

Digitrax Loconet Notes

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Chapter 1

Loconet Protocol

1.1 Overview

LocoNet is a peer to peer distributed network system on which all devices can monitor the network data flow. The network is event driven by different devices in time, and is not polled by a centralised controller in normal operation. The normal LocoNet state is idle, with no data traffic unless a device has information to send. With no traffic flow, the network is quiet.

LocoNet data is sent in asynchronous format using 1 start bit, 8 data bits and 1 stop bit. The 8 bit data is transmitted least significant bit first. The bit times are $60.0 \mu\text{S}$ or 16,660 baud $\pm 1.5\%$. A computer can connect to a Digitrax USB interface at higher baud rates and the device will make the necessary conversion. Bytes may be transmitted back-to-back, with a start bit immediately following the stop bit of the previous character.

Any message that has format or framing errors, data errors or is a fragment caused by noise glitches and does not completely follow the message format will be ignored by all receivers, and a new opcode will be scanned for re-synchronisation.

The OPC_BUSY opcode is included to allow the master to keep the network active whilst it is performing a task that requires a response, and entails a significant processing delay, i.e. it can ensure no new requests are started until it has responded to the last message. This OPC_BUSY opcode should be simply stripped and ignored.

If a device disconnects from LocoNet and so does not access or reference a slot within the system purge time, the master will force the un-accessed slot to common status so other system devices can use the slot. The typical purge time of a master is about 200 seconds. A good “ping” or slot update activity is about every 100 seconds, i.e. if a user makes no

change to a throttle/slot within 100 seconds, the throttle/device should automatically send another speed update at the current speed to reset the purge timeout for that slot.

1.2 Message Format

All LocoNet communications are via multi-byte messages. The master is defined as the device that is maintaining the refresh stack for DCC packet generation and is actively generating the DCC track data. Refresh of information is typically only performed for mobile decoders. Stationary type decoders are not refreshed and individual immediate commands are sent out to the track as requested.

The master is only privileged in respect to performing the task of maintaining the locomotive refresh stack and generating DCC packets. In this way other network transactions may occur that the master does not need to be involved with or understand, as long as they follow the message protocol and timing requirements. i.e. Other devices may have a dialog on the network without disturbing or involving the master. Devices on LocoNet monitor the messages, check for format and data integrity and parse good messages to decode if action is required in the context. Devices such as throttles, input sensors, computer interfaces and control panels may generate LocoNet messages without needing prompting or polling by a central controller.

Devices frequently will be added and removed from an operating LocoNet. The devices and protocol are tolerant of electrical and data transients. The format chosen gives a good degree of data integrity, guaranteed quick network-state synchronisation, high data throughput, good distribution of access to many competing devices and low event latency. Also, the devices may be operated without need for unique ID or other requirements that can make network administration awkward.

The data bytes on LocoNet are defined as 8 bit data with the most significant bit as an opcode flag bit. If the most significant bit, d7, is 1 then the 7 least significant bits are interpreted as a network opcode. The opcode byte may only occur once in a valid message and is the first byte of a message. All the remaining bytes in the message must have a most significant bit of 0, including the last checksum byte. The checksum is the 1's complement of the byte wise exclusive or of all the bytes in the message, except the checksum itself. To validate data accuracy, all the bytes in a correctly formatted message are exclusive or'ed. If this resulting byte value is 0xFF, then the message data is accepted as good.

The opcodes may be examined to determine message length and if subsequent response message is required. Data bits d6 and d5 encode the message length. The message length includes the opcode and the checksum bytes. The bit d3 = 1 implies that a follow-on message or reply is expected.

<u>d7</u>	<u>d6</u>	<u>d5</u>	<u>d4</u>	<u>d3</u>	<u>d2</u>	<u>d1</u>	<u>d0</u>	
1	0	0	E	D	C	B	A	2 byte message
1	0	1	E	D	C	B	A	4 byte message
1	1	0	E	D	C	B	A	6 byte message
1	1	1	E	D	C	B	A	Variable length message. The next byte in the message is a 7 bit byte count.

The A,B,C,D,E are bits available to encode 32 opcodes per message length.

