

INTRODUCTION AND HISTORICAL PERSPECTIVE



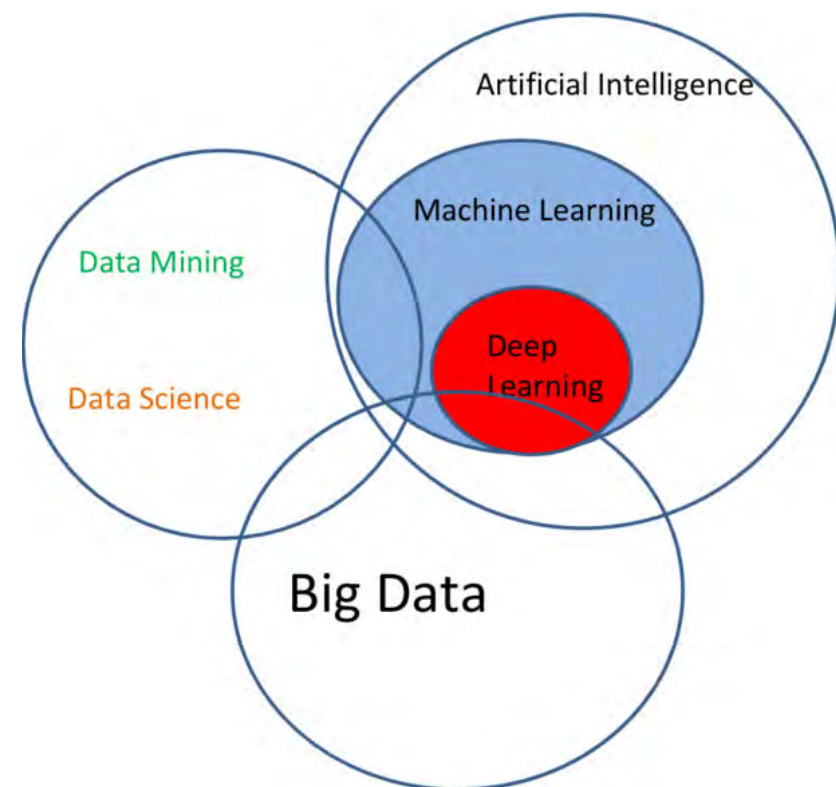
(IFCA)

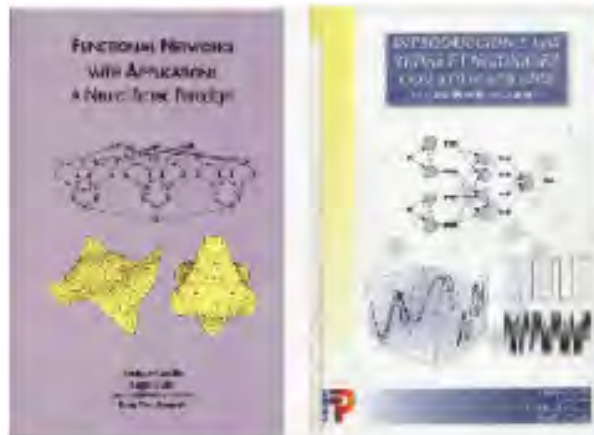
(IFCA)



31	1	2	3
15:30h -17:30h	15:30h -17:30h	15:30h -17:30h	15:30h -17:30h
Machine Learning II	Machine Learning I	Machine Learning II	Machine Learning I
Aprendizaje estadístico. Métodos kernel para clasificación. SVM	Fundamentos de Redes Neuronales	Práctica clasificación	Práctica de Aprendizaje con backpropagation
Ignacio Santamaría	Jose Manuel Gutierrez	Steven Van Vaerenbergh	Jorge Baño Medina
	Herramientas en la	Sistemas de computación para	

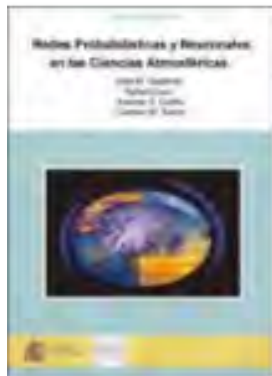
8 Feb - Redes multicapa y el algoritmo de backpropagation
 10 Feb - Prácticas de clasificación con redes multicapa
 15 Feb - Prácticas de predicción con redes multicapa
 17 Feb - Clustering y redes autoorganizativas
 22 Feb - Reservoir computing





An Introduction to Functional Networks
E. Castillo, A. Cobo, J.M. Gutiérrez and E. Pruneda
Kluwer Academic Publishers (1999).

Paraninfo/International Thomson Publishing



LIBRO

J.M. Gutiérrez, R. Cano, A.S. Cofiño, and C. Sordo
Redes Probabilísticas y Neuronales en las Ciencias Atmosféricas
Ministerio de Medio Ambiente (Monografías del Instituto Nacional de Meteorología), Madrid. 350 páginas, 2004

<http://www.meteo.unican.es/files/pdfs/LibroINM.pdf>

Inteligencia Artificial

50



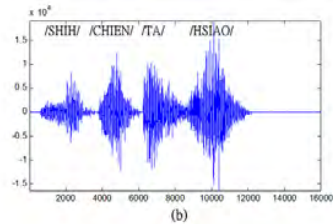
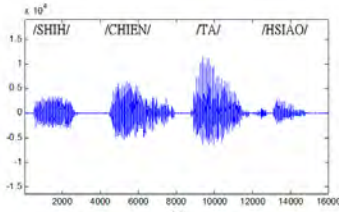
<http://yann.lecun.com/exdb/mnist/>

60000+10000 images 28x28

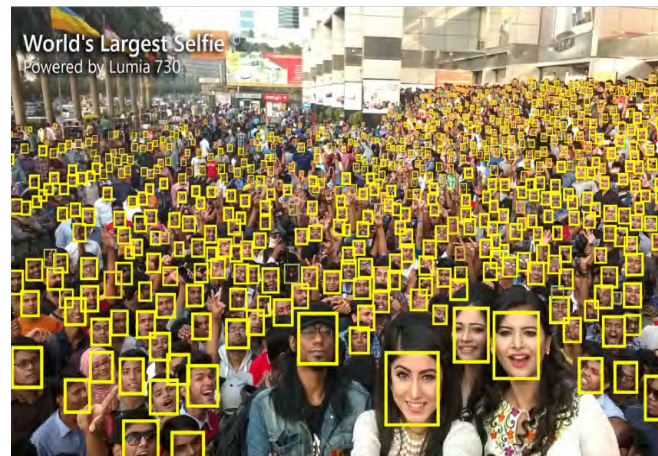
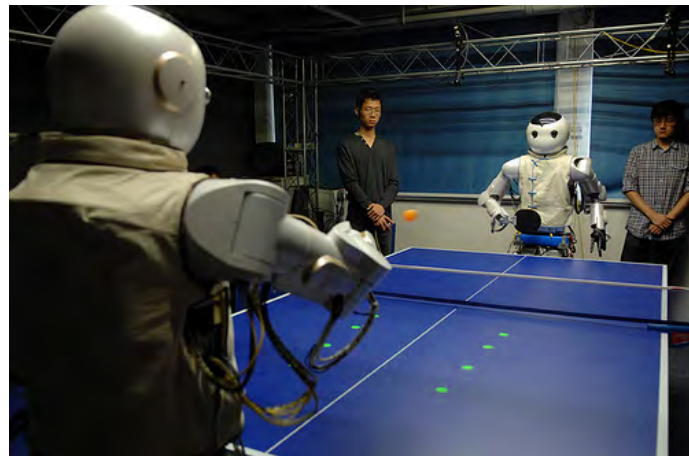
Labeled as {0,...,9}



Lineal: 10%. k-NN: 3%. SVM: 1%.
Deep: 0.3%



Overview of Natural Language Processing(NLP) with R and OpenNLP



Master Universitario Oficial **Data Science**

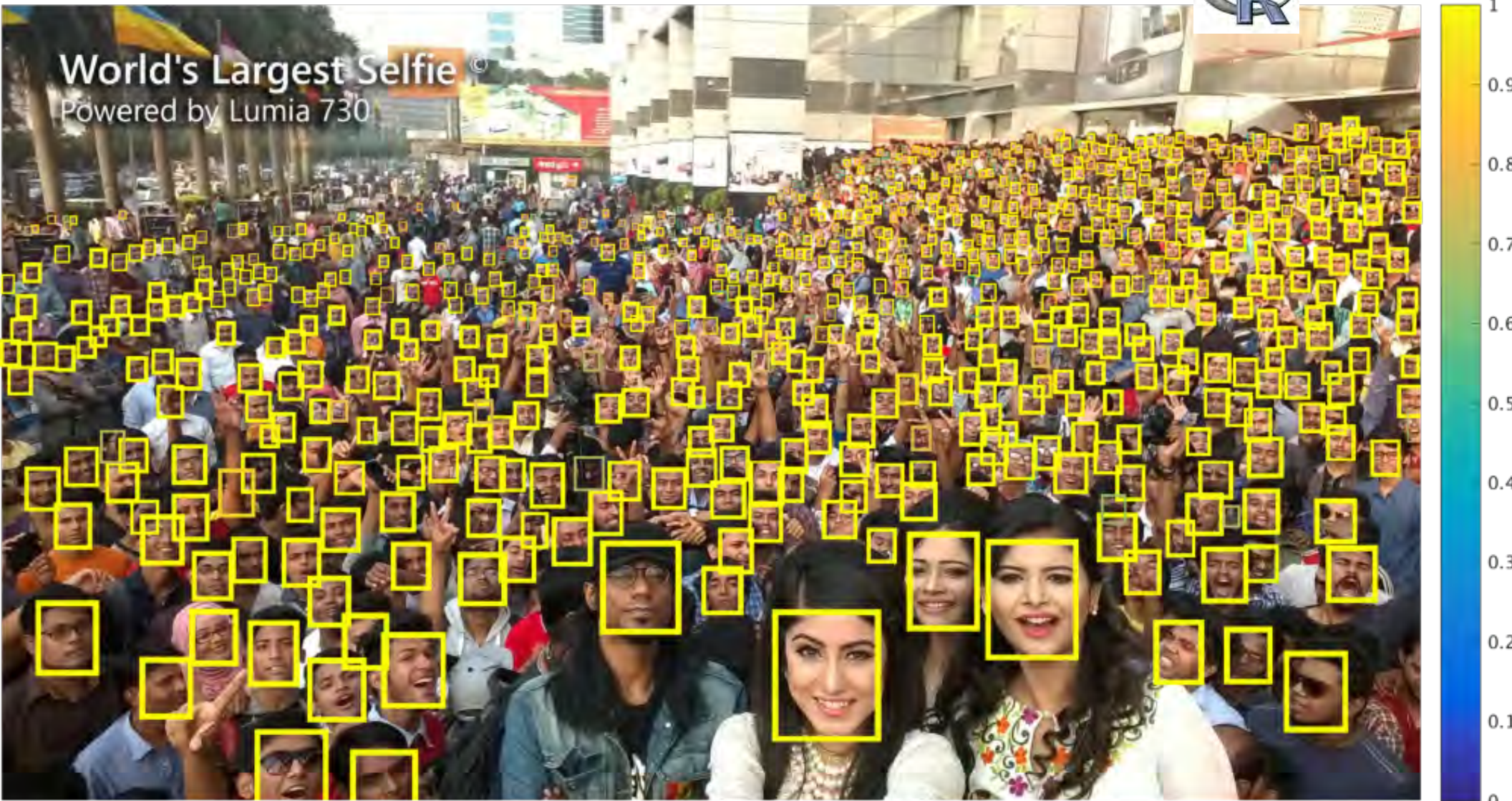


con el apoyo del



INTRO:

ARTIFICIAL INTELLIGENCE



We develop a face detector (Tiny Face Detector) that can find ~800 faces out of ~1000 reportedly present, by making use of novel characterization of scale, resolution, and context to find small objects.

