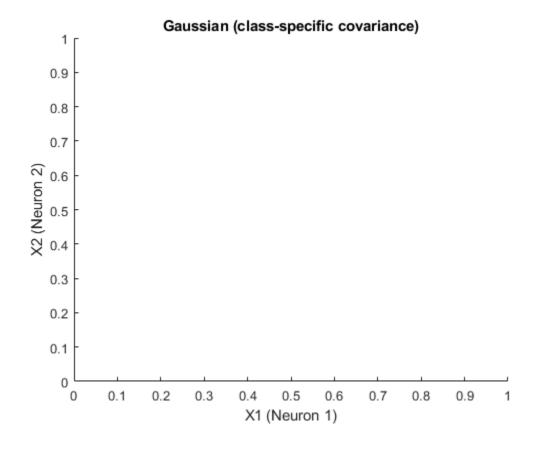
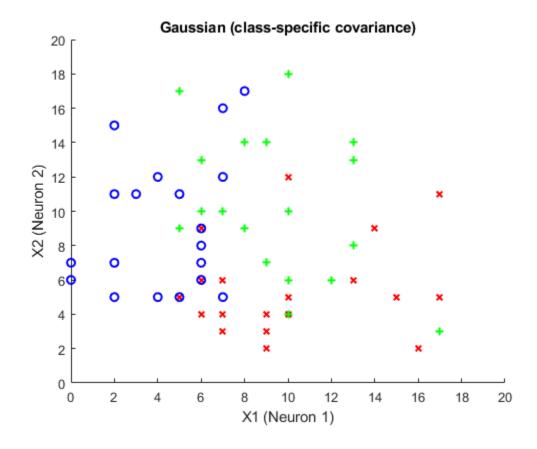
Table of Contents

```
load('ps3_simdata.mat')
figure
xlabel('X1 (Neuron 1)')
ylabel('X2 (Neuron 2)')
title('Gaussian (class-specific covariance)')
hold on
```



Plot the data points in a two-dimensional space. For classes k = 1, 2, 3, uses a red \times , green +, and blue o for each data point, respectively.

```
for k = 1:3
[X1, X2] = getValues(trial, k);
if k == 1; marker = 'rx';
elseif k == 2; marker = 'g+';
else; marker = 'bo';
end
plot(X1, X2, marker, 'LineWidth', 1.5)
end
axis([0 20 0 20])
```

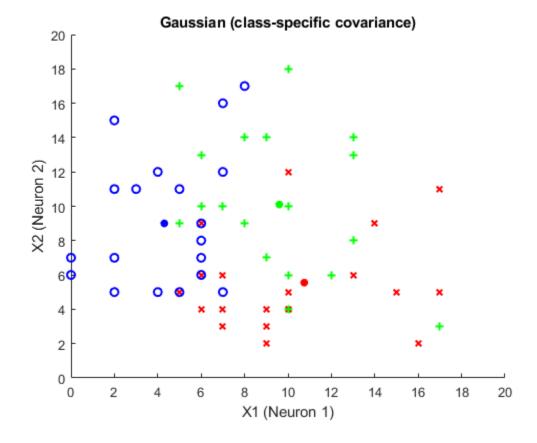


Find the maximum likelihood (ML) parameters for a Gaussian generative model with specific covariance for each class, and plots the ML mean as a solid dot.

```
pi = 20/60; %Nk/N

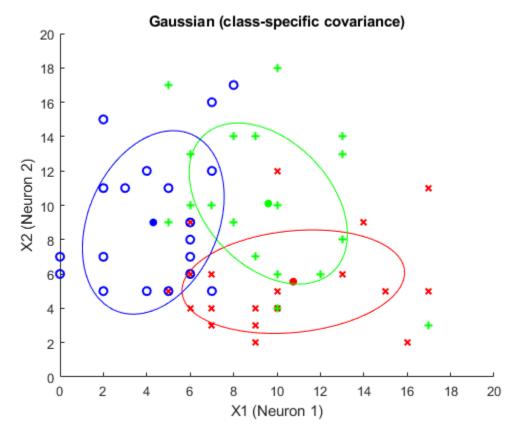
[mu1] = getMu(trial, 1);
plot(mu1(1), mu1(2), 'r.', 'MarkerSize', 20)
[mu2] = getMu(trial, 2);
plot(mu2(1), mu2(2), 'g.', 'MarkerSize', 20)
[mu3] = getMu(trial, 3);
plot(mu3(1), mu3(2), 'b.', 'MarkerSize', 20)

[sigma1] = getSigma(trial, 1);
[sigma2] = getSigma(trial, 2);
[sigma3] = getSigma(trial, 3);
```



