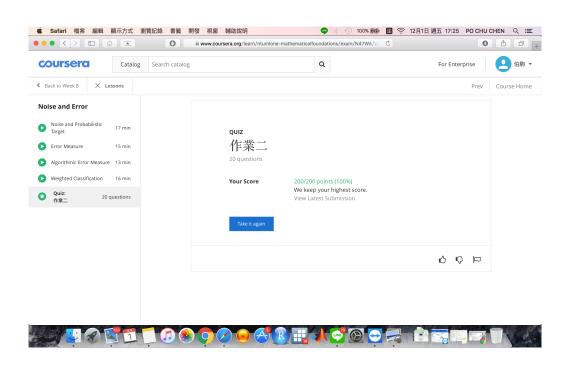
# Home Work 2 Machine Learning Foundations

## R04323050

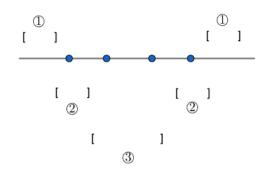
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## 1.



# **2**.

Positive & Negative interval on R. 可能的區間有以下情形:



- ①: 全為"-"或全為"+"
- ②: +- 或 -+
- ③: +-+ 或 -+-
- N 個點中間有 N-1 個間隔

$$\therefore m_{\mathcal{H}}(N) = 2 \times \left(1 + \binom{N-1}{1} + \binom{N-2}{2}\right) = N^2 - N + 2$$

## 3.

Claim:  $d_{vc}(\mathcal{H}) = D + 1$ 

We can observe the Hypothesis Set  $\mathcal{H}$  is a D-dim PLA from the slide in lecture 2.

 $\therefore$  By the slide in lecture 7, we've shown  $d_{vc}(\mathcal{H}) = D + 1$  during the class.

## 4.

"Triangle Waves" Hypothesis Set in  $\mathbb{R}$ :

$$\mathcal{H} = \{ h_{\alpha} | \quad h_{\alpha}(x) = sgn(|(\alpha x) \mod 4 - 2| - 1), \alpha \in \mathbb{R} \}$$

是個週期為  $\frac{4}{|\alpha|}$  的三角波函數. $^1$ 

 $:: \alpha \in \mathbb{R}$  ... 週期可以任意小。i.e x 軸  $(\mathbb{R}^1)$  可以被該曲線切成無限多個區域,故  $d_{vc}(\mathcal{H}) = \infty$ 

## **5.**

Claim: If  $\mathcal{H}_1 \subseteq \mathcal{H}_2$ , then  $d_{vc}(\mathcal{H}_1) \leq d_{vc}(\mathcal{H}_2)$ 

Suppose  $d_{vc}(\mathcal{H}) > d_{vc}(\mathcal{H}_2)$ ,則代表  $\mathcal{H}_1$  可以 shatter 的 inputs 個數超過  $\mathcal{H}_2$  所可以 shatter 的 inputs。i.e 至少存在一個 inputs x 使得  $\mathcal{H}_1(x) \notin \mathcal{H}_2$ , contradiction.(::

<sup>&</sup>lt;sup>1</sup>Triangle Waves Function: http://bit.ly/2nneX45

 $\mathcal{H}_1 \subseteq \mathcal{H}_2$ , ::  $\mathcal{H}_1$  所能夠產生的 dichotomies,  $\mathcal{H}_2$  也都要能夠產出) Hence,  $d_{vc}(\mathcal{H}) \leq d_{vc}(\mathcal{H}_2)$ 

**6.** 

By Q.15 on Couresa: 
$$\underline{\underline{\mathbf{Claim:}}} \max \{d_{vc}(\mathcal{H}_k)\}_{k=1}^K \le d_{vc}(\bigcup_{k=1}^K \mathcal{H}_k) \le K - 1 + \sum_{k=1}^K d_{vc}(\mathcal{H}_k)$$

**Left:** 設  $\mathcal{H}_1, \mathcal{H}_2, ..., \mathcal{H}_K$  所能夠 shatter 的最大 inputs 個數為 N,則  $\bigcup_{k=1}^{\infty} \mathcal{H}_k$  也至少能 夠 shatter N 個 inputs:

Suppose not, i.e suppose  $d_{vc}(\bigcup_{k=1}^{n} \mathcal{H}_k) = N-1$ , 這些  $\mathcal{H}_1, \mathcal{H}_2, ..., \mathcal{H}_K$  聯集起來 所形成的 Hypothesis Set 最多只能 shatter N-1 個 inputs, 代表這之中所能 shatter 最多的 inputs 也只會到 N-1 個, contradiction.

