# An Introduction to Deep Learning With Python

# [6.4] A temperature-forecasting problem

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#### Inspecting the data of the Jena weather dataset

The dataset was download from <a href="https://www.kaggle.com/stytch16/jena-climate-2009-2016/version/1">https://www.kaggle.com/stytch16/jena-climate-2009-2016/version/1</a> (<a href="https://www.kaggle.com/stytch16/jena-climate-2009-2016/version/1">https://www.kaggle.com/stytch16/jena-climate-2009-2016/v

```
In [1]: import os

data_dir = 'jena_climate'
    fname = os.path.join(data_dir, 'jena_climate_2009_2016.csv')
    f = open(fname)
    data = f.read()
    f.close()

lines = data.split('\n')
    header = lines[0].split(',')
lines = lines[1:]

print(header)
print(len(lines))

['"Date Time"', '"p (mbar)"', '"T (degC)"', '"Tpot (K)"', '"Tdew (degC)"', '"rh (%)"', '"VPmax (mbar)"',
    '"VPact (mbar)"', '"VPdef (mbar)"', '"sh (g/kg)"', '"H2OC (mmol/mol)"', '"rho (g/m**3)"', '"wv (m/s)"',
    '"max. wv (m/s)"', '"wd (deg)"']
420551
```

# Parsing the data

```
In [2]: import numpy as np

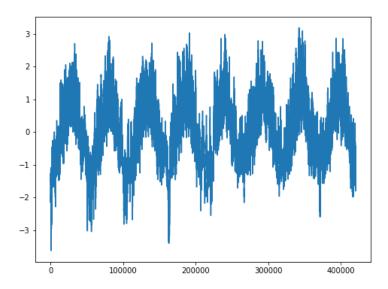
float_data = np.zeros((len(lines), len(header) - 1))
for i, line in enumerate(lines):
    values = [float(x) for x in line.split(',')[1:]]
    float_data[i, :] = values
```

Plotting the temperature timeseries

```
In [21]: import matplotlib.pyplot as plt

temp = float_data[:, 1]
   plt.figure(figsize=(8, 6))
   plt.plot(range(len(temp)), temp)
```

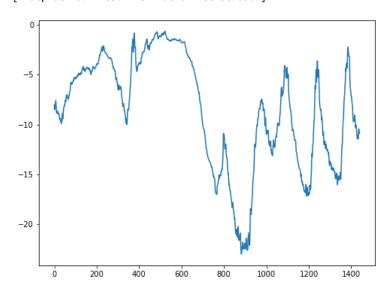
Out[21]: [<matplotlib.lines.Line2D at 0x14e80c1db38>]



# Plotting the first 10 days of the temperature timeseries

```
In [4]: plt.figure(figsize=(8, 6))
plt.plot(range(1440), temp[:1440])
```

Out[4]: [<matplotlib.lines.Line2D at 0x14ee73cab00>]



# Normalizing the data

```
In [5]: mean = float_data[:200000].mean(axis=0)
float_data -= mean
std = float_data[:200000].std(axis=0)
float_data /= std
```

# Generator yielding timseries samples and their targets

```
In [6]: def generator(data, lookback, delay, min_index, max_index,
                       shuffle=False, batch size=128, step=6):
             if max_index is None:
                max_index = len(data) - delay - 1
             i = min_index + lookback
             while 1:
                 if shuffle:
                     rows = np.random.randint(
                         min_index + lookback, max_index, size=batch_size)
                 else:
                     if i + batch_size >= max_index:
                         i = min_index + lookback
                     rows = np.arange(i, min(i + batch_size, max_index))
                     i += len(rows)
                 samples = np.zeros((len(rows),
                                     lookback // step,
                                     data.shape[-1]))
                 targets = np.zeros((len(rows),))
                 for j, row in enumerate(rows):
                     indices = range(rows[j] - lookback, rows[j], step)
                     samples[j] = data[indices]
targets[j] = data[rows[j] + delay][1]
                 yield samples, targets
```

