

1 Basics

Gaussian

$$f(x) = \frac{1}{\sqrt{(2\pi)\sigma^2}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}, \quad \mathcal{N}(x|\mu, \sigma^2)$$

$$f(x) = \frac{1}{\sqrt{(2\pi)^d \det \Sigma}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}, \quad \mathcal{N}(x|\mu, \Sigma)$$

$$X \sim \mathcal{N}(\mu, \Sigma), \quad Y = A + BX \Rightarrow Y \sim \mathcal{N}(A + B\mu, B\Sigma B^T)$$

Conditionate Gaussians

$$\begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \sim \mathcal{N}\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right) \Rightarrow a_2|a_1 \sim$$

$$\mathcal{N}(\mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(a_1 - \mu_1), \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12})$$

Primal Dual problem

$$\text{Let } \mathcal{P} = \begin{cases} \min_w f(w) \\ g_i(w) = 0 \quad \forall i \\ h_j(w) \leq 0 \quad \forall j \end{cases}$$

Then the Slater's condition is:

$$\exists w \mid g_i(w) = 0, h_j(w) < 0 \quad \forall i, j$$

The lagrangian is:

$$\mathcal{L}(w, \lambda, \alpha) = f(w) + \sum_i \lambda_i g_i(w) + \sum_j \alpha_j h_j(w)$$

$$\mathcal{D} = \begin{cases} \max_{\lambda, \alpha} \theta(\lambda, \alpha) \\ \theta(\lambda, \alpha) = \min_w \mathcal{L}(w, \lambda, \alpha) \\ \alpha_j(w) \geq 0 \quad \forall j \end{cases}$$

\mathcal{D} is always a convex optimization problem. In general the solution of the \mathcal{D} is smaller than \mathcal{P} . But if Slater's condition holds then they are equal. And we get the complementary slackness: $\alpha_j^* h_j(w^*) = 0 \quad \forall$

The optimal $w^* = \min_w \mathcal{L}(w, \lambda^*, \alpha^*)$

Moments

- $Var[X] = E[XX^T] - E[X]E[X^T]$
- $Var[X+Y] = Var[X] + Var[Y] + 2Cov[X, Y]$
- $Cov[X, Y] = E[(X - E[X])(Y - E[Y])]$
- $Cov[aX, bY] = abCov[X, Y]$

Calculus

- $\frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{A} \mathbf{x}) = (\mathbf{A}^T + \mathbf{A}) \mathbf{x} \stackrel{\text{A sym.}}{=} 2\mathbf{A} \mathbf{x}$
- $\frac{\partial}{\partial \mathbf{x}} (\mathbf{b}^T \mathbf{A} \mathbf{x}) = \mathbf{A}^T \mathbf{b} \quad \frac{\partial}{\partial \mathbf{X}} (\mathbf{c}^T \mathbf{X} \mathbf{b}) = \mathbf{c} \mathbf{b}^T$
- $\mathbf{x}^T \mathbf{A} \mathbf{x} = Tr(\mathbf{x}^T \mathbf{A} \mathbf{x}) = Tr(\mathbf{x} \mathbf{x}^T \mathbf{A}) = Tr(\mathbf{A} \mathbf{x} \mathbf{x}^T)$
- $\frac{\partial}{\partial \mathbf{A}} Tr(\mathbf{A} \mathbf{B}) = \mathbf{B}^T \quad \frac{\partial}{\partial \mathbf{A}} |\mathbf{A}| = |\mathbf{A}| \mathbf{A}^{-T}$
- $\sigma(x) = \frac{1}{1+e^{-x}}$
- $\nabla \sigma(x) = \sigma(x)(1 - \sigma(x)) = \sigma(x)\sigma(-x)$
- $\nabla \tanh(x) = 1 - \tanh^2(x)$
- $\tanh x = \frac{\sinh x}{\cosh x} = \frac{e^x - e^{-x}}{e^x + e^{-x}} \quad \bullet \quad 2\sigma(x) - 1 = \tanh(x/2)$
- $f(x) \sim f(x_0) + (x - x_0)^T \nabla f(x_0) + \frac{1}{2}(x - x_0)^T H_f(x_0)(x - x_0)$

