

INCLUDING IN SITU VISUALIZATION AND ANALYSIS IN PDI

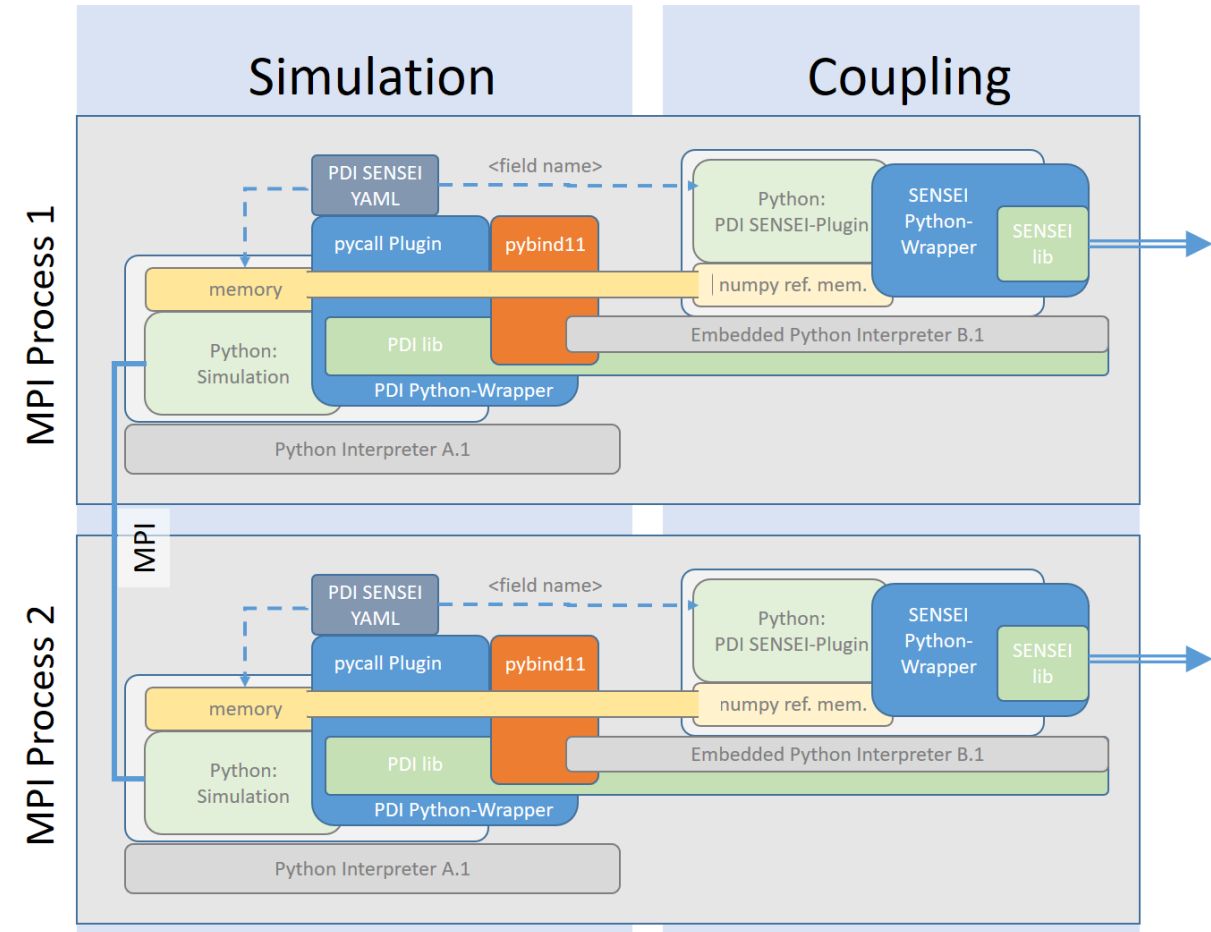
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- CoEC, grant agreement No 952181