#### Preparing the training, validation, and test generators

```
In [7]: lookback = 1440
        step = 6
        delay = 144
        batch_size = 128
        train_gen = generator(float_data,
                               lookback=lookback,
                               delay=delay,
                               min_index=0,
                               max index=200000,
                               shuffle=True,
                               step=step,
                               batch_size=batch_size)
        val_gen = generator(float_data,
                             lookback=lookback,
                             delay=delay,
                             min_index=200001,
                             max_index=300000,
                             step=step,
                             batch_size=batch_size)
        test_gen = generator(float_data,
                              lookback=lookback,
                              delay=delay,
                              min_index=300001,
                              max_index=None,
                              step=step,
                              batch_size=batch_size)
        val_steps = (300000 - 200001 - lookback) // batch_size
        test_steps = (len(float_data) - 300001 - lookback) // batch_size
```

#### Computing the common-sense baseline MAE

```
In [8]: def evaluate_naive_method():
    batch_maes = []
    for step in range(val_steps):
        samples, targets = next(val_gen)
        preds = samples[:, -1, 1]
        mae = np.mean(np.abs(preds - targets))
        batch_maes.append(mae)
        print(np.mean(batch_maes))
```

# Converting the MAE back to a Celsius error

```
In [9]: celsius_mae = 0.29 * std[1]
    celsius_mae
Out[9]: 2.5672247338393395
```

Training and evaluating a densely connected model

Using TensorFlow backend.

WARNING:tensorflow:From C:\Users\pablo\AppData\Roaming\Python\Python36\site-packages\tensorflow\python\framework\op\_def\_library.py:263: colocate\_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

Instructions for updating:

Colocations handled automatically by placer.

Layer (type)	Output Shape	Param #
flatten_1 (Flatten)	(None, 3360)	0
dense_1 (Dense)	(None, 32)	107552
dense_2 (Dense)	(None, 1)	33

Total params: 107,585 Trainable params: 107,585 Non-trainable params: 0

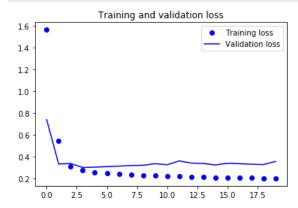
WARNING:tensorflow:From C:\Users\pablo\AppData\Roaming\Python\Python36\site-packages\tensorflow\python\ops\math\_ops.py:3066: to\_int32 (from tensorflow.python.ops.math\_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.cast instead.

Epoch 1/20 500/500 [===========] - 22s 44ms/step - loss: 1.5640 - val\_loss: 0.7385 Epoch 2/20 500/500 [============ ] - 22s 44ms/step - loss: 0.5444 - val loss: 0.3309 Epoch 3/20 500/500 [================= ] - 25s 51ms/step - loss: 0.3083 - val\_loss: 0.3359 Epoch 4/20 Epoch 5/20 Epoch 6/20 Epoch 7/20 500/500 [===========] - 26s 53ms/step - loss: 0.2391 - val\_loss: 0.3121 Epoch 8/20 Epoch 9/20 Epoch 10/20 Epoch 11/20 500/500 [===========] - 24s 47ms/step - loss: 0.2223 - val\_loss: 0.3245 Epoch 12/20 Epoch 13/20 500/500 [============ ] - 23s 46ms/step - loss: 0.2144 - val\_loss: 0.3401 Epoch 14/20 Epoch 15/20 Epoch 16/20 Epoch 17/20 500/500 [=========== ] - 23s 46ms/step - loss: 0.2055 - val\_loss: 0.3344 Epoch 18/20 Epoch 19/20 Epoch 20/20

```
In [11]: import matplotlib.pyplot as plt
    loss = history.history['loss']
    val_loss = history.history['val_loss']
    epochs = range(len(loss))
    plt.figure()
    plt.plot(epochs, loss, 'bo', label='Training loss')
    plt.plot(epochs, val_loss, 'b', label='Validation loss')
    plt.title('Training and validation loss')
    plt.legend()
    plt.show()
```

