Digitrax Loconet Notes

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Chapter 1

LocoNet Protocol

1.1 Overview

LocoNet is a peer to peer distributed network system on which all devices can monitor the network data flow. The network is event driven by different devices in time, and is not polled by a centralised controller in normal operation. The normal LocoNet state is idle, with no data traffic unless a device has information to send. With no traffic flow, the network is quiet.

LocoNet data is sent in asynchronous format using 1 start bit, 8 data bits and 1 stop bit. The 8 bit data is transmitted least significant bit first. The bit times are 60.0 μ S or 16,660 baud +/- 1.5%. A computer can connect to a Digitrax USB interface at higher baud rates and the device will make the necessary conversion. Bytes may be transmitted back-to-back, with a start bit immediately following the stop bit of the previous character.

Any message that has format or framing errors, data errors or is a fragment caused by noise glitches and does not completely follow the message format will be ignored by all receivers, and a new opcode will be scanned for re-synchronisation.

The OPC_BUSY opcode is included to allow the master to keep the network active whilst it is performing a task that requires a response, and entails a significant processing delay, i.e. it can ensure no new requests are started until it has responded to the last message. This OPC_BUSY opcode should be simply stripped and ignored.

If a device disconnects from LocoNet and so does not access or reference a slot within the system purge time, the master will force the un-accessed slot to common status so other system devices can use the slot. The typical purge time of a master is about 200 seconds. A good "ping" or slot update activity is about every 100 seconds, i.e. if a user makes no

change to a throttle/slot within 100 seconds, the throttle/device should automatically send another speed update at the current speed to reset the purge timeout for that slot.

1.2 Message Format

All LocoNet communications are via multi-byte messages. The master is defined as the device that is maintaining the refresh stack for DCC packet generation and is actively generating the DCC track data. Refresh of information is typically only performed for mobile decoders. Stationary type decoders are not refreshed and individual immediate commands are sent out to the track as requested.

The master is only privileged in respect to performing the task of maintaining the locomotive refresh stack and generating DCC packets. In this way other network transactions may occur that the master does not need to be involved with or understand, as long as they follow the message protocol and timing requirements. i.e. Other devices may have a dialog on the network without disturbing or involving the master. Devices on LocoNet monitor the messages, check for format and data integrity and parse good messages to decode if action is required in the context. Devices such as throttles, input sensors, computer interfaces and control panels may generate LocoNet messages without needing prompting or polling by a central controller.

Devices frequently will be added and removed from an operating LocoNet. The devices and protocol are tolerant of electrical and data transients. The format chosen gives a good degree of data integrity, guaranteed quick network-state synchronisation, high data throughput, good distribution of access to many competing devices and low event latency. Also, the devices may be operated without need for unique ID or other requirements that can make network administration awkward.

The data bytes on LocoNet are defined as 8 bit data with the most significant bit as an opcode flag bit. If the most significant bit, d7, is 1 then the 7 least significant bits are interpreted as a network opcode. The opcode byte may only occur once in a valid message and is the first byte of a message. All the remaining bytes in the message must have a most significant bit of 0, including the last checksum byte. The checksum is the 1's complement of the byte wise exclusive or of all the bytes in the message, except the checksum itself. To validate data accuracy, all the bytes in a correctly formatted message are exclusive or'ed. If this resulting byte value is 0xFF, then the message data is accepted as good.

The opcodes may be examined to determine message length and if subsequent response message is required. Data bits d6 and d5 encode the message length. The message length includes the opcode and the checksum bytes. The bit d3 = 1 implies that a follow-on message or reply is expected.

d7	$\underline{d6}$	d5	$\underline{\mathrm{d}4}$	$\underline{\mathrm{d}3}$	$\underline{d2}$	$\underline{d1}$	$\underline{d0}$	
1	0	0	${ m E}$	D	\mathbf{C}	В	A	2 byte message
1	0	1	${f E}$	D	\mathbf{C}	В	A	4 byte message
1	1	0	${ m E}$	D	\mathbf{C}	В	A	6 byte message
1	1	1	\mathbf{E}	D	\mathbf{C}	В	A	Variable length message. The next byte in
								the message is a 7 bit byte count.

The A,B,C,D,E are bits available to encode 32 opcodes per message length.

1.3 Refresh Slots

The model of the master refresh stack is an array of up to 120 read/write refresh slots. The slot address is a principal component and is generally the second byte or 1st argument of a message to the master. The refresh slot contains up to 10 data bytes relating to a locomotive and also controls a task in the track DCC refresh stack. Most mobile decoder or locomotive operations process the slot associated with the locomotive to be controlled. The slot number is a similar shorthand ID# to a file handle. Slot addresses 120-127 are reserved for system and master control. Slot #124 (0x7C) is allocated for read/write access to the programming track, and the format of the 10 data bytes is not the same as a normal slot.

1.3.1 Slot Format

Slots 0 to 119

Byte 0:

d7	d6 d5	d4 d	d3 d2 d1 d0	<stat1></stat1>	Slot status 1.
	d7	d6			
	0	0	Free, no consist	linking.	
	0	1	Consist sub-me	ember.	
	1	0	Consist top-me	mber.	
	1	1	Consist Mid-Co	onsist member.	

Note: d7 is set to 0 in the message by the command station and so may not correctly reflect the actual setting in the slot table.

	$\underline{\mathrm{d}5}$	$\underline{d4}$	
	0	0	Free slot, no valid data. Not refreshed.
	0	1	Common. Locomotive address in this slot. Refreshed.
	1	0	Idle. Locomotive address in this slot. Not refreshed.
	1	1	In Use. Locomotive address in this slot. Refreshed.
		<u>d3</u>	
		0	No slot consist linked into this slot.
		1	Slot consist linked into this slot.
$\underline{d2}$	<u>d1</u>	<u>d0</u>	
0	0	0	28 step decoder. 3-byte packet regular mode
0	0	1	28 step decoder. Generate trinary packets for this mobile address
0	1	0	14 step decoder.
0	1	1	128 step decoder.
1	0	0	28 step decoder. Allow advanced consisting
1	0	1	reserved
1	1	0	reserved
1	1	1	128 step decoder. Allow advanced consisting
Rvte 1			

Byte 1:

0	n	n	n	n	n	n	n	<ADR $>$	Low address.
---	---	---	---	---	---	---	---	----------	--------------

Byte 2:

v									
0	n	n	n	n	n	n	n	$\langle SPD \rangle$	Speed in the range 0x00 to 0x7F. 0x00 means
	'						•		inertial stop and $0x01$ means emergency stop.
									Other values mean increasing speed.

