

506 #1: We solve this equation using method of characteristics.  
(and the notation of Evans).

We want to solve

$$\begin{aligned}u_{x_1} + u_{x_2} &= u^2 \\ u(x_1, 0) &= h(x_1).\end{aligned}$$

~~Let~~

$$\rightarrow F(p, z, x) = p_1 + p_2 - z^2 = 0.$$

$$\begin{aligned}\rightarrow D_p F &= (1, 1) \\ D_x F &= (0, 0) \\ D_z F &= -2z.\end{aligned}$$

Then

$$\begin{aligned}\dot{p} &= -D_x F - D_z F p = 2z(p_1, p_2) \\ \dot{z} &= D_p F \cdot p = p_1 + p_2 = z^2. \\ \dot{x} &= D_p F = (1, 1)\end{aligned}$$

with

$$x_1(0) = x_1(0)$$

$$x_2(0) = 0$$

$$z(0) = h(x_1(0))$$

We have

$$x_1(s) = x_1(0) + s$$

$$x_2(s) = s$$

$$\begin{aligned}\dot{z} &= z^2 \rightarrow \frac{1}{z^2} dz = ds \\ -\frac{1}{z(s)} &= s + C\end{aligned}$$

$$\text{Since } z(0) = h(x_1(0)), \quad C = -\frac{1}{h(x_1(0))}.$$

Thus

$$z(s) = \frac{1}{\frac{1}{h(x_1(0))} - s} = \frac{1}{\frac{1}{h(x_1(0) - x_2(s))} - x_2(s)}.$$

There is

$$u(x_1, x_2) = \frac{1}{\frac{1}{h(x_1 - x_2)} - x_2}.$$

## Sol #2:

① Mass:

We have

$$\begin{aligned}\frac{d}{dt} \int_{-\infty}^{\infty} u(x,t) dx &= \int_{-\infty}^{\infty} u_t dx = - \int_{-\infty}^{\infty} u_{xxx} dx - 6 \int_{-\infty}^{\infty} uu_x dx \\ &= -u_{xx} \Big|_{x=-\infty}^{\infty} - 6 \cdot \frac{1}{2} u^2 \Big|_{x=-\infty}^{\infty} = 0.\end{aligned}$$

② Momentum:

We have

$$\begin{aligned}\frac{d}{dt} \int_{-\infty}^{\infty} u^2 dx &= \int_{-\infty}^{\infty} 2uu_t dx = 2 \int_{-\infty}^{\infty} u(-u_{xxx} - 6uu_x) dx \\ &= -2 \int_{-\infty}^{\infty} uu_{xxx} dx - 12 \int_{-\infty}^{\infty} u^2 u_x dx \\ &= -2 \int_{-\infty}^{\infty} uu_{xxx} dx - 12 \cdot \frac{1}{3} u^3 \Big|_{x=-\infty}^{\infty}\end{aligned}$$

Since

$$\begin{aligned}\int_{-\infty}^{\infty} uu_{xxx} dx &= - \int_{-\infty}^{\infty} u_x u_{xx} dx = + \int_{-\infty}^{\infty} u_{xx} u_x dx \\ &= - \int_{-\infty}^{\infty} u_{xxx} u dx,\end{aligned}$$

it follows that  $\int_{-\infty}^{\infty} uu_{xxx} dx = 0$ . Thus Momentum is conserved.

③ Energy:

We have

$$\begin{aligned}\frac{d}{dt} \int_{-\infty}^{\infty} \frac{1}{2} u_x^2 - u^3 dx &= \int_{-\infty}^{\infty} u_x u_{xt} - 3u^2 u_t dx \\ &= \int_{-\infty}^{\infty} u_x (-u_{xxx} - 6uu_x)_x + 3u^2 (u_{xxx} + 6uu_x) dx.\end{aligned}$$

