

# ESC101: Introduction to Computing

## Sorting



# Selection Sort

- ◆ Select the largest element in your array and swap it with the first element of the array.
- ◆ Consider the sub-array from the second element to the last, as your current array and repeat Step 1.
- ◆ Stop when the array has only one element.
  - Base case, trivially sorted

# Selection Sort: Pseudo code

```
selection_sort(a[], start, end) {  
    if (start == end) /* base case, one elt => sorted */  
        return;  
  
    idx_max = find_idx_of_max_elt(a, start, end);  
    swap(a, idx_max, start);  
    selection_sort(a, start+1, end);  
}
```

```
swap(a[], i, j) {  
    tmp = a[i];  
    a[i] = a[j];  
    a[j] = tmp;  
}
```

```
main() {  
    arr[] = { 5, 6, 2, 3, 1, 4 };  
    selection_sort(arr, 0, 5);  
    /* print arr */  
}
```

# Selection Sort: Time Estimate

## ◆ Recurrence

$$T(n) = T(n - 1) + k_1 \times n + k_2$$

## ◆ Solution

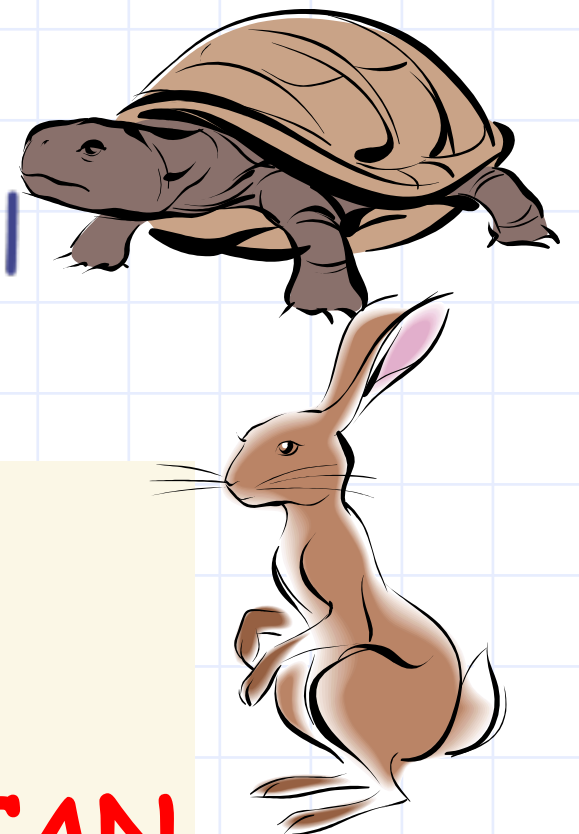
$$T(n) \propto n(n + 1)$$

## ◆ Or simply

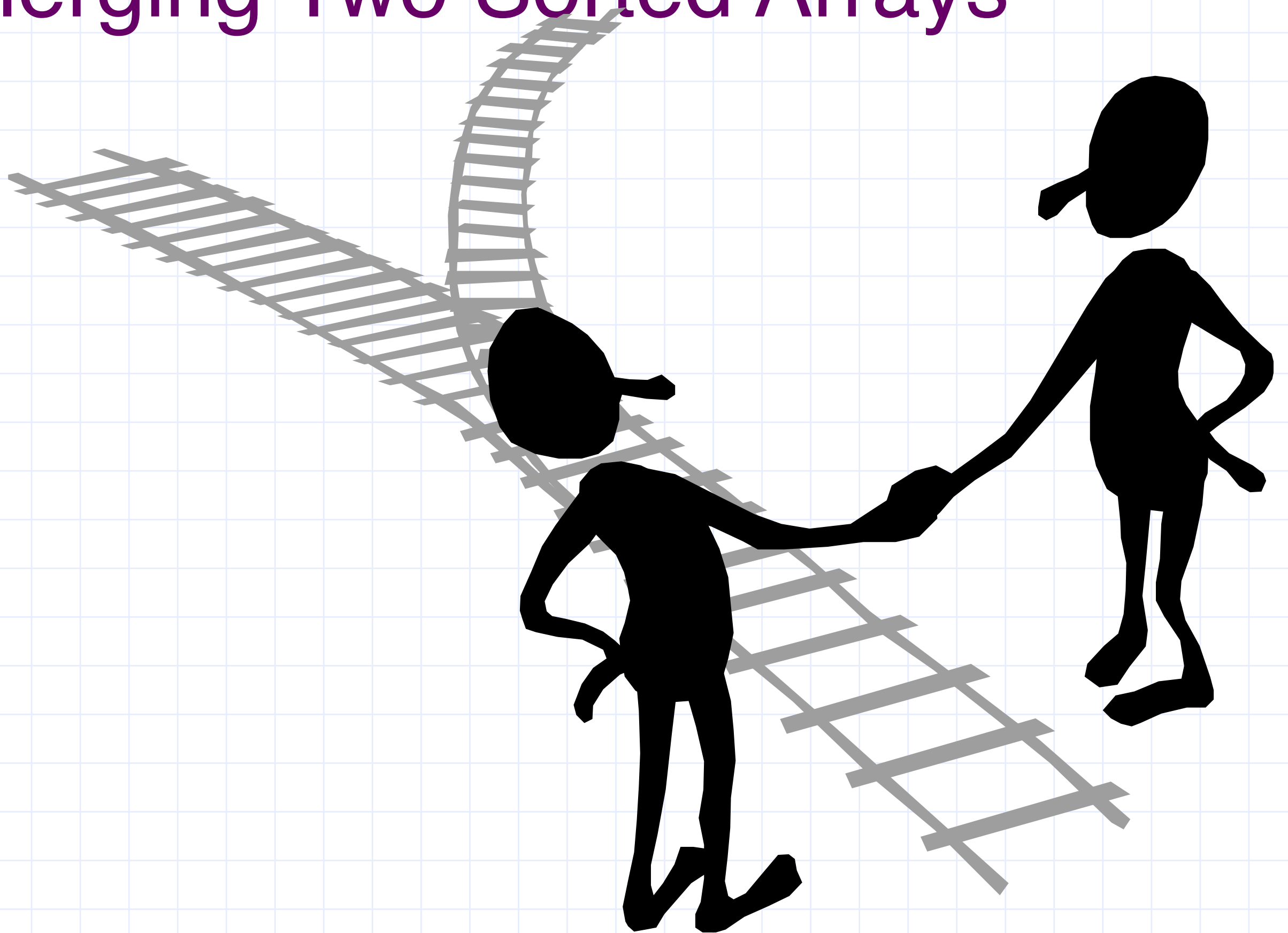
$$T(n) \propto n^2$$

Selection sort runs in time proportional to the **square** of the size of the array to be sorted.

Can we do  
**better?**  
**YES WE CAN**



# Merging Two Sorted Arrays





# Merging Two Sorted Arrays

- ◆ Input: Array A of size  $n$  & array B of size  $m$ .
- ◆ Create an empty array C of size  $n + m$ .
- ◆ Variables  $i$ ,  $j$  and  $k$ 
  - array variables for the arrays A, B and C resp.
- ◆ At each iteration
  - compare the  $i^{\text{th}}$  element of A (say  $u$ ) with the  $j^{\text{th}}$  element of B (say  $v$ )
  - if  $u$  is smaller, copy  $u$  to C; increment  $i$  and  $k$ ,