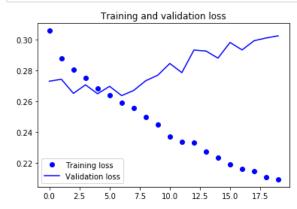


# A first recurrent baseline

Training and evaluating a GRU-based model

```
Layer (type)
                  Output Shape
                                    Param #
                _____
gru_1 (GRU)
                   (None, 32)
                                    4512
dense_3 (Dense)
                   (None, 1)
                                    33
______
Total params: 4,545
Trainable params: 4,545
Non-trainable params: 0
Epoch 1/20
500/500 [===========] - 99s 197ms/step - loss: 0.3057 - val_loss: 0.2730
Epoch 2/20
500/500 [==========] - 96s 192ms/step - loss: 0.2878 - val_loss: 0.2743
Epoch 3/20
Epoch 4/20
500/500 [============] - 94s 188ms/step - loss: 0.2752 - val_loss: 0.2707
Epoch 5/20
500/500 [=========== ] - 92s 183ms/step - loss: 0.2683 - val_loss: 0.2649
Epoch 6/20
500/500 [============ ] - 94s 188ms/step - loss: 0.2638 - val loss: 0.2697
Epoch 7/20
500/500 [===========] - 94s 187ms/step - loss: 0.2593 - val_loss: 0.2637
Epoch 8/20
500/500 [===========] - 94s 189ms/step - loss: 0.2555 - val_loss: 0.2670
Epoch 9/20
500/500 [==========] - 92s 185ms/step - loss: 0.2500 - val_loss: 0.2733
Epoch 10/20
500/500 [============ ] - 94s 188ms/step - loss: 0.2448 - val loss: 0.2769
Epoch 11/20
Epoch 12/20
500/500 [============= ] - 96s 191ms/step - loss: 0.2337 - val_loss: 0.2785
Epoch 13/20
500/500 [============] - 92s 185ms/step - loss: 0.2331 - val_loss: 0.2931
Epoch 14/20
Epoch 15/20
Epoch 16/20
500/500 [================= ] - 94s 187ms/step - loss: 0.2194 - val_loss: 0.2981
Epoch 17/20
500/500 [================= ] - 93s 185ms/step - loss: 0.2165 - val_loss: 0.2933
Epoch 18/20
500/500 [===========] - 93s 185ms/step - loss: 0.2146 - val_loss: 0.2992
Epoch 19/20
Epoch 20/20
500/500 [=========== ] - 63s 127ms/step - loss: 0.2095 - val_loss: 0.3024
```

```
In [13]: loss = history.history['loss']
    val_loss = history.history['val_loss']
    epochs = range(len(loss))
    plt.figure()
    plt.plot(epochs, loss, 'bo', label='Training loss')
    plt.plot(epochs, val_loss, 'b', label='Validation loss')
    plt.title('Training and validation loss')
    plt.legend()
    plt.show()
```



Using recurrent dropout to fight overfitting

Training and evaluating a dropout-regularized GRU-based model

 $\label{libsite-packages} WARNING: tensorflow: From C: \Users \pable \pathon \envs \DAVID \lib \site-packages \keras \backend \tensorflow\_backend \end{tensorflow}.$ d.py:3445: calling dropout (from tensorflow.python.ops.nn\_ops) with keep\_prob is deprecated and will be re moved in a future version.

Param #

Layer (type)

Instructions for updating:
Please use `rate` instead of `keep\_prob`. Rate should be set to `rate = 1 - keep\_prob`.