Nuevos Paradigmas DATA-driven

Inspiración estadística

STATISTICAL LEARNING 2000

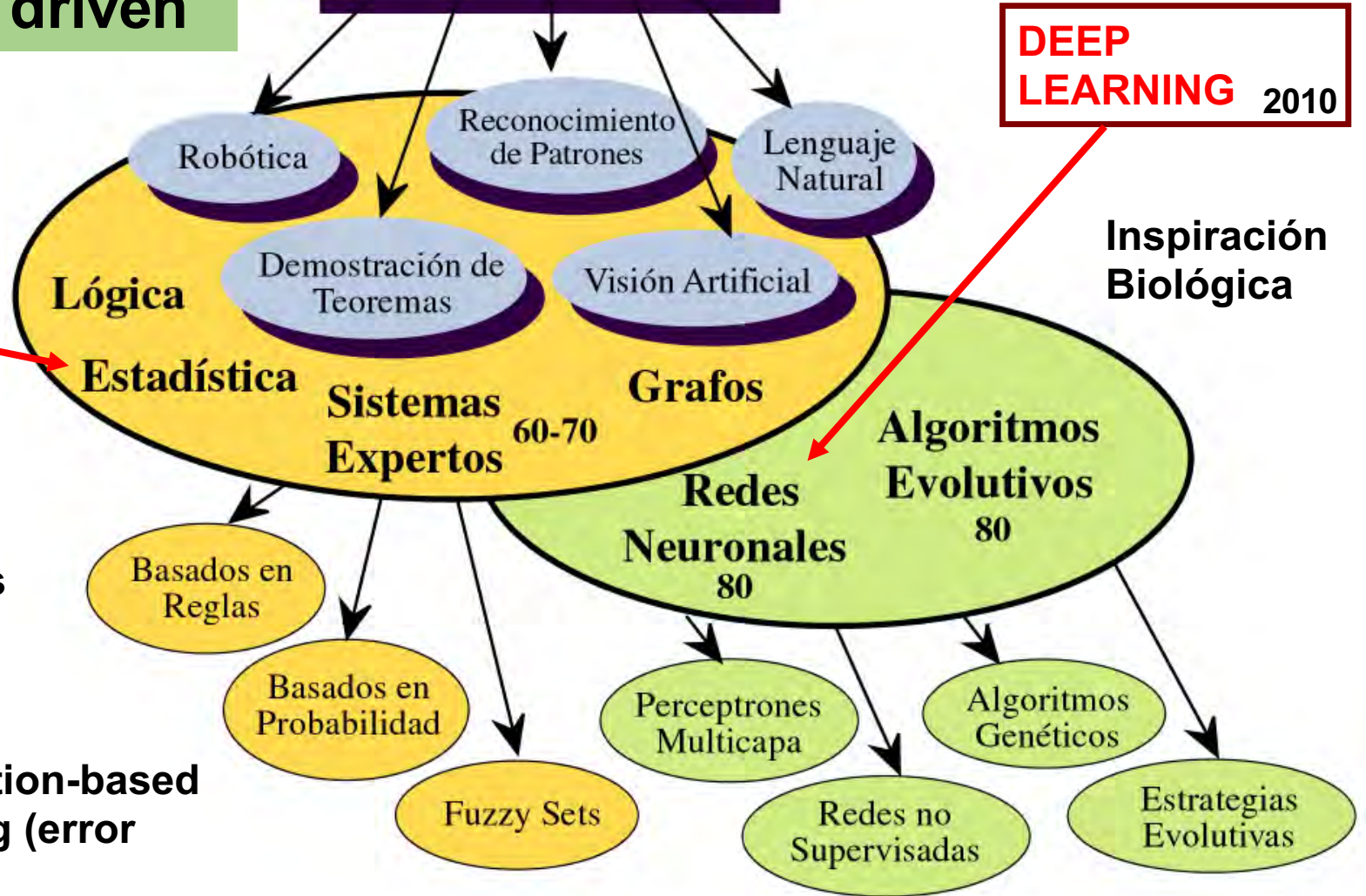
Data driven using abstract representations

Kernels, neural network, etc.

Optimization-based reasoning (error function).

Empirical risk, gradient descend, etc.

Inteligencia Artificial
50



DEEP LEARNING 2010

Inspiración Biológica

Parallel processing

HPC, GPUs, cloud, etc.

ImageNet is an image database organized according to the (nouns of the) [WordNet](#) hierarchy, in which each node of the hierarchy is depicted by an average of over five hundred images.

#synsets: 21841
#images: 14197122

150 GB [\[kaggle\]](#)



David G. Lowe, [Distinctive Image Features from Scale-Invariant Keypoints](#). *International Journal of Computer Vision*, 2004.

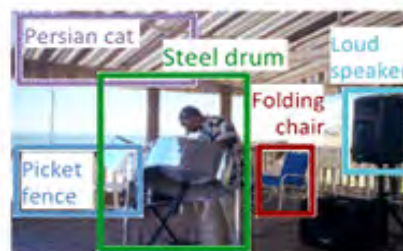
Single-object localization



Ground truth



Accuracy: 1



Accuracy: 0



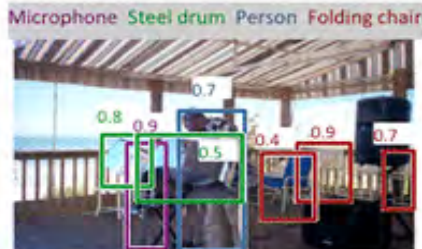
Accuracy: 0

Validation:
top-5 error
rate

Object detection



Ground truth



AP: 1.0 1.0 1.0 1.0



AP: 0.0 0.5 1.0 0.3



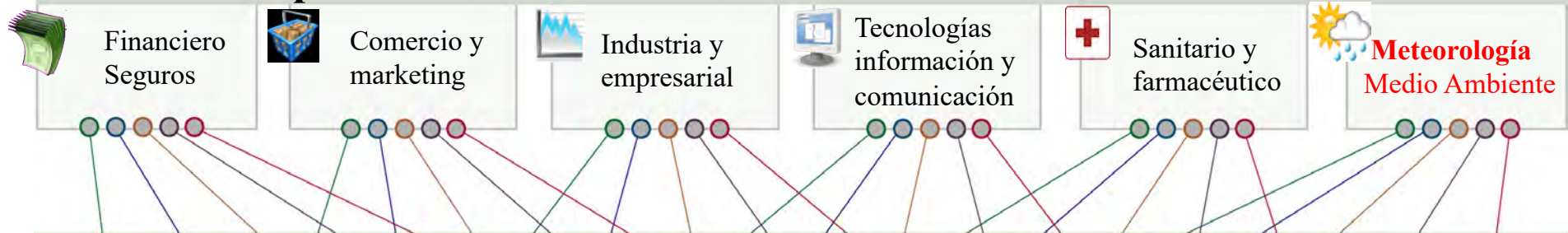
AP: 1.0 0.7 0.5 0.9

2017
video
included

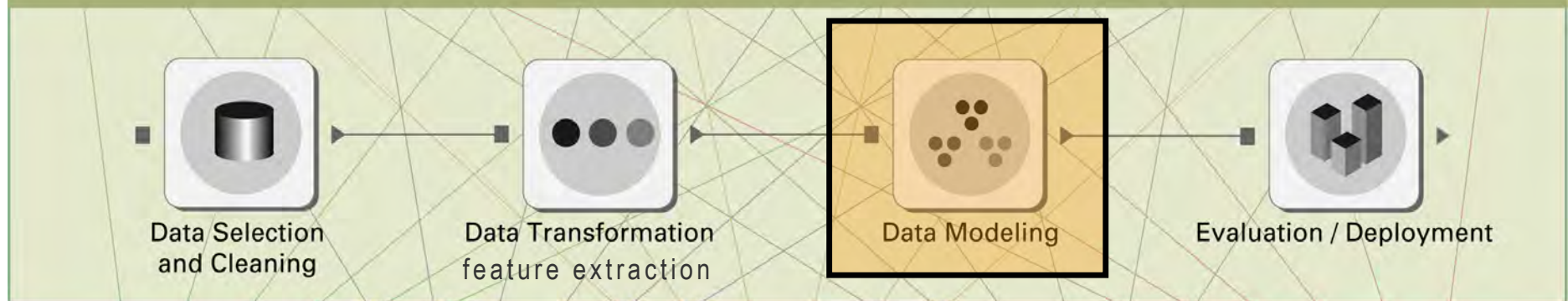
[Inception-v3](#): 3.46% top-5 and 17.3% top-1 (25 million parameters).
[Inception In [kaggle](#)]

O. Russakovsky (2015) [ImageNet Large Scale Visual Recognition Challenge](#), International Journal of Computer Vision, 115, 211–252

