



Introduction to Deep Learning and Tensorflow

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Deep learning
attracts lots of attention.

© Google Trends

Deep learning obtains many exciting results.

➡ The talks in this afternoon

This talk will focus on the technical part.



Outline

- Part I: Introduction of Deep Learning



- Part II: Why Deep?



- Part III: Tips for Training Deep Neural Network



- Part IV: Neural Network with Memory

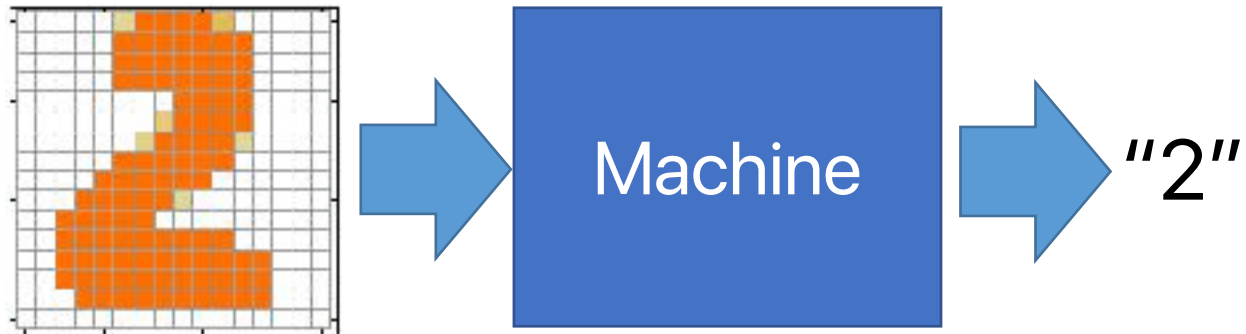
A decorative network diagram in the top-left corner, featuring a complex web of interconnected nodes and edges. The nodes are represented by small circles, some of which are highlighted with a double-circle outline. The edges are thin, light gray lines connecting the nodes.

Part I: **Introduction of Deep Learning**

A decorative network diagram in the bottom-right corner, similar to the one in the top-left. It shows a cluster of nodes connected by lines, with some nodes having a double-circle outline.

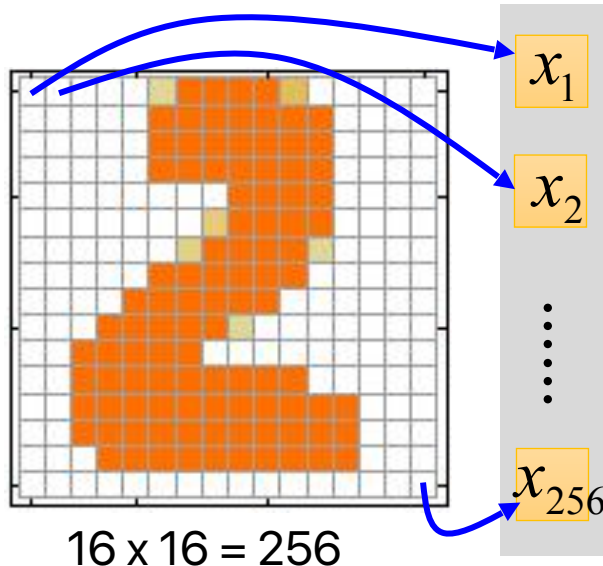
Example Application

© Handwriting Digit Recognition



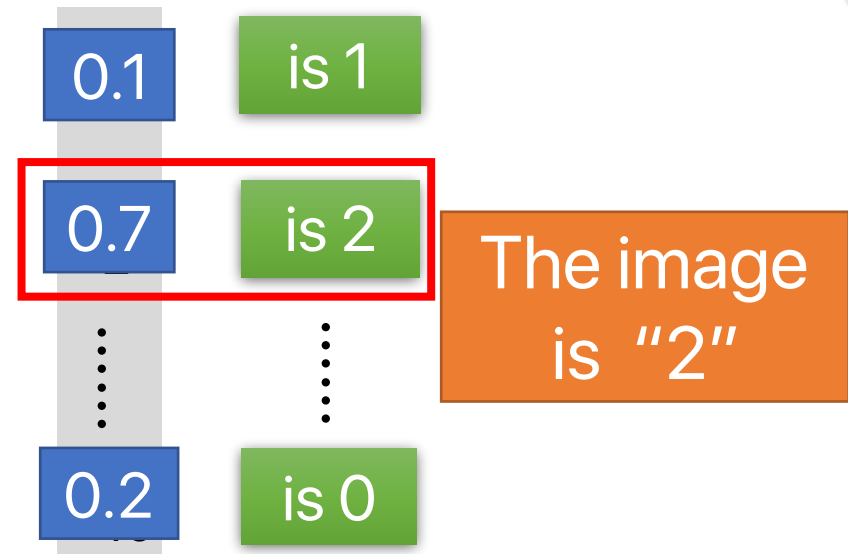
Handwriting Digit Recognition

Input



Ink \rightarrow 1

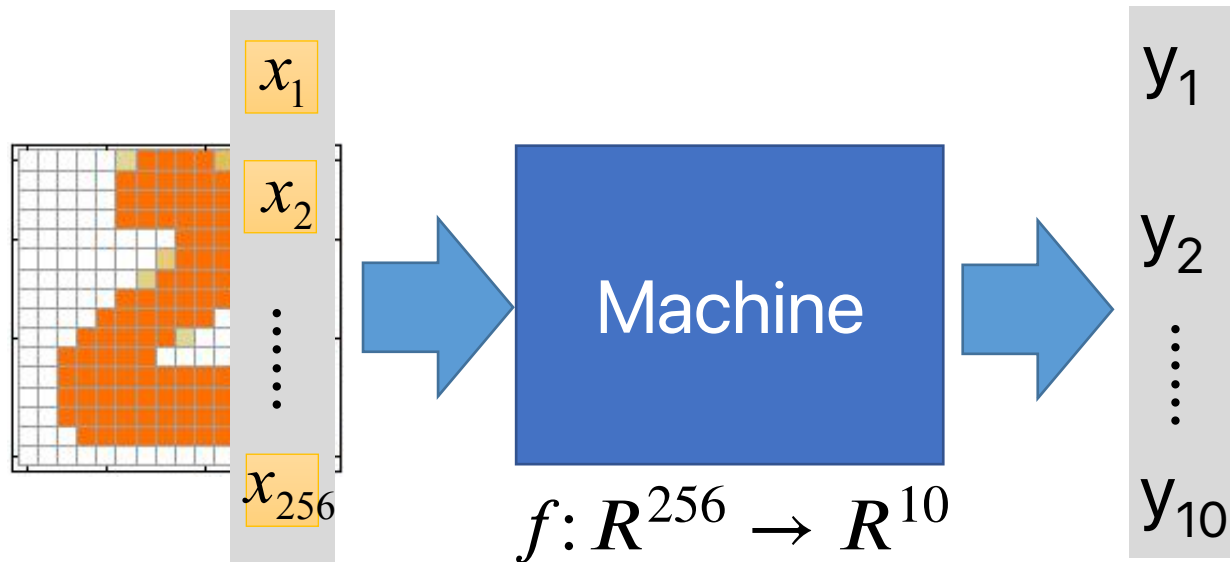
No ink \rightarrow 0



Each dimension represents the confidence of a digit.

Example Application

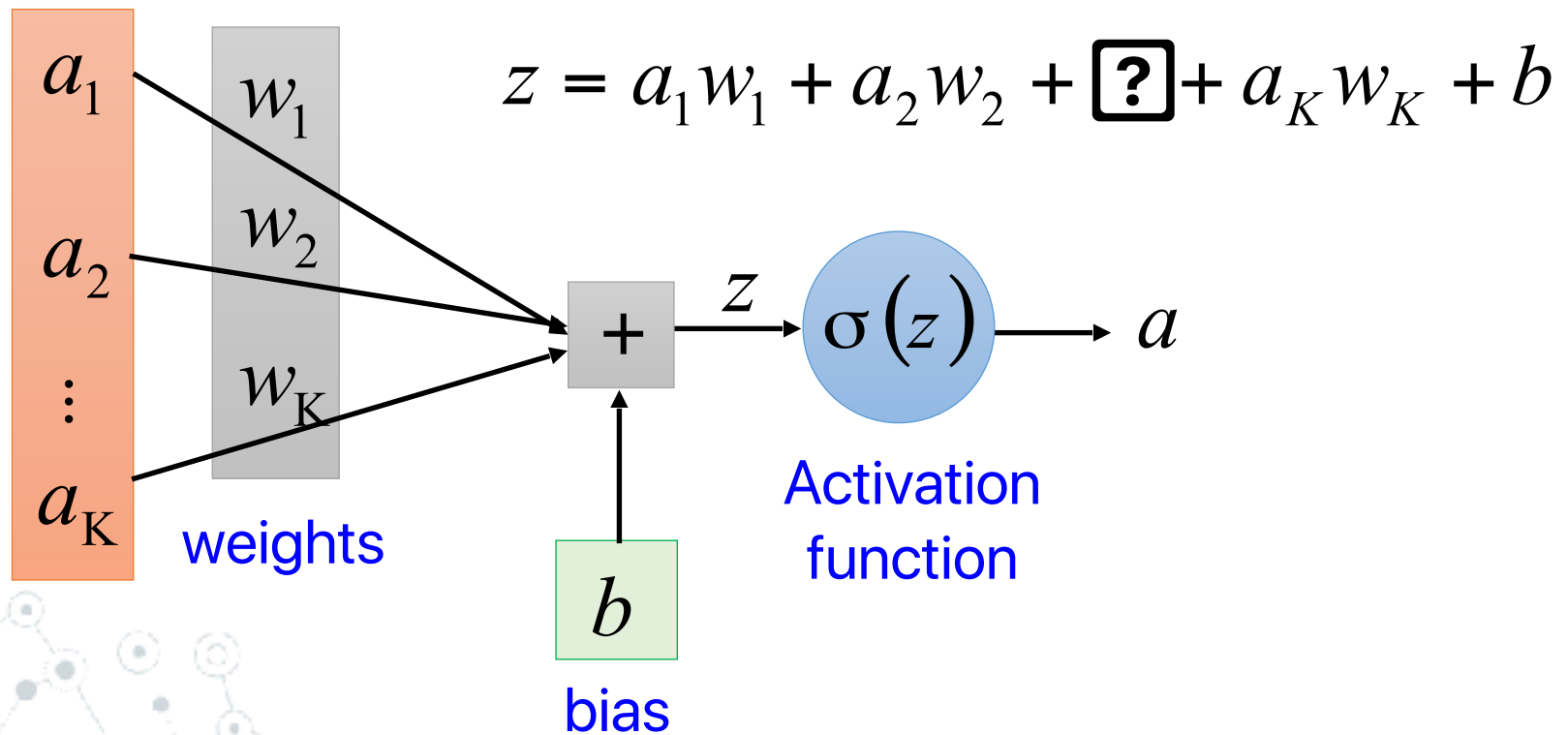
◎ Handwriting Digit Recognition



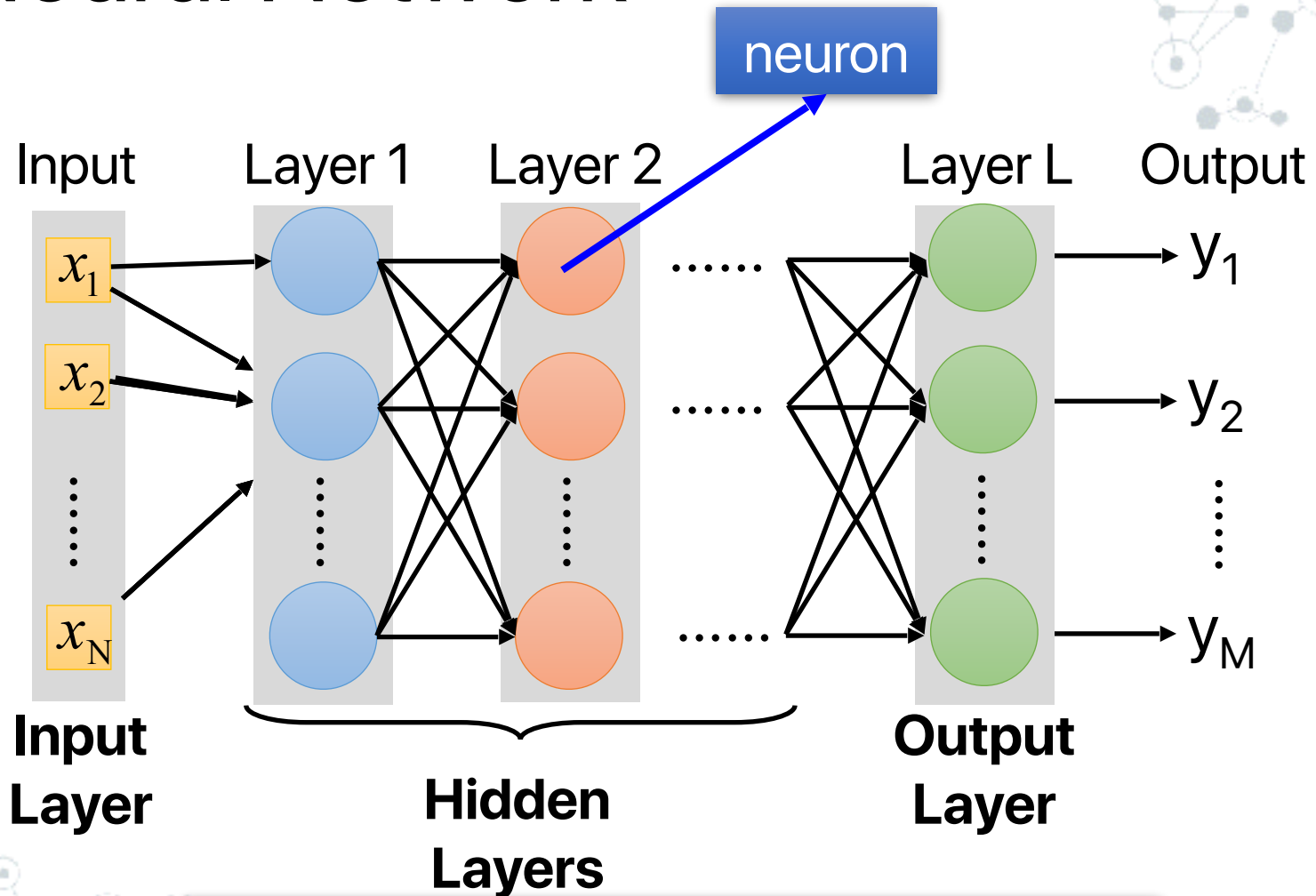
In deep learning, the function is represented by neural network

Element of Neural Network

Neuron $f: R^K \rightarrow R$

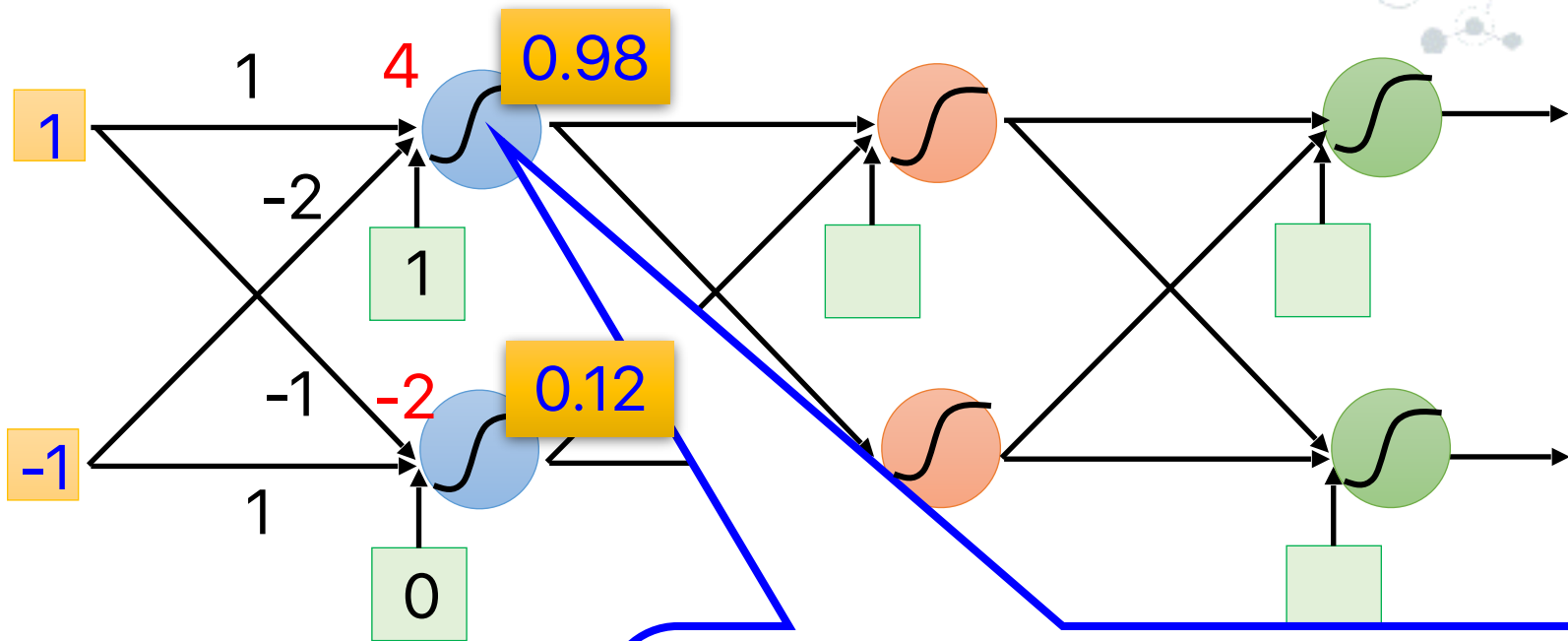


Neural Network



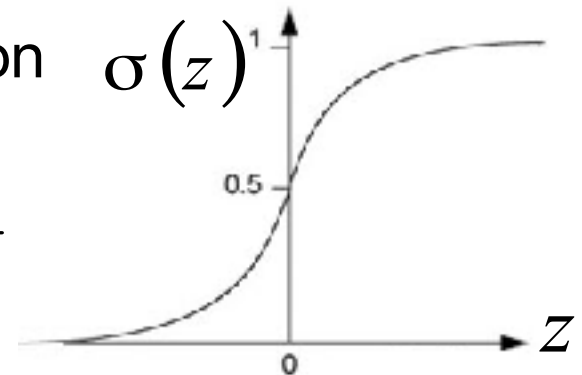
Deep means many hidden layers

Example of Neural Network

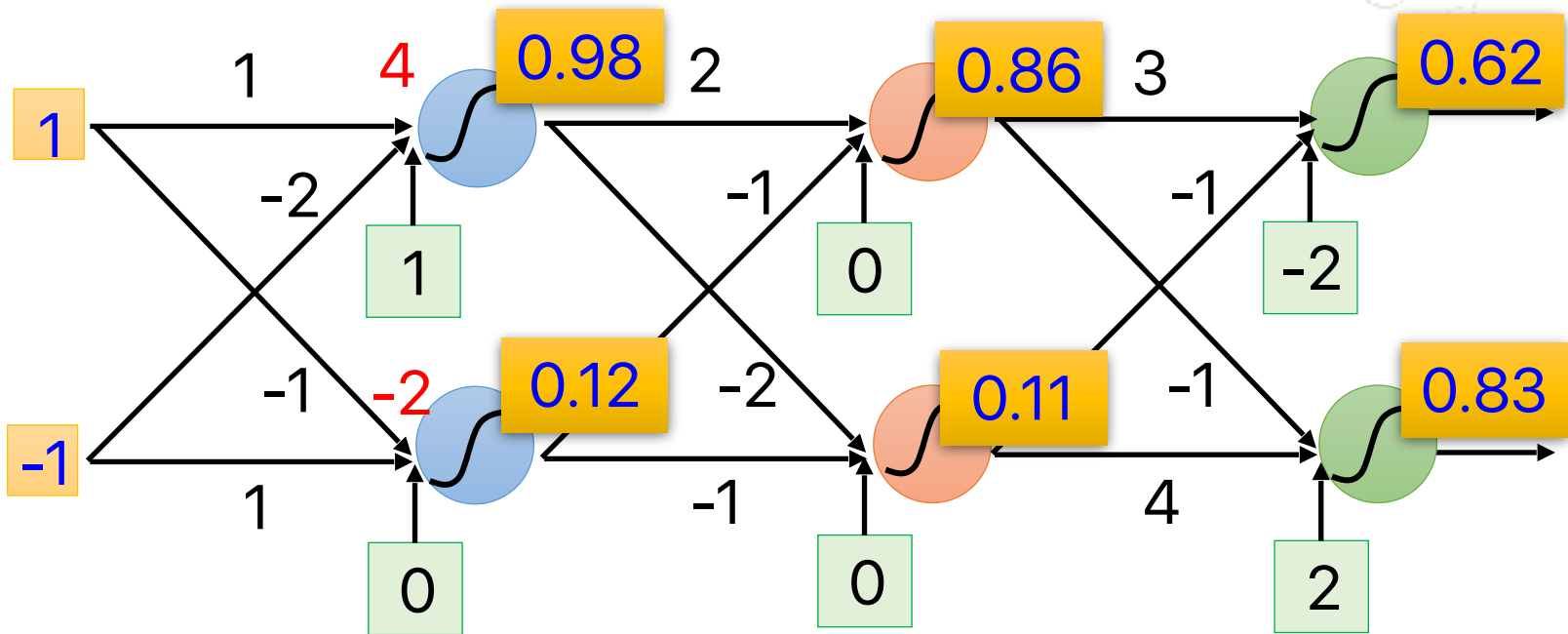


Sigmoid Function $\sigma(z)$

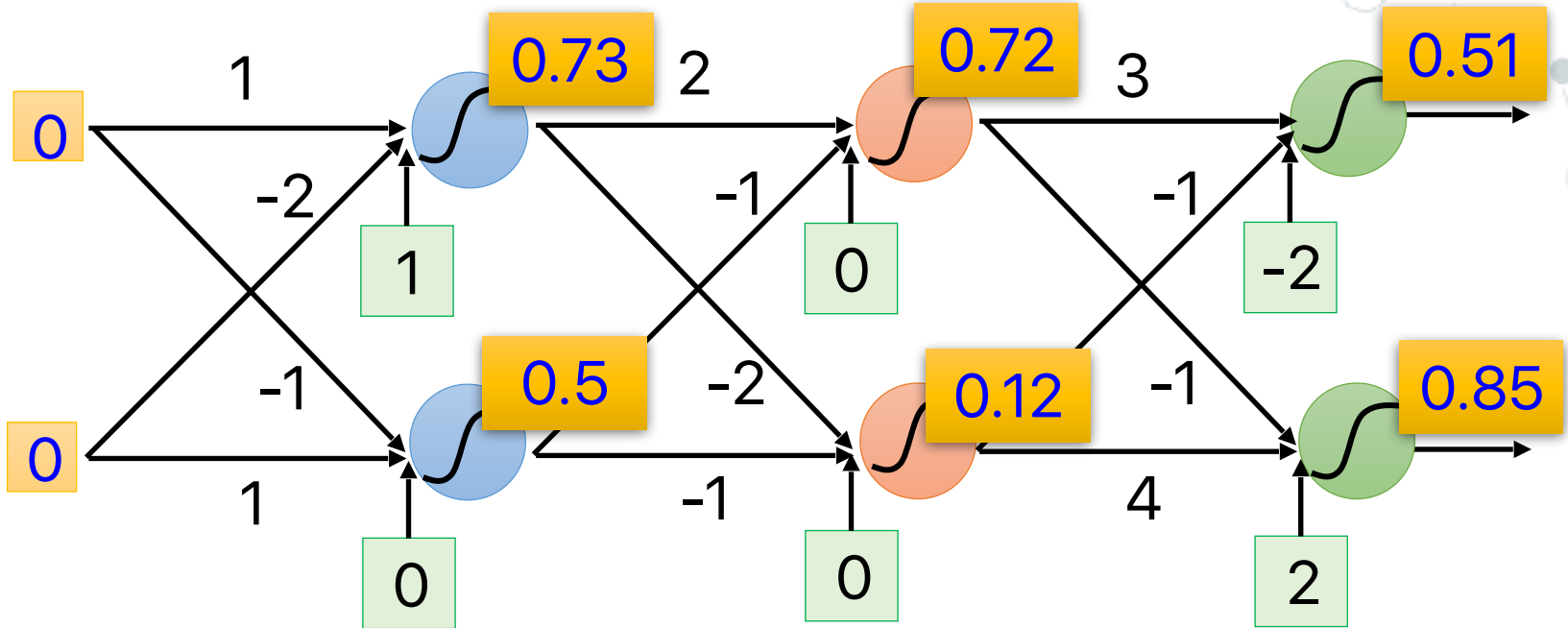
$$\sigma(z) = \frac{1}{1 + e^{-z}}$$



Example of Neural Network



Example of Neural Network

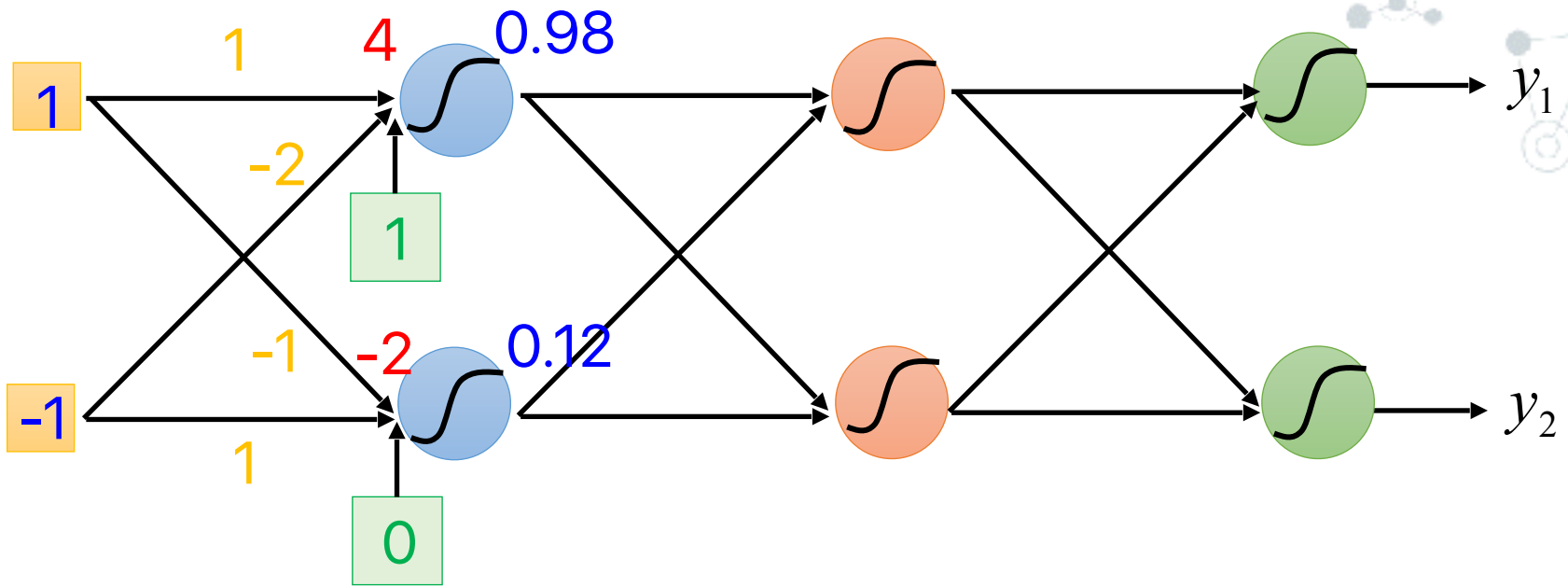


$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 0.62 \\ 0.83 \end{bmatrix} \quad f\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 0.51 \\ 0.85 \end{bmatrix}$$

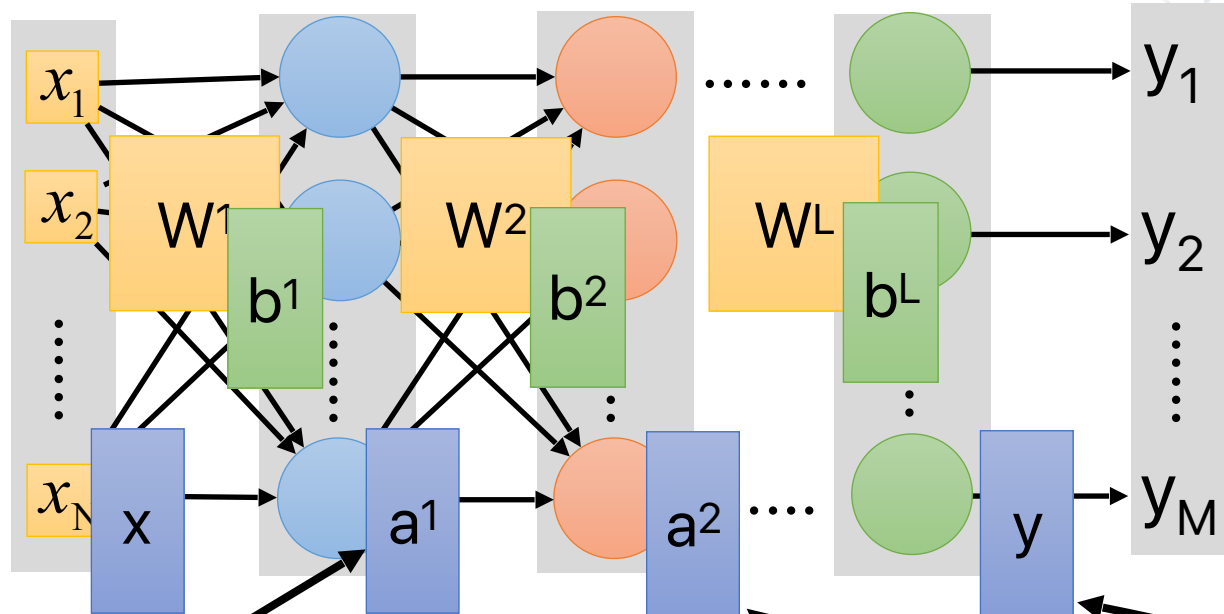
Different parameters define different function

Matrix Operation



$$\sigma\left(\underbrace{\begin{bmatrix} 1 & -2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{\begin{bmatrix} 4 \\ -2 \end{bmatrix}}\right) = \begin{bmatrix} 0.98 \\ 0.12 \end{bmatrix}$$

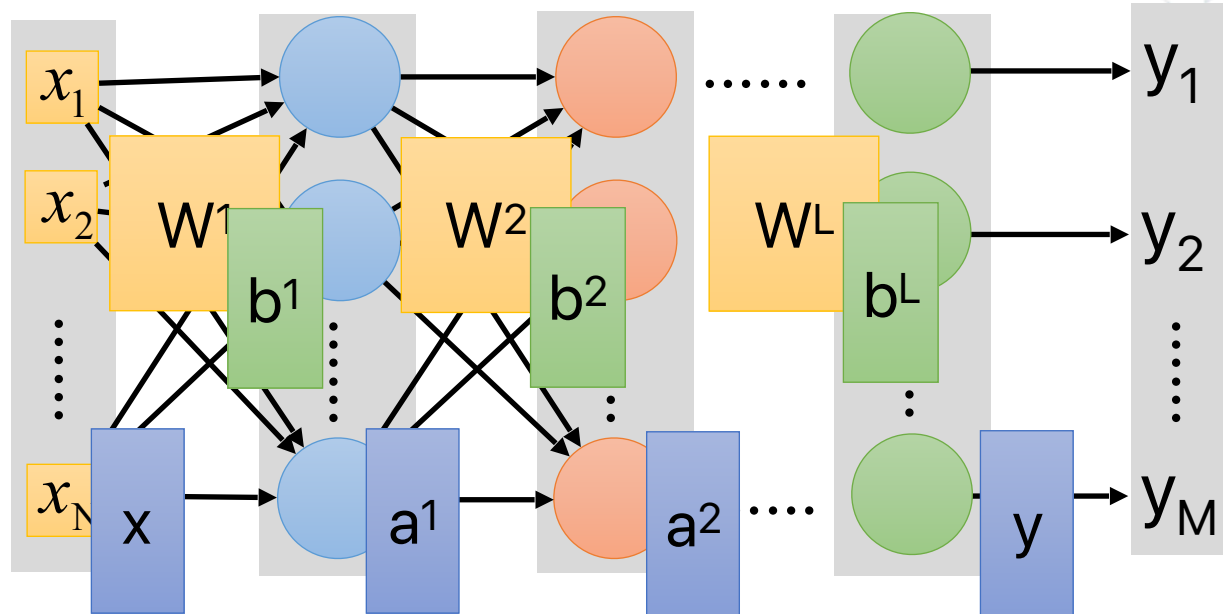
Neural Network



$$\sigma(W^1 x + b^1) \rightarrow \sigma(W^2 a^1 + b^2) \rightarrow \sigma(W^L a^{L-1} + b^L)$$

The diagram shows the mathematical representation of the forward pass for the first three layers. The activation function σ is applied to the weighted sum of inputs plus the bias for each layer. Arrows connect the corresponding nodes in the diagram above to the terms in the equations below.

Neural Network



$$y = f(x) \quad \text{Using parallel computing techniques to speed up matrix operation}$$

$$= \sigma(W^L \dots \sigma(W^2 \sigma(W^1 x + b^1) + b^2 \dots + b^L)$$

Softmax

◎ Softmax layer as the output layer

Ordinary Layer

$$z_1 \longrightarrow \sigma \longrightarrow y_1 = \sigma(z_1)$$

$$z_2 \longrightarrow \sigma \longrightarrow y_2 = \sigma(z_2)$$

$$z_3 \longrightarrow \sigma \longrightarrow y_3 = \sigma(z_3)$$

In general, the output of network can be any value.