Byte 3:

0	d6	d5	d4	d3	d2	d1	d0	<dirf></dirf>	Locomotive direction and state of functions
									F0 to F4.

- d6 Reserved. Set to 0.
- d5 Locomotive direction. 1 means forward, 0 means backwards.
- d4 F0 state. 1 means on, and 0 means off.
- d3 F4 state. 1 means on, and 0 means off.
- d2 F3 state. 1 means on, and 0 means off.
- d1 F2 state. 1 means on, and 0 means off.
- d0 F1 state. 1 means on, and 0 means off.

Byte 4:

1.3. REFRESH SLOTS	5
d6 Reserved. Set to 0.	
d5 Reserved. Set to 0.	
d4 Reserved. Set to 0.	
d3 1 means the programming track is busy.	
d2 1 means this master implements LocoNet version 1.1	
capability, 0 means the master is a DT200.	
d1 0 means the track is paused, broadcast an emergency	
stop.	
d0 1 means the DCC packets are on in the master, global	
power up.	
Byte 5:	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	
d6 Reserved. Set to 0.	
d5 Reserved. Set to 0.	
d4 Reserved. Set to 0.	
d3 1 means expansion in $ID1/2$, 0 means encoded alias.	
d2 1 means expansion $ID1/2$ is not ID usage.	
d1 Reserved. Set to 0.	
d0 1 means this slot has suppressed advanced consist.	
Byte 6:	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	
Ryte 7:	

Byte 7:

0	d6	d5	d4	d3	d2	d1	d0	$\langle SND \rangle$	Slot sound /	/ function mode II packets.
---	----	----	----	----	----	----	----	-----------------------	--------------	-----------------------------

- d6Reserved. Set to 0.
- Reserved. Set to 0. d5
- d4Reserved. Set to 0.
- Sound 4 / F8. Sound 3 / F7. d3
- d2
- Sound 2 / F6. d1
- Sound 1 / F5. d0

Byte 8:

0	n	n	n	n	n	n	n	<id1></id1>	7-bit ls	s ID	code	written	by	throttle	when
									STAT2	2.4 =	1.				

Byte 9:

0	n	n	n	n	n	n	n	<ID2 $>$	7-bit ms ID code written by throttle when
									STAT2.4 = 1.

Slot 0x7F

OST1 to OST6 encode the command station's option switch table. The narrative is based upon information in the the DCS210 and DCS240 user manuals. A bit value of 1 means that the switch is closed and a value of 0 means that a switch is thrown. OpSw 8, OpSw 16, OpSw 24, OpSw 32 and OpSw 40 cannot be read due to bit 7 being cleared in the message format. The manual shows these switches as defaulting to thrown, i.e. 0, and are flagged in all cases except OpSw 40 as "do not change".

Byte 0:

0	d6 d5 d4	$d3 \mid d2 \mid d1 \mid$	d0 <ost1> Option switch table byte 1.</ost1>
Bit	Switch #	<u>Default</u>	Effect on system operation
d6	OpSw 07	\mathbf{t}	do not change
d5	OpSw~06	\mathbf{t}	t = check for decoder before programming
			c = program without checking for device
d4	OpSw~05	\mathbf{t}	do not change
d3	OpSw 04	\mathbf{t}	do not change
d2	OpSw~03	\mathbf{t}	t = command station's booster normal
			c = command station's booster is auto reversing
d1	OpSw~02	t	t = command station mode
			c = booster only mode.
d0	${\rm OpSw}~01$	\mathbf{t}	do not change.

Byte 1:

0	d6 d5 d4	$d3 \mid d2 \mid d1 \mid$	d0 <ost2> Option switch table byte 2.</ost2>
$\frac{\text{Bit}}{\text{d6}}$	$\frac{\text{Switch } \#}{\text{OpSw 15}}$	$\frac{\mathrm{Default}}{\mathrm{t}}$	Effect on system operation t = purging will not change loco speed c = purging will force a loco to 0 speed
d5	OpSw 14	t	t = loco address purging enabled c = loco address purging disabled
d4	OpSw 13	t	t = loco address purge time 200 seconds c = loco address purge time 600 seconds
d3	OpSw 12	t	do not change
d2	OpSw 11	\mathbf{t}	do not change
d1	OpSw 10	\mathbf{c}	do not change
d0	OpSw~09	\mathbf{c}	do not change

Byte 2:

0	d6 d5	d4	d3 d	2 d1	d0	$\langle OST3 \rangle$	Option switch table byte 3.
---	-------	----	------	------	----	------------------------	-----------------------------

$\underline{\mathrm{Bit}}$	Switch #	<u>Default</u>	Effect on system operation
d6	$\overline{\mathrm{OpSw}\ 23}$	\mathbf{t}	$\overline{\mathrm{SW23}}$
d5	OpSw 22	\mathbf{c}	SW22
d4	OpSw 21	\mathbf{c}	SW21
d3	$\overline{\mathrm{OpSw}}\ 20$	\mathbf{t}	t = enable address 0x00 or analog stretching for conven-
	_		tional locos
			. $c = disable address 0x00 or analog stretching for con-$
			ventional locos
d2	OpSw 19	\mathbf{t}	do not change
d1	OpSw 18	\mathbf{t}	t = normal command station booster short circuit shut-
	-		down time
			c = extended command station booster short circuit
			shutdown time
d0	OpSw 17	\mathbf{t}	t = automatic advanced decode (FX) consists are enabled
	•		c = automatic advanced decode (FX) consists are dis-
			abled

$\underline{SW21}$	SW22	SW23	Global system default type for new locos
\mathbf{t}	\mathbf{t}	\mathbf{t}	28 step mode
\mathbf{t}	\mathbf{t}	\mathbf{c}	reserved
\mathbf{t}	\mathbf{c}	\mathbf{t}	14 step mode
\mathbf{t}	\mathbf{c}	\mathbf{c}	reserved
\mathbf{c}	\mathbf{t}	\mathbf{t}	reserved
\mathbf{c}	\mathbf{t}	\mathbf{c}	reserved
\mathbf{c}	\mathbf{c}	\mathbf{t}	128 step mode
С	С	С	128 step FX mode