  - otherwise, copy  $v$  to C; increment  $j$  and  $k$ ,

```
#include <stdio.h>
int merge(int a[], int n1, int b[], int n2, int c[], int n3);

int main()
{
    int a[]={10,20, 30};
    int b[]={5,15, 25};
    int c[10];
    int n;
    n = merge(a, 2, b, 2, c, 0);
    for(int i=0; i<n; i++)
        printf("%d ",c[i]);
    printf("\n");
    return 0;
}
```

```

int merge(int a[], int n1, int b[], int n2, int c[], int n3)
{
    if (n1 < 0 && n2 < 0)
        return n3;

    if(n1 < 0)
    {
        c[n3] = b[n2];
        n3++; n2--;
        return merge(a, n1, b, n2, c, n3); //could be done with a for loop too
    }

    if(n2 < 0)
    {
        c[n3] = a[n1];
        n3++; n1--;
        return merge(a, n1, b, n2, c, n3); //could be done with a for loop too
    }

    if(a[n1] > b[n2])
    {
        c[n3] = a[n1]; n3++; n1--;
    }
    else
    {
        c[n3] = b[n2]; n3++; n2--;
    }

    return merge(a, n1, b, n2, c, n3);
}

```



# Time Estimate

- ◆ Number of steps  $\propto 3(n + m)$ .
  - The constant 3 is not very important as it does not vary with different sized arrays.
- ◆ Now suppose A and B are halves of an array of size n (both have size  $n/2$ ).
- ◆ Number of steps =  $3n$ .

$$T(n) \propto n$$

# Merge Sort

- ◆ Merge function can be used to sort an array
  - recursively!
- ◆ Given an array  $C$  of size  $n$  to sort
  - Divide it into Arrays  $A$  and  $B$  of size  $n/2$  each (approx.)
  - Sort  $A$  into  $A'$  using MergeSort
  - Sort  $B$  into  $B'$  using MergeSort
  - Merge  $A'$  and  $B'$  to give  $C' \equiv C$  sorted
- ◆ Can we reduce #of extra arrays ( $A', B', C'$ )?