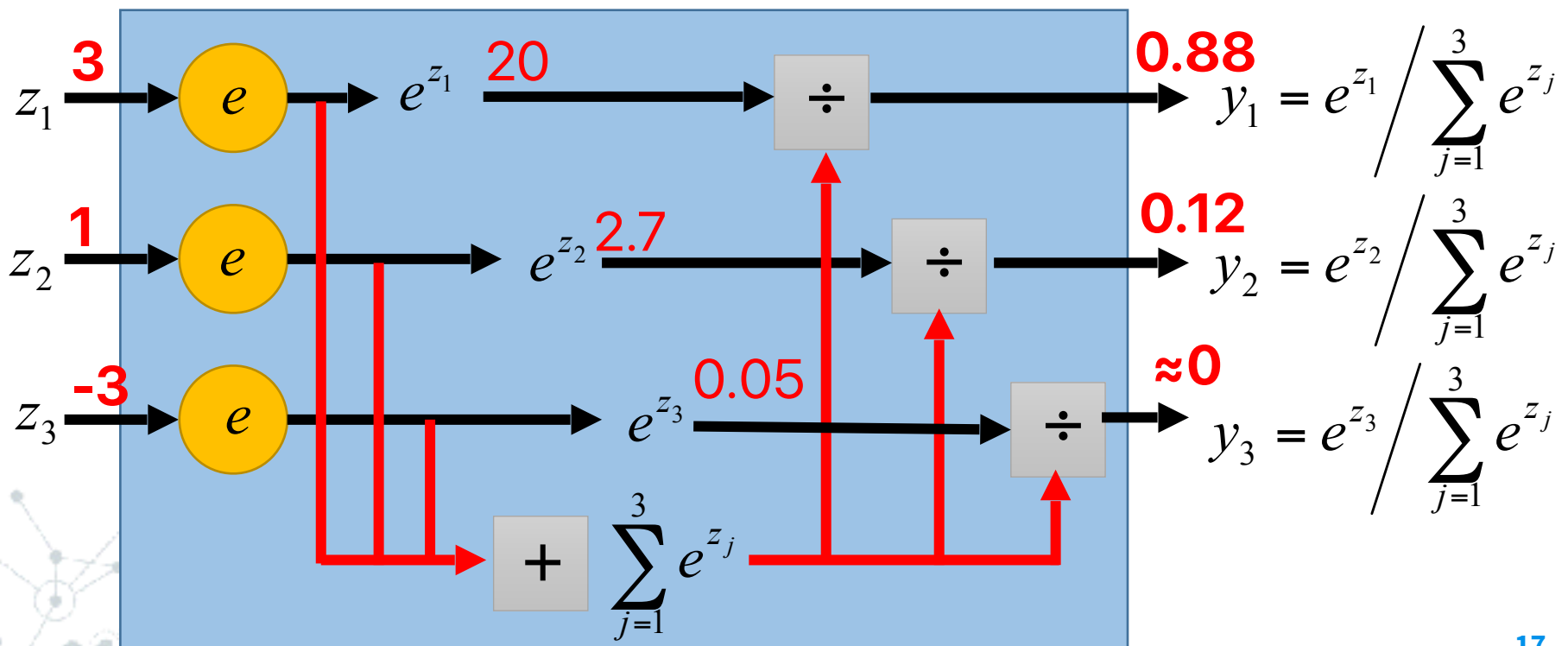
May not be easy to interpret

Softmax

Probability:

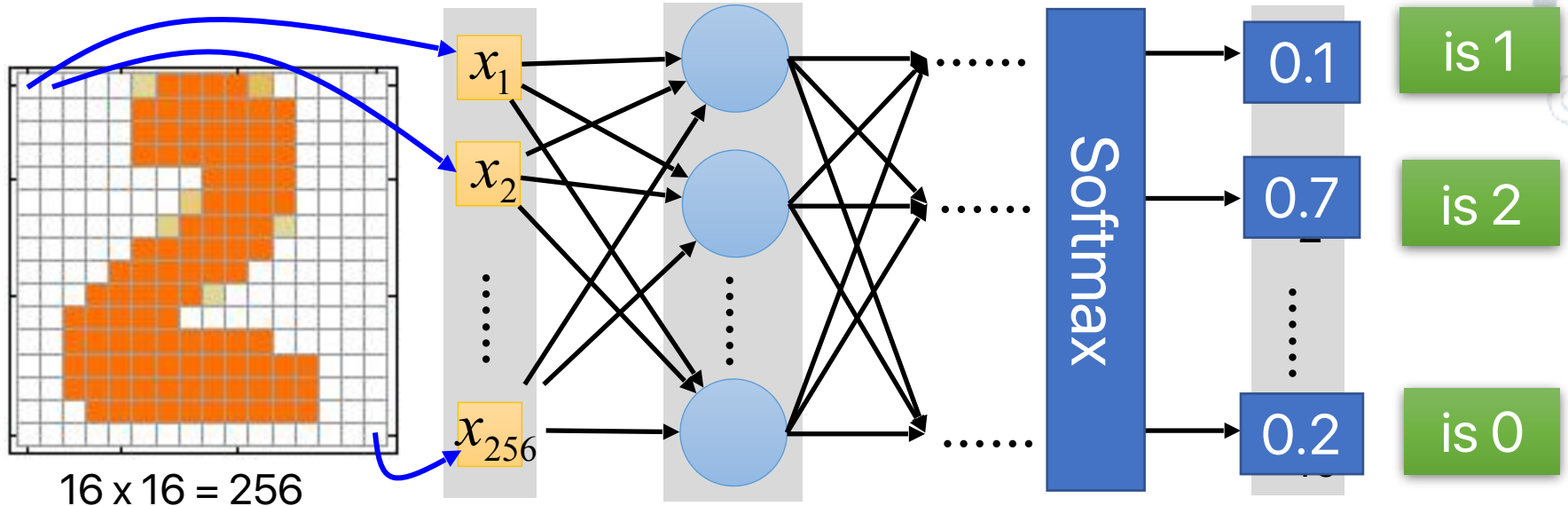
◎ Softmax layer as the output layer

Softmax Layer



How to set network parameters

$$\theta = \{W^1, b^1, W^2, b^2, \dots, W^L, b^L\}$$



Ink \rightarrow 1
No ink \rightarrow 0

Set the network parameters such that

Input

How to let the neural network achieve this

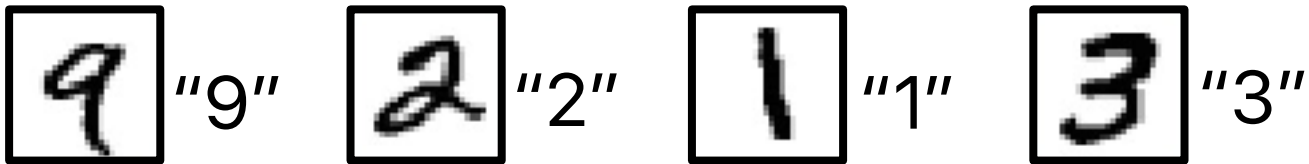
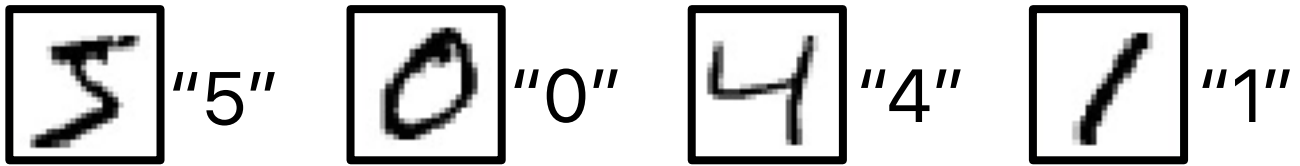
Input:



y_2 has the maximum value

Training Data

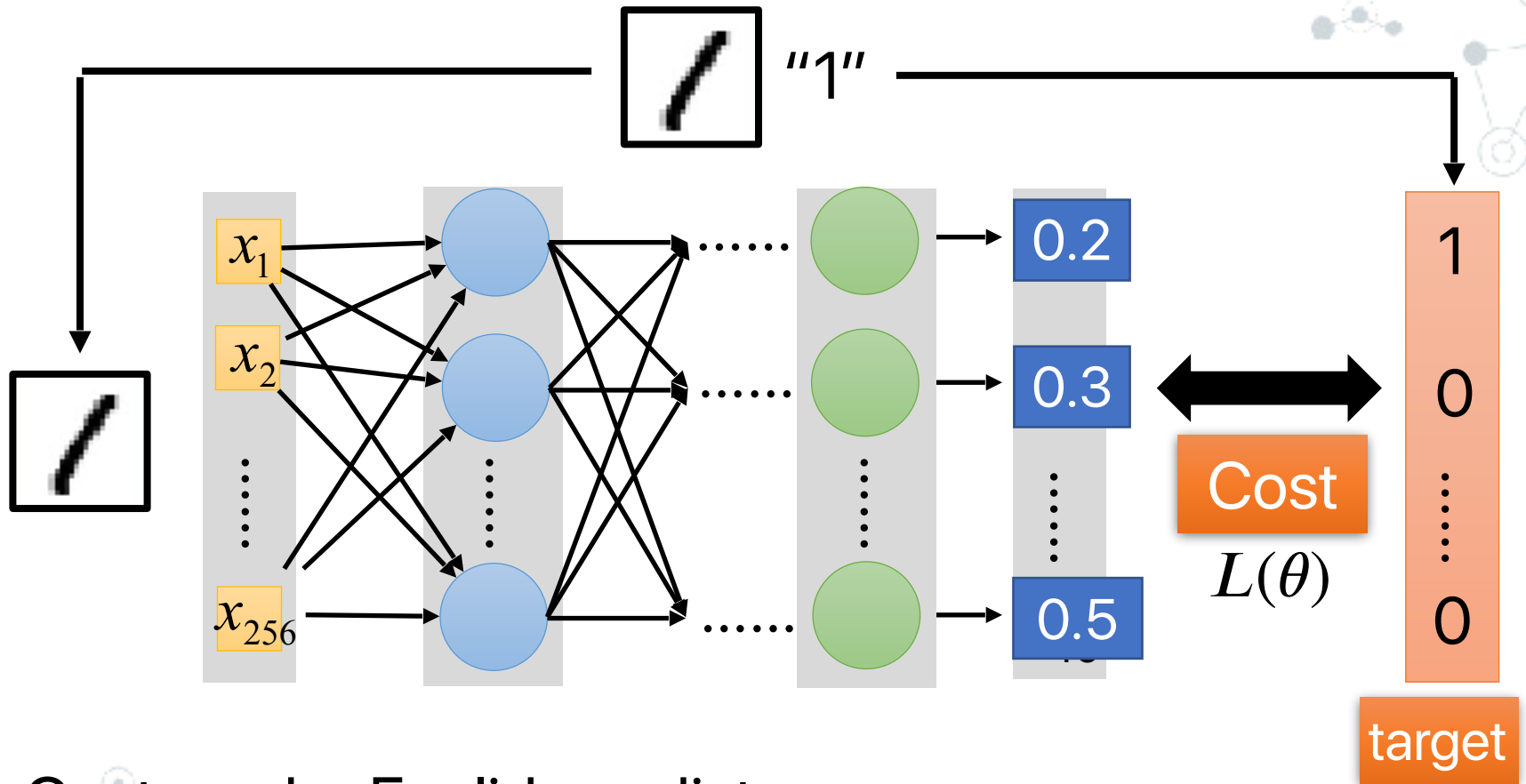
- © Preparing training data: images and their labels



Using the training data to find the network parameters.

Cost

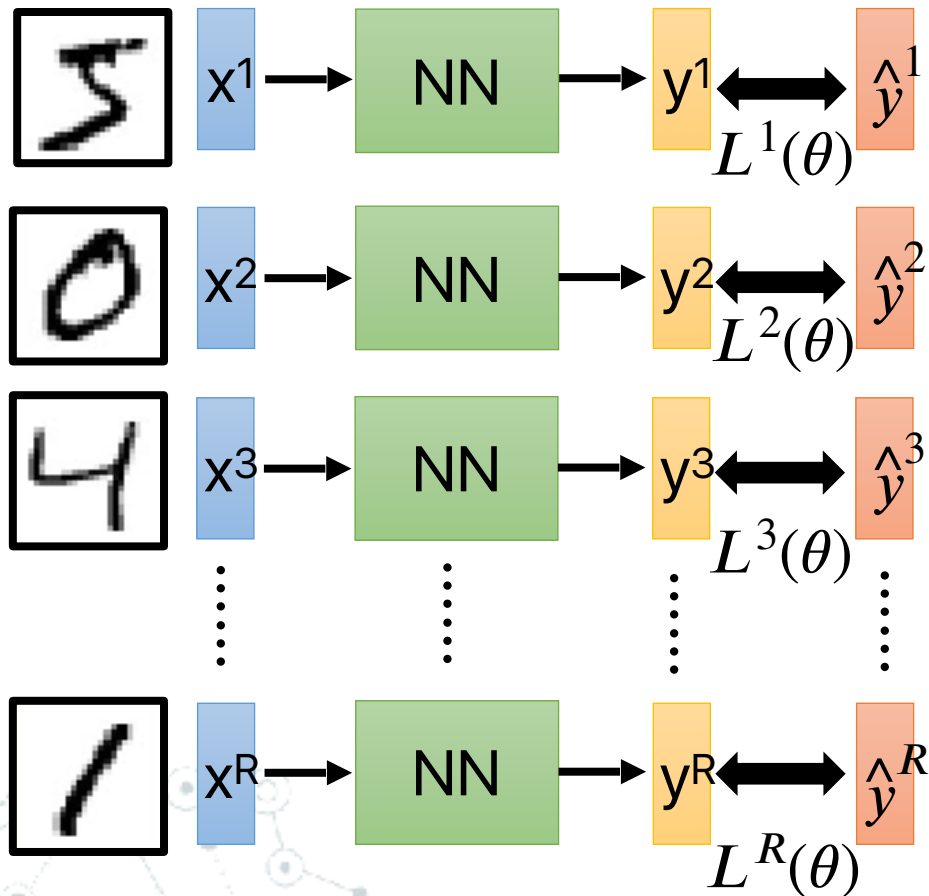
Given a set of network parameters, each example has a cost value.



Cost can be Euclidean distance or cross entropy of the network output and target

Total Cost

For all training data ...



Total Cost:

$$C(\theta) = \sum_{r=1}^R L^r(\theta)$$

How bad the network parameters is on this task

Find the network parameters that minimize this value

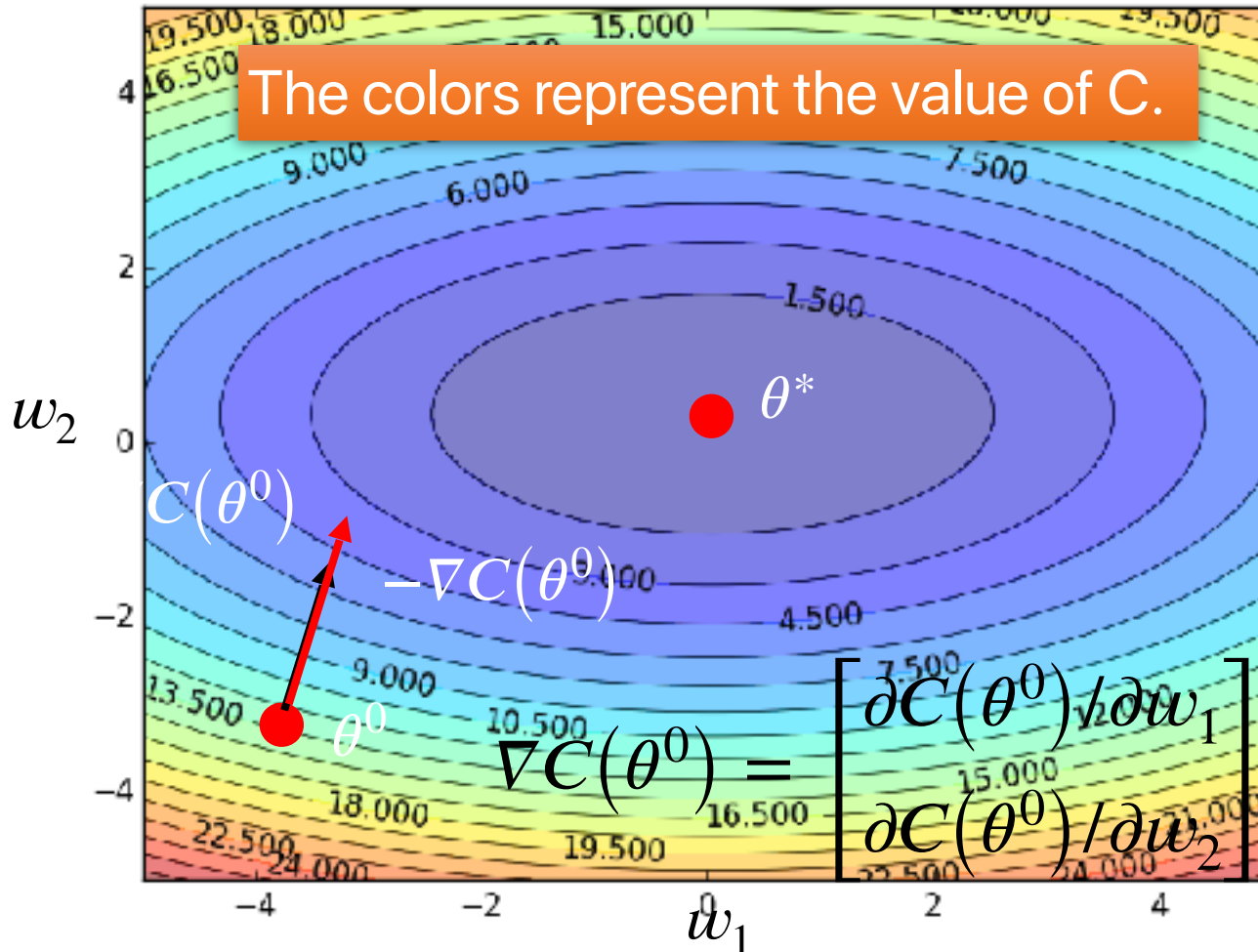
Gradient Descent

Assume there are only two parameters w_1 and w_2 in a network.

$$\theta = \{w_1, w_2\}$$

Error Surface

The colors represent the value of C .



Randomly pick a starting point

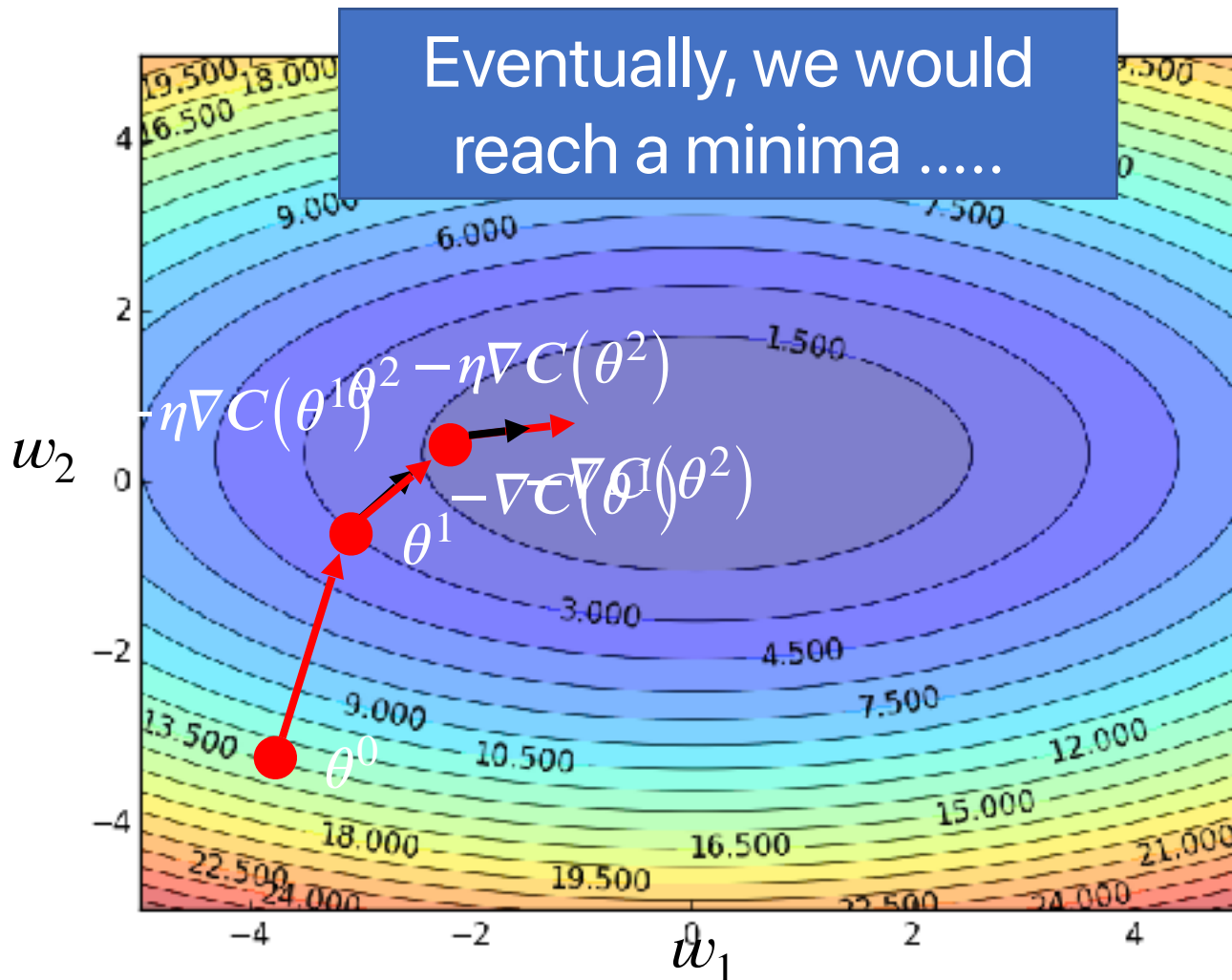
Compute the negative gradient at

→ $-\nabla C(\theta^0)$

Times the learning rate

→ $-\eta \nabla C(\theta^0)$

Gradient Descent



Randomly pick a starting point

Compute the negative gradient at

$\rightarrow -\nabla C(\theta^0)$

Times the learning rate

$\rightarrow -\eta \nabla C(\theta^0)$

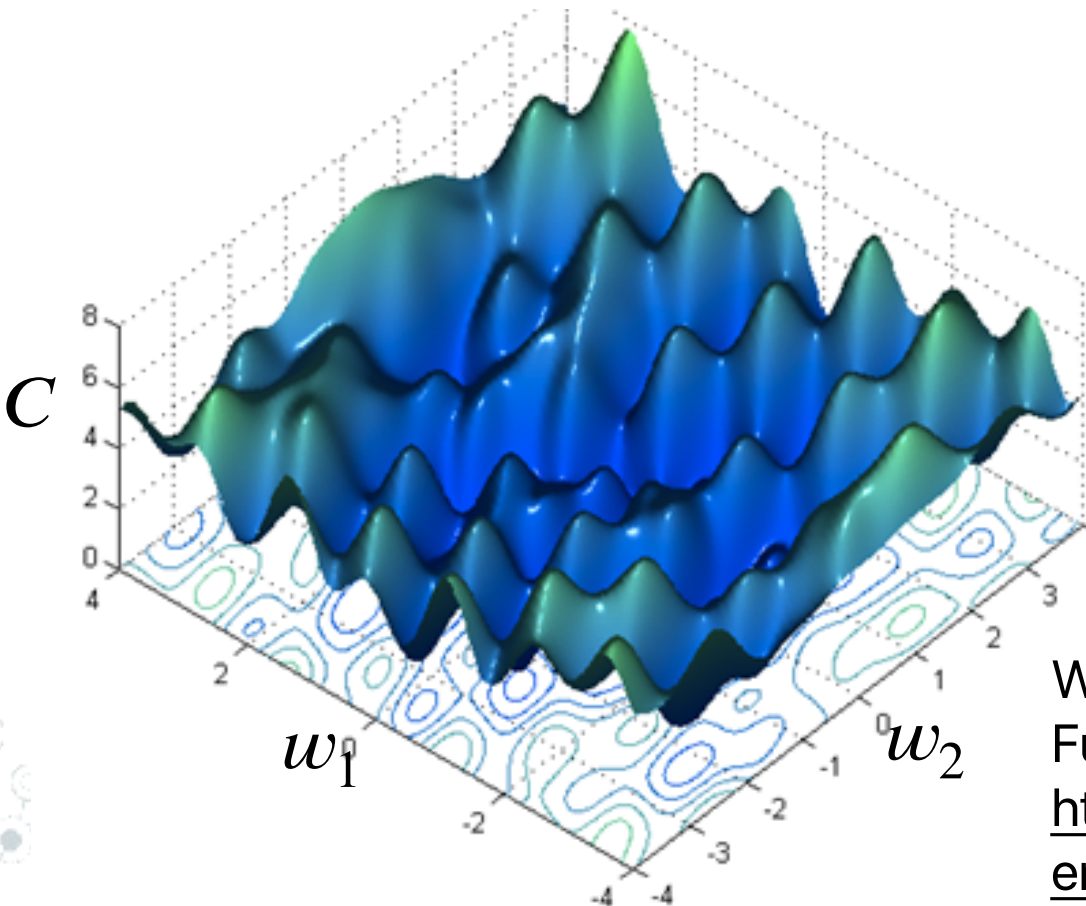
Local Minima

- ◎ Gradient descent never guarantee global

Different initial
point



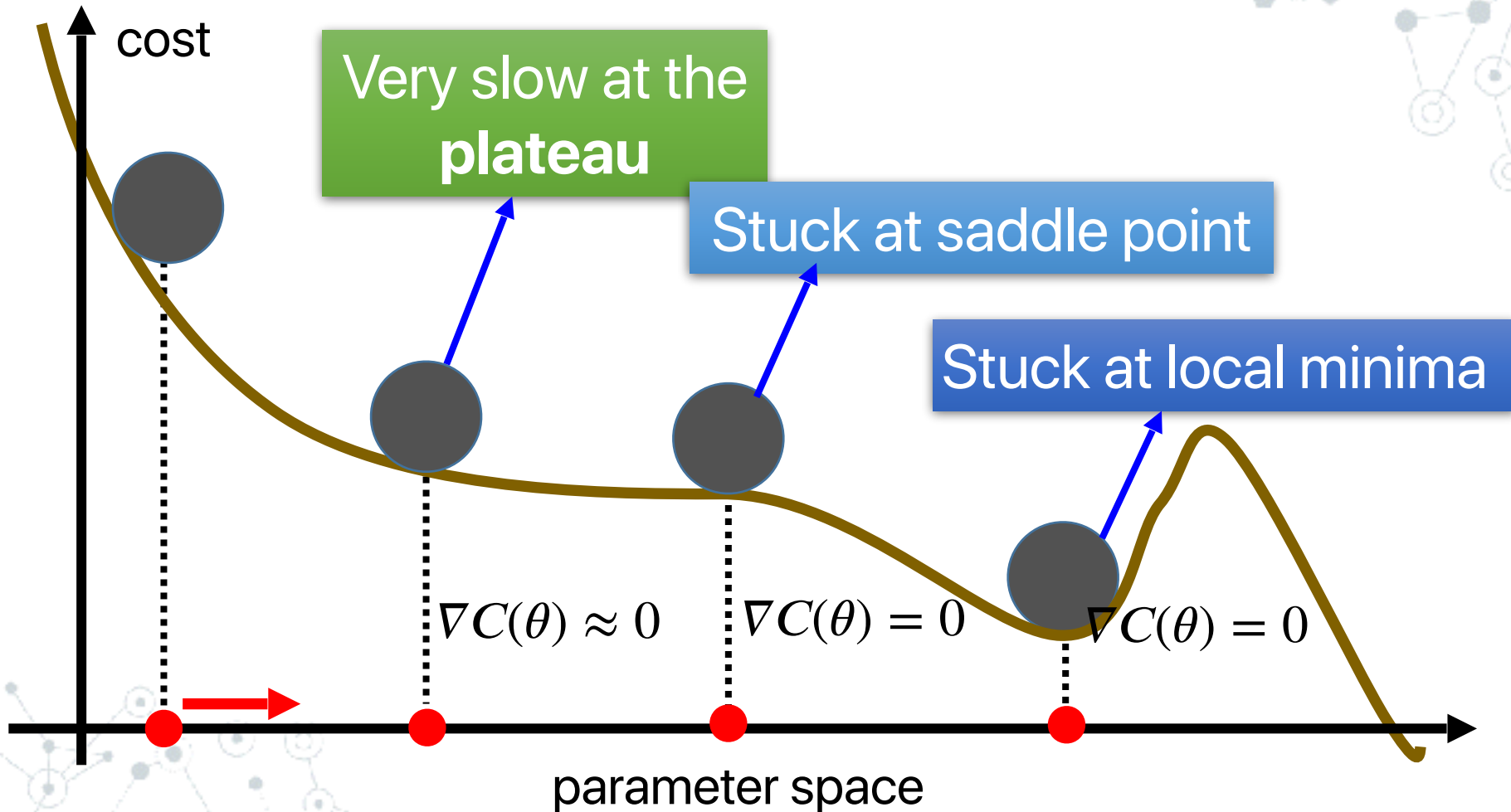
Reach different
minima, so different
results



Who is Afraid of Non-Convex Loss Functions?

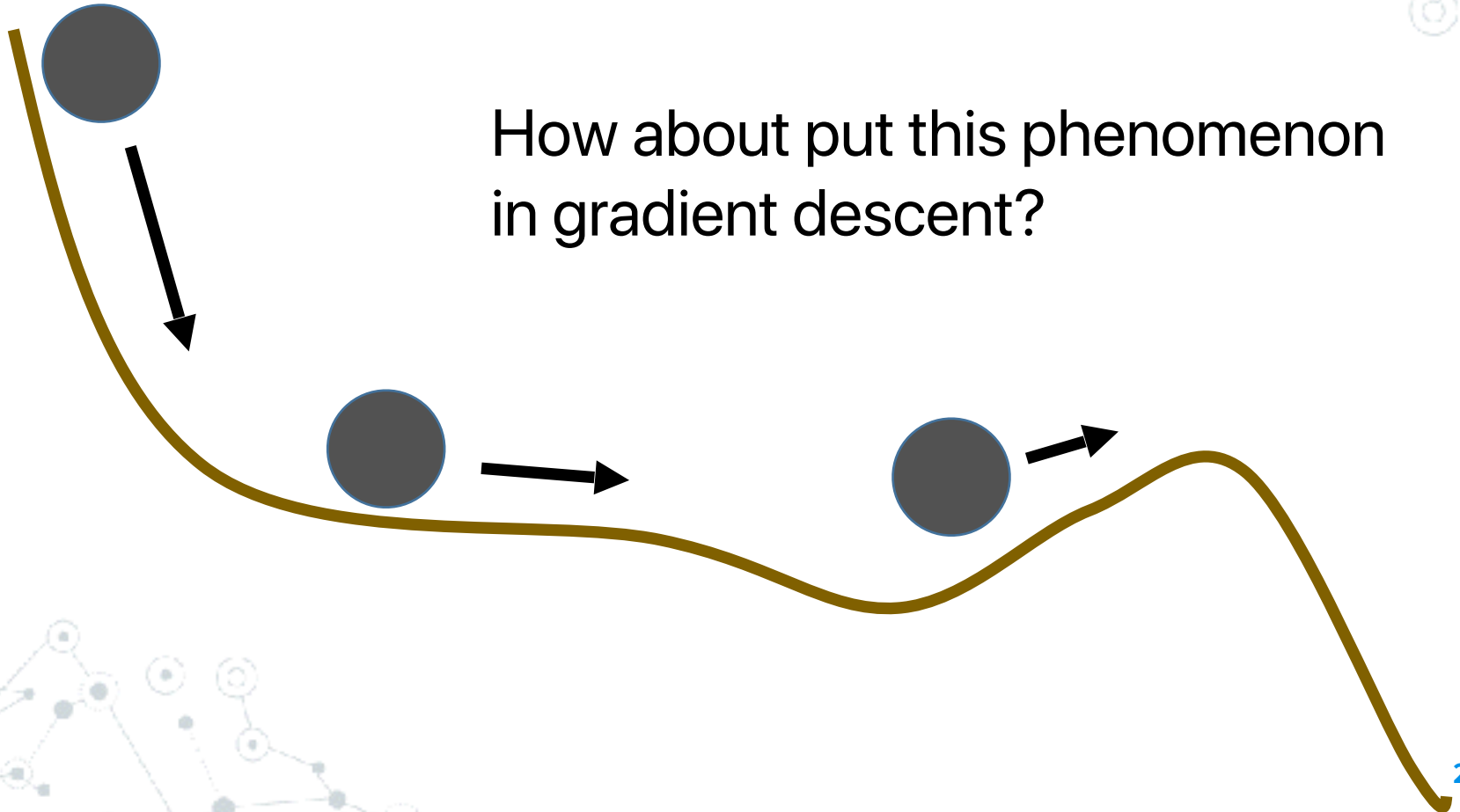
http://videolectures.net/eml07_lecun_wia/

Besides local minima



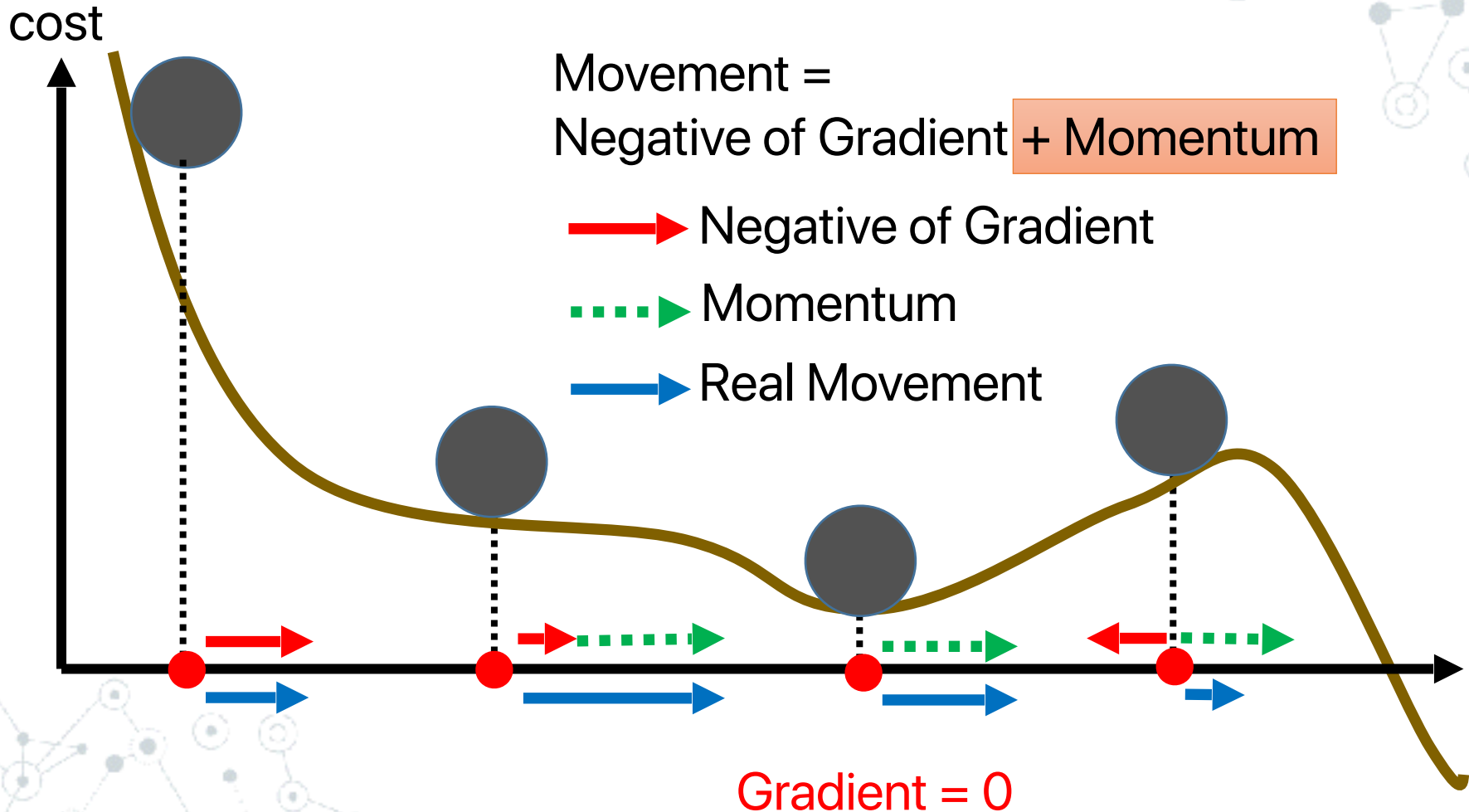
In physical world

◎ Momentum



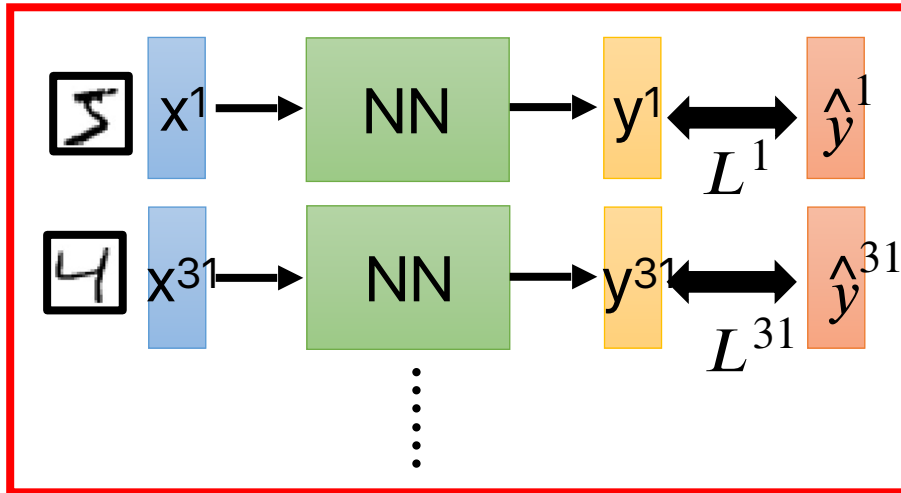
Momentum

Still not guarantee reaching global minima, but give some hope

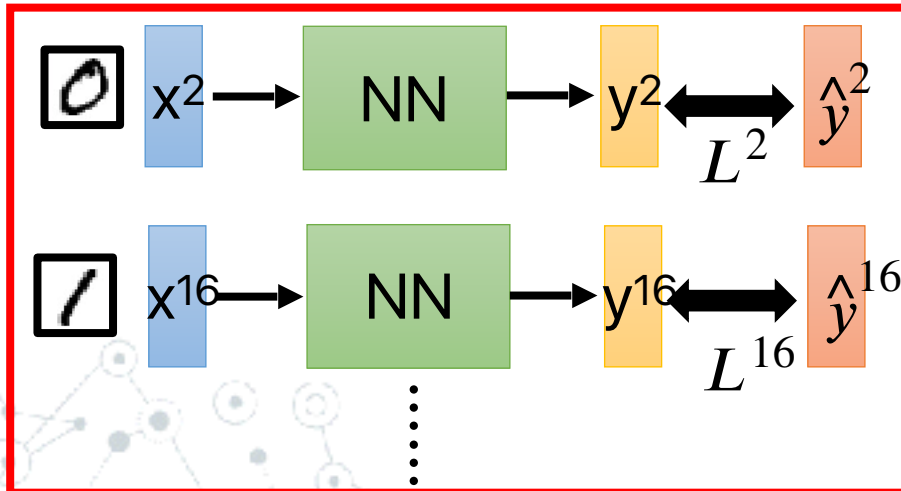


Mini-batch

Mini-batch



Mini-batch

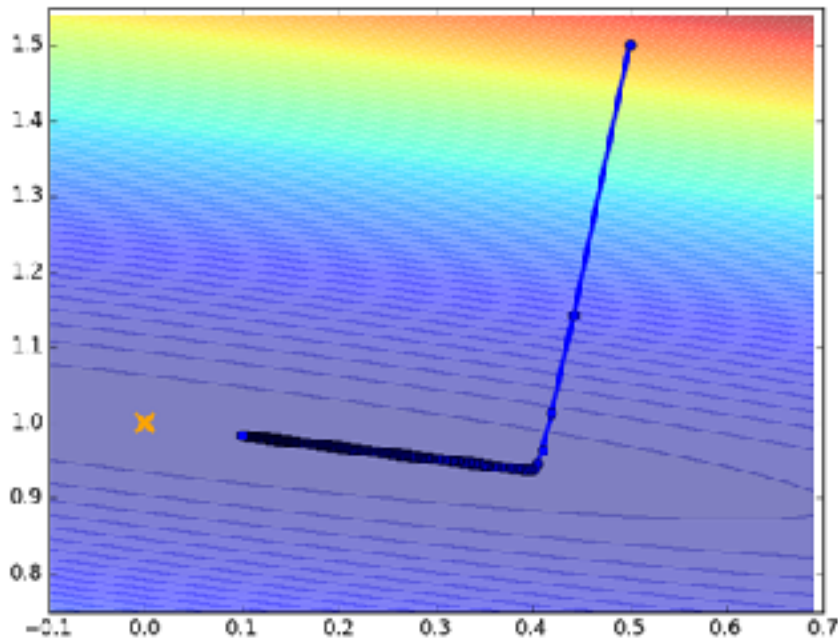


- Randomly initialize
- Pick the 1st batch
$$C = L^1 + L^{31} + \dots$$
$$\theta^1 \leftarrow \theta^0 - \eta \nabla C(\theta^0)$$
- Pick the 2nd batch
$$C = L^2 + L^{16} + \dots$$
$$\theta^2 \leftarrow \theta^1 - \eta \nabla C(\theta^1)$$
$$\vdots$$

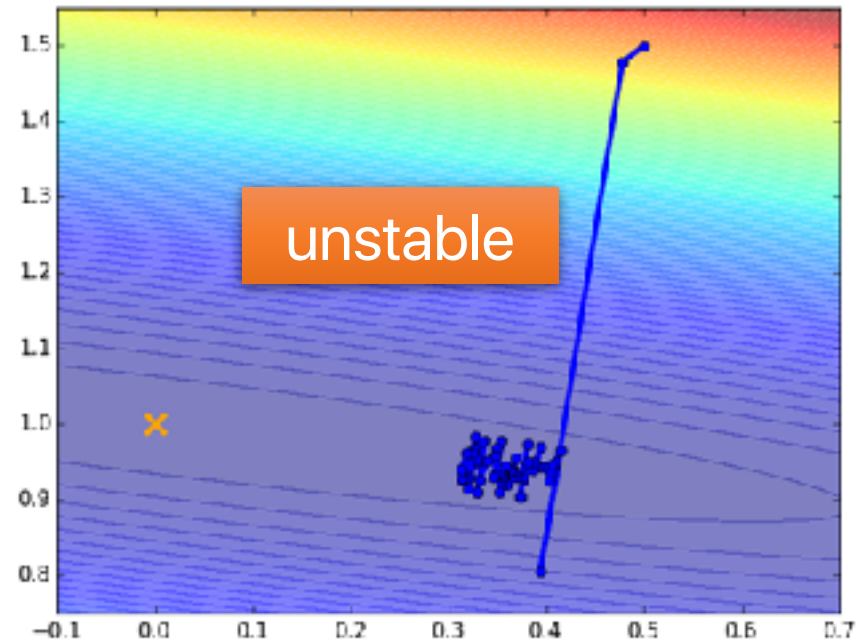
C is different each time when we update parameters!

