Clarification:

For this assignment, we used K-means as our initialization.

- trees ie2cf92c40c3f3306321d789f7e9c12893.jpg segmented into 10, 20 and 50 segments
 - o 10 segments:



o 20 segments:



o 50 segments:



• RobertMixedo3.jpg segmented into 10,20,50 segments

o 10 segments:



o 20 segments:



o 50 segments:



• smallstrelitzia.jpg segmented into 10, 20 and 50 segments

o 10 segments:



o 20 segments:



o 50 segments:



• smallsunset.jpg segmented into 10,20 and 50 segment



o 20 segments:



o 50 segments:



Display of tree image with 20 segments with 5 different initial points Set 1 of initial points:

Set 2 of initial points:



Set 3 of initial points:

Set 4 of initial points:



Set 5 of initial points:



• Code snippets for EM initialization, updates

```
def random_init(k, data, n):
    n = np.random.randint(0, n+1, size = k)
    pi = np.array([(1/k)]*k)
    return data[n, :], pi
def boot_step(k, data, state):
    #initialize cluster center
    kmeans = KMeans(n_clusters=k, random_state=state).fit(data)
    #initialize weight(scala) for each blob of data
    pi = np.array([(1/k)]*k)
    return kmeans.cluster_centers_, pi
def e_{step}(x, mu, pi, k, n):
    w = np.zeros((n, k))
    for i in range(n):
        #for numerical stability add dmin
        dmin = min(np.sum((x[i,:] - mu)**2, axis=1))
        for j in range(k):
            d1 = (x[i,:] - mu[j,:])
            d2 = (x[i,:] - mu[j,:])
            w[i,j] = np.exp(-0.5*(np.dot(d1.T, d2) - dmin)) * pi[j]
    w = w / np.sum(w, axis=1)[:, None]
    return w
def m_step(w, x, mu, pi, k, n, img_dim):
    mu = np.dot(x.T, w).T
    mu = mu / np.sum(w, axis=0)[:,None]
    pi = np.sum(w, axis=0) / (img_dim[0] * img_dim[1])
    pi[k-1] = 1 - sum(pi[:k-1])
    return mu, pi
```

• Other relevant code (optional)

```
def assign_pixel(w, image_data, k, n, img_dim):
    pred_cluster = np.argmax(w, axis=1) #nx1
    #get avg pixel value for ith cluster
    avg_pixel_for_cluster = [np.mean(image_data[pred_cluster==i], axis = 0) for i in range(k)]
    #new graph:
    new_graph = np.zeros((n, 3))
    for i in range(n):
        new_graph[i,:] = avg_pixel_for_cluster[pred_cluster[i]]
        new_graph = np.asarray(np.reshape(new_graph, (img_dim[0], img_dim[1], 3)), dtype="uint8")
    return new_graph

def show_graph(new_graph, name, k, state):
    plt.imshow(new_graph)
    plt.imsave(name[:-3] + '_' + str(k) + 'state_' + str(state) + 'segmentations.jpg', new_graph)
```

```
random = False
epsilon = 0.1
epsilon = 0.1
image_path = '/Users/pengyucheng/Desktop/Applied-ML/cs498_aml_hw8/dataset/'
load_image(image_path, image_name)
                    mu, pi = random_init(k, image_data, n)
else:
                   else:
    mu, pi = boot_step(k, image_data, i)
    old_mu = np.Inf
    iter = 1
    while(True):
        print('iteration:', iter)
        iter = 1
                          iter += 1
w = e_step(image_data, mu, pi, k, n)
mu, pi = m_step(w, image_data, mu, pi, k, n, img_dim)
diff = check_convergence(mu, old_mu)
                          old_mu = mu
if diff < epsilon:</pre>
                   \label{eq:graph} \begin{split} & graph = & assign\_pixel(w, image\_data, k, n, img\_dim) \\ & show\_graph(graph, image\_name, k, i) \end{split}
      for k in [10, 20, 50]:
    print('segmentation length:', k)
    image_data, img_dim = load_image(image_path, image_name)
             n = image_data.shape[0]
if (random):
    mu, pi = random_init(k, image_data, n)
else:
                   mu, pi =
                                 boot_step(k, image_data, 0)
             old_mu = np.Inf
iter = 1
             iter = 1
while(True):
                   print('iteration:', iter)
                   w = e_step(image_data, mu, pi, k, n)
mu, pi = m_step(w, image_data, mu, pi, k, n, img_dim)
diff = check_convergence(mu, old_mu)
                   old_mu = mu
if diff < epsilon:</pre>
             \label{eq:graph} \begin{split} & graph = & assign\_pixel(w, image\_data, k, n, img\_dim) \\ & show\_graph(graph, image\_name, k, 0) \end{split}
```