Recursive calls.  
Base case?

$n \leq 1$

```
/*Sort ar[start, ..., start+n-1] in place */  
void merge_sort(int ar[], int start, int n) {  
    if (n>1) {  
        int half = n/2;  
        merge_sort(ar, start, half);  
        merge_sort(ar, start+half, n-half);  
        merge(ar, start, n);  
    }  
}
```

```
int main() {  
    int arr[]={2,5,4,8,6,9,8,6,1,4,7};  
    merge_sort(arr,0,11);  
    /* print array */  
    return 0;  
}
```

```

void merge(int ar[], int start, int n) { //n is no of elems
    int temp[MAX_SZ], k, i=start, j=start+n/2;
    int lim_i = start+n/2, lim_j = start+n;
    for(k=0; k<n; k++) {
        if ((i < lim_i) && (j < lim_j)) { // both active
            if (ar[i] <= ar[j]) { temp[k] = ar[i]; i++; }
            else { temp[k] = ar[j]; j++; }
        } else if (i == lim_i) // 1st half done
            { temp[k] = ar[j]; j++; } // copy 2nd half
        else // 2nd half done
            { temp[k] = ar[i]; i++; } // copy 1st half
        }
    }
    for (k=0; k<n; k++)
        ar[start+k]=temp[k]; // in-place
}

```

# Time Estimate

```
void merge_sort(int a[], int s, int n) {  
    if (n > 1) {  
        int h = n/2;  
        merge_sort(a, s, h);  
        merge_sort(a, s+h, n-h);  
        merge(a, s, n);  
    }  
}
```

