InvocMap Overview

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Overview

Implementing correct method invocation is an important task for software developers. However, this is challenging work, since the structure of method invocation can be complicated. In this paper, we propose InvocMap, a code completion tool allows developers to obtain an implementation of multiple method invocations from a list of method names inside code context. InvocMap is able to predict the nested method invocations which their names didn't appear in the list of input method names given by developers. To achieve this, we analyze the Method Invocations by four levels of abstraction. We build a Machine Translation engine to learn the mapping from the first level to the third level of abstraction of multiple method invocations, which only requires developers to manually add local variables from generated expression to get the final code. We evaluate our proposed approach on six popular libraries: JDK, Android, GWT, Joda-Time, Hibernate, and Xstream. With the training corpus of 2.86 million method invocations extracted from 1000 Java Github projects and the testing corpus extracted from 120 online forums code snippets, InvocMap achieves the accuracy rate up to 84 in F1- score depending on how much information of context provided along with method names, which outperforms the state-of-the-art Neural Machine Translation approach by 40% and shows its potential for auto code completion.

Input and Output

```
Input
     public void setOffsets(int
        newHorizontalOffset, int
        newVerticalOffset) {
        . . .
            if (mView != null) {
                invalidateRectf.offset(-xoffset,
                     -yoffset);
6
                set:
                                                            6
27
                 . . .
                     InvocMap
```

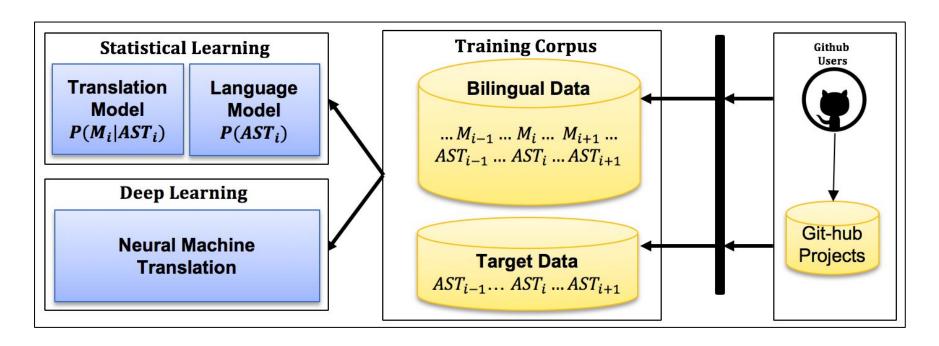
Output

```
LIBURE OF LAURIPIC III 1 .
public void setOffsets (int
   newHorizontalOffset, int
    newVerticalOffset) {
   . . .
       if (mView != null) {
            invalidateRectf.offset(-xoffset.
                -yoffset);
           invalidateRect.set((int) Math.
                floor (invalidate Rectf. left)
                ,(int) Math. floor(
                invalidateRectf.top),(int)
                Math. ceil (invalidateRectf.
                right),(int) Math.ceil(
                invalidateRectf.bottom));
            . . .
```

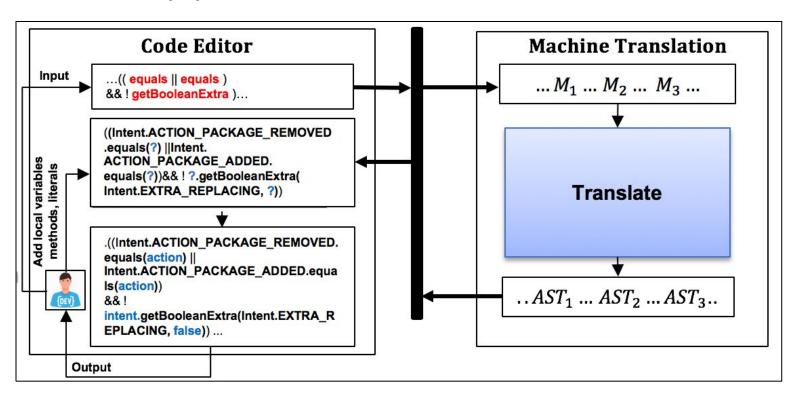
Input and Output (2)

```
public void dumpControllerStateLocked(
        PrintWriter pw, int filterUid) {
             final long nowElapsed =
                  SystemClock . elapsedRealtime();
             TimeUtils.formatDuration(
                  mNextDelayExpiredElapsedMillis,
                   nowElapsed, pw);
                                                                E-Total-000007754
                  Input: println
                                                                #.println()
6
                                                                iava.io.PrintWriter
                                                                iava.io.PrintWriter
8
                                                                java.io.PrintWriter#println#()
9
```

InvocMap



InvocMap (2)



Evaluation: Accuracy of InvocMap by SMT

	Extrinsic Evaluation with Configuration 3									
Library	Correct	Incorrect	OOSource	OOTarget	OOVoc	Total	Precision	Recall	F1-Score	
GWT	89	4	0	9	9	102	95.70%	90.82%	93.19%	
Joda-Time	55	3	2	15	17	75	94.83%	76.39%	84.62%	
JDK	174	32	0	44	44	250	84.47%	79.82%	82.08%	
Android	82	11	0	13	13	106	88.17%	86.32%	87.23%	
Hibernate	146	40	1	39	40	226	78.49%	78.49%	78.49%	
Xstream	50	0	0	14	14	64	100.00%	78.13%	87.72%	
Total	596	90	3	134	137	823	86.88%	81.31%	84.00%	

Evaluation (2): Comparison between SMT and NMT

Configuration	Statistic	al Machine Trar	slation	Neural Machine Translation			
Intrinsic	Precision	Recall	F1-Score	Precision	Recall	F1-Score	
Configuration 1	70.43%	75.89%	73.06%	54.09%	46.18%	49.82%	
Configuration 2	84.04%	78.98%	81.43%	46.77%	67.97%	55.41%	
Configuration 3	89.33%	79.98%	84.40%	49.27%	69.09%	57.52%	
Extrinsic	Precision	Recall	F1-Score	Precision	Recall	F1-Score	
Configuration 1	62.54%	75.80%	68.53%	44.62%	49.71%	47.03%	
Configuration 2	86.01%	81.16%	83.51%	33.38%	62.57%	43.54%	
Configuration 3	86.88%	81.31%	84.00%	34.84%	63.56%	45.01%	

Thank you

Appendix: Resolve multiple method names

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Prior work: AnyCode [1] Handle sequentially public void dumpControllerStateLocked(PrintWriter pw, int filterUid) { final long nowElapsed = Output 1: Input 1: elapse real time SystemClock.elapsedRealTime() TimeUtils.formatDuration(mNextDelayExpiredElapsedMillis, nowElapsed, pw); Output 2: Input 2: println pw.println("message")

Appendix: Resolve multiple method names

InvocMap Handle concurrently public void dumpControllerStateLocked(PrintWriter pw, int filterUid) { final long nowElapsed = Output 1: Input 1: elapse real time SystemClock.elapsedRealTime() TimeUtils.formatDuration(mNextDelayExpiredElapsedMillis, nowElapsed, pw); Output 2: Input 2: println pw.println("message") 6

References

1. AnyCode.

https://lara.epfl.ch/~kuncak/papers/GveroKuncak15SynthesizingJavaExpressionsFreeFormQueries.pdf