

Machine Learning for Bioinformatics & Systems Biology

3. Feature selection and extraction

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Some material courtesy of Robert Duin and David Tax

- Feature extraction
- Feature selection
- Regularized classifiers



- Feature extraction
 - Linear:
 - PCA
 - Fisher
 - Non-linear
 - MDS (Multi-dimensional scaling)



Feature selection

- Criteria
- search algorithms
 - Forward selection
 - Backward selection
 - Branch & Bound search



Regularized classifiers

- PAM (Prediction Analysis of Micro-arrays = shrunken centroids)
- Ridge regression
- LASSO (Least Absolute Shrinkage and Selection Operator)



Dimensionality reduction

Aim of Feature Extraction and Selection: reduce dimensionality



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Why is reducing dimensionality useful?



Dimensionality reduction

Aim of Feature Extraction and Selection: reduce dimensionality

Why is reducing dimensionality useful?

- **1. Fewer parameters**: faster, easier to estimate possibly better performance
- 2. **Explain** which measurements (features) are useful and which are not (reduce redundancy)
- 3. Visualisation



- Curse of dimensionality (# features / # samples):
 - for fixed sample size
 - and increasing number of features (number of parameters)
 - performance decreases
 - (There are fewer samples per parameter, i.e. worse estimates)



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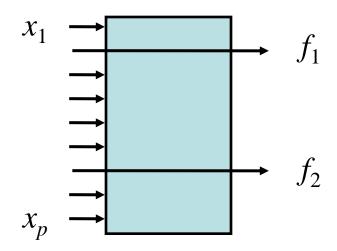
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- But genomic data (e.g. RNAseq) is extreme:
 - 100-1000 times fewer samples than parameters!
- For example: nearest mean classifier on Golub data
 - p = 3051, k = 2 → number of parameters = 6102
 - Number of samples, n = 38



^{*} measurements

Feature selection vs. extraction

Feature selection:
 select d out of p features

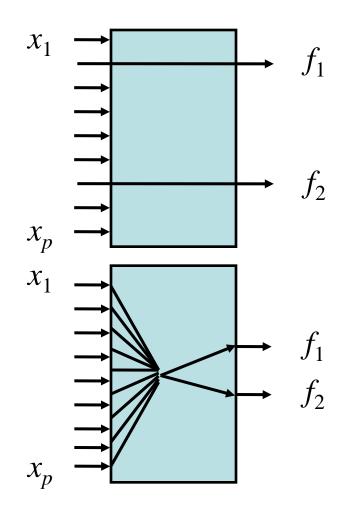




Feature selection vs. extraction

Feature selection:
 select d out of p features

Feature extraction:
 map p features
 to d features
 (e.g. PCA)





Feature selection v extraction (2)

| | Advantage | Disadvantage |
|-----------|---------------------|-------------------|
| Selection | cut in features | expensive |
| | easy interpretation | often approximate |



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| | Advantage | Disadvantage |
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| Selection | cut in features | expensive |
| | easy interpretation | often approximate |
| Extraction | cheap can be nonlinear not axis aligned | need all features criterion sub-optimal |



Feature extraction (2)

- Linear, unsupervised (= no class labels):
 - Principal Component Analysis (PCA)
- Linear, supervised (= use class labels):
 - Linear Discriminant Analysis (LDA)



Principal component analysis (PCA, 1901):
 Goal: find directions in data...

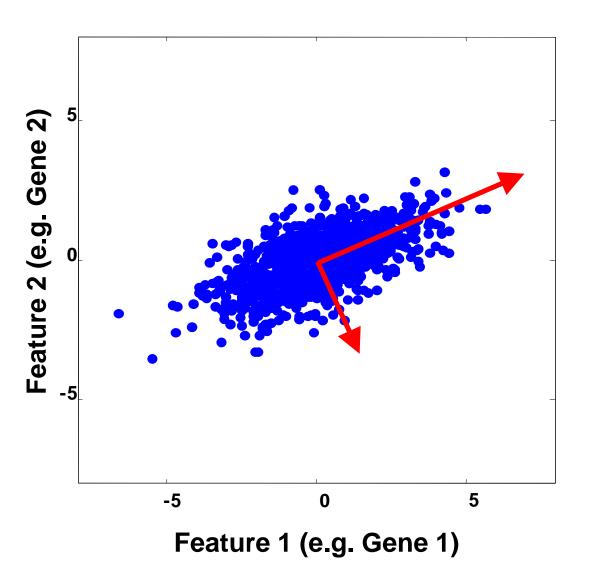


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 Goal: find directions in data...
 - which retain as much variation as possible
 - which minimise squared reconstruction error





Steps:

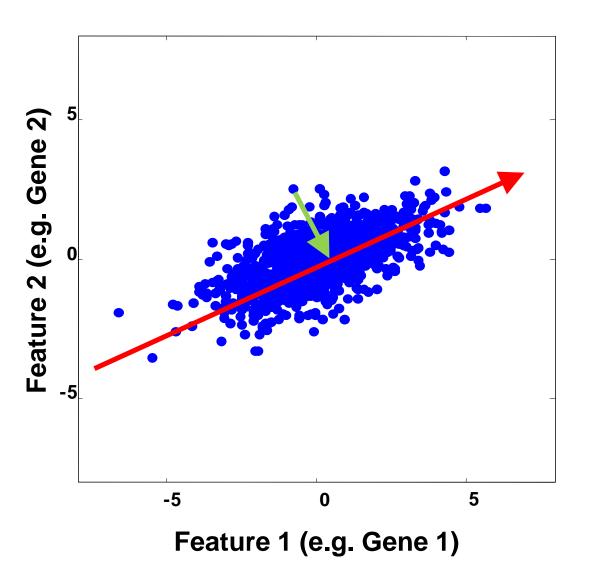
- 1. Center data
- 2. Compute covariance, C
- 3. Perform PCA on C