$T(n)$

$C$

$C$

$T(n/2)$

$T(n-n/2) \approx T(n/2)$

$\approx 4n$

$$T(n) \propto n \log_2 n$$

# Time Estimate

$$T(n) = 2T(n/2) + 4n$$

$$= 2(2T(n/4) + 4n/2) + 4n = 2^2T(n/4) + 8n$$

$$= 2^2(2T(n/8) + 4n/4) + 4n = 2^3T(n/8) + 12n$$

$$= \dots // \text{ keep going for } k \text{ steps}$$

$$= 2^kT(n/2^k) + k \cdot 4n$$

Assume  $n = 2^k$  for some  $k$ . Then,

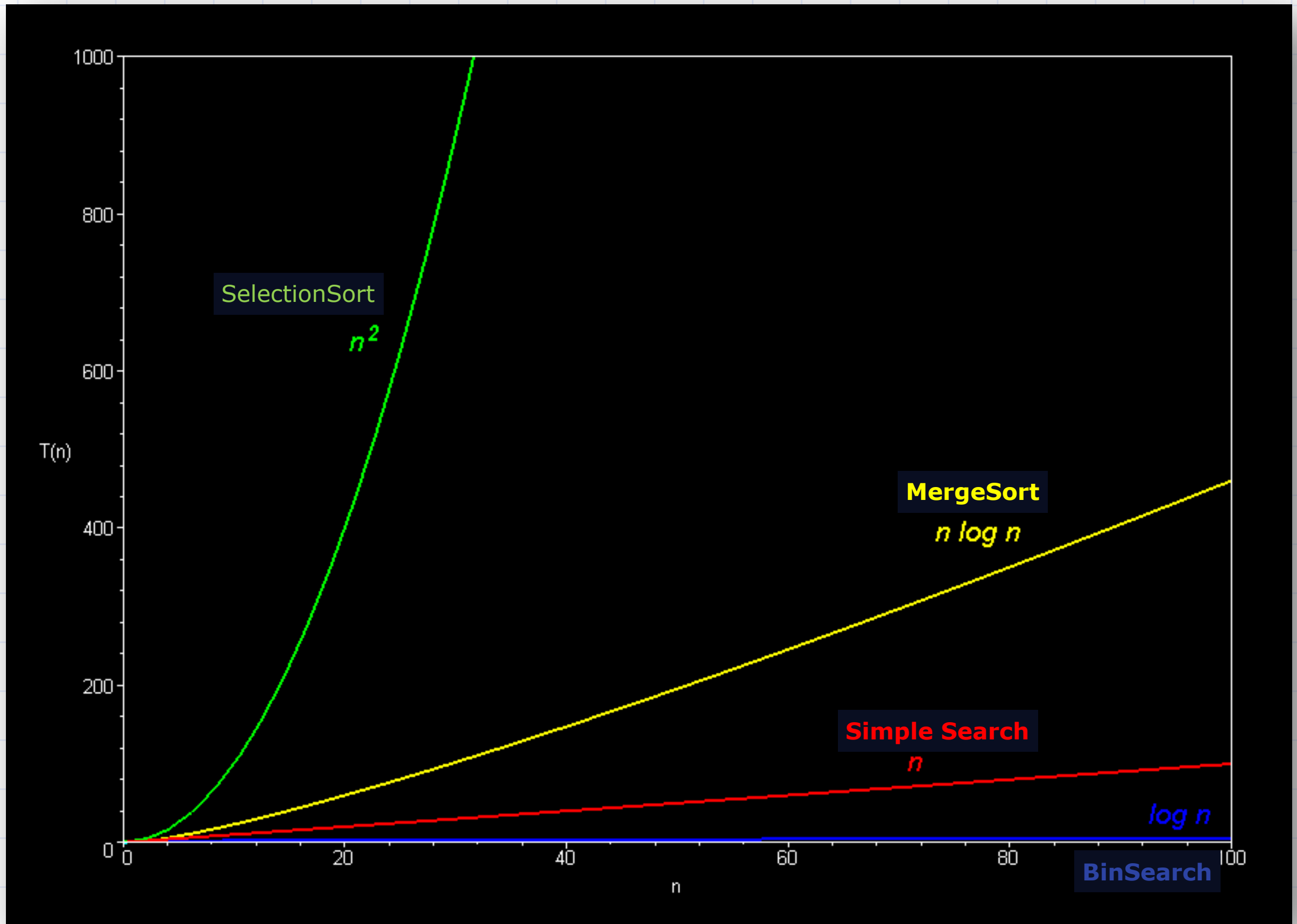
$$T(n) \propto n \log_2 n$$



# Time Estimates...

**Why worry  
about  $O(n)$  vs  
 $O(n^2)$  vs  $O(\dots)$   
algorithm?**

# Time Estimates...



Around Easter 1961, a course on ALGOL 60 was offered ...  
It was there that I first learned about recursive procedures and saw how to program the sorting method which I had earlier found such difficulty in explaining.

It was there that I wrote the procedure, immodestly named **QUICKSORT**, on which my career as a computer scientist is founded. Due credit must be paid to the genius of the designers of ALGOL 60 **who included recursion in their language** and enabled me to describe my invention so elegantly to the world.

I have regarded it as the highest goal of programming language design to enable good ideas to be elegantly expressed.

- **C. A. R. Hoare, ACM Turing Award Lecture, 1980**

# QuickSort - Partition Routine

A useful sub-routine (function) for many problems, including **quicksort**, one of the popular sorting methods.

- 1. Partition takes an array  $a[]$  of size  $n$  and a value called the pivot.**
  - 2. The pivot is an element in the array, for instance,  $a[0]$ .**
  - 3. Partition re-arranges the array elements into two parts:**
    - a) the left part has all elements  $\leq$  pivot.**
    - b) the right part has all elements  $\geq$  pivot.**
  - 4. Partition returns the index of the beginning of the right part.**
- Let us see an example.

1. **Partition** takes an array  $a[]$  of size  $n$  and a value called the pivot.
2. The pivot is an element in the array, for instance,  $a[0]$ .
3. Partition re-arranges the array elements into two parts:
  - a) all elements in the left part are  $\leq$  pivot
  - b) all elements in the right part are  $\geq$  pivot

Input Array  $a[]$ , size is  $n : 11$

31	4	10	35	59	31	3	25	35	11	0
----	---	----	----	----	----	---	----	----	----	---

**Pivot** element is assumed to be  $a[0] : 31$

0	4	10	11	25	3	31	59	35	35	31
---	---	----	----	----	---	----	----	----	----	----

left partition

right partition

# Observations

Multiple “partitions” of an array are possible, even for the same pivot. They all would satisfy the above specification.

Note: Partition **DOES NOT** sort the array. It is “weaker” than sorting. But it is useful step towards sorting (useful for other problems also).