Mini-batch

Original Gradient Descent



With Mini-batch



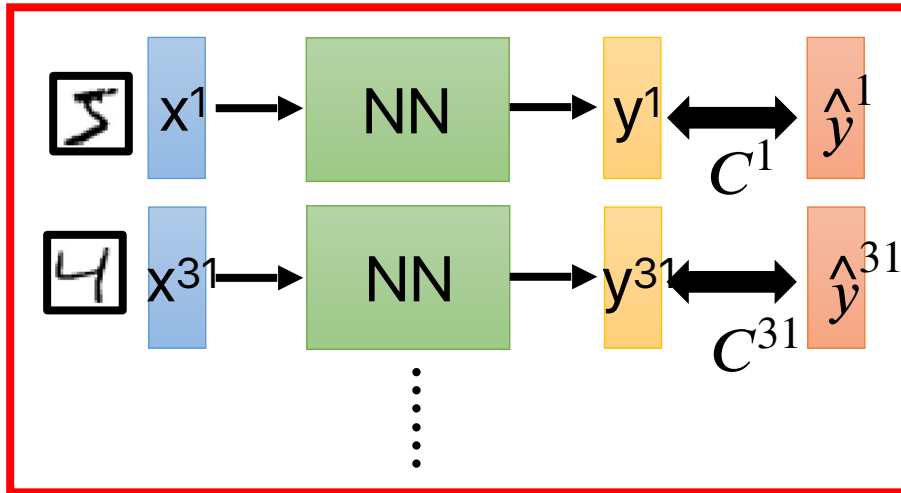
The colors represent the total C on all training data.

Mini-batch

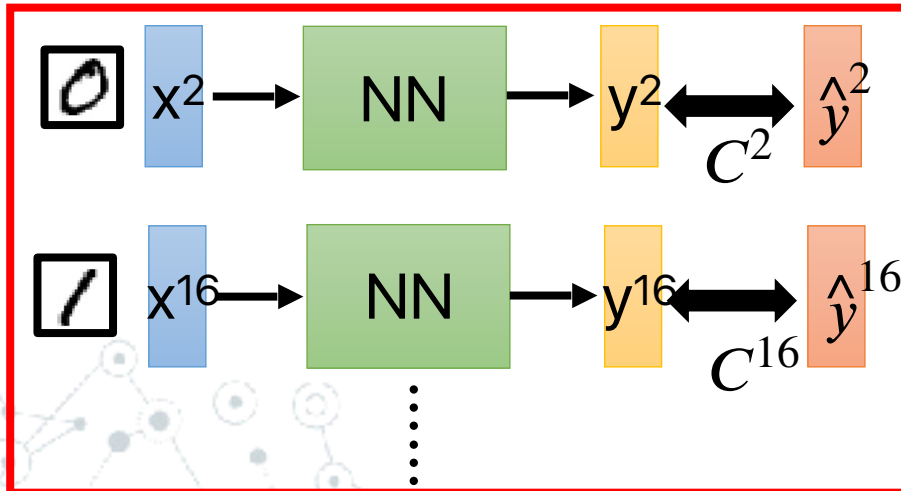
Faster

Better!

Mini-batch



Mini-batch



➤ Randomly initialize

➤ Pick the 1st batch

$$C = C^1 + C^{31} + \dots$$

$$\theta^1 \leftarrow \theta^0 - \eta \nabla C(\theta^0)$$

➤ Pick the 2nd batch

$$C = C^2 + C^{16} + \dots$$

$$\theta^2 \leftarrow \theta^1 - \eta \nabla C(\theta^1)$$

⋮

➤ Until all mini-batches have been picked

one epoch

Repeat the above process

Backpropagation

- ◎ A network can have millions of parameters.
 - Backpropagation is the way to compute the gradients efficiently (not today)
 - Ref: http://speech.ee.ntu.edu.tw/~tlkagk/courses/MLDS_2015_2/Lecture/DNN%20backprop.ecm.mp4/index.html
- ◎ Many toolkits can compute the gradients automatically

theano



Ref: http://speech.ee.ntu.edu.tw/~tlkagk/courses/MLDS_2015_2/Lecture/Theano%20DNN.ecm.mp4/index.html



Part II: **Why Deep?**

Deeper is Better?

Layer X Size	Word Error Rate (%)
1 X 2k	24.2
2 X 2k	20.4
3 X 2k	18.4
4 X 2k	17.8
5 X 2k	17.2
7 X 2k	17.1

Not surprised, more parameters,
better performance

Seide, Frank, Gang Li, and Dong Yu. "Conversational Speech Transcription Using Context-Dependent Deep Neural Networks." *Interspeech*. 2011.

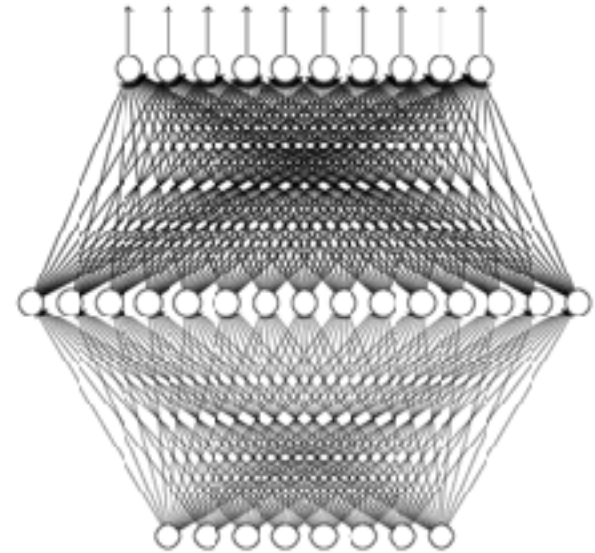
Universality Theorem

Any continuous function f

$$f : R^N \rightarrow R^M$$

Can be realized by a network
with one hidden layer

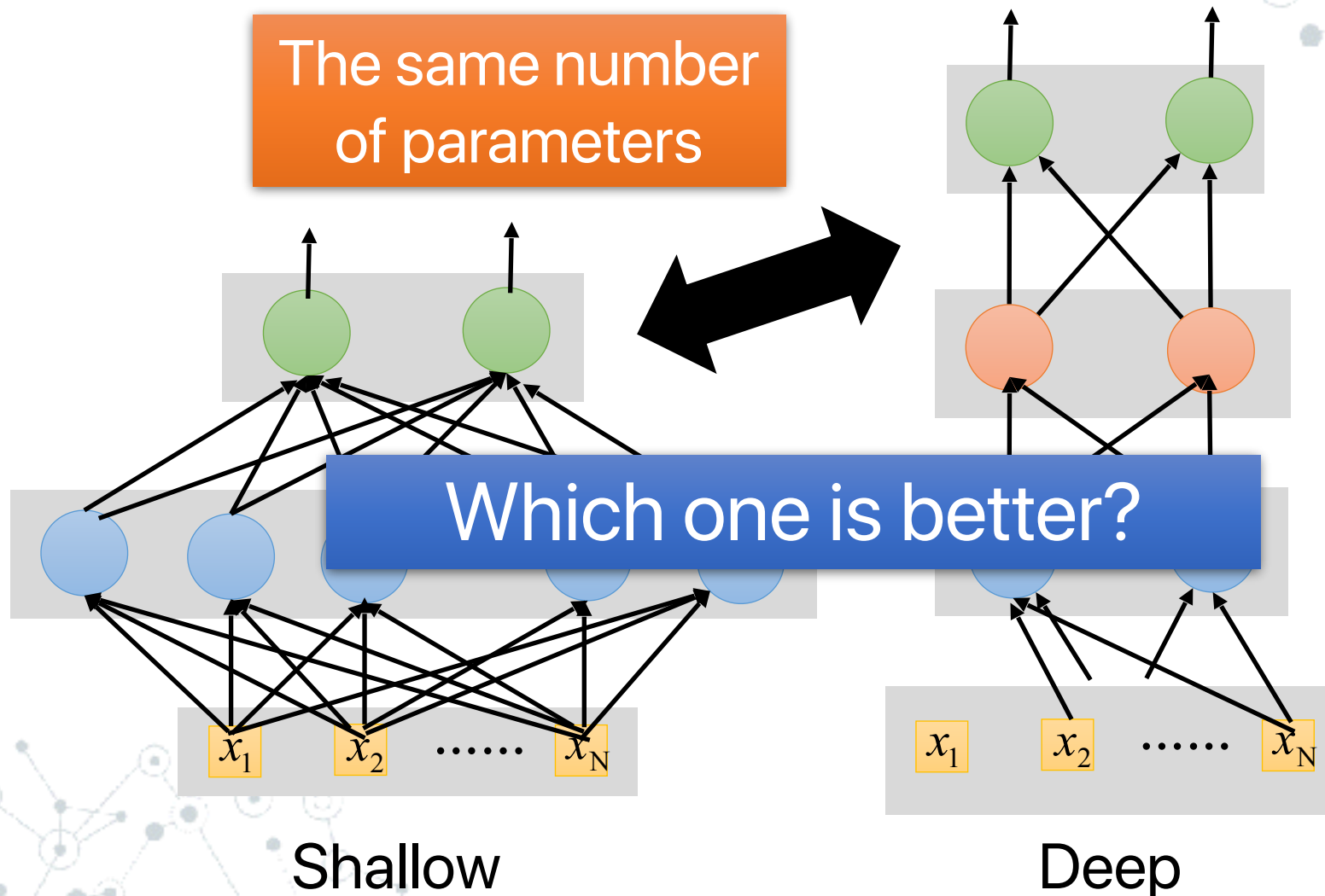
(given **enough** hidden
neurons)



Reference for the reason: <http://neuralnetworksanddeeplearning.com/chap4.html>

Why "Deep" neural network not "Fat" neural network?

Fat + Short v.s. Thin + Tall



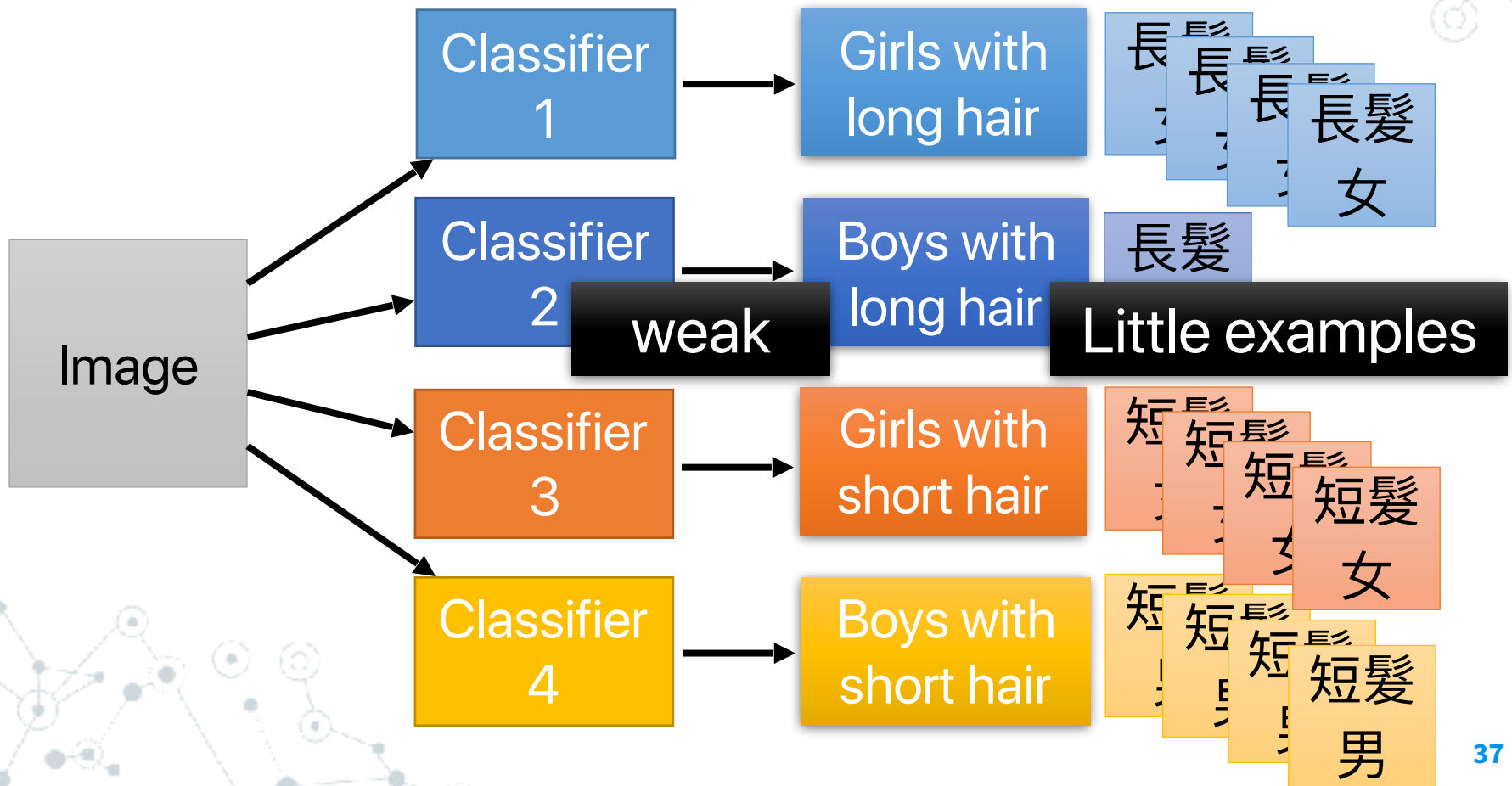
Fat + Short v.s. Thin + Tall

Layer X Size	Word Error Rate (%)	Layer X Size	Word Error Rate (%)
1 X 2k	24.2		
2 X 2k	20.4		
3 X 2k	18.4		
4 X 2k	17.8		
5 X 2k	17.2	1 X 3772	22.5
7 X 2k	17.1	1 X 4634	22.6
		1 X 16k	22.1

Seide, Frank, Gang Li, and Dong Yu. "Conversational Speech Transcription Using Context-Dependent Deep Neural Networks." *Interspeech*. 2011.

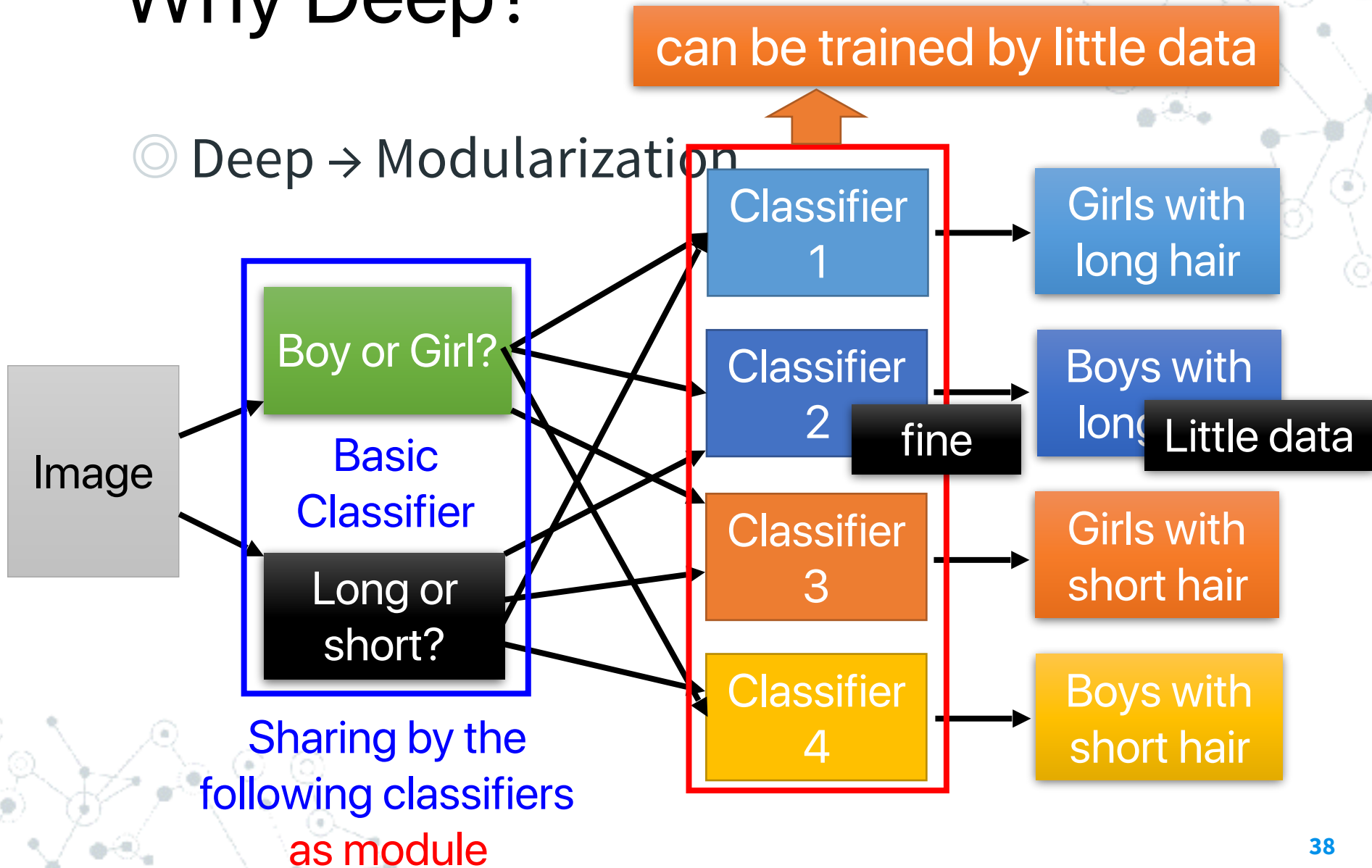
Why Deep?

◎ Deep → Modularization



Why Deep?

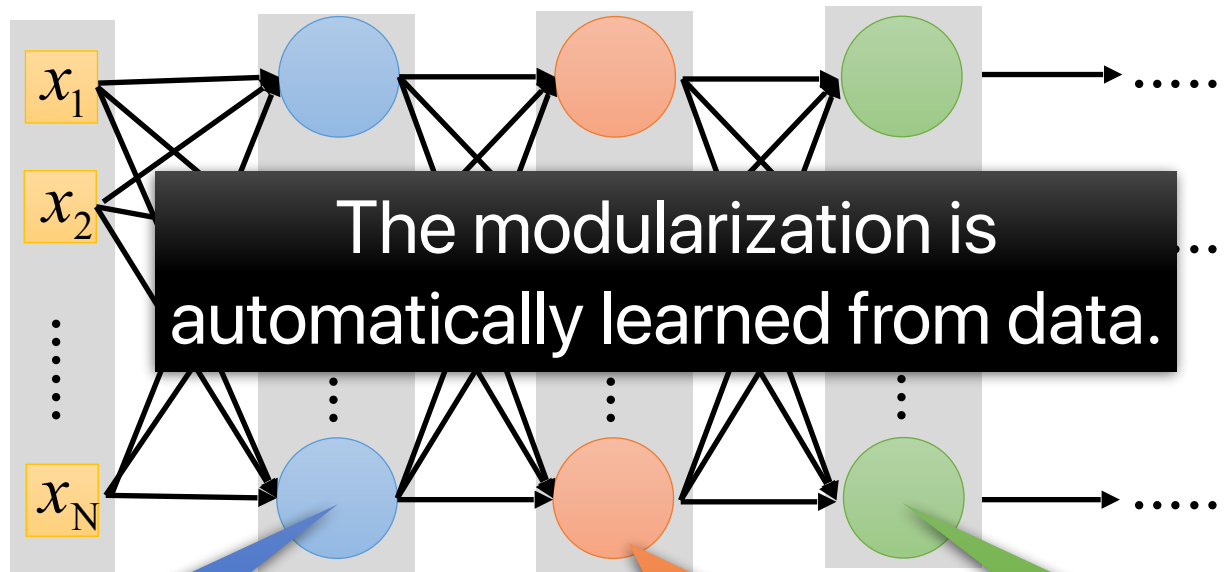
◎ Deep → Modularization



Why Deep?

Deep Learning also works on small data set like TIMIT.

◎ Deep → Modularization → Less training data?



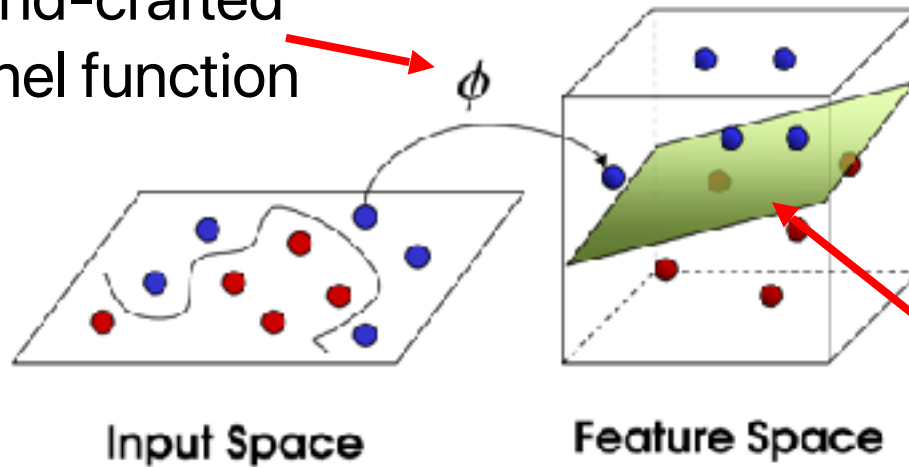
The most basic classifiers

Use 1st layer as module to build classifiers

Use 2nd layer as module

SVM

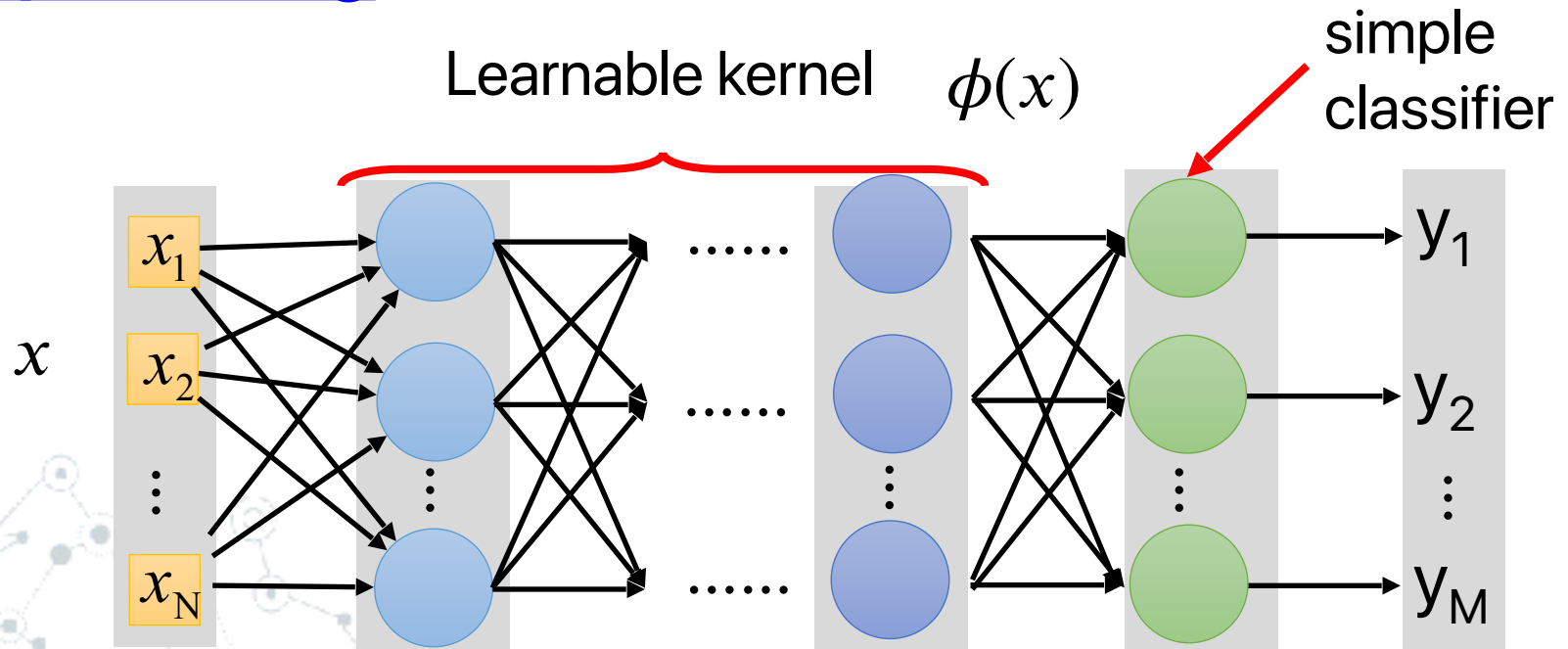
Hand-crafted
kernel function



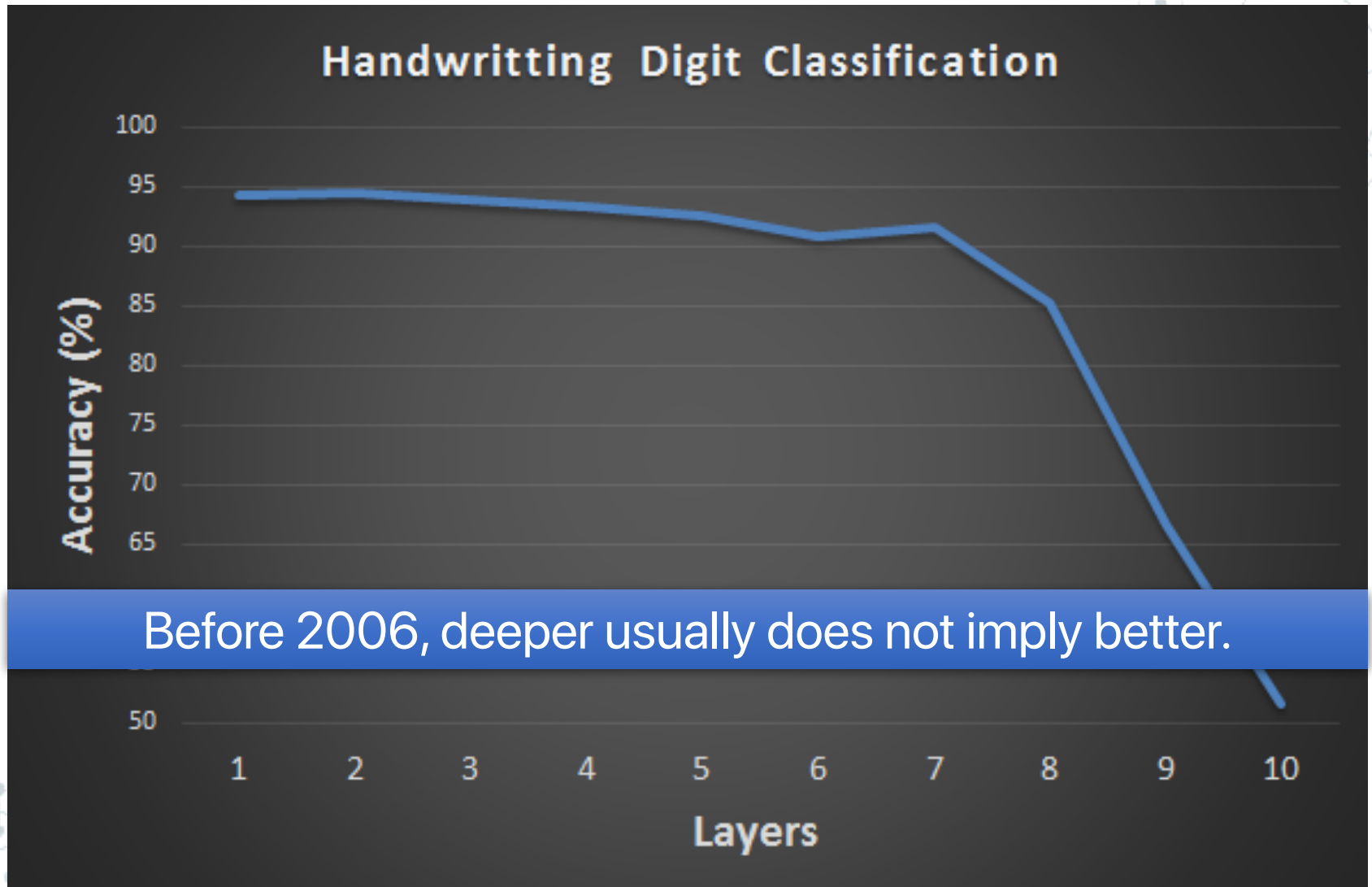
Apply simple
classifier

Source of image: http://www.gipsa-lab.grenoble-inp.fr/transfert/seminaire/455_Kadri2013Gipsa-lab.pdf

Deep Learning



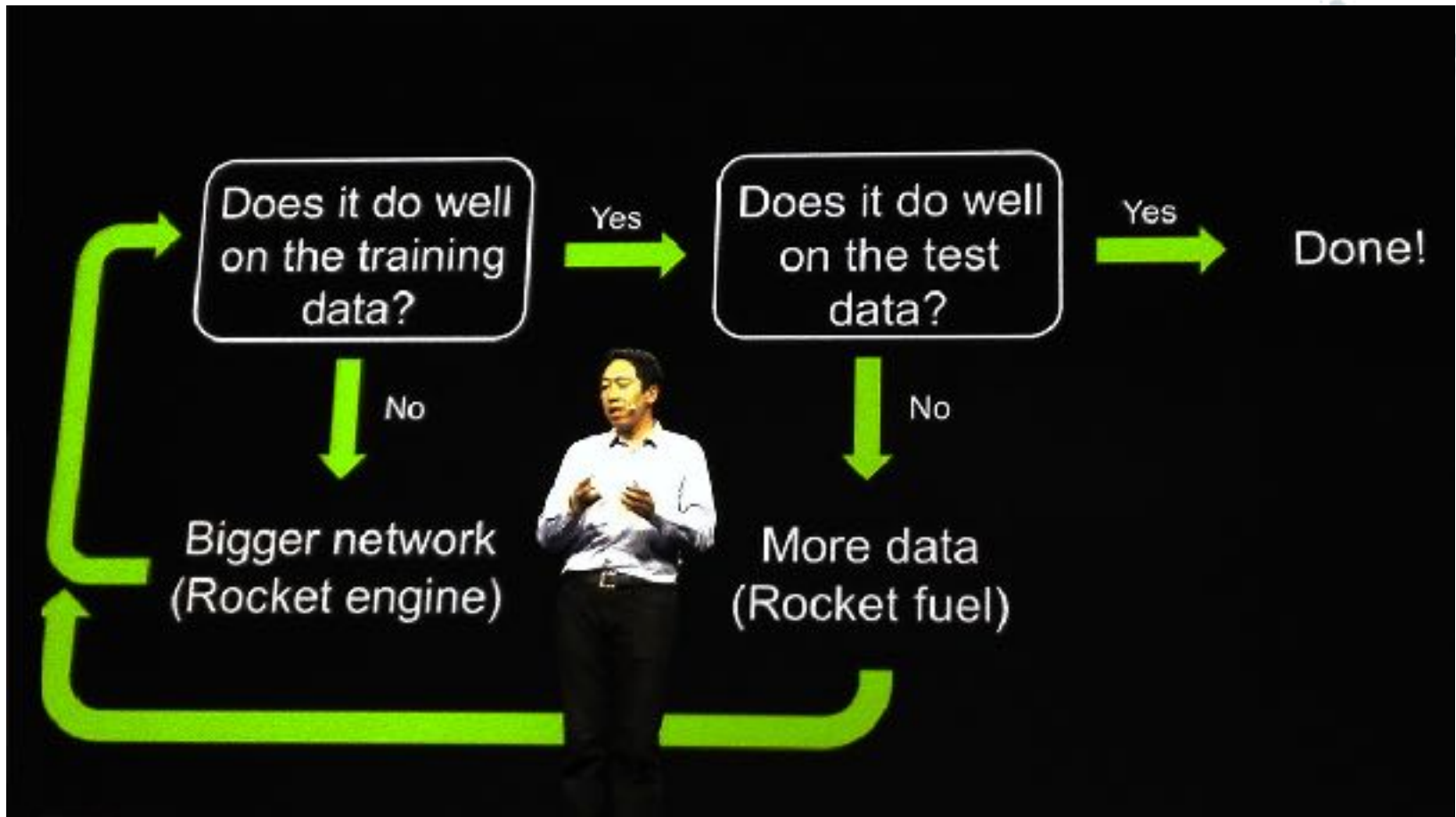
Hard to get the power of Deep ...





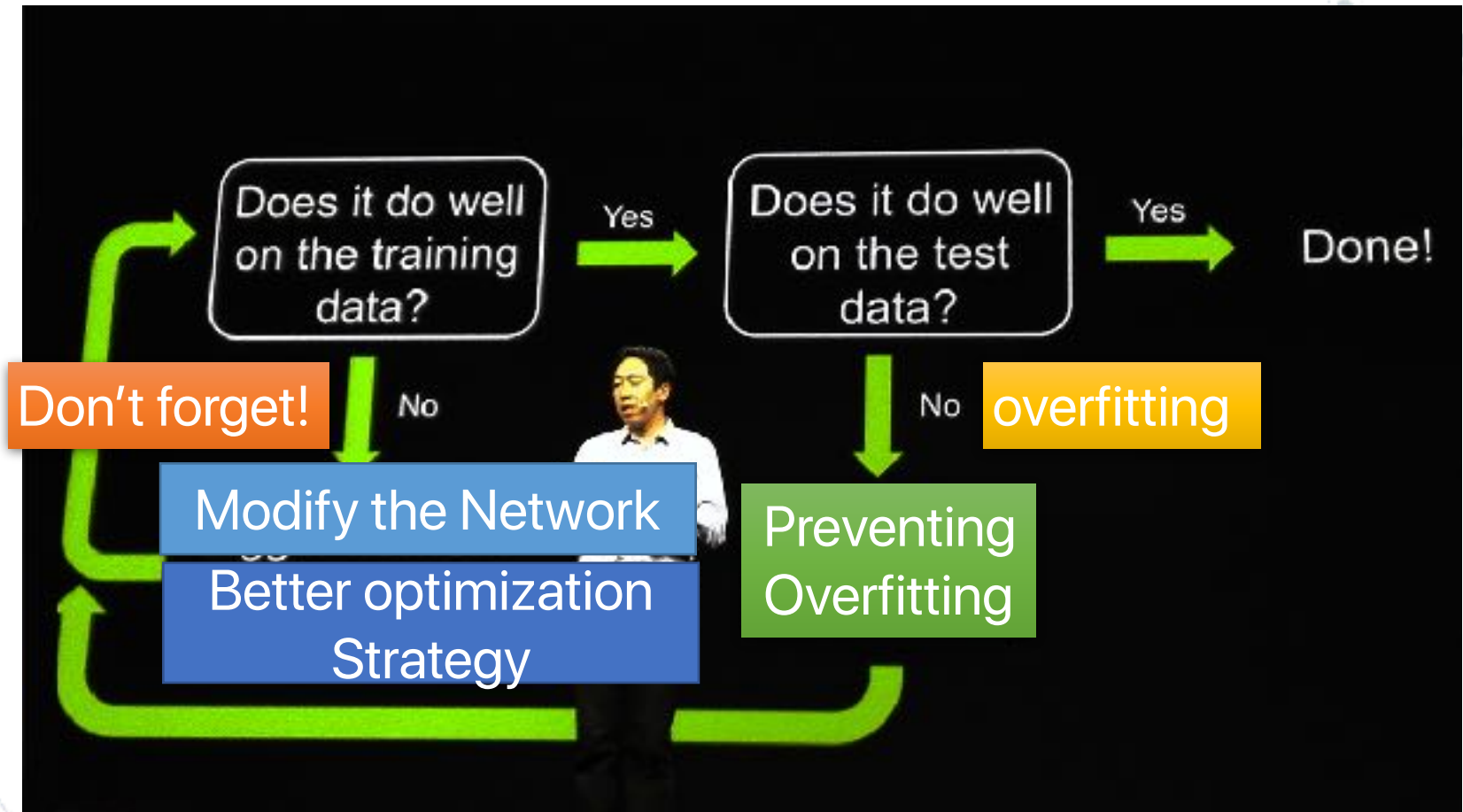
Part III: **Tips for Training DNN**

Recipe for Learning



<http://www.gizmodo.com.au/2015/04/the-basic-recipe-for-machine-learning-explained-in-a-single-powerpoint-slide/>

Recipe for Learning



<http://www.gizmodo.com.au/2015/04/the-basic-recipe-for-machine-learning-explained-in-a-single-powerpoint-slide/>

Recipe for Learning

Modify the Network

- New activation functions, for

Better optimization Strategy

- Adaptive learning rates

Prevent Overfitting

- Dropout

Only use this approach when you already obtained good results on the training data.