Hence,  $\max \{d_{vc}(\mathcal{H}_k)\}_{k=1}^K \leq d_{vc}(\bigcup_{k=1}^m \mathcal{H}_k)$ 

**Right:** 假設現在只有  $\mathcal{H}_1$ ,  $\mathcal{H}_2$  這兩種 Hypothesis Sets,  $\mathcal{H}_1$  是把平面上所有的點歸類為 +1;  $\mathcal{H}_2$  是把平面上所有點歸類為 -1,則我們知道  $d_{vc}(\mathcal{H}_1)=0$  &  $d_{vc}(\mathcal{H}_2)=0$ ,  $d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) = 1.$ 

... 從 Coursera Q.15 的選項中,
$$d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) = 1$$
,  $\sum_{k=1}^K d_{vc}(\mathcal{H}_k) = 0$ .

Hence, 
$$d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) = 1 \le 2 - 1 + 0 = K - 1 + \sum_{k=1}^{K} d_{vc}(\mathcal{H}_k) = 0$$
 成立。

Therefore,  $\max \{d_{vc}(\mathcal{H}_k)\}_{k=1}^K \le d_{vc}(\bigcup_{k=1}^K \mathcal{H}_k) \le K - 1 + \sum_{k=1}^K d_{vc}(\mathcal{H}_k).$ 

Now let  $\mathcal{H}_1$  be positive-ray hypothesis set and  $\mathcal{H}_2$  be negative-ray hypothesis set. By the slides in lecture 5, we know:  $m_{\mathcal{H}_1}(N) = N + 1$ ,  $d_{vc}(\mathcal{H}_1) = 1$ 

$$m_{\mathcal{H}_2}(N) = N + 1, \quad d_{vc}(\mathcal{H}_2) = 1$$

$$m_{\mathcal{H}_2}(N) = N + 1, \quad d_{vc}(\mathcal{H}_2) = 1$$

$$\therefore \max \{d_{vc}(\mathcal{H}_k)\}_{k=1}^2 = 1 \le d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) \le K - 1 + \sum_{k=1}^2 d_{vc}(\mathcal{H}_k) = 2 - 1 + 2 = 3$$

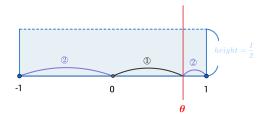
$$\Rightarrow 1 \le d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) \le 3.$$

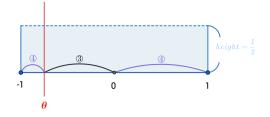
Also, we know the hypothesis set  $\mathcal{H}_1 \cup \mathcal{H}_2$  is actually the 1-d perceptron. Hence,  $m_{\mathcal{H}_1 \cup \mathcal{H}_2}(N) = 2N$  and  $d_{vc}(\mathcal{H}_1 \cup \mathcal{H}_2) = 2$  by the slides in lecture 5 and 7, which holds in the above inequality.

# **7.**

x is generated by a uniform distribution in [-1,1].

	$\theta$	s	預測錯誤率 $\mu = P(h \neq f)$
			$= P(s \cdot sgn(x - \theta) \neq sgn(x))$
0	> 0	+1	$P(sgn(x-\theta) \neq sgn(x)) = \theta \times \frac{1}{2}$
(2)	> 0	_1	$P(-sgn(x-\theta) \neq sgn(x))$
			$= [1 + (1 - \theta)] \times \frac{1}{2} = 1 - \frac{\theta}{2}$
3	< 0	+1	$P(sgn(x - \theta) \neq sgn(x)) = -\theta \times \frac{1}{2}$
4	< 0	-1	$P(-sgn(x-\theta) \neq sgn(x))$
			$= [1 + (1 + \theta)] \times \frac{1}{2} = 1 + \frac{\theta}{2}$



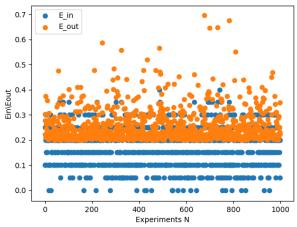


綜合
$$\Phi$$
、 $\Phi$ 、 $\Phi$ :  $\mu = \begin{cases} |\theta| \times \frac{1}{2} & \text{if } s = +1 \\ 1 - \frac{|\theta|}{2} & \text{if } s = -1 \end{cases}$  兩點式  $\mu = \frac{1}{2} + \left(\frac{|\theta| - 1}{2}\right) \times s$ 。  $^2$ 

$$\stackrel{\text{MLR}}{\Longrightarrow} \mu = \frac{1}{2} + \left(\frac{|\theta| - 1}{2}\right) \times s. \quad ^{2}$$

By Q.1 on coursera, we know 
$$E_{out}(h_{s,\theta}) = \lambda \cdot \mu + (1 - \lambda) \cdot (1 - \mu)$$
, where  $\lambda = 1 - 0.2 = 0.8$   
=  $0.8 \times \mu + 0.2 \times (1 - \mu)$   
=  $0.5 + 0.3 \cdot (|\theta| - 1) \cdot s$ 

### 8.

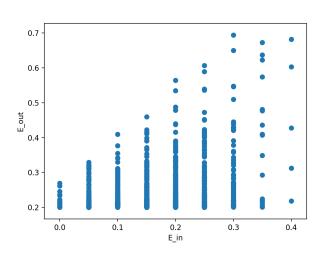


In the left figure, we can observe that the value of  $E_{in}$  is at least 0.2, which is exactly the probability of flipping noise. Intuitively,  $E_{out}$  is the expectation of  $[g(x) \neq f(x)]$ out of sample, now the flipping rate is 20%, then the above expectation term will be at least 20%.