Output Shape

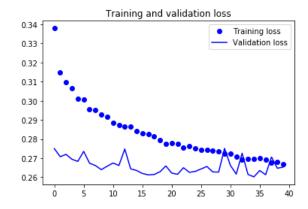
======================================	ойтрит зпар		
gru_2 (GRU)	(None, 32)	4512	
dense_4 (Dense)	(None, 1)	33	
Tatal	========		
Total params: 4,545			
Trainable params: 4,545			
Non-trainable params: 0			
Epoch 1/40			
500/500 [===========	======]	- 73s 145ms/step - loss:	0.3379 - val_loss: 0.2750
Epoch 2/40	,	72- 146/	0.2150
500/500 [=========== Epoch 3/40	,	- /35 146ms/step - 1055:	0.3130 - Val_10SS: 0.2707
500/500 [==========	=======1	- 70s 140ms/step - loss:	0.3096 - val loss: 0.2720
Epoch 4/40	•	, , , , , , , , , , , , , , , , , , ,	
500/500 [=========	======]	- 70s 140ms/step - loss:	0.3066 - val_loss: 0.2694
Epoch 5/40			
500/500 [===================================	]	- 70s 140ms/step - loss:	0.3009 - val_loss: 0.2683
Epoch 6/40 500/500 [===================================	1	- 68s 137ms/sten - loss:	0 3008 - val loss: 0 2735
Epoch 7/40	,	200 2575, 5 ccp 2005 t	0.5000 .01_1035. 0.12735
500/500 [==========	]	- 71s 141ms/step - loss:	0.2957 - val_loss: 0.2673
Epoch 8/40			
500/500 [===========	======]	- 68s 136ms/step - loss:	0.2952 - val_loss: 0.2661
Epoch 9/40 500/500 [===================================	1	- 71c 1/2mc/ctan - locc	0 2030 - val loss: 0 2640
Epoch 10/40		713 142m3/3ccp 1033.	0.2330 Vai_1033. 0.2040
500/500 [=========	]	- 73s 147ms/step - loss:	0.2917 - val_loss: 0.2657
Epoch 11/40	_		
500/500 [===================================	]	- 68s 137ms/step - loss:	0.2886 - val_loss: 0.2674
500/500 [==========	======1	- 70s 139ms/step - loss:	0.2873 - val loss: 0.2661
Epoch 13/40	,		
500/500 [========	]	- 69s 138ms/step - loss:	0.2867 - val_loss: 0.2748
Epoch 14/40	,	60 407 / / 1	0.0064 1.1 0.0644
500/500 [===================================	]	- 68S 13/mS/Step - 10SS:	0.2864 - Val_loss: 0.2644
500/500 [==========	1	- 68s 137ms/step - loss:	0.2843 - val loss: 0.2635
Epoch 16/40	-		_
500/500 [=========	]	- 68s 135ms/step - loss:	0.2831 - val_loss: 0.2620
Epoch 17/40 500/500 [===================================	1	- 67s 135ms/ston - loss:	0 2827 - val loss: 0 2612
Epoch 18/40	]	- 0/3 133m3/3cep - 1033.	0.2027 - Val_1033. 0.2012
500/500 [=========	]	- 65s 130ms/step - loss:	0.2814 - val_loss: 0.2614
Epoch 19/40		/	
500/500 [=========== Epoch 20/40	======]	- 63s 127ms/step - loss:	0.2794 - val_loss: 0.2629
500/500 [=========	======1	- 65s 130ms/step - loss:	0.2776 - val loss: 0.2659
Epoch 21/40	-		_
500/500 [=========	]	- 64s 128ms/step - loss:	0.2778 - val_loss: 0.2622
Epoch 22/40 500/500 [========	1	- 63s 125ms/ston - loss:	0 2774 - val loss: 0 2616
Epoch 23/40	]	- 033 123m3/3cep - 1033.	0.2774 - Val_1033. 0.2010
500/500 [=========	]	- 66s 131ms/step - loss:	0.2754 - val_loss: 0.2650
Epoch 24/40	_		
500/500 [===========	]	- 62s 124ms/step - loss:	0.2765 - val_loss: 0.2626
Epoch 25/40 500/500 [===================================	1	- 62s 124ms/sten - loss:	0.2750 - val loss: 0.2630
Epoch 26/40	,		
500/500 [=========	]	- 65s 130ms/step - loss:	0.2743 - val_loss: 0.2643
Epoch 27/40 500/500 [========	1	625 122ms/s+on loss.	0 2742 val lass, 0 2656
Epoch 28/40	,	- 625 123mS/Step - 1055:	0.2742 - Val_1055: 0.2656
500/500 [========	]	- 62s 125ms/step - loss:	0.2739 - val_loss: 0.2628
Epoch 29/40	_	·	_
500/500 [===========	]	- 64s 128ms/step - loss:	0.2736 - val_loss: 0.2627
Epoch 30/40 500/500 [===================================	1	- 62s 124ms/sten - loss.	0.2723 - val loss 0.2751
Epoch 31/40	]	эдэ дания, эсер 1033.	1.1.15 101_1033. 0.2/31
500/500 [========	======]	- 63s 127ms/step - loss:	0.2722 - val_loss: 0.2662
Epoch 32/40		646 120	0 2700 1 1 0 2617
500/500 [===================================	]	- 645 129MS/STEP - 10SS:	v.2/v8 - Val_10ss: 0.2617
LPUCII 33/40			