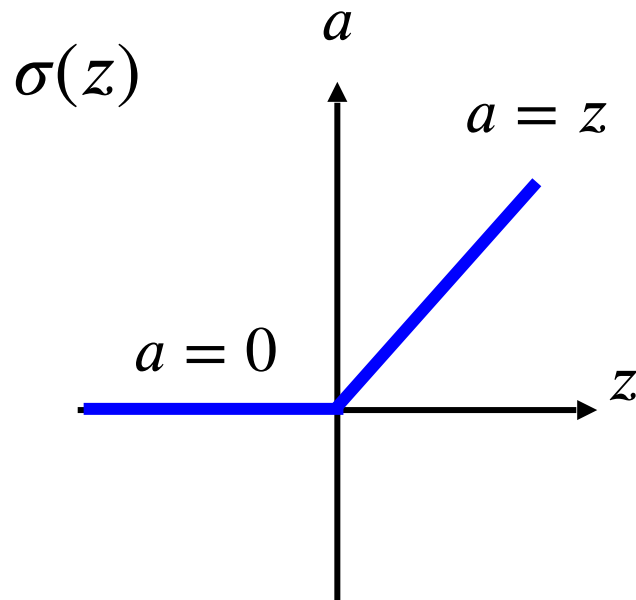


Part III: **Tips for Training DNN**

New Activation Function

ReLU

◎ Rectified Linear Unit (ReLU)

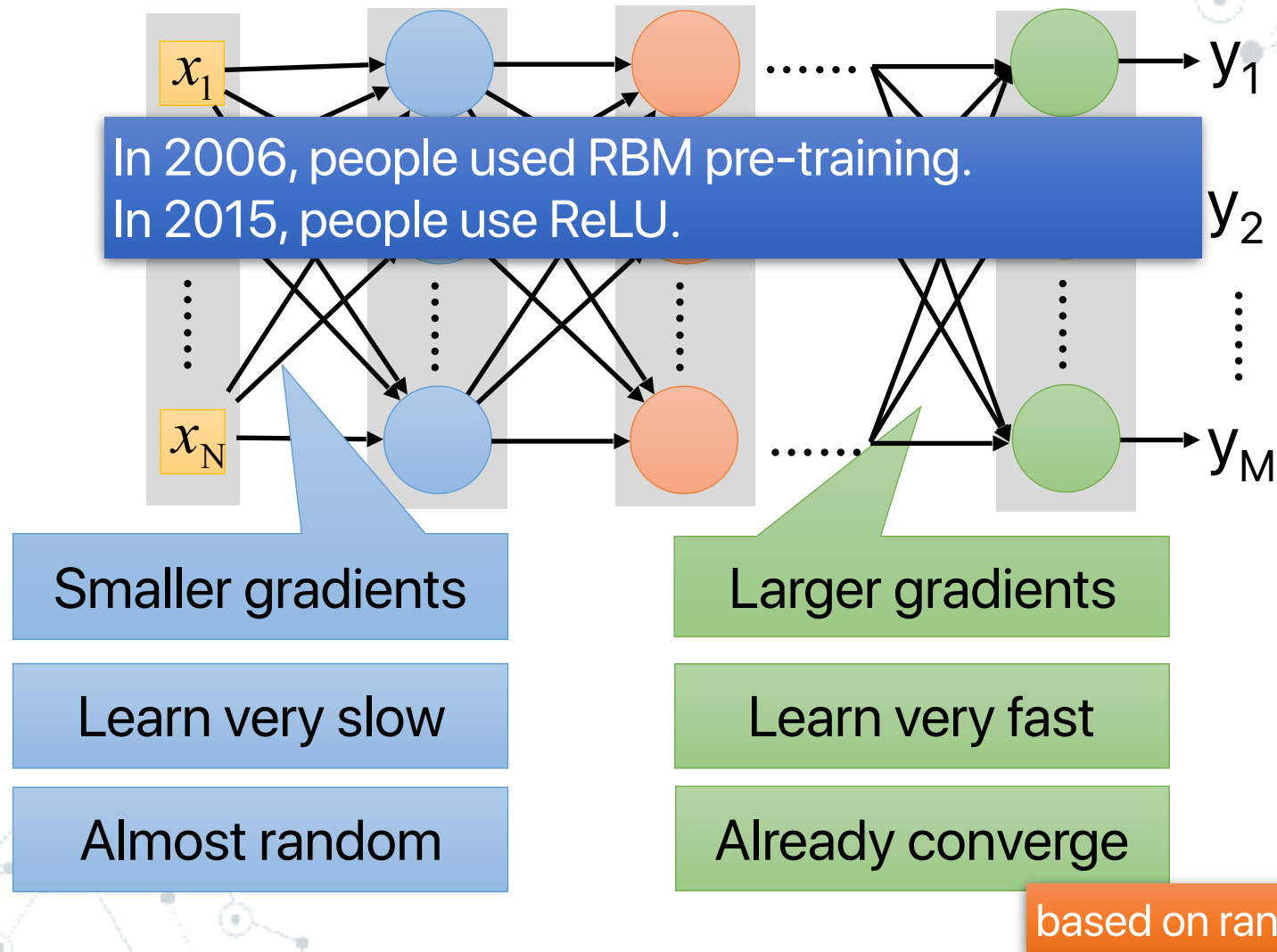


[Xavier Glorot, AISTATS'11]
[Andrew L. Maas, ICML'13]
[Kaiming He, arXiv'15]

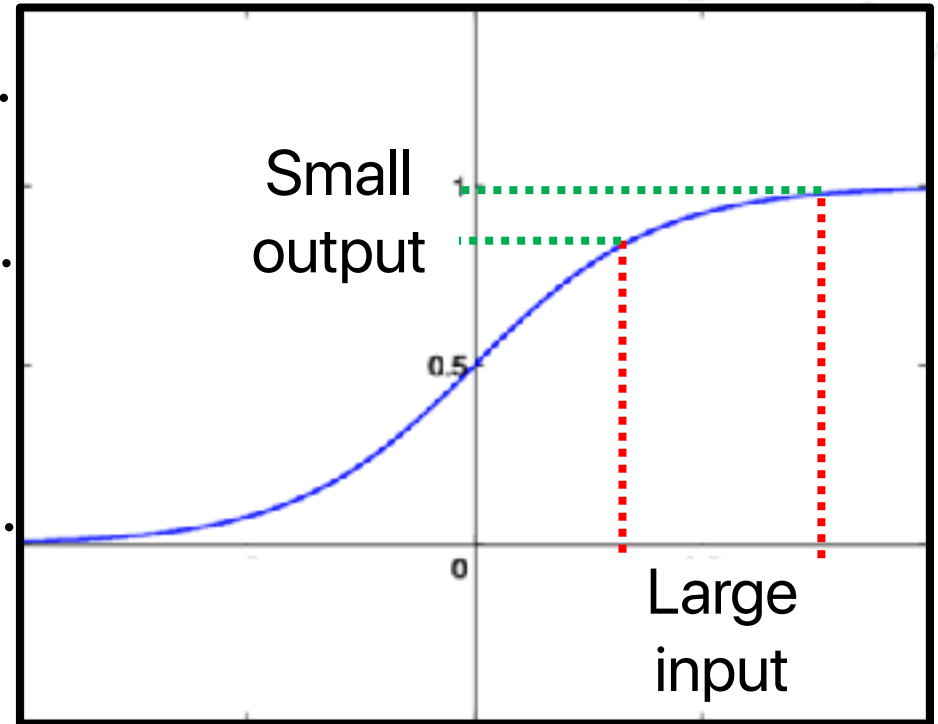
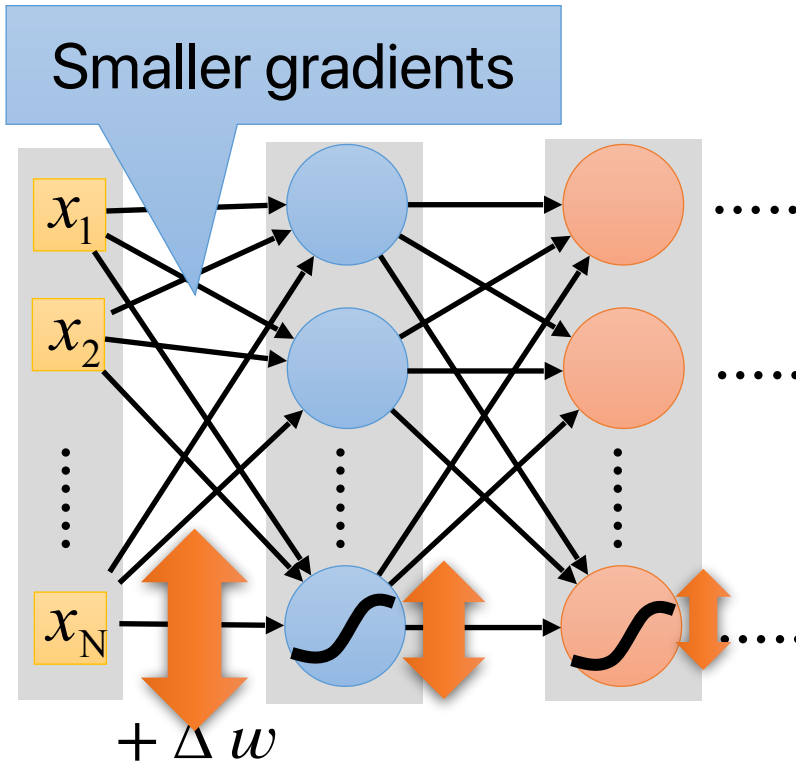
Reason:

1. Fast to compute
2. Biological reason
3. Infinite sigmoid with different biases
4. Vanishing gradient problem

Vanishing Gradient Problem



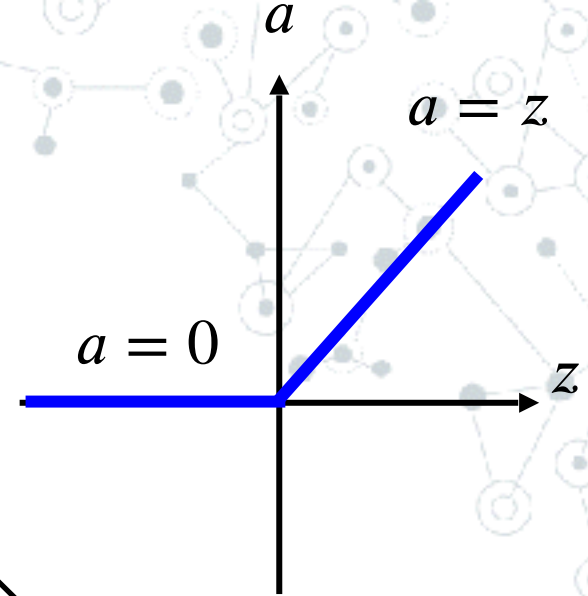
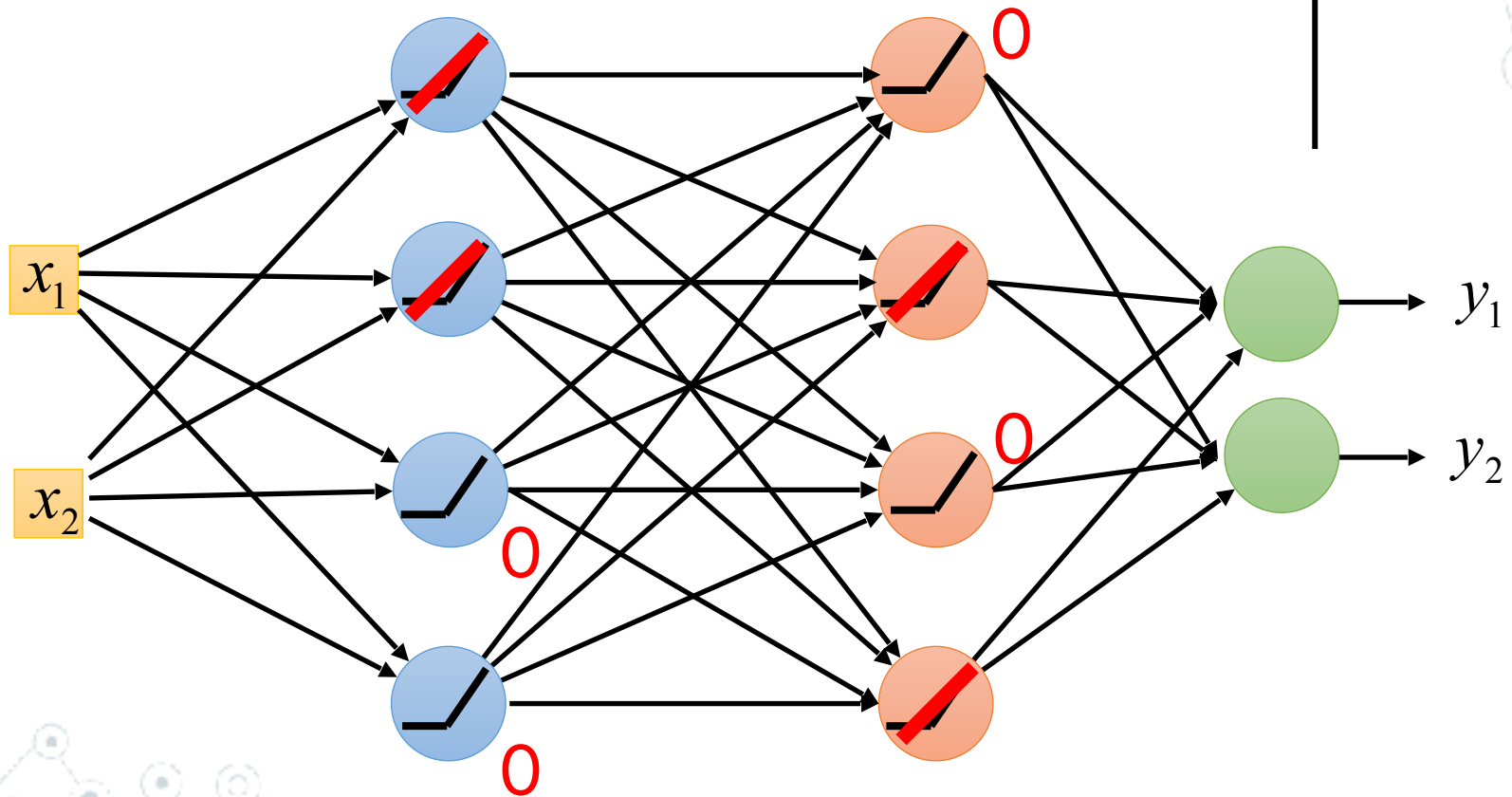
Vanishing Gradient Problem



Intuitive way to compute the gradient ...

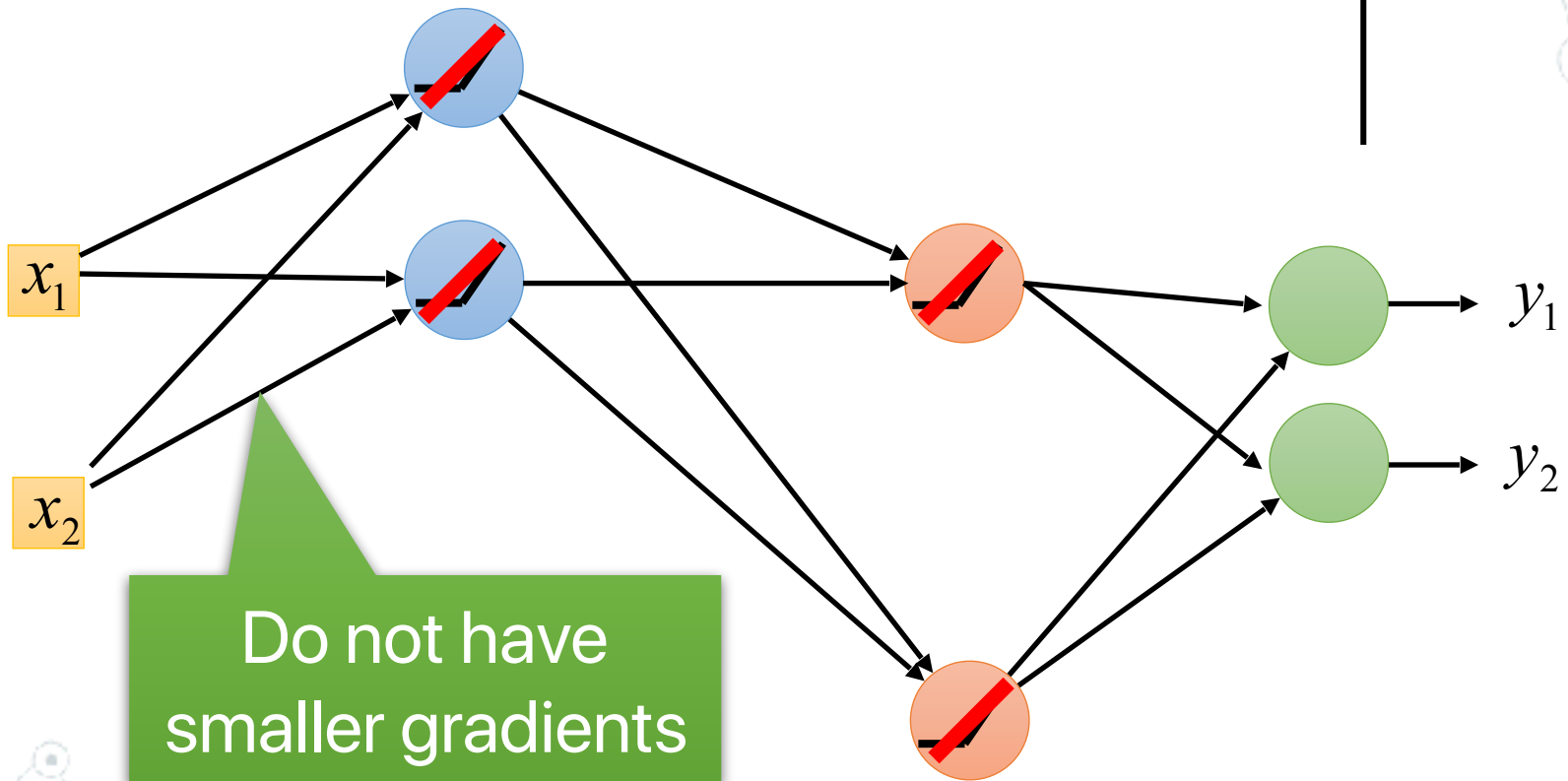
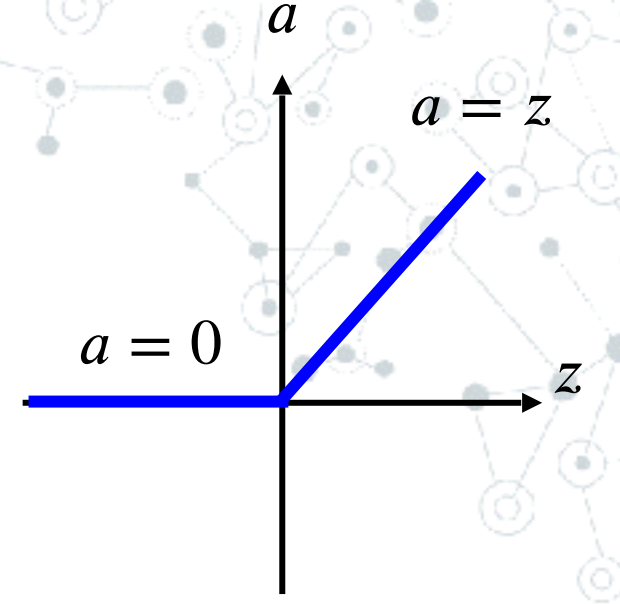
$$\frac{\partial C}{\partial w} = ? \frac{\Delta C}{\Delta w}$$

ReLU



ReLU

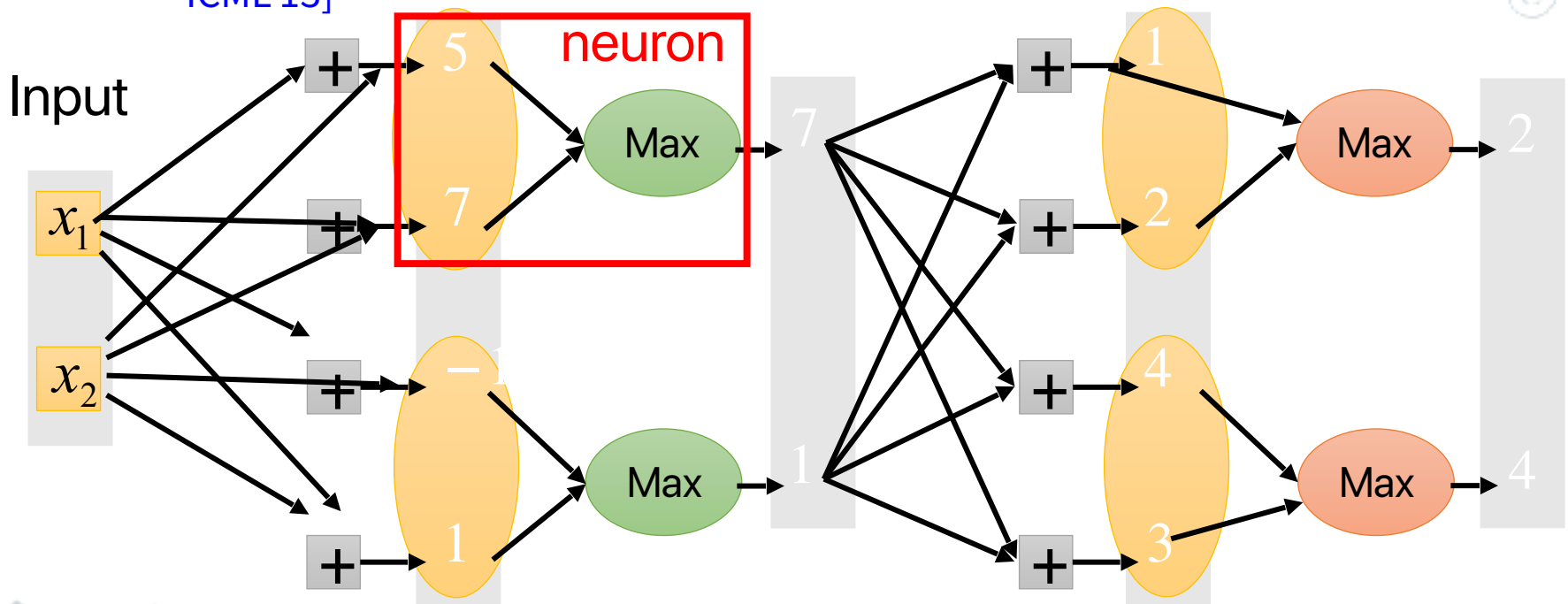
A Thinner linear network



Maxout

ReLU is a special cases of Maxout

◎ Learnable activation function [Ian J. Goodfellow, ICML'13]



You can have more than 2 elements in a group.

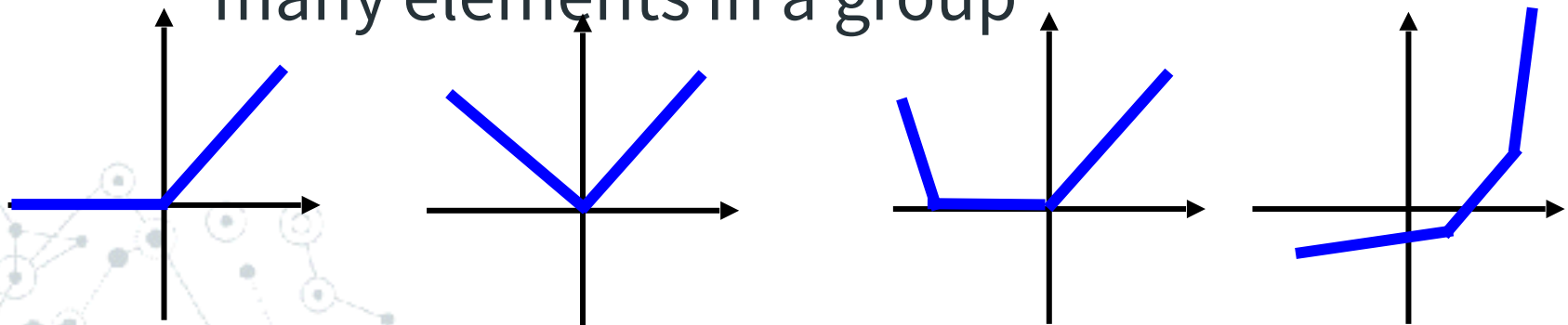
Maxout

ReLU is a special cases of
Maxout

◎ Learnable activation function [Ian J. Goodfellow,
ICML'13]

- Activation function in maxout network can be any piecewise linear convex function

2 elements in a group as dep many elements in a group 3 elements in a group



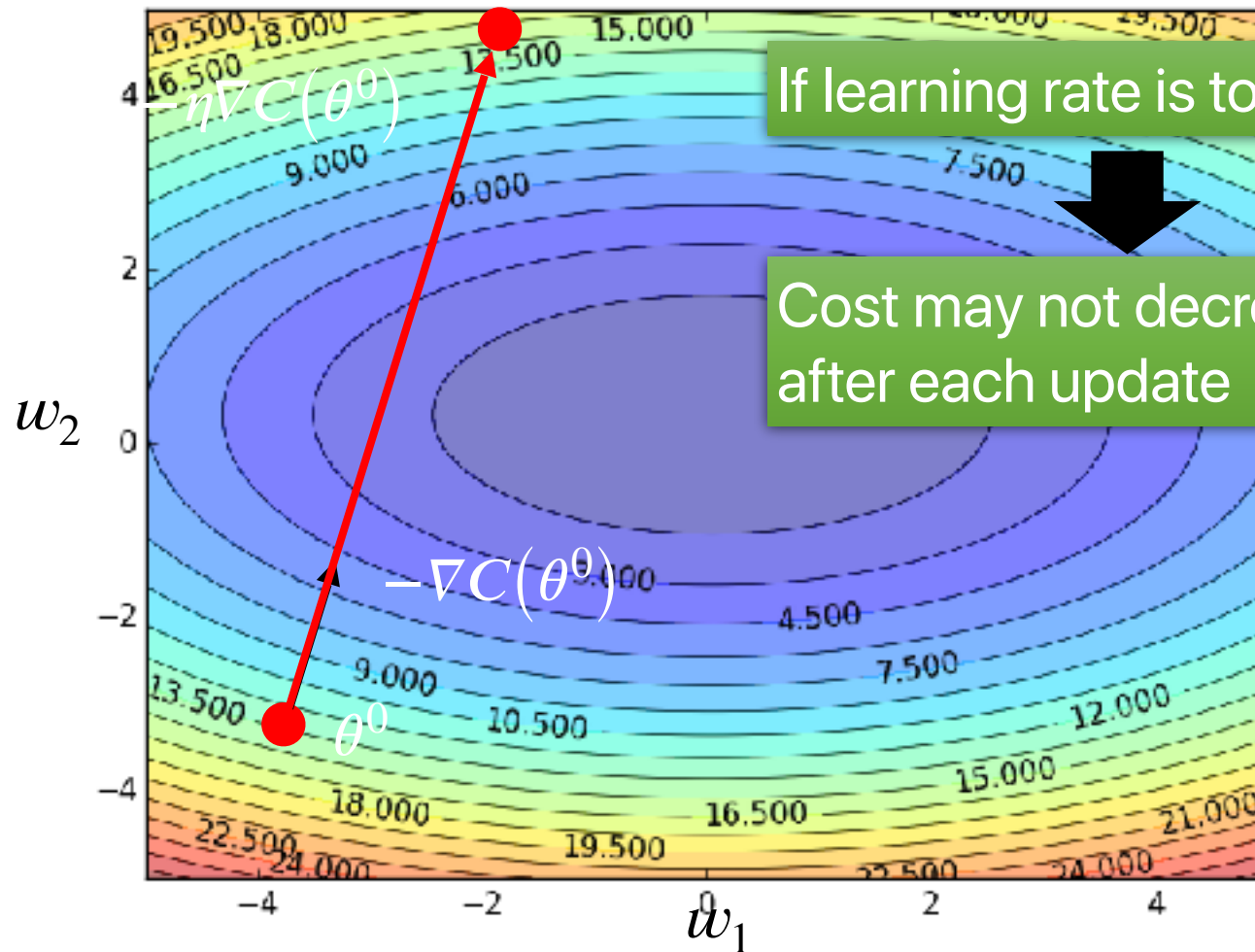


Part III: **Tips for Training DNN**

Adaptive Learning Rate

Learning Rate

Set the learning rate η carefully

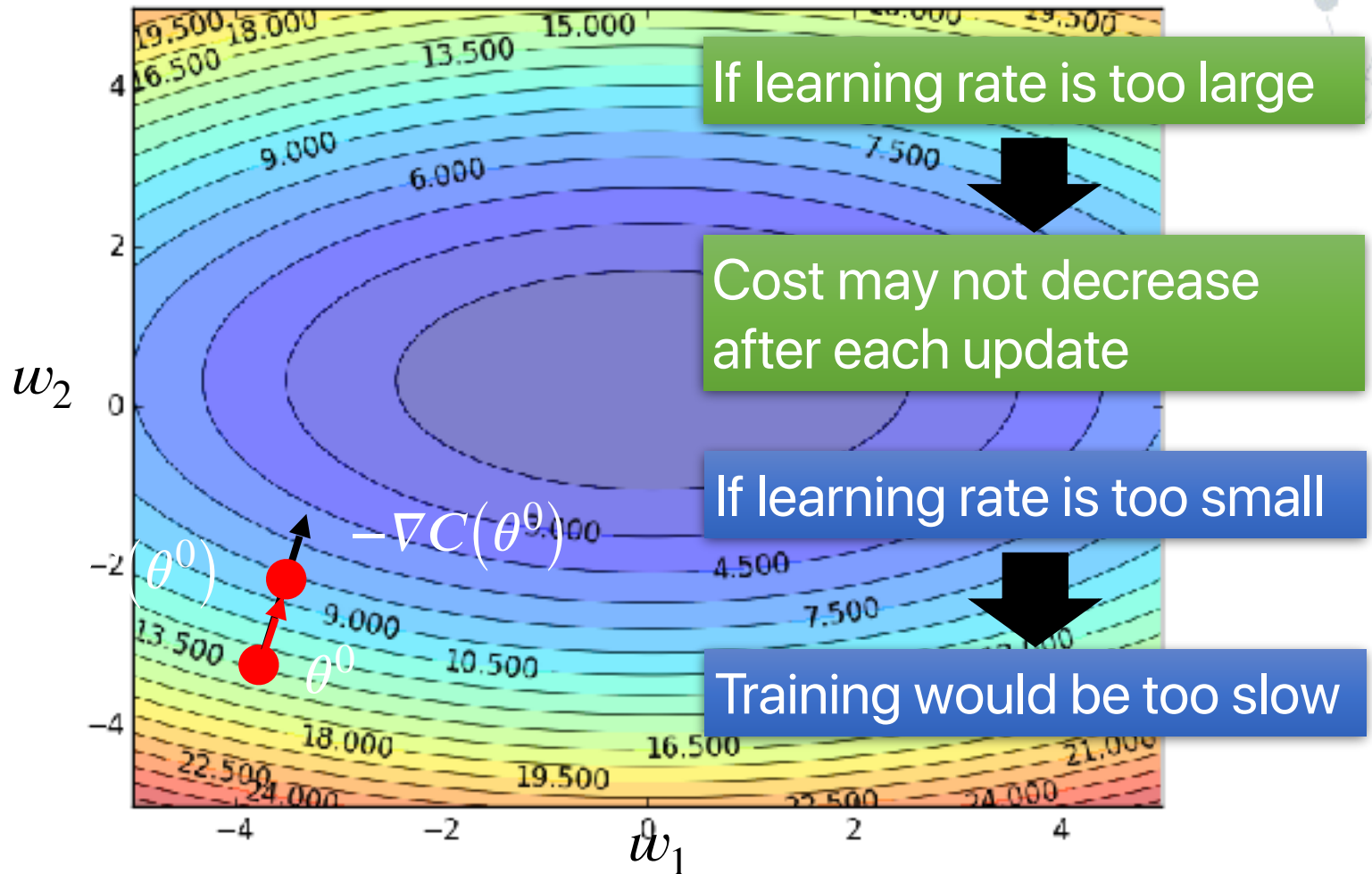


If learning rate is too large

Cost may not decrease after each update

Learning Rate

Can we give different parameters different learning rates?



Adagrad

Original Gradient Descent

$$\theta^t \leftarrow \theta^{t-1} - \eta \nabla C(\theta^{t-1})$$

Each parameter w are considered separately

$$w^{t+1} \leftarrow w^t - \eta_w g^t$$

$$g^t = \frac{\partial C(\theta^t)}{\partial w}$$

Parameter dependent learning rate

$$\eta_w = \frac{\eta}{\sqrt{\sum_{i=0}^t (g^i)^2}}$$

constant

Summation of the square of the previous derivatives

Adagrad

$$\eta_w = \frac{\eta}{\sqrt{\sum_{i=0}^t (g^i)^2}}$$

$$w_1 \begin{array}{|c|} \hline g^0 \\ \hline 0.1 \\ \hline \end{array}$$

$$w_2 \begin{array}{|c|} \hline g^0 \\ \hline 20.0 \\ \hline \end{array}$$

Learning rate:

$$\frac{\eta}{\sqrt{0.1^2}} = \frac{\eta}{0.1}$$

$$\frac{\eta}{\sqrt{0.1^2 + 0.2^2}} = \frac{\eta}{0.22}$$

Learning rate:

$$\frac{\eta}{\sqrt{20^2}} = \frac{\eta}{20}$$

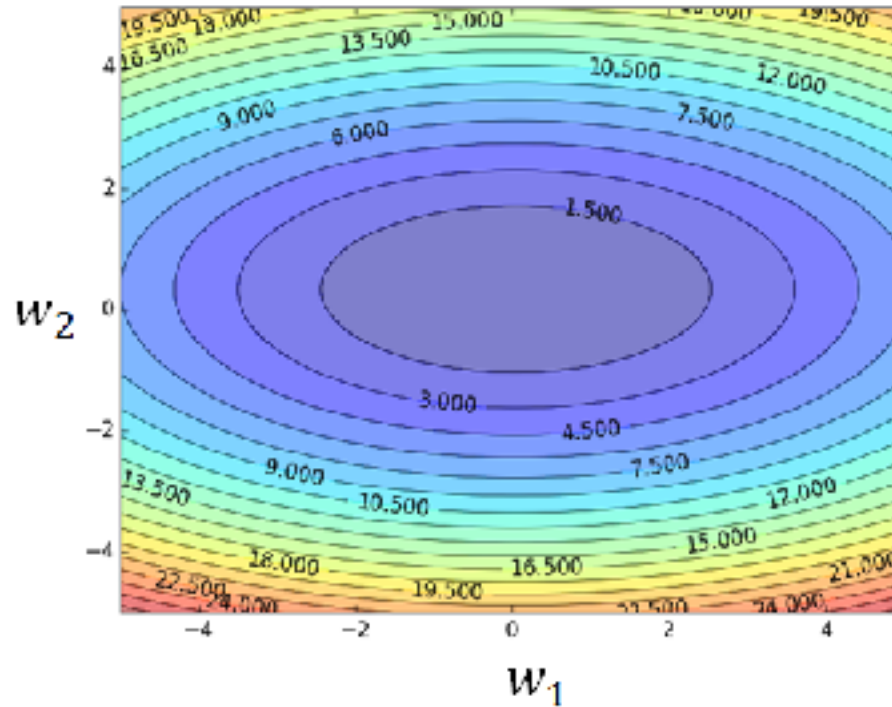
$$\frac{\eta}{\sqrt{20^2 + 10^2}} = \frac{\eta}{22}$$

Observation: 1. Learning rate is smaller and smaller for all parameters
2. Smaller derivatives, larger learning rate, and vice versa

Why?

Larger
derivatives

Smaller
Learning Rate



Smaller Derivatives



Larger Learning Rate

2. Smaller derivatives, larger learning rate, and vice versa

Why?