Newton's Method

$$\mathbf{x}^{(n+1)} \leftarrow \mathbf{x}^{(n)} - H_F^{-1}(\mathbf{x}^{(n)}) \nabla F(\mathbf{x}^{(n)})$$

$$f(x^*) = 0, f'(x^*) \neq 0 \Rightarrow Q$$

$$f(x^*) = 0, f^{(k)}(x^*) = 0 \Rightarrow L$$
$$\mathbf{x}^{(n+1)} \leftarrow \mathbf{x}^{(n)} - k H_F^{-1}(\mathbf{x}^{(n)}) \nabla F(\mathbf{x}^{(n)}) \Rightarrow Q$$

Jensen's inequality

$$\varphi: \text{convex} \rightarrow \varphi(E[X]) \leq E[\varphi(X)]$$

2 Gaussian Processes

$$p(y_{n+1} | x_{n+1}, X, y) = \mathcal{N}(y_{n+1} | \mu_{y_{n+1}}, \sigma_{y_{n+1}}^2)$$

$$\mu_{y_{n+1}} = k^T C_n^{-1} y = k^T (K + \sigma^2 I)^{-1} y$$

$$\sigma_{y_{n+1}}^2 = c - k^T C_n^{-1} k$$

$$C_n = K + \sigma^2 I$$

$$c = k(x_{n+1}, x_{n+1}) + \sigma^2$$

$$k = (x_{n+1}, X), K = (X, X)$$

2.1 Kernels

A function $k: \mathcal{X} \times \mathcal{X}$ is a kernel if: $k(x_1, x_2) =$

$$\langle \phi(x_1), \phi(x_2) \rangle$$

$k(x, y)$ is a kernel if it's symmetric semidefinite positive:

$\forall \{x_1, \dots, x_n\}$ then for the Gram Matrix

$$[K]_{ij} = k(x_i, x_j) \text{ holds } c^T K c \geq 0 \quad \forall c$$

Closure Properties:

$$k(x, y) = k_1(x, y) + k_2(x, y), \quad k(x, y) =$$

$$k_1(x, y) k_2(x, y)$$

$$k(x, y) = f(x) f(y), \quad k(x, y) = k_3(\phi(x), \phi(y))$$

$$k(x, y) = \exp(\alpha k_1(x, y)), \alpha > 0, |X \cap Y| = \text{kernel}$$

$$k(x, y) = p(k_1(x, y)), p(\cdot)$$

$$k(x, y) = k_1(x, y) / \sqrt{(k_1(x, x) k_1(y, y))}$$

$$\text{Gaussian (rbf): } k(x, y) = \sigma^2 \exp\left(-\frac{\|x-y\|^2}{2l^2}\right)$$

$$\text{Sigmoid: } k(x, y) = \tanh(k \cdot x^T y - b)$$

$$\text{Polynomial: } k(x, y) = (x^T y + c)^d, d \in \mathbb{N}, c \geq 0$$

$$\text{Periodic: } k(x, y) = \sigma^2 \exp\left(-\frac{2 \sin^2(\pi \|x-y\|/p)}{\ell^2}\right)$$

$$\text{Linear: } k(x, y) = \sigma_b^2 + \sigma^2(x - c)(y - c) = xy$$

$$\text{Rational Quadratic: } k(x, y) = \sigma^2(1 + \frac{(x-y)^2}{2a^2})^{-\alpha} \rightarrow \text{RBF}$$

