

# An Introduction to Deep Learning With Python

## [5.5] Visualizing convnet filters

Prof. Yuzo Iano

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### Defining the loss tensor for filter visualization

```
In [1]: from keras.applications import VGG16
        from keras import backend as K

        model = VGG16(weights='imagenet', include_top=False)

        layer_name = 'block3_conv1'
        filter_index = 0

        layer_output = model.get_layer(layer_name).output
        loss = K.mean(layer_output[:, :, :, filter_index])
```

Using TensorFlow backend.

WARNING:tensorflow:From C:\Users\pablo\AppData\Roaming\Python\Python36\site-packages\tensorflow\python\framework\ops\_def\_library.py:263: colocate\_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.  
Instructions for updating:  
Colocations handled automatically by placer.

### Obtaining the gradient of the loss with regard to the input

```
In [2]: grads = K.gradients(loss, model.input)[0]
```

### Gradient-normalization trick

```
In [3]: grads /= (K.sqrt(K.mean(K.square(grads))) + 1e-5)
```

### Fetching Numpy output values given Numpy input values

```
In [4]: iterate = K.function([model.input], [loss, grads])

        import numpy as np
        loss_value, grads_value = iterate([np.zeros((1, 150, 150, 3))])
```

### Loss maximization via stochastic gradient descent

```
In [5]: input_img_data = np.random.random((1, 150, 150, 3)) * 20 + 128.
        step = 1.

        for i in range(40):
            loss_value, grads_value = iterate([input_img_data])
            input_img_data += grads_value * step
```

### Utility function to convert a tensor into a valid image

```
In [6]: def deprocess_image(x):
        x -= x.mean()
        x /= (x.std() + 1e-5)
        x *= 0.1

        x += 0.5
        x = np.clip(x, 0, 1)

        x *= 255
        x = np.clip(x, 0, 255).astype('uint8')
        return x
```

## Function to generate filter visualizations

```
In [7]: def generate_pattern(layer_name, filter_index, size=150):
        layer_output = model.get_layer(layer_name).output
        loss = K.mean(layer_output[:, :, :, filter_index])

        grads = K.gradients(loss, model.input)[0]

        grads /= (K.sqrt(K.mean(K.square(grads))) + 1e-5)

        iterate = K.function([model.input], [loss, grads])

        input_img_data = np.random.random((1, size, size, 3)) * 20 + 128.

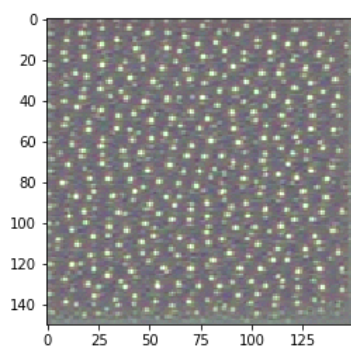
        step = 1.
        for i in range(40):
            loss_value, grads_value = iterate([input_img_data])
            input_img_data += grads_value * step

        img = input_img_data[0]
        return deprocess_image(img)
```

```
In [10]: import matplotlib.pyplot as plt

plt.imshow(generate_pattern('block3_conv1', 0))
```