Not the whole story

© Adagrad [John Duchi, JMLR'11]

© RMSprop

- <https://www.youtube.com/watch?v=O3sxAc4hxZU>

© Adadelta [Matthew D. Zeiler, arXiv'12]

© Adam [Diederik P. Kingma, ICLR'15]

© AdaSecant [Caglar Gulcehre, arXiv'14]

© “No more pesky learning rates” [Tom Schaul, arXiv'12]



Part III: **Tips for Training DNN**

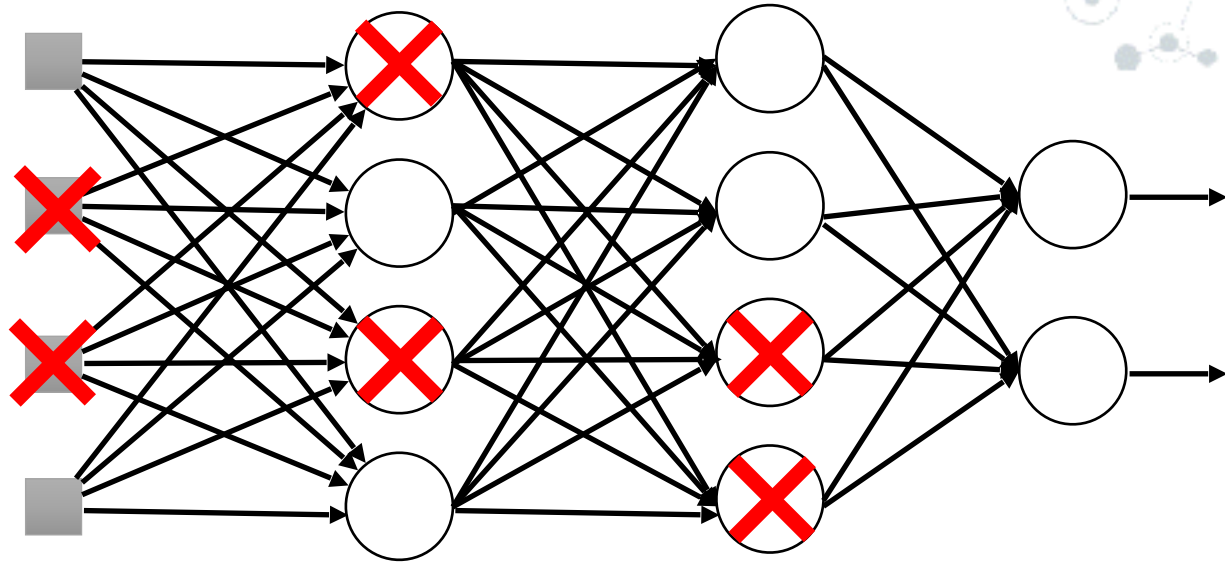
Dropout

Dropout

Pick a mini-batch

$$\theta^t \leftarrow \theta^{t-1} - \eta \nabla C(\theta^{t-1})$$

Training:



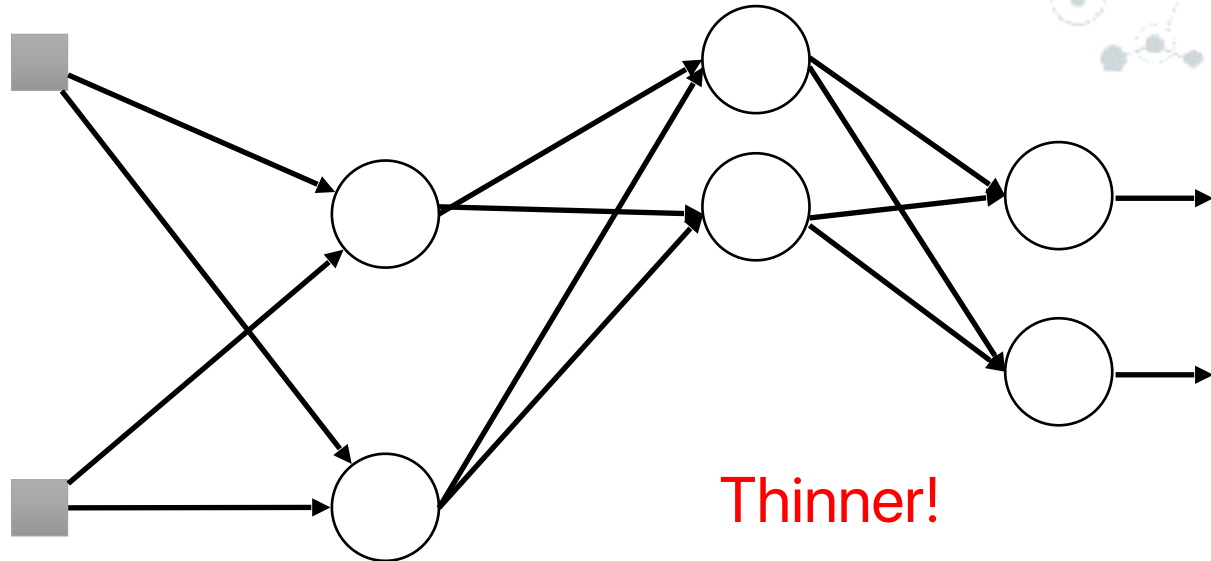
- **Each time before computing the gradients**
 - Each neuron has $p\%$ to dropout

Dropout

Pick a mini-batch

$$\theta^t \leftarrow \theta^{t-1} - \eta \nabla C(\theta^{t-1})$$

Training:



- Each time before computing the gradients
- Each neuron has p% to dropout



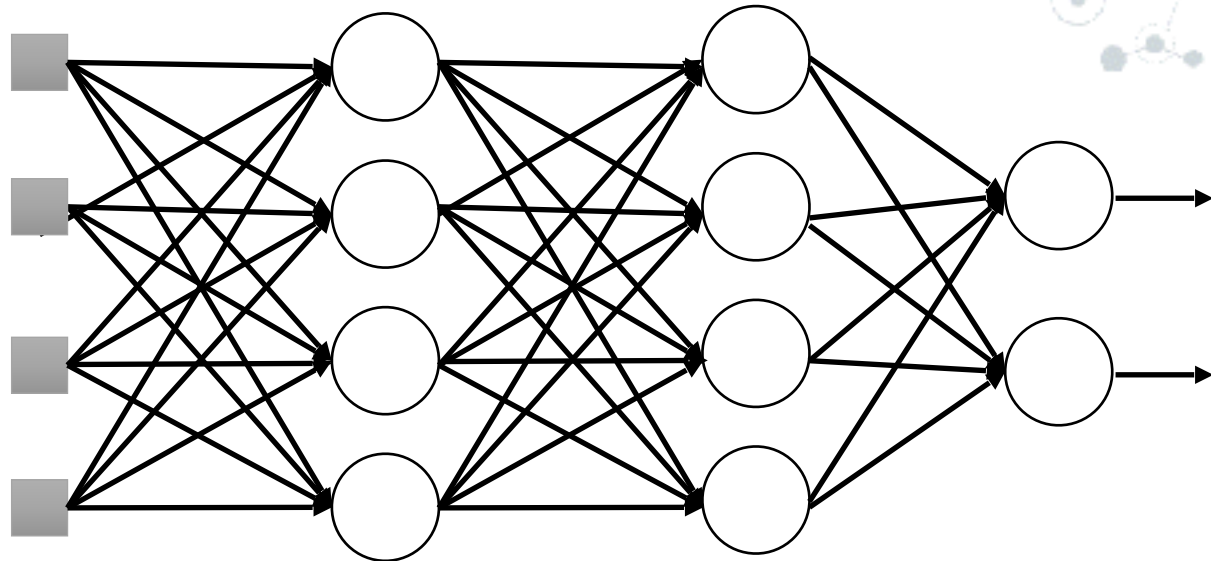
The structure of the network is changed.

- Using the new network for training

For each mini-batch, we resample the dropout neurons

Dropout

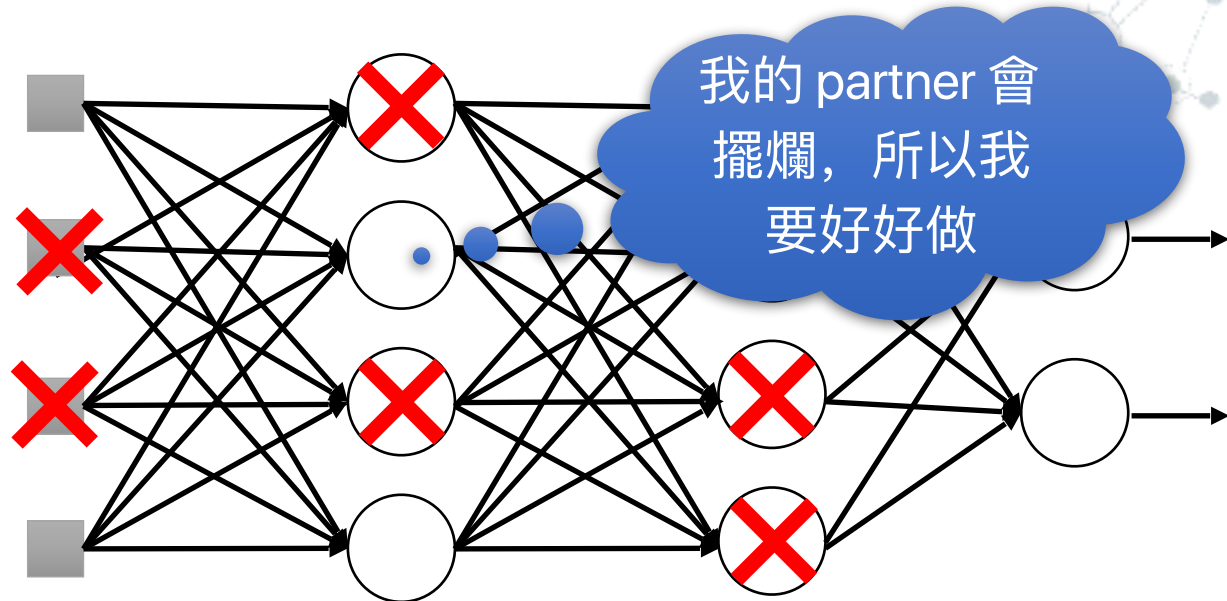
Testing:



➤ No dropout

- If the dropout rate at training is $p\%$, all the weights times $(1-p)\%$
- Assume that the dropout rate is 50%. If a weight by training, set for testing.

Dropout - Intuitive Reason



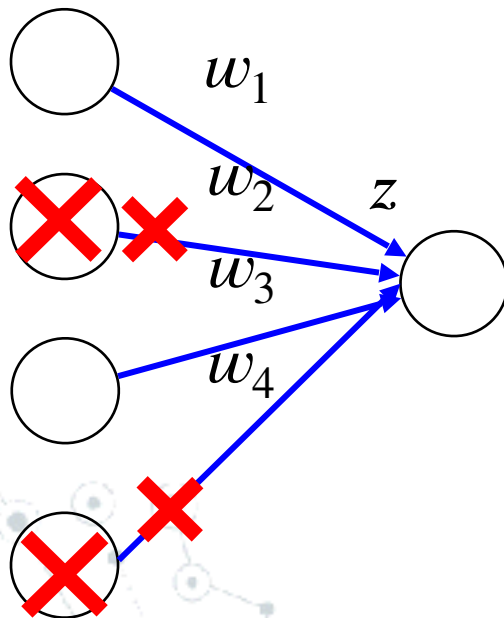
- When teams up, if everyone expect the partner will do the work, nothing will be done finally.
- However, if you know your partner will dropout, you will do better.
- When testing, no one dropout actually, so obtaining good results eventually.

Dropout - Intuitive Reason

- Why the weights should multiply $(1-p)\%$ (dropout rate) when testing?

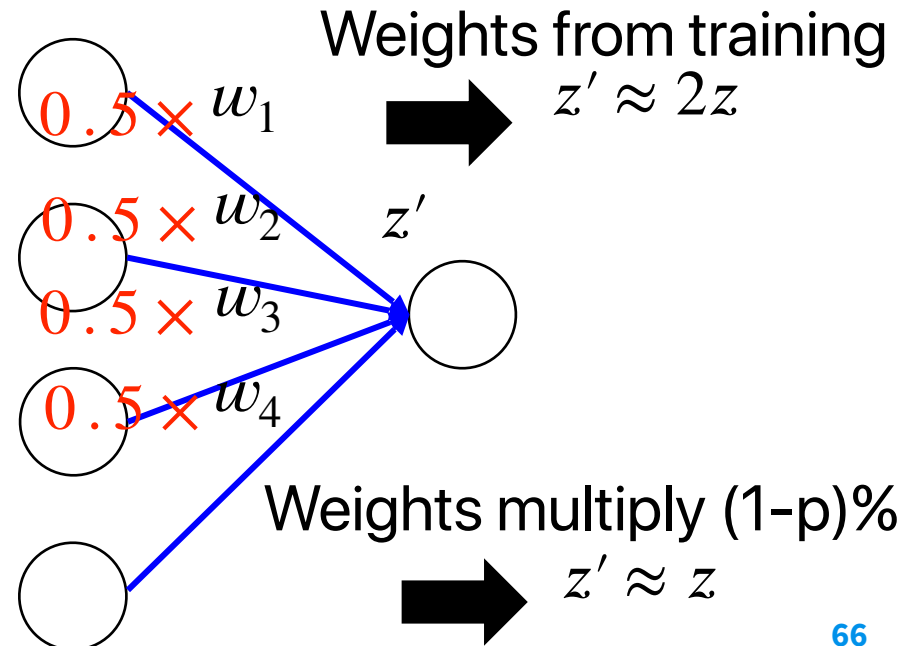
Training of Dropout

Assume dropout rate is 50%

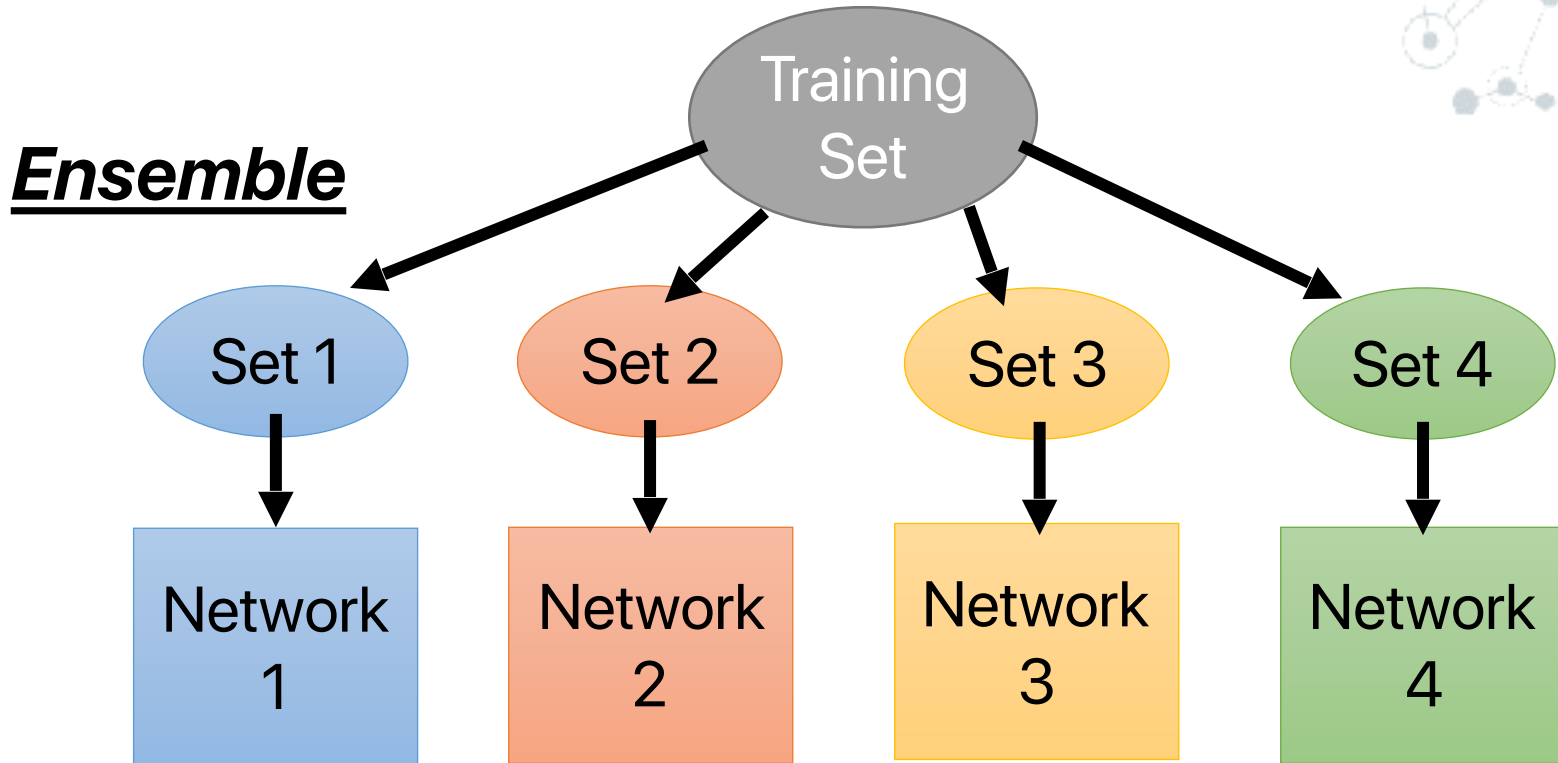


Testing of Dropout

No dropout



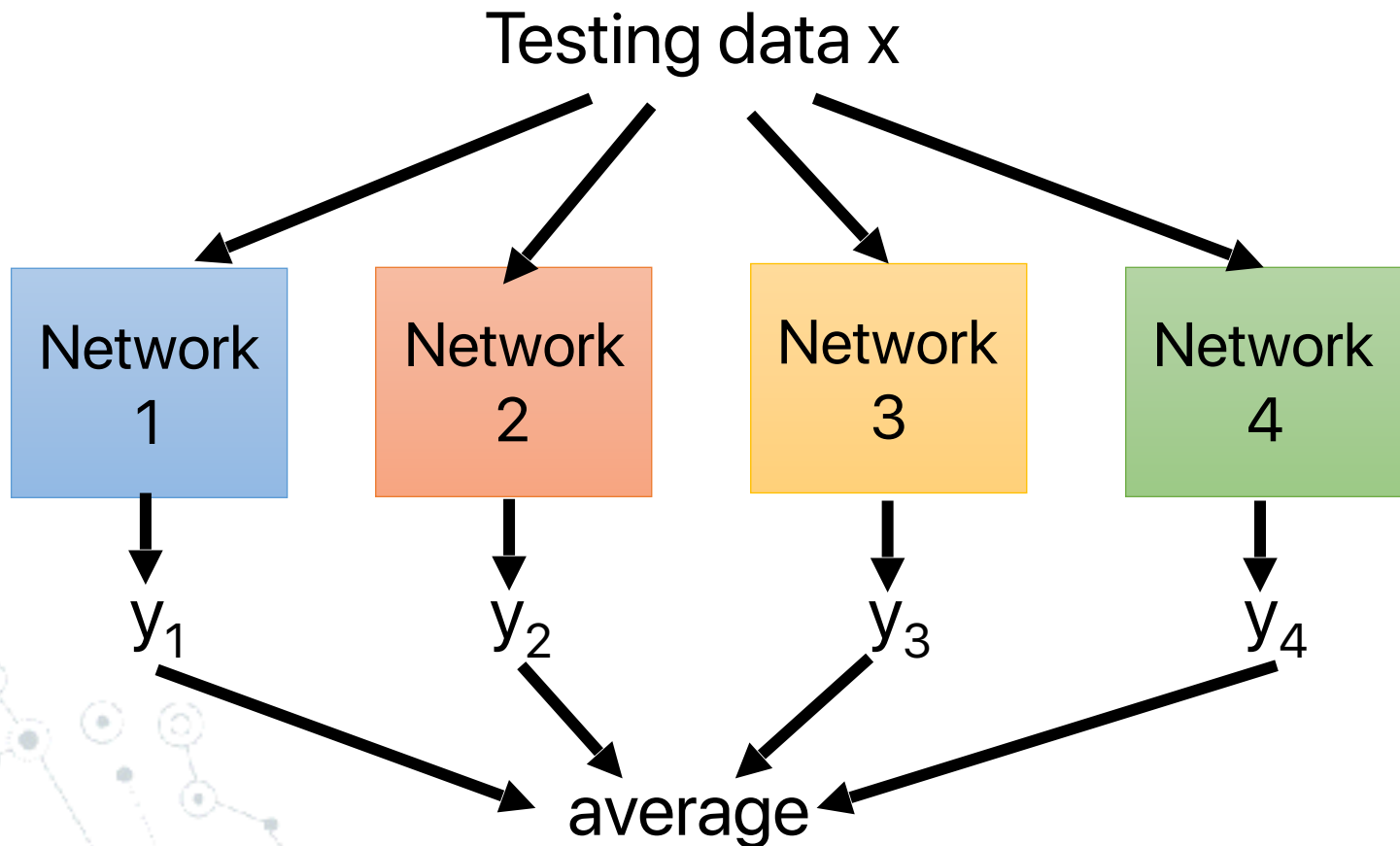
Dropout is a kind of ensemble.



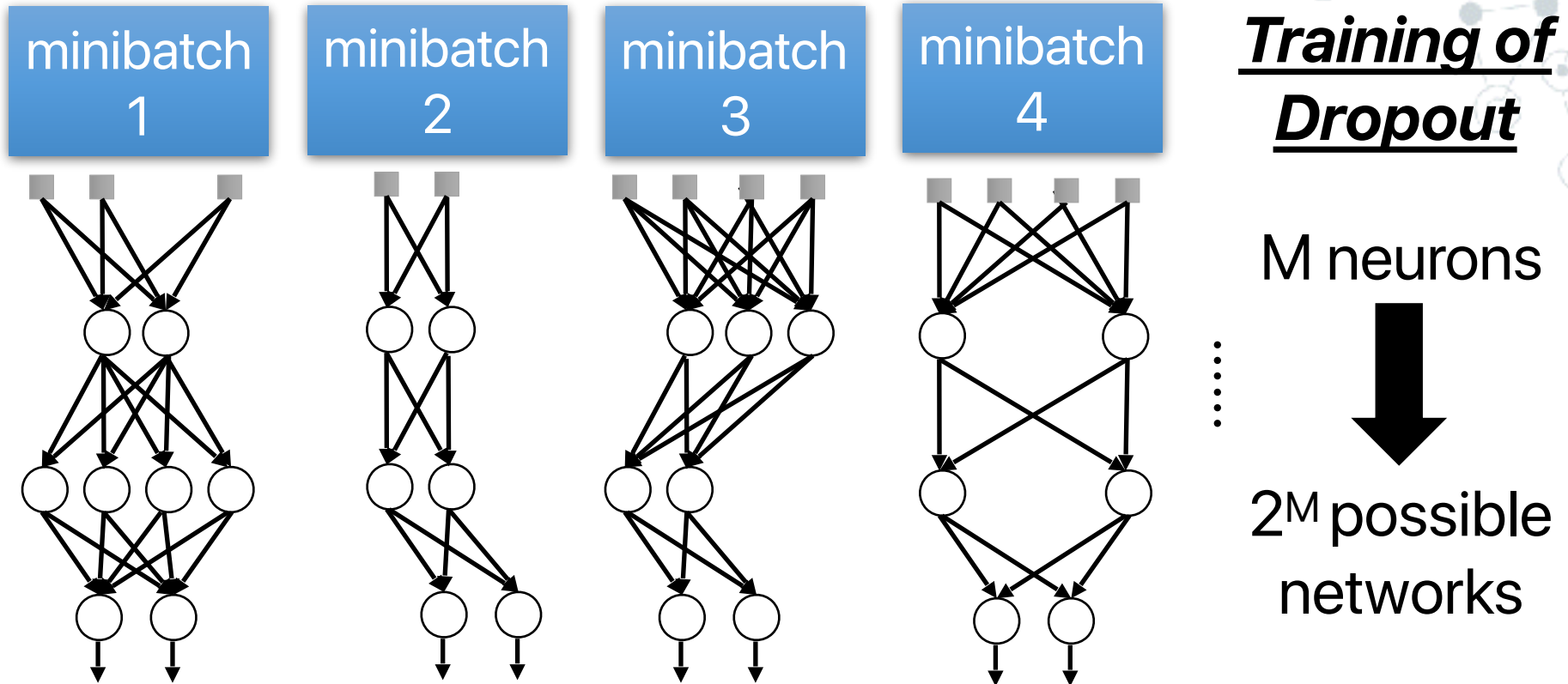
Train a bunch of networks with different structures

Dropout is a kind of ensemble.

Ensemble



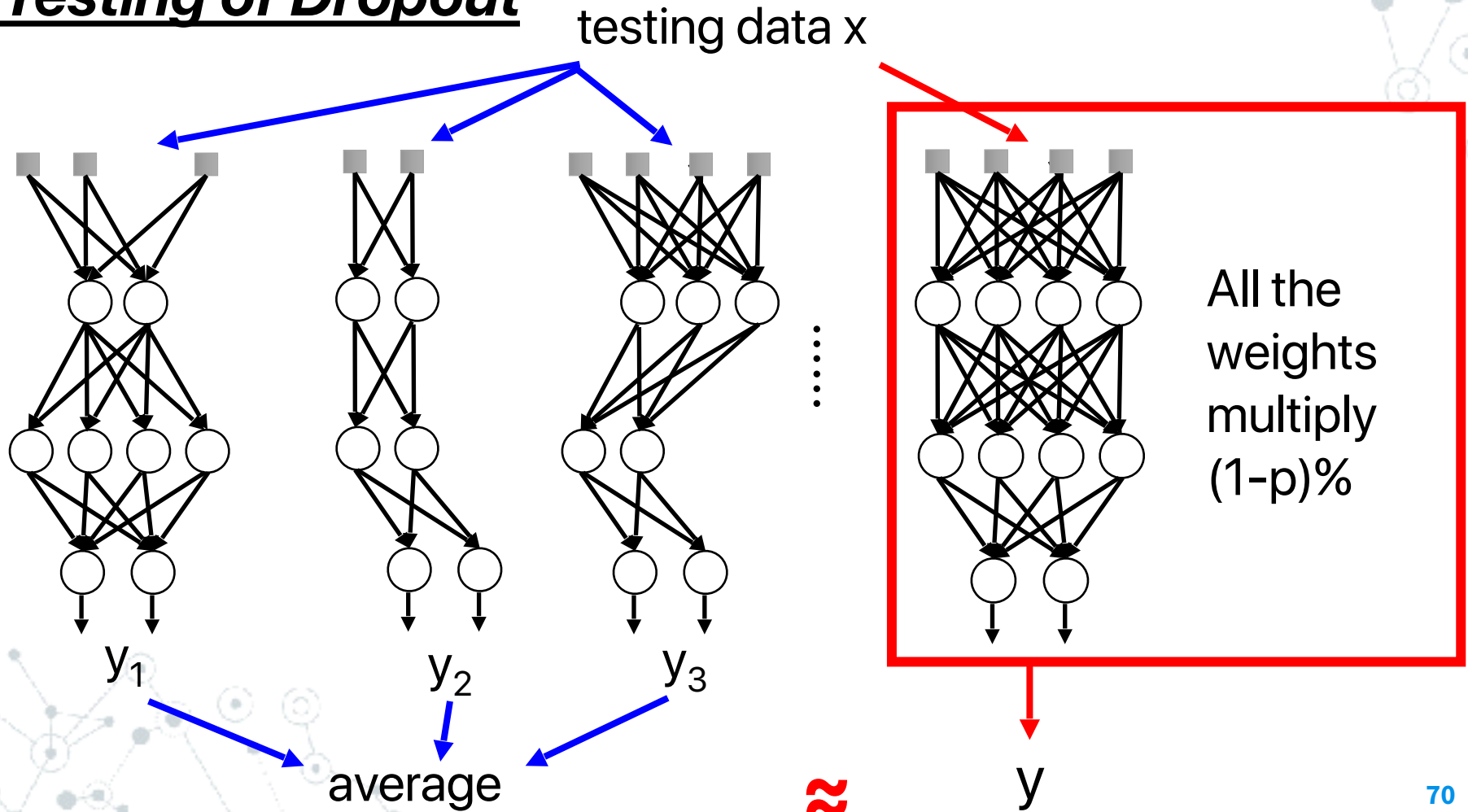
Dropout is a kind of ensemble.



- Using one mini-batch to train one network
- Some parameters in the network are shared

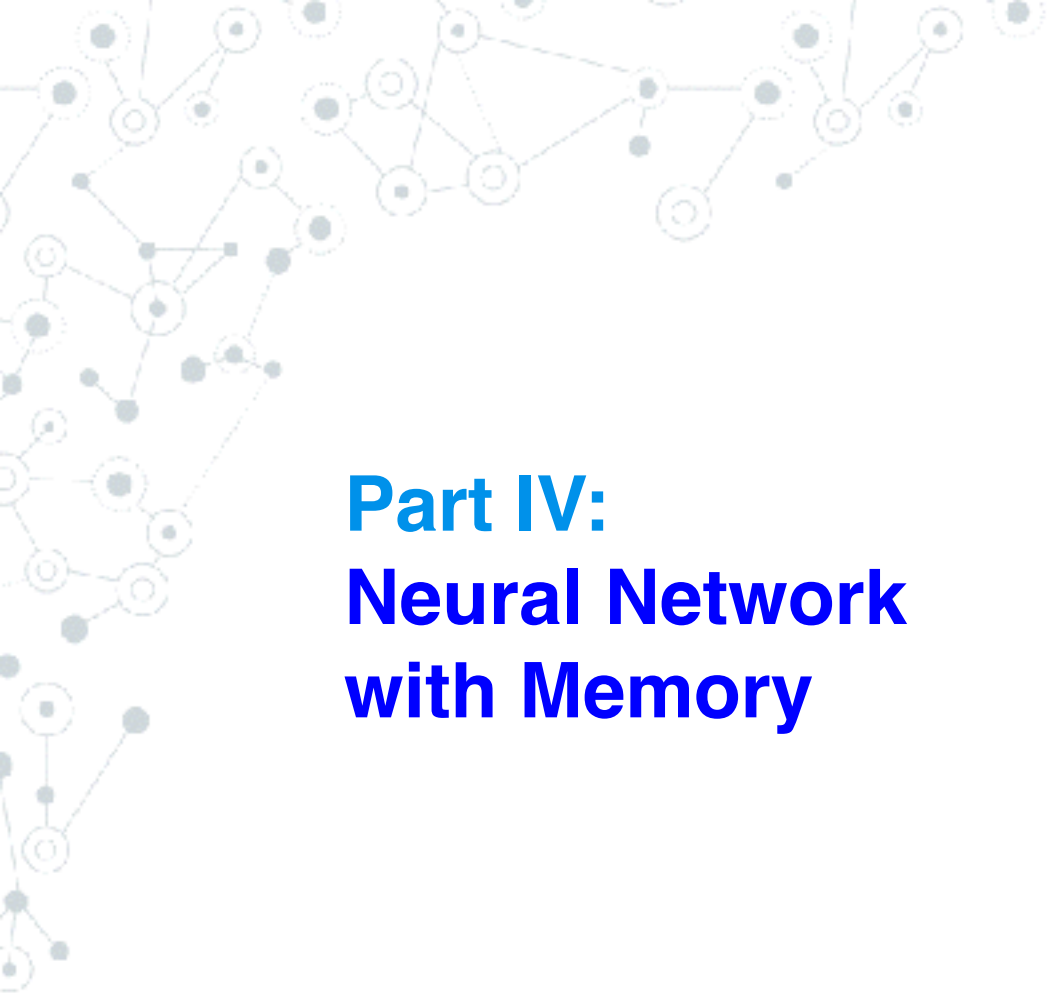
Dropout is a kind of ensemble.

Testing of Dropout



More about dropout

- More reference for dropout [Nitish Srivastava, JMLR'14] [Pierre Baldi, NIPS'13][Geoffrey E. Hinton, arXiv'12]
- Dropout works better with Maxout [Ian J. Goodfellow, ICML'13]
- Dropconnect [Li Wan, ICML'13]
 - Dropout delete neurons
 - Dropconnect deletes the connection between neurons
- Annealed dropout [S.J. Rennie, SLT'14]
 - Dropout rate decreases by epochs
- Standout [J. Ba, NIPS'13]
 - Each neural has different dropout rate

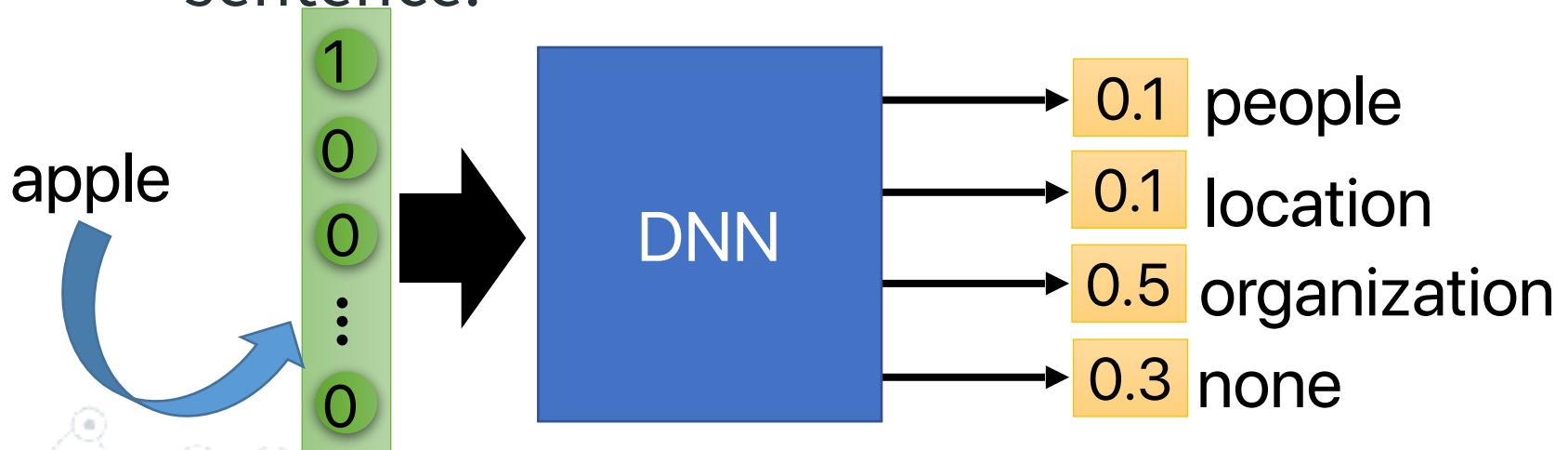


Part IV: **Neural Network with Memory**

Neural Network needs Memory

◎ Name Entity Recognition

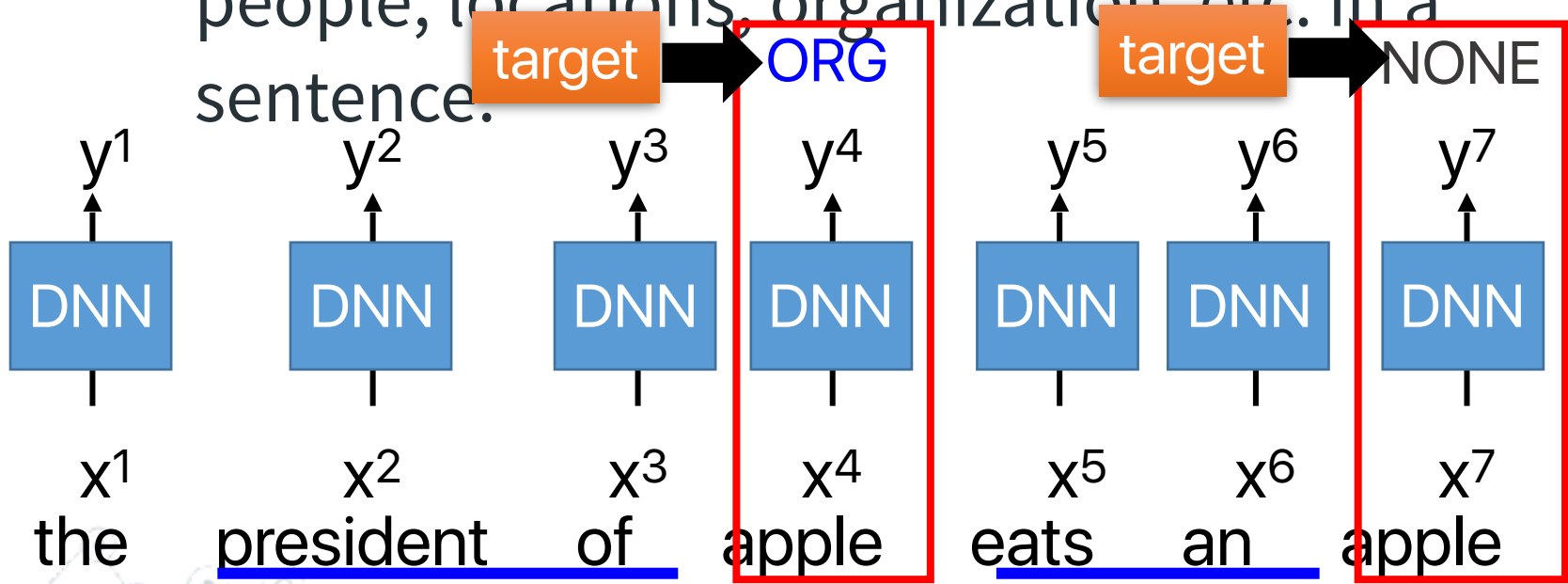
- Detecting named entities like name of people, locations, organization, etc. in a sentence.



