

W04 #1:

a) $\lambda = 0$:

$$\Delta u = 0$$

$$u(x, 0) = u(x, \pi) = 0$$

$$\downarrow$$
$$G(0) = G(\pi) = 0.$$

$$u = F(x)G(y).$$

$$F''(x)G(y) + F(x)G''(y) = 0.$$

$$-\frac{F''(x)}{F(x)} = \frac{G''(y)}{G(y)} = -\mu.$$

Need $\mu \geq 0$.

$$G''(y) + \mu G(y) = 0.$$

$$G(y) = A \cos(\sqrt{\mu} y) + B \sin(\sqrt{\mu} y).$$

$$0 = G(0) = A \rightarrow G(y) = B \sin(\sqrt{\mu} y).$$

$$0 = G(\pi) \Rightarrow 0 = \sin(\sqrt{\mu} \pi) \rightarrow \sqrt{\mu} \pi = n\pi, n = 1, 2, \dots$$

$$\mu_n = n^2, n = 1, 2, \dots$$

$$\rightarrow \frac{F''}{F} = \mu \rightarrow F'' - n^2 F = 0.$$

$$G_n(y) = \sin(ny)$$

$$\rightarrow F(x) = A e^{-nx} + B e^{nx}.$$

$B = 0$ since we want bdd solutions.

Therefore

$$u(x, y) = \sum_{n=1}^{\infty} A_n e^{-nx} \sin(ny).$$

b) $\lambda > 0$. We have

$$F''(x)G(y) + F(x)G''(y) + \lambda F(x)G(y) = 0.$$

$$-\frac{F'' + \lambda F}{F} = +\frac{G''}{G} = -\mu \text{ and } \mu > 0.$$

$$\rightarrow \mu_n = n^2$$

$$G_n(y) = \sin(ny).$$

$$\rightarrow F'' + \lambda F - n^2 F = 0.$$

$$F'' + (\lambda - n^2) F = 0.$$

W04 #1 cont:

We have:

$$\text{if } \lambda > n^2: F'' + (\lambda - n^2)F = 0$$

$$\text{if } \lambda = n^2: F = A \cos(\sqrt{\lambda - n^2} x) + B \sin(\sqrt{\lambda - n^2} x)$$

$$F = A + Bx$$

$$\text{if } \lambda < n^2$$

$$F = A e^{-\sqrt{n^2 - \lambda} x} + B e^{+\sqrt{n^2 - \lambda} x}$$

since we want both solutions

Thus

$$u(x, y) = \sum_{n < \sqrt{\lambda}} [A_n \cos(\sqrt{\lambda - n^2} x) + B_n \sin(\sqrt{\lambda - n^2} x)] \sin(ny) \\ + (C + Dx) \sin(\sqrt{\lambda} y) e^{\pm \sqrt{\lambda} x} \\ + \sum_{n > \sqrt{\lambda}} E_n e^{-\sqrt{n^2 - \lambda} x} \sin(ny)$$

c) $\lambda < 0$. here $\gamma = -\lambda > 0$. Then the only thing that changes is the equation for F is now

$$F'' + (\lambda - n^2)F = 0 \rightarrow F'' - (\gamma + n^2)F = 0$$

Thus

$$\rightarrow F_n(x) = A_n e^{-\sqrt{\gamma + n^2} x} + B_n e^{\sqrt{\gamma + n^2} x}$$

$$u(x, y) = \sum_{n \geq 1} A_n e^{-\sqrt{\gamma + n^2} x} \sin(ny)$$

(Since we only want both solutions).

W04 #2: Fix arbitrary $v \in C_0^\infty(\Omega)$. Since u_0 is the minimizer of the functional,

$$\begin{aligned}
 0 &= \lim_{\varepsilon \rightarrow 0} \frac{D(u_0 + \varepsilon v) - D(u_0)}{\varepsilon} \\
 &= \int_{\Omega} 2(u_0)_x v_x + 2(u_0)_y v_y + f v \, dx + \int_{\partial\Omega} 2\alpha u_0 v \, d\sigma \\
 &= \int_{\Omega} 2(\nabla u_0 \cdot \nabla v) + f v \, dx + 2 \int_{\partial\Omega} \alpha u_0 v \, d\sigma \\
 &= 2 \int_{\Omega} -v \Delta u_0 \, dx + 2 \int_{\partial\Omega} (\nabla u_0 \cdot \gamma) v \, d\sigma + \int_{\Omega} f v \, dx \\
 &\quad + 2 \int_{\partial\Omega} \alpha u_0 v \, d\sigma. \\
 &= \int_{\Omega} (-2\Delta u_0 + f) v \, dx + 2 \int_{\partial\Omega} (\nabla u_0 \cdot \gamma + \alpha u_0) v \, d\sigma.
 \end{aligned}$$