Byte 3:

0	d6	d5	d4	d3	d2	d1	d0	$\langle OST4 \rangle$	Option switch table byte 4.
---	----	----	----	----	----	----	----	------------------------	-----------------------------

Switch $\#$	<u>Default</u>	Effect on system operation
$\overline{\mathrm{OpSw}\ 31}$	t	$\overline{t = \text{normal route/switch o}}$ utput rate when not trinary
		c = fast route/switch output rate when not trinary
OpSw~30	\mathbf{t}	do not change
OpSw 29	\mathbf{t}	do not change
OpSw 28	\mathbf{t}	t = enable interrogate commands at power on
		c = disable interrogate commands at power on
OpSw 27	\mathbf{t}	t = enable normal switch commands, a.k.a. the "Bushby"
		bit"
		c = disable normal switch commands, a.k.a. the "Bushby"
		bit" (allows attached computer to handle switch control
		logic)
OpSw 26	\mathbf{c}	t = disable routes
		c = enable routes
OpSw~25	\mathbf{t}	t = enable route echo over LocoNet
		c = disbale route echo over LocoNet
	OpSw 31 OpSw 30 OpSw 29 OpSw 28 OpSw 27 OpSw 27	OpSw 31 t OpSw 30 t OpSw 29 t OpSw 28 t OpSw 27 t OpSw 26 c

Byte 4:

0	d6	d5	d4	d3	d2	d1	d0	<TRK $>$	Global system track status.
---	----	----	----	----	----	----	----	----------	-----------------------------

- d6 Reserved. Set to 0.
- d5 Reserved. Set to 0.
- d4 Reserved. Set to 0.
- d3 1 means the programming track is busy.
- d2 1 means this master implements LocoNet version 1.1 capability, 0 means the master is a DT200.
- d1 0 means the track is paused, broadcast an emergency stop.
- d0 $\,$ 1 means the DCC packets are on in the master, global power up.

Byte 5:

0	d6	d5	d4	d3	d2	d1	d0	$\langle OST5 \rangle$	Option switch	table byte 5.
---	----	----	----	----	----	----	----	------------------------	---------------	---------------

$\underline{\mathrm{Bit}}$	Switch $\#$	<u>Default</u>	Effect on system operation
d6	$\overline{\mathrm{OpSw}\ 39}$	\mathbf{t}	$\overline{c = clear}$ all internal memory states, including OpSw 36
			and 37
d5	OpSw~38	\mathbf{t}	t = loco reset button activates OpSw 39
			c = loco reset activates slot zero
d4	OpSw 37	\mathbf{t}	c = clears all routes
d3	OpSw~36	\mathbf{t}	c = clears all mobile decoder info and consists
d2	OpSw~35	\mathbf{t}	t = enables loco reset buttone
			c = disable loco reset button
d1	OpSw 34	t	t = disallow track to power up to run state, if set to run
			prior to power up
			c = allow track to power up to run state, if set to run
			prior to power up
d0	OpSw~33	\mathbf{c}	t = track power off at power on
			c = allow track power to restore to prior state at power
			on

Byte 6:

0	d6 d5 d4	$d3 \mid d2 \mid d1 \mid$	d0 <ost6> Option switch table byte 6.</ost6>
Bit	Switch #	<u>Default</u>	Effect on system operation
d6	$\overline{\mathrm{OpSw}\ 47}$	t	$\overline{t = normal program track}$ setting
			c = program track is brake generator when not program-
			ming. Braking is DCC set to speed 0 (not emergency
			stop) for address 0, light on, broadcast to all addresses.
d5	OpSw 46	t	do not change
d4	OpSw 45	t	t = enable reply for switch state request
			c = disable reply for switch state request
d3	OpSw 44	t	do not change
d2	OpSw 43	t	t = enable LocoNet update of command station's track
			status
			c = disable LocoNet update of command station's track
			status
d1	OpSw 42	t	t = enable 2 short beeps when loco address purged
			c = disable 2 short beeps when loco address purged
d0	OpSw 41	t	t = diagnostic click disabled
			c = diagnostic click when valid LocoNet commands in-
			coming and routes being output

Byte 7:

0	d6 $d5$	d4 d3	d2 d1	d0	Unknown
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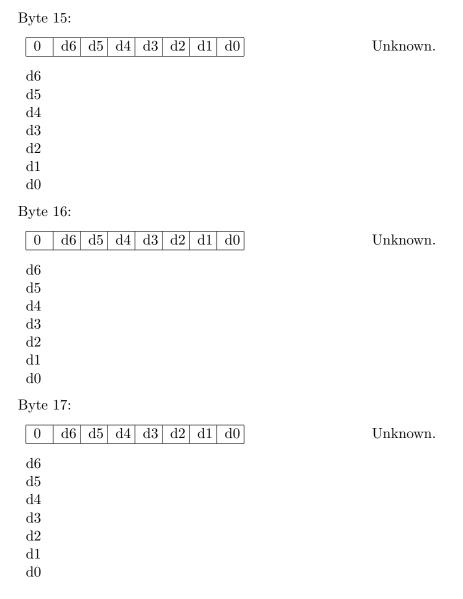
d6						
d5						
d4						
d3						
d2						
d1						
d0						
Byte 3:						
0 r	n n	n r	n n	n n	<adr></adr>	Low address.
Byte 4:						
0 r	n n	n r	n n	n n	<ADR2 $>$	High address.
Byte 5:						
0	d6 d5	d4 (d3 d2	d1 d0	<TRK $>$	Global system track status.
d6	Dogory	rod S	et to 0			
d5			et to 0 et to 0			
d4			et to 0			
d3					ack is busy.	
d2				_	ents LocoNet ver	sion 1.1
				-	er is a DT200.	
d1	-				broadcast an em	ergency
	stop.			,		5 2
d0	_	ns the	DCC	packets are	on in the master	r, global
	power	up.				
Byte 6:						
Б у (С. 0.						

0	d6 d5	d4 d3	d2 d1	d0	Unknown.
d6					
d5					
d4					
d3					
d2					
d1					
d0					
Byte	7:				
0	d6 d5	d4 d3	d2 d1	d0	Unknown.