2.2 Kernel Properties

$$k(u, u) \geq 0 \quad \forall u$$

$$k(u, v)^2 \leq k(u, u) k(v, v) \quad \forall u, v$$

$$\binom{n+k-1}{k} \text{ Comb. w rep. } \binom{n+d}{d} \text{ poly kernel}$$

3 Statistics Recap

Estimation

$$\bullet \text{ Consistency: } \hat{\theta}_n \xrightarrow{P} \theta, \text{ i.e. } \forall \epsilon P\{|\hat{\theta}_n - \theta| \geq \epsilon\} \xrightarrow{n \rightarrow \infty} 0$$

$$\bullet \text{ Asymptotic normality: } \sqrt{N}(\theta - \hat{\theta}_n) \rightarrow \mathcal{N}(0, J^{-1} I J^{-1})$$

$$\bullet \text{ Asymptotic efficiency: } \hat{\theta}_n \text{ minimizes } E[(\hat{\theta}_n - \theta)^2] \text{ as } n \rightarrow \infty$$

$$\bullet \text{ Not necessarily efficient for finite samples (e.g. Stein estimator of } \mathcal{N}(\theta, \sigma^2 I) \text{ for } d \geq 3 \text{ is}$$

better)

\bullet Equivariant: if $\hat{\theta}_n$ is the MLE of θ then $g(\hat{\theta}_n)$ is the MLE of $g(\theta)$ (w/ nice g)

\bullet Possibly Biased

Rao-Cramer

$$\Lambda = \frac{\partial \log \mathbb{P}(x|\theta)}{\partial \theta} \text{ (score function), } E[\Lambda] = 0$$

Fisher information: $\mathcal{I}(\theta) = \mathbb{V}[\Lambda]$

$$\mathcal{I}(\theta) = E[\Lambda^2] = -E\left[\frac{\partial^2 \log \mathbb{P}(x|\theta)}{\partial \theta \partial \theta^T}\right] = -E\left[\frac{\partial \Lambda}{\partial \theta}\right]$$

Oss: For the whole model:

$$\mathcal{I}_n = \mathbb{V}\left[\frac{\partial \log \mathbb{P}(x_i, i=1:n|\theta)}{\partial \theta}\right] = n\mathcal{I}$$

$$\text{MSE bound: } E[(\hat{\theta}_n - \theta)^2] \geq \frac{[1+b'(\hat{\theta}_n)]^2}{nE[\Lambda^2]} + b(\hat{\theta}_n)^2$$

$$\text{Cauchy-Schwarz: } |E(XY)|^2 \leq E(X^2)E(Y^2)$$

4 Linear Regression

$$y = X\beta + \epsilon \text{ where } y \in \mathbb{R}^n, X \in \mathbb{R}^{n \times d}, \beta \in \mathbb{R}^d$$

Risk Decomposition Theorem

$$\mathbb{E}_{Y,D} \left[(Y - \hat{f}(x_0))^2 \right] = \text{Bias}^2 + \text{Var.} + \text{Noise}$$

$$\text{Bias} = (\mathbb{E}_D [\hat{f}(x_0)] - \mathbb{E}[Y|X = x_0])$$

$$\text{Variance} = \mathbb{E}_D \left[(\mathbb{E}_D [\hat{f}(x_0)] - \hat{f}(x_0))^2 \right]$$

$$\text{Noise} = \mathbb{E}_Y \left[(Y - \mathbb{E}[Y|X = x_0])^2 \right]$$

Combination of Regression Models:

$$\text{bias}[\hat{f}(x)] = \frac{1}{B} \sum_{i=1}^B \text{bias}[\hat{f}_i(x)]$$

$$\mathbb{V}[\hat{f}(x)] = \frac{1}{B^2} \sum_i \mathbb{V}[\hat{f}_i(x)] + \frac{1}{B^2} \sum_{i \neq j} \text{cov}[\hat{f}_i(x), \hat{f}_j(x)] = \rho \sigma^2 + \frac{1-\rho}{B} \sigma^2 \approx \frac{\sigma^2}{B}$$

Minimum square linear regression

$$\hat{\beta} = \arg \min_{\beta} \|X\beta - y\|^2 \Rightarrow \hat{\beta} = (X^T X)^{-1} X^T y.$$

Here $\hat{\beta}$ is the BLUE (Best Linear Unbiased Estimator)