Output:

- 1. Eigenvectors: **e**₁, **e**₂
- 2. Eigenvalues: λ_1 , λ_2

Reducing dimensions: Choosing 'd'





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- 1. Choosing d = 1
- 2. Project data on **e**₁



Choosing reduced dimensionality

To choose d inspect the retained variance,

$$\sum_{i=1}^{d} \lambda_i$$

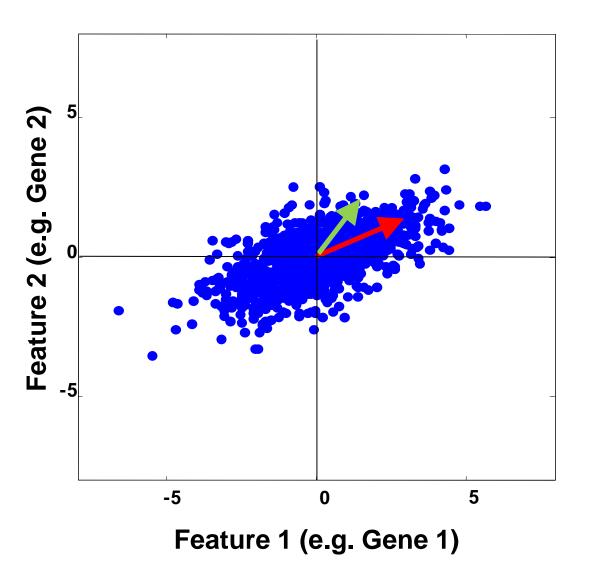
or the ratio of retained variance,

$$\sum_{i=1}^{d} \lambda_i / \sum_{j=1}^{p} \lambda_j$$

- Rule of thumb: Select d for which 80-90% variance is retained
- Reduced dimensionality data set

•
$$[\mathbf{x}_1^{\mathsf{T}}; \mathbf{x}_2^{\mathsf{T}}; \dots; \mathbf{x}_2^{\mathsf{T}}][\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_d]$$





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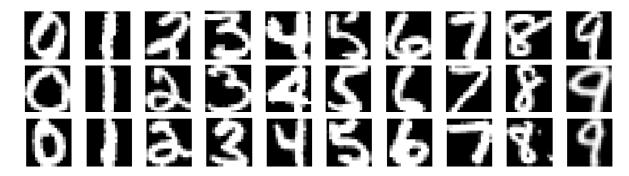
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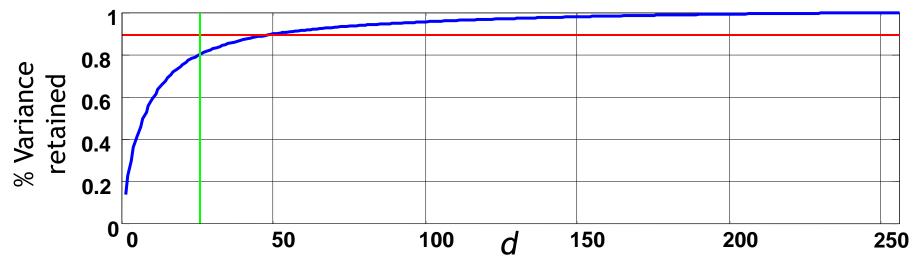
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PCA example

• *e.g.* NIST digits: 2000 samples, $p = 256 (16 \times 16)$







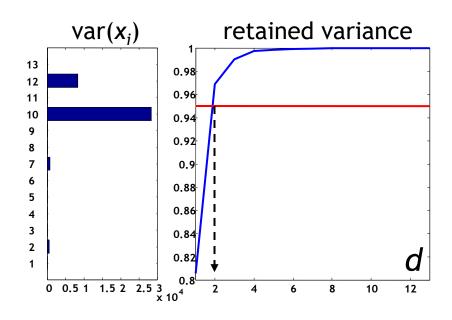
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 x' ← (x - μ)



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 - length in cm has a much larger variance than length in m
 - best to standardise: $x' \leftarrow (x \mu) / \sigma$

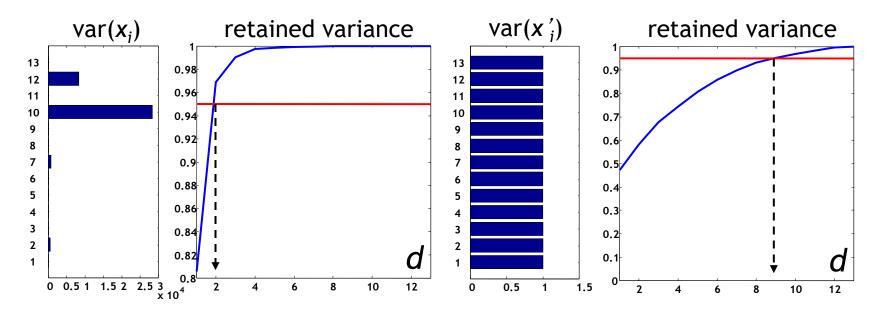


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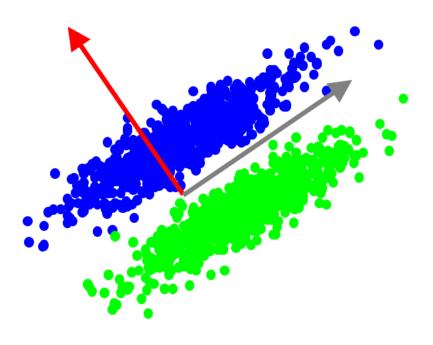
PCA conclusions