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$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Unknown.
d6	
d5	
d4	
d3	
d2	
d1	
d0	
Byte 12:	
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Unknown.
d6	
d5	
d4	
d3	
d2	
d1	
d0	
Byte 13:	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Unknown.
d6	
d5	
d4	
d3	
d2	
d1	
d0	
Byte 14:	
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Unknown.
d6	
d5	
d4	
d3	
d2	
d1	
d0	



1.4 Standard Address Selection

To request a mobile or locomotive decoder task in the refresh stack, a throttle device requests a locomotive address for use, (opcode OPC_LOCO_ADR). The master (or computer in a limited master environment) responds with a slot data read for the slot, (OPC_SL_RD_DATA), that contains this locomotive address and all of its state information. If the address is currently not in any slot, the master will load this new locomotive address into a new

slot (speed=0, direction forwards, functions off and 128 step mode) and return this as a OPC_SL_RD_DATA. If no inactive slots are free to load the new locomotive address, the response will be the OPC_LONG_ACK with a fail code 0x00.

The throttle/computer must then examine the slot data bytes to work out how to process the master response. If the slot status 1 byte shows the slot to be common idle or new the throttle may change the slot to in use by performing a null move instruction (see OPC_MOVE_SLOTS) on this slot. This activation mechanism is used to guarantee proper slot usage interlocking in a multi-user asynchronous environment.

If the slot return information shows the locomotive requested is in use or up-consisted (i.e. the SL_CONUP , bit 6 of slot status 1=1) the user should not use the slot. Any up-consisted locomotives must be unlinked before usage. Always process the result from the OPC_LINK_SLOTS and OPC_UNLINK_SLOTS commands, since the master reserves the right to change the reply slot number and can reject the linking tasks under several circumstances. Verify the reply slot number and the link UP/DN bits in slot status 1 are as you expected.

The throttle will then be able to update speed, direction and function information. Whenever slot information is changed in an active slot, the slot is flagged to be updated as the next DCC packet sent to the track. If the slot is part of linked consist slots the whole consist chain is updated consecutively.

If a throttle is disconnected from the LocoNet, upon reconnection (if the throttle retains the slot state from before disconnection) it will request the full status of the slot it was previously using. If the reported status and speed, function data etc., from the master exactly matches the remembered slot state the throttle will continue using the slot. If the SLOT data does not match, the throttle will assume the slot was purged free by the system and will go through the setup log on procedure again.

With this procedure the throttle does not need to have a unique ID number. slot addresses do not imply they contain any particular locomotive address. The system can be mapped such that the slot address matches the locomotive address within, if the user directly reads and writes to slots without using the master to allocate locomotive addresses.

1.5 Opcodes

OPC_BUSY

Operation: Indicates that the master is busy.

Group: 2-Byte Message

Direction: \leftrightarrow Command Station

Encoding:

Byte 0:

|--|

Byte 1:

0	1	1	1	1	1	1	0	0x7E	Checksum.

Description:

This message indicates that the master is busy. When sent to a command station it responds with an OPC_PEER_XFER message.

Response:

None.

Notes:

None.

OPC_CONSIST_FUNC

Operation: Set function bits in a consist uplink element.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

	_	-	-4		-4		_	0. D.0	O 1
	()		I I	()	I I	I I	()	l OvB6	()ncode
1		I	_ T	1 0	1	T		UADU	Opcode.
	_	l .		_		l .	_		- I

Byte 1:

0	n	n	n	n	n	n	n	<slot#></slot#>	Slot number in the range $0x00$ to $0x7F$
---	---	---	---	---	---	---	---	-----------------	---

Byte 2:

- d6 Reserved. Set to 0.
- d5 Locomotive direction. 1 means forward, 0 means backwards.
- d4 F0 state. 1 means on, and 0 means off.
- d3 F4 state. 1 means on, and 0 means off.
- d2 F3 state. 1 means on, and 0 means off.
- d1 F2 state. 1 means on, and 0 means off.
- d0 F1 state. 1 means on, and 0 means off.

Byte 3:

0	n	n	n	n	n	n	n	<CHK $>$	Checksum

Description:

This function sets the consist element's direction and function F0 to F4 states.

Response:

None.

Notes:

None.

OPC_GPOFF

Operation: Global power off request.

Group: 2-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

1	0	0	0	0	0	1	0	0x82	Opcode

Byte 1:

0	1	1	1	1	1	0	1	0x7D	Checksum.
---	---	---	---	---	---	---	---	------	-----------

Description:
This command turns off the track power.
Response:
None.
Notes:
None.

OPC_GPON

Operation: Global power on request.

Group: 2-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

1	0	0	0	0	0	1	1	0x83	Opcode.
								•	

Byte 1:

()	1	1	1	1	1	0	0	0x7C	Checksum.
---	---	---	---	---	---	---	---	---	------	-----------

Description:

This command sends a global power on request.

Response:

The command station sends an OPC_RQ_SL_DATA message for slot 0x7F. It also sends a sequence of OPC_SW_REQ messages with the following values of SW1 and SW2:

1.5. OPCODES 19 $\underline{\mathrm{SW1}}$ $\underline{SW2}$ 0x780x270x790x270x7A0x270x7B0x270x78ox070x790x070x7A0x070x7B0x07 $\underline{\text{Notes:}}$ None. OPC_IDLE Operation: Force idle state and broadcast emergency stop. Group: 2-Byte Message $\underline{\text{Direction:}} \ \to \text{Command Station}$ Encoding: Byte 0: 1 0 0 0 0 1 0 1 0x85Opcode. Byte 1: 0 1 1 1 1 0 1 0 0x7AChecksum. Description: This command forces LocoNet into the idle state and broadcasts an emergency stop. Response:

None

Notes:

None.

OPC_IMM_PACKET

Operation: Send n-byte packet immed	liate.	
Group: Variable-Byte Message		
$\underline{\text{Direction:}} \rightarrow \text{command station}$		
Encoding:		
Byte 0:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	0xED	Opcode.
Byte 1:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	0x0B	Message length (11 bytes).
Byte 2:		
$egin{array}{ c c c c c c c c c c c c c c c c c c c$	0x7F	Source id in the range 0x00 to 0x7F.
Byte 3:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	<reps></reps>	Number of immediate bytes and repeat count.
d6 N2. Number of immediate by d5 N1. Number of immediate by d4 N0. Number of immediate by d3 A4. Reserved. Set to 0. d2 R2. Repeat count. d1 R1. Repeat count. d0 R0. Repeat count.	tes.	
Byte 4:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	<dhii></dhii>	High bits of IM1 to IM5.
 d4 IM5.7. High bit. d3 IM4.7. High bit. d2 IM3.7. High bit. d1 IM2.7. High bit. d0 IM1.7. High bit. 		

