Estimation of group effects

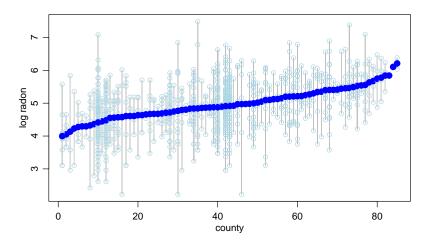
Peter Hoff Duke STA 610 Bias, variance and MSE

Fixed groups perspective

Random groups perspective

Bayesian perspective

MN radon data



Different amounts of information

```
y[g=="LACQUIPARLE"]

## [1] 6.036210 6.383751

y[g=="WASHINGTON"]

## [1] 5.933906 5.653191 4.412045 5.484196 6.112774 5.139915 5.437089 5.484196

## [9] 4.648416 4.269652 3.834061 4.497065 3.668259 3.834061 4.104487 3.473607

## [17] 4.162503 5.161298 4.162503 4.810531 3.473607 5.893950 5.280842 5.751848

## [25] 4.269652 5.499419 4.950219 5.387661 5.202746 4.537062 5.981707 4.497065

## [33] 4.366735 5.161298 4.923785 6.206521 4.682979 5.072896 4.950219 4.217459

## [41] 4.043070 4.217459 3.908367 5.499419 6.626603 5.404409
```

Linear shrinkage estimator: $\hat{\theta}_j = (1 - w_j)\bar{y}_j + w_j c$

- What should c be?
- What should w_i depend on?

Mean squared error

- Let θ be the subpopulation mean of a generic group;
- let $\hat{\theta}$ be an estimator of θ (a function of the data).

The mean squared error (MSE) of $\hat{\theta}$ is

$$MSE[\hat{\theta}|\theta] = E[(\hat{\theta} - \theta)^2|\theta]$$

Bias-variance decomposition: Let $m(\theta) = E[\hat{\theta}|\theta]$.

$$\begin{aligned} MSE[\hat{\theta}|\theta] &= \mathsf{E}[(\hat{\theta}-m+m-\theta)^2|\theta] \\ &= \mathsf{E}[(\hat{\theta}-m)^2|\theta] + 2\mathsf{E}[(\hat{\theta}-m)(m-\theta)|\theta] + \mathsf{E}[(m-\theta)^2|\theta] \\ &= \mathsf{E}[(\hat{\theta}-m)^2|\theta] + (m-\theta)^2 \\ &= \mathsf{Var}[\hat{\theta}|\theta] + \mathsf{Bias}^2[\hat{\theta}|\theta] \end{aligned}$$

Bias-variance tradeoff

In general,

$$MSE[\hat{\theta}|\theta] = Var[\hat{\theta}|\theta] + Bias(\hat{\theta}|\theta)^2$$

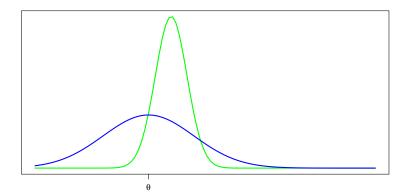
How well an estimator $\hat{\theta}$ does at estimating θ depends on variance and bias.

In general,

- estimators with low bias have have high variance $(\hat{\theta} = \bar{y} \text{ but small } n)$;
- estimators with low variance have high bias $(\hat{\theta} = 5)$.

Minimizing MSE requires balancing bias and variance.

Bias-variance tradeoff



Sample mean bias and variance

Let y_1, \ldots, y_n be sample from a population with mean θ , variance σ^2 .

Sample mean estimator: Let $\hat{\theta} = \bar{y}$

$$\mathsf{E}[\bar{y}|\theta] = \theta$$
$$\mathsf{Bias}[\bar{y}|\theta] = 0$$

$$Var[\bar{y}|\theta] = \sigma^2/n$$

$$MSE[\bar{y}|\theta] = Var[\bar{y}|\theta] = \sigma^2/n$$

Linear shrinkage bias and variance

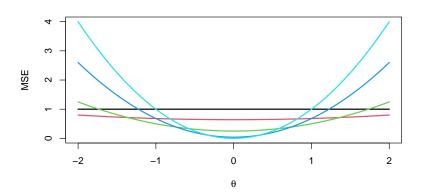
Linear shrinkage estimator: $\hat{\theta} = (1 - w)\bar{y} + wc$ for some $w \in [0, 1]$.