- PCA:
 - Is global and linear
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PCA conclusions

- PCA:
 - Is global and linear
 - Is unsupervised (but we can do PCA on each class)
 - Needs a lot of data to estimate Σ well.
- Danger:
 - Criterion is not necessarily related to the goal;
 - Might discard important directions



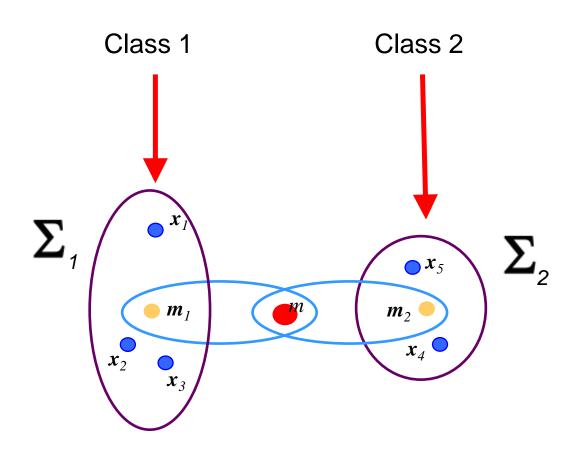
Supervised, linear feature extraction

- If class label ω (or y) is given, supervised extraction
- Examples: Fisher mapping; Linear Discriminant Analysis (Day 2)



Supervised feature extraction (2)

(supervised = we know the class labels)

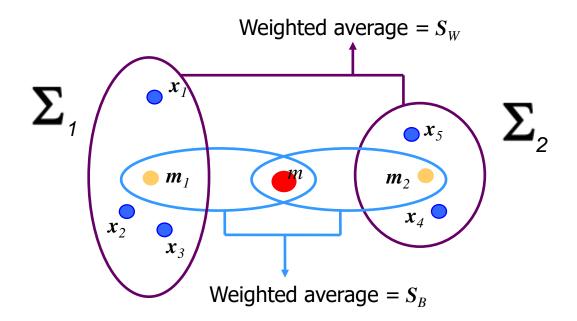




Supervised feature extraction (2)

Within-class and between-class scatter matrices:

• Within-class:
$$S_w = \sum_{i=1}^C \frac{n_i}{n} \Sigma_i$$



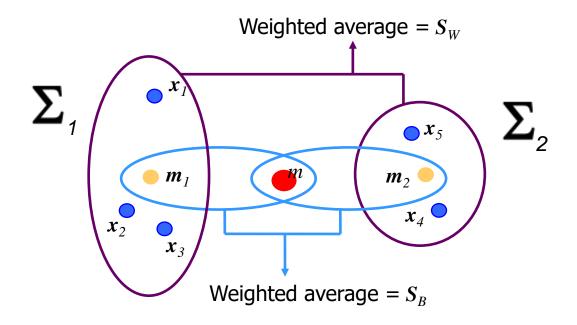


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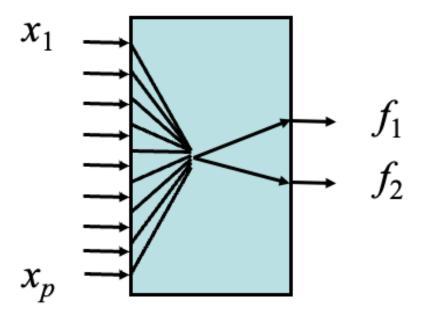
• Between-class:
$$S_B = \sum_{i=1}^C \frac{n_i}{n} (m_i - m)(m_i - m)^T$$





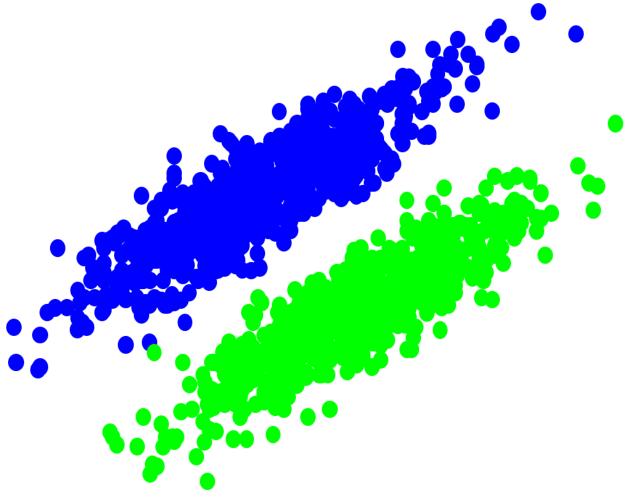
Supervised, linear feature extraction

- Example: Fisher mapping
- Supervised: we know the class labels
- Extraction: mapping of features to new (sub)space
- This (sub)space gives the best class separation