1.3 Refresh Slots

The model of the master refresh stack is an array of up to 120 read/write refresh slots. The slot address is a principal component and is generally the second byte or 1st argument of a message to the master. The refresh slot contains up to 10 data bytes relating to a locomotive and also controls a task in the track DCC refresh stack. Most mobile decoder or locomotive operations process the slot associated with the locomotive to be controlled. The slot number is a similar shorthand ID# to a file handle. Slot addresses 120-127 are reserved for system and master control. Slot #124 (0x7C) is allocated for read/write access to the programming track, and the format of the 10 data bytes is not the same as a normal slot.

1.4 Standard Address Selection

To request a mobile or locomotive decoder task in the refresh stack, a throttle device requests a locomotive address for use,(opcode OPC_LOCO_ADR). The master (or computer in a limited master environment) responds with a slot data read for the slot,(OPC_SL_RD_DATA), that contains this locomotive address and all of its state information. If the address is currently not in any slot, the master will load this new locomotive address into a new slot (speed=0, direction forwards, functions off and 128 step mode) and return this as a OPC_SL_RD_DATA. If no inactive slots are free to load the new locomotive address, the response will be the OPC_LONG_ACK with a fail code 0x00.

The throttle/computer must then examine the slot data bytes to work out how to process the master response. If the slot status 1 byte shows the slot to be common idle or new the throttle may change the slot to in use by performing a null move instruction (see OPC_MOVE_SLOTS) on this slot. This activation mechanism is used to guarantee proper slot usage interlocking in a multi-user asynchronous environment.

If the slot return information shows the locomotive requested is in use or up-consisted (i.e. the SL_CONUP, bit 6 of slot status 1 = 1) the user should not use the slot. Any

up-consisted locomotives must be unlinked before usage. Always process the result from the OPC_LINK_SLOTS and OPC_UNLINK_SLOTS commands, since the master reserves the right to change the reply slot number and can reject the linking tasks under several circumstances. Verify the reply slot number and the link UP/DN bits in slot status 1 are as you expected.

The throttle will then be able to update speed, direction and function information. Whenever slot information is changed in an active slot, the slot is flagged to be updated as the next DCC packet sent to the track. If the slot is part of linked consist slots the whole consist chain is updated consecutively.

If a throttle is disconnected from the LocoNet, upon reconnection (if the throttle retains the slot state from before disconnection) it will request the full status of the slot it was previously using. If the reported status and speed, function data etc., from the master exactly matches the remembered slot state the throttle will continue using the slot. If the SLOT data does not match, the throttle will assume the slot was purged free by the system and will go through the setup log on procedure again.

With this procedure the throttle does not need to have a unique ID number. slot addresses do not imply they contain any particular locomotive address. The system can be mapped such that the slot address matches the locomotive address within, if the user directly reads and writes to slots without using the master to allocate locomotive addresses.

1.5 Opcodes

OPC_BUSY

Operation: Indicates that the master is busy.

Group: 2-Byte Message

Direction: ↔ Command Station

Encoding:

Byte 0:

1	0	0	0	0	0	0	1
---	---	---	---	---	---	---	---

0x81
Opcode.

Byte 1:

0	1	1	1	1	1	1	0
---	---	---	---	---	---	---	---

0x7E
Checksum.

Description:

This message indicates that the master is busy. When sent to a command station it responds with an OPC_PEER_XFER message.

Response:

None.

Notes:

None.

OPC_CONSIST_FUNC

Operation: Set function bits in a consist uplink element.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	0	1	1	0
---	---	---	---	---	---	---	---

0xB6
Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SLOT#>
Slot number in the range 0x00 to 0x7F.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<DIRF>
Consist element's direction and state of functions F0 to F4.

- d6 Reserved. Set to 0.
- d5 Locomotive direction. 1 means forward, 0 means backwards.
- d4 F0 state. 1 means on, and 0 means off.
- d3 F4 state. 1 means on, and 0 means off.
- d2 F3 state. 1 means on, and 0 means off.
- d1 F2 state. 1 means on, and 0 means off.
- d0 F1 state. 1 means on, and 0 means off.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This function sets the consist element's direction and function F0 to F4 states.

Response:

None.

Notes:

None.

OPC_GPOFF

Operation: Global power off request.

Group: 2-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	0	0	0	0	1	0	0x82	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	1	1	1	1	1	0	1	0x7D	Checksum.
---	---	---	---	---	---	---	---	------	-----------

Description:

This command turns off the track power.

Response:

None.