Though we also have noise in sample of  $E_{in}$ , we can choose s and  $\theta$  to let  $E_{in}$  become smaller, so  $E_{in}$  could be less than 20%. However, the flipped y for out-of-sample is fol-

<sup>2</sup>Let 
$$\mu = a \cdot s + b$$
.  $|\theta| \times \frac{1}{2} = a + b - \mathbb{O}$ ,  $1 - \frac{|\theta|}{2} = -a + b - \mathbb{O}$  By  $\mathbb{O}$ ,  $\mathbb{O} \Rightarrow a = \frac{|\theta| - 1}{2}$ ,  $b = \frac{1}{2}$ 

lowed a distribution (i.e our target function) like Q.1 in coursera, which has a 20% filpped rate the optimal s and  $\theta$  that I choose through  $E_{in}$ , so  $E_{out}$  will be at least 20%.



Moreover, if we put  $E_{in}$  and  $E_{out}$  in the same plot, we can observe that when  $E_{in}$  is smaller; the variation of  $E_{out}$  will also be smaller. This result corresponds to what we expect: we can let  $E_{out}$  be small enough as long as we choose optimal s and  $\theta$  to minimize  $E_{in}$ . i.e Learning succeed:  $E_{in} \approx E_{out}$  and  $E_{in}$ ,  $E_{out}$  are small.

9.

#### Cover's Function Counting Theorem:

Let  $\{x^1, x^2, ..., x^p\}$  be vectors in  $\mathbb{R}^N$ , then the number of distinct dichotomies applied to these points that can be realized by a plane through the origin is:

$$C(P, N) = 2 \times \sum_{k=0}^{N-1} {P-1 \choose k}$$

在 d-維的 PLA 中,我們會對門檻值  $w_0$  再墊高一個向量  $x_0 = (1,1,1,...,1)$ ,用來突破分隔線只能通過原點的限制,而廣義上來說就是在  $\mathbb{R}^{d+1}$  中的向量  $\{x_1,x_2,...,x_N\}$  做通過原點的 PLA。

$$\therefore \text{ By Cover's theorem, } m_{\mathcal{H}}(N) = C(N, d+1) = 2 \times \sum_{i=0}^{d+1-1} \binom{N-1}{i} = 2 \times \sum_{i=0}^{d} \binom{N-1}{i}$$

#### Proof of Cover's theorem:<sup>3</sup>

Denote the number of linearly separable partition by C(P, N). We will find the expression for C(P, N) by induction. Image first having p points and then adding one more point. Now, considering the linearly separable partitions of previous p points, there are two possibilities:

<sup>&</sup>lt;sup>3</sup>Reference: http://bit.ly/2nnEtGC

Case 1: there is a separating hyperplane for the previous p points passing through the new point, in which case each such linearly separable partition of the previous p points gives rise to two distinct linearly separable partitions as the hyperplane can be shifted infinitesimally to place the new point in either class.

Case 2: there is no separating hyperplane for the previous p points passing through the new point, in which case each such linearly separable partition gives rise to only one linearly separable partition.

The number of linearly separable partition in Case 1 is precisely C(P, N-1), because restricting the separating hyperplane to pass through a fixed point is the same as eliminating one degree of freedom and thus projecting the p points to a N-1-dim space. This can be understood if the new point is on the x-axis, for example - then the hyperplane has N-1 axes left to work with. If the point is not on the x-axis, then rotate the axes of space around to get the point on the x axis, and this of course has no effect on the geometry of the problem.

The recursive relation:

C(P+1,N) = C(P,N) + C(P,N-1), where C(P,N) is the number of separable hyperplanes in Case 2, and C(P,N-1) is the number of separable hyperplanes in Case 1.

Iterating the recursion once, we have

$$C(P+1,N) = C(P-1,N) + 2C(P-1,N-1) + C(P-1,N-2)$$

Continue to iterate the recursion (twice)

$$C(P+1,N) = C(P-2,N) + 3C(P-2,N-1) + 3C(P-2,N-2) + C(P-2,N-3)$$

After P-1 iterations, we have

$$C(P+1,N) = \binom{P}{0}C(1,N) + \binom{P}{1}C(1,N-1) + \dots + \binom{P}{P}C(1,N-P)$$
, where  $C(1,k) = 2$  for all  $k \le 1$ .

So, finally we have 
$$C(P+1,N) = 2 \times \sum_{i=0}^{N-1} {P \choose i}$$
, where  ${P \choose i} = 0$  if  $i > P$ .