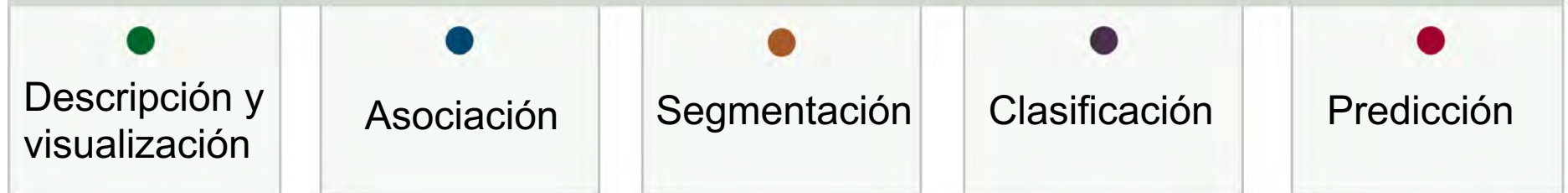
Sectores de aplicación



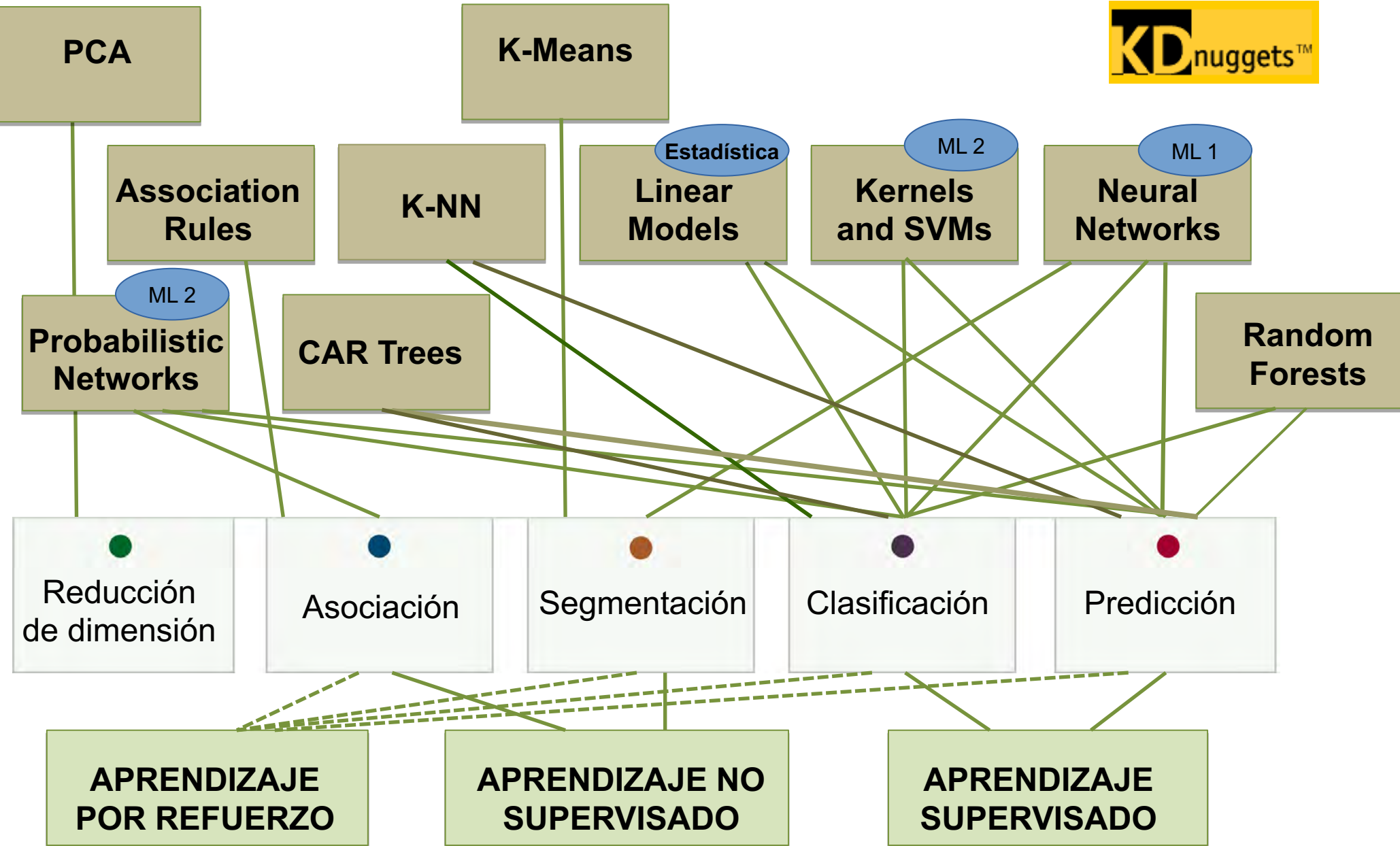
Proceso de Minería de Datos

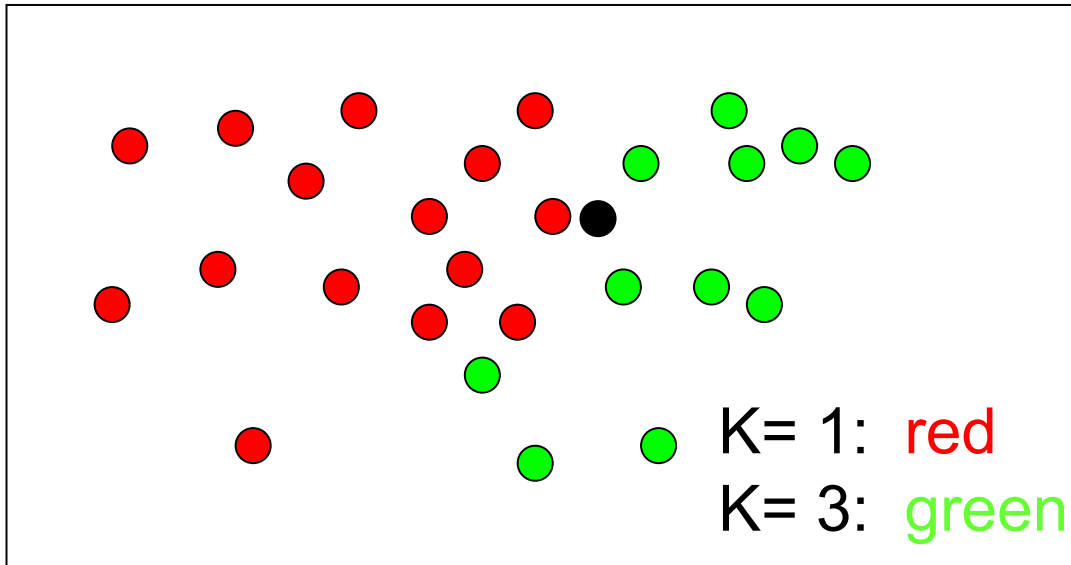
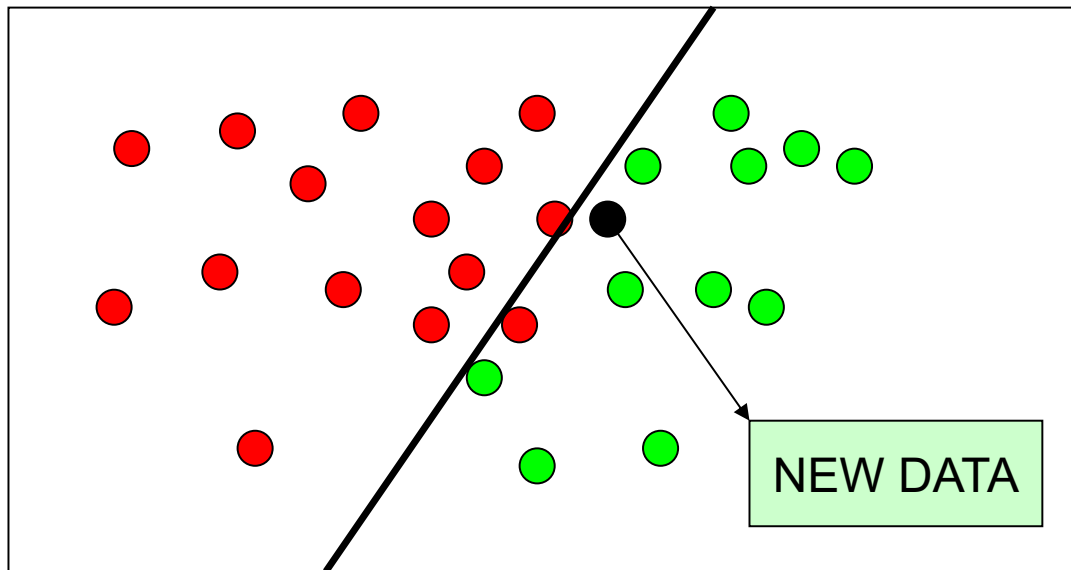


Problemas habituales



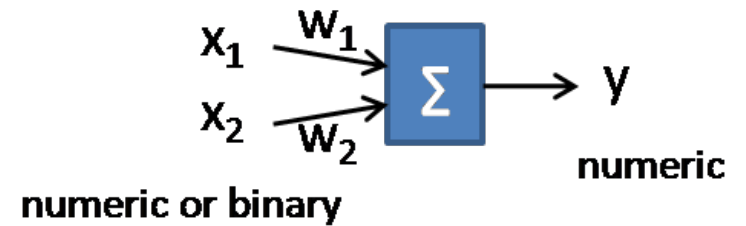
Machine learning develop methods for data modelling and prognosis.





GENERATIVE METHODS:

Linear models are the simplest family for machine learning and have good generalization properties.



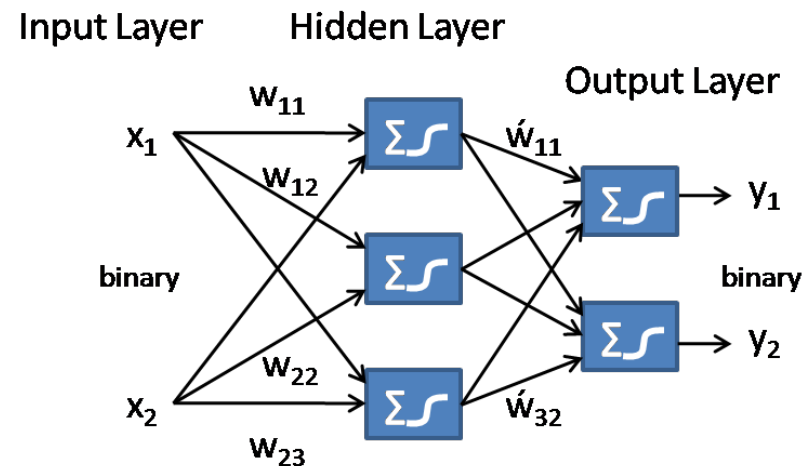
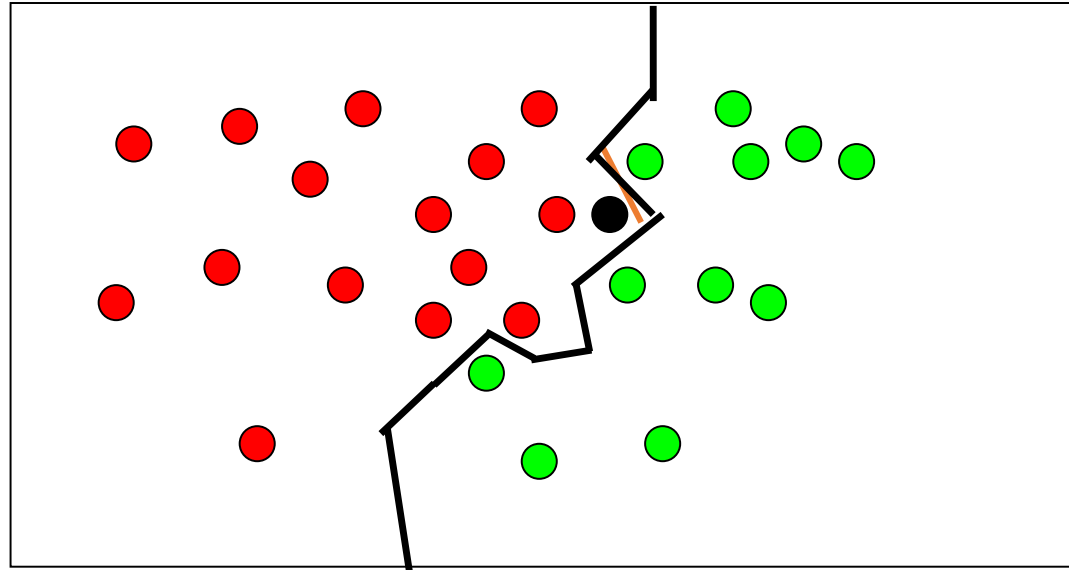
$$y = w_0 + w_1x_1 + w_2x_2$$