Notes:

None.

OPC_GPON

Operation: Global power on request.

Group: 2-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	0	0	0	0	1	1
---	---	---	---	---	---	---	---

0x83
Opcode.

Byte 1:

0	1	1	1	1	1	0	0
---	---	---	---	---	---	---	---

0x7C
Checksum.

Description:

This command sends a global power on request.

Response:

The command station sends an OPC_RQ_SL_DATA message for slot 0x7F. It also sends a sequence of OPC_SW_REQ messages with the following values of SW1 and SW2:

SW1	SW2
0x78	0x27
0x79	0x27
0x7A	0x27
0x7B	0x27
0x78	0x07
0x79	0x07
0x7A	0x07
0x7B	0x07

Notes:

None.

OPC_IDLE

Operation: Force idle state and broadcast emergency stop.

Group: 2-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	0	0	0	1	0	1
---	---	---	---	---	---	---	---

0x85
Opcode.

Byte 1:

0	1	1	1	1	0	1	0
---	---	---	---	---	---	---	---

0x7A
Checksum.

Description:

This command forces Loconet into the idle state and broadcasts an emergency stop.

Response:

None

Notes:

None.

OPC_IMM_PACKET

Operation: Send n-byte packet immediate.

Group: Variable-Byte Message

Direction: → command station

Encoding:

Byte 0:

1	1	1	0	1	1	0	1
---	---	---	---	---	---	---	---

0xED
Opcode.

Byte 1:

0	0	0	1	0	0	0	0
---	---	---	---	---	---	---	---

0x0B
Message length (11 bytes).

Byte 2:

0	1	1	1	1	1	1	1
---	---	---	---	---	---	---	---

0x7F
Source id in the range 0x00 to 0x7F.

Byte 3:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<REPS>
Number of immediate bytes and repeat count.

- d6 N2. Number of immediate bytes.
- d5 N1. Number of immediate bytes.
- d4 N0. Number of immediate bytes.
- d3 A4. Reserved. Set to 0.
- d2 R2. Repeat count.
- d1 R1. Repeat count.
- d0 R0. Repeat count.

Byte 4:

0	0	1	d4	d3	d2	d1	d0	<DHII>	High bits of IM1 to IM5.
---	---	---	----	----	----	----	----	--------	--------------------------

- d4 IM5.7. High bit.
- d3 IM4.7. High bit.
- d2 IM3.7. High bit.
- d1 IM2.7. High bit.
- d0 IM1.7. High bit.

Byte 5:

0	d6	d5	d4	d3	d2	d1	d0	<IM1>	Data item 1 low 7 bits.
---	----	----	----	----	----	----	----	-------	-------------------------

Byte 6:

0	d6	d5	d4	d3	d2	d1	d0	<IM2>	Data item 2 low 7 bits.
---	----	----	----	----	----	----	----	-------	-------------------------

Byte 7:

0	d6	d5	d4	d3	d2	d1	d0	<IM3>	Data item 3 low 7 bits.
---	----	----	----	----	----	----	----	-------	-------------------------

Byte 8:

0	d6	d5	d4	d3	d2	d1	d0	<IM4>	Data item 4 low 7 bits.
---	----	----	----	----	----	----	----	-------	-------------------------

Byte 9:

0	d6	d5	d4	d3	d2	d1	d0	<IM5>	Data item 5 low 7 bits.
---	----	----	----	----	----	----	----	-------	-------------------------

Byte 10:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

Send n-byte packet immediate.

Response:

OPC_LONG_ACK.

Notes:

None.

OPC_INPUT_REPOperation: General sensor input report.Group: 4-Byte MessageDirection: General sensor →Encoding:

Byte 0:

1	0	1	1	0	0	1	0
---	---	---	---	---	---	---	---

 0xB2 Opcode.

Byte 1:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

 <IN1> Sensor address A7 to A1.

d6 A7.

d5 A6.

d4 A5.

d3 A4.

d2 A3.

d1 A2.

d0 A1.

Byte 2:

0	1	d5	d4	d3	d2	d1	d0
---	---	----	----	----	----	----	----

 <IN2> Switch address A11 to A8 and sensor input state.

d5 A0.

d4 Input state. 1 means sensor input $\geq 6V$, and 0 means sensor input = 0V.

d3 A11.

d2 A10.

d1 A9.

d0 A8.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

General sensor report.

