

proposición: sea $A \in \mathbb{K}^{n \times n}$ y sean $\{t_i\}_{i=1}^n \in \mathbb{R}_+$:

$$\begin{cases} t_1 = \frac{1}{|a_{11}|} \sum_{j=2}^n |a_{1j}| \\ t_i = \frac{1}{|a_{ii}|} \left(\sum_{j=1}^{i-1} |a_{ij}| t_j + \sum_{j=i+1}^n |a_{ij}| \right) \end{cases} \quad \underline{i=2, \dots, n}$$

si $\max_{i \in \{1, \dots, n\}} t_i < 1 \Rightarrow$ la iteración de GS converge $\forall x_0$.

demonstración: queremos mostrar que $\|B_{GS}(A)\|_\infty < 1$

• $B_{GS}(A)x = - (D_A + L_A)^{-1} U_A x = y$

\hookrightarrow queremos ver que $\|y\|_\infty < 1$ para $\|x\|_\infty = 1$

• recordemos la forma explícita de G-S

$\hookrightarrow y_i = - \sum_{j=1}^{i-1} \frac{a_{ij}}{a_{ii}} y_j - \sum_{j=i+1}^n \frac{a_{ij}}{a_{ii}} x_j$

$$\Rightarrow |y_i| \leq \frac{1}{|a_{ii}|} \left(\sum_{j=1}^{i-1} |a_{ij}| \cdot |y_j| + \sum_{j=i+1}^n |a_{ij}| \cdot \overbrace{|x_j|}^1 \right)$$

$$\leq \frac{1}{|a_{ii}|} \left(\sum_{j=1}^{i-1} |a_{ij}| \cdot |y_j| + \sum_{j=i+1}^n |a_{ij}| \right)$$

• $i=1 \quad |y_1| \leq t_1$

$$\begin{aligned} i=2 \quad |y_2| &\leq \frac{1}{|a_{22}|} \left(\sum_{j=1}^{2-1} |a_{2j}| \cdot \overbrace{|y_j|}^{t_1} + \sum_{j=2+1}^n |a_{2j}| \right) \\ &\leq t_2 \end{aligned}$$

$\hookrightarrow |y_i| \leq t_i \quad \forall i \in \{1, \dots, n\}$

• $\|y\|_\infty \leq \max_{i=1 \dots n} t_i < 1 \quad \#$

corolario : sea $A \in \mathbb{R}^{n \times n}$

$$\text{si } \sum_{j=1, j \neq i}^n |a_{ij}| < |a_{ii}| \quad \forall i \in \{1, \dots, n\}$$

DIAGONAL
DOMINANTE
ESTRICTA
POR FILAS

\Rightarrow G-S converge $\forall x_0$

demonstración

$$\bullet \quad r_1 = \frac{1}{|a_{11}|} \sum_{j=2}^n |a_{1j}| < 1 \quad \text{por hipótesis}$$

$$\bullet \quad r_i = \frac{1}{|a_{ii}|} \left(\sum_{j=1}^{i-1} |a_{ij}| r_j + \sum_{j=i+1}^n |a_{ij}| \right)$$

$$< \frac{1}{|a_{ii}|} \sum_{j=1}^n |a_{ij}| < 1 \quad \text{por hipótesis.} \quad \#$$

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Ejemplos :

$$\bullet \quad A = \begin{pmatrix} 2 & 1 & 0 & 0 \\ 1 & 3 & 1/2 & 0 \\ 0 & 1/2 & 4 & 1 \\ 1 & 0 & -1 & 7 \end{pmatrix} \quad \text{es diagonal dominante estricta por filas}$$

$$\bullet \quad A = \begin{pmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{pmatrix} \quad \text{no es diagonal dominante estricta por filas : en las filas 2 y 3 } a_{ii}=2, \sum_{j=1}^n |a_{ij}|=2$$

$$\begin{aligned} \hookrightarrow \text{pero : } r_1 &= \frac{1}{2} < 1 \\ r_2 &= \frac{1}{2} \left(\frac{1}{2} + 1 \right) = \frac{3}{4} < 1 \\ r_3 &= \frac{1}{2} \left(\frac{3}{4} + 1 \right) = \frac{7}{8} < 1 \\ r_4 &= \frac{1}{2} \cdot \frac{7}{8} = \frac{7}{16} < 1 \end{aligned}$$

teorema: sea $A \in \mathbb{K}^{n \times n}$, $A = A^*$, $A > 0 \Rightarrow$
 $(\langle Ax, x \rangle > 0 \ \forall x)$
 $\Rightarrow G-S$ converge $\forall x_0$.

