# Notes on Ordinary Differential Equations—Summer 2025 $_{\rm w/Self}$

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# Chapter 1

# First Order Differential Equations

# 1.1 An Introduction to Differential Equations

In this chapter we will study:

- Separable
- Linear
- Homogeneous
- Bernoulli
- Exact

#### 1.1.1 Separable

### Solution Method for Separable Differential Equations

- 1. Determine the equilibrium solutions. These a ll of teh constant solutions  $y = y_0$  add are determined by solving the equation g(y) = 0 for  $y_0$ .
- 2. Separate the variables in a form convenient for integration. That is, we formally write

$$\frac{1}{g(y)}dy = h(t)dt$$

and refere to this equation as teh differential form of the separable differential equation.

3. Integrate both sides, the left-hand side with respect to y and the right-hand side with respect to t. This yields

$$\int \frac{1}{g(y)} dy = \int h(t) dt,$$

which produces the implict solution

$$Q(y) = H(t) + c,$$

where Q(y) is an antidierivative of 1/g(y) and H(t) is an antiderivative of h(t). Such antiderivatives differe by a constant c.

4. (If possible, solve the implicit relation explicitly for y.)

#### 1.2 Direction Fields

## 1.3 Separable Differential Equations

When we have a first order differential equation of the form

$$y' = F(t, y)$$

it is **separable** if there exists h(t) and g(y) such that

$$y' = h(t)g(y)$$

#### Solution Method for Separable Differentiable Equations

1. Determine the Equilibrium Solutions

These are all of the constant solutions  $y = y_0$ , determined by solving the equation g(y) = 0.

2. Separate the functions in a form convenient for Integration.

That is, we formally write

$$\frac{1}{g(y)}dy = h(t)dt$$

and refer to this equation as the *differential form* of teh separable differential equation.

3. Integrate both sides, the left-hand side with respect to y adn the right-hand side with respect to t. This yields

$$\int \frac{1}{g(y)} dy = \int h(t) dt.$$

which produces the implicit solution

$$Q(y) = H(t) + c.$$

where Q(y) is an antiderivative of 1/g(y) and H(t) is an antiderivative of h(t). Such antiderivatives differe by a constant c.

4. (if possible, solve the implicit relation explicitly for y.)

# 1.4 Linear First Order Equations

**Theorem 1.4.1.** Let p and f be continuous functions on an interval I. a function y is a solution of the first order linear differential equation y' + py = f on I if and only if

$$y = \frac{1}{\mu} \int \mu f dt + \frac{c}{\mu}$$

### Solution Method for First Order Linear Equations

- 1. Put the given linear equation in standard form: y' + py = f.
- 2. Find an inegratin factor,  $\mu$ : To do this, compute an anitderivative  $P = \int pdt$  and set  $\mu = e^P$ .
- 3. Multiply the equation (in standard form) by  $\mu$ : This yields

$$\mu y' + \mu' y = \mu f.$$

4. Simplify the left-had<br/>n side: Since  $(\mu y)' = \mu y' + \mu' y$ , we get

$$(\mu y)' = \mu f.$$

5. Integrate both sides of the resulign equation: This yields

$$\mu y = \int \mu f dt + c.$$

6. Divide by  $\mu$  to get the solution y:

$$y = \frac{1}{\mu} \int \mu f dt + \frac{c}{\mu}$$

- 1.5 Substitutions
- 1.6 Exact Equations
- 1.7 Existence and Uniqueness Theorem