



# Certified defences hurt generalisation

Piersilvio De Bartolomeis<sup>1</sup>, Jacob Clarysse<sup>1</sup>, Fanny Yang<sup>1</sup>, Amartya Sanyal<sup>2</sup>

<sup>1</sup>Department of Computer Science, ETH Zürich <sup>2</sup>ETH AI Center



### ADVERSARIALLY ROBUST CLASSIFICATION

**Goal:** Low robust test error for a class of perturbations  $\mathcal{B}_{\epsilon}(x)$ 

$$\min_{\theta} \mathbb{E}_{(x,y) \sim \mathcal{D}} \left[ \max_{x' \in B_{\epsilon}(x)} L(f_{\theta}(x'), y) \right]$$

- Empirical defences
  - Solve the inner maximisation with firstorder optimisation methods
  - Find a lower bound solution  $x^*$

$$L(f_{\theta}(x^{\star}), y) \le \max_{x' \in \mathcal{B}_{\epsilon}(x)} L(f_{\theta}(x'), y)$$

- Certified defences
  - Solve a convex relaxation of the innermaximisation
  - Find an upper bound solution  $x^*$

$$\max_{x' \in \mathcal{B}_{\epsilon}(x)} L(f_{\theta}(x'), y) \le L(f_{\theta}(x^{\star}), y)$$

#### **FAIRNESS**

We measure the degree of unfairness as follows:

$$\frac{\max_k \mathbf{R}^k(\theta) - \mathbf{R}(\theta)}{1 - \mathbf{R}(\theta)}$$

where

- $ightharpoonup \mathbf{R}(\theta)$  is the error of the classifier
- $\mathbf{R}^k(\theta)$  is the error conditioned on the label k

#### REFERENCES

- [1] Aleksander Madry et al, Towards Deep Learning Models Resistant to Adversarial Attacks. ICLR, 2018.
- [2] Eric Wong and J. Zico Kolter, Provable Defenses against Adversarial Examples via the Convex Outer Adversarial Polytope. ICML, 2018.
- [3] Huan Zhang et al., Towards Stable and Efficient Training of Verifiably Robust Neural Networks. ICLR, 2020.

# How effective are certified defences in practice?

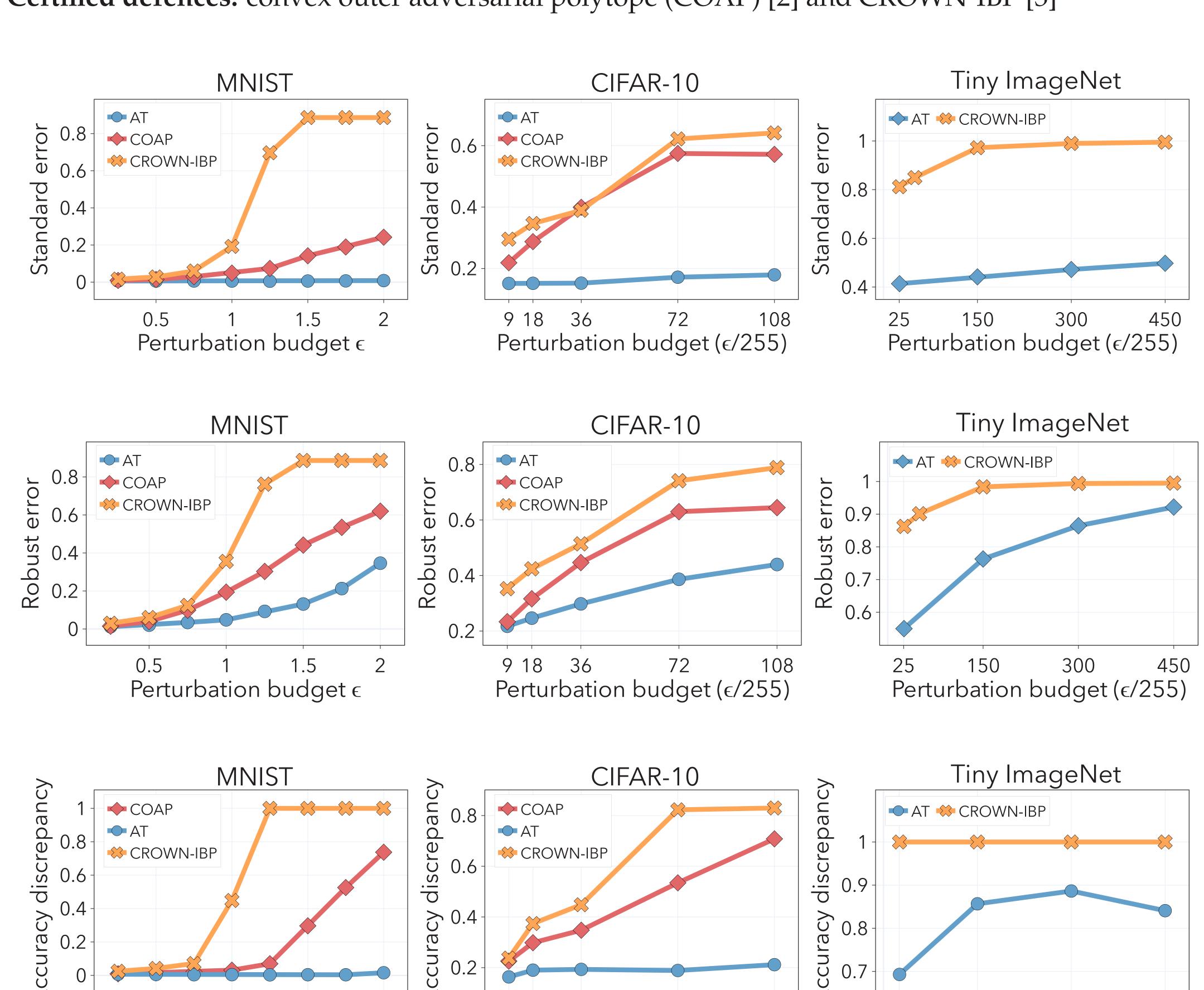
# CERTIFIED DEFENCES HURT GENERALISATION AND FAIRNESS