OUTLINE

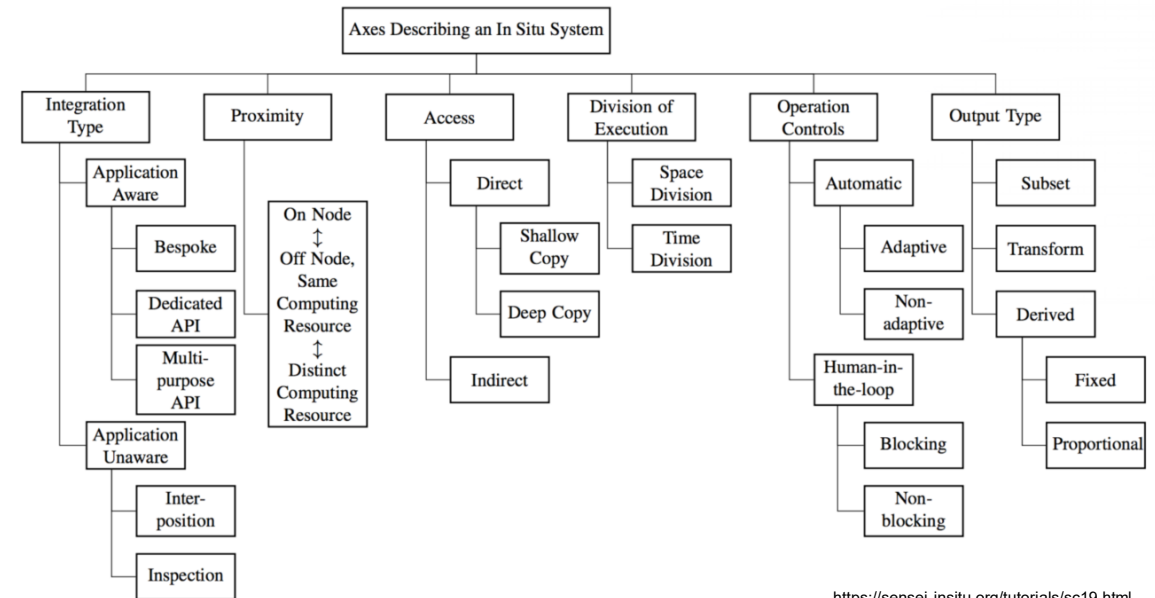
- Motivation
- PDI
- Design decisions
 - Sensei
 - Adios2
 - ParaView Catalyst
- Usage
 - PDI integration
 - YAML file
 - Catalyst
- Example Bolund



MOTIVATION

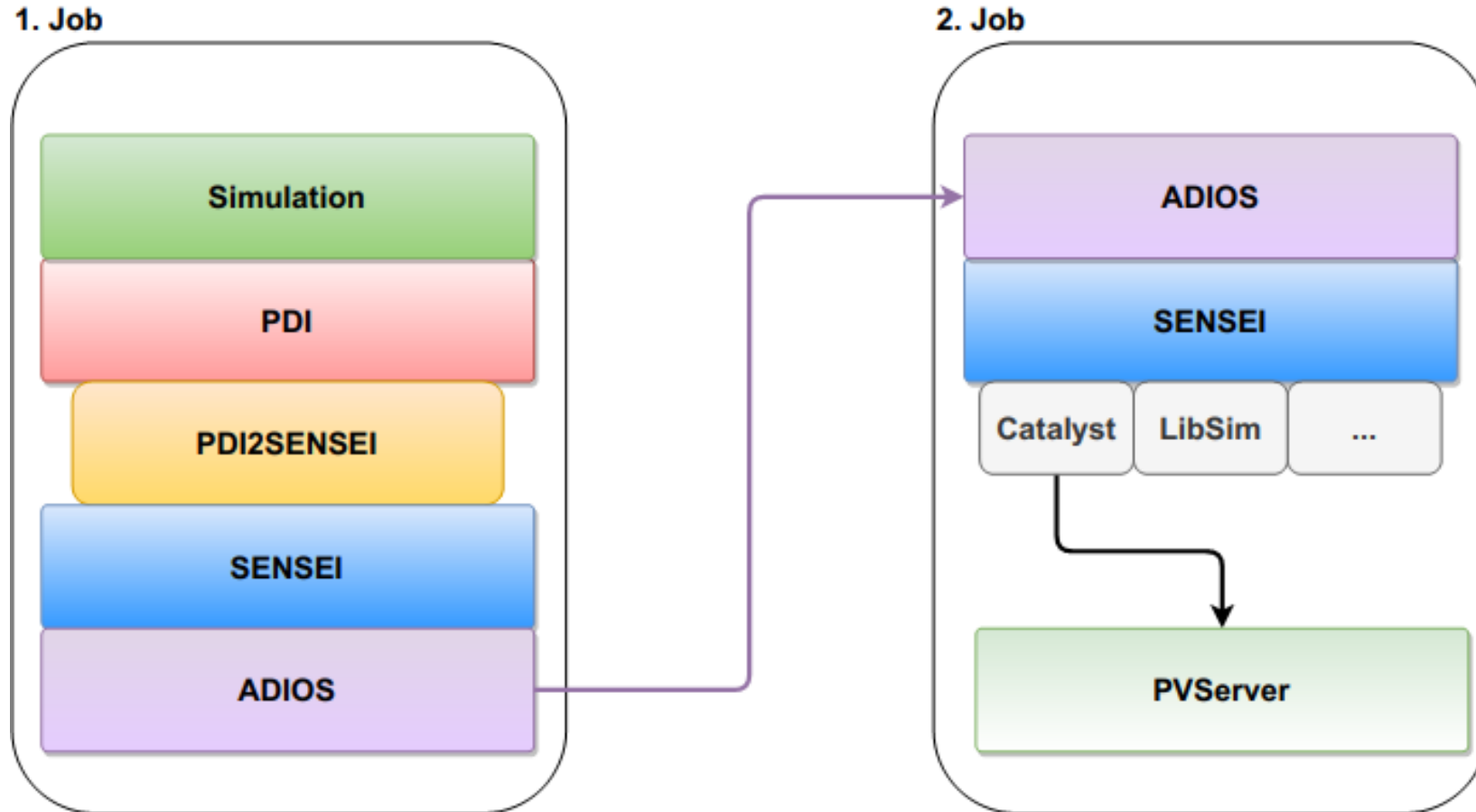
What do we need?