<IM1>

Data item 1 low 7 bits.

Byte 6:

| d6 | d5 | d4 | d3 | d2 | d1 | d0 |

Byte 5:

0

d6 d5 d4 d3 $d2 \mid d1 \mid d0$ 0 <IM2>Data item 2 low 7 bits. Byte 7: 0 d6 d5d4 d3d2 d1 d0Data item 3 low 7 bits. <IM3> Byte 8: d4 d30 d6 d5 $d2 \mid d1 \mid$ d0<IM4>Data item 4 low 7 bits. Byte 9: 0 $d6 \mid d5 \mid$ d4 d3d2 d1d0Data item 5 low 7 bits. <IM5>Byte 10:

n

n

<CHK>

Checksum.

Description:

n

n

0

Send n-byte packet immediate.

n

 \mathbf{n}

n

Response:

OPC_LONG_ACK.

Notes:

None.

OPC_INPUT_REP

Operation: General sensor input report.

Group: 4-Byte Message

Direction: General sensor \rightarrow

Encoding:

Byte 0:

 1
 0
 1
 1
 0
 0
 1
 0
 0xB2
 Opcode.

Byte 1:

- d6 A7.
- d5 A6.
- d4 A5.
- d3 A4.
- d2 A3.
- d1 A2.
- d0 A1.

Byte 2:

- d5 A0.
- d4 Input state. 1 means sensor input >= 6V, and 0 means sensor input = 0V.
- d3 A11.
- d2 A10.
- d1 A9.
- d0 A8.

Byte 3:

0	n	n	n	n	n	n	n	<CHK $>$	Checksum.
---	---	---	---	---	---	---	---	----------	-----------

Description:

General sensor report.

Response:

None.

Notes:

None.

OPC_LINK_SLOTS

Operation: Link slots.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

1 0 1 1 1 0 0 1 0xB9 Opcode.

Byte 1:

Byte 2:

Byte 3:

Description:

This function links slot SL1 to slot SL2. The command station setsSL_CONUP/DN flags appropriately. Invalid link will return a fail acknowledgement.

Response:

OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_LOCO_ADR

Operation: Request a slot number for a locomotive.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

1 0 1 1 1 1 1 0xBF Opcode.

Byte 1:

Byte 2:

	0	n	n	n	n	n	n	n	<ADR $>$	Low address.
Е	Byte	3:								

Description:

This message requests the slot number for the selected locomotive address. If the locomotive is found in the slot table then the command station returns an OPC_SL_RD_DATA message with the slot information. If it is not found then the command station will put the locomotive into a free slot and then return an OPC_SL_RD_DATA message with the slot information. If there are no free slots then the command station returns an OPC_LONG_ACK error code.

Note that regular short 7 bit NMRA addresses are denoted by $\langle ADR2 \rangle = 0$. The Analog, zero stretched, locomotive is selected when both $\langle ADR2 \rangle = 0$ and $\langle ADR \rangle = 0$. $\langle ADR \rangle$ is always a 7 bit value. If $\langle ADR2 \rangle$ is non-zero then the master will generate NMRA type 14 bit or long address packets using all 14 bits from $\langle ADR2 \rangle$ and $\langle ADR \rangle$ with $\langle ADR2 \rangle$ being the most significant address bits. Note that a DT200 Master does not process 14 bit address requests and will consider the $\langle ADR2 \rangle$ to be zero. You can check the $\langle TRK \rangle$ return bits to see if the master is a DT200.

Response:

OPC_SL_RD_DATA if success, otherwise OPC_LONG_ACK.

Notes:

The LocoNet 1.1 specification specifies that <ADR2> value is 0x00.

OPC_LOCO_ADR_EXT

Operation: Request an extended slot for a locomotive.

Group: 4-Byte Message

Direction: \rightarrow Command Station

Encoding:

Byte 0:

	1	0	1	1	1	1	1	0	0xBE	Opcode.
Ε	Byte	1:								
	0	n	n	n	n	n	n	n	<adr2></adr2>	High address.
Ε	Byte	2:								
	0	n	n	n	n	n	n	n	<adr></adr>	Low address.
Ε	Byte	3:								
	0	n	n	n	n	n	n	n	<chk></chk>	Checksum.

Description:

This message requests the slot number for the selected locomotive address. If the locomotive is found in the slot table then the command station returns an OPC_SL_RD_DATA_EXT message with the slot information. If it is not found then the command station will put the locomotive into a free slot and then return an OPC_SL_RD_DATA_EXT message with the slot information. If there are no free slots then the command station returns an OPC_LONG_ACK error code.

Note that regular short 7 bit NMRA addresses are denoted by $\langle ADR2 \rangle = 0$. The Analog, zero stretched, locomotive is selected when both $\langle ADR2 \rangle = 0$ and $\langle ADR \rangle = 0$. $\langle ADR \rangle$ is always a 7 bit value. If $\langle ADR2 \rangle$ is non-zero then the master will generate NMRA type 14 bit or long address packets using all 14 bits from $\langle ADR2 \rangle$ and $\langle ADR \rangle$ with $\langle ADR2 \rangle$ being the most significant address bits. Note that a DT200 Master does not process 14 bit address requests and will consider the $\langle ADR2 \rangle$ to be zero. You can check the $\langle TRK \rangle$ return bits to see if the master is a DT200.

Response:

OPC_SL_RD_DATA_EXT if success, otherwise OPC_LONG_ACK.

Notes:

None.

OPC_LOCO_DIRF

Operation: Set locomotive direction and function F0 to F4 states.