Projection of Y on space of X: $X\hat{\beta}$

Lasso regression

$$\hat{\beta} = \arg \min_{\beta} \|X\beta - y\|^2 + \lambda \|\beta\|_1 \Rightarrow \hat{\beta} = \text{No closed form (LARS algorithm) but it is a convex problem}$$

$$\text{Bayesian prior: } p(\beta_i) = \frac{1}{4\sigma^2} \exp\left(-|\beta_i| \frac{\lambda}{2\sigma^2}\right)$$

$$\text{Const. opt. } \hat{\beta} = \arg \min_{\beta} \|X\beta - y\|^2 \text{ s.t. } \|\beta\|_1 < s_{\lambda}$$

Ridge regression

$$\hat{\beta} = \arg \min_{\beta} \|X\beta - y\|^2 + \lambda \|\beta\|_2^2 \Rightarrow \hat{\beta} = (X^T X + \lambda I)^{-1} X^T y$$

$$\text{Bayesian prior } p(\beta) = N(0, \frac{\sigma^2}{\lambda} I)$$

$$\text{Const. opt. } \hat{\beta} = \arg \min_{\beta} \|X\beta - y\|^2 \text{ s.t. } \|\beta\|_2 < s_{\lambda}$$

$$X\hat{\beta}_{\text{ridge}} = X(X^T X + \lambda I)^{-1} X^T y = UD(D^2 + \lambda I)^{-1} DU^T y = \sum_{j=1}^d u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T y$$

The shrinkage factor shrinks small singular values and it approaches 1 for large singular values.

5 Classification

Loss-Functions

True class: $y \in \{-1, 1\}$, pred. $z \in [-1, 1]$

Cross-entropy (log loss): $(y' = \frac{(1+y)}{2} \text{ and } z' = \frac{(1+z)}{2})$ $L(y', z') = -[y' \log(z') + (1 - y') \log(1 - z')]$

Hinge Loss: $L(y, z) = \max(0, 1 - yz)$

Perceptron Loss: $L(y, z) = \max(0, -yz)$

Logistic loss: $L(y, z) = \log(1 + \exp(-yz))$

Square loss: $L(y, z) = \frac{1}{2}(y - z)^2$

Exponential loss: $L(y, z) = \exp(-yz)$

0/1 Loss: $L(y, z) = \mathbb{I}\{z \neq y\}$

Perceptron Algo

Classifier $c(x) = w^T x + w_0$. Loss $\mathcal{L}(w) = \sum_i y_i w^T x_i < 0 - y_i w^T x_i$. Train using (S)GD. Converges if data is linearly separable, and learning rate $\eta(k) \geq 0, \sum_k \eta(k) \rightarrow \infty$ and $(\sum_k \eta^2(k)) / (\sum_k \eta(k))^2 \rightarrow 0$. Update rule (on misclassified points): $w^{(k+1)} = w^{(k)} + \eta^{(k)} x_n y_n$

Fisher Discriminant

$$w^* = \arg \max_w \frac{w^T S_B w}{w^T S_w w} \propto S_w^{-1} (m_2 - m_1) \text{ where:}$$

$$S_B = (m_2 - m_1)(m_2 - m_1)^T$$

$$S_w = \sum_{i=1}^2 \sum_{n \in C_i} (x_n - m_i)(x_n - m_i)^T$$

6 SVM

Like Perceptron but maximizing the margin. Equivalent to

$$\mathcal{P} = \begin{cases} \min_{w, w_0} \frac{\|w\|_2^2}{2} \\ y_i(w^T x_i + w_0) \geq 1 \quad \forall i \end{cases} \quad \text{where the margin size is } \frac{2}{\|w\|^2}.$$

Slater conditions \Rightarrow

$$\mathcal{D} = \begin{cases} \max_{\alpha} \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \\ \alpha_i \geq 0 \quad \forall i \\ \sum_i \alpha_i y_i = 0 \end{cases}$$

Complementary slackness $\alpha_i^* h_i(w^*) = 0$ so either $\alpha_i^* = 0$ or x_i is a Support Vector