Thus

$$\begin{aligned}
 -2\Delta u_0 + f &= 0 \quad \text{in } \Omega \\
 \nabla u_0 \cdot \gamma + \alpha u_0 &= 0 \quad \text{on } \partial\Omega.
 \end{aligned}$$

W04 #3:

$$\frac{\partial}{\partial \bar{w}} = \frac{1}{2} \left(\frac{\partial}{\partial y_1} - i \frac{\partial}{\partial y_2} \right) \quad w = y_1 + i y_2.$$

We have

$$u(z) = \frac{1}{2\pi} \int_{\mathbb{C}} \frac{f(w)}{w-z} dw$$

Let $K(w) = \frac{1}{2\pi} \log |w| = \frac{1}{4\pi} \log(y_1^2 + y_2^2)$. We have

$$\frac{\partial}{\partial \bar{w}} K(w) = \frac{1}{2} \cdot \frac{1}{4\pi} \left[\frac{2y_1}{y_1^2 + y_2^2} - i \frac{2y_2}{y_1^2 + y_2^2} \right] = \frac{1}{4\pi} \cdot \frac{1}{w}.$$

Thus

$$\begin{aligned} u(z) &= \frac{4\pi}{2\pi} \int_{\mathbb{C}} f(w) K_w(z-w) dw \\ &= 2 \int_{\mathbb{C}} f(z-w) K_w(w) dw. \end{aligned}$$

Therefore

$$\begin{aligned} \left(\frac{\partial}{\partial x_1} + i \frac{\partial}{\partial x_2} \right) u &= 2 \frac{\partial u}{\partial \bar{z}} = 4 \int_{\mathbb{C}} \frac{\partial}{\partial \bar{z}} f(z-w) K_w(w) dw \\ &= -4 \int_{\mathbb{C}} \frac{\partial}{\partial \bar{w}} f(z-w) K_w(w) dw \\ &= 4 \int_{\mathbb{C}} f(z-w) \frac{\partial}{\partial \bar{w}} \frac{\partial}{\partial w} K(w) dw \\ &= \int_{\mathbb{C}} f(z-w) \Delta K(w) dw \\ &= \int_{\mathbb{C}} f(z-w) \delta(w) dw \\ &= f(z). \end{aligned}$$

WO4 #4:

Let y_1, y_2 be 2 ~~linearly~~ independent solutions. Then $w = y_1 - y_2$ satisfies

$$-w'' + pw = 0 \quad 0 < x < \pi$$

$$w(0) = 0, w'(\pi) = 0.$$

We have

$$0 = \int_0^\pi -w''w + pw^2 dx = \int_0^\pi (w')^2 + pw^2 dx$$

~~here~~

By Poincaré's

We now find the eigenvalues of the $-\Delta$:

$$-y'' = \lambda y$$

$$y(0) = y'(\pi) = 0.$$

$$\rightarrow \lambda > 0 \quad y(x) = A \cos \sqrt{\lambda} x + B \sin \sqrt{\lambda} x.$$

$$0 = y(0) = A \rightarrow y(x) = B \sin \sqrt{\lambda} x.$$

$$\downarrow$$
$$y'(x) = B \sqrt{\lambda} \cos \sqrt{\lambda} x.$$

$$\rightarrow \sqrt{\lambda} \pi = \frac{2n+1}{2} \pi, n=0,1,2,\dots$$

$$\lambda_n = \left(n + \frac{1}{2}\right)^2; n=0,1,2,\dots$$

Let $\phi_n := \sin\left(\left(n + \frac{1}{2}\right)x\right)$, $\lambda_n := \left(n + \frac{1}{2}\right)^2$. Then

$$-\phi_n'' = \lambda_n \phi_n$$

$$\phi_n(0) = \phi_n'(\pi) = 0.$$

We have $w(x) = \sum_{n=0}^{\infty} a_n \phi_n(x)$. Then

W04 #4 con:

$$\int_0^\pi -w''w \, dx = \int_0^\pi \left(\sum_{n \geq 0} a_n \lambda_n \phi_n(x) \right) \left(\sum_{m \geq 0} a_m \phi_m(x) \right) dx$$

$$= \int_0^\pi \sum_{n \geq 0} a_n^2 \lambda_n \phi_n^2(x) \, dx$$

$$= \sum_{n \geq 0} a_n^2 \lambda_n \int_0^\pi \phi_n^2(x) \, dx$$

$$\geq \frac{1}{4} \sum_{n \geq 0} a_n^2 \int_0^\pi \phi_n^2(x) \, dx$$

$$= \frac{1}{4} \int_0^\pi w^2 \, dx$$

and the $\frac{1}{4}$ is sharp. Thus (*)

$$0 = \int_0^\pi -w''w + p w^2 \, dx \geq \int_0^\pi \left(\frac{1}{4} + p \right) w^2 \, dx.$$