- w is the amount of shrinkage;
- c is the shrinkage point.

$$\begin{split} \mathsf{E}[\hat{\theta}|\theta] &= (1-w)\theta + wc = \theta + w(c-\theta) \\ \mathsf{Bias}[\hat{\theta}|\theta]^2 &= w^2(c-\theta)^2 \geq 0 \\ \\ \mathsf{Var}[\hat{\theta}|\theta] &= (1-w)^2\sigma^2/n \leq \sigma^2/n \\ \\ \mathit{MSE}[\hat{\theta}|\theta] &= (1-w)^2\sigma^2/n + w^2(c-\theta)^2 \end{split}$$

Mean squared error function

$$\sigma^2/n=1$$
 $c=0$



Consider a LSE for
$$\theta = (\theta_1, \dots, \theta_m)$$
 where $\hat{\theta}_j = (1 - w)\bar{y}_j + wc$

$$\begin{aligned} MSE[\hat{\theta}|\theta] &= E[||\hat{\theta} - \theta||^2|\theta] \\ &= \sum_{j} E[(\hat{\theta}_j - \theta_j)^2|\theta] \\ &= \frac{\sigma^2}{n} m(1 - w)^2 + w^2 \sum_{j} (c - \theta_j)^2 \end{aligned}$$

What should the values of w and c be?

Oracle estimator

Using calculus you can show that MSE is optimized by

- $c = \bar{\theta} = \sum_{j} \theta_{j}/m$;
- $w = \frac{1/\tau^2}{n/\sigma^2 + 1/\tau^2}$, where
- $\tau^2 = \sum_j (\theta_j \bar{\theta})^2/m$.

This gives the oracle estimator

$$\hat{ heta}_j = rac{n/\sigma^2}{n/\sigma^2 + 1/ au^2} ar{y}_j + rac{1/ au^2}{n/\sigma^2 + 1/ au^2} ar{ heta}.$$

This can also be written

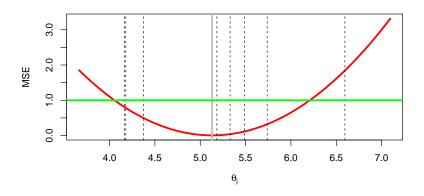
$$\hat{\theta}_j = \frac{\tau^2}{\sigma^2/n + \tau^2} \bar{y}_j + \frac{\sigma^2/n}{\sigma^2/n + \tau^2} \bar{\theta}.$$

- $\bar{\mathbf{y}} = (\bar{y}_1, \dots, \bar{y}_m)$, the vector of sample means;
- $\hat{\theta} = (\hat{\theta}_1, \dots, \hat{\theta}_m)$, the vector of oracle estimates.

$$\begin{split} \mathit{MSE}[\bar{\mathbf{y}}|\boldsymbol{\theta}] &= m \frac{\sigma^2}{n} \\ \mathit{MSE}[\hat{\boldsymbol{\theta}}|\boldsymbol{\theta}] &= m \frac{\sigma^2}{n} \times \left(\frac{\tau^2}{\sigma^2/n + \tau^2}\right) < \mathit{MSE}[\bar{\mathbf{y}}|\boldsymbol{\theta}]. \end{split}$$

The oracle estimator is better than $\bar{\mathbf{y}}$ in terms of composite risk.

$$MSE[\hat{\theta}_j|\boldsymbol{\theta}] = (1-w)^2\sigma^2/n + w^2(\theta_j - \bar{\theta})^2.$$



Summary

Composite risk

- $\bar{\mathbf{y}}$ is an unbiased estimator of $\boldsymbol{\theta}$;
- $\hat{\theta}$ is a biased estimator of θ , but has lower variance than \bar{y} .
- $MSE[\hat{\theta}|\theta] \leq MSE[\bar{\mathbf{y}}|\theta]$.

Group-level risk

- \bar{y}_i is an unbiased estimator of θ_i for each $j=1,\ldots,m$.
- $\hat{\theta}_j$ is a biased estimator of θ_j , but has lower variance than \bar{y}_j .
- $MSE[\hat{\theta}_j|\theta] \geqslant MSE[\bar{y}_j|\theta]$ and you don't know which!