- Minimal dependencies for simulation code
- Error resistant visualization
- Minimal influence on simulation
- Easy to use



<https://sensei-insitu.org/tutorials/sc19.html>

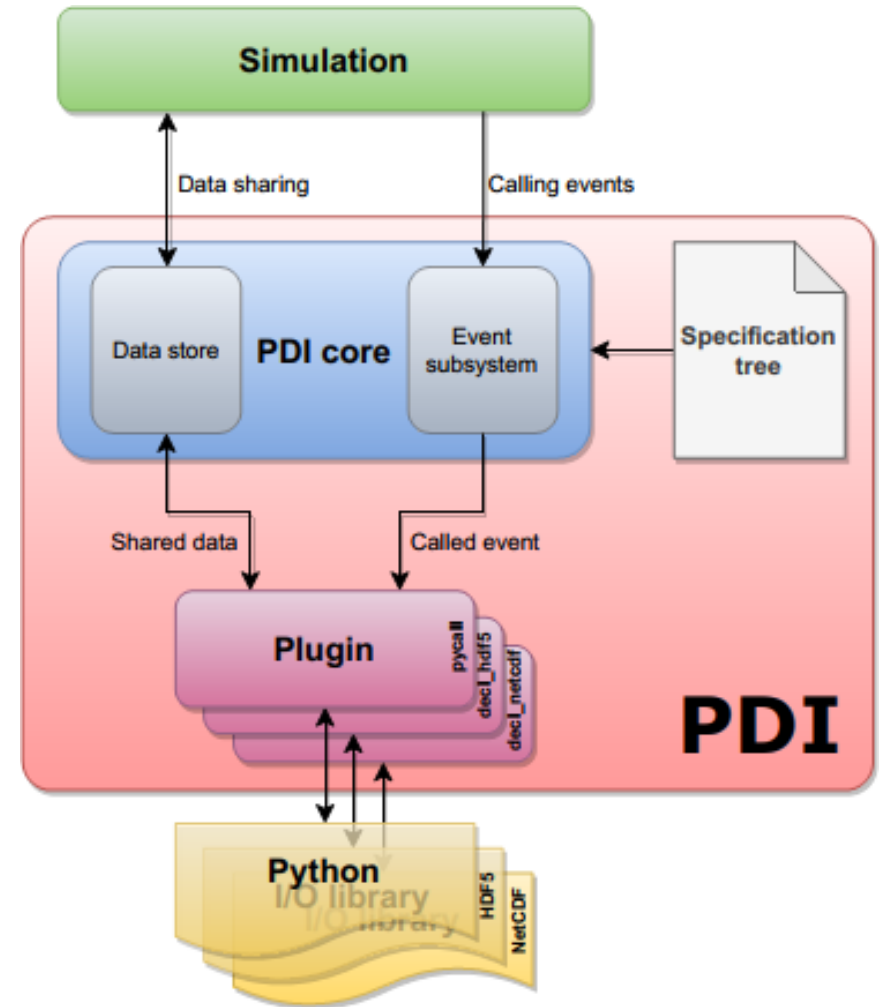
DESIGN



PDI DATA INTERFACE

- Decouple I/O from HPC codes
- 3 parts:
 - PDI core
 - Specification tree
 - Plugins