Response:

None.

Notes:

None.

OPC_LINK_SLOTS

Operation: Link slots.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	1	0	0	1	0xB9	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SL1>	Slot number in the range 0x00 to 0x7F.
---	---	---	---	---	---	---	---	-------	--

Byte 2:

0	n	n	n	n	n	n	n	<SL2>	Slot number in the range 0x00 to 0x7F.
---	---	---	---	---	---	---	---	-------	--

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This function links slot SL1 to slot SL2. The command station sets SL_CONUP/DN flags appropriately. Invalid link will return a fail acknowledgement.

Response:

OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_LOCO_ADR

Operation: Request a slot number for a locomotive.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	1	1	1	1
---	---	---	---	---	---	---	---

0xBF
Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<ADR2>
High address.

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<ADR>
Low address.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>
Checksum.

Description:

This message requests the slot number for the selected locomotive address. If the locomotive is found in the slot table then the command station returns an OPC_SL_RD_DATA message with the slot information. If it is not found then the command station will put the locomotive into a free slot and then return an OPC_SL_RD_DATA message with the slot information. If there are no free slots then the command station returns an OPC_LONG_ACK error code.

Note that regular short 7 bit NMRA addresses are denoted by <ADR2> = 0. The Analog, zero stretched, locomotive is selected when both <ADR2> = 0 and <ADR> = 0. <ADR> is always a 7 bit value. If <ADR2> is non-zero then the master will generate NMRA type 14 bit or long address packets using all 14 bits from <ADR2> and <ADR> with <ADR2> being the most significant address bits. Note that a DT200 Master does not process 14 bit

address requests and will consider the <ADR2> to be zero. You can check the <TRK> return bits to see if the master is a DT200.

Response:

OPC_SL_RD_DATA if success, otherwise OPC_LONG_ACK.

Notes:

The Loconet 1.1 specification specifies that <ADR2> value is 0x00.

OPC_LOCO_DIRF

Operation: Set locomotive direction and function F0 to F4 states.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	0	0	0	0	1	0xA1	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SLOT#>	Slot number in the range 0x00 to 0x7F.
---	---	---	---	---	---	---	---	---------	--

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	<DIRF>	Locomotive's direction and state of functions F0 to F4.
---	----	----	----	----	----	----	----	--------	---

- d6 Reserved. Set to 0.
- d5 Locomotive direction. 1 means forward, 0 means backwards.
- d4 F0 state. 1 means on, and 0 means off.
- d3 F4 state. 1 means on, and 0 means off.
- d2 F3 state. 1 means on, and 0 means off.
- d1 F2 state. 1 means on, and 0 means off.
- d0 F1 state. 1 means on, and 0 means off.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This function sets the locomotive's direction and function F0 to F4 states.

Response:

None.

Notes:

None.

OPC_LOCO_RESET

Operation: Loco reset button has been pressed on the command station.

Group: 2-Byte Message

Direction: Command Station →

Encoding:

Byte 0:

1	0	0	0	1	0	1	0
---	---	---	---	---	---	---	---

0x8A
Opcode.

Byte 1:

0	1	1	1	0	1	0	1
---	---	---	---	---	---	---	---

0x75
Checksum.
Description:

The Loco reset button has been pressed.

Response:

None, this is a response.

Notes:

None.

OPC_LOCO_SND

Operation: Set locomotive sound functions.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	0	0	0	1	0
---	---	---	---	---	---	---	---

0xA2

Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SLOT#>

Slot number in the range 0x00 to 0x7F.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<SND>

Locomotive's function F5 to F8 states.

d6 Reserved. Set to 0.

d5 Reserved. Set to 0.

d4 Reserved. Set to 0.

d3 Reserved. Set to 0.

d3 Sound 4 / F8.

d2 Sound 3 / F7.

d1 Sound 2 / F6.

d0 Sound 1 / F5.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>

Checksum.

Description:

This function sets the locomotive's function F5 to F8 states.

Response:

None.

Notes:

None.

OPC_LOCO_SPD

Operation: Set locomotive speed.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	0	0	0	0	0	0xA0	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SLOT#>	Slot number in the range 0x00 to 0x7F.
---	---	---	---	---	---	---	---	---------	--

Byte 2:

0	n	n	n	n	n	n	n	<SPD>	Locomotive speed in the range 0x00 to 0x7F. 0x00 means inertial stop and 0x01 means emergency stop. Other values mean increasing speed.
---	---	---	---	---	---	---	---	-------	---

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This function sets the locomotive's speed.