Practical considerations

Typically,

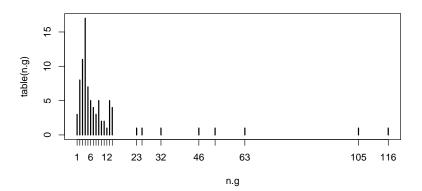
- μ, τ^2, σ^2 are unknown;
- sample sizes may vary across groups.

In practice, people use the following adaptive shrinkage estimator:

$$\hat{\theta}_j = \frac{n_j/\hat{\sigma}^2}{n_j/\hat{\sigma}^2 + 1/\hat{\tau}^2} \bar{y}_j + \frac{1/\hat{\tau}^2}{n_j/\hat{\sigma}^2 + 1/\hat{\tau}^2} \bar{\theta}.$$

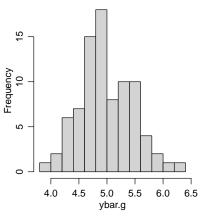
- $\hat{\mu}, \hat{\tau}^2, \hat{\sigma}^2$ are obtained from the data (e.g. ANOVA or lme4).
- If $n_j = n$, can obtain $\hat{\mu}, \hat{\tau}^2, \hat{\sigma}^2$ so that $\hat{\theta}$ is guaranteed better than $\bar{\mathbf{y}}$ (Stein).
- Otherwise, for large m, $\hat{\theta}$ will be approximately optimal linear estimator (under composite risk).

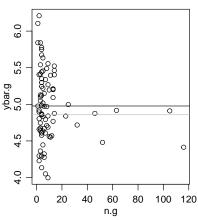
```
n.g<-c(table(g) )
plot(table(n.g))
```



Radon example

```
# county specific radon means
ybar.g<-c(tapply(y,g,"mean"))</pre>
```





MLEs

```
library(lme4)
fit.lme<-lmer(y~1+(1|g),REML=FALSE)
summary(fit.lme)
## Linear mixed model fit by maximum likelihood ['lmerMod']
## Formula: v ~ 1 + (1 | g)
##
##
       AIC
               BIC logLik deviance df.resid
    2164.1 2178.5 -1079.0 2158.1
##
                                       916
##
## Scaled residuals:
##
      Min
              10 Median
                                  Max
                            30
## -3.6165 -0.6141 0.0292 0.6526 3.4932
##
## Random effects:
## Groups Name
                 Variance Std.Dev.
## g
      (Intercept) 0.08804 0.2967
## Residual 0.57154 0.7560
## Number of obs: 919, groups: g, 85
##
## Fixed effects:
##
            Estimate Std. Error t value
## (Intercept) 4.94656 0.04664 106.1
```

Parameter estimates

```
VarCorr(fit.lme)
## Groups
             Name
                         Std.Dev.
##
             (Intercept) 0.29672
## Residual
                         0.75600
t2.mle<-as.numeric(VarCorr(fit.lme)$g)
t2.mle
## [1] 0.08804027
sigma(fit.lme)
## [1] 0.7559996
s2.mle<-sigma(fit.lme)^2
s2.mle
## [1] 0.5715354
fixef(fit.lme)
## (Intercept)
##
      4.946557
mu.mle<-fixef(fit.lme)
```

Adaptive shrinkage estimates

Replace μ, σ^2, τ^2 with estimates:

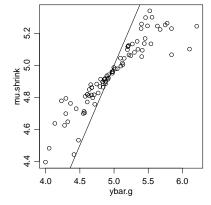
$$\hat{\mu}_j = w_j ar{y}_j + (1-w_j)\hat{\mu} \;, \; ext{where} \; w_j = rac{ extstyle n_j/\hat{\sigma}^2}{ extstyle n_j/\hat{\sigma}^2 + 1/\hat{ au}^2}.$$

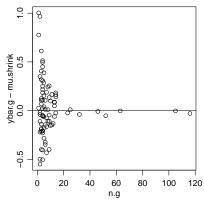
```
w.shrink\leftarrow (n.g/s2.mle) /(n.g/s2.mle + 1/t2.mle)
mu.shrink <-w.shrink *vbar.g + (1-w.shrink) *mu.mle
mu.mle
## (Intercept)
##
     4.946557
cbind(ybar.g, n.g, mu.shrink)[1:8,]
##
              ybar.g n.g mu.shrink
## AITKIN
            4.293832 4 4.697704
## ANOKA
            4.479973 52 4.531757
## BECKER
            4.675008 3 4.860730
## BELTRAMI 4.793035 7 4.866904
## BENTON
          4.869503 4 4.917180
## BIGSTONE 5.128199
                       3 5.003968
## BLUEEARTH 5.522876
                     14 5.340299
## BROWN
            5.244160
                       4 5.060018
```

