## Pierre Kibleur

## Ph.D., Engineer in CSE

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French nationality . Driving license B

With hands-on experience in materials and robotics, my ambition is to actively participate in the deployment of automation and technical solutions in the naval industry



## **Experience**

Experience	
<ul> <li>UGent Center for X-ray Tomography (UGCT), Ghent, Belgium</li> <li>3D Data analyst</li> <li>Consulting on industrial R&amp;D, using non-destructive testing to assess quality, product development, and processes. Group promotion at several conferences and seminars. Lecturer on "Advanced applications of deep learning for X-ray CT"</li> </ul>	2022-present
• Researcher  Dynamic testing of fiber-based composite materials with quantitative image processing. Presenter at 6 international conferences; presentation award at ICTMS2022. Gave training on robotics and deep learning	2018–2022
Confinis AG, Geneva, Switzerland Consultant (4 months internship) Writing regulatory compliance of joint prosthetics in preparation of marketing application dossiers	2018–2018
University of Fribourg, Fribourg, Switzerland • Scientific support staff Robotic modeling and decoding of the primate arm to parameterize a therapeutic brain-computer interface	2018–2018
<ul> <li>G-therapeutics, Lausanne, Switzerland</li> <li>Roboticist (9 months internship)</li> <li>Programming the Rysen medical robot for gait rehabilitation: C++ control architecture and implementation</li> </ul>	2017–2017
<ul> <li>École Polytechnique Fédérale de Lausanne (EPFL), Lausanne, Switzerland</li> <li>Teaching assistant</li> <li>Providing support in mathematics for a group of 20 second-year physicists</li> </ul>	2015–2016
Education	
<ul> <li>Ghent University, Ghent, Belgium</li> <li>Ph.D. Bioscience Engineering; thesis on "4D X-ray micro-tomography investigation of water-induced swelling of wood fiberboards"</li> </ul>	2018–2022
<ul> <li>EPFL, Lausanne, Switzerland</li> <li>M.Sc. Computational Science and Engineering; thesis on "Biomechanical model of the primates' upper limb: design of stimulation protocols for the recovery of reaching movements in tetraplegia"</li> </ul>	2015–2018
B.Sc. Physics; Erasmus+ exchange at ULB, Brussels	2011–2015

## **Competencies**

English/French: Fluent

Russian/Dutch: Limited proficiency

Coding: C/C++, Python, Matlab, Bash, shell, CUDA, Basic, C#, LaTeX

**Libraries:** Pandas, Scipy, scikit-image, OpenCV, TwinCAT, Keras, PyTorch, TensorFlow, numpy **Software:** Git, Dragonfly, Avizo, VGStudio Max, Fiji, Abaqus, Solid Works, Fusion 360, Visio **Environments:** Linux/Windows, Vim, Atom, Visual Studio, Jupyter, Overleaf, Microsoft Office Suite **Soft skills:** Project management, Multidisciplinary collaboration, Creativity, Problem solving

Communication: Author of 24 peer-reviewed articles, regular presenter at conferences and meetings

**Languages** Hobbies

Competition rowing: twice Belgian champion Sailing, flute and saxophone