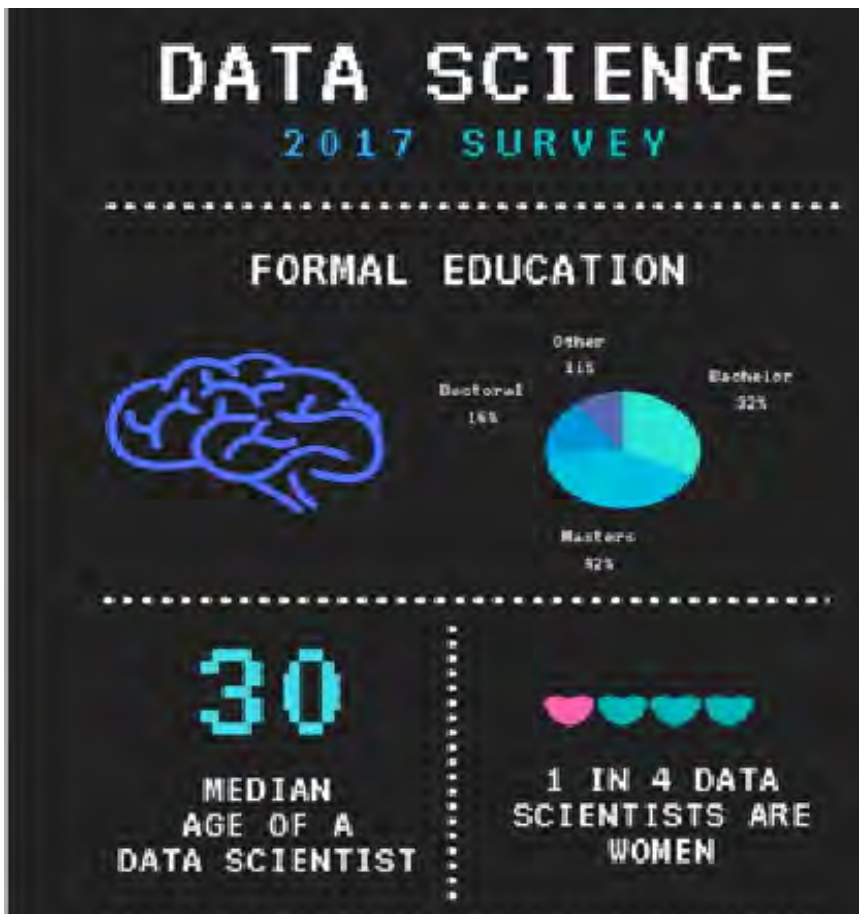
$$y = f(\mathbf{X}, \mathbf{W}) = \mathbf{X}^T \cdot \mathbf{W}$$

NON-GENERATIVE (OR ALGORITHMIC)

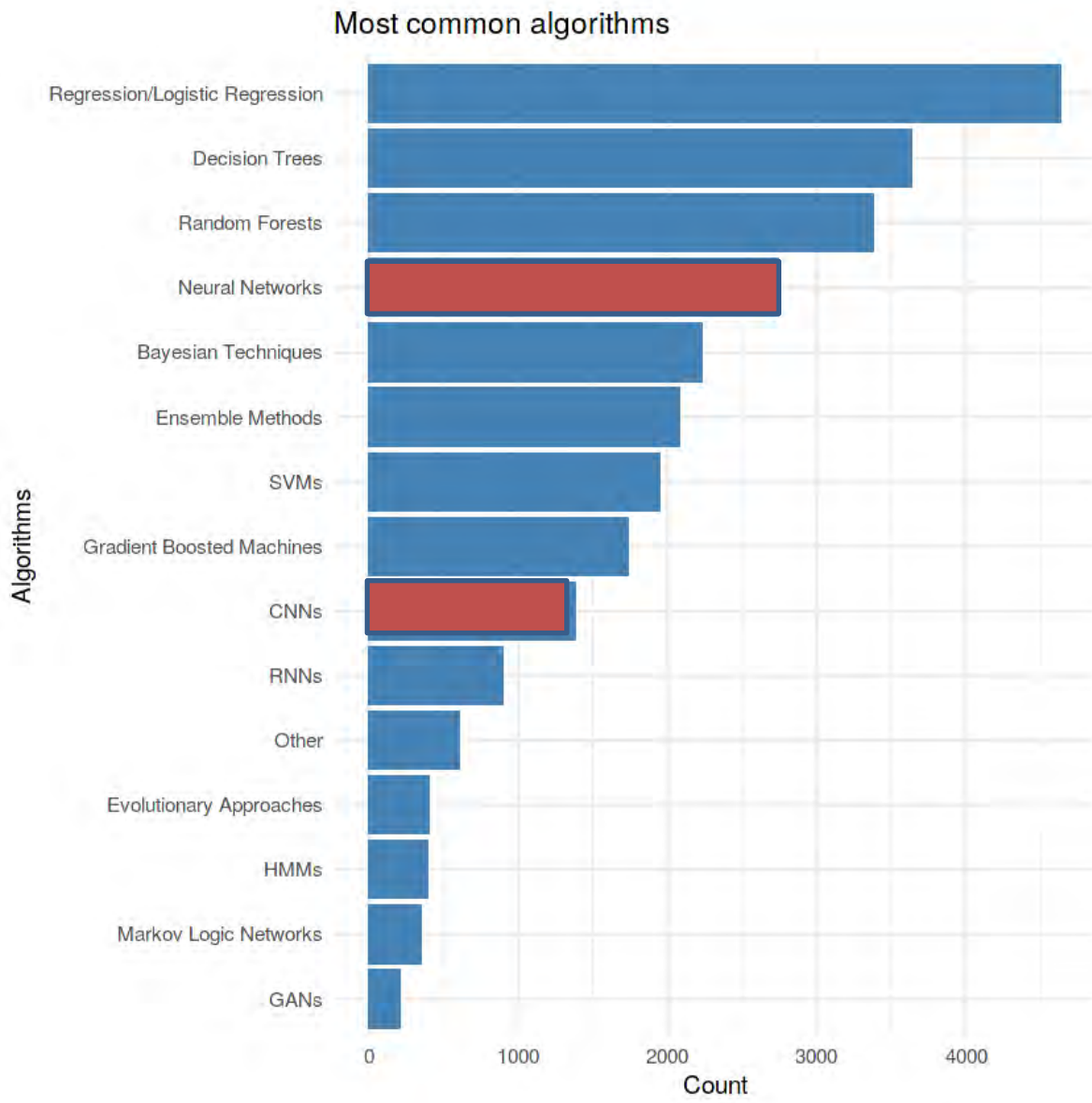
K Nearest Neighbours is the simplest non-generative method. It depends on a single parameter (K) to be tuned (generalization depends on K).

Increasing model complexity (e.g. number of parameters) can result in **overfitting** (lack of generalization).





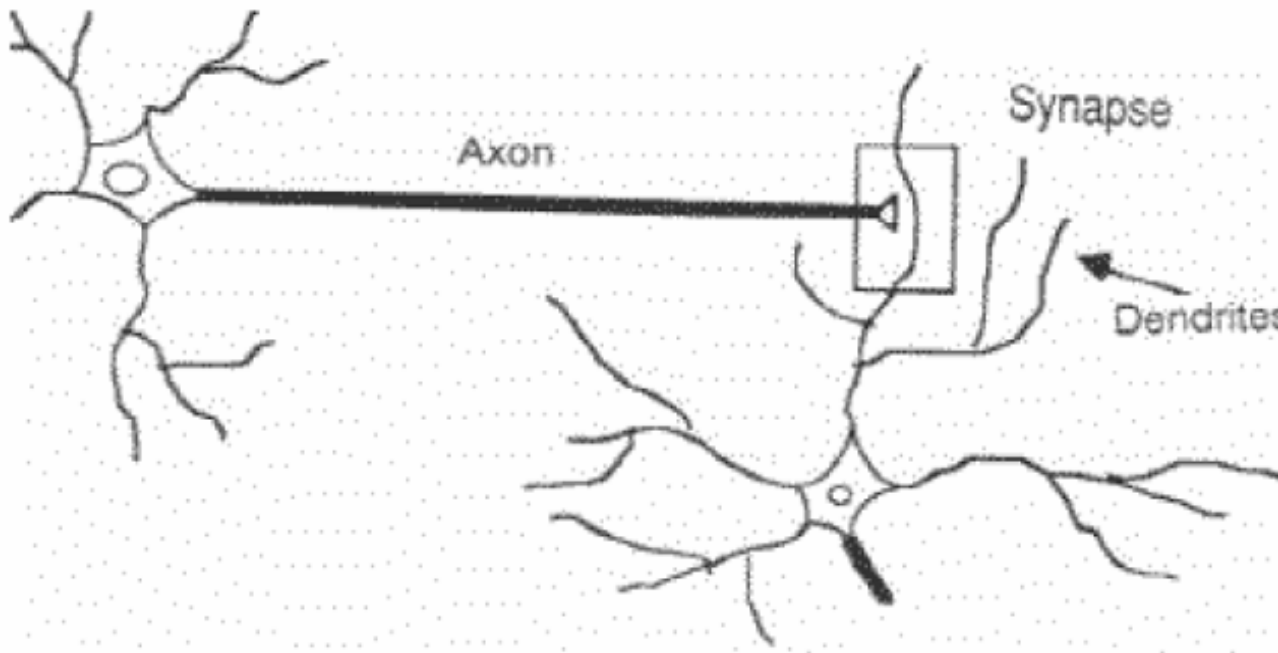
If you can't explain it **simply**,
you don't understand it well enough.



<https://www.kaggle.com/kaggle/kaggle-survey-2017>

Artificial Neural Networks are inspired in the structure and functioning of the **brain**, which is a collection of **interconnected neurons** (the simplest computing elements performing information processing):

- ✓ Each neuron consists of a cell body, that contains a cell **nucleus**.
- ✓ There are number of fibers, called **dendrites**, and a single long fiber called **axon** branching out from the cell body.
- ✓ The axon connects one neuron to others (through the dendrites).
- ✓ The connecting junction is called **synapse**.

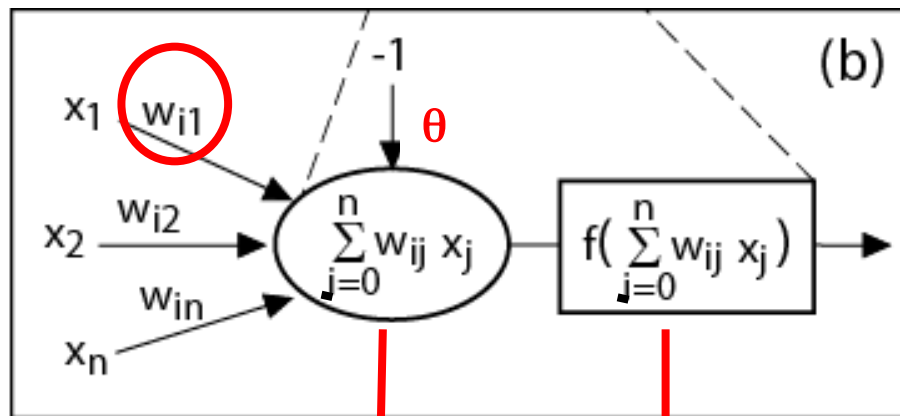


There are over **10^{11} neurons** in a human brain, each **connected with 1000** on average.