Response:

None.

Notes:

None.

OPC LONG ACK

Operation: Long acknowledge.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	0	1	0	0
---	---	---	---	---	---	---	---

0xB4

Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<LOPC>

Opcode that this message is a response to with the most significant bit set to 0.

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<ACK1>

Response code.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>

Checksum.

Description:

This message provides a response code from a command.

Response:

None, it is the response.

Notes:

<u>Responding Opcode</u>	<u><LOPC></u>	<u><ACK1></u>	<u>Meaning</u>
OPC_SW_ACK	0x3D	0x00	DCS100 FIFO is full, command rejected.
OPC_SW_ACK	0x3D	0x7F	DCS100 command accepted.
OPC_MOVE_SLOTS	0x3A	0x00	Illegal move.
OPC_LINK_SLOTS	0x39	0x00	Invalid link, link failed.
OPC_SW_REQ	0x30	0x00	Command failed.
OPC_LOCO_ADR	0x3F	0x00	No free slot, command failed.
OPC_IMM_PACKET	0x7D	0x7F	Command OK, if not limited master.
OPC_IMM_PACKET	0x7E	<lim address>	Command OK, if limited master.
OPC_IMM_PACKET	0x7D	0x00	Internal buffer busy or full.

OPC_MOVE_SLOTSOperation: Move slot.Group: 4-Byte MessageDirection: → SwitchEncoding:

Byte 0:

1	0	1	1	1	0	1	0
---	---	---	---	---	---	---	---

0xBA

Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SRC>

Source slot number in the range 0x00 to 0x77.

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<DEST>

Destination slot number in the range 0x00 to 0x77.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>

Checksum.

Description:

Move slots.

<u>SRC</u>	<u>DEST</u>	<u>Action</u>
0x00	Don't Care	Dispatch get. Return slot read of dispatch slot.
SRC	SRC	Null move. SRC is set to in use.
SRC	0x00	Dispatch put. Mark slot as dispatch.
SRC	DEST	Move slot data from SRC to DEST if not in use. Clear SRC.

Response:

OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_PEER_XFEROperation: Move 8 bytes peer to peer.Group: Variable-Byte MessageDirection: device → deviceEncoding:

Byte 0:

1	1	1	0	0	1	0	1
---	---	---	---	---	---	---	---

0xE5

Opcode.

Byte 1:

0	0	0	1	0	0	0	0
---	---	---	---	---	---	---	---

0x10

Message length (16 bytes).

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SRC>

Source id in the range 0x00 to 0x7F.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<DSTL>

Destination id low in the range 0x00 to 0x7F.

Byte 4:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<DSTH>

Destination id high in the range 0x00 to 0x7F.

Byte 5:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<PXCT1>

Address type code and high bits of D1 to D4.

d6 XC2. Address type code.

d5 XC1. Address type code.

d4 XC0. Address type code.

d3 D4.7. High bit

d2 D3.7. High bit

d1 D2.7. High bit

d0 D1.7. High bit

<u>XC2</u>	<u>XC1</u>	<u>XC0</u>	<u>Meaning</u>
0	0	0	7 bit peer to peer addresses.
0	0	1	reserved.
0	1	0	reserved.
0	1	1	reserved.
1	0	0	reserved.
1	0	1	reserved.
1	1	0	reserved.
1	1	1	reserved.

Byte 6:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D1>

Data item 1. Low 7 bits.

Byte 7:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D2>

Data item 2. Low 7 bits.

Byte 8:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D3>

Data item 3. Low 7 bits.

Byte 9:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D4>

Data item 4. Low 7 bits.

Byte 10:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<PXCT2>

Data type code and high bits for D5 to D8.

d6 XC5. Data type code.
d5 XC4. Data type code.
d4 XC3. Data type code.
d3 D8.7. High bit
d2 D7.7. High bit
d1 D6.7. High bit
d0 D5.7. High bit

<u>XC5</u>	<u>XC4</u>	<u>XC3</u>	Meaning
0	0	0	ANSI text string.
0	0	1	reserved.
0	1	0	reserved.
0	1	1	reserved.
1	0	0	reserved.
1	0	1	reserved.
1	1	0	reserved.
1	1	1	reserved.