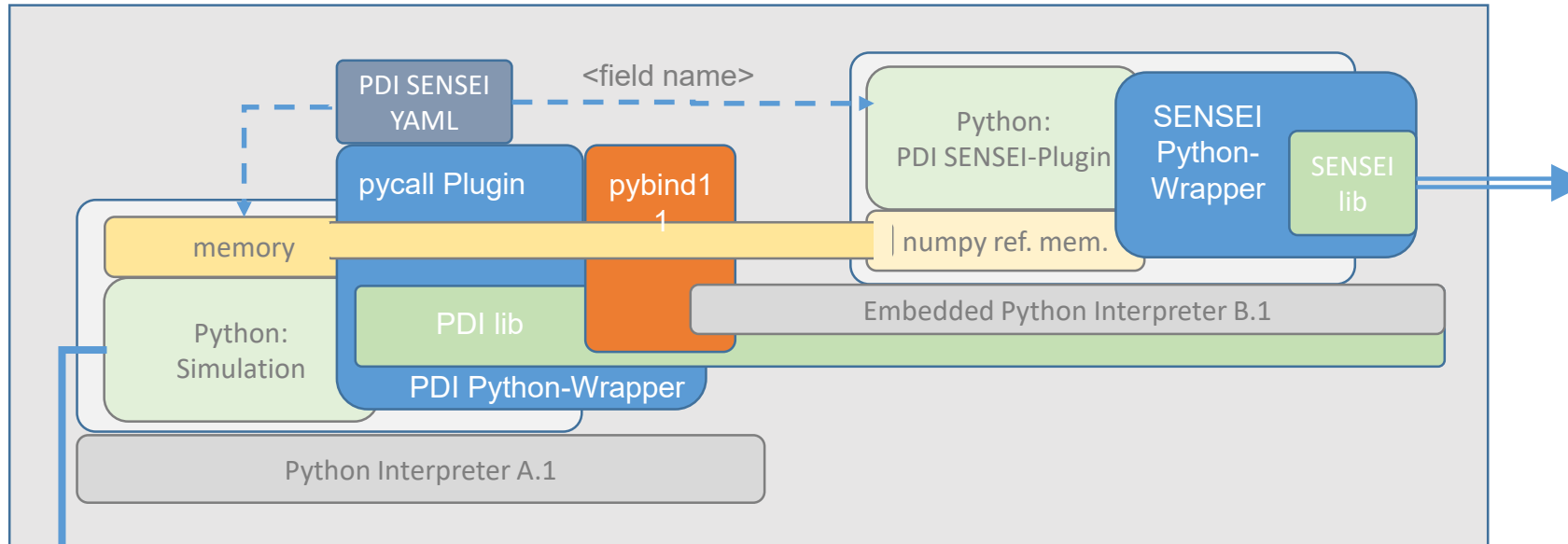
<https://pdi.julien-bigot.fr/1.2/>
<https://gitlab.maisondelasimulation.fr/pdidev/pdi>
<https://hal.archives-ouvertes.fr/hal-01587075>