506#2  
work

$$\begin{aligned}
 & \text{Now } \int_{-\infty}^{\infty} u^2 u_x dx = \frac{1}{4} u^4 \Big|_{-\infty}^{\infty} = 0. \\
 & = - \int_{-\infty}^{\infty} u_x (u_{xxx} + 6uu_x) dx + 3 \int_{-\infty}^{\infty} u^2 u_{xxx} dx \\
 & = \int_{-\infty}^{\infty} u_{xx} (u_{xxx} + 6uu_x) dx + 3 \int_{-\infty}^{\infty} u^2 u_{xxx} dx \\
 & = \int_{-\infty}^{\infty} u_{xx} u_{xxx} + 6uu_x u_{xx} dx - 6 \int_{-\infty}^{\infty} u u_x u_{xx} dx \\
 & = \int_{-\infty}^{\infty} u_{xx} u_{xxx} dx = 0
 \end{aligned}$$

as

$$\int_{-\infty}^{\infty} u_{xx} u_{xxx} dx = - \int_{-\infty}^{\infty} u_{xxx} u_{xx} dx.$$

### Sob #3:

Consider the Sturm-Liouville problem

$$(p(x)u')' = -\lambda u$$

$$u'(0) = u'(L) = 0.$$

This is indeed Sturm-Liouville since  $p(x) > 0$ . Then we have eigenfunctions  $\{\phi_n\}$  corresponding to eigenvalues  $\{\lambda_n\}_{n \geq 0}$  which form an orthogonal basis for the space of functions. ~~Since~~ Furthermore  $\lambda_0 < \lambda_1 < \lambda_2 < \dots \rightarrow \infty$  and

$$\lambda_0 = \min_u - \frac{\langle u, (pu')' \rangle}{\langle u, u \rangle}.$$

Since

$$\int_0^L u (pu')' dx = - \int_0^L p(u')^2 dx \leq 0$$

We have  $\lambda_0 \geq 0$ . Since 0 is an eigenvalue,  $\lambda_0 = 0$ . Thus  $\lambda_n > 0 \forall n > 0$ .

hence

$$u(x, t) = \sum_{n=0}^{\infty} a_n(t) \phi_n(x).$$

We have

$$u_t = \partial_x(p(x)u_x)$$

$$\begin{aligned} \sum_{n=0}^{\infty} a_n'(t) \phi_n(x) &= \sum_{n=0}^{\infty} \partial_x(p(x) \phi_n(x)) a_n(t) \\ &= \sum_{n=0}^{\infty} a_n(t) (-\lambda_n) \phi_n(x). \end{aligned}$$

Therefore

$$a_n'(t) = -\lambda_n a_n(t)$$

$$\rightarrow a_n(t) = e^{-\lambda_n t} a_n(0)$$

$$a_n(0) = \frac{\int_0^L \psi(x) \phi_n(x) dx}{\int_0^L \phi_n(x)^2 dx}$$

Sob #3 cont:

Thus

$$\lim_{t \rightarrow \infty} u(x, t) = a_0(0) = \frac{\int_0^L \varphi(x) \phi_0(x) dx}{\int_0^L \phi_0(x)^2 dx}$$

Since  $\phi_0 = 1$  is the eigenfunction corresponding to  $\lambda_0 = 0$ ,

we have

$$\lim_{t \rightarrow \infty} u(x, t) = a_0(0) = \frac{1}{L} \int_0^L \varphi(x) dx \quad \neq 1$$

806 #4

$$\text{Let } f(y) = \begin{cases} y \log(2 + \frac{1}{|y|}) & \text{for } y \neq 0 \\ 0 & \text{for } y = 0. \end{cases}$$

We will show that the ODE

$$\frac{dy}{dt} = f(y)$$
$$y(0) = 0$$

has only the zero solution. This will be shown by showing if  $y(t_0) \neq 0$  for some  $t_0 \in \mathbb{R}$ , then  $y(t) \neq 0 \forall t \in \mathbb{R}$ .

Suppose  $\exists t^+$  w/  $y(t^+) \neq 0$ . Replacing  $y$  w/  $-y$  if necessary, we may suppose wlog that  $y(t^+) > 0$ . Let  $(a, b)$  be the largest open interval <sup>w/ max  $t^+$</sup>  s.t.  $y > 0$  (here we have implicitly used continuity of  $y$ ).

①  $b = \infty$

Pf: Suppose  $b < \infty$ . Then by continuity,  $y(b) = 0$ , but

$$y(b) = y(t^+) + \int_{t^+}^b f(y(t)) dt > y(t^+) > 0. \quad \text{#}$$

②  $a = -\infty$

Pf: Suppose  $a > -\infty$ . Then  $y(a) = 0$ .