When $p > -\frac{1}{4}$, the same

$$0 = \int_0^\pi \left(\frac{1}{4} + p \right) w^2 \, dx \geq 0$$

and hence $w = 0$. Since $\frac{1}{4}$ is sharp in (*), $\lambda_0 = -\frac{1}{4}$.

W04 #5

Taking the Fourier Transform in the x -variable, we have

$$u_{xx} + u_{yy} = 0 \rightarrow -4\pi^2 \xi^2 \hat{u} + \hat{u}_{yy} = 0.$$

Now A, B will depend on ξ

$$\rightarrow \hat{u}(\xi, y) = A e^{-2\pi|\xi|y} + B e^{2\pi|\xi|y}$$

Since we want a bounded solution, $B = 0$. Therefore

$$\hat{u}(\xi, y) = A e^{-2\pi|\xi|y}.$$

Since

$$u_y(x, 0) - u(x, 0) = f(x) \rightarrow \hat{u}_y(\xi, 0) - \hat{u}(\xi, 0) = \hat{f}(\xi)$$

Then as $\hat{u}_y(\xi, y) = -2\pi|\xi| A e^{-2\pi|\xi|y}$, we have

$$-2\pi|\xi| A - A = \hat{f}(\xi)$$

$$A = \frac{-\hat{f}(\xi)}{2\pi|\xi| + 1}.$$

Thus

$$\hat{u}(\xi, y) = \frac{-\hat{f}(\xi)}{2\pi|\xi| + 1} e^{-2\pi|\xi|y}.$$

~~Since f is smooth of compact support, the RHS is Schwartz, so~~

$$u(x, y) = \int_{\mathbb{R}} \frac{-\hat{f}(\xi)}{2\pi|\xi| + 1} e^{-2\pi|\xi|y} e^{2\pi i \xi x} d\xi$$

Since $y > 0$ and $\hat{f} \in \mathcal{S}(\mathbb{R})$ (or $f \in \mathcal{S}(\mathbb{R})$), we have $|\hat{u}(\xi, y)| \leq |\hat{f}(\xi)|$. Thus $\hat{u}(\xi, y)$ is integrable on ξ .

Therefore

$$\begin{aligned} u(x, y) &= \int_{\mathbb{R}} \hat{u}(\xi, y) e^{2\pi i \xi x} d\xi \\ &= \int_{\mathbb{R}} \frac{-\hat{f}(\xi)}{2\pi|\xi| + 1} e^{-2\pi|\xi|y} e^{2\pi i \xi x} d\xi \end{aligned}$$

We also have

$$|u(x, y)| \leq \int_{\mathbb{R}} |\hat{f}(\xi)| e^{-2\pi|\xi|y} d\xi$$

$$\leq \left(\int_{\mathbb{R}} |\hat{f}(\xi)|^2 d\xi \right)^{1/2} \left(\int_{\mathbb{R}} e^{-4\pi^2 \xi^2 y^2} d\xi \right)^{1/2}$$

Since

$$u = 2\pi \xi y \\ du = 2\pi y d\xi$$

$$\int_{-\infty}^{\infty} e^{-(2\pi \xi y)^2} d\xi = \frac{1}{2\pi y} \int_{-\infty}^{\infty} e^{-u^2} du = \frac{1}{2\sqrt{\pi} y}.$$

Thus

$$|u(x, y)| \leq \|f\|_{L^2} (2\sqrt{\pi})^{-1/2} y^{-1/2} \rightarrow 0 \\ \text{as } y \rightarrow \infty \text{ uniformly in } x$$

Characteristics point \uparrow same they pt in increasing time.