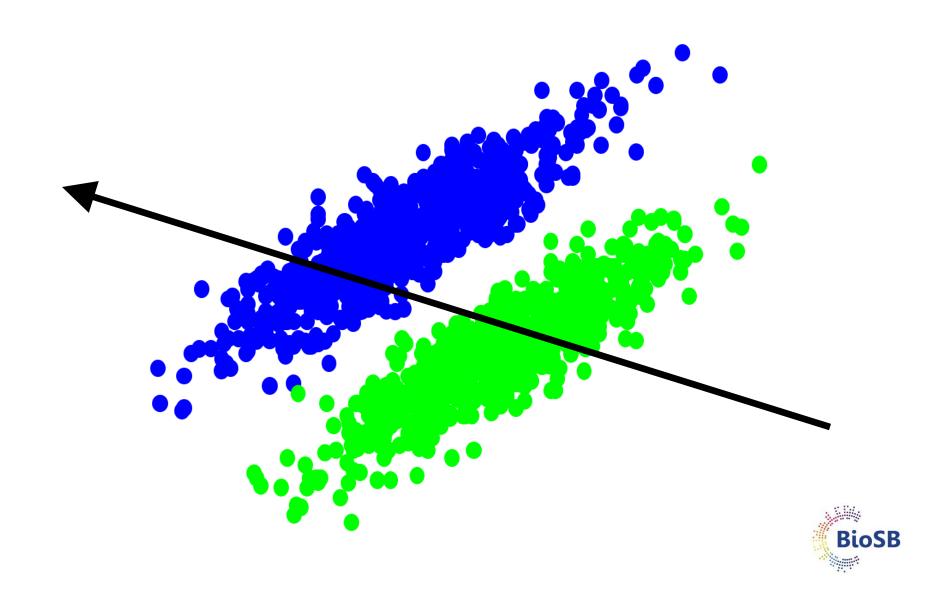


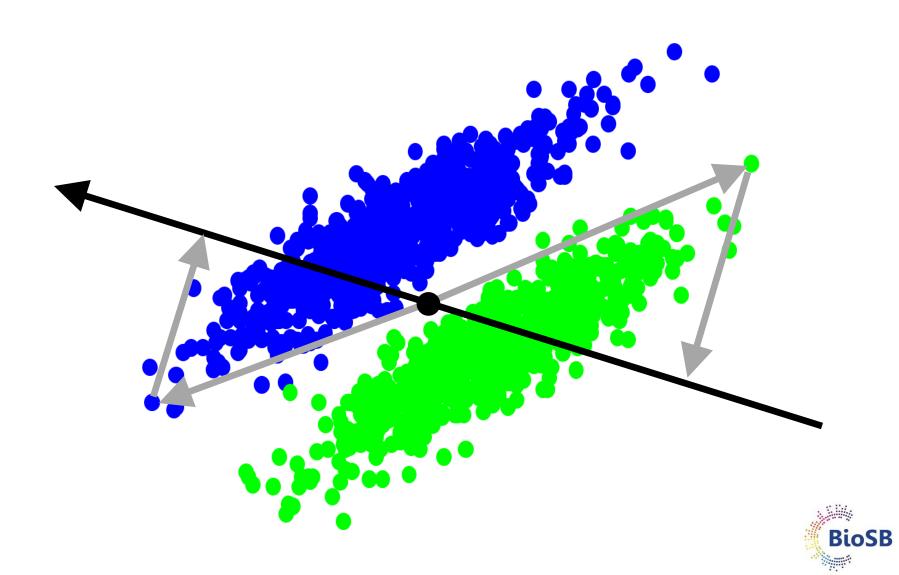


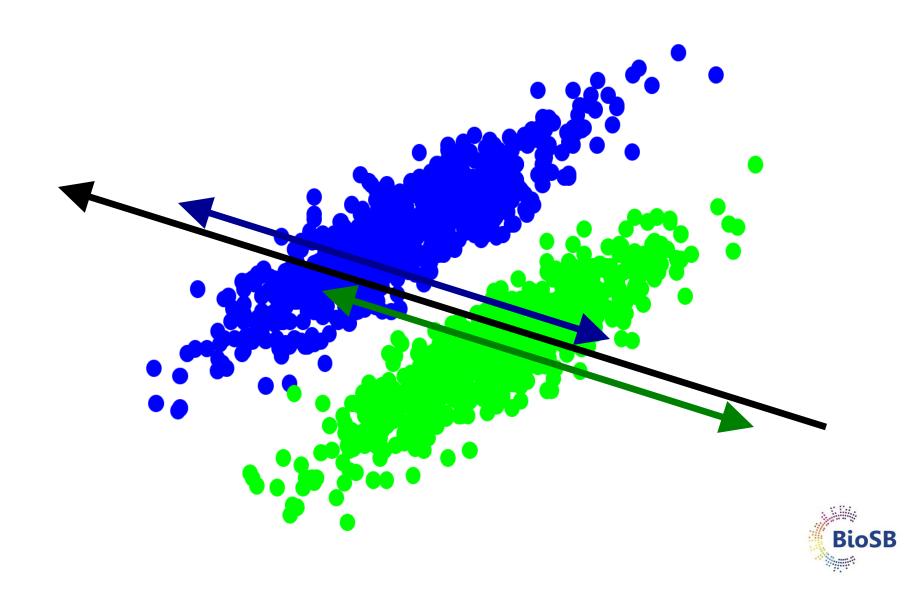
Fisher mapping: finding the direction (subspace) to project onto for the best class separation