Shrinkage

```
topten <- order (ybar.g, decreasing=TRUE) [1:10]
cbind(ybar.g, n.g, mu.shrink)[topten,]
##
                 ybar.g n.g mu.shrink
## LACQUIPARLE 6.209980
                              5.244122
## MURRAY
               6.104550
                              5.101126
## WILKIN
               5.841654
                              5.066035
## WATONWAN
               5.841041
                              5.229271
## NICOLLET
               5.777273
                              5.263269
## LINCOLN
               5.748294
                              5.252221
                              5.224006
## KANDIYOHI
               5.674289
## JACKSON
               5.633758
                              5.245555
## FREEBORN
               5.555495
                              5.300322
## NOBLES
                              5.134149
               5.540083
```

Shrinkage





Shrinkage estimates from 1me4

```
mu.shrink[1:10]
##
      AITKIN
                 ANOKA
                          BECKER.
                                   BELTRAMI
                                               BENTON
                                                       BIGSTONE BLUEEARTH
                                                                               BROWN
    4.697704
              4.531757
                        4.860730
                                   4.866904
                                             4.917180
                                                       5.003968 5.340299
                                                                            5.060018
##
     CARLTON
                CARVER
   4.712463
              4.958725
a.shrink<-ranef(fit.lme)[[1]][.1]
mu.mle+a.shrink[1:10]
    [1] 4.697704 4.531757 4.860730 4.866904 4.917180 5.003968 5.340299 5.060018
    [9] 4.712463 4.958725
```

In lme4, ranef(fit.lme)[[k]][,1] refers to the

- 1th random effect for the
- kth grouping variable.

$$y_{i,j} = \mu + a_j + \epsilon_{i,j}$$
 $\{\epsilon_{1,1}, \dots, \epsilon_{n,1}\}, \dots, \{\epsilon_{1,m}, \dots, \epsilon_{n,m}\} \sim \text{i.i.d. normal}(0, \sigma^2)$ $a_1, \dots, a_m \sim \text{i.i.d. normal}(0, \tau^2)$

Equivalently,

$$y_{i,j} = heta_j + \epsilon_{i,j}$$
 $\{\epsilon_{1,1}, \dots, \epsilon_{n,1}\}, \dots, \{\epsilon_{1,m}, \dots, \epsilon_{n,m}\} \sim \text{i.i.d. normal}(0, \sigma^2)$ $\theta_1, \dots, \theta_m \sim \text{i.i.d. normal}(\mu, \tau^2)$

In this model, we think of

- the groups as being randomly selected from a larger set of possible groups,
- so the means are randomly selected from a set of possible means.
- This interpretation is not appropriate for the radon data!

Unbiased predictors

Suppose you will sample a random group with subgroup mean θ , so

$$heta \sim N(\mu, \tau^2)$$
 $\bar{y}|\theta \sim N(\theta, \sigma^2/n).$

How should you plan on estimating θ ? Consider estimators $\tilde{\theta}$ that are unbiased "on average:"

$$\mathsf{E}[\tilde{\theta} - \theta] = \int_{\theta} \left(\int_{y} (\hat{\theta} - \theta) p(y|\theta) \, d\theta \right) \, p(\theta|\mu, \tau^{2}) \, d\theta$$

- Such estimators are sometimes called "unbiased predictors";
- They might not be unbiased for any particular value of θ !

Unbiased predictors

$$\begin{split} \bar{y} &= \sum y_i/n \\ \hat{\theta} &= \frac{\tau^2}{\sigma^2/n + \tau^2} \bar{y} + \frac{\sigma^2/n}{\sigma^2/n + \tau^2} \mu. \end{split}$$

Exercises:

- 1. Show that \bar{y} is an "unbiased predictor";
- 2. Show that $\hat{\theta}$ is an "unbiased predictor".
- 3. Identify some other "unbiased predictors".