W04 #6:

We have

Characteristics:

$$u_t - u_x = 0 \rightarrow$$

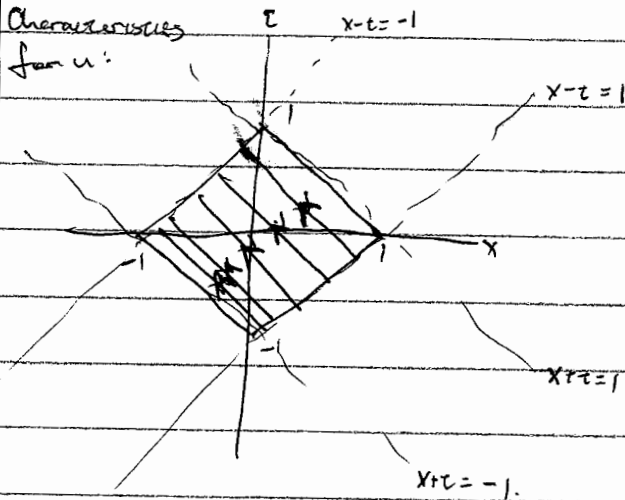
$$x + t = C$$

$$v_t + v_x = 0$$

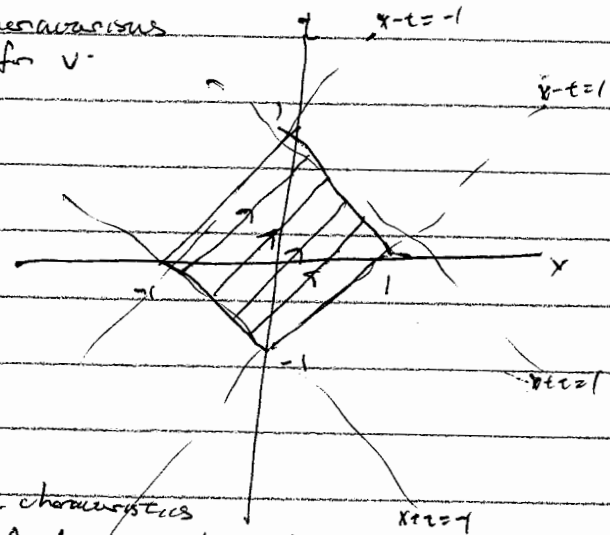
$$x - t = C$$

u and v are constant on their respective characteristics

Characteristics for u :



Characteristics for v :



- a) This problem is well posed since \checkmark to ~~find the~~ solve for u it suffices to know u on the line $x-t=-1$ and to solve for v it suffices to know v on the line $x+t=-1$. The ~~solution~~ solution is given by

$$u(x, t) = u_0(x+t)$$

$$v(x, t) = v_0(x-t)$$

- b) From the characteristics, this problem is not well-posed.

W04 #7:

a) We have

$$\begin{aligned} f(x') &= \int_{-\infty}^{\infty} \delta(x-x') f(x) dx \\ &= \int_{-\infty}^{\infty} \mathcal{L}G(x, x') f(x) dx = \int_{-\infty}^{\infty} G(x, x') \mathcal{L}f(x) dx \end{aligned}$$

We also have

$$\begin{aligned} \int_{-\infty}^{\infty} \mathcal{L}f(x) G(x-x', 0) dx &= \int_{-\infty}^{\infty} (\mathcal{L}f)(x+x') G(x, 0) dx \\ &= \int_{-\infty}^{\infty} (\mathcal{L}g)(x) G(x, 0) dx \quad g(x) = f(x+x') \\ &= g(0) = f(x'). \end{aligned}$$

So

$$\int_{-\infty}^{\infty} \mathcal{L}f(x) G(x-x', 0) dx = \int_{-\infty}^{\infty} \mathcal{L}f(x) G(x, x') dx \quad \forall f.$$

Therefore $G(x-x', 0) = G(x, x')$.

b) Since we want

$\frac{d^2}{dx^2} G - G = \delta(x-x') = \begin{cases} 0 & \text{if } x \neq x' \end{cases}$
and $G \rightarrow 0$ as $x \rightarrow -\infty$ and $G \rightarrow 0$ as $x \rightarrow \infty$,
 G must be a homogeneous ~~linear~~ solution to $y'' - y = 0$
and satisfy the jump conditions. Thus

$$G(x, x') = \begin{cases} a_1 e^x & \text{if } x < x' \\ a_2 e^{-x} & \text{if } x > x' \end{cases}$$

W04 #7 (cont.)

We need $a_- e^{x'} = a_+ e^{-x'}$.