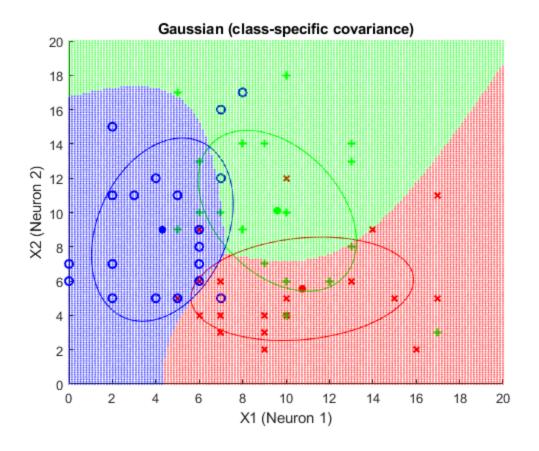
For each class, plots the ML covariance using an ellipse of the appropriate color.

```
X1 = linspace(0,20);
X2 = linspace(0,20);
[X,Y] = meshgrid(X1(:),X2(:));
nX = [X(:) Y(:)];
Z = mvnpdf(nX, mu1', sigma1);
Z = reshape(Z,[100 100]);
contour(X, Y, Z, [0.007, 0.007], 'r');
Z = mvnpdf(nX, mu2', sigma2);
Z = reshape(Z,[100 100]);
contour(X, Y, Z, [0.007, 0.007], 'g');
Z = mvnpdf(nX, mu3', sigma3);
Z = reshape(Z,[100 100]);
contour(X, Y, Z, [0.007, 0.007], 'b');
```



Plot multi-class decision boundaries corresponding to the decision rule: $k = argmax_k P(Ck \mid x)$

plotDecisionSpecificSigma(mu1, mu2, mu3, sigma1, sigma2, sigma3);



FUNCTIONS

```
function [X1, X2] = getValues(trial, k)
Returns spike counts from neuron 1 and neuron 2 as an array given
%trial number and class k
X1 = zeros(20, 1);
X2 = zeros(20, 1);
for n = 1:20
    X1(n) = trial(n, k).x(1);
    X2(n) = trial(n, k).x(2);
end
end
function [mu] = getMu(trial, k)
Returns means spike count for a given class for neuron 1 and neuron 2
as an array
[X1, X2] = getValues(trial, k);
mu = [sum(X1)/20; sum(X2)/20];
end
function [sigma] = getSigma(trial, k)
Returns covariance for a given class as a 2x2 matrix
[mu] = getMu(trial, k);
sigma = zeros(2, 2);
for n = 1:20
```

```
x = trial(n, k).x;
    s_x = ((x - mu) * (x - mu)');
    sigma = sigma + s_x;
end
sigma = sigma / 20;
end
function [] = plotDecisionSpecificSigma(mu1, mu2, mu3, sigma1, sigma2,
 sigma3)
%Plots a decision boundary for a Gaussian model with different
covariance
%for each class
X1 = linspace(0, 20, 150);
X2 = linspace(0,20,150);
count = 0;
for i = 1:length(X2)
    for j = 1:length(X1)
        vx = [X1(i); X2(j)];
        c1 = log(1/3) - log(2*pi) - ((1/2)*log(det(sigma1))) - ((1/2)*(vx-var))
mu1)'*inv(sigma1)*(vx-mu1));
        c2 = log(1/3) - log(2*pi) - ((1/2)*log(det(sigma2))) - ((1/2)*(vx-var))
mu2)'*inv(sigma2)*(vx-mu2));
        c3 = log(1/3) - log(2*pi) - ((1/2)*log(det(sigma3))) - ((1/2)*(vx-var))
mu3)'*inv(sigma3)*(vx-mu3));
        k = max([c1, c2, c3]);
        if c3 >= c1; count = count + 1;
        elseif c3 >= c2; count = count + 1;
        end
        if k == c1; marker = '.r';
        elseif k == c2; marker = '.q';
        elseif k == c3; marker = '.b';
        plot(X1(i),X2(j),marker, 'MarkerSize', 1);
    end
end
end
```

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