**Threat model:**  $\ell_2$ -ball perturbations of radius  $\epsilon$ 

Empirical defences: adversarial training (AT) [1]

Perturbation budget  $\epsilon$ 

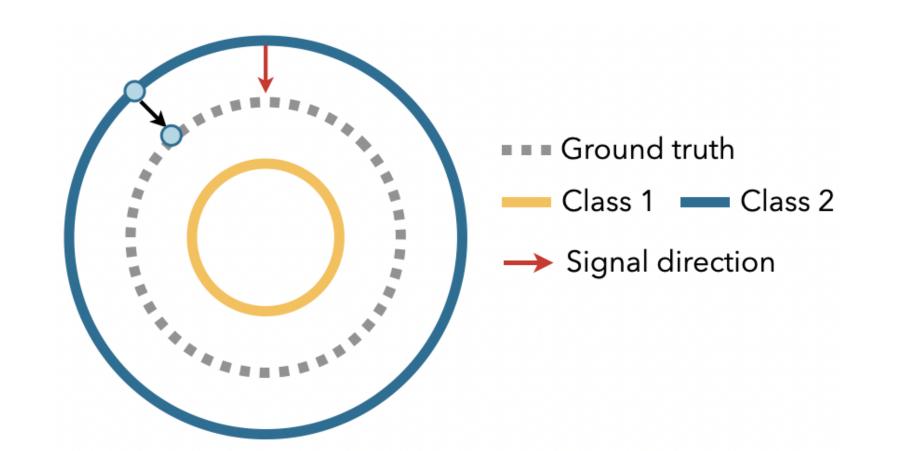
Certified defences: convex outer adversarial polytope (COAP) [2] and CROWN-IBP [3]



Perturbation budget ( $\epsilon/255$ )

#### WHY? INTUITION ON SYNTHETIC DATA

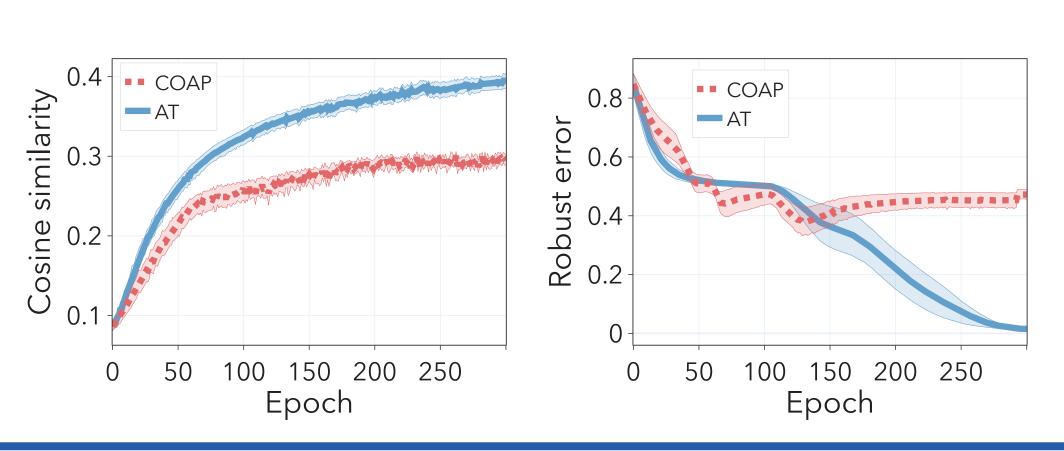
A more controlled setting: concentric spheres



Certified defences hurt generalisation when

- perturbation magnitude is large and
- perturbation aligns with the signal direction





## THEORETICAL RESULT

#### Setting

300

Perturbation budget ( $\epsilon$ /255)

150

450

- $y \sim \{-1, 1\}, x_1 = \gamma \operatorname{sgn}(y), x_{2:d} \sim \mathcal{N}(0, \sigma^2 I_{d-1})$
- $\mathcal{B}_{\epsilon}(x) = \{ z_1 = x + e_1 \beta \mid |\beta| \le \epsilon \}$
- $f_{\theta}(x) = a \operatorname{ReLU}(\theta^{\top} x) + b$
- $\theta_1$  is the only trainable parameter

#### Theorem (informal)

For  $\frac{2}{3}\gamma < \epsilon < \gamma$  and d large enough, after one step of gradient descent with respect to the COAP and AT objectives, we have:  $\mathbf{R}_{\epsilon}(\theta^{\mathrm{COAP}}) > \mathbf{R}_{\epsilon}(\theta^{\mathrm{AT}})$