Neural Network needs Memory

◎ Name Entity Recognition

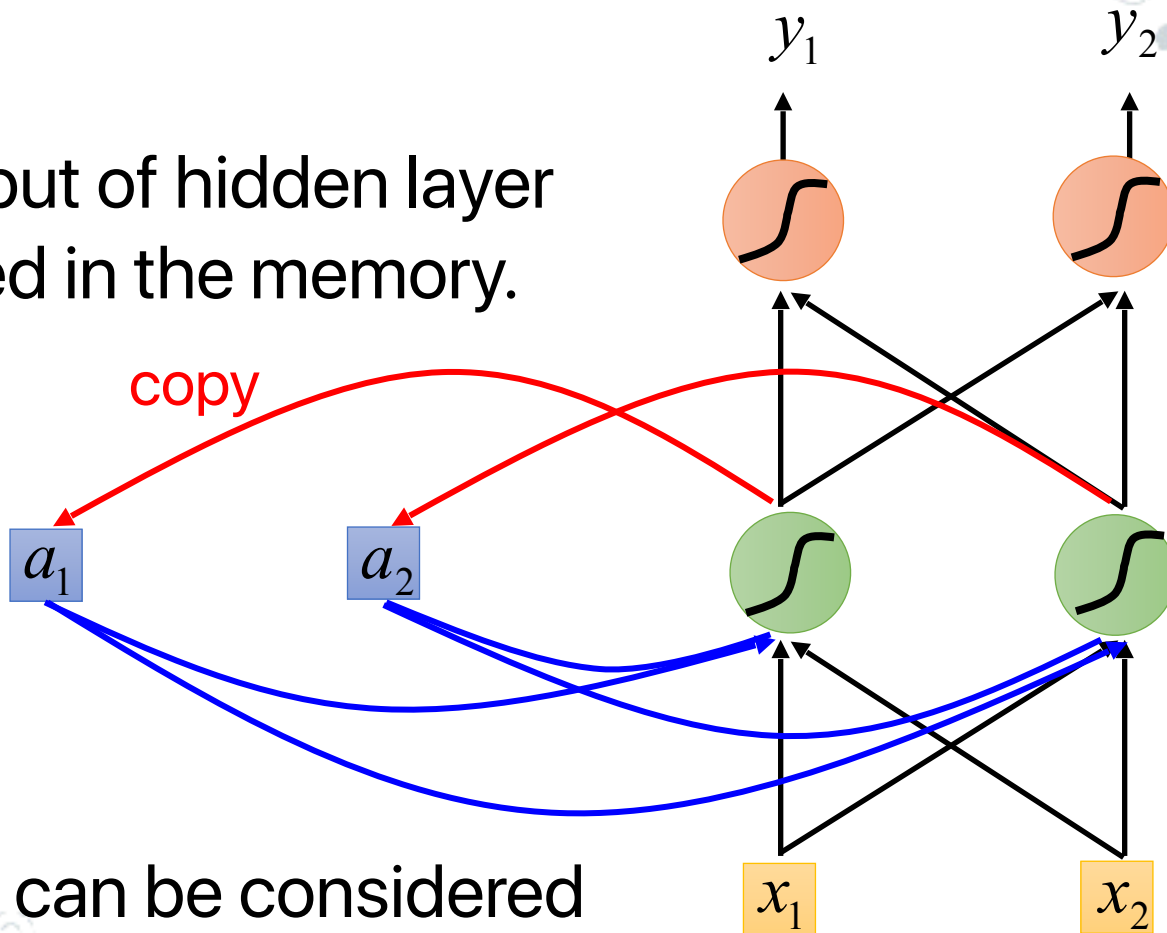
- Detecting named entities like name of people, locations, organization etc. in a sentence.



DNN needs memory!

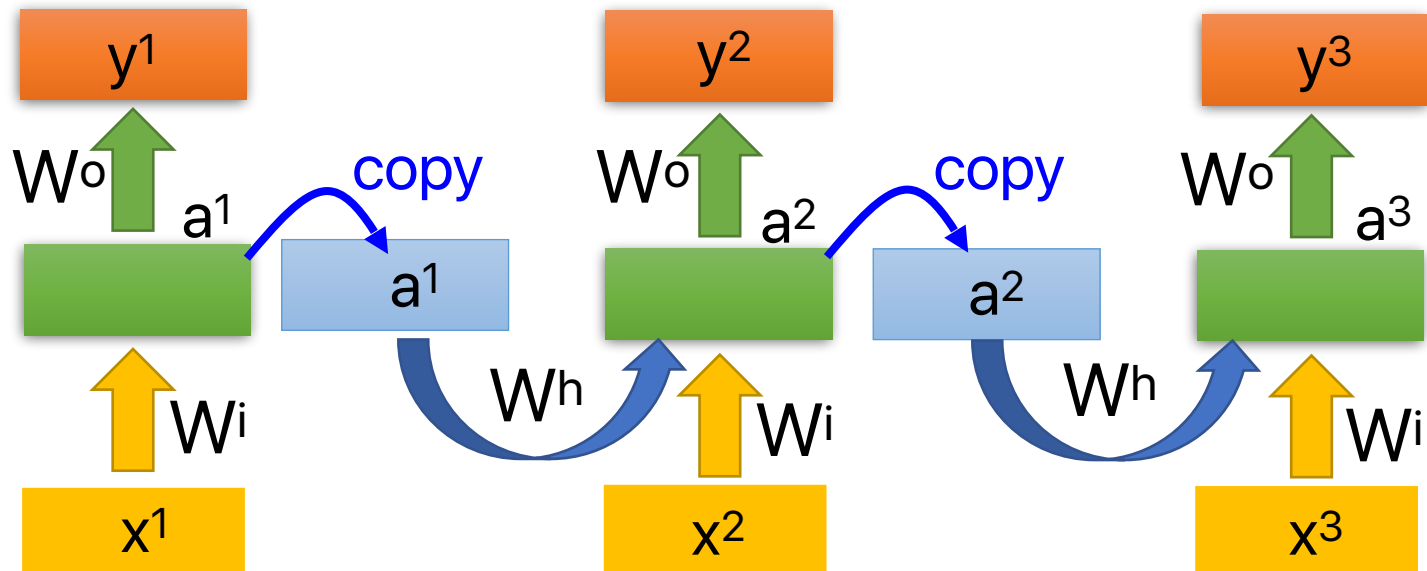
Recurrent Neural Network (RNN)

The output of hidden layer are stored in the memory.



Memory can be considered as another input.

RNN

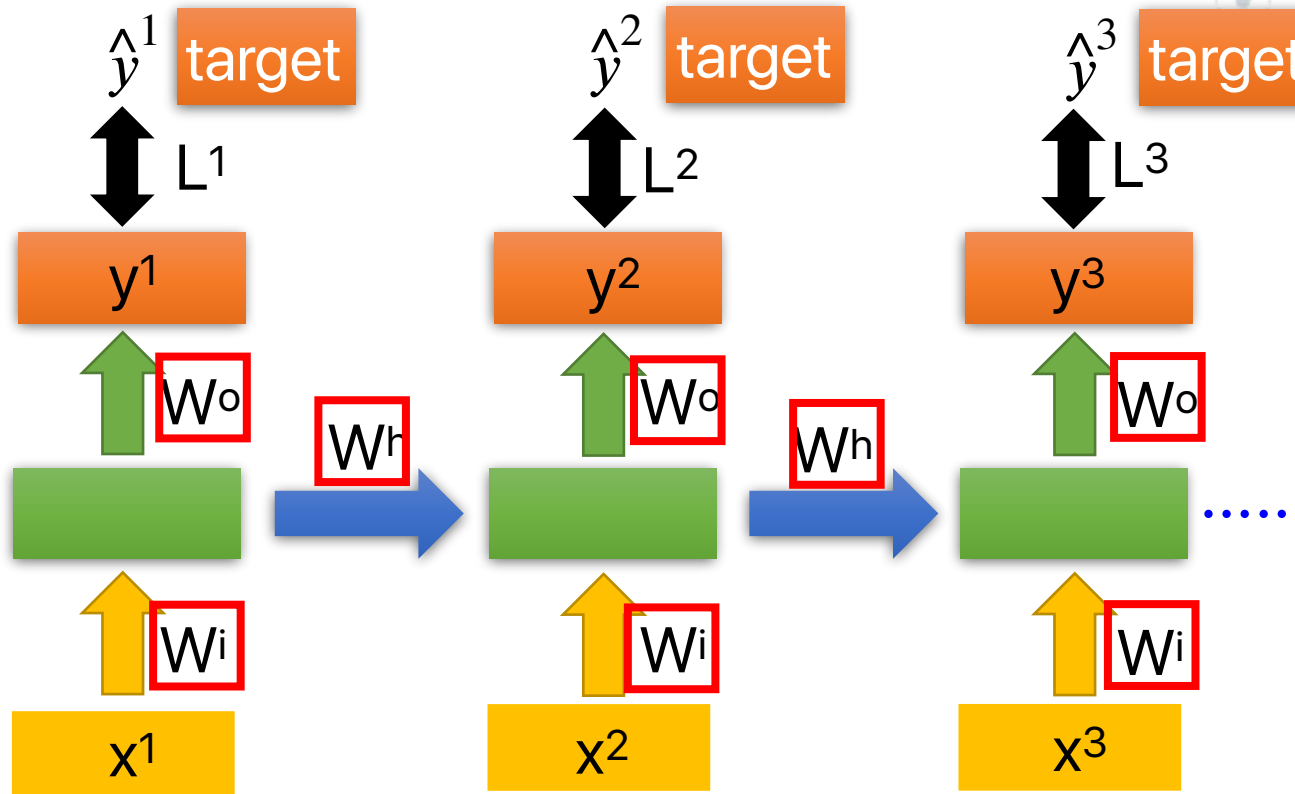


The same network is used again and
again.

Output y_i depends on x^1, x^2, \dots, x^i

RNN

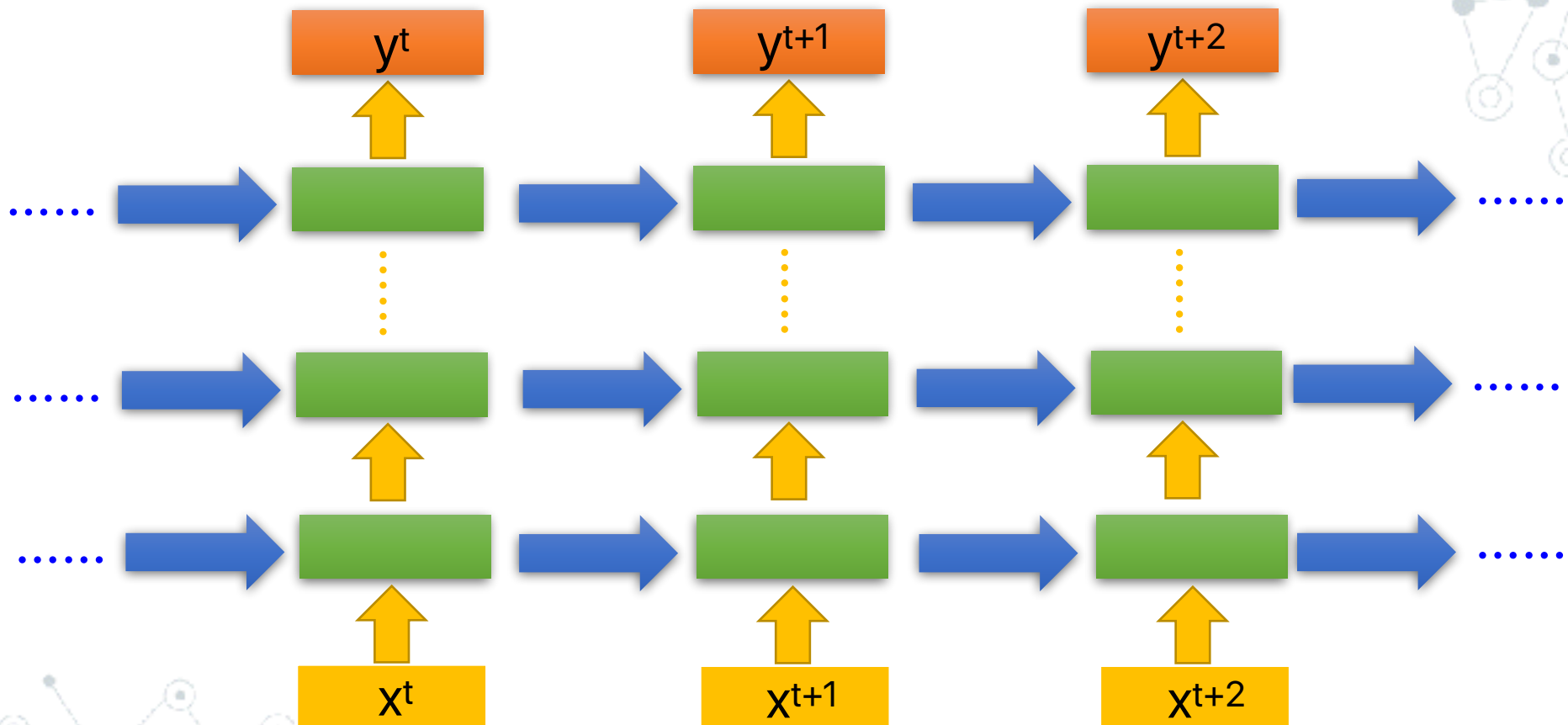
How to train?



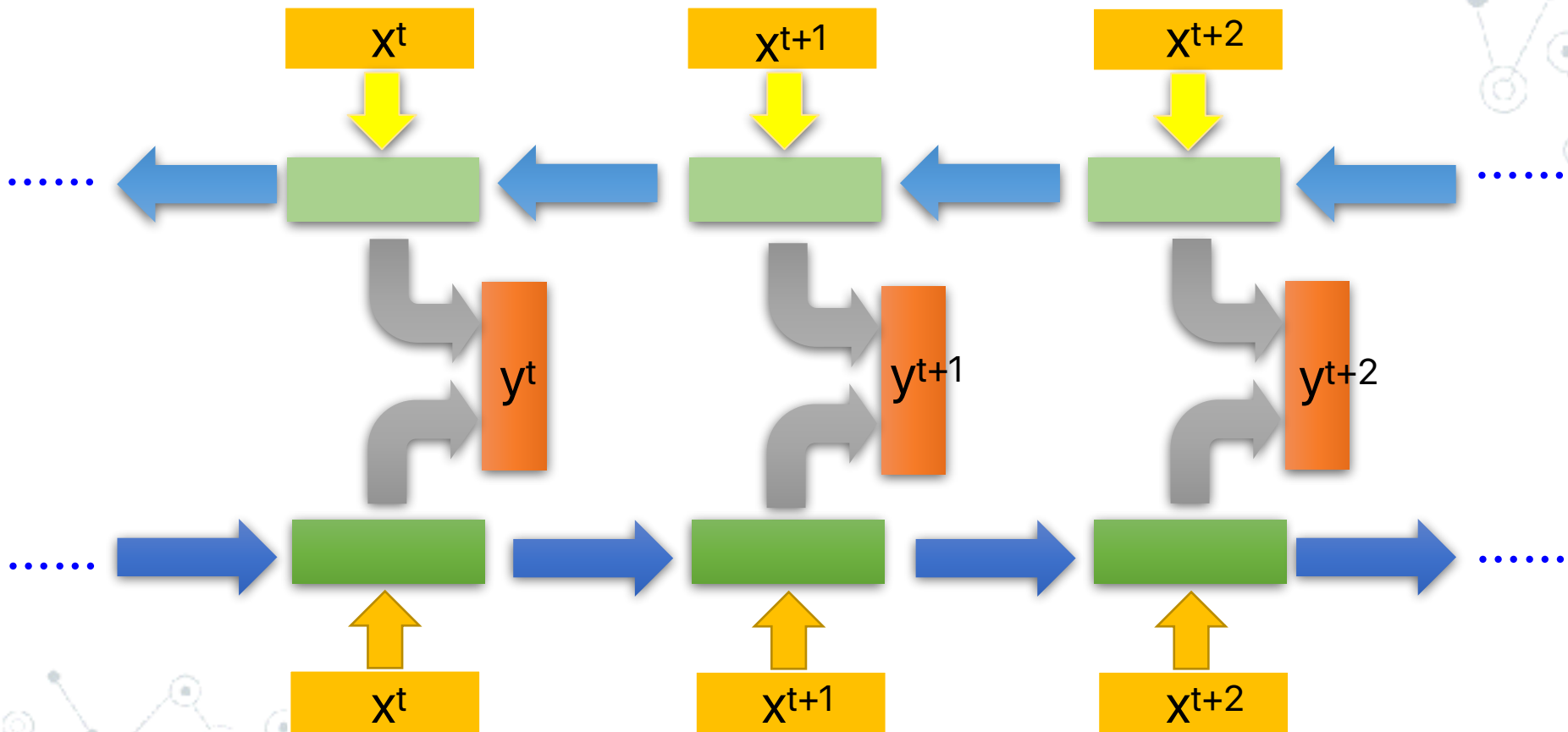
Find the network parameters to minimize the total cost:

Backpropagation through time (BPTT)

Of course it can be deep ...



Bidirectional RNN



Many to Many (Output is shorter)

◎ Both input and output are both sequences, **but the output is shorter.**

○ E.g. **Speech Recognition**

Output: "好棒" (character sequence)



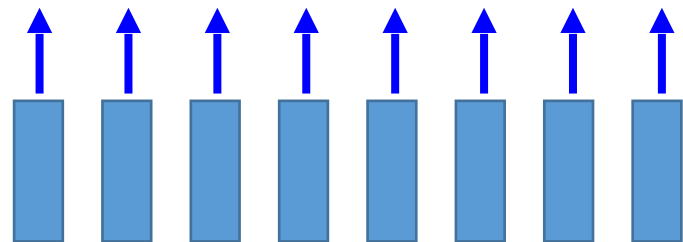
Trimming

Problem?

Why can't it be
"好棒棒"

好 好 好 棒 棒 棒 棒 棒

Input:

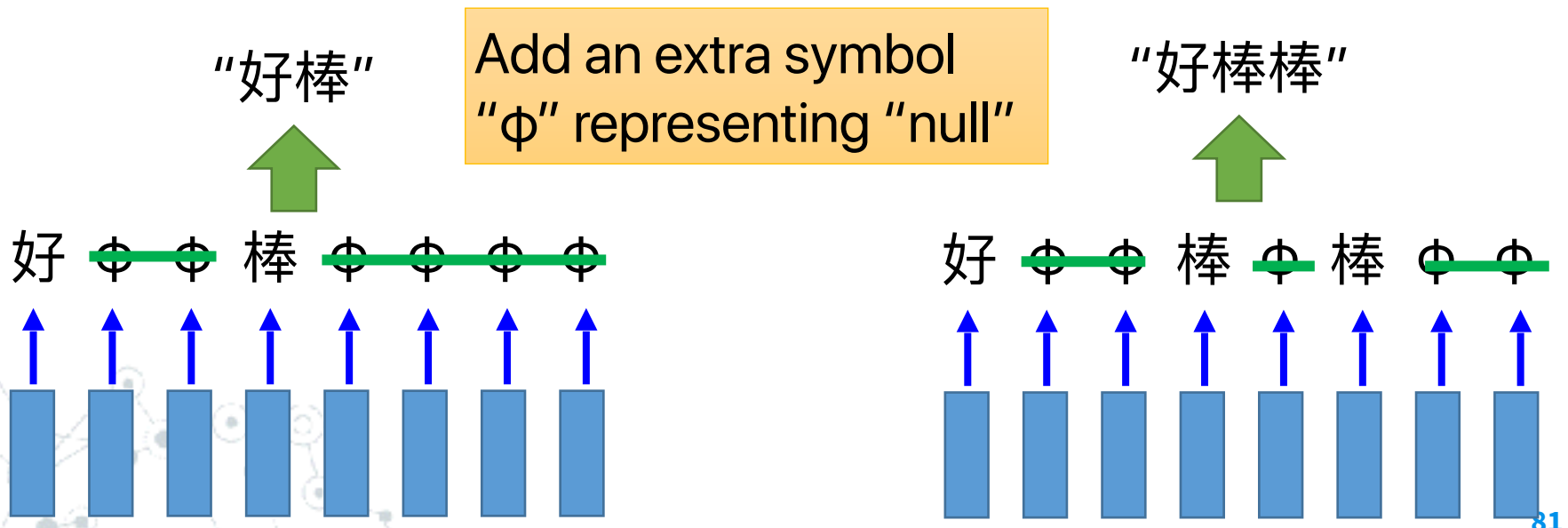


(vector
sequence

)

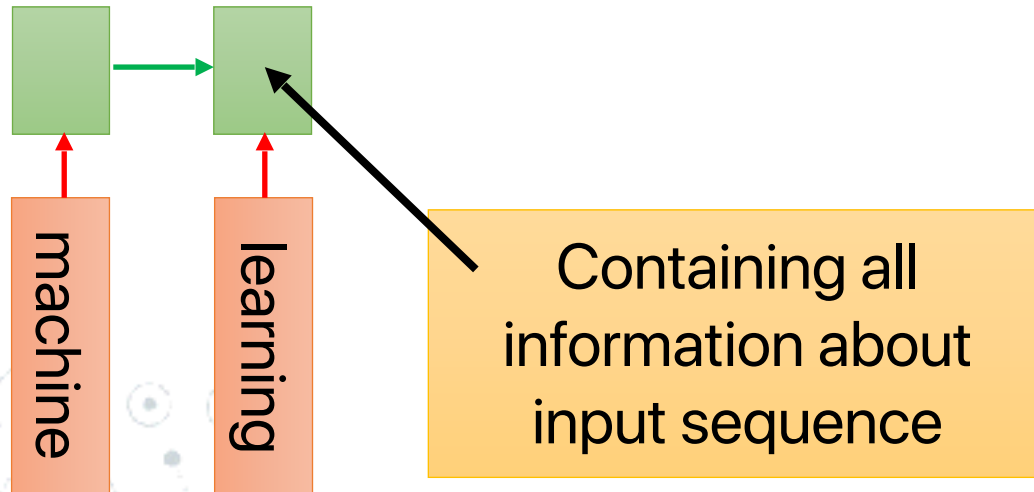
Many to Many (Output is shorter)

- ◎ Both input and output are both sequences, **but the output is shorter.**
- Connectionist Temporal Classification (CTC) [Alex Graves, ICML'06][Alex Graves, ICML'14][Haşim Sak, Interspeech'15][Jie Li, Interspeech'15][Andrew Senior, ASRU'15]



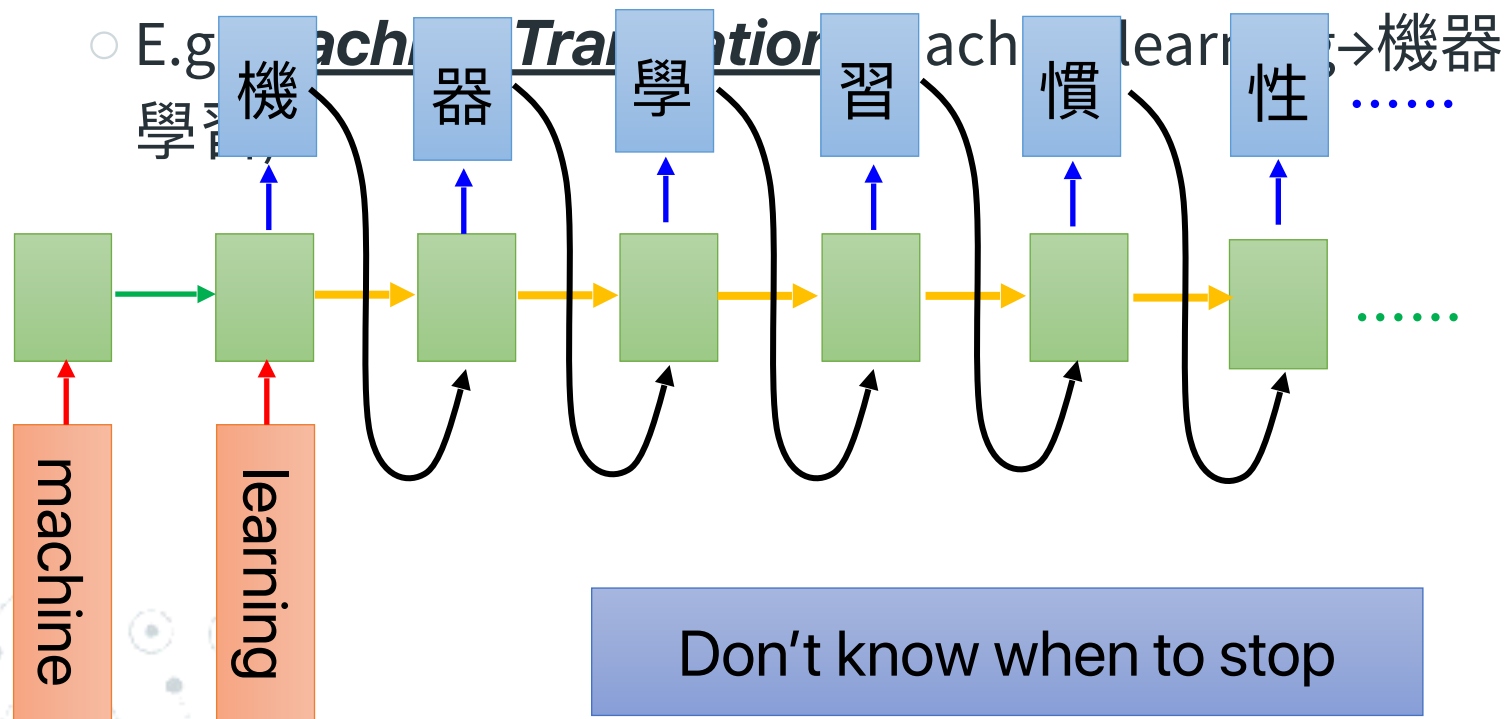
Many to Many (No Limitation)

- ◎ Both input and output are both sequences **with different lengths.** → **Sequence to sequence learning**
 - E.g. **Machine Translation** (machine learning → 機器學習)



Many to Many (No Limitation)

- Both input and output are both sequences with different lengths. → Sequence to sequence learning



Many to Many (No Limitation)

推	:	超	06/12 10:39
推	n:	人	06/12 10:40
推	tion:	正	06/12 10:41
→	host:	大	06/12 10:47
推	:	中	06/12 10:59
推	403:	天	06/12 11:11
推	:	外	06/12 11:13
推	527:	飛	06/12 11:17
→	990b:	仙	06/12 11:32
→	512:	草	06/12 12:15
推 tlkagk: =====斷=====			

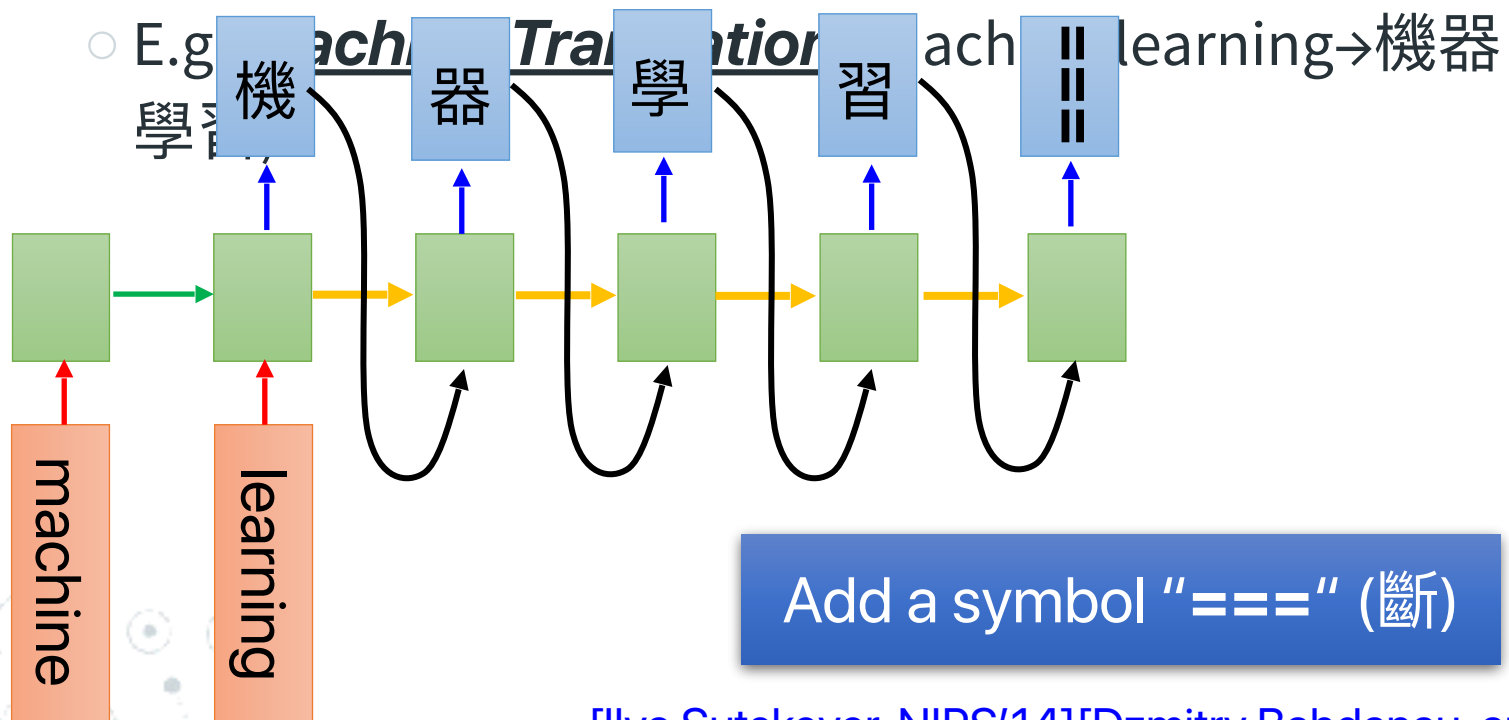
Ref:<http://zh.pttpedia.wikia.com/wiki/>

%E6%8E%A5%E9%BE%8D%E6%8E%A8%E6%96%87 (鄉民百

科)

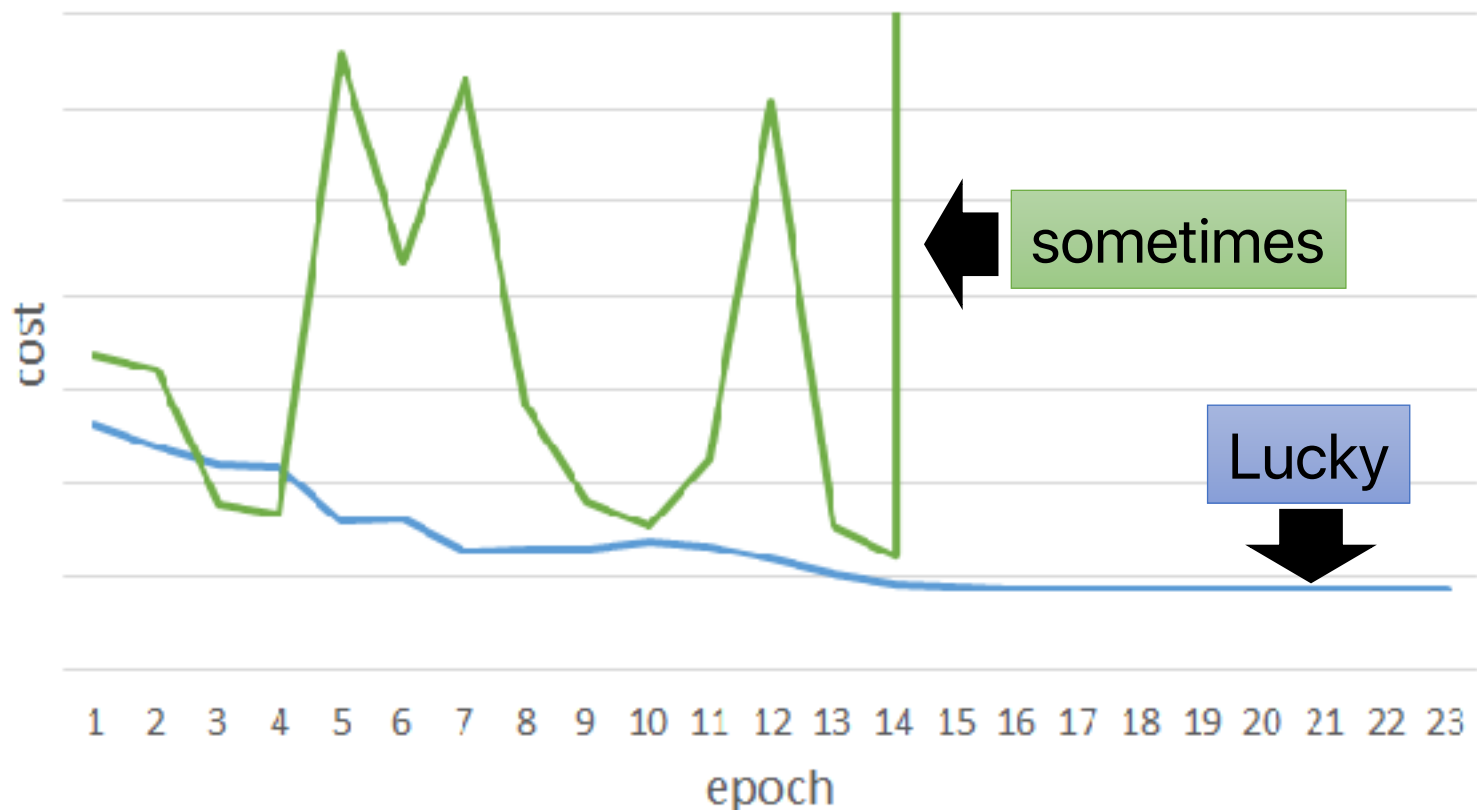
Many to Many (No Limitation)

- Both input and output are both sequences with different lengths. → Sequence to sequence learning

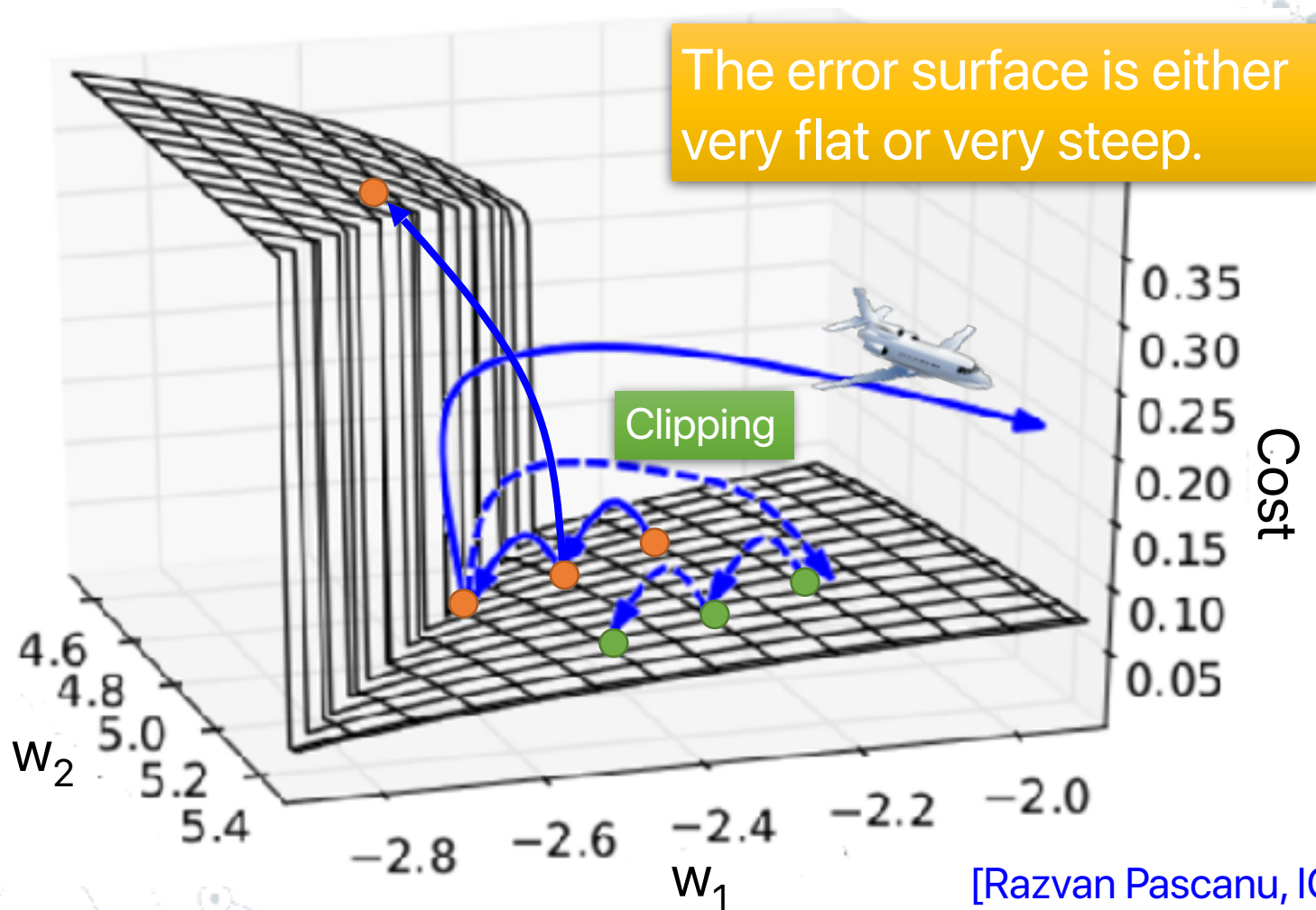


Unfortunately

- ◎ RNN-based network is not always easy to learn
- Real experiments on Language modeling



The error surface is rough.