Group: 4-Byte Message

Direction: \rightarrow Command Station Encoding: Byte 0: 1 0 1 0 0 0 1 0xA1Opcode. Byte 1: 0 n n n \mathbf{n} \mathbf{n} n n <SLOT#>Slot number in the range 0x00 to 0x7F. Byte 2: 0 d6d5d4d3d2d1d0<DIRF> Locomotive's direction and state of functions F0 to F4. Reserved. Set to 0. d6Locomotive direction. 1 means forward, 0 means backwards. d5d4F0 state. 1 means on, and 0 means off. d3F4 state. 1 means on, and 0 means off. d2F3 state. 1 means on, and 0 means off. d1F2 state. 1 means on, and 0 means off. d0F1 state. 1 means on, and 0 means off. Byte 3: 0 <CHK> Checksum. \mathbf{n} n n \mathbf{n} n n n Description: This function sets the locomotive's direction and function F0 to F4 states. Response: None. Notes: None.

OPC_LOCO_RESET

Operation: Loco reset button has been pressed on the command station.

Group: 2-Byte Message

<u>Direction:</u> Command Station \rightarrow Encoding: Byte 0: Opcode. 1 0 0 0 1 0 1 0 0x8AByte 1: 0 1 1 1 0 1 01 0x75Checksum. Description: The Loco reset button has been pressed. Response: None, this is a response. Notes: None. OPC_LOCO_SND Operation: Set locomotive sound functions. Group: 4-Byte Message $\underline{\text{Direction:}} \rightarrow \text{Command Station}$ Encoding: Byte 0: Opcode. 0 1 0 0 0 0 0xA21

<SLOT#>

 $\langle SND \rangle$

Slot number in the range 0x00 to 0x7F.

Locomotive's function F5 to F8 states.

Byte 1:

0 n

Byte 2:

0

n

 $n \mid n$

n

d6 d5 d4 d3 d2 d1 d0

n

 \mathbf{n}

- d6 Reserved. Set to 0.
- d5 Reserved. Set to 0.
- d4 Reserved. Set to 0.
- d3 Reserved. Set to 0.
- d3 Sound 4 / F8.
- d2 Sound 3 / F7.
- d1 Sound 2 / F6.
- d0 Sound 1 / F5.

Byte 3:

0	n	n	n	n	n	n	n	<chk></chk>	Checksum

Description:

This function sets the locomotive's function F5 to F8 states.

Response:

None.

Notes:

None.

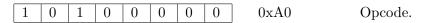
OPC_LOCO_SPD

Operation: Set locomotive speed.

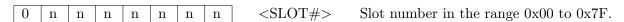
Group: 4-Byte Message

Encoding:

Byte 0:



Byte 1:



Byte 2:

Locomotive speed in the range 0x00 to 0x7F. 0x00 means inertial stop and 0x01 means emergency stop. Other values mean increasing speed.

Byte 3:

Description:

This function sets the locomotive's speed.

Response:

None.

Notes:

None.

OPC_LOCO_SPD_DIRF_EXT

Operation: Set locomotive speed, direction, and functions for extended slots.

Group: 6-Byte Message

Direction: \rightarrow Command Station

Encoding:

Byte 0:

1	1 0	1	0	1	0	0	0xD4	Opcode.
---	-----	---	---	---	---	---	------	---------

Byte 1:

0 0 1 0 0 0 1 0x21 Unknown - It might be the high slot address with a mask in high nibble.

Byte 2:

Byte 3:

Checksum.

0x04Set speed. 0x05Set functions F12, F20, F28. 0x06Set direction and functions F0 to F4. 0x07Set functions F5 to F11. Set functions F13 to F19. 0x08Set functions F21 to F27. 0x09Sound 1 / F5. d0Byte 3: 0 <CHK> \mathbf{n} n n n n n n Description: This function sets the locomotive's function F5 to F8 states.

Response:

None.

Notes:

None.

OPC_LONG_ACK

Operation: Long acknowledge.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:

1	0	1	1	0	1	0	0	0xB4	Opcode

Byte 1:

Byte 2:

Byte 3:

0	n n	n	n	n	n	n	<CHK $>$	Checksum.
---	-----	---	---	---	---	---	----------	-----------

Description:

This message provides a response code from a command.

Response:

None, it is the response.

Notes:

Responding ()pcode	\leq LOPC $>$	\leq ACK1 \geq	Meaning
OPC_SW_AC	K	0x3D	0x00	$\overline{\rm DCS100}$ FIFO is full, command rejected.
OPC_SW_AC	K	0x3D	0x7F	DCS100 command accepted.
OPC_MOVE	SLOTS	0x3A	0x00	Illegal move.
OPC_LINK_S	LOTS	0x39	0x00	Invalid link, link failed.
OPC_SW_RE	Q	0x30	0x00	Command failed.
OPC_LOCO_	ADR	0x3F	0x00	No free slot, command failed.
OPC_IMM_P.	ACKET	0x7D	0x7F	Command OK, if not limited master.
OPC_IMM_P	ACKET	0x7E	<lim address $>$	Command OK, if limited master.
OPC_IMM_P	ACKET	0x7D	0x00	Internal buffer busy or full.

$\mathbf{OPC_MOVE_SLOTS}$

Operation: Move slot.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \ \to \text{Switch}$

Encoding:

Byte 0:

	0xBA	Opcode.
Byte 1:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	<src></src>	Source slot number in the range $0x00$ to $0x77$.
Byte 2:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	<dest></dest>	Destination slot number in the range $0x00$ to $0x77$.

Byte 3:

Destination id low in the range 0x00 to 0x7F.

	0	n	n	n	n	n	n	n	<chk></chk>	Checksum.
								•		
Ι	escr	iptic	n:							

Move slots.

SRC 0x00	DEST Don't Care	Action Dispatch get. Return slot read of dispatch slot.
SRC	SRC	Null move. SRC is set to in use.
SRC	0x00	Dispatch put. Mark slot as dispatch.
SRC	DEST	Move slot data from SRC to DEST if not in
		use. Clear SRC.

Response:

OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_PEER_XFER

Operation: Move 8 bytes peer to peer.

