# Pierre Kibleur

## Ph.D., Engineer in Computational Mathematics

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French nationality . Driving license B

With hands-on experience in complex materials and robotics, I am eager to contribute to the advancement of automation and innovative technical solutions in the industry.



## **Experience**

| <b>UGent Center for X-ray</b> | Tomography (LIGCT)  | Chent Relaium      |
|-------------------------------|---------------------|--------------------|
| OGENI CENTER FOR A-PAY        | TOTTOUTABLE (OGCI). | Giletti, belalulli |

Consulting on industrial R&D

3D non-destructive testing of materials and assemblies, for quality and process evaluation. Project man-

 $agement, \ experiment \ design, \ commercial \ promotion \ at \ international \ events.$ 

• Research engineer 2018–2022

Quantified the deterioration of MDF composite materials with X-rays, image processing, and FEM simulations to improve their durability. Took an active part in many external R&D projects.

#### Confinis AG, Geneva, Switzerland

Consulting on regulatory compliance (4 months)

Evaluated the medical viability of joint prostheses in preparation of marketing application dossiers.

2018–2018

2022-present

### University of Fribourg, Fribourg, Switzerland

Robotics engineer

Reverse-engineering and modeling of the non-human primate arm for use in tetraplegia therapy.

2018-2018

#### G-therapeutics, Lausanne, Switzerland

• Robotics engineer (9 months)

Programming the Rysen medical robot for gait rehabilitation: defined the C++ control architecture, implemented training tasks for patients, and integrated embedded IMU sensors for real-time state estimation.

2017–2017

## École Polytechnique Fédérale de Lausanne (EPFL), Lausanne, Switzerland

Teaching assistant

Provided support in mathematics for a group of 20 second-year physicists.

2015-2016

## **Education**

#### **Ghent University, Ghent, Belgium**

• Ph.D. Bio-science Engineering; specialized in X-ray imaging, material analyses and testing, and artificial intelligence / deep learning for image vision. Presentation award at ICTMS2022.

2018–2022

#### EPFL, Lausanne, Switzerland

• M.Sc. Computational Science and Engineering; specialized in robotics, programming, mathematics. Created an autonomous control algorithm for air/sea-borne drones.

2015–2018

• B.Sc. Physics; Erasmus+ exchange at ULB, Brussels.

2011-2015

## Competencies

Coding: C/C++, Python, Matlab, Bash, shell, CUDA, Basic, C#, LaTeX

**Libraries:** Pandas, Scipy, scikit-image, OpenCV, TwinCAT, Keras, PyTorch, TensorFlow, numpy **Software:** Git, Dragonfly, Avizo, VGStudio Max, Fiji, Abaqus, Solid Works, Fusion 360, Visio **Environments:** Linux/Windows, Vim, Atom, Visual Studio, Jupyter, Overleaf, Microsoft Office Suite **Soft skills:** Project management, Multidisciplinary collaboration, Creativity, Problem solving

**Communication:** Author of 21 peer-reviewed articles, regular presenter at conferences and meetings

Languages Hobbies

**English/French:** Fluent Rowing: two times champion of Belgium Russian/Dutch: Limited proficiency Trainee sailor with a passion for tall ships