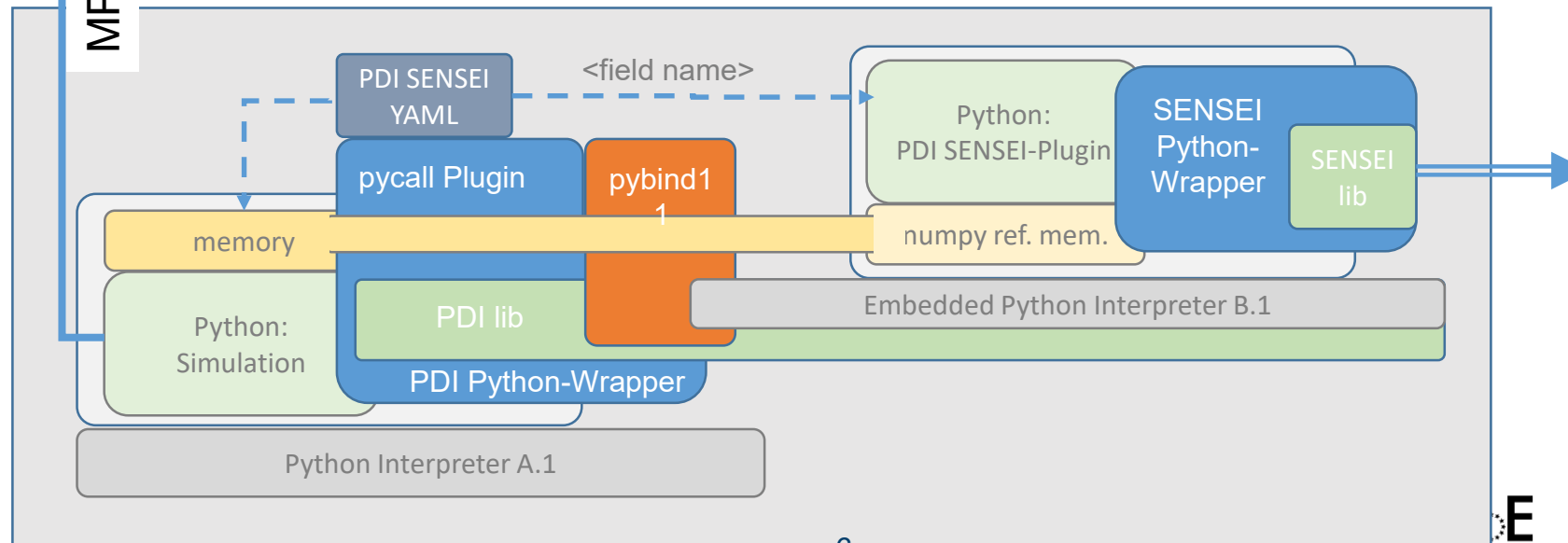
Simulation

Coupling

MPI Process 1



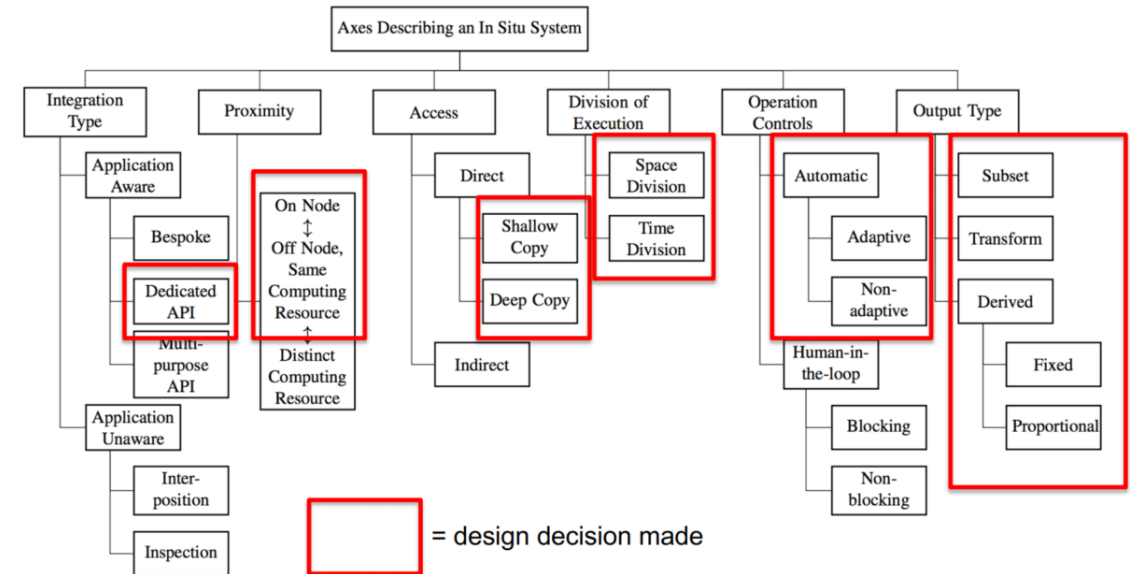
MPI Process 2



DESIGN DECISIONS

SENSEI

- Flexible connection to different frameworks
 - Adios, Catalyst, LibSim
 - Allows in-transit
- But:
 - No build in data transport