- The synapses releases chemical transmitter substances, entering the dendrite, raising or lowering (**excitatory and inhibitory synapses**) the electrical potential of the cell body.
- When the potential **reaches a threshold**, an electric pulse or action potential is sent down to the axon affecting other neurons (*there is a **nonlinear activation***).

$$y = f(\mathbf{w}^T \mathbf{x}), \text{ with } x_0 = -1 \text{ to account for } \theta: f(\mathbf{w}^T \mathbf{x} - \theta).$$

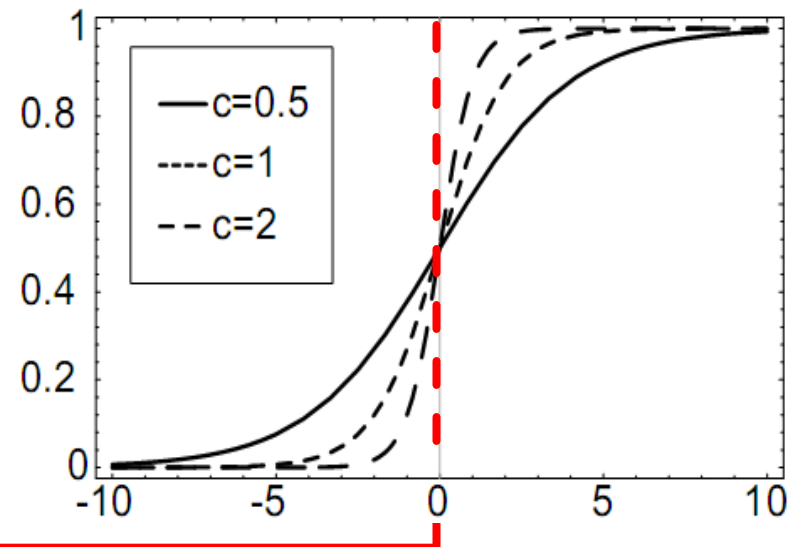
weights (+ or -, excitatory or inhibitory)



neuron potential:
mixed input of
neighboring neurons

nonlinear **activation** function

McCulloch & Pitts (1943)



(threshold = θ)

- **Funciones lineales:** $f(x) = x$.

- **Funciones paso:** Dan una salida binaria dependiente de si el valor de entrada está por encima o por debajo del valor umbral.

$$\text{sgn}(x) = \begin{cases} -1, & \text{si } x < 0, \\ 1, & \text{sino,} \end{cases}, \quad \Theta(x) = \begin{cases} 0, & \text{si } x < 0, \\ 1, & \text{sino.} \end{cases}$$

- **Funciones sigmoidales:** Funciones monótonas acotadas que dan una salida gradual no lineal.

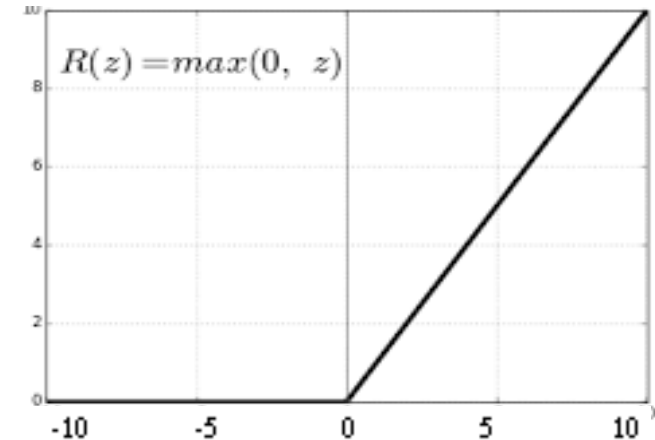
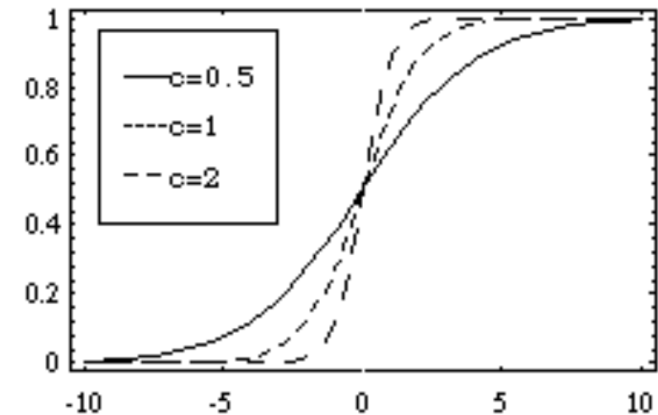
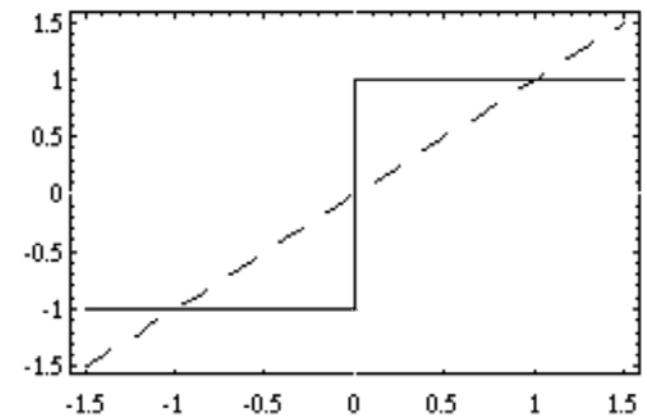
1. La función logística de 0 a 1:

$$f_c(x) = \frac{1}{1 + e^{-cx}}.$$

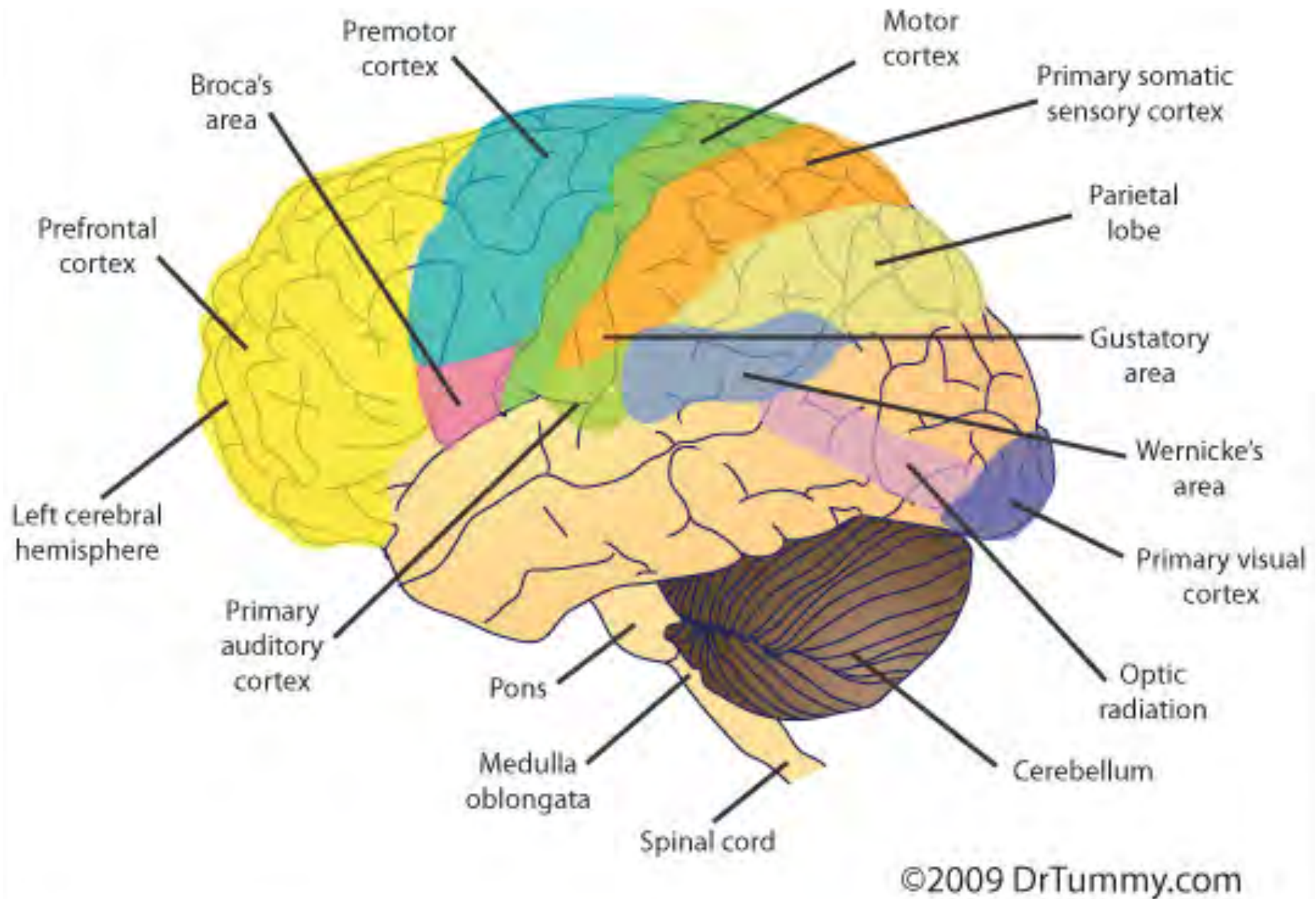
2. La función tangente hiperbólica de -1 a 1

$$f_c(x) = \tanh(cx).$$

- **Rectified linear unit (ReLU):** Utilizadas para evitar el “desvanecimiento del gradiente”.



TanH	$f(x) = \tanh(x) = \frac{2}{1+e^{2x}} - 1$	$f'(x) = 1 - f(x)^2$	$(-1, 1)$	C^∞
SoftSign	$f(x) = \frac{x}{1+ x }$	$f'(x) = 1 - f(x)^2$	$(-1, 1)$	C^1
SoftPlus	$f(x) = \ln(1 + e^x)$	$f'(x) = \frac{1}{1 + e^{-x}}$	$(0, \infty)$	C^∞
SoftExponential	$f(\alpha, x) = \begin{cases} -\frac{\ln(1-\alpha(x+\alpha))}{\alpha} & \text{for } \alpha < 0 \\ x & \text{for } \alpha = 0 \\ \frac{e^{\alpha x} - 1}{\alpha} + \alpha & \text{for } \alpha > 0 \end{cases}$	$f'(\alpha, x) = \begin{cases} \frac{1}{1-\alpha(x+\alpha)} & \text{for } \alpha < 0 \\ e^{\alpha x} & \text{for } \alpha \geq 0 \end{cases}$	$(-\infty, \infty)$	C^∞
Sinusoid	$f(x) = \sin(x)$	$f'(x) = \cos(x)$	$[-1, 1]$	C^∞
Sinc	$f(x) = \begin{cases} 1 & \text{for } x = 0 \\ \frac{\sin(x)}{x} & \text{for } x \neq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x = 0 \\ \frac{\cos(x)}{x} - \frac{\sin(x)}{x^2} & \text{for } x \neq 0 \end{cases}$	$[\approx -0.217234, 1]$	C^∞
Scaled exponential linear unit (SELU)	$f(\alpha, x) = \lambda \begin{cases} \alpha(e^x - 1) & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$ $\lambda = 1.0507$ y $\alpha = 1.67326$	$f'(\alpha, x) = \lambda \begin{cases} f(\alpha, x) + \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$(-\lambda\alpha, \infty)$	C^0
Rectified linear unit (ReLU)	$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(x) = \begin{cases} 0 & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$[0, \infty)$	C^0
Randomized leaky rectified linear unit (RReLU)	$f(\alpha, x) = \begin{cases} \alpha x & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(\alpha, x) = \begin{cases} \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$(-\infty, \infty)$	C^0
Parametric rectified linear unit (PReLU)	$f(\alpha, x) = \begin{cases} \alpha x & \text{for } x < 0 \\ x & \text{for } x \geq 0 \end{cases}$	$f'(\alpha, x) = \begin{cases} \alpha & \text{for } x < 0 \\ 1 & \text{for } x \geq 0 \end{cases}$	$(-\infty, \infty)$	C^0
Logistic (a.k.a soft step)	$f(x) = \frac{1}{1+e^{-x}}$	$f'(x) = f(x)(1 - f(x))$	$(0, 1)$	C^∞