Soft margin SVM

C small \Rightarrow more misclassifications C high \Rightarrow hard margin

$$\mathcal{P} = \begin{cases} \min_{w, w_0, \xi} \frac{\|w\|_2^2}{2} + C \sum_i \xi_i \\ y_i(w^T x_i + w_0) \geq 1 - \xi_i \quad \forall i \\ \xi_i \geq 0 \quad \forall i \end{cases}$$

$$\mathcal{D} = \begin{cases} \max_{\alpha_i} \sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \\ 0 \leq \alpha_i \leq C \forall i \\ \sum_i \alpha_i y_i = 0 \end{cases}$$

$$\xi_i^* = \max(0, 1 - y_i(w^* x_i + w_0^*))$$

$$w^* = (\sum_i \alpha_i^* y_i x_i)$$

$$y = \text{sgn}(w^{*T} x) = \text{sgn}\left(\left(\sum_i \alpha_i^* y_i x_i\right)^T x_j\right)$$

Non linear SVM: $x_i^T x_j \rightarrow \phi(x_i)^T \phi(x_j) \rightarrow k(x_i, x_j)$

Multiclass SVM (one v. rest)

Train a binary classifier for each class (one vs the rest). Then assign a score $f_c(x) = w_c^T x$. Predictions: $c^* = \arg \max_c f_c(x)$

Structured SVM

Too many class for ovr. $\Psi : X \times Y \rightarrow \mathbb{R}^{m+d}$ is called Joint feature map $\mathcal{P} = \begin{cases} \min_{w,w_0} \frac{\|w\|^2}{2} + \frac{C}{n} \sum_{i=1}^n \xi_i \\ w^T \Psi(x_i, y_i) \geq \Delta(y_i, y') + w^T \Psi(x_i, y') - \xi_i \forall i \forall y' \neq y_i \\ \xi \geq 0 \forall i \end{cases}$

Theorem Δ as Loss (Structured SVM in Statistical Learning):

$$\hat{\mathcal{R}}(\mathcal{Z}_{train}) \doteq \frac{1}{n} \sum_{i=1}^n \Delta(y_i, c_{w^*}(x_i)) \leq \frac{1}{n} \sum_{i=1}^n \xi_i^*$$

7 Ensemble method Bagging

We train $b^{(1)}, \dots, b^{(M)}$ different classifiers.

$$\text{Then } \bar{b}(x) = \begin{cases} \frac{1}{M} \sum_{i=1}^M b^{(i)}(x) & \text{regression} \\ \text{majority}\left(b^{(i)}\right) & \text{classification} \end{cases}$$

Works if: the $b^{(i)}$ are almost independent. Bagging classifiers worse than random chance does not achieve good results

7.0.1 Theorem:

if $|y| < \infty$ then $\exists M$ large enough s.t.

$$\mathbb{E}_{Z,Z',Y|X} \left[(Y - \bar{b}(x))^2 \right] \leq \mathbb{E}_{Z,Z',Y|X} \left[(Y - b^{(i)}(x))^2 \right]$$

Random Forest

Sample B datasets Z^1, \dots, Z^B from Z with replacement. For each Z^b train a full decision tree $f^b(x)$ with one small modification: before each split randomly subsample $k \leq d$ features and only consider these for your split.

Adaboost

Boosting: Train weak learners sequentially on all data, but reweight misclassified samples higher, Bias \downarrow

Initialize weights $w_i = 1/n$, for $b=1:B$ do:

1. Fit classifier $c_b(x)$ with weights w_i
2. Compute error $\epsilon_b = \sum_i w_i^{(b)} \mathbb{1}_{[c_b(x_i) \neq y_i]} / \sum_i w_i^{(b)}$
3. Compute coeff. $\alpha_b = \log(\frac{1-\epsilon_b}{\epsilon_b})$
4. Update weights $w_i = w_i \exp(-\alpha_b y_i c_b(x_i))$
5. Normalize w_i dividing by $Z = 2\sqrt{\epsilon(1-\epsilon)}$

Return $\hat{c}_B(x) = \text{sign}(\sum_{b=1}^B \alpha_b c_b(x))$

Loss: Exponential loss $L(y, y') = \exp(-yy')$

Model: Forward Stagewise Additive

Oss: Self averaging algos that train Spiky interpolating classifiers.

AdaBoost trains max-margin classifier.