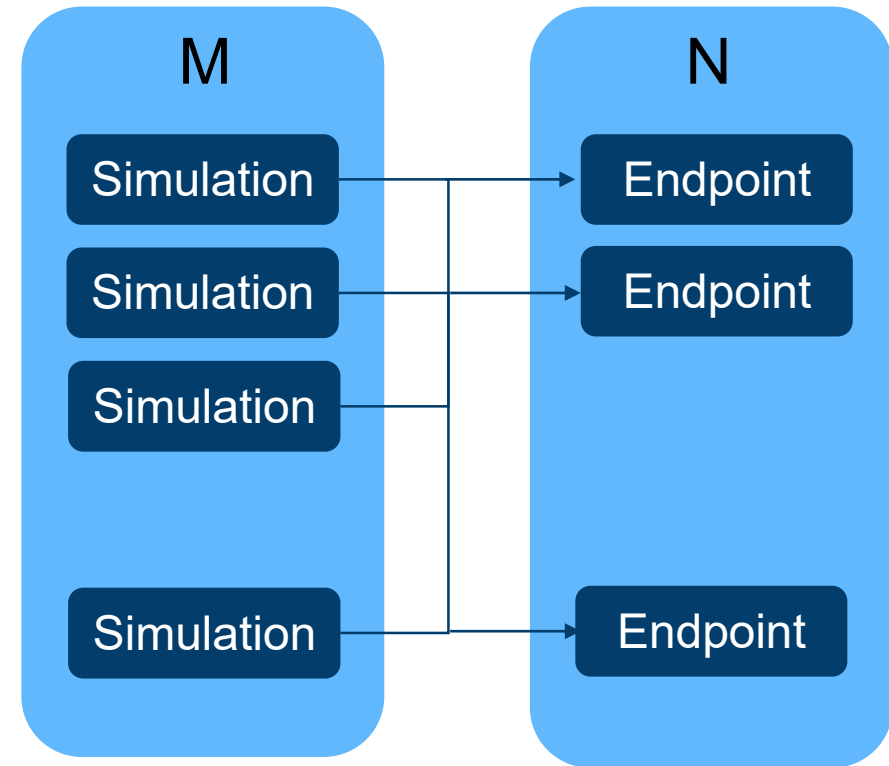


<https://sensei-insitu.org/tutorials/sc19.html>

DESIGN DECISIONS

ADIOS2

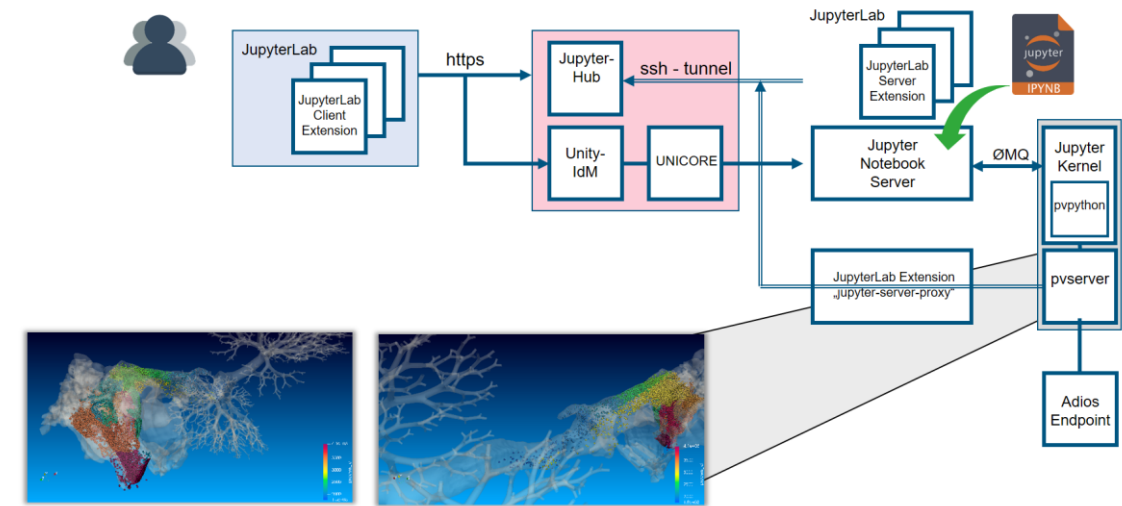
- Using Adios2 SST for data transport
 - Simple to use
 - Scales well
 - Allows M2N communication
 - Uses RDMA
- But:
 - Creates configuration file
 - Needs shared file system



DESIGN DECISIONS

ParaView Catalyst

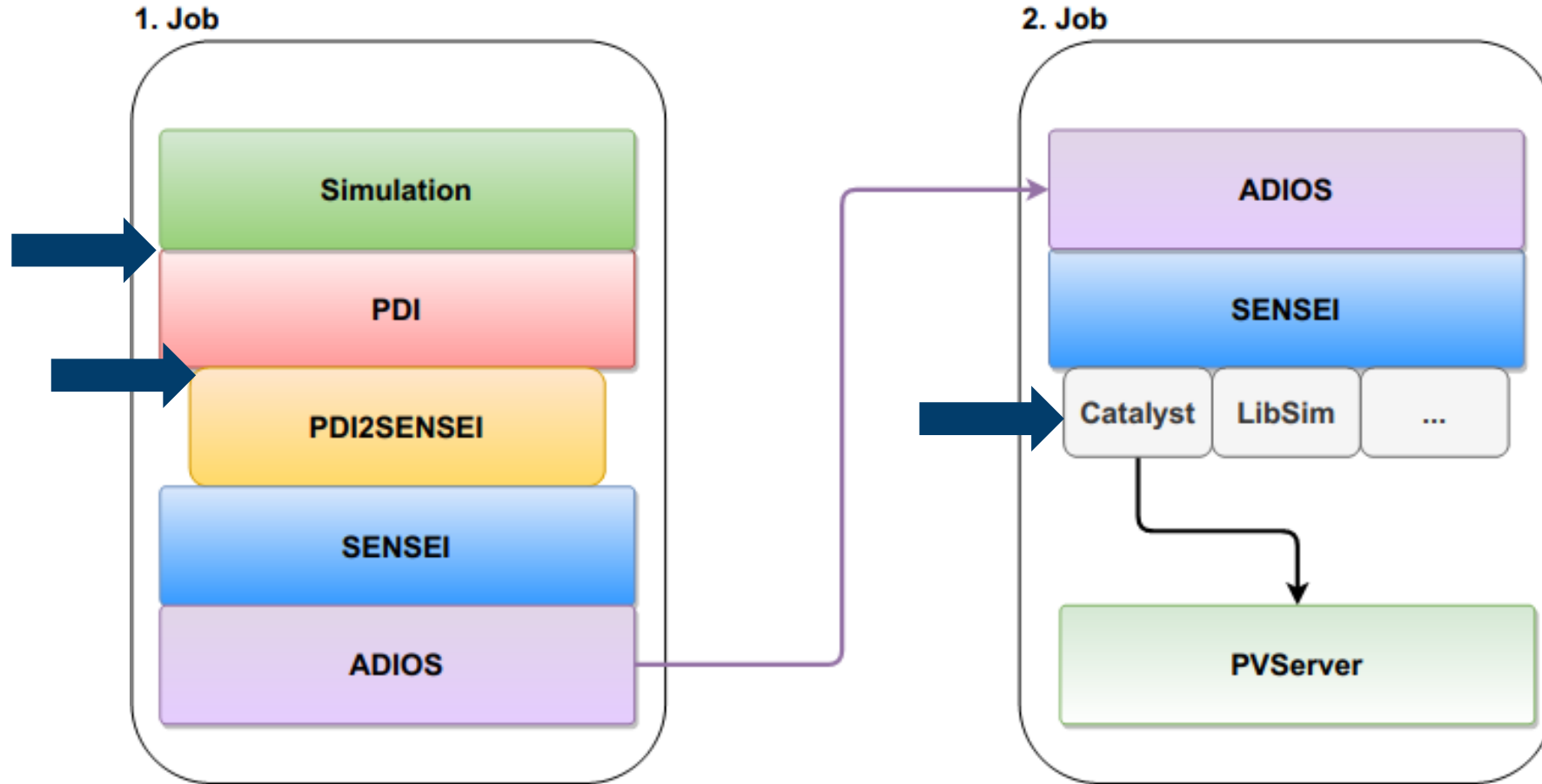
- Used for visualization
- Can be run in parallel
- Predefined visualization scripts
- Interaktive live visualization
- Is integrated in Jupyter-JSC