Neural Network Study (1988, AFCEA International Press, p. 60):

*... a neural network is a system composed of **many simple processing elements operating in parallel** whose function is determined by network structure, connection strengths, and the processing performed at computing elements or nodes.*

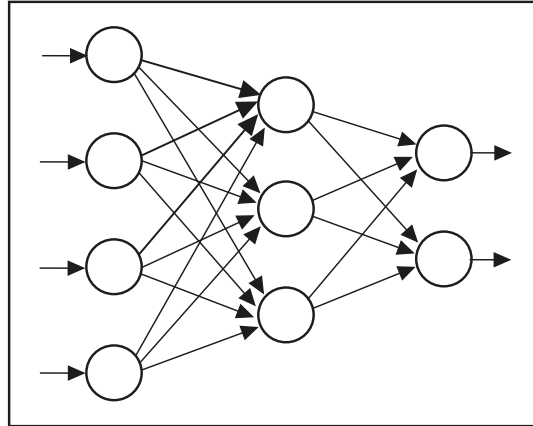
Haykin, S. (1994), Neural Networks: A Comprehensive Foundation, NY: Macmillan, p. 2:

A neural network is a massively parallel distributed processor that has a natural propensity for storing experiential knowledge and making it available for use. It resembles the brain in two respects:

- 1. Knowledge is acquired through a learning process.*
- 2. Neuron weights are used to store the knowledge.*

Supervised Problems. Input-Output pairs are provided:
 $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ and the network learns $y = f(x + \epsilon)$.

Multilayer Networks or Feedforward Nets.
Several layers connected (input+hidden+output)



Pattern Recognition

OCR, images

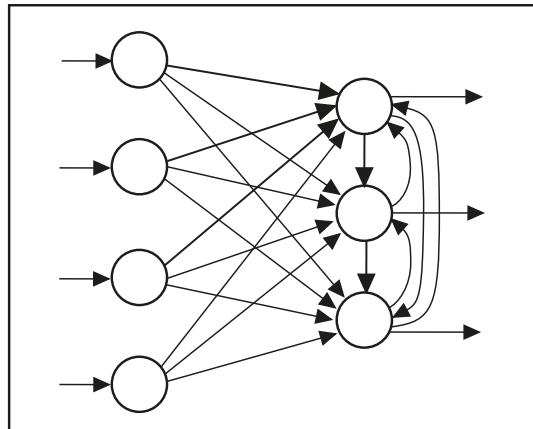
Interpolation and fitting

Prediction: Input \Rightarrow Output

Learning: Backpropagation

Unsupervised Problems. Only input data is provided:
 x_1, x_2, \dots, x_n and the network self-organizes it to provide a clustering.

Competitive Networks
Multilayer networks with lateral connections (competitive) in the last layer.



Segmentation

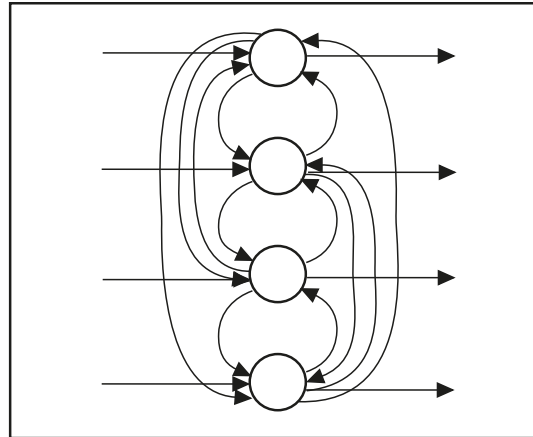
Feature extraction.

Prediction: Input \Rightarrow Clusters

Learning: Ad hoc
Winner-takes-all

Supervised Problems. Input-Input pairs are provided:
 $(x_1, x_1), (x_2, x_2), \dots, (x_n, x_n)$ and the network learns $x = f(x + \epsilon)$.

Autoassociative memories (Hopfield).
 Single layer with lateral delayed connections.



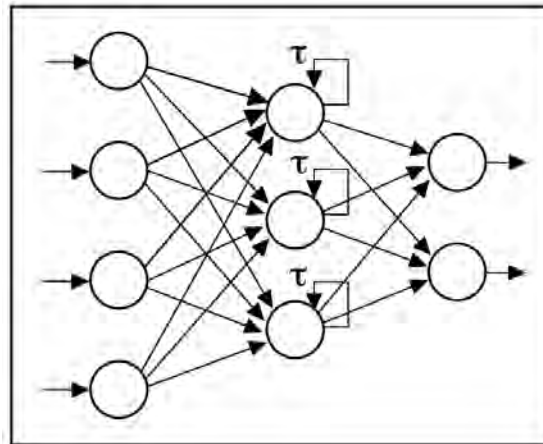
Pattern Recognition
 OCR, images
 Memories (robust to noise)
Prediction: Input \Rightarrow Input
Learning: Hegg

Autoencoders (later)

Feature extraction, compression.

Supervised Problems (with memory). Input-Output pairs are provided:
 $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ and the network learns $y_t = f(x_{t-1}, x_{t-2}, \dots + \epsilon)$.

Recurrent Networks or Elman/Jordan nets.
 Multilayer network with hidden/output delayed lines.

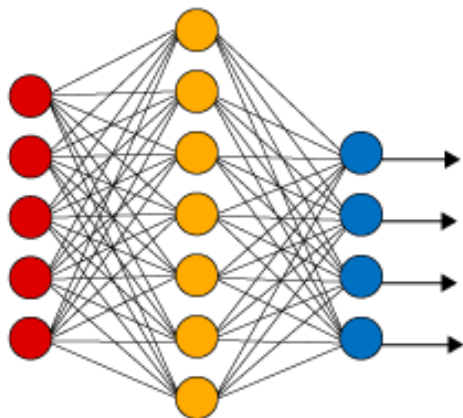


Time series analysis
 Video, natural language
 Interpolation and fitting
Prediction: Input \Rightarrow Output
Learning: Backpropagation in time

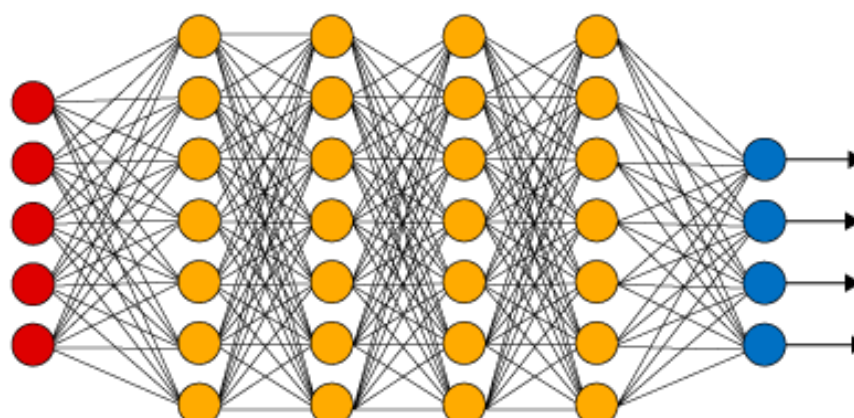
Deep Learning: Supervised and Reinforced Problems

$(x_1, y_1), (x_2, ?), \dots, (x_n, y_n)$ and the network self-organizes and learn $y = f(x)$.

Simple Neural Network



Deep Learning Neural Network



● Input Layer ● Hidden Layer ● Output Layer

<http://yann.lecun.com/exdb/mnist/>

60000+10000 images 32x32

Labeled as $\{0, \dots, 9\}$



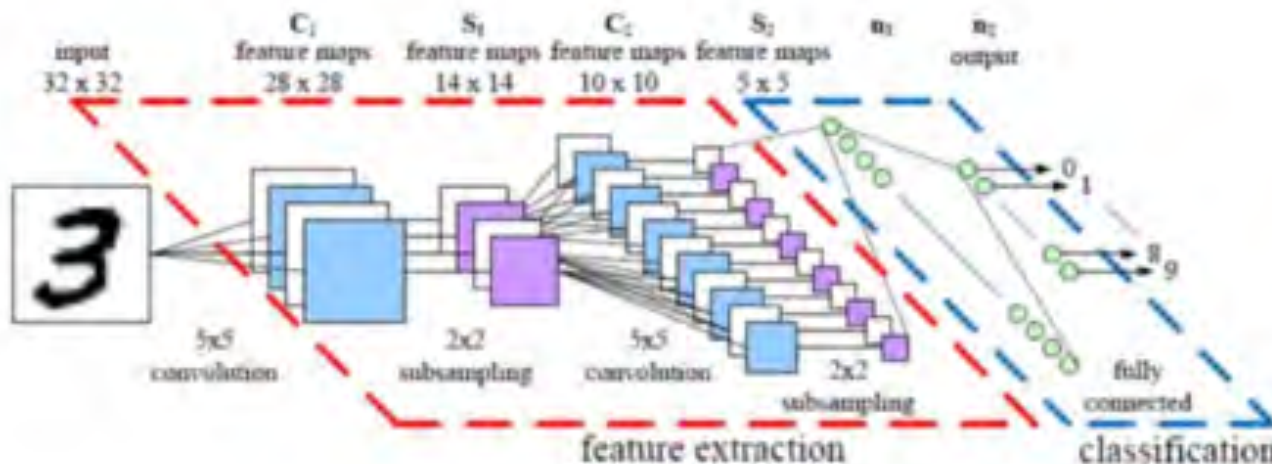
Linear: 10%. k-NN: 3%. SVM: 1%.

