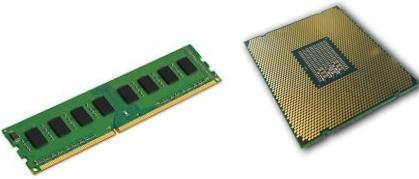
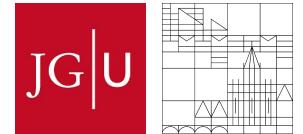
- Both SSVP- and penalty-based approaches
  - Operate in two phases, similar to exact
  - Reduce search space
  - But, still need to generate candidate  $k$ -subsets

Inspired by [Jeong et al., KSCE'09]



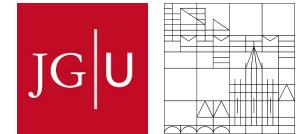
- Direct approach
  - Incrementally build  $P_{kMDNSP}$  in  $k-1$  rounds
  - Initially,  $P_{kMDNSP} = \{p_s\}$
  - In each round
    - Consider last recommended path  $p$
    - Alter  $p$  to construct the near-shortest  $p'$  with the highest dissimilarity to all paths in  $P_{kMDNSP}$
    - Add  $p'$  to  $P_{kMDNSP}$

# Experimental analysis

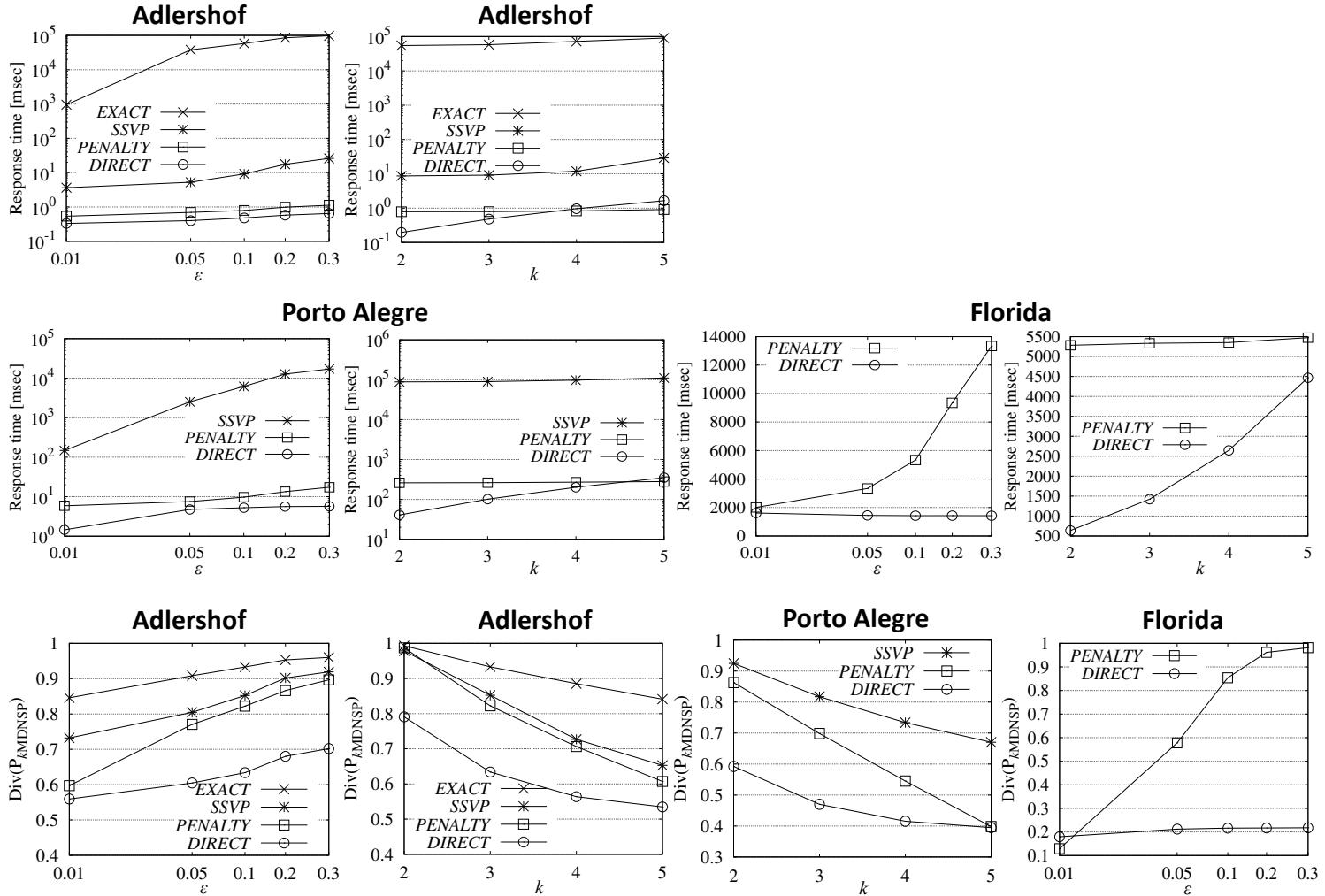


- **Setup**
  - 2x AMD EPYC 7351 16-Core Processors, 512 GiB 2666Mhz DDR4 RAM
  - GNU/Linux 5.4.0-66
- **Methods**
  - Implemented in C++, compiled with GNU G++ 9
  - *EXACT* and *SSVP*, *PENALTY*, *DIRECT*
- **Datasets & experiments**
  - 5 real-world road networks
    - Different sizes and topologies: city-center, grid-based, ring-based, state-wide
    - Adlershof, Oldenburg, Porto Alegre, Milan, Chicago, Florida
  - Varied number of recommended paths  $k$  and near-shortest path factor  $\varepsilon$
  - Measured response time and result diversity, counted computed near-shortest paths
- **Key questions**
  - Is computation of  $k$ MDSNP with *EXACT* practical?
  - How good can heuristic-based methods scale?
  - How is result quality affected?

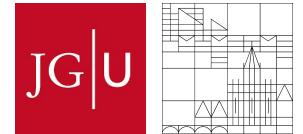
# Findings



- Is *EXACT* practical?
  - Only for toy-networks with up to some 100's of nodes
  - Already orders of magnitude slower
- How good heuristic-based methods scale?
  - *SSVP* can handle networks with less than 100,000 of nodes
  - *PENALTY* and *DIRECT* can handle even state-wide networks
- How is result quality affected?
  - Best heuristic *SSVP*, followed by *PENALTY*



# To sum up...



- Contributions

- A novel instance of alternative routing problem
- Recommend  $k$  near-shortest paths with the highest diversity
- Exact and heuristic-based solutions

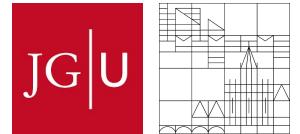
- Future work

- Other evaluation approaches, e.g., flow algorithms
- Alternative definitions of path diversity
- Visualize and compare results



Thank you

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# Questions

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26