<https://www.paraview.org/in-situ/>

<https://cfp.jupytercon.com/2020/schedule/presentation/123/jupyter-for-interactive-in-situ-visualization-with-paraviewcatalyst/>

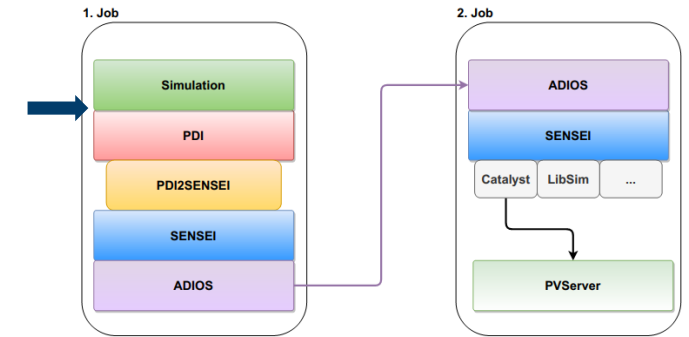
USAGE



USAGE

PDI integration

- PDI Events
 - Initialization
 - In-situ update
 - Finalization
- PDI Data:
 - Data share/expose



```
pdi.event('init_insitu')
```

```
...|
```

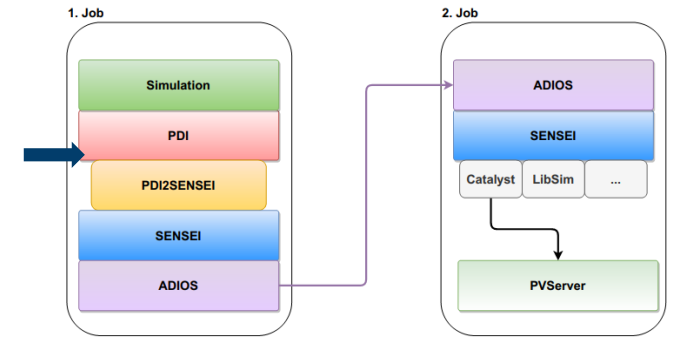
```
pdi.multi_expose('update_insitu', [  
    ('iter', ii, pdi.INOUT),  
    ('main_field', field, pdi.INOUT),  
    ('time', time, pdi.INOUT)  
)
```