Byte 11:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D5>

Data item 5. Low 7 bits.

Byte 12:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D6>

Data item 6. Low 7 bits.

Byte 13:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D7>

Data item 7. Low 7 bits.

Byte 14:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<D8>

Data item 8. Low 7 bits.

Byte 15:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>

Checksum.

Description:

This command sends the data from one device to another peer to peer.

<u>SRC</u>	<u>DSTL</u>	<u>DSTH</u>	Comments
0x00			Source is command station.
Don't Care	0x00	0x00	Broadcast Message.
0x70 to 0x7E			Reserved.
0x7F	0x00	0x00	Broadcast throttle message transfer.
0x7F	ID1	ID2	Throttle message transfer. ID1 and ID2 encode ID.

Response:

None

Notes:

None.

OPC RQ.SL DATA

Operation: Request slot data or status block.

Group: 4-Byte Message

Direction: → Switch

Encoding:

Byte 0:

1	0	1	1	1	0	1	1	0xBB	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SLOT#>	Slot number in the range 0x00 to 0x7F. 0 returns the command station status block
---	---	---	---	---	---	---	---	---------	---

Byte 2:

0	0	0	0	0	0	0	0	0x00	Reserved.
---	---	---	---	---	---	---	---	------	-----------

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

Request slot data or status block.

Response:

OPC_SL_RD_DATA.

Notes:

None.

OPC_SL_RD_DATA

Operation: Returns slot data.

Group: Variable-Byte Message

Direction: Command Station →

Encoding:

Byte 0:

1	1	1	0	0	1	1	1
---	---	---	---	---	---	---	---

0xE7

Opcode.

Byte 1:

0	1	1	1	1	1	1	0
---	---	---	---	---	---	---	---

0x0E

Message length (14 bytes).

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SLOT#>

Slot number in the range 0x00 to 0x7F. Slot 0x00 is a special slot, and slots in the range 0x70 to 0x7F are reserved to Digitrax.

Byte 3:

d7	d6	d5	d4	d3	d2	d1	d0
----	----	----	----	----	----	----	----

<STAT1>

Slot status 1.

<u>d7</u>	<u>d6</u>	
0	0	Free, no consist linking.
0	1	Consist sub-member.
1	0	Consist top-member.
1	1	Consist Mid-Consist member.

Note: d7 is set to 0 in the message by the command station and so may not correctly reflect the actual setting in the slot table.

<u>d5</u>	<u>d4</u>	
0	0	Free slot, no valid data. Not refreshed.
0	1	Common. Locomotive address in this slot. Refreshed.
1	0	Idle. Locomotive address in this slot. Not refreshed.
1	1	In Use. Locomotive address in this slot. Refreshed.

<u>d3</u>	
0	No slot consist linked into this slot.
1	Slot consist linked into this slot.

<u>d2</u>	<u>d1</u>	<u>d0</u>	
0	0	0	28 step decoder. 3-byte packet regular mode
0	0	1	28 step decoder. Generate trinary packets for this mobile address
0	1	0	14 step decoder.
0	1	1	128 step decoder.
1	0	0	28 step decoder. Allow advanced consisting
1	0	1	reserved
1	1	0	reserved
1	1	1	128 step decoder. Allow advanced consisting

Byte 4:

0	n	n	n	n	n	n	n	<ADR>	Low address.
---	---	---	---	---	---	---	---	-------	--------------

Byte 5:

0	n	n	n	n	n	n	n	<SPD>	Speed in the range 0x00 to 0x7F. 0x00 means inertial stop and 0x01 means emergency stop. Other values mean increasing speed.
---	---	---	---	---	---	---	---	-------	--

Byte 6:

0	d6	d5	d4	d3	d2	d1	d0	<DIRF>	Locomotive direction and state of functions F0 to F4.
---	----	----	----	----	----	----	----	--------	---

d6	Reserved. Set to 0.
d5	Locomotive direction. 1 means forward, 0 means backwards.
d4	F0 state. 1 means on, and 0 means off.
d3	F4 state. 1 means on, and 0 means off.
d2	F3 state. 1 means on, and 0 means off.
d1	F2 state. 1 means on, and 0 means off.
d0	F1 state. 1 means on, and 0 means off.