Out[10]: <matplotlib.image.AxesImage at 0x1ff727e2b38>



## Generating a grid of all filter response patterns in a layer

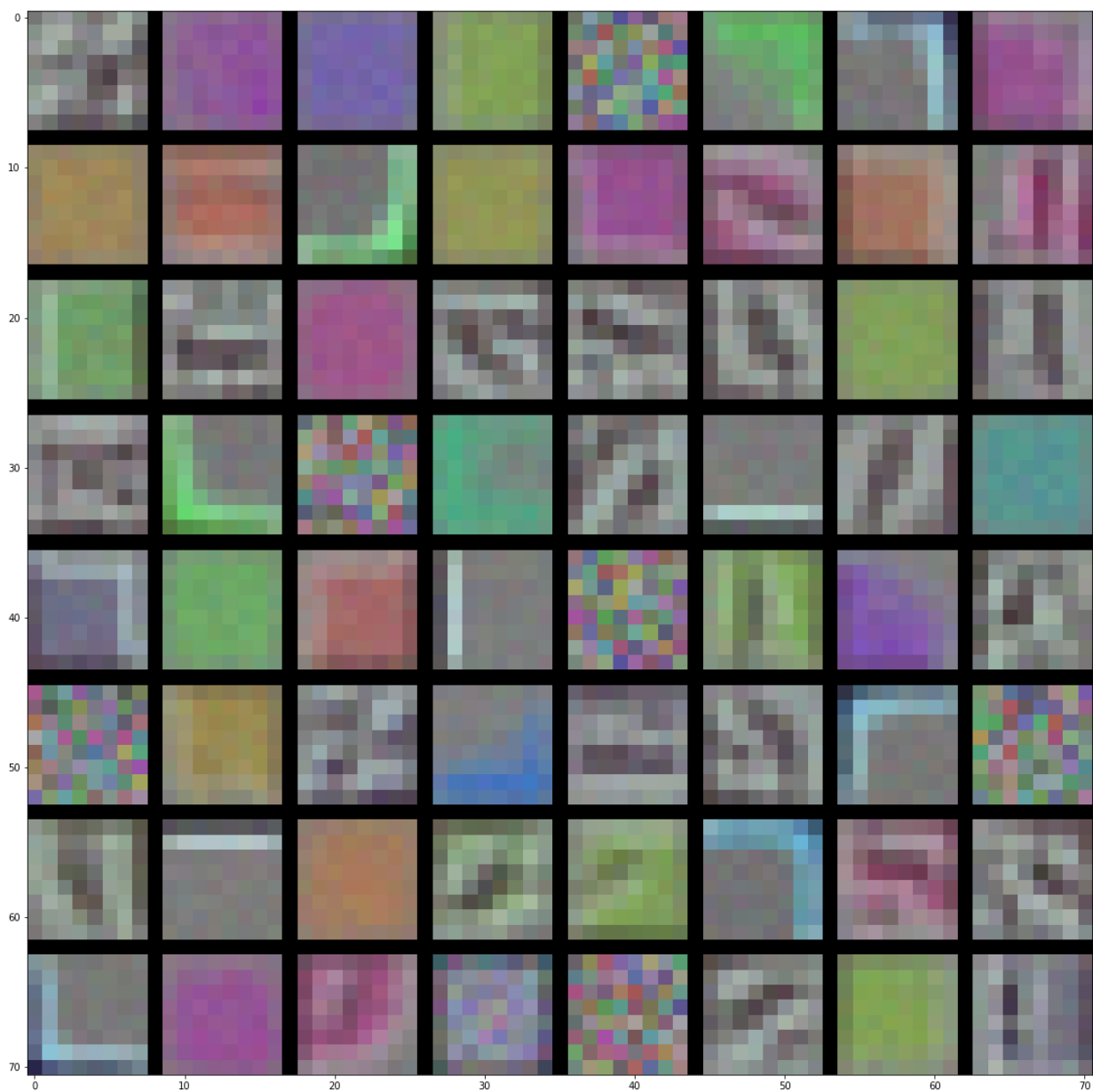
```
In [9]: for layer_name in ['block1_conv1', 'block2_conv1', 'block3_conv1', 'block4_conv1']:
        size = 8
        margin = 1