Variable-Byte Message Group:

Direction: device \rightarrow device

n n

n

 \mathbf{n}

 $n \mid n \mid n$

Encoding:		
Byte 0:		
1 1 1 0 0 1 0 1	0xE5	Opcode.
Byte 1:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	0x10	Message length (16 bytes).
Byte 2:		
$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	<src></src>	Source id in the range $0x00$ to $0x7F$.
Byte 3:		

 $\langle DSTL \rangle$

Byte 4:

Byte 5:

0	d6	d5	d4	d3	d2	d1	d0	<pxct1></pxct1>	Address type c	code a	and high	bits of	D1 to 1	D4.
---	----	----	----	----	----	----	----	-----------------	----------------	--------	----------	---------	---------	-----

- d6 XC2. Address type code.
- d5 XC1. Address type code.
- d4 XC0. Address type code.
- d3 D4.7. High bit
- d2 D3.7. High bit
- d1 D2.7. High bit
- d0 D1.7. High bit

$\underline{\text{XC2}}$	$\underline{\text{XC1}}$	$\underline{\text{XC0}}$	Meaning
0	0	0	7 bit peer to peer addresses.
0	0	1	reserved.
0	1	0	reserved.
0	1	1	reserved.
1	0	0	reserved.
1	0	1	reserved.
1	1	0	reserved.
1	1	1	reserved.

Byte 6:

0	n n n	n n n	<d1></d1>	Data item 1. Low 7 b
---	-------	-------	-----------	----------------------

Byte 7:

0	n	n	n	n	n	n	n	<d2></d2>	Data item 2. Low 7 bits
---	---	---	---	---	---	---	---	-----------	-------------------------

Byte 8:

								۲D95	D 4 24 9 T 7124
0	n	n	n	n	n	n	n	<d3></d3>	Data item 3. Low 7 bits.

Byte 9:

Byte 10:

0

- d6 XC5. Data type code.
- d5 XC4. Data type code.
- d4 XC3. Data type code.
- d3 D8.7. High bit
- d2 D7.7. High bit
- d1 D6.7. High bit
- d0 D5.7. High bit

$\underline{\text{XC5}}$	$\underline{\text{XC4}}$	$\underline{XC3}$	Meaning
0	0	0	ANSI text string.
0	0	1	reserved.
0	1	0	reserved.
0	1	1	reserved.
1	0	0	reserved.
1	0	1	reserved.
1	1	0	reserved.
1	1	1	reserved.

Byte 11:

0	n n	n	n	n	n	n	$\langle D5 \rangle$	Data item 5. Low 7 bit
---	-----	---	---	---	---	---	----------------------	------------------------

Byte 12:

0	n	n	n	n	n	n	n	<d6></d6>	Data item 6. Low 7 bits.
---	---	---	---	---	---	---	---	-----------	--------------------------

Byte 13:

0	$\mid \mathbf{n} \mid$	n	n	n	n	n	n	<D7 $>$	Data item 7. Low 7 bits
---	------------------------	---	---	---	---	---	---	---------	-------------------------

Byte 14:

0	n	n	n	n	n	n	n	<d8></d8>	Data item 8. Low 7 bits.
---	---	---	---	---	---	---	---	-----------	--------------------------

Byte 15:

0	n	n	n	n	n	n	n	<chk></chk>	Checksum.

Description:

This command sends the data from one device to another peer to peer.

$\underline{\operatorname{SRC}}$	$\overline{\mathrm{DSTL}}$	$\overline{\mathrm{DSTH}}$	Comments
0x00			Source is command station.
Don't Care	0x00	0x00	Broadcast Message.
0x70 to $0x7E$			Reserved.
0x7F	0x00	0x00	Broadcast throttle message transfer.
0x7F	ID1	ID2	Throttle message transfer. ID1 and
			ID2 encode ID.

Response:

None

Notes:

None.

$OPC_RQ_SL_DATA$

Operation: Request slot data or status block.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \ \to \text{Switch}$

Encoding:

Byte 0:

|--|

Byte 1:

0	n	n	n	n	n	n	n	<slot#></slot#>	Slot number in the range 0x00 to 0x7F. 0 re-
									turns the command station status block

Byte 2:

0	0	0	0	0	0	0	0	0x00	Reserved.
---	---	---	---	---	---	---	---	------	-----------

Byte 2: (extended)

Byte 3:

0	n	n	n	n	n	n	n	<chk></chk>	Checksum.
---	---	---	---	---	---	---	---	-------------	-----------

Description:

Request slot data or status block.

Response:

if SLOTH = 0x00 then OPC_SL_RD_DATA, otherwise OPC_SL_RD_DATA_EXT.

Notes:

None.

OPC_SL_RD_DATA

Operation: Returns slot data.

Group: Variable-Byte Message

Direction: Command Station \rightarrow

Encoding:

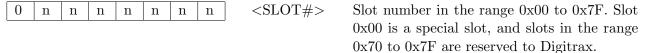
Byte 0:

1	1	1	0	0	1	1	1	0xE7	Opcode.
_	_	_	_		_	_	_	· · · · · · · · · · · · · · · · · · ·	- P

Byte 1:

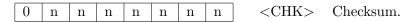
0	1	1	1	1	1	1	0	0x0E	Message length (14 bytes).
---	---	---	---	---	---	---	---	------	----------------------------

Byte 2:



Bytes 3 to 12 encode as per slot bytes 0 to 9.

Byte 13:



Description:

This message is sent by the command station in response to a slot data request.

Response:

None.

1.5. OPCODES 37 Notes: None. $OPC_SL_RD_DATA_EXT$ Operation: Returns extended slot data. Group: Variable-Byte Message <u>Direction</u>: Command Station \rightarrow Encoding: Byte 0: 1 1 1 0 0 1 1 0 0xE6Opcode. Byte 1: 0 0 0 1 0 1 0 1 0x15Message length (21 bytes). Bytes 2 to XX encode as per extended slot bytes 0 to YY. Byte 20: 0 <CHK> n n n \mathbf{n} \mathbf{n} n \mathbf{n} Checksum. Description: This message is sent by the command station in response to an extended slot data request. Response: None.

OPC_SLOT_STAT1

Notes:

None.

Operation: Set slot status 1.

4-Byte Message Group: $\underline{\text{Direction:}} \rightarrow \text{Command Station}$ Encoding: Byte 0: 1 0xB5Opcode. 0 1 1 1 1 Byte 1: 0 <SLOT#>Slot number in the range 0x00 to 0x7F. \mathbf{n} n \mathbf{n} \mathbf{n} \mathbf{n} Byte 2: 0 Slot status 1. See OPC_SL_RD_DATA for bit d6d5d4d3d2d1d0<STAT1>encoding details. Byte 3: 0 <CHK> Checksum. n n n n \mathbf{n} \mathbf{n} n Description: This function sets the slot's status 1 values. Response: None. Notes: None.

