## Pierre Kibleur

## Ph.D., Engineer in CSE

pierre.kibleur@gmail.com • +33 (0)6 09 90 18 77

French nationality . Driving license B

With hands-on experience in materials and robotics, my ambition is to actively participate in the deployment of automation and technical solutions in the naval industry



## **Experience**

Experience	
<ul> <li>UGent Center for X-ray Tomography (UGCT), Ghent, Belgium</li> <li>3D Data analyst</li> <li>Consulting on industrial R&amp;D, using non-destructive testing to assess quality, product development, and processes. Group promotion at several conferences and seminars. Lecturer on "Advanced applications of deep learning for X-ray CT"</li> </ul>	2022-present
• Researcher  Dynamic testing of fiber-based composite materials with quantitative image processing. Presenter at 6 international conferences; presentation award at ICTMS2022. Gave training on robotics and deep learning	2018–2022
<ul> <li>Confinis AG, Geneva, Switzerland</li> <li>Consultant (4 months internship)</li> <li>Writing regulatory compliance of joint prostheses in preparation of marketing application dossiers</li> </ul>	2018–2018
University of Fribourg, Fribourg, Switzerland • Scientific support staff Robotic modeling and decoding of the primate arm to parameterize a therapeutic brain-computer interface	2018–2018
G-therapeutics, Lausanne, Switzerland • Roboticist (9 months internship) Programming the Rysen medical robot for gait rehabilitation: C++ control architecture and implementation	2017–2017
École Polytechnique Fédérale de Lausanne (EPFL), Lausanne, Switzerland  • Teaching assistant Providing support in mathematics for a group of 20 second-year physicists	2015–2016
Education	
<ul> <li>Ghent University, Ghent, Belgium</li> <li>Ph.D. Bio-science Engineering; thesis on "4D X-ray micro-tomography investigation of water-induced swelling of wood fiberboards"</li> </ul>	2018–2022
<ul> <li>EPFL, Lausanne, Switzerland</li> <li>M.Sc. Computational Science and Engineering; thesis on "Bio-mechanical model of the primates' upper limb: design of stimulation protocols for the recovery of reaching movements in tetraplegia"</li> </ul>	2015–2018
B.Sc. Physics; Erasmus+ exchange at ULB, Brussels	2011–2015

## **Competencies**

English/French: Fluent

Russian/Dutch: Limited proficiency

Coding: C/C++, Python, Matlab, Bash, shell, CUDA, Basic, C#, LaTeX

**Libraries:** Pandas, Scipy, scikit-image, OpenCV, TwinCAT, Keras, PyTorch, TensorFlow, numpy **Software:** Git, Dragonfly, Avizo, VGStudio Max, Fiji, Abaqus, Solid Works, Fusion 360, Visio **Environments:** Linux/Windows, Vim, Atom, Visual Studio, Jupyter, Overleaf, Microsoft Office Suite **Soft skills:** Project management, Multidisciplinary collaboration, Creativity, Problem solving

Communication: Author of 24 peer-reviewed articles, regular presenter at conferences and meetings

**Languages** Hobbies

Competition rowing: twice Belgian champion Sailing, flute and saxophone