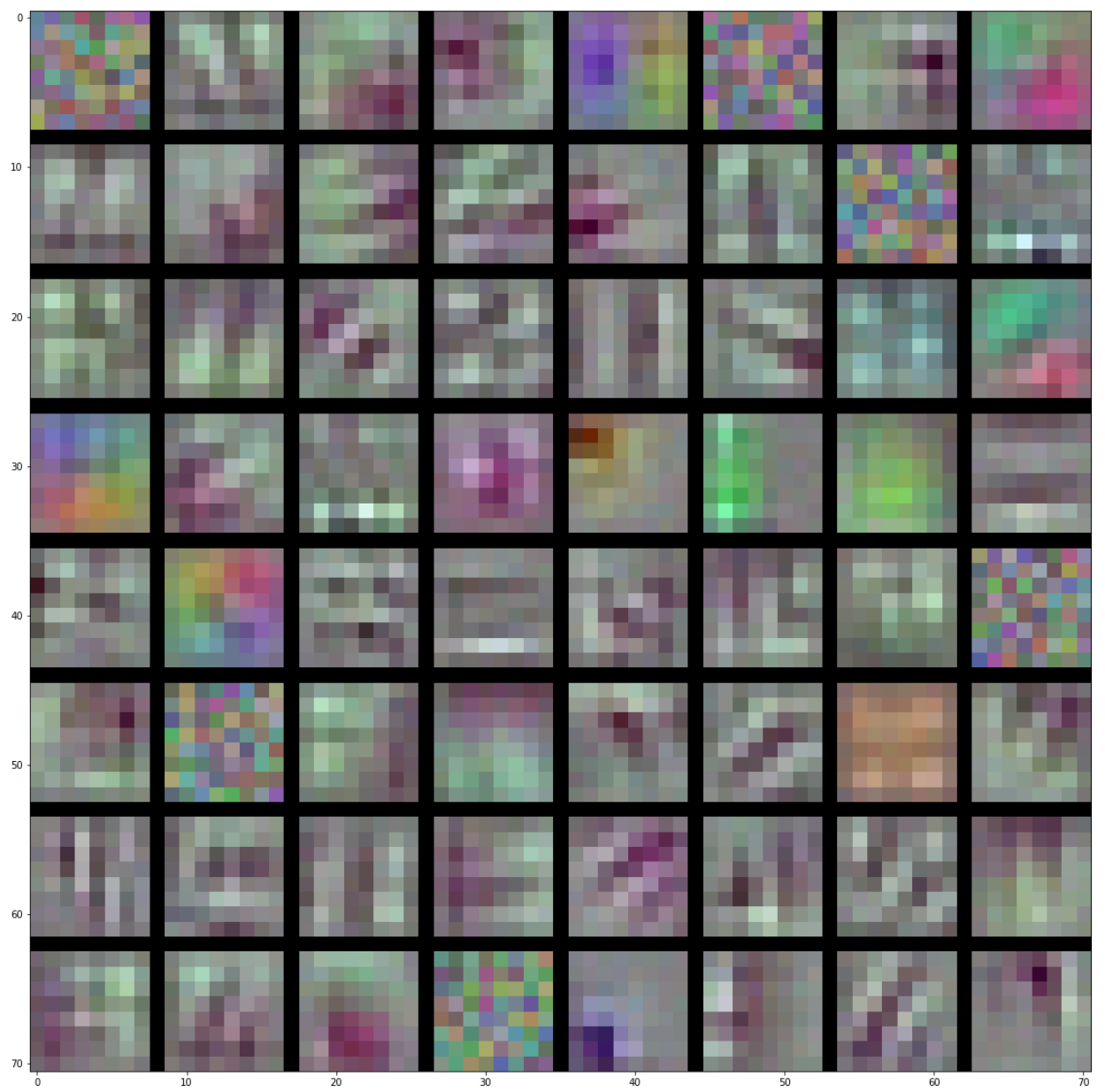
        results = np.zeros((8 * size + 7 * margin, 8 * size + 7 * margin, 3))

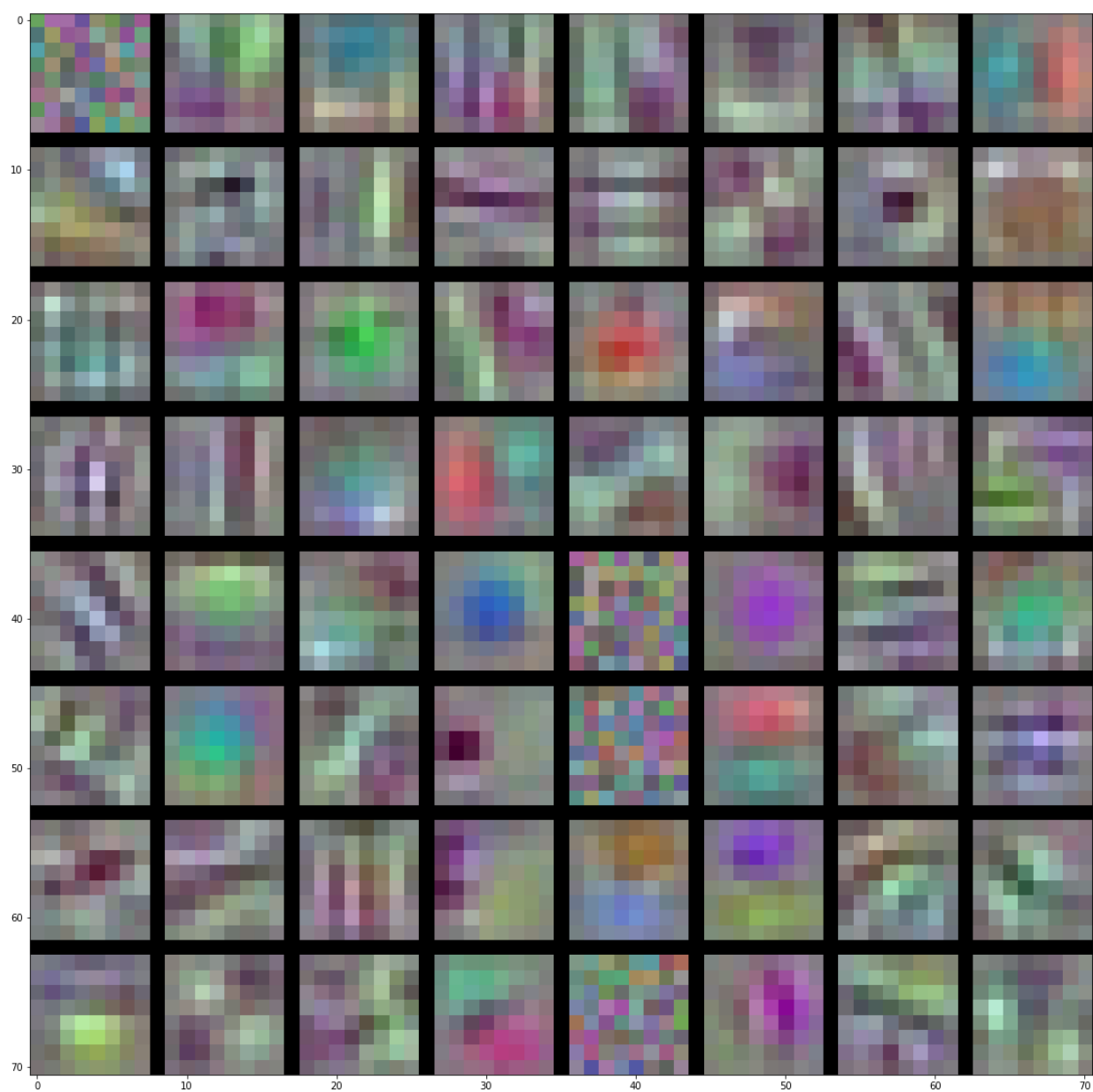
        for i in range(8):
            for j in range(8):
                filter_img = generate_pattern(layer_name, i + (j * 8), size=size)