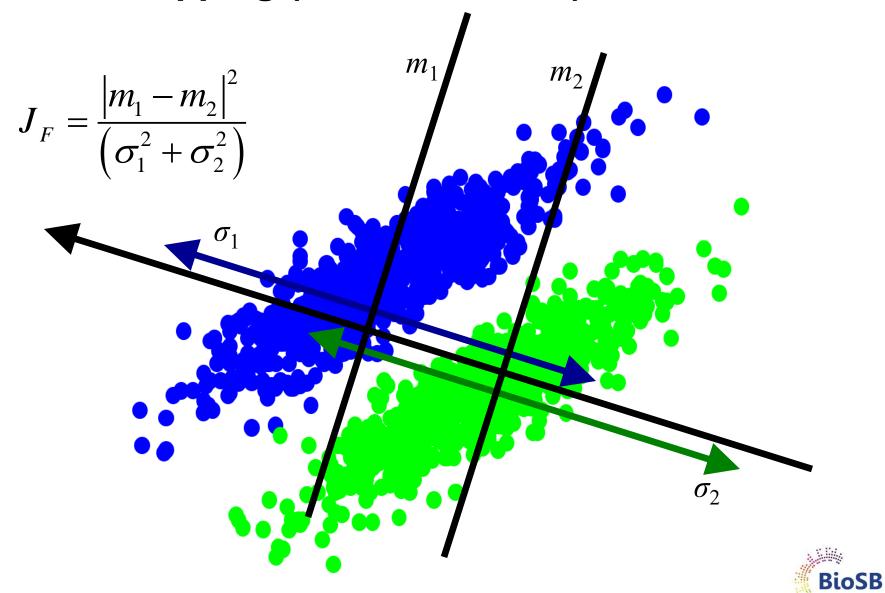


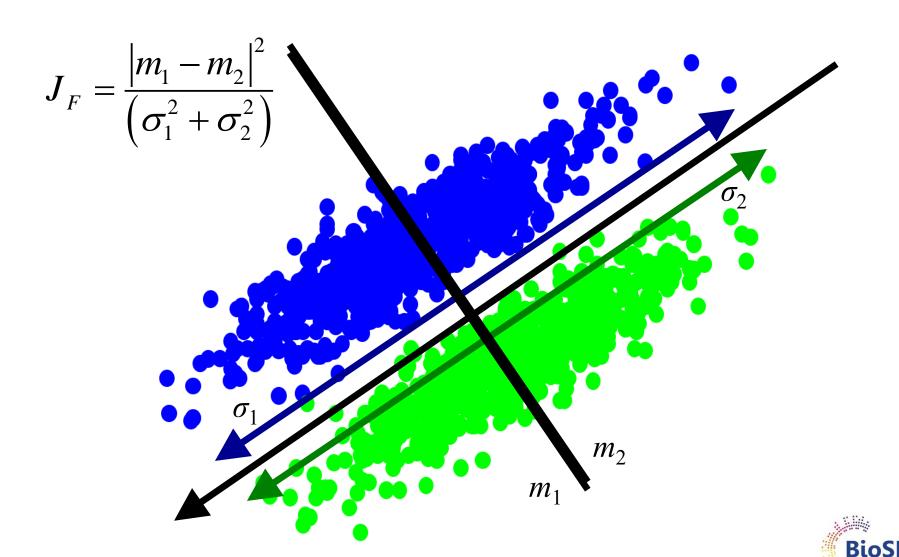


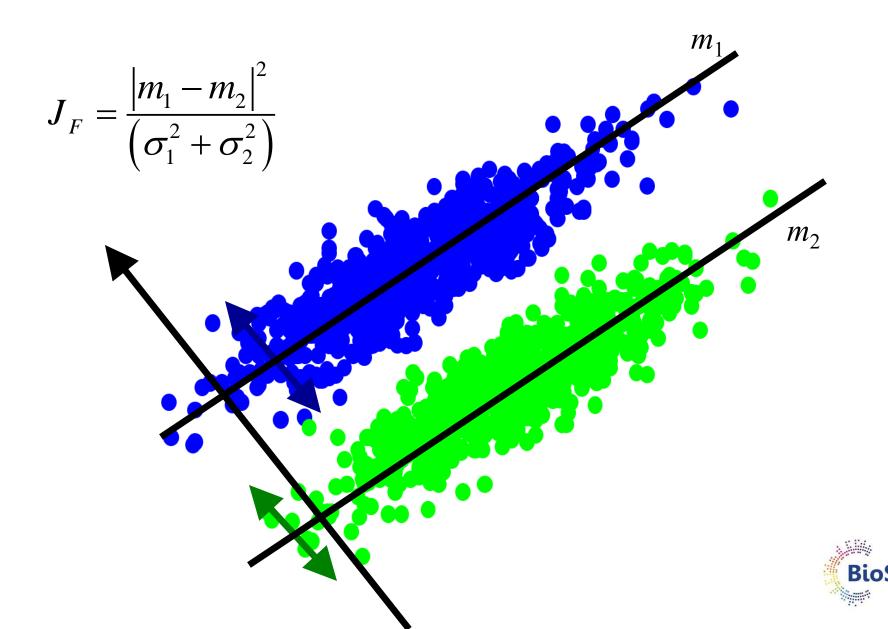




Fisher mapping (Fisher criterion)