Byte 7:

0	d6	d5	d4	d3	d2	d1	d0	<TRK>	Global system track status.
---	----	----	----	----	----	----	----	-------	-----------------------------

- d6 Reserved. Set to 0.
- d5 Reserved. Set to 0.
- d4 Reserved. Set to 0.
- d3 1 means the programming track is busy.
- d2 1 means this master implements Loconet version 1.1 capability, 0 means the master is a DT200.
- d1 0 means the track is paused, broadcast an emergency stop.
- d0 1 means the DCC packets are on in the master, global power up.

Byte 8:

0	d6	d5	d4	d3	d2	d1	d0	<SS2>	Slot status 2.
---	----	----	----	----	----	----	----	-------	----------------

- d6 Reserved. Set to 0.
- d5 Reserved. Set to 0.
- d4 Reserved. Set to 0.
- d3 1 means expansion in ID1/2, 0 means encoded alias.
- d2 1 means expansion ID1/2 is not ID usage.
- d1 Reserved. Set to 0.
- d0 1 means this slot has suppressed advanced consist.

Byte 9:

0	n	n	n	n	n	n	n	<ADR2>	High address.
---	---	---	---	---	---	---	---	--------	---------------

Byte 10:

0	d6	d5	d4	d3	d2	d1	d0	<SND>	Slot sound / function mode II packets.
---	----	----	----	----	----	----	----	-------	--

- d6 Reserved. Set to 0.
- d5 Reserved. Set to 0.
- d4 Reserved. Set to 0.
- d3 Sound 4 / F8.
- d2 Sound 3 / F7.
- d1 Sound 2 / F6.
- d0 Sound 1 / F5.

Byte 11:

0	n	n	n	n	n	n	n	<ID1>	7-bit ls ID code written by throttle when STAT2.4 = 1.
---	---	---	---	---	---	---	---	-------	--

Byte 12:

0	n	n	n	n	n	n	n	<ID2>	7-bit ms ID code written by throttle when STAT2.4 = 1.
---	---	---	---	---	---	---	---	-------	--

Byte 13:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This message is sent by the command station in response to a slot data request.

Response:

None.

Notes:

None.

OPC_SLOT_STAT1

Operation: Set slot status 1.

Group: 4-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	0	1	0	1	0xB5	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SLOT#>	Slot number in the range 0x00 to 0x7F.
---	---	---	---	---	---	---	---	---------	--

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	<STAT1>	Slot status 1. See OPC_SL_RD_DATA for bit encoding details.
---	----	----	----	----	----	----	----	---------	---

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This function sets the slot's status 1 values.

Response:

None.

Notes:

None.

OPC_SW_ACK

Operation: Request switch command with acknowledge.

Group: 4-Byte Message

Direction: → Turnout controller

Encoding:

Byte 0:

1	0	1	1	1	1	0	1
---	---	---	---	---	---	---	---

0xBD

Opcode.

Byte 1:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<SW1>

Switch address A6 to A0.

d6 A6.

d5 A5.

d4 A4.

d3 A3.

d2 A2.

d1 A1.

d0 A0.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<SW2>

Switch address A10 to A7 and switch control bits.

- d6 Reserved. Set to 0.
- d5 Direction. 1 means closed/green, and 0 means thrown/red.
- d4 Output. 1 means on, and 0 means off.
- d3 A10.
- d2 A9.
- d1 A8.
- d0 A7.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

Command a turnout controller to a specified state and send acknowledge.

Response:

OPC_LONG_ACK.

Notes:

None.

OPC_SW_REP

Operation: Turnout sensor report.

Group: 4-Byte Message

Direction: Turnout sensor →

Encoding:

Byte 0:

1	0	1	1	0	0	0	1	0xB1	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	d6	d5	d4	d3	d2	d1	d0	<SN1>	Sensor address.
---	----	----	----	----	----	----	----	-------	-----------------

SN2.d6 = 1

d6 A7.
d5 A6.
d4 A5.
d3 A4.
d2 A3.
d1 A2.
d0 A1.

SN2.d6 = 0

d6 A6.
d5 A5.
d4 A4.
d3 A3.
d2 A2.
d1 A1.
d0 A0.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0
---	----	----	----	----	----	----	----

<SN2>

Sensor address and sensor state.

