# An Introduction to Deep Learning With Python

## [5.5] Visualizing convnet filters

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#### Defining the loss tensor for filter visualization

```
In [1]: from keras.applications import VGG16
    from keras import backend as K

model = VGG16(weights='imagenet', include_top=False)

layer_name = 'block3_conv1'
    filter_index = 0

layer_output = model.get_layer(layer_name).output
loss = K.mean(layer_output[:, :, :, filter_index])
```

Using TensorFlow backend.

WARNING:tensorflow:From C:\Users\pablo\AppData\Roaming\Python\Python36\site-packages\tensorflow\py thon\framework\op\_def\_library.py:263: colocate\_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

Instructions for updating:
Colocations handled automatically by placer.

colocations managed automatically by place.

## Obtaining the gradient of the loss with regard to the input

```
In [2]: grads = K.gradients(loss, model.input)[0]
```

### **Gradient-normalization trick**

```
In [3]: grads /= (K.sqrt(K.mean(K.square(grads))) + 1e-5)
```

#### Fetching Numpy output values given Numpy input values

```
In [4]: iterate = K.function([model.input], [loss, grads])
    import numpy as np
    loss_value, grads_value = iterate([np.zeros((1, 150, 150, 3))])
```

#### Loss maximization via stochastic gradient descent

```
In [5]: input_img_data = np.random.random((1, 150, 150, 3)) * 20 + 128.
step = 1.

for i in range(40):
    loss_value, grads_value = iterate([input_img_data])
    input_img_data += grads_value * step
```

## Utility function to convert a tensor into a valid image

```
In [6]: def deprocess_image(x):
    x -= x.mean()
    x /= (x.std() + 1e-5)
    x *= 0.1

    x += 0.5
    x = np.clip(x, 0, 1)

    x *= 255
    x = np.clip(x, 0, 255).astype('uint8')
    return x
```

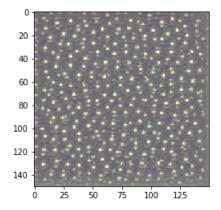
## Function to generate filter visualizations

```
In [7]: def generate_pattern(layer_name, filter_index, size=150):
    layer_output = model.get_layer(layer_name).output
    loss = K.mean(layer_output[:, :, :, filter_index])
    grads = K.gradients(loss, model.input)[0]
    grads /= (K.sqrt(K.mean(K.square(grads))) + 1e-5)
    iterate = K.function([model.input], [loss, grads])
    input_img_data = np.random.random((1, size, size, 3)) * 20 +128.
    step = 1.
    for i in range(40):
        loss_value, grads_value = iterate([input_img_data])
        input_img_data += grads_value * step

img = input_img_data[0]
    return deprocess_image(img)
```

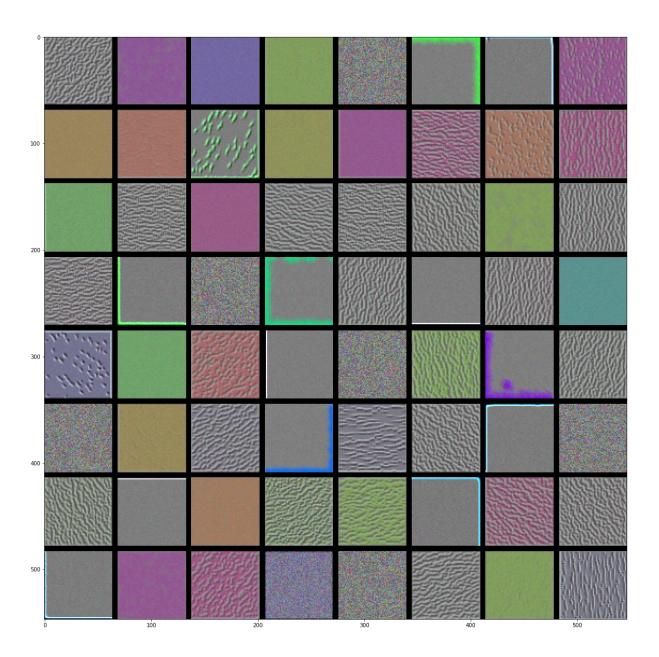
```
In [9]: import matplotlib.pyplot as plt
plt.imshow(generate_pattern('block3_conv1', 0))
```