demonstración: queremos mostrar $\rho(B_{GS}(A)) < 1$
 $\Leftrightarrow \forall \lambda$ autovalor de $B_{GS}(A) : |\lambda| < 1$

. $A = A^* \Rightarrow U_A = L_A^*$ (↔)

. $A > 0 \Rightarrow$ todos sus elementos diagonales son > 0 :

$$a_{ii} = \langle Ae_i, e_i \rangle > 0$$

\Rightarrow en particular podemos definir

$$D_A^{-1} = \begin{pmatrix} \frac{1}{a_{11}} & & 0 \\ & \frac{1}{a_{22}} & \\ 0 & & \ddots & \\ & & & \frac{1}{a_{nn}} \end{pmatrix}, \quad D_A^{1/2} = \begin{pmatrix} \sqrt{a_{11}} & & 0 \\ & \sqrt{a_{22}} & \\ 0 & & \ddots & \\ & & & \sqrt{a_{nn}} \end{pmatrix}$$

. $B_{GS}(A) = -(D_A + L_A)^{-1} L_A^*$ tiene los mismos autovalores de $T B_{GS}(A) T^{-1}$, $\forall T \in \mathbb{K}^{n \times n}$ invertible

. sea $T = D_A^{1/2}$:

$$D_A^{1/2} B_{GS}(A) D_A^{-1/2} = - D_A^{1/2} (D_A + L_A)^{-1} \underbrace{L_A^*}_{I = D_A^{1/2} D_A^{-1/2}} D_A^{-1/2}$$

$$= - \underbrace{D_A^{1/2} (D_A + L_A)^{-1} D_A^{1/2}}_{I + D_A^{-1/2} L_A D_A^{-1/2}} \underbrace{D_A^{-1/2} L_A^* D_A^{-1/2}}_{L^*}$$

$$= - \underbrace{\left(D_A^{-1/2} (D_A + L_A) D_A^{-1/2} \right)^{-1}}_{I + L} \underbrace{D_A^{-1/2} L_A^* D_A^{-1/2}}_{L^*}$$

$$= - (I + L)^{-1} L^*$$

• see $v_\lambda \in \mathcal{H}^m$: $-(I+L)^{-1} L^* v_\lambda = \lambda v_\lambda$, $\|v_\lambda\|_2 = 1$

$\hookrightarrow -L^* v_\lambda = \lambda(I+L) v_\lambda$

$\Rightarrow -\langle v_\lambda, L^* v_\lambda \rangle = \lambda \langle v_\lambda, (I+L) v_\lambda \rangle = \lambda (1 + \langle v_\lambda, L v_\lambda \rangle)$

$\Rightarrow \lambda = - \frac{\langle v_\lambda, L^* v_\lambda \rangle}{1 + \langle v_\lambda, L v_\lambda \rangle}$

$= - \frac{\bar{z}}{1+z}$

$z = \langle v_\lambda, L v_\lambda \rangle \in \mathbb{C}$
 $= \langle L^* v_\lambda, v_\lambda \rangle$
 $= \overline{\langle v_\lambda, L^* v_\lambda \rangle}$

• $z = a + ib$, $a = \operatorname{Re}(z) \in \mathbb{R}$, $b = \operatorname{Im}(z) \in \mathbb{R}$

$|\lambda|^2 = \left| \frac{a - ib}{1 + a + ib} \right|^2 = \frac{a^2 + b^2}{1 + a^2 + 2a + b^2}$

$\hookrightarrow \boxed{|\lambda| < 1} \Leftrightarrow a^2 + b^2 < 1 + 2a + a^2 + b^2 \Leftrightarrow \boxed{1 + 2a > 0}$

• $1 + 2a = \|v_\lambda\|_2^2 + 2 \operatorname{Re} z = \|v_\lambda\|_2^2 + z + \bar{z}$

$= \|v_\lambda\|_2^2 + \langle v_\lambda, L v_\lambda \rangle + \langle v_\lambda, L^* v_\lambda \rangle$

$= \langle v_\lambda, (I + L + L^*) v_\lambda \rangle$

$D_A^{-1/2} D_A D_A^{-1/2} + D_A^{-1/2} L_A D_A^{-1/2} + D_A^{-1/2} L_A^* D_A^{-1/2}$

$= D_A^{-1/2} \underbrace{(D_A + L_A + L_A^*)}_A D_A^{-1/2}$

$= \underbrace{\langle D_A^{-1/2} v_\lambda, \rangle}_x \underbrace{A D_A^{-1/2} v_\lambda}_x = \langle Ax, x \rangle > 0 \quad \neq$