USAGE

YAML file

- Connect the Events and data shares

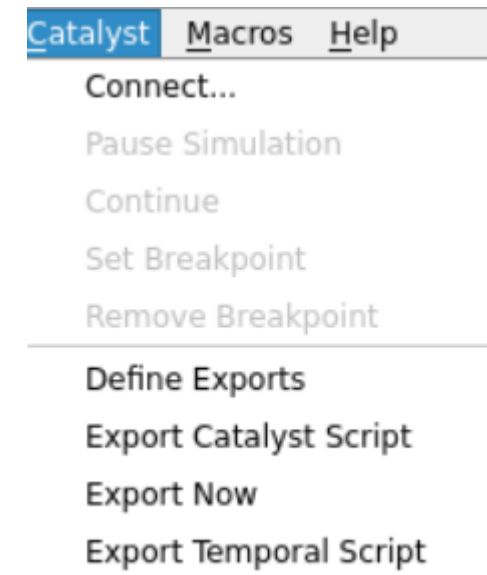
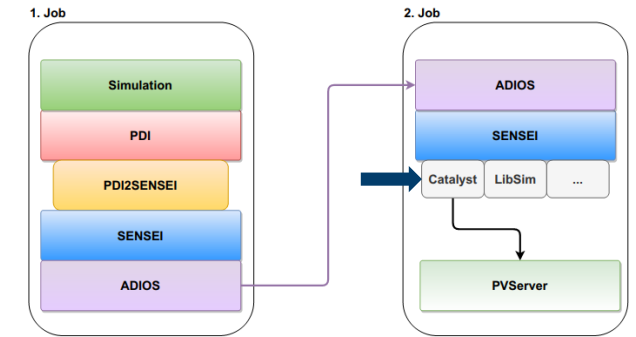
```
18 plugins:
19   pycall:
20     on_event:
21       init_insitu:
22         with: { size: '$size', offset: '$offset' }
23         exec: |
24           import pdi2sensei
25           from pdi2sensei.utility import getVtkImageData
26
27           bridge = pdi2sensei.Bridge(adiosFile = 'adios.cfg')
28           bridge.addMesh(getVtkImageData(size, offset))
29
30       update_insitu:
31         with: { newiter: '$iter', field: '$main_field', time: '$time' }
32         exec: |
33           bridge.addDataForTimeStep(EveryXTimesteps = 10, data = field, name = "main_field")
34           bridge.update(time)
35       finalization:
36         exec: |
37           bridge.finalize()
38
```



USAGE

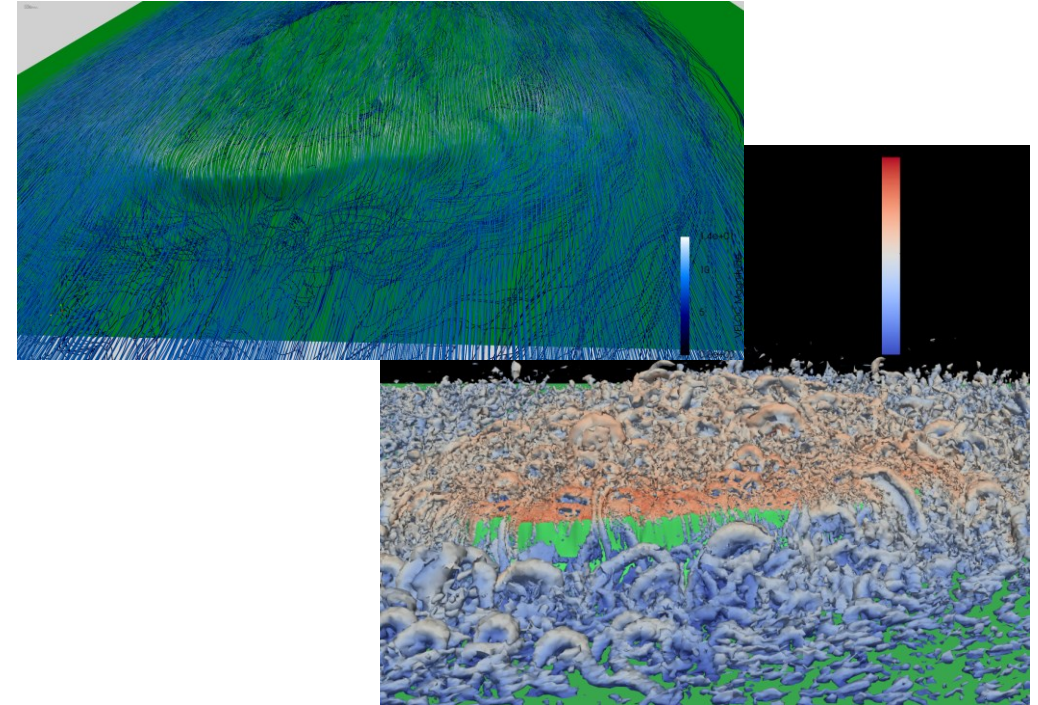
Catalyst

- Connect with a small simulation or load a sample file
- Setup your visualisation pipeline
- Export catalyst Script



EXAMPLE CASE: BOLUND

- ALYA
 - parallel multi-physics/multi-scale simulation code
 - Developed at BSC
- Example case Bolund
 - Incompressible flow
 - Large Eddy Simulation



SUMMARY

- Minimal dependencies on simulation site
 - Only pdi needed
 - **All other dependencies are indirekt**
- In-transit visualization
 - 2nd (3rd) visualization job
 - **Independent visualization**
- Easy configuration
 - YAML file
 - **Simple functions to setup your in-transit workflow**

QUESTIONS?

Thank you for your attention

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