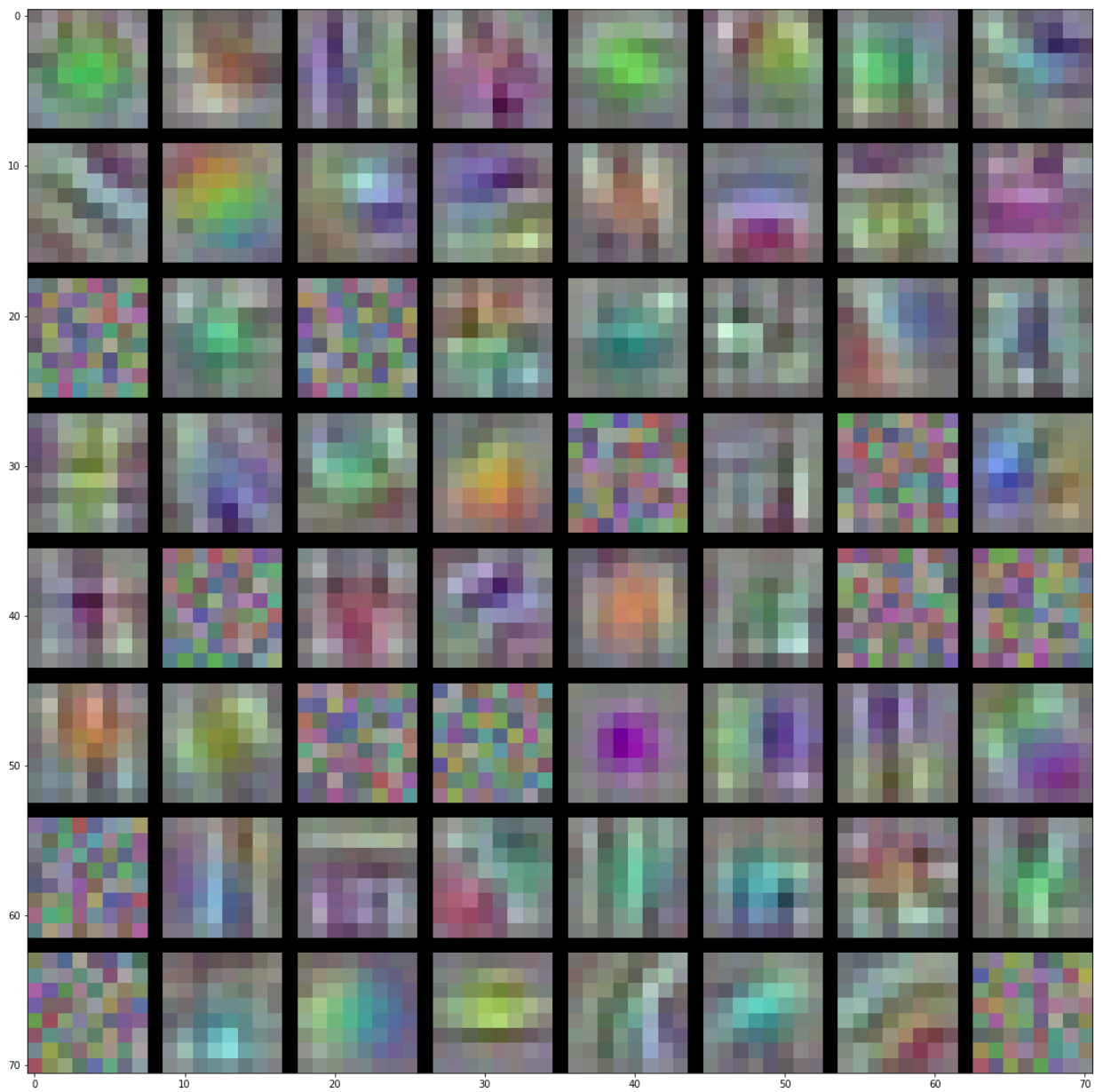
                horizontal_start = i * size + i * margin
                horizontal_end = horizontal_start + size
                vertical_start = j * size + j * margin
                vertical_end = vertical_start + size
                results[horizontal_start: horizontal_end, vertical_start: vertical_end, :] = filter_img

        plt.figure(figsize=(20, 20))
        plt.imshow(results.astype('uint8'))
        plt.show()
```









**Pablo Minango**

- [pablodavid218@gmail.com](mailto:pablodavid218@gmail.com)