OPC_SW_ACK

Operation: Request switch command with acknowledge.

Group: 4-Byte Message

Direction: \rightarrow Turnout controller

Encoding:

Byte 0:

1	0	1	1	1	1	0	1	0xBD	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	d6 d5	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	<sw1></sw1>	Switch address A6 to A0.
d6	A6.			
1-	110.			

- d5A5.
- d4A4.
- d3A3.
- d2A2.
- d1A1.
- d0A0.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	$\langle SW2 \rangle$	Switch address A10 to A7 and switch cont		
									bits.		

- d6Reserved. Set to 0.
- 1 means closed/green, and 0 means d5Direction. thrown/red.
- Output. 1 means on, and 0 means off. d4
- d3A10.
- d2A9.
- d1A8.
- d0A7.

Byte 3:

0	n	n	n	n	n	n	n	<chk></chk>	Checksum.

Description:

Command a turnout controller to a specified state and send acknowledge.

Response:

OPC_LONG_ACK.

Notes:

None.

OPC_SW_REP

C	peration:	Turnout	sensor	report.
---	-----------	---------	-------------------------	---------

0 d6 d5 d4 d3 d2 d1 d0

Group: 4-Byte Message

Direction: Turnout sensor \rightarrow

Encoding:

Byte 0:

1	0	1	1	0	0	0	1	0xB1	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

	40	- 40	 	 	-	(01.17		Scribor dataross
SN2	.d6 =	= 1					SN2.	d6 = 0
d6	A7	7.					d6	A6.
d5	A6	j.					d5	A5.
d4	A_5	Ď.					d4	A4.
d3	A4	ŀ.					d3	A3.
d2	A3	3.					d2	A2.
d1	A2	2.					d1	A1.
d0	A1						d0	A0.

Byte 2:

0	d6 d	$d5 \mid d4$	d3	d2	d1	d0	$\langle SN2 \rangle$	Sensor address and sensor state.
---	------	--------------	----	----	----	----	-----------------------	----------------------------------

<SN1>

SN2.d6 = 1

- d6 Report type. 1 means the report is an input report, and 0 means the report is an output report.
- d5 A0.
- d4 Input sensor state, 1 means sensor >= 6V, 0 means sensor = 0V.
- d3 A11.
- d2 A10.
- d1 A9.
- d0 A8.

SN2.d6 = 0

d6 Report type. 1 means the report is an input report, and 0 means the report is an output report.

Sensor address.

- d5 0 means closed output line is off, 1 means the closed output line is on.
- d4 0 means thrown output line is off, 1 means the thrown output line is on.
- d3 A10.
- d2 A9.
- d1 A8.
- d0 A7.

Byte 3:

		0	n	n	n	n	n	n	n	<chk></chk>	Checksum.
--	--	---	---	---	---	---	---	---	---	-------------	-----------

Description:

Turnout sensor report.

Response:

None.

Notes:

None.

OPC_SW_REQ

Operation: Request switch command.

Group: 4-Byte Message

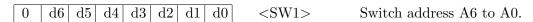
 $\underline{\text{Direction:}} \ \to \text{Turnout controller}$

Encoding:

Byte 0:

1	0	1	1	0	0	0	0	0xB0	Opcode.
	_	l		_	_	_	_		- I

Byte 1:



- d6 A6.
- d5 A5.
- d4 A4.
- d3 A3.
- d2 A2.
- d1 A1.
- d0 A0.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	$\langle SW2 \rangle$	Switch address A10 to A7 and switch control
									bits.

- d6 Reserved. Set to 0.
- d5 Direction. 1 means closed/green, and 0 means thrown/red.
- d4 Output. 1 means on, and 0 means off.
- d3 A10.
- d2 A9.
- d1 A8.
- d0 A7.

Byte 3:

U n n n n n n n n n		0	n	n	n	n	n	n	n	<chk></chk>	Checksum
---------------------------------------	--	---	---	---	---	---	---	---	---	-------------	----------

Description:

Command a turnout controller to a specified state.

Response:

OPC_LONG_ACK if command failed, otherwise no response.

 $\underline{\text{Notes:}}$

None.

OPC_SW_STATE

Operation: Request state of switch.

Group: 4-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Switch}$

Encoding:

Byte 0:

		1	0	1	1	1	1	0	0	0xBC	Opcode.
--	--	---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<sw1></sw1>	Switch address A6 to A0.
0	11	11	11	11	11	11	11	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Switch address At to At.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	$\langle SW2 \rangle$	Switch address A10 to A7 and switch control
	•								bits.

- d6 Reserved. Set to 0.
- d5 Direction. 1 means closed/green, and 0 means thrown/red.
- d4 Output. 1 means on, and 0 means off.
- d3 A10.
- d2 A9.
- d1 A8.
- d0 A7.

Byte 3:

0 n n n n n n	<CHK $>$	Checksum.
---------------------------	----------	-----------

Description:

Request state of switch.

Response:

OPC_LONG_ACK.

Notes:

This needs to be tested to see what the real purpose is.

OPC_UNLINK_SLOTS

Operation: Unlink slots.

Group: Variable-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

n

n

 $n \mid n \mid n$

Encoding:

Byte 0:

0

	1	0	1	1	1	0	0 0	0xB8	Opcode.	
Byte 1:										
	0	n	n	n	n	n	n n	<sl1></sl1>	Slot number in the range $0x00$ to $0x7F$.	
Byte 2:										

Slot number in the range 0x00 to 0x7F.

 $\langle SL2 \rangle$

Byte 3:

Description:

This command unlinks slot SL1 from slot SL2.

Response:

Returns OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_WR_SL_DATA

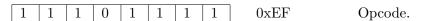
Operation: Write slot data.

Group: Variable-Byte Message

 $\underline{\text{Direction:}} \rightarrow \text{Command Station}$

Encoding:

Byte 0:



Byte 1:

0 1 1 1 1 1 0 0x0E Message length (14 bytes).

Byte 2:

0x70 to 0x7F are reserved to Digitrax.

Bytes 3 to 12 encode the same as bytes 3 to 12 of OPC_SL_RD_DATA.

Byte 13:

Description:

This command sends the slot data to the command station.

Response:

Returns OPC_LONG_ACK.

Notes:

None.