SN2.d6 = 1

d6 Report type. 1 means the report is an input report, and 0 means the report is an output report.
d5 A0.
d4 Input sensor state, 1 means sensor $\geq 6V$, 0 means sensor = 0V.
d3 A11.
d2 A10.
d1 A9.
d0 A8.

SN2.d6 = 0

d6 Report type. 1 means the report is an input report, and 0 means the report is an output report.
d5 0 means closed output line is off, 1 means the closed output line is on.
d4 0 means thrown output line is off, 1 means the thrown output line is on.
d3 A10.
d2 A9.
d1 A8.
d0 A7.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>

Checksum.

Description:

Turnout sensor report.

Response:

None.

Notes:

None.

OPC_SW_REQ

Operation: Request switch command.

Group: 4-Byte Message

Direction: → Turnout controller

Encoding:

Byte 0:

1	0	1	1	0	0	0	0	0xB0	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	d6	d5	d4	d3	d2	d1	d0	<SW1>	Switch address A6 to A0.
---	----	----	----	----	----	----	----	-------	--------------------------

d6 A6.

d5 A5.

d4 A4.

d3 A3.

d2 A2.

d1 A1.

d0 A0.

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	<SW2>	Switch address A10 to A7 and switch control bits.
---	----	----	----	----	----	----	----	-------	---

d6 Reserved. Set to 0.

d5 Direction. 1 means closed/green, and 0 means thrown/red.

d4 Output. 1 means on, and 0 means off.

d3 A10.

d2 A9.

d1 A8.

d0 A7.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

Command a turnout controller to a specified state.

Response:

OPC_LONG_ACK if command failed, otherwise no response.

Notes:

None.

OPC_SW_STATE

Operation: Request state of switch.

Group: 4-Byte Message

Direction: → Switch

Encoding:

Byte 0:

1	0	1	1	1	1	0	0	0xBC	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	n	n	n	n	n	n	n	<SW1>	Switch address A6 to A0.
---	---	---	---	---	---	---	---	-------	--------------------------

Byte 2:

0	d6	d5	d4	d3	d2	d1	d0	<SW2>	Switch address A10 to A7 and switch control bits.
---	----	----	----	----	----	----	----	-------	---

d6 Reserved. Set to 0.

d5 Direction. 1 means closed/green, and 0 means thrown/red.

d4 Output. 1 means on, and 0 means off.

d3 A10.

d2 A9.

d1 A8.

d0 A7.

Byte 3:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

Request state of switch.

Response:

OPC_LONG_ACK.

Notes:

This needs to be tested to see what the real purpose is.

OPC_UNLINK_SLOTS

Operation: Unlink slots.

Group: Variable-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	0	1	1	1	0	0	0
---	---	---	---	---	---	---	---

0xB8
Opcode.

Byte 1:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SL1>
Slot number in the range 0x00 to 0x7F.

Byte 2:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<SL2>
Slot number in the range 0x00 to 0x7F.

Byte 3:

0	n	n	n	n	n	n	n
---	---	---	---	---	---	---	---

<CHK>
Checksum.

Description:

This command unlinks slot SL1 from slot SL2.

Response:

Returns OPC_SL_RD_DATA or OPC_LONG_ACK.

Notes:

None.

OPC_WR_SL_DATA

Operation: Write slot data.

Group: Variable-Byte Message

Direction: → Command Station

Encoding:

Byte 0:

1	1	1	0	1	1	1	1	0xEF	Opcode.
---	---	---	---	---	---	---	---	------	---------

Byte 1:

0	1	1	1	1	1	1	0	0x0E	Message length (14 bytes).
---	---	---	---	---	---	---	---	------	----------------------------

Byte 2:

0	n	n	n	n	n	n	n	<SLOT#>	Slot number in the range 0x00 to 0x7F. Slot 0x00 is a special slot, and slots in the range 0x70 to 0x7F are reserved to Digitrax.
---	---	---	---	---	---	---	---	---------	---

Bytes 3 to 12 encode the same as bytes 3 to 12 of OPC_SL_RD_DATA.

Byte 13:

0	n	n	n	n	n	n	n	<CHK>	Checksum.
---	---	---	---	---	---	---	---	-------	-----------

Description:

This command sends the slot data to the command station.

Response:

Returns OPC_LONG_ACK.

Notes:

None.