#### Plotting results

```
In [15]: loss = history.history['loss']
    val_loss = history.history['val_loss']
    epochs = range(len(loss))
    plt.figure()

    plt.plot(epochs, loss, 'bo', label='Training loss')
    plt.plot(epochs, val_loss, 'b', label='Validation loss')
    plt.title('Training and validation loss')
    plt.legend()

    plt.show()
```



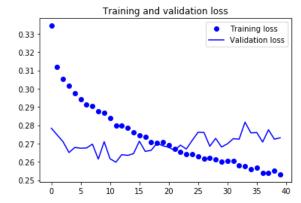
Training and evaluating a dropout-regularized, stacked GRU model

Layer (type)	Output Shape	Param #
gru_3 (GRU)	(None, None, 32)	4512
gru_4 (GRU)	(None, 64)	18624
dense_5 (Dense)	(None, 1)	65
Total params: 23,201 Trainable params: 23,201 Non-trainable params: 0		

Epoch 1/40 500/500 [============ ] - 225s 449ms/step - loss: 0.3343 - val loss: 0.2783 Epoch 2/40 Epoch 3/40 500/500 [=== Epoch 4/40 500/500 [============ ] - 224s 448ms/step - loss: 0.3015 - val\_loss: 0.2651 Epoch 5/40 500/500 [============] - 224s 448ms/step - loss: 0.2974 - val\_loss: 0.2679 Epoch 6/40 Epoch 7/40 500/500 [============= ] - 223s 446ms/step - loss: 0.2913 - val\_loss: 0.2676 Epoch 8/40 Epoch 9/40 500/500 [=========== ] - 222s 444ms/step - loss: 0.2878 - val\_loss: 0.2615 Epoch 10/40 Epoch 11/40 500/500 [============] - 223s 446ms/step - loss: 0.2841 - val\_loss: 0.2617 Epoch 12/40 500/500 [============ ] - 233s 465ms/step - loss: 0.2800 - val loss: 0.2598 Epoch 13/40 Epoch 14/40 Epoch 15/40 Epoch 16/40 500/500 [============ ] - 229s 458ms/step - loss: 0.2746 - val loss: 0.2713 Epoch 17/40 500/500 [============] - 233s 466ms/step - loss: 0.2735 - val\_loss: 0.2657 Epoch 18/40 Epoch 19/40 500/500 [===== Epoch 20/40 500/500 [==== Epoch 21/40 Epoch 22/40 Epoch 23/40 500/500 [===== Epoch 24/40 Fnoch 25/40 500/500 [============ ] - 230s 460ms/step - loss: 0.2640 - val loss: 0.2717 Epoch 26/40 Epoch 27/40 500/500 [============ ] - 236s 472ms/step - loss: 0.2615 - val\_loss: 0.2761 Epoch 28/40 500/500 [============] - 250s 500ms/step - loss: 0.2622 - val\_loss: 0.2685 Epoch 29/40 500/500 [============= ] - 251s 503ms/step - loss: 0.2612 - val loss: 0.2728 Epoch 30/40 Epoch 31/40 500/500 [============] - 229s 458ms/step - loss: 0.2604 - val\_loss: 0.2698 Epoch 32/40 500/500 [===========] - 229s 459ms/step - loss: 0.2604 - val\_loss: 0.2726 Epoch 33/40 500/500 [=========== ] - 236s 473ms/step - loss: 0.2581 - val loss: 0.2724 Epoch 34/40 