Deep: 0.3%

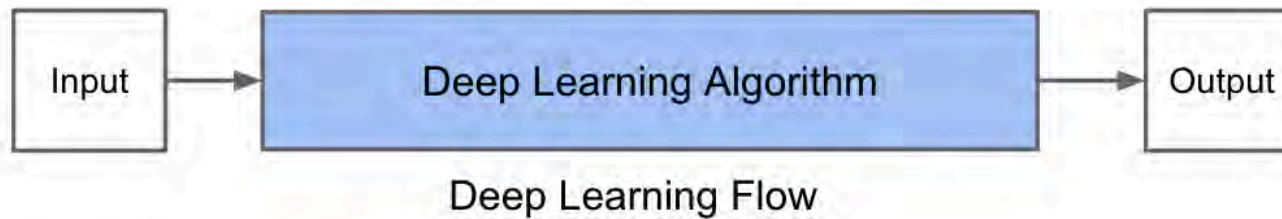
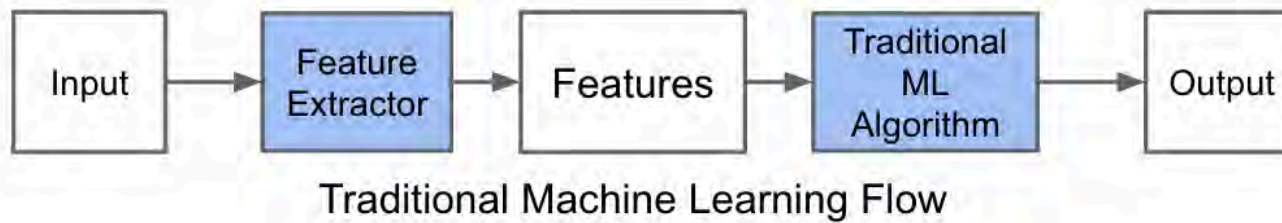
Include preprocessing layers for feature extraction:

- Convolutions
- Autoencoders

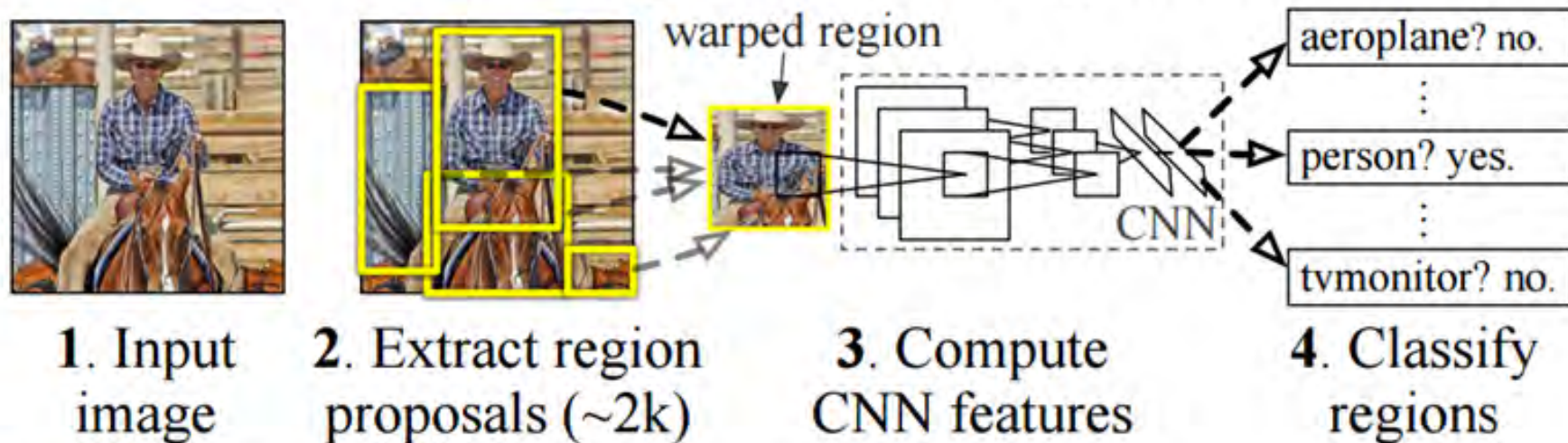
New optimization/learning.



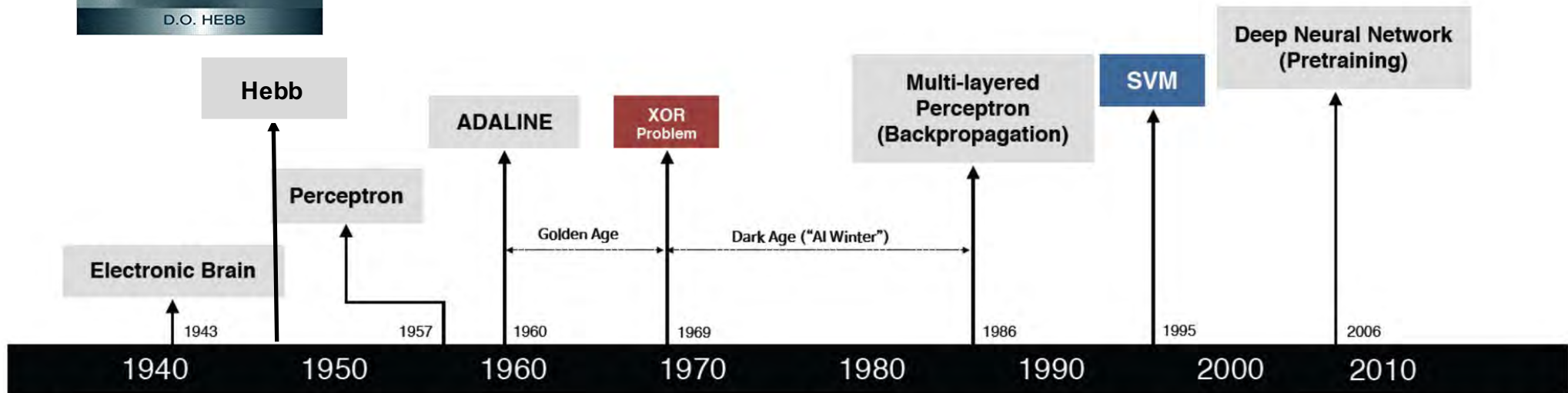
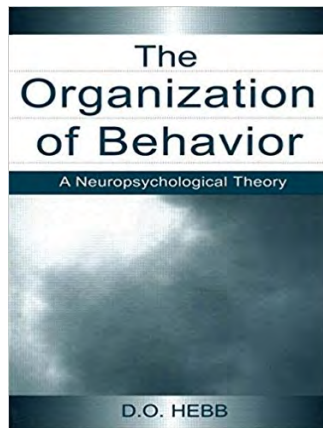
<http://www.kdnuggets.com/2017/08/convolutional-neural-networks-image-recognition.html>



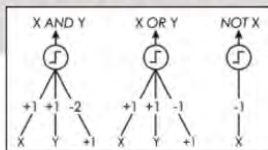
R-CNN: *Regions with CNN features*



R-CNN workflow



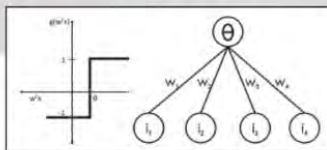
S. McCulloch – W. Pitts



- Adjustable Weights
- Weights are not Learned



F. Rosenblatt



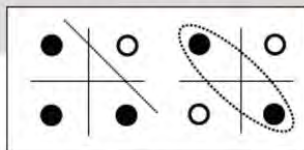
- Learnable Weights and Threshold



B. Widrow – M. Hoff



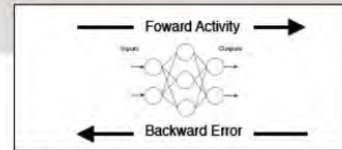
M. Minsky – S. Papert



- XOR Problem



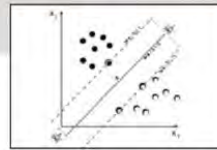
D. Rumelhart – G. Hinton – R. Williams



- Solution to nonlinearly separable problems
- Big computation, local optima and overfitting



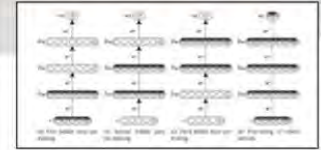
V. Vapnik – C. Cortes



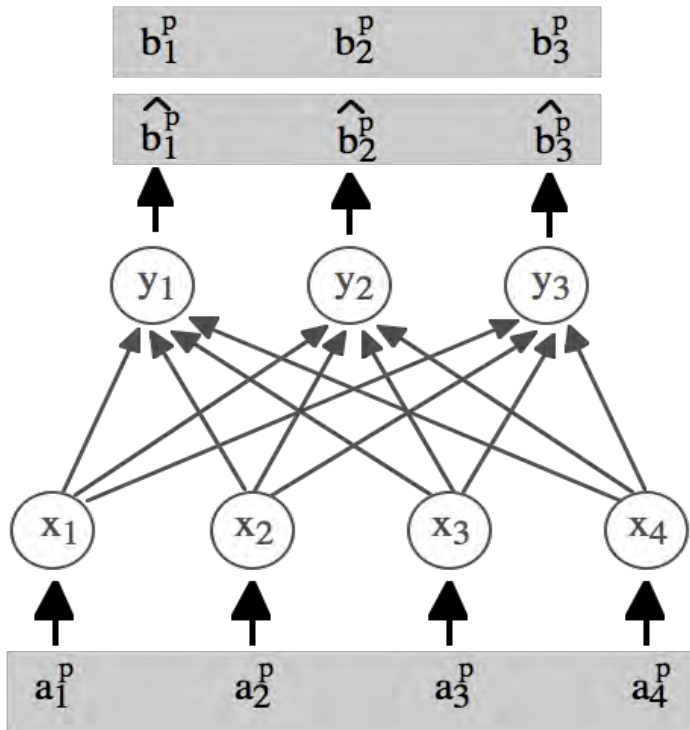
- Limitations of learning prior knowledge
- Kernel function: Human Intervention



G. Hinton – S. Ruslan



- Hierarchical feature Learning



$$E(w) = \frac{1}{2} \sum_{i,p} (b_i^p - \hat{b}_i^p)^2.$$

Inercia



Regularización



Inicialmente se eligen valores aleatorios para los pesos.

Aprendizaje Hebbiano (1949): Se modifican los pesos acorde a la correlación entre las unidades. Se eligen los patrones (a^p, b^p) de uno en uno y se modifican los pesos de los nodos con salidas incorrectas:

$$\Delta w_{ij} = \eta (b_i^p - \hat{b}_i^p) a_j^p$$

Descenso de gradiente: Se modifican los pesos acorde la dirección del gradiente del error.

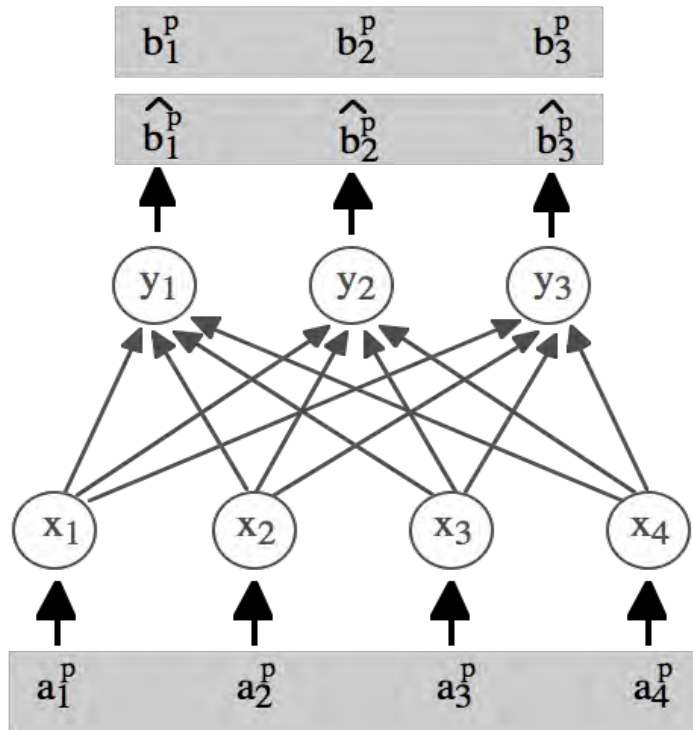
$$\Delta w_{ij} = -\eta \frac{\partial E}{\partial w_{ij}} = \eta \sum_p (b_i^p - \hat{b}_i^p) f'(B_i^p) a_j^p$$