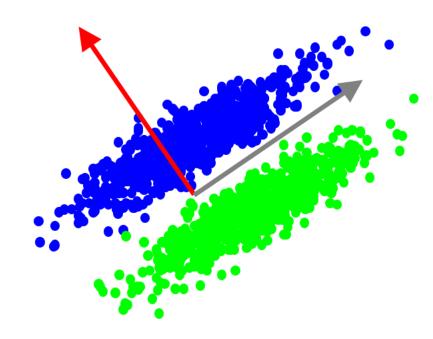


Fisher mapping

- Find basis vector a_1 for $\{x\}$ such that in the projections, the classes are maximally separated
- Choose a_1 to maximise Fisher criterion:

$$J_F(\boldsymbol{a}_1) = \frac{\boldsymbol{a}_1^T \boldsymbol{S}_B \boldsymbol{a}_1}{\boldsymbol{a}_1^T \boldsymbol{S}_W \boldsymbol{a}_1}$$

Maximize between class variance
 Minimize within class variance



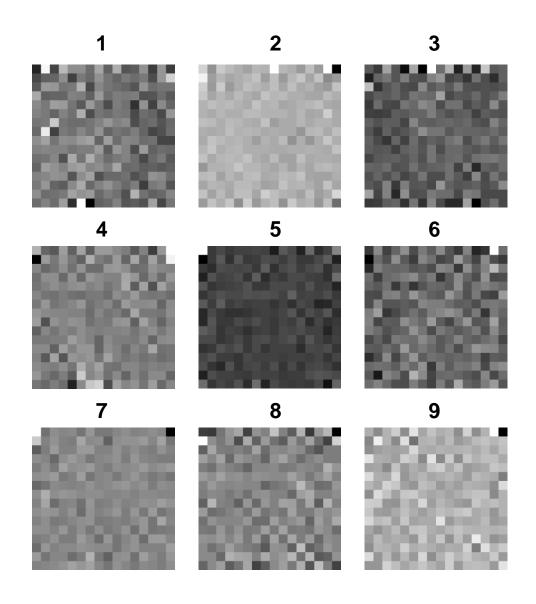
- Solution:
 - eigen-analysis on $S_W^{-1}S_B$
 - select c-1 (# classes 1) dimensions for final classifier

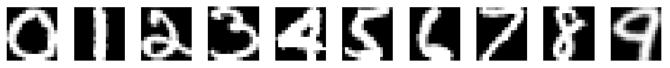


Fisher mapping (3)

 Map down to a maximum of c - 1 dimensions

Example: NIST digits







Fisher mapping (4)

- To avoid fitting noise, can do PCA first
- If system is underdetermined $(n \le p)$, first doing PCA is required, otherwise matrix inversion results in singularity
- But then...?



Fisher mapping (4)

- To avoid fitting noise, can do PCA first
- If system is underdetermined $(n \le p)$, first doing PCA is required, otherwise matrix inversion results in singularity
- But then we might be destroying the class separation as PCA is unsupervised



Summary

- Discussed:
 - Linear feature extraction
 - Unsupervised: Principal Component Analysis (PCA)
 - Supervised: Fisher mapping



Nonlinear, unsupervised feature extraction

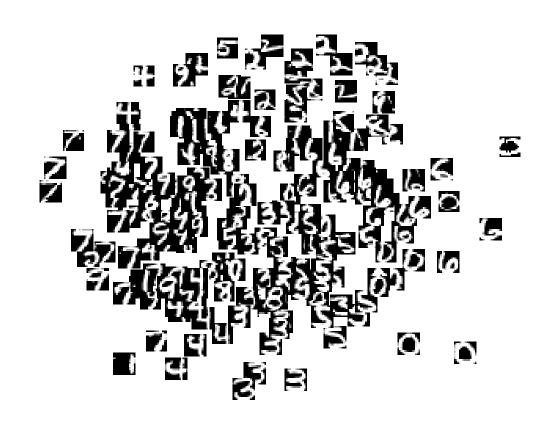
- Multidimensional scaling (MDS):
 - Nonlinear:
 - Sammon mapping
 - t-SNE / UMAP



Nonlinear feature extraction (3)

Example: embedding

 Find new representation such that distances between samples are preserved as well as possible





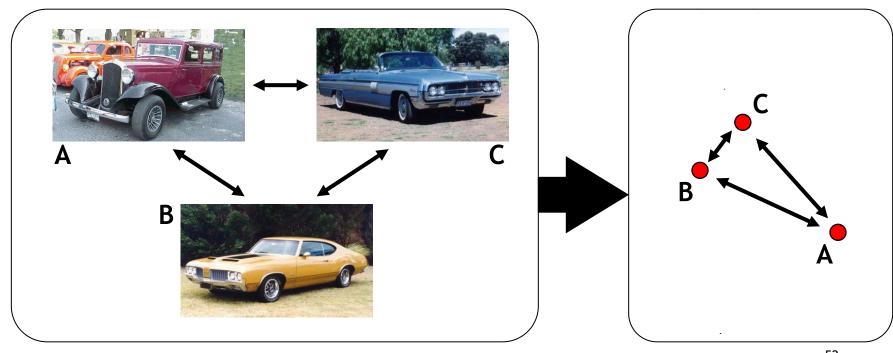
Multidimensional scaling (MDS)

- Criterion: preserve all inter-sample distances
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- Map samples to a new (lower dimensional) space



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 - easy to introduce nonlinearity
- Algorithms should find:
 - new, low-dimensional coordinates for each object
 - the number of dimensions to embed the data in