#### **Plotting results**

```
In [17]: loss = history.history['loss']
    val_loss = history.history['val_loss']
    epochs = range(len(loss))
    plt.figure()
    plt.plot(epochs, loss, 'bo', label='Training loss')
    plt.plot(epochs, val_loss, 'b', label='Validation loss')
    plt.title('Training and validation loss')
    plt.legend()
    plt.show()
```



# Using bidirectional RNNs

You need to do is write a variant of the data generator where the input sequences are reverted along the time dimension (replace the last line with yield samples[:, ::-1, :], targets).

```
In [18]: def generator(data, lookback, delay, min_index, max_index,
                       shuffle=False, batch size=128, step=6):
             if max_index is None:
                 max_index = len(data) - delay - 1
             i = min_index + lookback
             while 1:
                 if shuffle:
                      rows = np.random.randint(
                         min_index + lookback, max_index, size=batch_size)
                 else:
                     if i + batch_size >= max_index:
                         i = min_index + lookback
                      rows = np.arange(i, min(i + batch_size, max_index))
                     i += len(rows)
                 samples = np.zeros((len(rows),
                                     lookback // step,
                                     data.shape[-1]))
                 targets = np.zeros((len(rows),))
                 for j, row in enumerate(rows):
                     indices = range(rows[j] - lookback, rows[j], step)
                     samples[j] = data[indices]
                      targets[j] = data[rows[j] + delay][1]
                 yield samples[:, ::-1, :], targets
         lookback = 1440
         step = 6
         delay = 144
         batch_size = 128
         train_gen = generator(float_data,
                                lookback=lookback,
                                delay=delay,
                                min_index=0,
                                max_index=200000,
                                shuffle=True,
                                step=step,
                                batch_size=batch_size)
         val_gen = generator(float_data,
                             lookback=lookback,
                              delay=delay,
                             min_index=200001,
                              max_index=300000,
                             step=step,
                             batch_size=batch_size)
         test_gen = generator(float_data,
                               lookback=lookback,
                               delay=delay,
                               min_index=300001,
                               max_index=None,
                               step=step,
                               batch_size=batch_size)
         # This is how many steps to draw from `val_gen`
         # in order to see the whole validation set:
         val steps = (300000 - 200001 - lookback) // batch size
         # This is how many steps to draw from `test_gen`
         # in order to see the whole test set:
         test_steps = (len(float_data) - 300001 - lookback) // batch_size
```

```
In [19]: | from keras.models import Sequential
          from keras.layers import GRU, Dense
          from keras.optimizers import RMSprop
          model = Sequential()
          model.add(GRU(32, input_shape=(None, float_data.shape[-1])))
          model.add(Dense(1))
          model.summary()
          model.compile(optimizer=RMSprop(), loss='mae')
          history = model.fit_generator(train_gen,
                                           steps_per_epoch=500,
                                           epochs=20,
                                           validation_data=val_gen,
                                           validation_steps=val_steps)
          loss = history.history['loss']
          val_loss = history.history['val_loss']
          epochs = range(len(loss))
          plt.figure()
          plt.plot(epochs, loss, 'bo', label='Training loss')
plt.plot(epochs, val_loss, 'b', label='Validation loss')
          plt.title('Training and validation loss')
          plt.legend()
          plt.show()
```