8 Mixtures Models (Unsupervised Learning) K-means

We find μ_1, \dots, μ_k such that our predictions are

$c(x) : \mathbb{R}^d \rightarrow \{1, \dots, k\}$.

Find $c(\cdot)$ and $\mu_i \forall i$ that minimize:

$$\mathcal{R}^{km}(c, \mu_i \forall i) = \sum_x \|x - \mu_{c(x)}\|^2$$

Initialize $\mu_i \forall i$;

while μ_i are changing **do**

$$\left[\begin{array}{l} c(x) \leftarrow \arg \min_c \|x - \mu_c\|^2 \forall x; \\ \mu_\alpha = \frac{1}{n_\alpha} \sum_{x:c(x)=\alpha} x \forall \alpha; \end{array} \right.$$

Gaussian Mixtures

1) Draw $z \sim \pi$ Categorical.

2) Draw $x \sim N(\mu_z, \Sigma_z)$

Expectation Maximization

Initialize $\theta^0 = \pi^0, \mu^0, \sigma^{20}$;

while $\|\theta^{j+1} - \theta^j\| > \epsilon$ **do**

E-step:

$$\gamma_{xc} \doteq \mathbb{E}[M_{xc}|X, \theta^j] =$$

$$\frac{p(X|c, \theta^j) p(c|\theta^j)}{p(x|\theta^j)} = \frac{N(\mu_c^j, \sigma_c^{2j}) \pi_c^j}{\sum_v \pi_v N(\mu_v, \sigma_v^{2j})}$$

$$Q(\theta, \theta^j) = \mathbb{E}[\sum_i \log p(x_i, z_i | \theta)]$$

$$= \sum_{x \in X} \sum_c (\gamma_{xc} \log(\pi_c P(x|\theta_c)))$$

M-step: $\theta_{j+1} = \arg \max_{\theta} Q(\theta, \theta_j)$

$$\pi_c^{j+1} = \frac{1}{|X|} \sum_{x \in X} \gamma_{xc}$$

$$\mu_c^{j+1} = \frac{\sum_{x \in X} \gamma_{xc} x}{\sum_{x \in X} \gamma_{xc}}$$

$$\sigma_c^{2j+1} = \frac{\sum_{x \in X} \gamma_{xc} (x - \mu_c)^2}{\sum_{x \in X} \gamma_{xc}}$$

Where $M_{xc} = \mathbb{I}_{\{x \text{ generated by } c\}}(x)$

9 Neural Network

Backpropagation

Let $\Phi(x) = f_{\theta_n}^{(n)} \circ f_{\theta_{n-1}}^{(n-1)} \circ \dots \circ f_{\theta_1}^{(1)}(x)$

$$\partial_{\Phi} f^{(i)} \doteq \partial_z f^{(i)}(z, \theta_i)|_{z=\Phi^{(i-1)}(x)}$$

$$\partial_{\theta} f^{(i)} \doteq \partial_z f^{(i)}(\Phi^{(i-1)}(x), \theta)|_{\theta=\theta_i}$$

Result: $\partial_{\theta_i} \Phi(x) \forall i$

Initialize $B = 1$;

for $i \leftarrow n, n-1, \dots, 1$ **do**

$$\left[\begin{array}{l} \partial_{\theta_i} \Phi(x) \leftarrow B \partial_{\theta} f^{(i)}; \\ B \leftarrow B \partial_{\Phi} f^{(i)}; \end{array} \right.$$

Once we have this we can $\nabla \downarrow$

Robinson-Monro

Given $f : \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}$, \underline{Z} random variable over \mathbb{R}^m , compute $\underline{\theta}^*$ s.t. $\mathbb{E}_{\underline{Z}}[f(\underline{Z}, \underline{\theta})] = 0$. Iteratively sample $z^{(k)} \sim \underline{Z}$ and set $\underline{\theta}^{(k)} \leftarrow \underline{\theta}^{(k-1)} - \eta(k) f(z_k, \underline{\theta}^{(k-1)})$.

For SGD, $f(\underline{z}, \underline{\theta}) = \nabla_{\theta} \mathcal{L}(y, NN_{\underline{\theta}}(x))$.