η : Tasa de aprendizaje

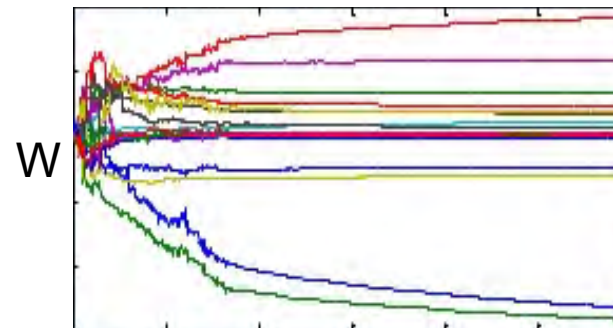
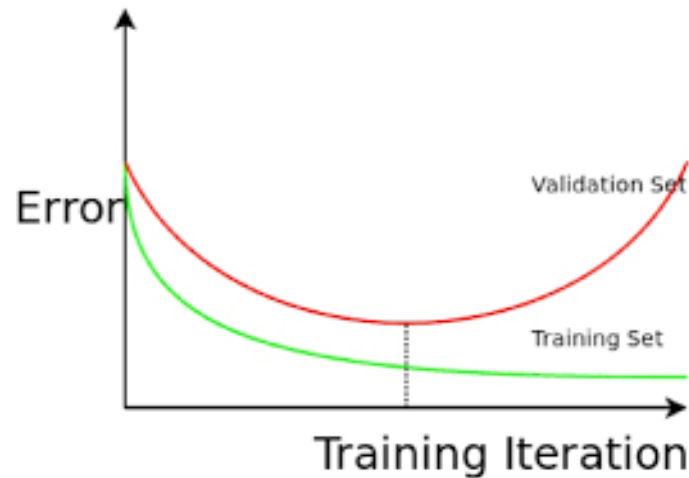
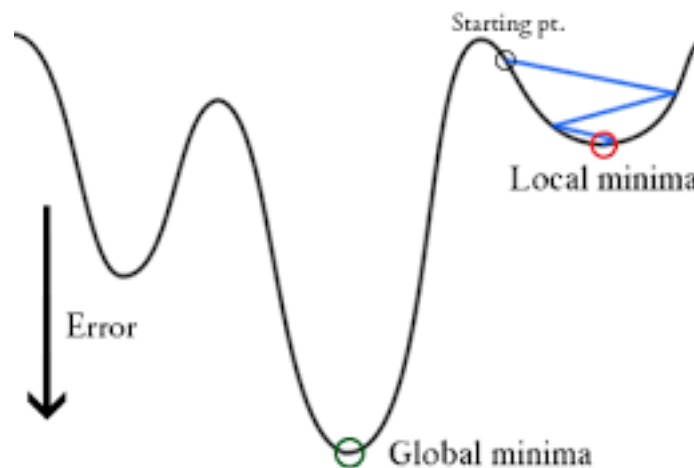
$$\Delta w_{ij}(t+1) = -\eta \frac{\partial E}{\partial w_{ij}} + \alpha \Delta w_{ij}(t-1)$$

$$E(w) = \sum_{p=1}^r (y_p - \hat{y}_p)^2 + \lambda \sum_{i,j} w_{ij}^2$$

RSNNS



$$E(w) = \frac{1}{2} \sum_{i,p} (b_i^p - \hat{b}_i^p)^2.$$



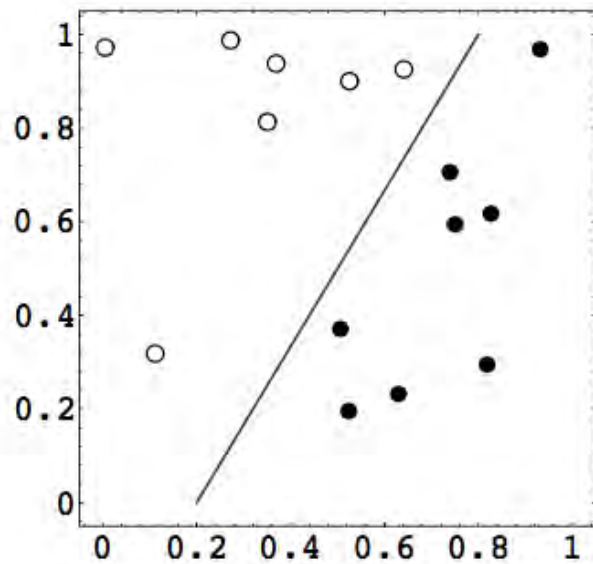
Error functions can be **highly nonlinear** and optimization can get trapped in local minima.

Several **replications** of the learning process are necessary (from different random initial weights).

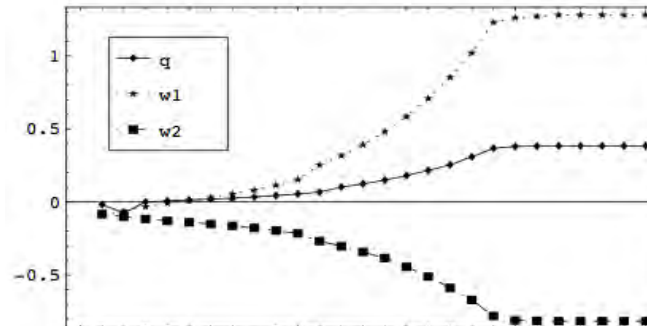
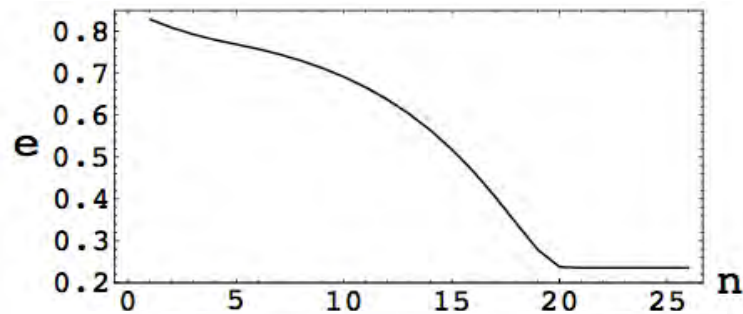
This process can be very **time consuming**.

Recent **advances** mitigate these problems.

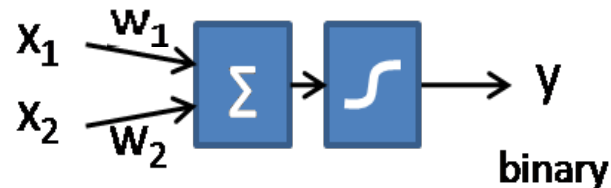
Overfitting is a critical problem in neural networks. The network should be carefully designed and/or **early stopping** learning should be adopted.



$$c_i = w_1 x_i + w_2 y_i + q,$$



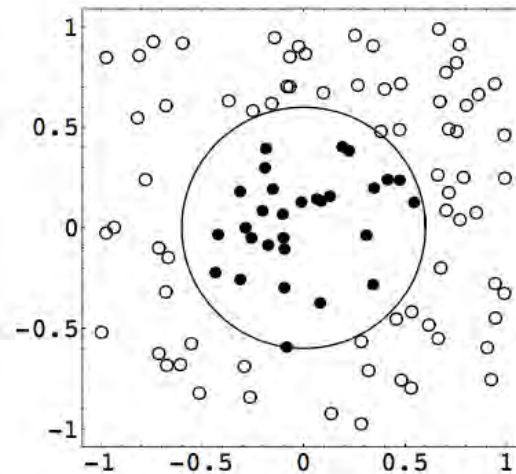
$$c_i = 1.28x_i - 0.815y_i + 0.384.$$



$$y = f(\mathbf{X}, \mathbf{W}) = \text{sigmod}(\mathbf{X}^T \cdot \mathbf{W})$$

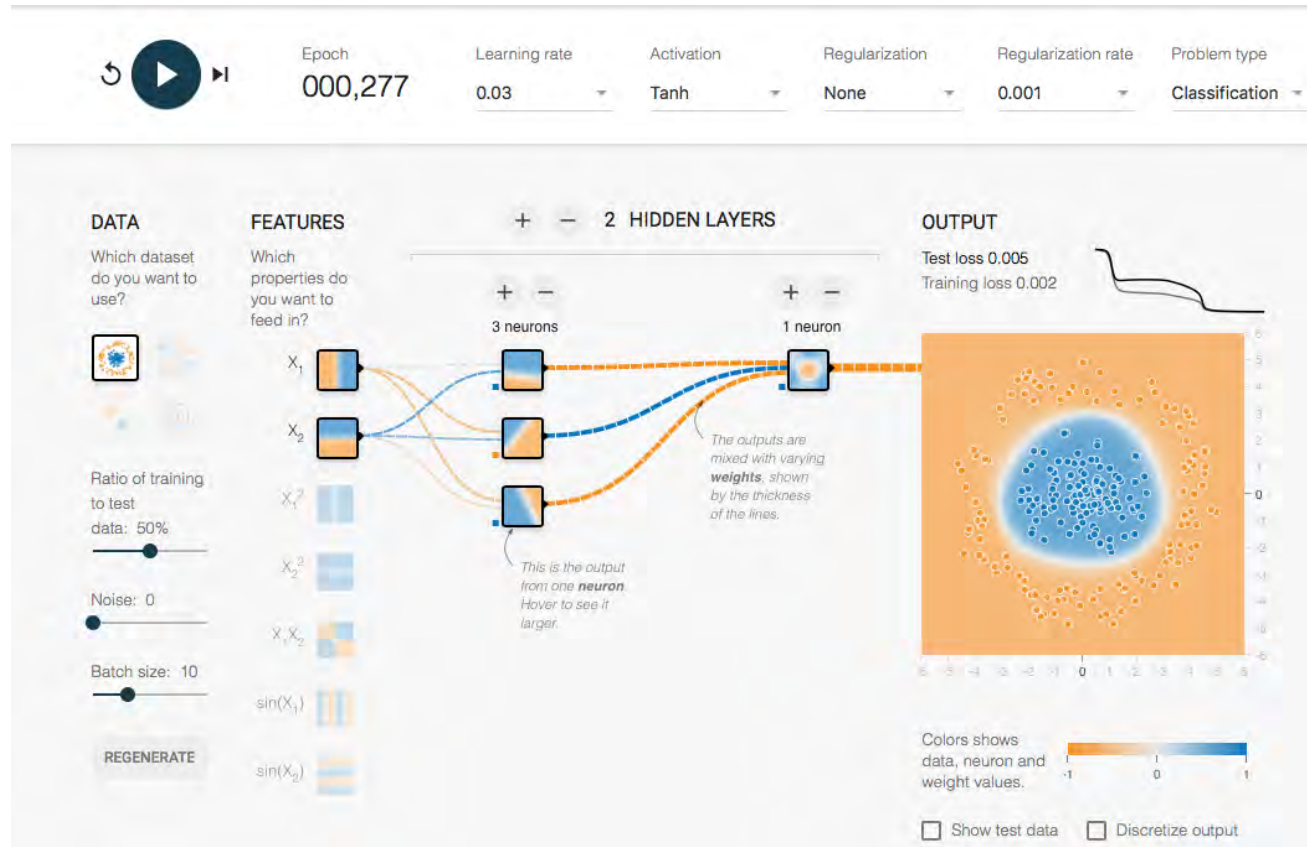
LOGISTIC REGRESSION

Single-layer networks
cannot approximate
nonlinear problems.



1. Watch an introductory video (19') on multi-layer neural networks.
2. Play around with the tensorflow illustrative tool.

Introductory video: <https://www.youtube.com/watch?v=aircAruvnKk>



<http://playground.tensorflow.org/>