Sob #4 wnc:

Let  $g(x) = \int_1^x \frac{1}{s \log(2 + \frac{1}{|s|})} ds$ ,  $x > 0$ . Then

$$\frac{d}{dt}(g(y(t))) = 1 \quad \forall t \in (a, b)$$

and so

$$g(y(t^+)) - \lim_{t \rightarrow a^+} g(y(t)) = t^+ - a^+.$$

Since  $y(a) = 0$  and  $\lim_{x \rightarrow 0} g(x) = -\infty$  and  $g(y(t^+)) < \infty$ ,

we have  $g(y(t^+)) - \lim_{t \rightarrow a^+} g(y(t)) = \infty$ , a contradiction.

Therefore if  $\exists t^+ \text{ w/ } y(t^+) \neq 0$ , then  $y \neq 0 \forall t$ .

Thus the zero sol. is the only solution.

It now remains to show  $f$  is not Lipschitz. We have

$$\left| \frac{f(\frac{1}{n}) - f(\frac{1}{2n})}{\frac{1}{2n}} \right| = \left| \frac{\frac{1}{n} \log(2+n) - \frac{1}{2n} \log(2+2n)}{\frac{1}{2n}} \right|$$

$$= |2 \log(2+n) - \log(2+2n)|$$

$$= \left| \log\left(\frac{(2+n)^2}{2+2n}\right) \right| \rightarrow \infty \text{ as } n \rightarrow \infty.$$

Therefore  $f$  is not Lipschitz.  $\neq$

S06 #5: We rewrite the ~~system~~<sup>ODE</sup> as a system:

$$\begin{aligned}x' &= y \\ y' &= -x - 2x^2.\end{aligned}\quad (1)$$

This is a Hamiltonian system and hence all equilibrium points are either centers or saddles. Let

$$H(x, y) := \frac{1}{2}y^2 + \frac{1}{2}x^2 + \frac{2}{3}x^3 = \frac{1}{2}(x')^2 + \frac{1}{2}x^2 + \frac{2}{3}x^3.$$

Then

$$\begin{aligned}\frac{d}{dt} H(x, y) &= x'x'' + xx' + 2x^2x' \\ &= x'(x'' + x + 2x^2) = 0.\end{aligned}$$

Thus  $\frac{1}{2}(x')^2 + \frac{1}{2}x^2 + \frac{2}{3}x^3$  is a conserved quantity.

The equilibrium points of (1) are  $(0, 0)$  and  $(-\frac{1}{2}, 0)$ .

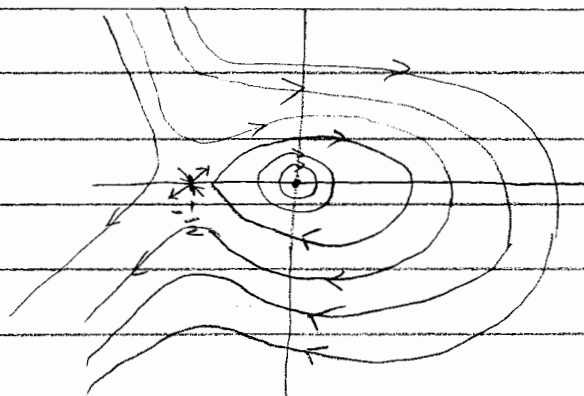
The Jacobian is

$$J(x, y) = \begin{pmatrix} 0 & 1 \\ -1-4x & 0 \end{pmatrix}$$

We have

$$J(0, 0) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \rightarrow \text{eigenvalues } \pm i \quad \text{center}$$

$$J(-\frac{1}{2}, 0) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \rightarrow \begin{array}{l} \text{eigenvalues } \pm 1 \\ \text{eigenvectors } \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \end{array} \quad \text{saddle.}$$





S06 #6 : ~~Let~~ Suppose  $\max u(x) > 0$ . Let  $x_0$  be s.t.  $u(x_0) = \max u(x)$

Then  $x_0 \in \Omega$  and  $\Delta u(x_0) \leq 0$ ,  $u_{x_k}(x_0) = 0$ . Then at the

as  $u=0$  on  $\partial\Omega$  ← point  $x_0$ ,

$$\Delta u + \sum_{k=1}^n a_k(x) u_{x_k} + c(x)u = \Delta u + c(x_0)u(x_0) \leq c(x_0)u(x_0) < 0$$

as  $u(x_0) > 0$  and  $c(x) < 0$  in  $\Omega$ . This is a contradiction.