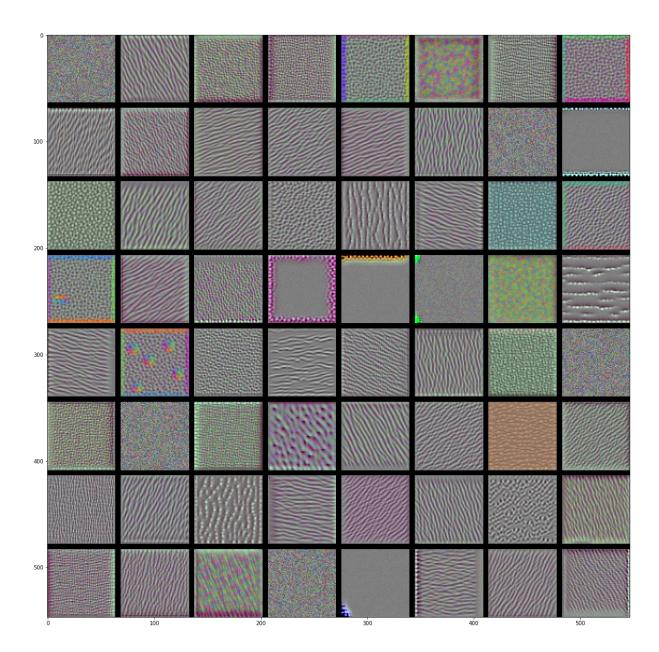
Out[9]: <matplotlib.image.AxesImage at 0x12fc0ed8940>

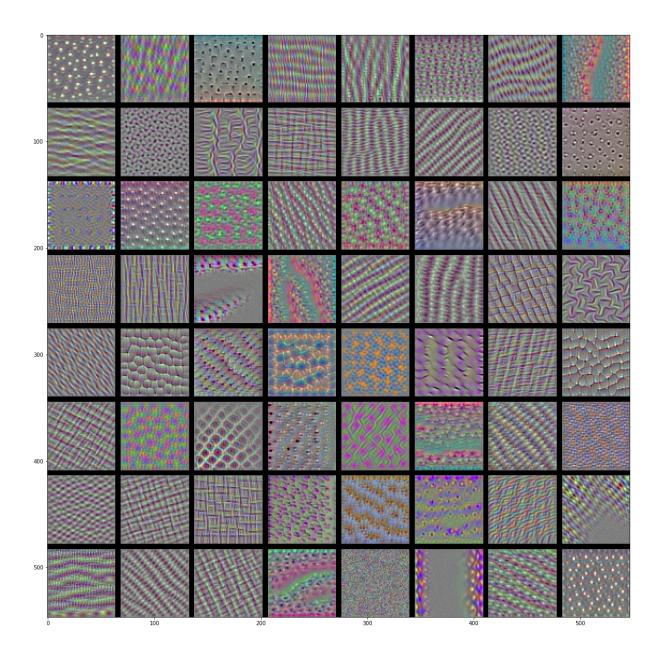


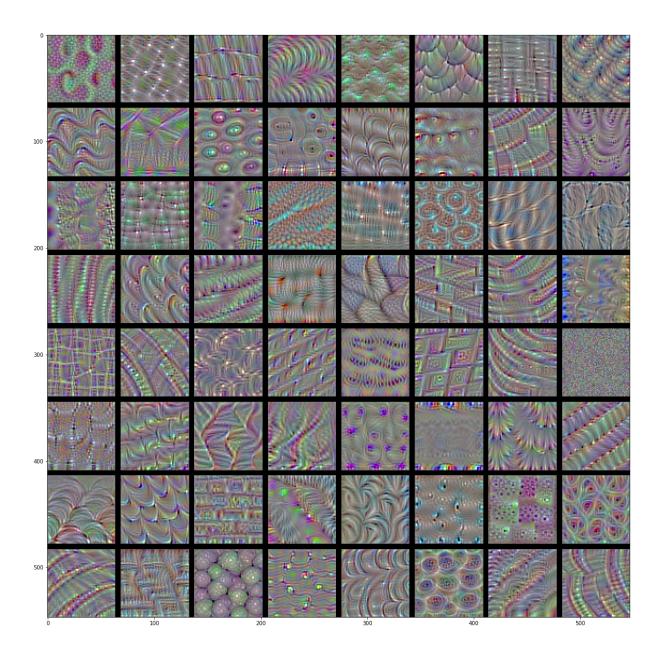
Generating a grid of all filter response patterns in a layer

```
In [10]: for layer_name in ['block1_conv1', 'block2_conv1', 'block3_conv1', 'block4_conv1']:
             size = 64
             margin = 5
             results = np.zeros((8 * size + 7 * margin, 8 * size + 7 * margin, 3))
             for i in range(8):
                 for j in range(8):
                     filter_img = generate_pattern(layer_name, i + (j * 8), size=size)
                     horizontal_start = i * size + i * margin
                     horizontal_end = horizontal_start + size
                     vertical_start = j * size + j * margin
                     vertical_end = vertical_start + size
                     results[horizontal_start: horizontal_end, vertical_start: vertical_end, :] = filter_im
         g
             plt.figure(figsize=(20, 20))
             plt.imshow(results.astype('uint8'))
             plt.show()
```









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