[Razvan Pascanu, ICML'13]

Why?

$$w = 1 \rightarrow y^{1000} = 1$$

$$w = 1.01 \rightarrow y^{1000} \approx 20000$$

$$w = 0.99 \rightarrow y^{1000} \approx 0$$

$$w = 0.01 \rightarrow y^{1000} \approx 0$$

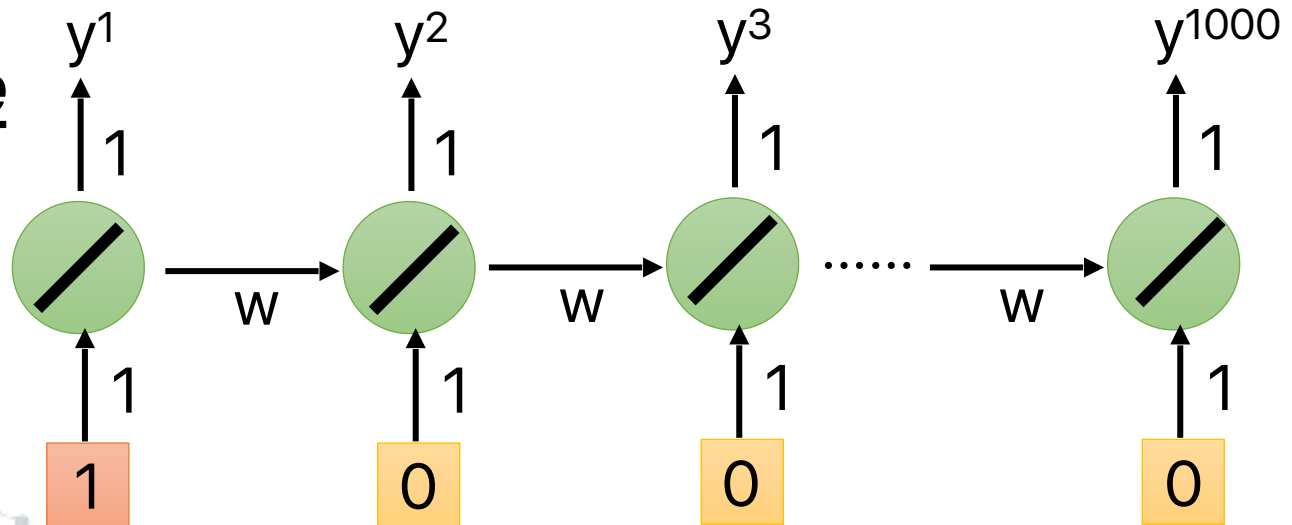
Large
gradient

small
gradient

Small
Learning
rate?
Large
Learning
rate?

$= w^{999}$

Toy Example



Helpful Techniques

◎ Nesterov's Accelerated Gradient (NAG):

- Advance momentum method

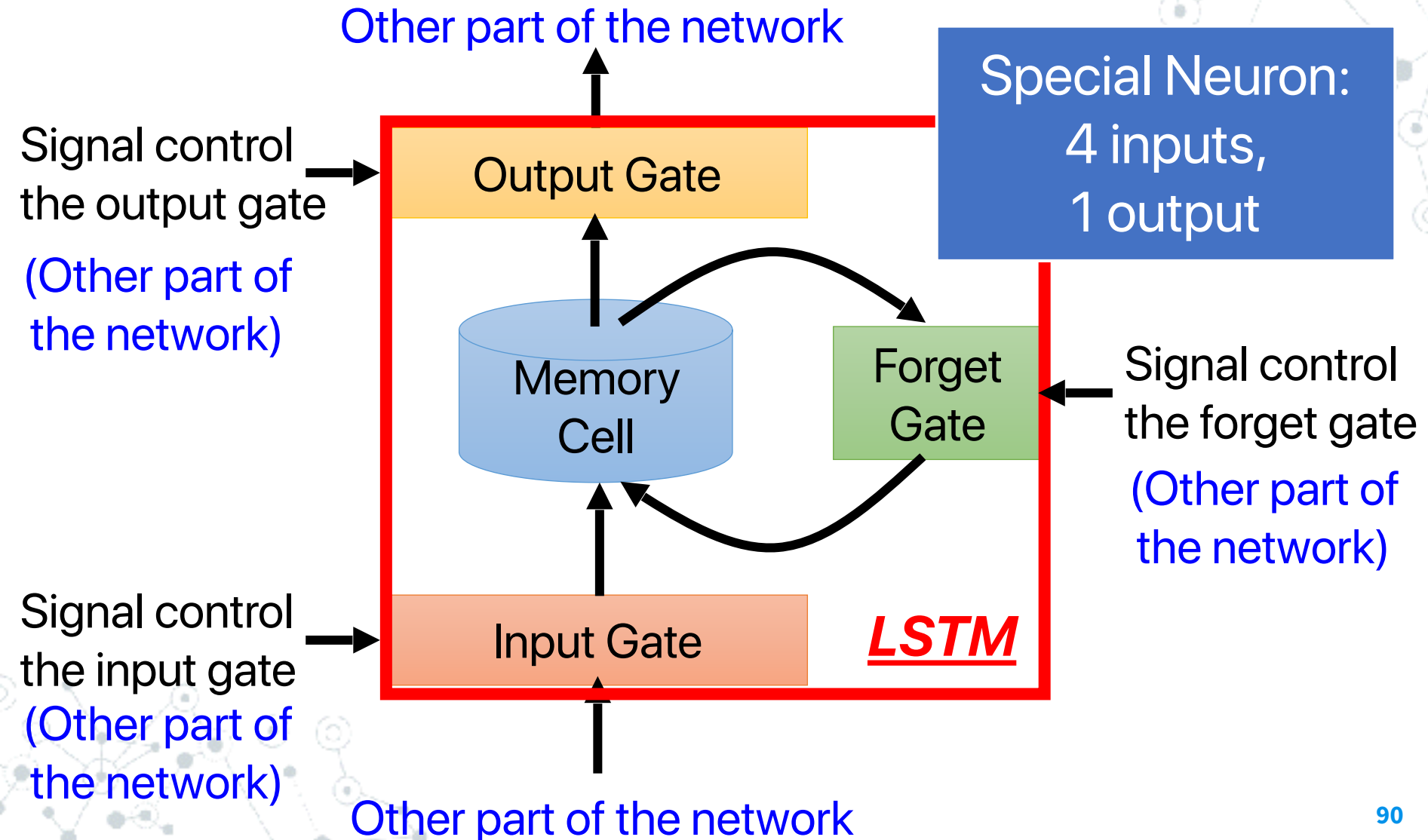
◎ RMS Prop

- Advanced approach to give each parameter different learning rates
- Considering the change of Second derivatives

◎ Long Short-term Memory (LSTM)

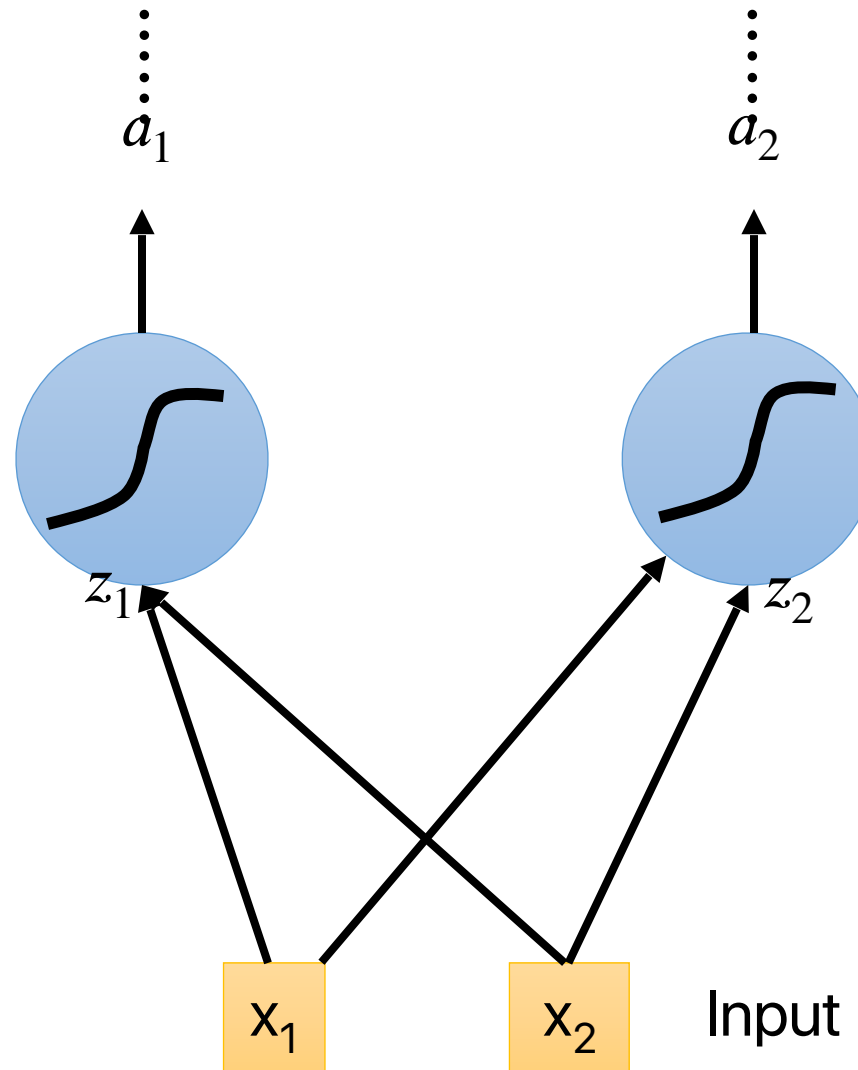
- Can deal with gradient vanishing (not gradient explode)

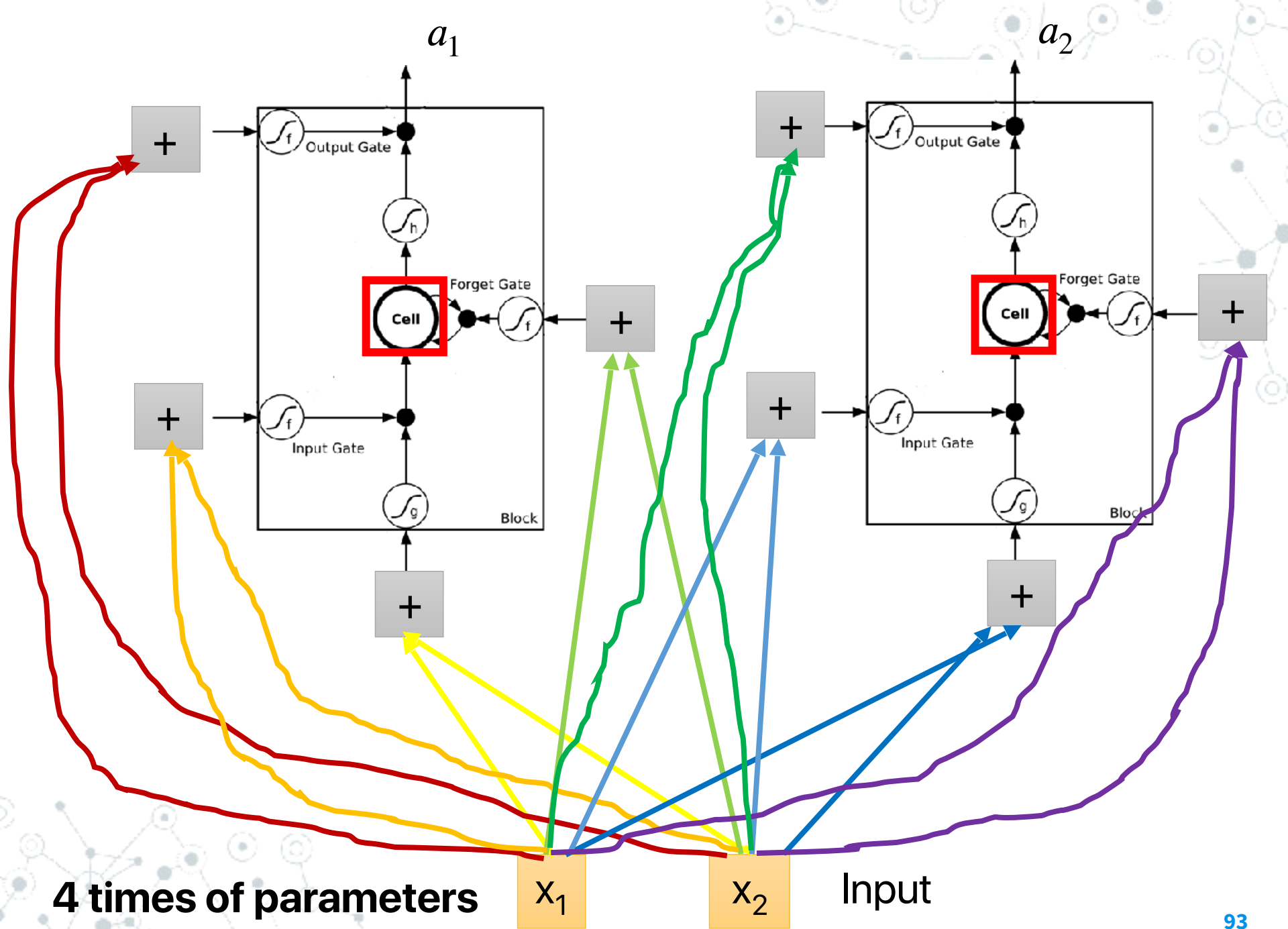
Long Short-term Memory (LSTM)



Original Network:

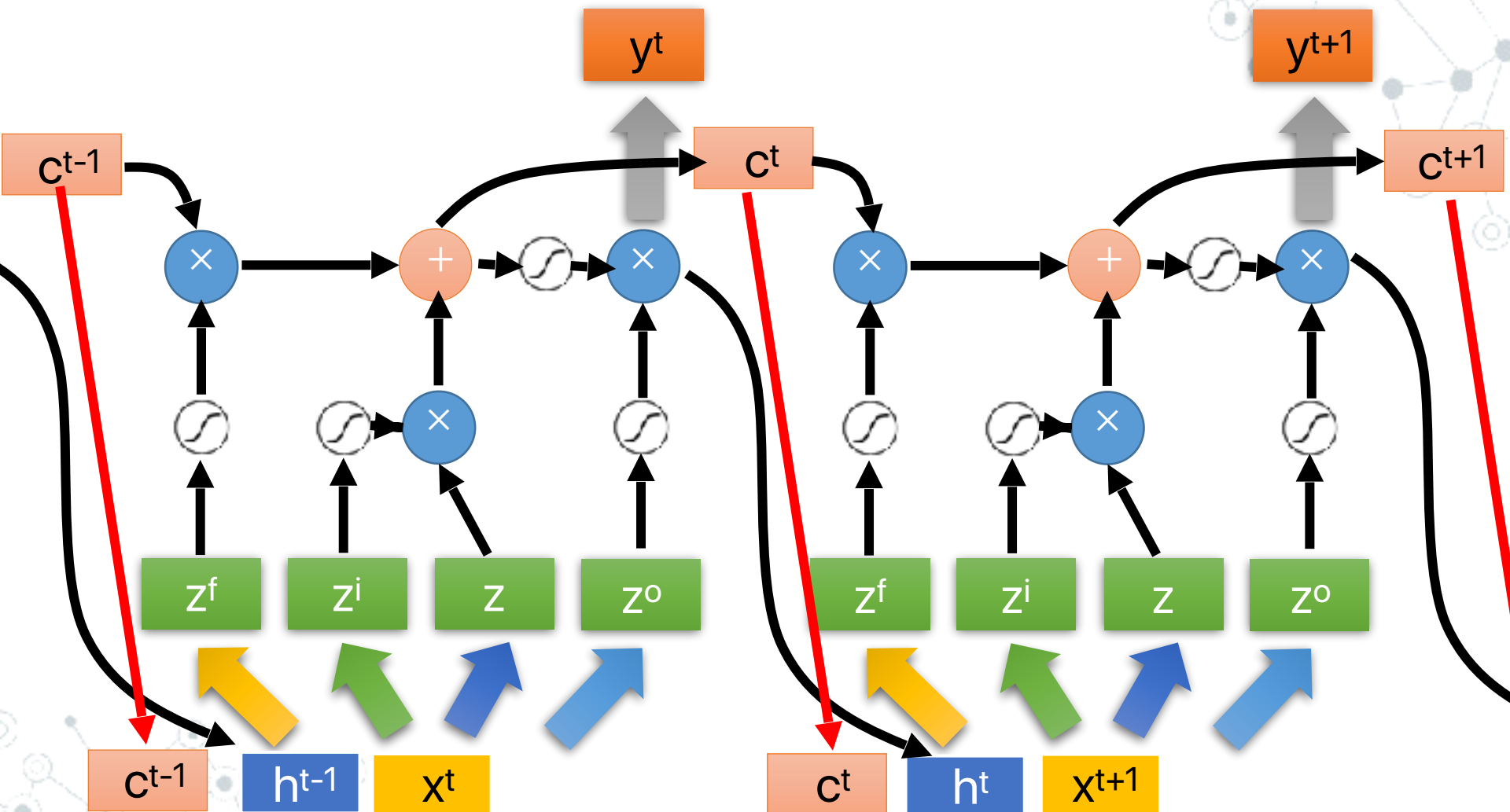
- Simply replace the neurons with LSTM





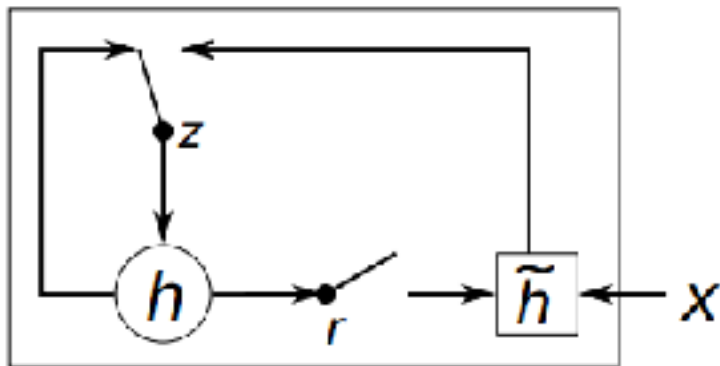
LSTM

Extension: "peephole"



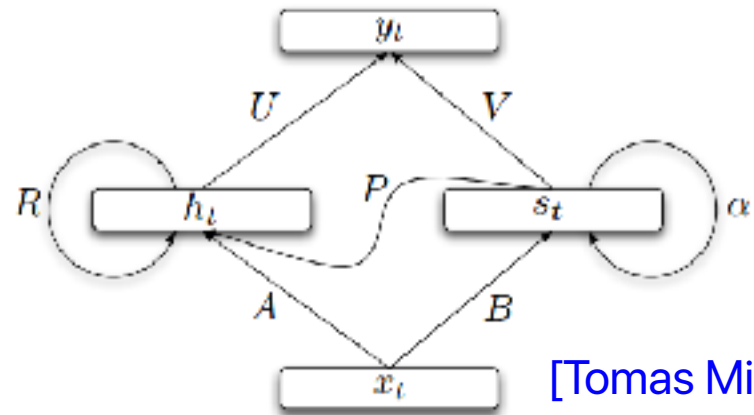
Other Simpler Alternatives

Gated Recurrent Unit (GRU)



[Cho, EMNLP'14]

Structurally Constrained Recurrent Network (SCRN)



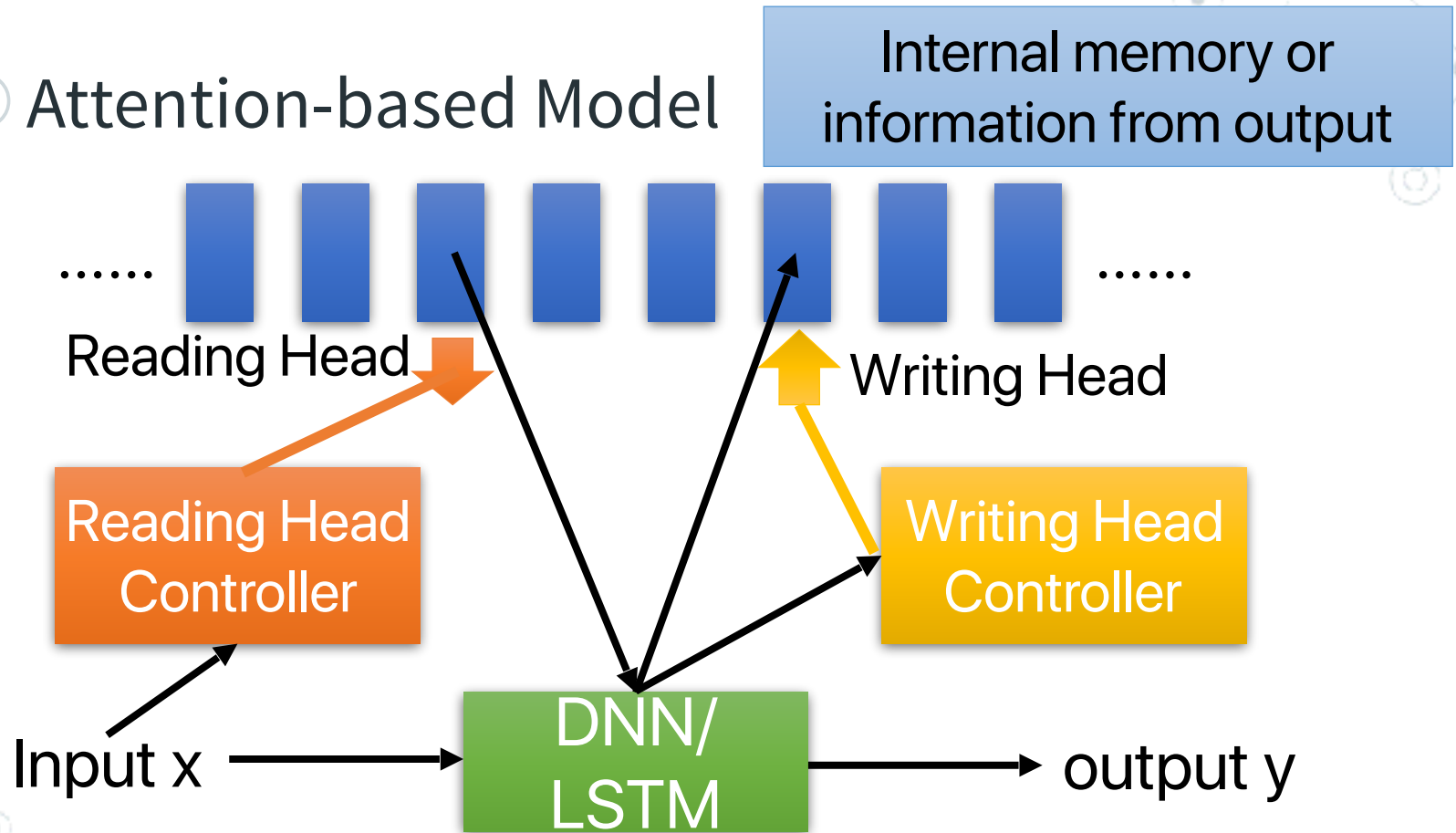
[Tomas Mikolov, ICLR'15]

Vanilla RNN Initialized with Identity matrix + ReLU activation function [Quoc V. Le, arXiv'15]

➤ Outperform or be comparable with LSTM in 4 different tasks

What is the next wave?

◎ Attention-based Model



Already applied on speech recognition, caption generation, QA, visual QA

What is the next wave?

◎ Attention-based Model

- ◎ End-To-End Memory Networks. S. Sukhbaatar, A. Szlam, J. Weston, R. Fergus. arXiv Pre-Print, 2015.
- ◎ Neural Turing Machines. Alex Graves, Greg Wayne, Ivo Danihelka. arXiv Pre-Print, 2014
- ◎ Ask Me Anything: Dynamic Memory Networks for Natural Language Processing. Kumar et al. arXiv Pre-Print, 2015
- ◎ Neural Machine Translation by Jointly Learning to Align and Translate. D. Bahdanau, K. Cho, Y. Bengio; International Conference on Representation Learning 2015.
- ◎ Show, Attend and Tell: Neural Image Caption Generation with Visual Attention. Kelvin Xu et. al.. arXiv Pre-Print, 2015.
- ◎ Attention-Based Models for Speech Recognition. Jan Chorowski, Dzmitry Bahdanau, Dmitriy Serdyuk, Kyunghyun Cho, Yoshua Bengio. arXiv Pre-Print, 2015.
- ◎ Recurrent models of visual attention. V. Mnih, N. Hees, A. Graves and K. Kavukcuoglu. In NIPS, 2014.
- ◎ A Neural Attention Model for Abstractive Sentence Summarization. A. M. Rush, S. Chopra and J. Weston. EMNLP 2015.

A decorative network diagram in the top-left corner, consisting of a complex web of interconnected nodes and lines. The nodes are represented by small circles, some of which are solid grey and others are hollow with a grey outline. The lines are thin and grey, connecting the nodes in a non-linear fashion.

Concluding Remarks

A decorative network diagram in the bottom-right corner, similar to the one in the top-left. It features a cluster of interconnected nodes and lines. The nodes are small circles, some solid grey and some hollow with a grey outline, connected by thin grey lines.

Concluding Remarks

- ◎ Introduction of deep learning
- ◎ Discussing some reasons using deep learning
- ◎ New techniques for deep learning
 - ReLU, Maxout
 - Giving all the parameters different learning rates
 - Dropout
- ◎ Network with memory
 - Recurrent neural network
 - Long short-term memory (LSTM)

Reading Materials

- ◎ “Neural Networks and Deep Learning”
 - written by Michael Nielsen
 - <http://neuralnetworksanddeeplearning.com/>
- ◎ “Deep Learning” (not finished yet)
 - Written by Yoshua Bengio, Ian J. Goodfellow and Aaron Courville
 - <http://www.iro.umontreal.ca/~bengioy/dlbook/>

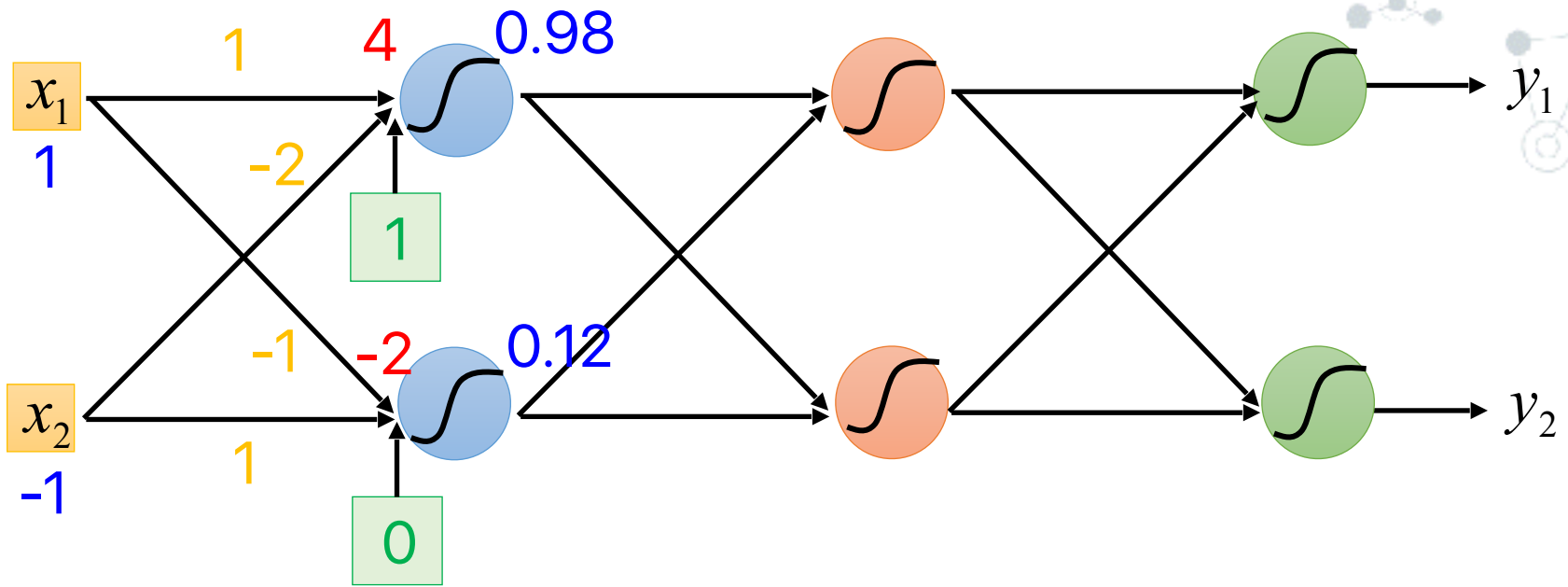


Thank you!



Appendix

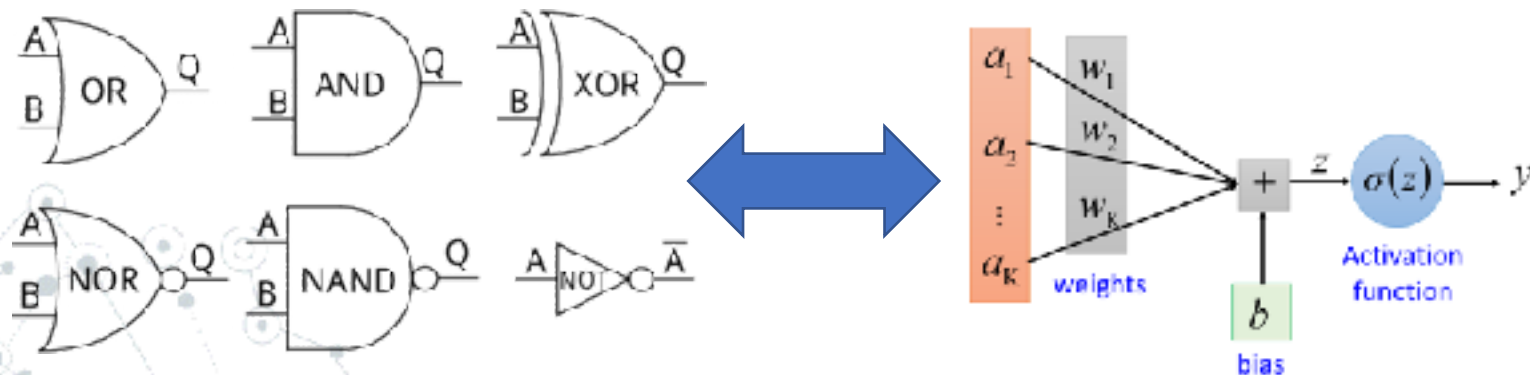
Matrix Operation



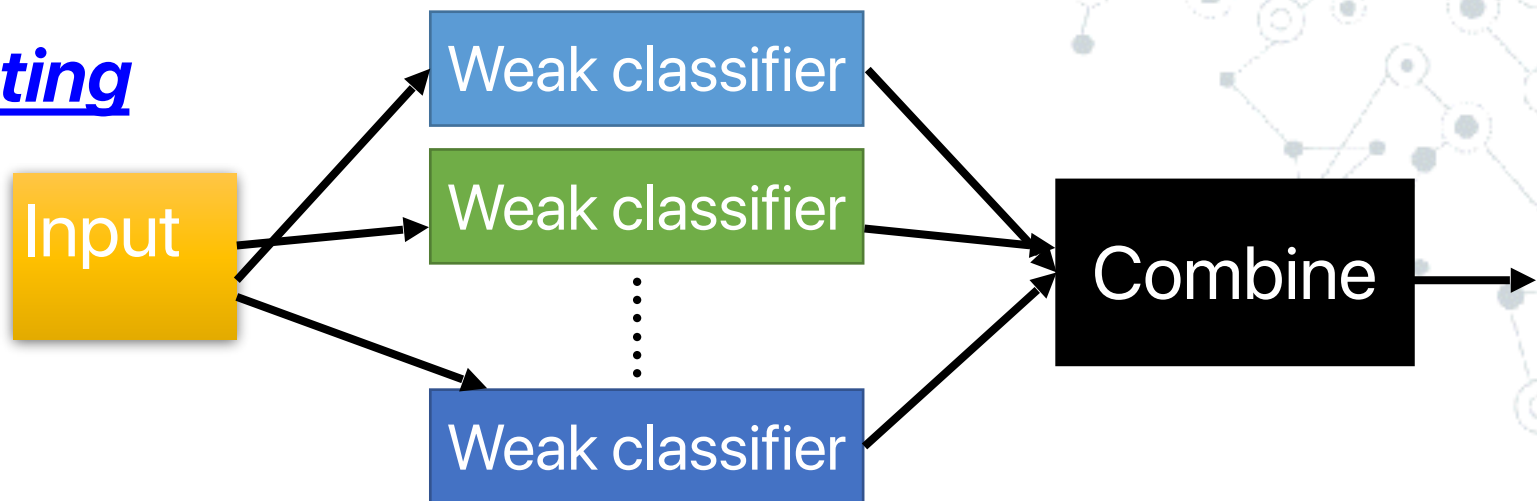
$$\sigma \left(\begin{matrix} \text{W} \end{matrix} \begin{matrix} \text{x} \end{matrix} \right) + \begin{matrix} \text{b} \end{matrix} = \begin{matrix} \begin{matrix} \text{a} \end{matrix} \end{matrix}$$

Why Deep? – Logic Circuits

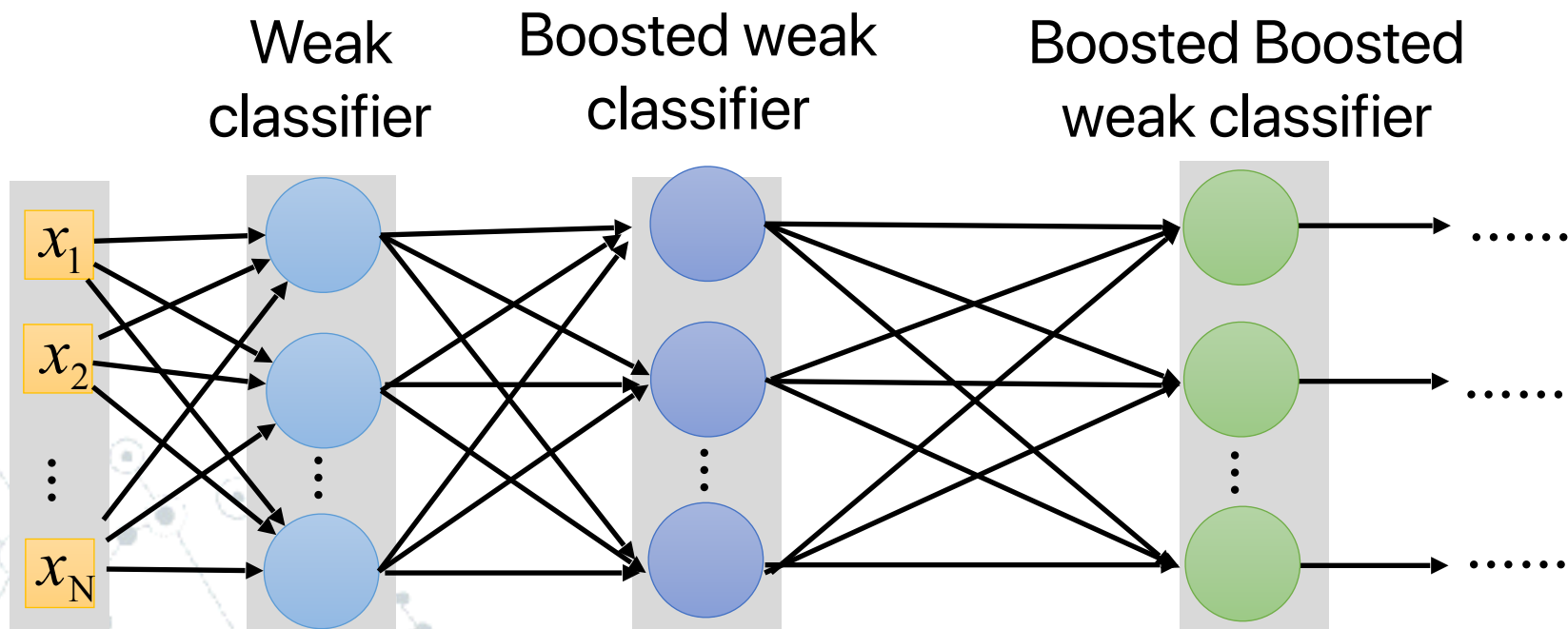
- ◎ A two levels of basic logic gates can represent any Boolean function.
- ◎ However, no one uses two levels of logic gates to build computers
- ◎ Using multiple layers of logic gates to build some functions are much simpler (less gates needed).



