

1. Use sleep/wakeup in KBD driver

Download samples/LAB4/lab4.tgz

run `zcat lab4.tgz | tar xvf -` to extract files.

(1). wait.c files contains `kexit()`, `ksleep()`, `kwakeup()`.

Implement `ksleep()`, `kwakeup()` as in 5.6.1 of textbook

ADD two commands: `sleep` and `wakeup` to test YOUR `ksleep/kwakeup`

`sleep` : ask for a value to sleep on; sleep on that value.

`wakeup`: ask for a value to wakeup with; wakeup ALL procs sleeping on that value.

(2). The KBD driver `kbd.c` uses BUSY wait loop in `kgetc()`.

Use `sleep/wakeup` in `kgetc()/kbd_handler()` to synchronize

process and KBD interrupts.

2. 5.13.2.2 shows a PIPE using sleep/wakeup. However,

It does not check for BROKEN pipe condition for `pipe_writer`,
and no-writer condition for `pipe_reader`.

Download samples/LAB4/pipe.tgz

Implement `write_pipe()` to detect BROKEN pipe condition (if so, `kexit`)

`read_pipe()` to detect no-writer condition (if so, return 0).

Testing: 1. Let writer do `while(1)` loop; reader only read 2 times

2. Let reader do `while(1)` loop; writer only write 2 times.

3. Duplicate and RUN the message passing program in 5.13.4.2