Layer (type)	Output Shape	Param #	
gru_5 (GRU)	(None, 32)	4512	
dense_6 (Dense)	(None, 1)	33	
Total params: 4,545 Trainable params: 4,545 Non-trainable params: 0			
Epoch 1/20 500/500 [=======		- 64s 128ms/step - loss:	0.4767 - val_loss: 0.4909
Epoch 2/20 500/500 [========	- 	- 72s 144ms/step - loss:	0.4442 - val_loss: 0.4610
Epoch 3/20	_	·	0.4088 - val_loss: 0.4651
Epoch 4/20	_		
500/500 [========== Epoch 5/20	-====] -	- 66s 132ms/step - loss:	0.3719 - val_loss: 0.4623
500/500 [===================================	] -	- 64s 128ms/step - loss:	0.3378 - val_loss: 0.4552
500/500 [=========	] -	- 60s 120ms/step - loss:	0.3184 - val_loss: 0.4437
<del>-</del>	] -	- 62s 125ms/step - loss:	0.3021 - val_loss: 0.4783
Epoch 8/20 500/500 [========	] -	- 61s 123ms/step - loss:	0.2908 - val_loss: 0.4433
Epoch 9/20		- 60s 121ms/sten - loss:	0.2828 - val loss: 0.4508
Epoch 10/20	-		_
Epoch 11/20	_		0.2741 - val_loss: 0.4476
500/500 [=========== Epoch 12/20	-=====] -	- 62s 124ms/step - loss:	0.2649 - val_loss: 0.4372
•	] -	- 61s 121ms/step - loss:	0.2593 - val_loss: 0.4447
500/500 [=========	] -	- 63s 127ms/step - loss:	0.2554 - val_loss: 0.4518
Epoch 14/20 500/500 [==========	] -	- 61s 123ms/step - loss:	0.2510 - val_loss: 0.4397
Epoch 15/20 500/500 [========		- 60s 120ms/step - loss:	0.2448 - val_loss: 0.4524
Epoch 16/20	_		0.2410 - val_loss: 0.4547
Epoch 17/20	_	·	_
500/500 [========== Epoch 18/20	-=====] -	- 61s 122ms/step - loss:	0.2362 - val_loss: 0.4577
500/500 [=========== Epoch 19/20	] -	- 60s 119ms/step - loss:	0.2340 - val_loss: 0.4921
500/500 [==========	] -	- 63s 126ms/step - loss:	0.2294 - val_loss: 0.4494
Epoch 20/20 500/500 [========	] -	- 61s 123ms/step - loss:	0.2256 - val_loss: 0.4567
Training and	validation loss		
0.50		$\overline{}$	
0.45	<b></b>		
0.40 -			
0.35 -			
0.30 -			
0.25 - Training loss Validation loss	•••••	•••	

0.0

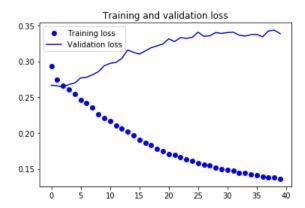
7.5

10.0 12.5 15.0 17.5

```
In [23]: | from keras.layers import Bidirectional
          model = Sequential()
          model.add(Bidirectional(GRU(32), input_shape=(None, float_data.shape[-1])))
          model.add(Dense(1))
          model.summary()
          model.compile(optimizer=RMSprop(), loss='mae')
          history = model.fit_generator(train_gen,
                                           steps_per_epoch=500,
                                           epochs=40,
                                           validation_data=val_gen,
                                           validation_steps=val_steps)
          loss = history.history['loss']
          val_loss = history.history['val_loss']
          epochs = range(len(loss))
          plt.figure()
          plt.plot(epochs, loss, 'bo', label='Training loss')
plt.plot(epochs, val_loss, 'b', label='Validation loss')
          plt.title('Training and validation loss')
          plt.legend()
          plt.show()
```

Layer (type)	Output	Shape	Param #
bidirectional_2 (Bidirection	(None,	64)	9024
dense_8 (Dense)	(None,	1)	65
Total params: 9,089 Trainable params: 9,089 Non-trainable params: 0			