Best unbiased prediction

Result 1: (Best unbiased predictor). Let $\tilde{\theta}$ be any unbiased predictor, meaning $\mathrm{E}[\tilde{\theta}-\theta]=0$ where the expectation is averaging over *both y* and θ . Then

$$\mathsf{E}[(\hat{\theta} - \theta)^2] \le \mathsf{E}[(\tilde{\theta} - \theta)^2]$$

where the expectation is over both y and θ .

Best linear unbiased predictor

A similar result holds even if the data are not normal. Suppose

- $E[\bar{y}|\theta] = \theta$, $Var[\bar{y}|\theta] = \sigma^2/n$.
- $E[\theta] = \mu$, $Var[\theta] = \tau^2$.

Result 2: (Best linear unbiased predictor). Let $\tilde{\theta}$ be any linear unbiased predictor, meaning

- $\tilde{\theta} = a\bar{y} + b$ for some fixed a and b;
- $E[\tilde{\theta} \theta] = 0$ where the expectation is averaging over both y and θ .

Then

$$\mathsf{E}[(\hat{\theta} - \theta)^2] \le \mathsf{E}[(\tilde{\theta} - \theta)^2]$$

where the expectation is over both v and θ .

As before.

- μ, τ^2, σ^2 are unknown;
- sample sizes may vary across groups.

In practice, people use the following Empirical BLUP:

$$\hat{ heta}_j = rac{n_j/\hat{\sigma}^2}{n_j/\hat{\sigma}^2 + 1/\hat{ au}^2} ar{y}_j + rac{1/\hat{ au}^2}{n_j/\hat{\sigma}^2 + 1/\hat{ au}^2} ar{ heta},$$

where $\hat{\mu}, \hat{\tau}^2, \hat{\sigma}^2$ are estimated from the data (ANOVA or lme4)

This is the same estimator as the adaptive shrinkage estimator.

- variabiliy in "random" θ_i 's \approx heterogeneity in "fixed" θ_i 's.
- integration over θ_j's to get MSE ≈ summing over θ_j's to get composite MSE.

BLUPs

The $\hat{\theta}_i$'s are sometimes called the best unbiased linear predictors (BLUPs) .

This is confusing, as we have discussed how these estimators are biased:

$$\begin{aligned} \mathsf{E}[\hat{\theta}_j|\theta_j] &= \mathsf{E}[w\bar{y}_j + (1-w)\mu|\theta_j] \\ &= w\theta_j + (1-w)\mu \neq \theta_j \end{aligned}$$

 $\hat{\theta}_i$ is conditionally biased.

The "U" in BLUP refers to bias only in an unconditional sense:

$$E[\hat{\theta}_j] = E[E[\hat{\theta}_j | \theta_j]]$$

$$= E[w\theta_j + (1 - w)\mu]$$

$$= w\mu + (1 - w)\mu = \mu.$$

Since $E[\hat{\theta}_i] = E[\theta_i] = \mu$ unconditionally, people might say $\hat{\theta}_i$ is "unbiased."

Understanding conditional and unconditional expectation

Let
$$\mu = (\theta_A + \cdots \theta_J)/10$$
.

Study design:

- sample m schools at random from the population of schools.
- sample *n* students at random from each of the *m* schools.

What is the expectation of θ_1 , \bar{y}_1 , $\hat{\theta}_1$?

Expectation of θ_1 : Since each school A through J has equal probability of being selected as unit 1:

$$E[\theta_1] = \theta_A \times Pr(\text{unit } 1 = A) + \dots + \theta_J \times Pr(\text{unit } 1 = J)$$
$$= \theta_A \frac{1}{10} + \dots + \theta_J \frac{1}{10} = \mu$$

Understanding conditional expectation

$$\mathsf{E}[\bar{y}_1 - \theta_1 | \mathsf{unit} \ \mathbf{1} = \mathsf{D} \] = \mathsf{E}[\bar{y}_D - \theta_D] = \theta_D - \theta_D = 0$$

$$E[\hat{\theta}_1 - \theta_1 | \text{unit } 1 = D] = E[w\bar{y}_D + (1 - w)\mu - \theta_D]$$

= $w\theta_D + (1 - w)\mu - \theta_D = (1 - w)(\mu - \theta_D) \neq 0$

Conditionally on unit 1=D,

- $\bar{y}_1 = \bar{y}_D$ is unbiased for θ_D ,
- $\hat{\theta}_1 = \hat{\theta}_D$ is biased for θ_D .