Boosting

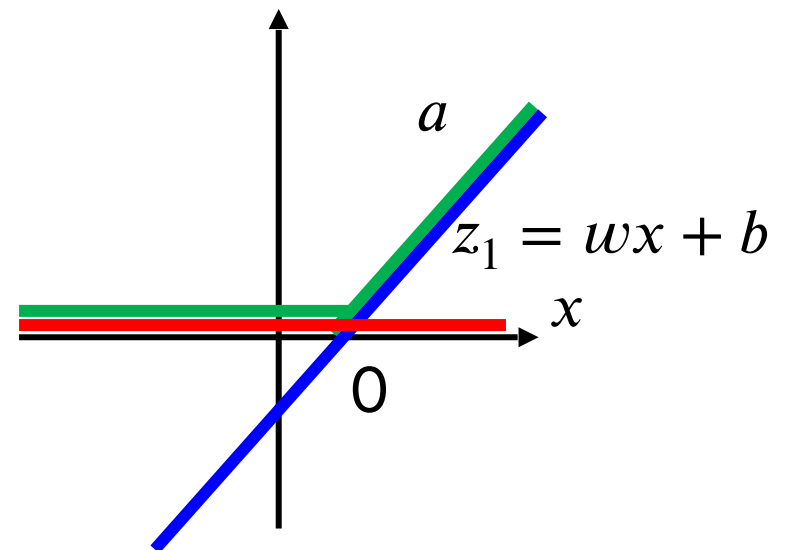
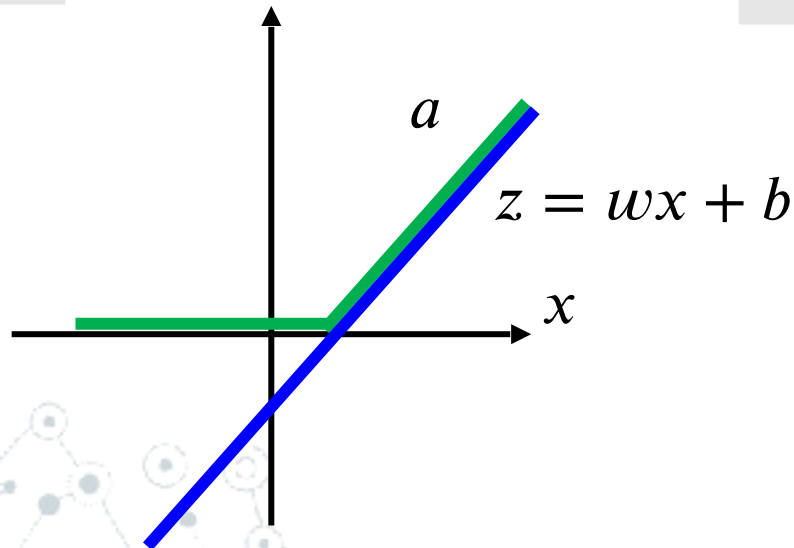
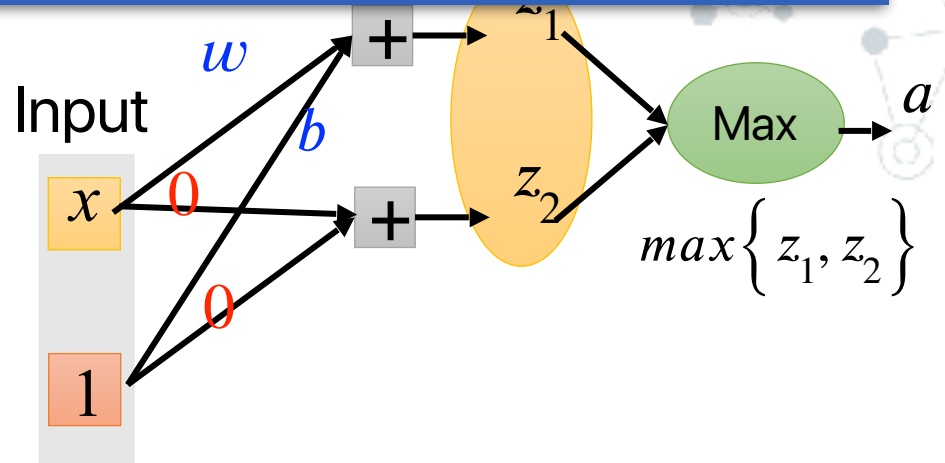
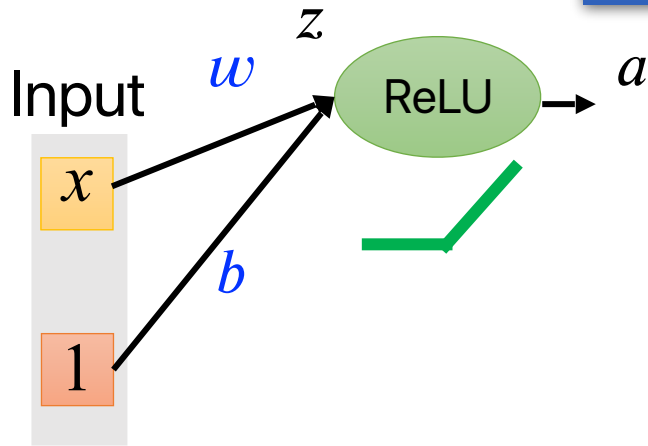


Deep Learning



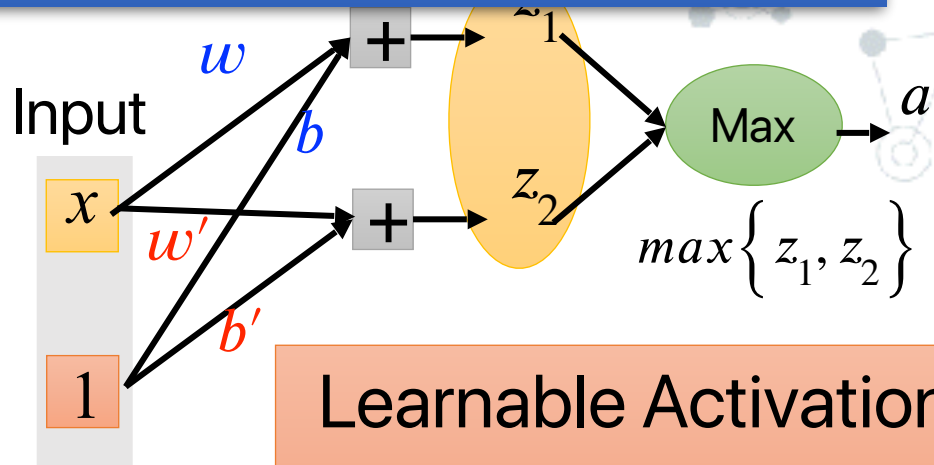
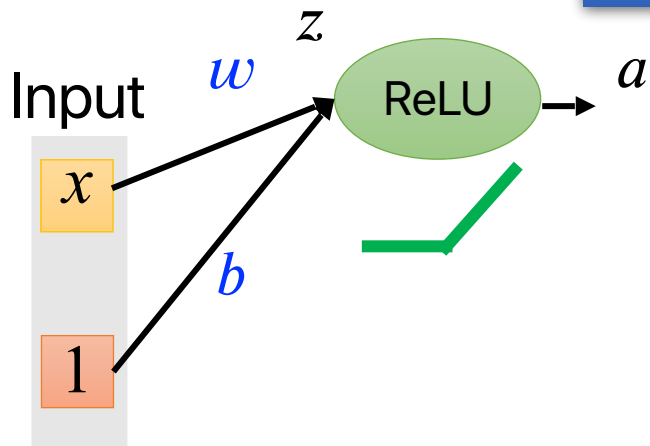
Maxout

ReLU is a special cases of Maxout

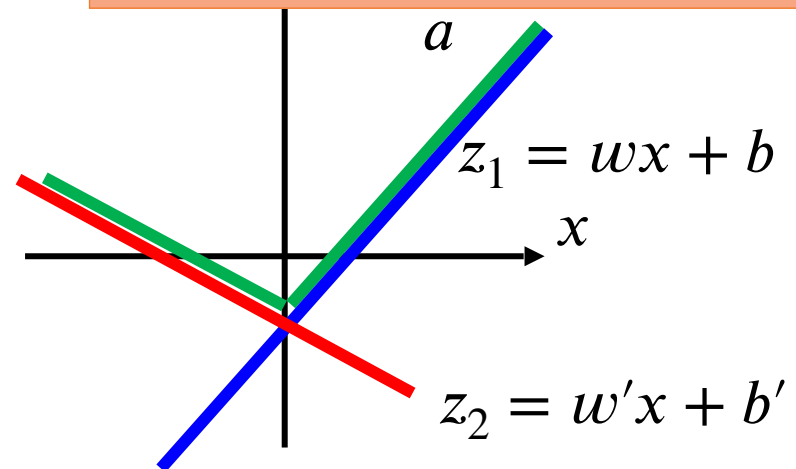
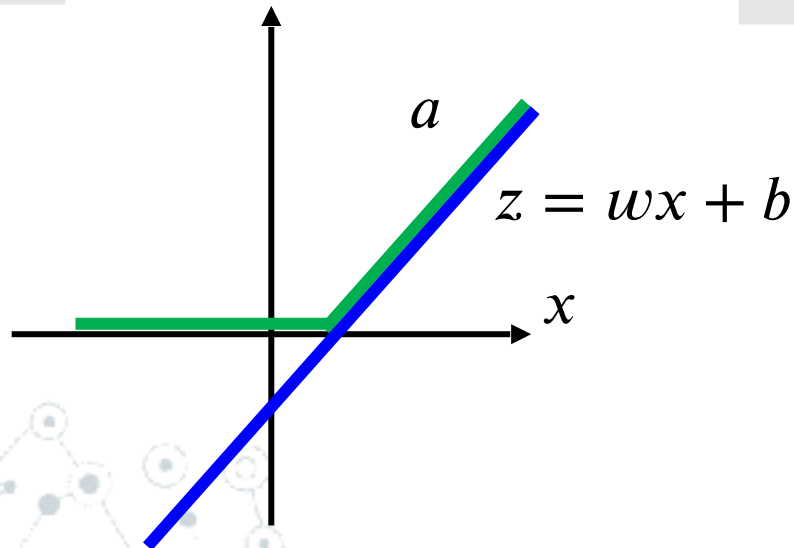


Maxout

ReLU is a special cases of Maxout



Learnable Activation Function


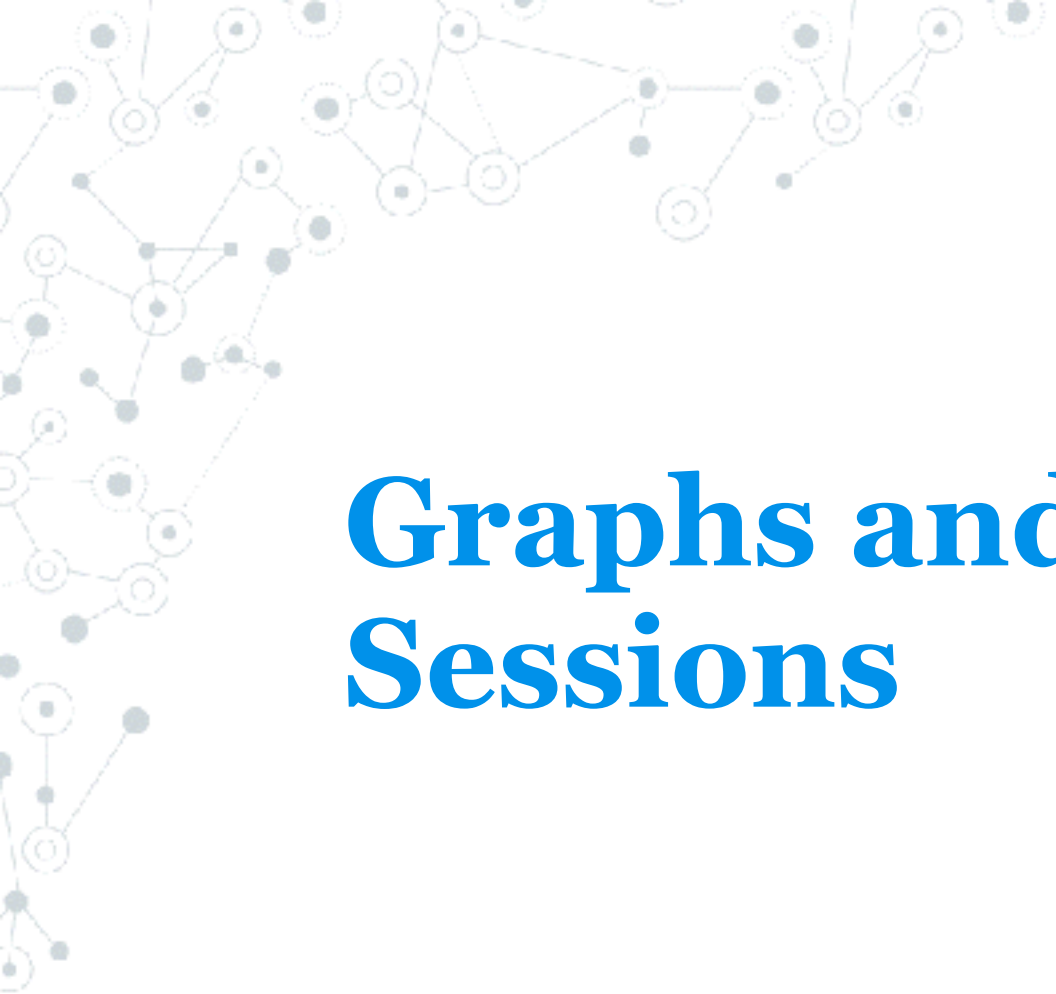


A decorative background featuring a network diagram. It consists of numerous nodes, represented by small circles of varying shades of gray, connected by thin, light gray lines. The nodes are distributed across the page, with higher concentrations in the top-left and bottom-right corners, creating a sense of connectivity and structure.

Getting Started



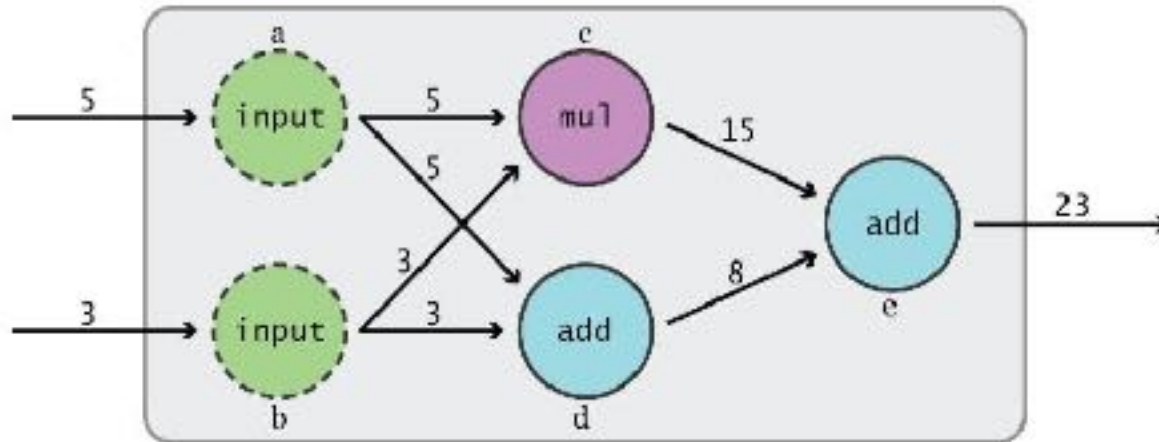
```
import  
tensorflow as tf
```



Graphs and Sessions

Data Flow Graphs

TensorFlow separates definition of computations from their execution

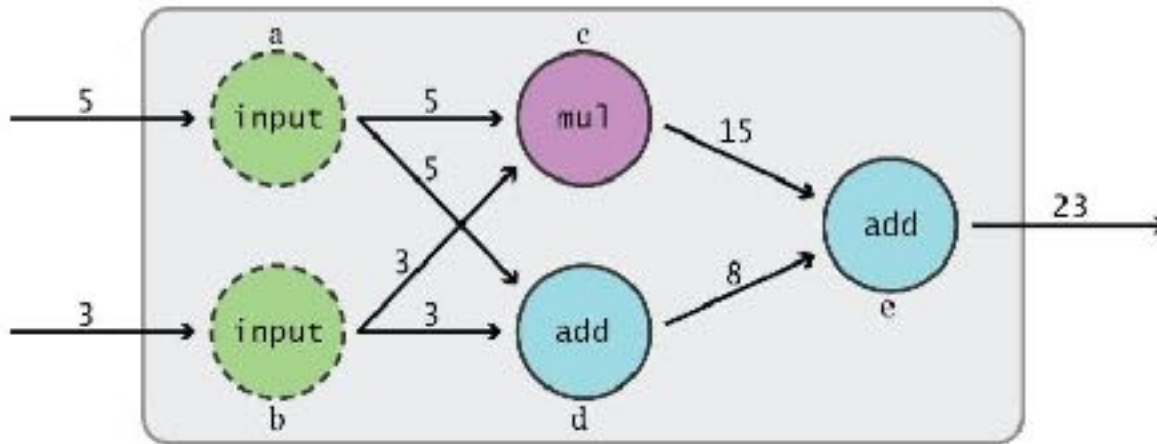


Graph from *TensorFlow for Machine Intelligence*

Data Flow Graphs

Phase 1: assemble a graph

Phase 2: use a session to execute operations in the graph

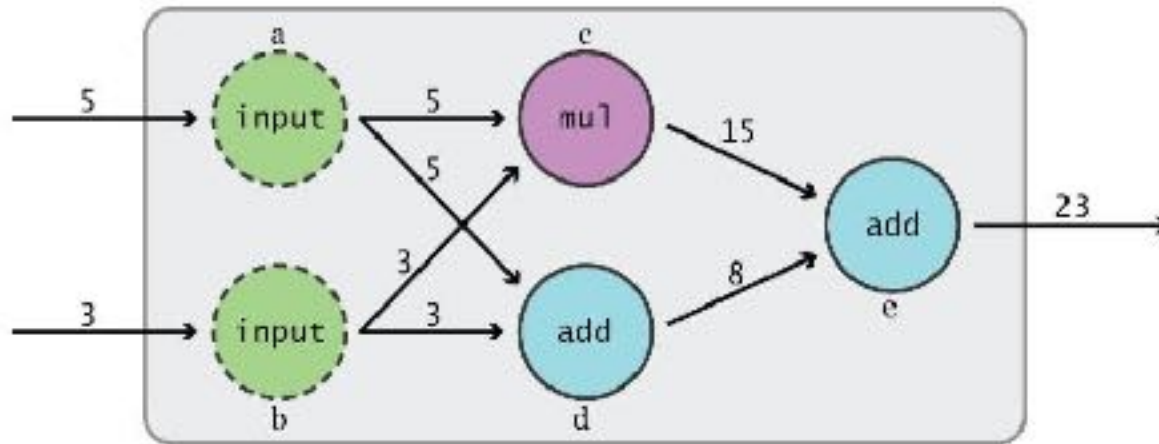


Graph from *TensorFlow for Machine Intelligence*

Data Flow Graphs

Phase 1: assemble a graph

Phase 2: use a session to execute operations in the graph



Graph from *TensorFlow for Machine Intelligence*

A decorative background featuring a network diagram with nodes and edges, primarily located in the top-left and bottom-right corners. The nodes are represented by circles of varying sizes, some containing smaller circles or squares, and are connected by thin, light gray lines. The overall style is minimalist and technical.

What's a tensor?



What's a tensor?

An n-dimensional array

0-d tensor: scalar (number)

1-d tensor: vector

2-d tensor: matrix

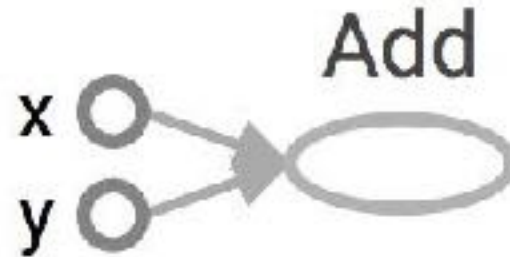
and so on



Data Flow Graphs

```
import tensorflow as tf  
a = tf.add(3, 5)
```

Visualized by TensorBoard



Data Flow Graphs

```
import tensorflow as tf  
a = tf.add(3, 5)
```

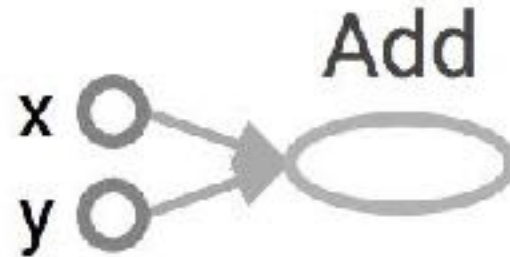
Visualized by TensorBoard

Why x, y?

TF automatically names the nodes when you don't explicitly name them.

x = 3

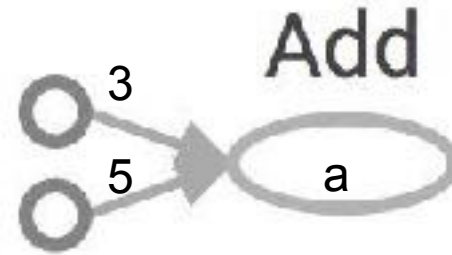
y = 5



Data Flow Graphs

```
import tensorflow as tf  
a = tf.add(3, 5) Interpreted?
```

Nodes: operators, variables, and constants
Edges: tensors



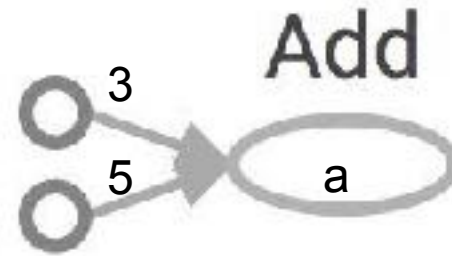
Data Flow Graphs

```
import tensorflow as tf  
a = tf.add(3, 5) Interpreted?
```

Nodes: operators, variables, and constants
Edges: tensors

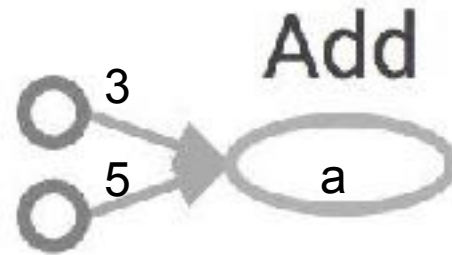
Tensors are data.

TensorFlow = tensor + flow = data + flow



Data Flow Graphs

```
import tensorflow as tf  
a = tf.add(3, 5)  
print(a)
```



```
>> Tensor("Add:0", shape=(),  
dtype=int32)  
(Not 8)
```




How to get the value of a?

Create a **session**, assign it to variable sess so we can call it later

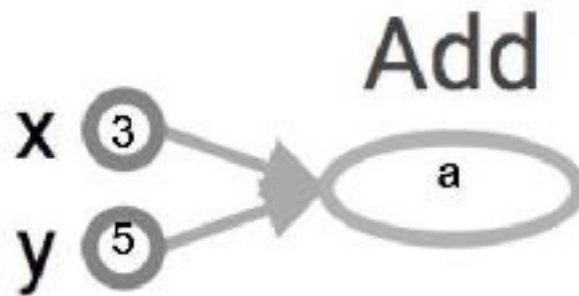
Within the session, evaluate the graph to fetch the value of a

How to get the value of a?

Create a **session**, assign it to variable `sess` so we can call it later

Within the session, evaluate the graph to fetch the value of `a`

```
import tensorflow as tf
a = tf.add(3, 5)
sess = tf.Session()
print(sess.run(a))
sess.close()
```

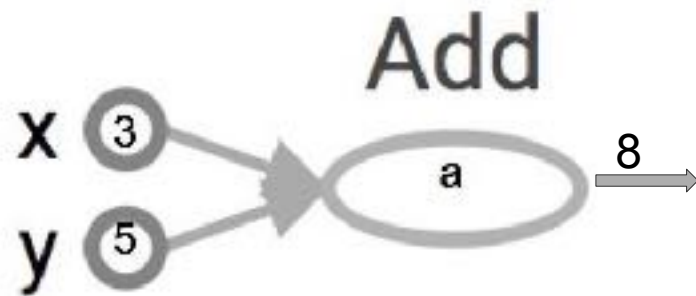


How to get the value of a?

Create a **session**, assign it to variable `sess` so we can call it later

Within the session, evaluate the graph to fetch the value of `a`

```
>>> 8
import tensorflow as tf
a = tf.add(3, 5)
sess = tf.Session()
print(sess.run(a))
sess.close()
```

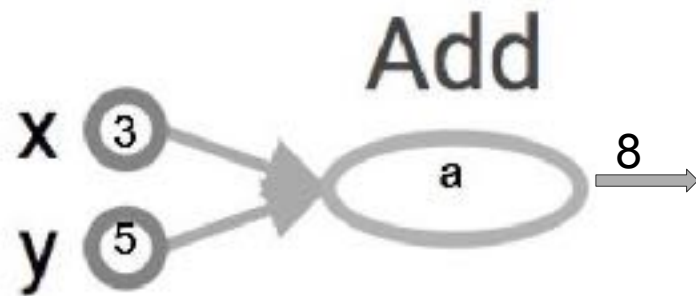


How to get the value of a?

Create a **session**, assign it to variable `sess` so we can call it later

Within the session, evaluate the graph to fetch the value of `a`

```
import tensorflow as tf
a = tf.add(3, 5)
sess = tf.Session()
with tf.Session() as sess:
    print(sess.run(a))
sess.close()
```





tf.Session()

A Session object encapsulates the environment in which Operation objects are executed, and Tensor objects are evaluated.

`tf.Session()`

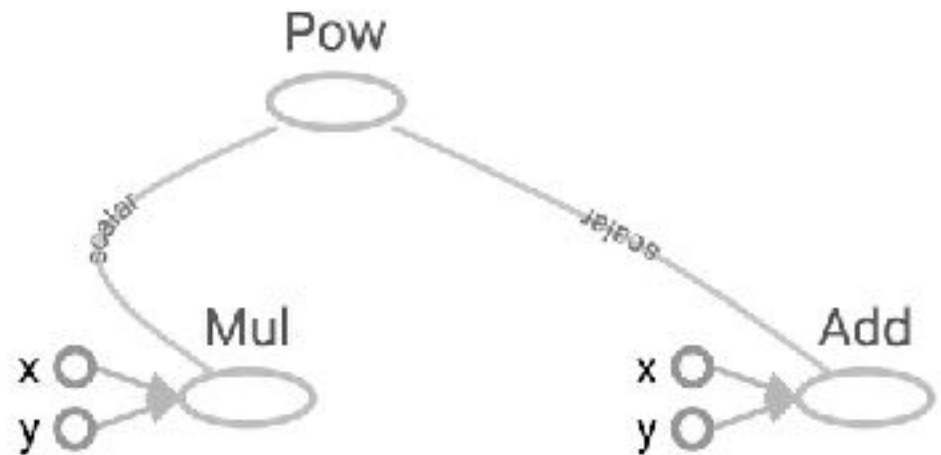
A Session object encapsulates the environment in which Operation objects are executed, and Tensor objects are evaluated.

Session will also allocate memory to store the current values of variables.

More graph

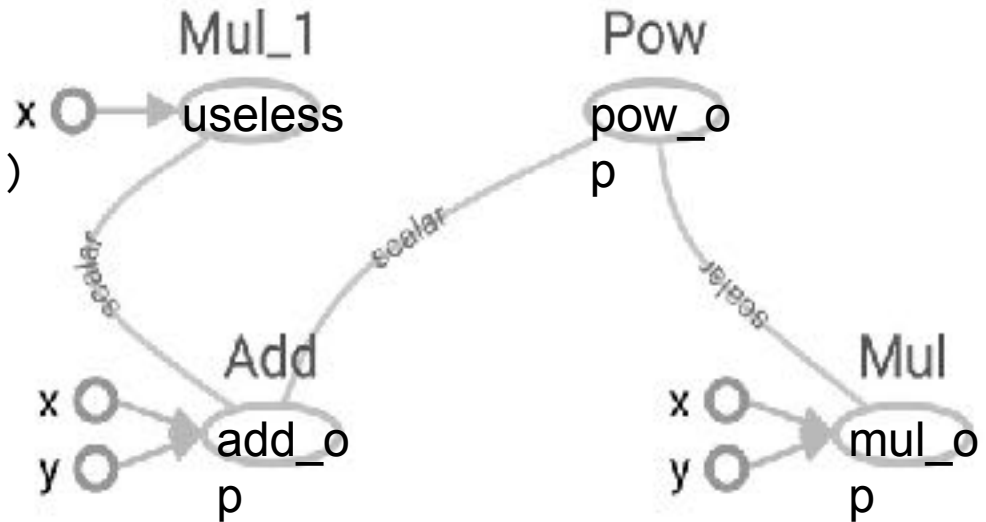
```
x = 2
y = 3
op1 = tf.add(x, y)
op2 = tf.multiply(x, y)
op3 = tf.pow(op2, op1)
with tf.Session() as sess:
    op3 = sess.run(op
```

Visualized by TensorBoard



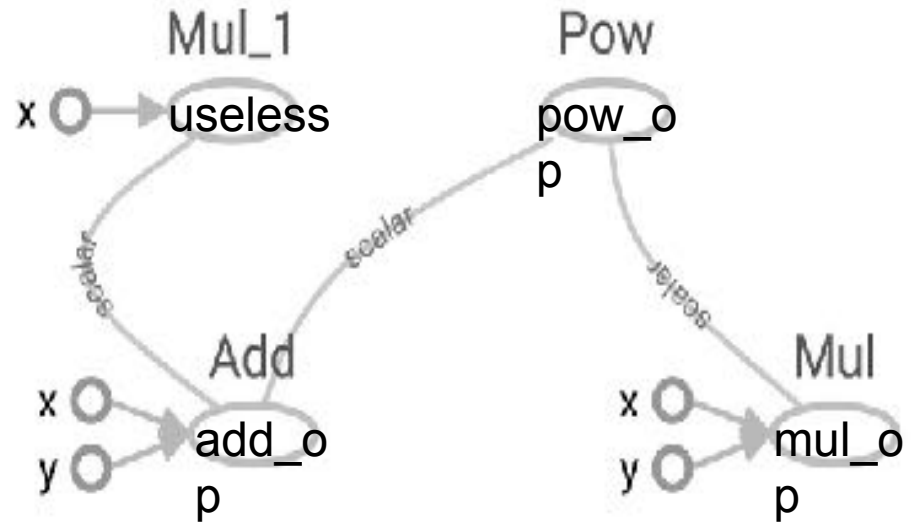
Subgraphs

```
x = 2
y = 3
add_op = tf.add(x, y)
mul_op = tf.multiply(x, y)
useless = tf.multiply(x, add_op)
pow_op = tf.pow(add_op, mul_op)
with tf.Session() as sess:
    z = sess.run(pow_op)
```



Subgraphs

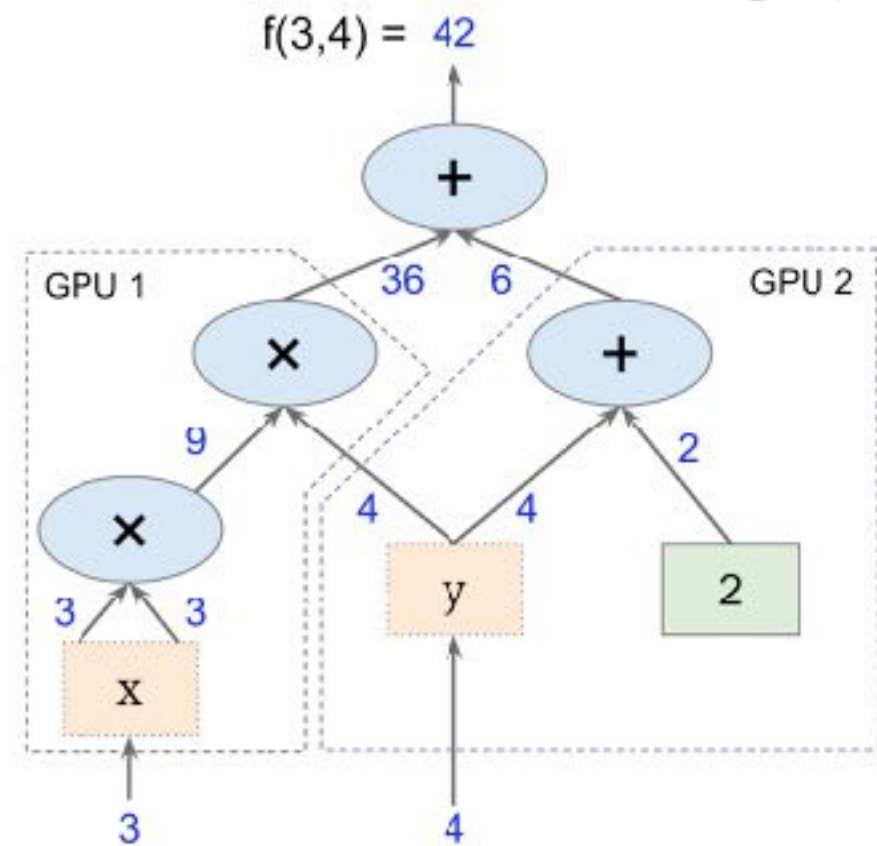
```
x = 2
y = 3
add_op = tf.add(x, y)
mul_op = tf.multiply(x, y)
useless = tf.multiply(x, add_op)
pow_op = tf.pow(add_op, mul_op)
with tf.Session() as sess:
    z, not_useless = sess.run
```



Subgraphs

Possible to break graphs into several chunks and run them parallelly across multiple CPUs, GPUs, TPUs, or other devices

Example: AlexNet



Graph from *Hands-On Machine Learning with Scikit-Learn and TensorFlow*

Distributed Computation

To put part of a graph on a specific CPU or GPU:

```
# Creates a graph.  
with tf.device('/gpu:2'):  
    a = tf.constant([1.0, 2.0, 3.0, 4.0, 5.0, 6.0], name='a')  
    b = tf.constant([1.0, 2.0, 3.0, 4.0, 5.0, 6.0], name='b')  
    c = tf.multiply(a, b)  
  
# Creates a session with log_device_placement set to True.  
sess =  
tf.Session(config=tf.ConfigProto(log_device_placement=True))  
  
# Runs the op.  
print(sess.run(c))
```

tf.Graph()

create a graph:

```
g = tf.Graph()
```

tf.Graph()

to add operators to a graph, set it as default:

```
g = tf.Graph()
with g.as_default():
    x = tf.add(3, 5)
sess = tf.Session(graph=g)
with tf.Session() as sess:
    sess.run(x)
```

tf.Graph()

To handle the default graph:

```
g = tf.get_default_graph()
```

tf.Graph()

Do not mix default graph and user created graphs

```
g = tf.Graph()

# add ops to the default graph
a = tf.constant(3)

# add ops to the user created graph
with g.as_default():
    b = tf.constant(5)
```

tf.Graph()

Do not mix default graph and user created graphs

```
g1 = tf.get_default_graph()
g2 = tf.Graph()

# add ops to the default graph
with g1.as_default():
    a = tf.Constant(3)

# add ops to the user created graph
with g2.as_default():
    b = tf.Constant(5)
```


A decorative background featuring a network diagram with nodes and connecting lines, primarily located in the top-left and bottom-right corners.

Install Tensorflow



Install Tensorflow

To install the library we will create an environment in Anaconda with **python 3.5** we name it **tensorflow**. However, you may choose your own desired name for it. Open command prompt (or terminal) and type:

```
conda create --name tensorflow python=3.5
```

Once the environment is created, we can activate the environment:

(for Windows):

```
activate tensorflow
```

(for Linux & Mac):

```
source activate tensorflow
```



(for Windows):

(CPU version):

```
pip install --upgrade tensorflow
```

(GPU version):

```
pip install --upgrade tensorflow-gpu
```

For Mac - CPU

```
pip install --ignore-installed --upgrade https://storage.googleapis.com/tensorflow/mac/cpu/tensorflow-1.10.0-py3-none-any.whl
```



For Linux - CPU

```
pip install --ignore-installed --upgrade https://storage.googleapis.com/tensorflow/linux/cpu/tensorflow-1.10.0-cp35-cp35m-linux_x86_64.whl
```

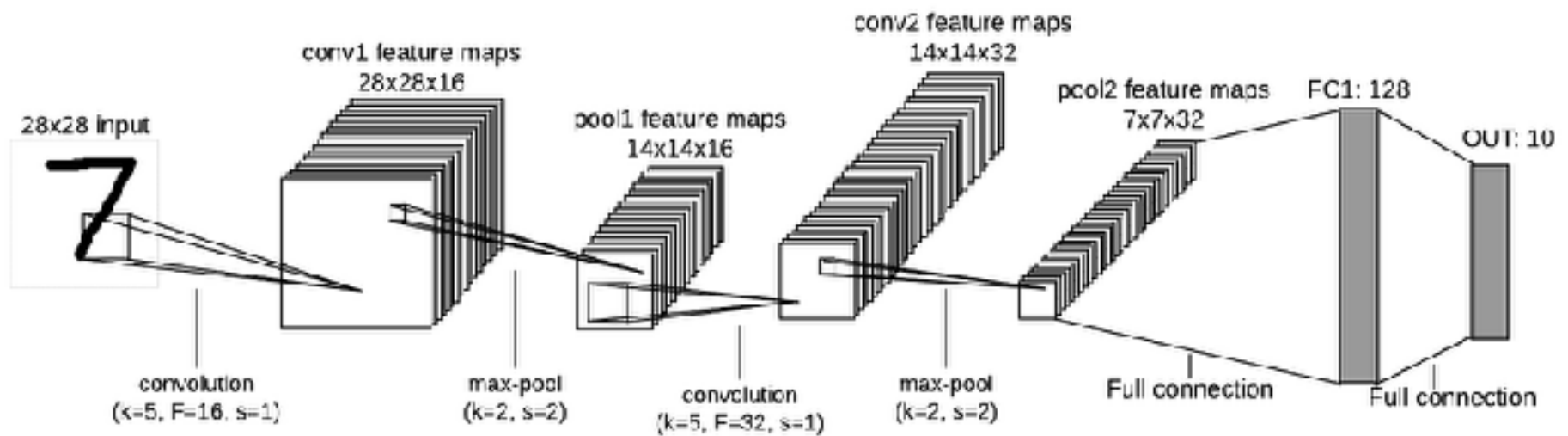
For Linux - GPU

```
pip install --ignore-installed --upgrade https://storage.googleapis.com/tensorflow/linux/gpu/tensorflow_gpu-1.10.0-cp35-cp35m-linux_x86_64.whl
```

Install Jupiter

◎ `conda install jupyter`

CNN (Convolution Neural Networks)



A decorative network diagram in the top-left corner, featuring a complex web of interconnected nodes and lines. The nodes are represented by small circles, some of which are larger and have concentric circles inside, suggesting a hierarchical or multi-layered structure. The lines are thin and gray, connecting the nodes in a non-linear fashion.

**See Jupiter
Notebook**

A decorative network diagram in the bottom-right corner, similar to the one in the top-left. It shows a cluster of nodes connected by lines, with some nodes being larger and having concentric circles, indicating a similar hierarchical or multi-layered structure. The lines are thin and gray.

A decorative network diagram in the top-left corner, featuring a complex web of interconnected nodes and lines. The nodes are represented by small circles, some of which are larger and have a double-ring border, while others are smaller and solid. The lines are thin and gray, connecting the nodes in a non-linear fashion.

Thank you

A decorative network diagram in the bottom-right corner, similar to the one in the top-left. It shows a cluster of nodes connected by lines. Some nodes are larger with double borders, and some are smaller and solid. The lines are thin and gray.