Epoch 1/40 500/500 [============ ] - 92s 185ms/step - loss: 0.2929 - val loss: 0.2665 Epoch 2/40 500/500 [============ ] - 95s 190ms/step - loss: 0.2746 - val loss: 0.2658 Epoch 3/40 500/500 [================== ] - 93s 186ms/step - loss: 0.2661 - val\_loss: 0.2642 Epoch 4/40 500/500 [==== Epoch 5/40 500/500 [============= ] - 91s 181ms/step - loss: 0.2543 - val\_loss: 0.2699 Epoch 6/40 500/500 [===========] - 88s 176ms/step - loss: 0.2465 - val\_loss: 0.2769 Epoch 7/40 500/500 [===========] - 91s 183ms/step - loss: 0.2423 - val\_loss: 0.2777 Epoch 8/40 500/500 [=============] - 89s 177ms/step - loss: 0.2351 - val\_loss: 0.2812 Epoch 9/40 500/500 [================= ] - 90s 181ms/step - loss: 0.2265 - val\_loss: 0.2854 Epoch 10/40 500/500 [=========== ] - 88s 177ms/step - loss: 0.2209 - val\_loss: 0.2939 Epoch 11/40 Epoch 12/40 500/500 [=========== ] - 88s 176ms/step - loss: 0.2104 - val\_loss: 0.2985 Epoch 13/40 500/500 [============= ] - 90s 179ms/step - loss: 0.2064 - val loss: 0.3039 Epoch 14/40 500/500 [============ ] - 87s 175ms/step - loss: 0.2023 - val\_loss: 0.3158 Epoch 15/40 500/500 [============] - 90s 179ms/step - loss: 0.1971 - val\_loss: 0.3125 Epoch 16/40 500/500 [============ ] - 87s 174ms/step - loss: 0.1907 - val\_loss: 0.3102 Epoch 17/40 Epoch 18/40 500/500 [========== ] - 87s 175ms/step - loss: 0.1831 - val\_loss: 0.3189 Epoch 19/40 500/500 [================= ] - 90s 180ms/step - loss: 0.1781 - val\_loss: 0.3216 Epoch 20/40 500/500 [===== Epoch 21/40 500/500 [============= ] - 90s 180ms/step - loss: 0.1707 - val\_loss: 0.3314 Epoch 22/40 500/500 [============ ] - 88s 176ms/step - loss: 0.1691 - val\_loss: 0.3276 Epoch 23/40 500/500 [============= ] - 90s 180ms/step - loss: 0.1666 - val\_loss: 0.3331 Epoch 24/40 500/500 [============ ] - 88s 175ms/step - loss: 0.1628 - val\_loss: 0.3321 Epoch 25/40 500/500 [=============] - 90s 180ms/step - loss: 0.1610 - val\_loss: 0.3334 Fnoch 26/40 500/500 [============= ] - 86s 172ms/step - loss: 0.1580 - val loss: 0.3407 Epoch 27/40 500/500 [===========] - 89s 177ms/step - loss: 0.1561 - val\_loss: 0.3349 Epoch 28/40 500/500 [============ ] - 86s 172ms/step - loss: 0.1544 - val\_loss: 0.3356 Epoch 29/40 500/500 [============ ] - 88s 177ms/step - loss: 0.1521 - val\_loss: 0.3402 Epoch 30/40 500/500 [============= ] - 86s 172ms/step - loss: 0.1496 - val loss: 0.3389 Epoch 31/40 Epoch 32/40 500/500 [============= ] - 86s 172ms/step - loss: 0.1477 - val\_loss: 0.3408 Epoch 33/40 Epoch 34/40 500/500 [===========] - 86s 172ms/step - loss: 0.1439 - val\_loss: 0.3353 Epoch 35/40 500/500 [============ ] - 87s 174ms/step - loss: 0.1425 - val\_loss: 0.3371



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