- d_{ij} : distance $||x_i x_j||$ in original space (? dimensional)
- δ_{ij} : distance $||y_i y_j||$ in new space (*d* dimensional)



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$$Stress(y) = \frac{1}{\sum_{i} \sum_{j>i} d_{ij}^{(q+2)}} \sum_{i} \sum_{j>i} d_{ij}^{q} (\delta_{ij} - d_{ij})^{2}$$

• weight factor q = ..., -2, -1, 0, 1, 2,...

q > 0: emphasise large distances

q < 0: de-emphasise large distances (smaller more important)

Sammon mapping: q = -1



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- Compute derivative of the stress with respect to positions of samples in new space
- Adapt the positions of samples in lower dimensional space

$$\mathbf{y'} = \mathbf{y} - \alpha \frac{\partial Stress(\mathbf{y})}{\partial \mathbf{y}}$$



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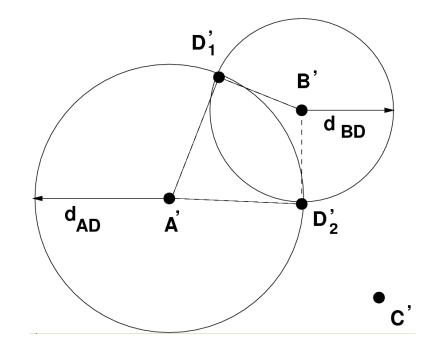
$$y' = y - \alpha \frac{\partial Stress(y)}{\partial y}$$

Repeat till convergence (positions of samples do not change)



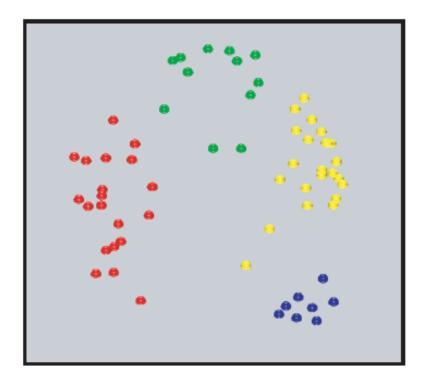
Embedding new points

- Problematic: re-run entire algorithm...
- Sub-optimal solution: triangulation
 - Embed new point D
 - D has A and B as neighbors in original space
 - Preserve distance to two embedded neigbours A', B' exactly
 - Use C' to decide which of the two candidates D₁', D₂' to use

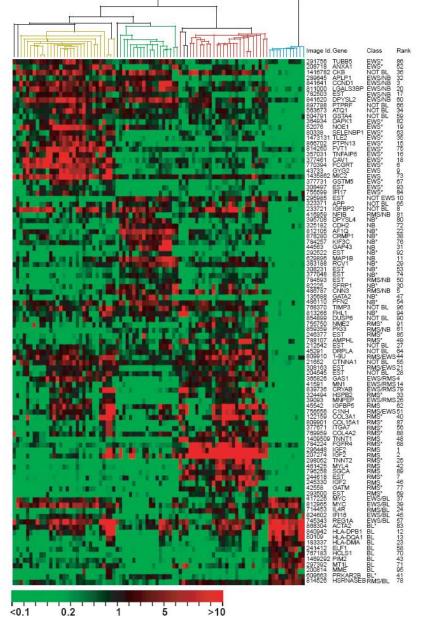




MDS example



- Neuroblastoma (NB)
- Rhabdomyosarcoma (RMS)
- Burkitt lymphoma (BL)
- Ewing family of tumors (EWS),



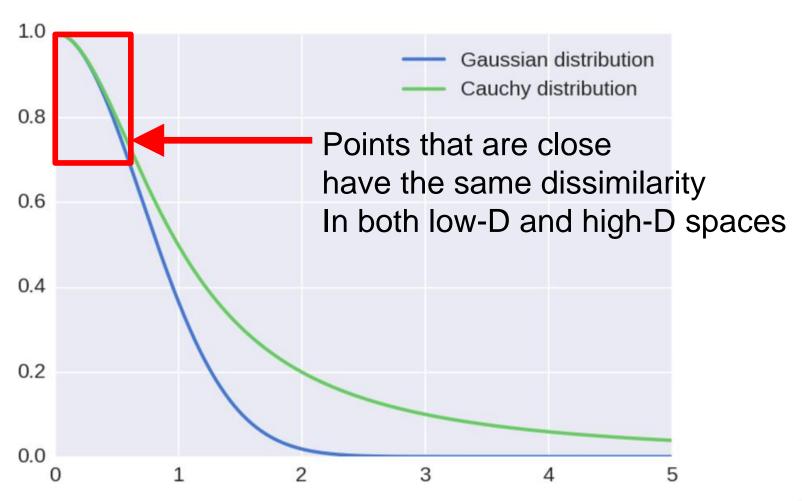


t-SNE (t-distributed stochastic neighbor embedding) (van der Maaten et al, 2008)

- In the input (high-D) space, X: compute dissimilarities between all pairs of points using a gaussian dissimilarity measure, pij
- In the output (low-D) space, Y: compute dissimilarities between all pairs of points using a t-distribution (with 1 d.o.f. (Cauchy)) dissimilarity measure, qij
- Minimize the Kullback-Leibler distance between these two distributions