Thus  $\max u(x) \leq 0$ .

Suppose  $\min u(x) < 0$ . Let  $y_0$  be s.t.  $u(y_0) = \min u(x)$

Then as  $u=0$  on  $\partial\Omega$ ,  $\Delta u(y_0) \geq 0$ ,  $u_{x_k}(y_0) = 0$ . At the point  $y_0$ ,

~~$$\Delta u + \sum_{k=1}^n a_k(x) u_{x_k} + c(x)u = \Delta u + c(y_0)u(y_0) \geq c(y_0)u(y_0) > 0$$~~

$$\begin{aligned} (\Delta u)(y_0) + \sum_{k=1}^n a_k(y_0) u_{x_k}(y_0) + c(y_0)u(y_0) \\ = (\Delta u)(y_0) + c(y_0)u(y_0) \\ \geq c(y_0)u(y_0) > 0 \end{aligned}$$

Since  $u(y_0) > 0$  and  $c(x) > 0 \forall x \in \Omega$ . This is a contradiction.

Thus  $\min u(x) \geq 0$ .

Therefore  $u=0$  on  $\partial\Omega$  implies  $u=0$  on  $\Omega$ .

Lagrange multipliers: optimize  $f$  subj. to  $g = h$ .

1. Solve system  $\nabla f = \lambda \nabla g$   
 $g = h$ .

2. Plug in all solutions  $(x, y, z)$  from 1. into  $f(x, y, z)$  to find min./max.

SOB #7:

Let  $E[u] := \int_{\Omega} \frac{1}{2} |\nabla u|^2 - f u \, dx$ ,  $F[u] := \int_{\Omega} u \, dx$ . We want to minimize  $E[u]$  subject to  $F[u] = A$  and  $u|_{\partial\Omega} = 0$ .

By Lagrange multipliers, the minimum  $u$  must satisfy

$$\left( \lim_{\varepsilon \rightarrow 0} \frac{E[u+\varepsilon v] - E[u]}{\varepsilon} \right) = \lambda \left( \lim_{\varepsilon \rightarrow 0} \frac{F[u+\varepsilon v] - F[u]}{\varepsilon} \right)$$

the moral is  
 choose  $v$  so that  $u+\varepsilon v$   
 has the same properties  
 as  $u$ .

for some constant  $\lambda$  and  $v$  s.t.  $v|_{\partial\Omega} = 0$  and  $\int_{\Omega} v \, dx = 0$  (since  $E$  eats functions with  $u|_{\partial\Omega} = 0$  and  $\int_{\Omega} u \, dx = A$  thus we need  $\int_{\Omega} v \, dx = 0$  so that  $\int_{\Omega} u + \varepsilon v \, dx = A$ ) We have

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \frac{E[u+\varepsilon v] - E[u]}{\varepsilon} &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \left( \int_{\Omega} \frac{1}{2} |\nabla(u+\varepsilon v)|^2 - f(u+\varepsilon v) - \frac{1}{2} |\nabla u|^2 - f u \, dx \right) \\ &= \int_{\Omega} \nabla u \cdot \nabla v - f v \, dx \\ &= \int_{\Omega} (-\Delta u - f) v \, dx \end{aligned}$$

and

$$\lim_{\varepsilon \rightarrow 0} \frac{F[u+\varepsilon v] - F[u]}{\varepsilon} = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_{\Omega} u + \varepsilon v - u \, dx = \int_{\Omega} v \, dx = 0.$$

Thus

$$\int_{\Omega} (-\Delta u - f) v \, dx = 0 \rightarrow -\Delta u = f \text{ in } \Omega.$$

Therefore the minimum of  $E[u]$  subject to  $u|_{\partial\Omega} = 0$  and  $\int_{\Omega} u \, dx = A$  is the unique solution to

$$\Delta u = -f \text{ in } \Omega$$

$$u = 0 \text{ on } \partial\Omega.$$