$z \rightarrow X, y$

Thm: R-M (and thus SGD) converges if $\eta(k) \geq 0$, $\sum_{k=1}^{\infty} \eta(k) = \infty$, $\sum_{k=1}^{\infty} \eta^2(k) < \infty$ and some regularity conditions on $\mathbb{E}_{\underline{Z}}[f(z, \theta)]$ hold.

Stochastic Gradient Descent

Result: optimal θ^*

Initialize θ ;

while Test error is decreasing **do**

$$\left[\begin{array}{l} \nabla_{\theta} Loss = \sum_{(x,y) \in S_k} \nabla_{\theta} \mathcal{L}(NN(x), y); \\ \theta \leftarrow \theta - \eta(k) \nabla_{\theta} Loss; \end{array} \right.$$

Oss: $S_k \in D$ and changes at each iteration (Mini Batch)

Oss: As long as $\sum_k \eta(k) = \infty$ and $\sum_k \eta^2(k) < \infty$ the SGD converges

Advantages over Normal Gradient Descent:

1) Can handle large Dataset 2) Faster improvement (w.r.t. time, not iterations) 3) Escapes local minima 4) Lower generalization error

Regularization techniques: 1) Dropout 2) Batch norm. 3) Early stop 4) Weight decay

Avoid dying ReLu:

$$\begin{cases} \alpha g(z), \text{ if } z < 0 \\ z, \text{ if } z \geq 0 \end{cases}$$

where $g(z)$ is $(\exp(z) - 1)$ for ELU and z for LeakyReLU. Dropout slows down training (not inference): noisy updates.

10 Autoencoders

Infomax principle

$I(X, Y) \doteq H(X) - H(X|Y)$ = mutual inform

$$\theta^* = \arg \max_{\theta} I(X, \text{enc}_{\theta} X) = \mathbb{E}_Z[\log(P(X, Z) - \log(P(X)P(Z)))]$$

$$\theta^* \simeq \arg \max_{\theta} \sum_i \mathbb{E}_Z[\log p(x_i|Z)]$$

It is informative but not Disentangled and Robust

Variation Autoencoders

Find encoder $q_{\phi}(z|x)$ and decoder $p_{\theta}(x|z)$ as:

$$\arg \max_{\theta, \phi} \sum_i \log p_{\theta, \phi}(x_i):$$

$$\log p_{\theta, \phi}(x_i) = \mathbb{E}_{z \sim q_{\phi}(\cdot|x_i)} \left[\log \left(\frac{p_{\theta}(x_i, z)}{p_{\theta}(z|x_i)} \frac{q_{\phi}(z|x_i)}{q_{\phi}(z|x_i)} \right) \right] =$$

$$E_{z \sim q_{\phi}(\cdot|x_i)} \left[\log \left(\frac{p_{\theta}(x_i, z)}{q_{\phi}(z|x_i)} \right) \right] + E_{z \sim q_{\phi}(\cdot|x_i)} \left[\log \frac{q_{\phi}(z|x_i)}{p_{\theta}(z|x_i)} \right] = E_{z \sim q_{\phi}(\cdot|x_i)} [\log p_{\theta}(x_i|z)] - D_{KL}(q_{\phi}(\cdot|x_i) || p_{\theta}(\cdot)) + D_{KL}(q_{\phi}(\cdot|x_i) || p_{\theta}(\cdot|x_i))$$

First term is Infomax and the second one is a regularization term.

11 Nonparametric Bayesian methods

$$\beta(x|a, b) = \frac{x^{(a-1)} \cdot (1-x)^{(b-1)}}{B(a, b)}, \quad B(\alpha) = \frac{\prod_{k=1}^n \Gamma(\alpha_k)}{\Gamma(\sum_{k=1}^n \alpha_k)}$$

$$Dir(x|\alpha) = \frac{1}{B(\alpha)} \prod_{k=1}^n x_k^{\alpha_k - 1}$$

Chinese Restaurant Process

$$p(\text{cust}_{n+1} \text{ joins table } \tau | \mathcal{P}) = \begin{cases} \frac{|\tau|}{\alpha + n} & \tau \in \mathcal{P} \\ \frac{\alpha}{\alpha + n} & \tau \notin \mathcal{P} \end{cases}$$

de Finetti: $p(X_1, \dots, X_n) = \int (\prod_{i=1}^n p(x_i|G)) dP(G)$

Stick breaking: $\rho = \{\rho_i\}_{i \in \mathbb{N}} \sim GEM(\alpha)$ if:

$\rho_k = \beta_k (1 - \sum_{i=1}^{k-1} \rho_k)$ Higher α , smaller pieces

Then $G(\theta) = \sum_{i=1}^{\infty} \rho_k \delta_{\theta_k}(\theta)$, $\theta_k \sim H$

$\Rightarrow G \sim DP(\alpha, H)$

Gibbs Sampling

DP generative model:

- Centers of the clusters: $\mu_k \sim \mathcal{N}(\mu_0, \sigma_0)$
- Prob.s of clusters: $\rho = \{\rho_k\}_{k=1}^{\infty} \sim GEM(\alpha)$
- Assignments to clusters: $z_i \sim \text{Categorical}(\rho)$
- Coordinates of data points: $\mathcal{N}(\mu_{z_i}, \sigma)$

$$p(z_i = k | z_{-i}, x, \alpha, \mu) = \begin{cases} \frac{N_{k,i}}{\alpha + N - 1} p(x_i | x_{-i,k}, \mu) & \exists k \\ \frac{\alpha}{\alpha + N - 1} p(x_i | \mu) & \text{otherwise} \end{cases}$$

12 PAC Learning

Empirical error: $\hat{\mathcal{R}}_n(c) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}_{\{c(x_i) \neq y_i\}}$

Expected error: $\mathcal{R}(c) = P\{c(x) \neq y\}$

ERM: $\hat{c}_n^* = \arg \min_{c \in \mathcal{C}} \hat{\mathcal{R}}_n(c)$

Generalization error: $\mathcal{R}(\hat{c}_n^*) = P\{\hat{c}_n^*(x) \neq y\}$

\mathcal{A} can learn c if $\exists \Pi$ in Polynomials s.t.:

- \forall distribution \mathcal{D} over X
- $\forall \epsilon \in (0, \frac{1}{2})$, $\forall \delta \in (0, \frac{1}{2})$
- $\forall n \geq \pi(\frac{1}{\epsilon}, \frac{1}{\delta}, \text{size}(\mathcal{C}))$

then $\mathbb{P}_{Z \sim \mathcal{D}}(\mathcal{R}(\mathcal{A}(Z)) - \inf_{c \in \mathcal{C}} \mathcal{R}(c) \leq \epsilon) \geq 1 - \delta$

If \mathcal{A} runs in time polynomial in $1/\epsilon, 1/\delta$, we say that \mathcal{C} is efficiently PAC learnable.

VC ineq.:

$$\mathcal{R}(\hat{c}_n^*) - \inf_{c \in \mathcal{C}} \mathcal{R}(c) \leq 2 \sup_{c \in \mathcal{C}} |\hat{\mathcal{R}}_n(c) - \mathcal{R}(c)|$$

$$P\{\mathcal{R}(\hat{c}_n^*) - \mathcal{R}(c^*) > \epsilon\} \leq P\{\sup_{c \in \mathcal{C}} |\hat{\mathcal{R}}_n(c) - \mathcal{R}(c)| > \frac{\epsilon}{2}\}$$

$$P\{\mathcal{R}(\hat{c}_n^*) - \mathcal{R}(c^*) > \epsilon\} \leq 2|\mathcal{C}| \exp(-2n\epsilon^2/4) \text{ if } \mathcal{C} \text{ is finite}$$

$$P\{\mathcal{R}(\hat{c}_n^*) - \mathcal{R}(c^*) > \epsilon\} \leq 9n^{\mathcal{VC}} \exp(-n\epsilon^2/32) \text{ if } |\mathcal{C}| \text{ is infinite}$$

where the \mathcal{VC} dimension of a function class \mathcal{C} is the maximum number of points that can be arranged so that \mathcal{C} shatters them.