In English, if your first sampled school is school D, then

- $\bar{\mathbf{v}}_1 = \bar{\mathbf{v}}_D$ and $\bar{\mathbf{v}}_D$ is unbiased for θ_D
- $\hat{\theta}_1 = \hat{\theta}_D$ and $\hat{\theta}_D$ is biased for θ_D .

Understanding unconditional expectation

Before you sample the schools, unit 1 is equally likely to be school A, B, ..., J.

$$\begin{split} \mathsf{E}[\hat{\theta}_1 - \theta_1] &= \mathsf{E}[\hat{\theta}_A - \theta_A] \, \mathsf{Pr}(\mathsf{unit} \ 1 \! = \! \mathsf{A}) + \dots + \mathsf{E}[\hat{\theta}_J - \theta_J] \, \mathsf{Pr}(\mathsf{unit} \ 1 \! = \! \mathsf{J}) \\ &= (1 - w)(\mu - \theta_A) \times \frac{1}{10} + \dots + (1 - w)(\mu - \theta_J) \times \frac{1}{10} \\ &= (1 - w)\mu - (1 - w)(\theta_A + \dots + \theta_J) \frac{1}{10} \\ &= (1 - w)\mu - (1 - w)\mu = 0. \end{split}$$

This unconditional expectation, and the "U" in BLUP, refers to averaging across the possibilities for the samples:

- $\hat{\theta}_i$ will be a biased estimator of the mean of whatever unit is picked jth.
- on average across studies, $\hat{\theta}_1, \dots, \hat{\theta}_m$ will be unbiased.

In many applications interest is more in the conditional expectations.

From this perspective, the shrinkage estimators $\hat{ heta}_1,\dots,\hat{ heta}_m$

- are biased;
- have conditional MSE given by

$$w^2\sigma^2/n_j + (1-w)^2(\theta_j - \mu)^2$$
,

• which is usually lower than the conditional MSE of \bar{y}_j .

Review of Bayesian inference

- Prior density: $p(\gamma)$
- Sampling density: $p(y_1, \ldots, y_n | \gamma)$

The prior density describes where you think γ is, before having seen the data.

The sampling density describes where you think the data will be, for each possible value of γ .

Bayes rule:

$$p(\gamma|y_1,\ldots,y_n) = \frac{p(\gamma)p(y_1,\ldots,y_n|\gamma)}{\int p(\gamma')p(y_1,\ldots,y_n|\gamma')\,d\gamma'}$$
$$\propto p(\gamma)p(y_1,\ldots,y_n|\gamma)$$

The posterior density $p(\gamma|y_1,...,y_n)$ describes where you think the γ is, after having seen the data.

Bayesian inference for a normal subpopulation

- Prior density: $\theta \sim N(\mu, \tau^2)$
- Sampling density: $y_1, \ldots, y_n | \theta \sim N(\theta, \sigma^2)$.

Bayes rule: $\theta|y_1,\ldots,y_n$ is normal, with

$$\mathsf{E}[\theta|y_1,\ldots,y_n] = \frac{\tau^2}{\sigma^2/n + \tau^2} \bar{y} + \frac{\sigma^2/n}{\sigma^2/n + \tau^2} \mu$$

$$\mathsf{Var}[\theta|y_1,\ldots,y_n] = 1/(1/\sigma^2/n + 1/\tau^2)$$

Bayes estimator: Let $\hat{\theta} = E[\theta|y_1, \dots, y_n]$. Then

$$\mathsf{E}[(\hat{\theta}-\theta)^2|y_1,\ldots,y_n] \leq \mathsf{E}[(\tilde{\theta}-\theta)^2|y_1,\ldots,y_n]$$

for any estimator $\tilde{\theta}$.

Bayes interpretation

A Bayesian interpretation of $\hat{\theta}$:

- θ_j is some fixed quantity for group j;
- $\theta_j \sim N(\mu, \tau^2)$ describes prior info about θ_j ;
- $\theta_i \sim N(\hat{\theta}_i, 1/(n_i/\sigma^2 + 1/\tau^2))$ describes posterior info about θ_i ;
- $\hat{ heta}_j$ is "where you think $heta_j$ is".

Practical considerations:

- μ, τ^2, σ^2 ;
- estimate these parameters with a "fully Bayesian procedures", or
- use plug-in estimates (Empirical Bayes), obtained from data (ANOVA, lme4).

Again, the estimator is the same but the justification can be different.