We also need

$$G'(x'_+, x') - G'(x'_-, x') = \int_{x'_-}^{x'_+} \Delta G(x, x') dx = \int_{x'_-}^{x'_+} \delta(x - x') = 1$$

We have

$$G'(x, x') = \begin{cases} a_- e^x & \text{if } x < x' \\ -a_+ e^{-x} & \text{if } x > x' \end{cases}$$

Then

$$\begin{aligned} -a_+ e^{-x'} - a_- e^{x'} &= 1 \\ a_- e^{x'} &= a_+ e^{-x'} \end{aligned} \quad \rightarrow \quad \begin{aligned} -a_- e^{x'} &= \frac{1}{2} \\ a_- &= -\frac{1}{2e^{x'}} \end{aligned}$$

$$\begin{aligned} a_+ &= a_- e^{2x'} = -\frac{1}{2e^{x'}} e^{2x'} \\ &= -\frac{e^{x'}}{2} \end{aligned}$$

So

$$G(x, \xi) = \begin{cases} -\frac{1}{2e^\xi} e^x & \text{if } x < \xi \\ -\frac{e^\xi}{2} e^{-x} & \text{if } x > \xi \end{cases}$$

W04 #8:

The system

$$\begin{aligned}x' &= x - y^2 \\ y' &= y - x^2.\end{aligned}$$

The equilibrium pts are:

$$\begin{aligned}x &= y^2 \\ y &= x^2 \rightarrow y = y^4 \rightarrow y(y^3 - 1) = 0.\end{aligned}$$

$$\begin{aligned}y &= 0, y = 1. \\ \downarrow & \quad \downarrow \\ x &= 0 \quad x = 1.\end{aligned}$$

$(0,0)$ and $(1,1)$.

The Jacobian is:

$$J(x,y) = \begin{pmatrix} 1 & -2y \\ -2x & 1 \end{pmatrix}$$

$$J(0,0) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$J(1,1) = \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix}$$

\downarrow
unstable source node

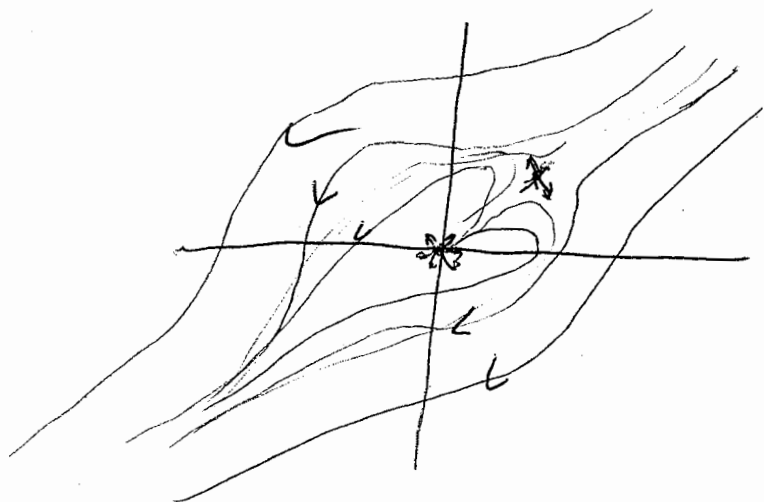


\downarrow
eigenvalues $3, -1$
eigenvectors $\begin{pmatrix} -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}$
saddle.

Can also sketch direction field to guess phase plane.

W04 #8 cont.

Since the x, y large, the paths look like $x^3 - y^3 = C$



Let $w(t) = u(t) - v(t)$. Then

$$\begin{aligned} \dot{w} &= u_t - v_t = u - v^2 - v + u^2 \\ &= (u - v) + (u^2 - v^2) \\ &= (u - v) + (u - v)(u + v) \\ &= (u - v)(u + v + 1) \end{aligned}$$

$$\int_0^t w(s) ds = \int_0^t (u - v)(u + v + 1) ds$$

$$w(t) = \int_0^t w(s)(u + v + 1) ds$$

$$w_t = w(u + v + 1)$$

$$w(0) = 0$$

Therefore if $w \geq 0 \forall t$, then

$$w_t \leq w(u + v + 1)$$

and so by Gronwall, $w(t) \leq e^{\int_0^t (u + v + 1) ds}$

and here $w(t) = 0 \forall t$.

$$w(0) = 0$$

W04 #8 cont.

Thus

$$\int_0^t u_t(s) - v_t(s) ds = \int_0^t (u-v)(u+v+1) ds.$$

As $u(0) - v(0) = 0$,

$$u(t) - v(t) = \int_0^t (u-v)(u+v+1) ds$$

Then

$$|u(t) - v(t)| \leq \int_0^t |u(s) - v(s)| |u(s) + v(s) + 1| ds.$$

Then by the integral form of Gronwall,

$$|u(t) - v(t)| \leq 0.$$

$$\rightarrow u = v \quad \forall t. \quad \#$$