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1 # -----
2 # Author: Philip Coyle
3 # Date Created: 05/26/2020
4 # ps1_Q7_optimize.jl
5 # -----
6
7 using Parameters
8 using Plots
9 ## Housekeeping
10 # Directory
11 dir = "/Users/philipcoyle/Documents/School/University_of_Wisconsin/SecondYear/Summer_2020/CodingBootcamp/ProblemSets/PS1/"
12
13 ## Structures
14 @with_kw struct Params
15     β::Float64 = 0.99
16     δ::Float64 = 0.025
17     θ::Float64 = 0.36
18
19     tol::Float64 = 1e-10
20     maxit::Int64 = 10000
21 end
22
23 @with_kw struct Shocks
24     Zg::Float64 = 1.25
25     Zb::Float64 = 0.2
26
27     # Transition Probabilities
28     #  $P_{yx} = \Pr(Z' = Zy \mid Z = Zx) \quad x \in \{g, b\} \text{ \& } y \in \{g, b\}$ 
29     Pgg::Float64 = 0.977
30     Pbg::Float64 = 1 - Pgg
31     Pbb::Float64 = 0.926
32     Pgb::Float64 = 1 - Pbb
33     Tmat::Array{Float64,2} = [
34         Pgg Pbg
35         Pgb Pbb
36     ]
37 end
38
39 @with_kw struct Grids
40     Zg::Float64 = 1.25
41     Zb::Float64 = 0.2
42
43     k_lb::Float64 = 1
44     k_ub::Float64 = 75
45     n_k::Int64 = 100
46     k_grid::Array{Float64,1} = range(k_lb, stop = k_ub, length = n_k)
47
48     n_Z::Int64 = 2
49     Z_grid::Array{Float64,1} = [Zg, Zb]
50 end
51
52 mutable struct PolFuncs
53     pf_c::Array{Float64,2}
54     pf_k::Array{Float64,2}
55     pf_v::Array{Float64,2}
56 end
57
58 ## Functions
59 function solve_model()
60     P = Params()
61     S = Shocks()
62     G = Grids()
63
64     @unpack n_k, n_Z = G
65     # Initial Guess
66     pf_c = zeros(n_k, n_Z)
67     pf_k = zeros(n_k, n_Z)
68     pf_v = zeros(n_k, n_Z)
69     PFs = PolFuncs(pf_c, pf_k, pf_v)
70
71     converged = 0
72     it = 1
73     while converged == 0 && it < P.maxit
74         @unpack pf_v, pf_k, pf_c = PFs
75
76         pf_c_up, pf_k_up, pf_v_up = Bellman(P, S, G, PFs)
77
78         diff_v = sum(abs.(pf_v_up - pf_v))
79         diff_k = sum(abs.(pf_k_up - pf_k))
80         diff_c = sum(abs.(pf_c_up - pf_c))

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82
83     max_diff = diff_v + diff_k + diff_c
84
85     if mod(it, 250) == 0 || max_diff < P.tol
86         println(" ")
87         println("*****")
88         println("AT ITERATION = ", it)
89         println("MAX DIFFERENCE = ", max_diff)
90         println("*****")
91
92         if max_diff < P.tol
93             converged = 1
94         end
95     end
96     # Update the policy functions
97     PFs = PolFuncs(pf_c_up, pf_k_up, pf_v_up)
98     it = it + 1
99 end
100
101 return G, PFs
102 end
103
104 function Bellman(P::Params, S::Shocks, G::Grids, PFs::PolFuncs)
105     @unpack β, δ, θ = P
106     @unpack Zg, Zb, Pgg, Pbg, Pbb, Pgb, Tmat = S
107     @unpack n_k, k_grid, n_Z, Z_grid = G
108     @unpack pf_c, pf_k, pf_v = PFs
109
110     # To make updating work
111     pf_k_up = zeros(n_k, n_Z)
112     pf_c_up = zeros(n_k, n_Z)
113     pf_v_up = zeros(n_k, n_Z)
114
115     for (i_Z, Z) in enumerate(Z_grid)
116         Pr = Tmat[i_Z, :]
117         for (i_k, k_today) in enumerate(k_grid)
118             # Must be defined outside loop.
119             v_today = log(0)
120             c_today = log(0)
121             k_tomorrow = log(0)
122
123             # Find optimal investment/consumption given capital level today
124             for (i_kpr, k_temp) in enumerate(k_grid)
125                 y_today = Z * k_today^θ
126                 c_temp = y_today + (1 - δ) * k_today - k_temp
127                 v_tomorrow = Pr[1] * pf_v[i_kpr, 1] + Pr[2] * pf_v[i_kpr, 2]
128                 if c_temp < 0
129                     v_temp = log(0) + β * v_tomorrow
130                 else
131                     v_temp = log(c_temp) + β * v_tomorrow
132                 end
133
134                 if v_temp > v_today
135                     v_today = v_temp
136                     c_today = c_temp
137                     k_tomorrow = k_temp
138                 end
139             end
140
141             # Update PFs
142             pf_k_up[i_k, i_Z] = k_tomorrow
143             pf_c_up[i_k, i_Z] = c_today
144             pf_v_up[i_k, i_Z] = v_today
145         end
146     end
147
148     return pf_c_up, pf_k_up, pf_v_up
149 end
150
151 function plot_pfs(dir::String, G::Grids, PFs::PolFuncs)
152     @unpack k_grid = G
153     @unpack pf_c, pf_k, pf_v = PFs
154
155     pf1 = plot(k_grid, pf_v[:,1], legend = false, color=:black, label = "Good State", lw = 2);
156     pf_1 = plot!(pf1, k_grid, pf_v[:,2], title="Value Function", legend = true, color=:blue, label = "Bad State", lw = 2);
157
158     pf2 = plot(k_grid, pf_k[:,1], legend = false, color=:black, lw = 2);
159     pf_2 = plot!(pf2, k_grid, pf_k[:,2], title="Capital Investment", legend = false, color=:blue, lw = 2);
160
161     pf3 = plot(k_grid, pf_c[:,1], legend = false, color=:black, lw = 2);
162     pf_3 = plot!(pf3, k_grid, pf_c[:,2], title="Consumption", legend = false, color=:blue, lw = 2);
163

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164     pf = plot(pf_1,pf_2,pf_3,layout=(1,3),size = (600,400)) #Size can be adjusted so don't need to mess around with 'blank space'
165     xlabel!("Initial Capital Stock")
166     # savefig(dir * "Q7_PFs.pdf")
167 end
168
169 ## Main Code
170 @time G, PFs = solve_model()
171 plot_pfs(dir, G, PFs)
```