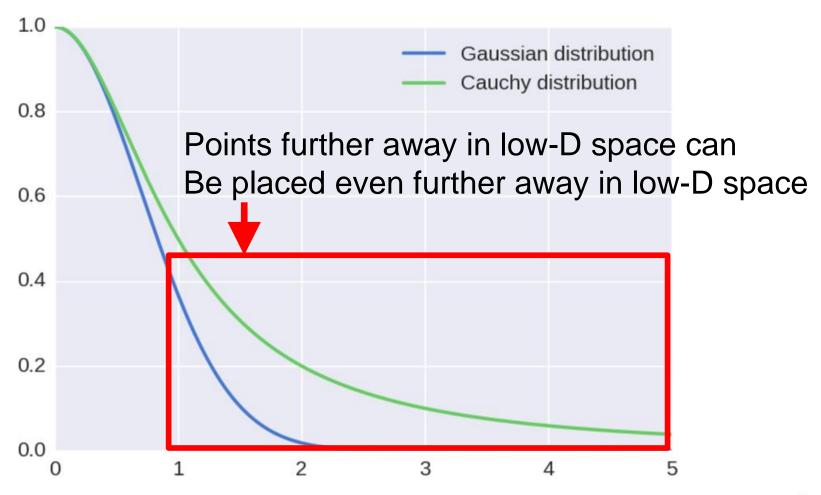


t-SNE: Cauchy and Gaussian distribution





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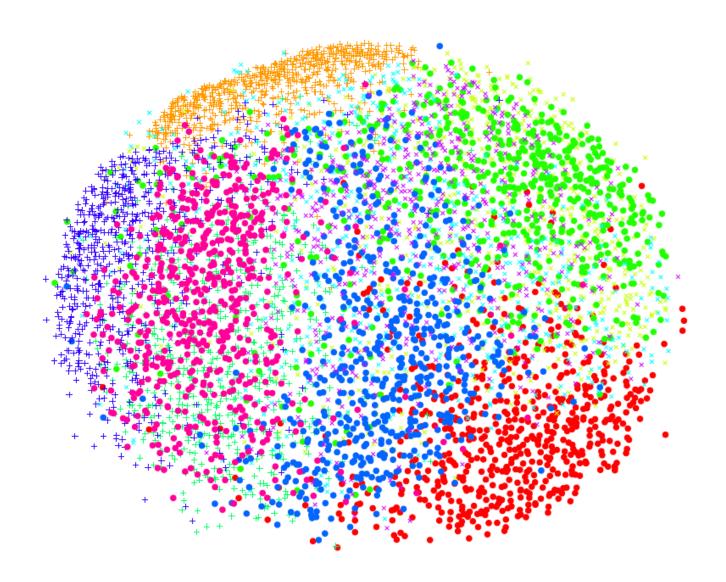


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- Minimize the Kullback-Leibler distance between these two distributions (P and Q)
- t-SNE faithfully retains small distances

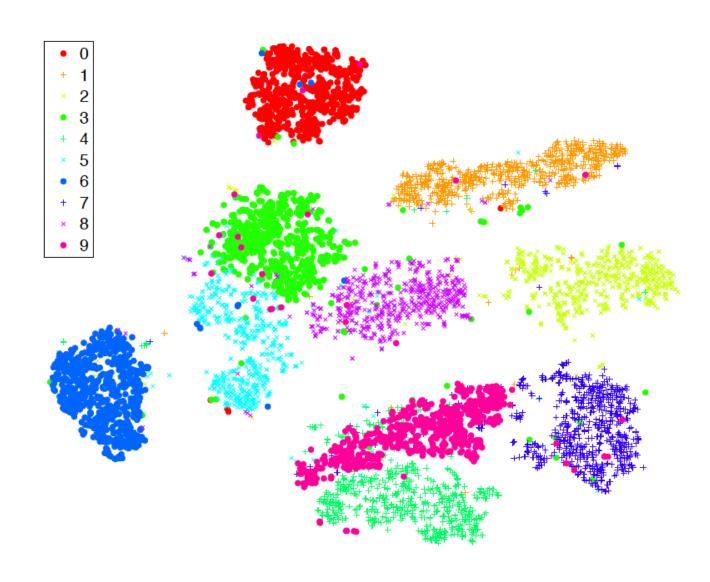


t-SNE: Sammon map of digit data





t-SNE: t-SNE map of digit data





MDS conclusions

- Experts or measurements give distances
- Optimise a stress-function (MDS) or KL distance (t-SNE)
- Important:
 - the distance measure used: is it representative?
 - the weighting of distances (q): can influence outcome heavily.
 - t-SNE run with defaults is quite reliable
- Largest risk: seeing structure in the data that is not really there
- Remaining problem: embedding new data points
- t-SNE (and now UMAP) are modern techniques to perform representation of data in high-D space in 2D



Feature selection

- For feature selection, we need:
 - A criterion function
 e.g. error, class overlap, information loss
 - A search algorithm
 e.g. pick the best single feature at each time



Criteria

- 1. Wrapper: exact performance measure
 - base performance estimate on classifier;
 - estimate performance using cross-validation:
 - very expensive!



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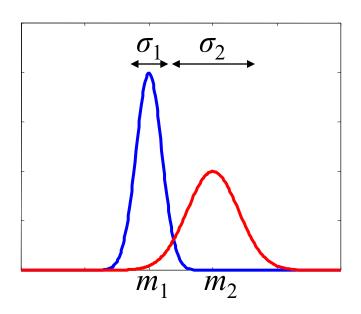
- 2. **Filter**: approximate performance predictors:
 - calculate the performance of an easy-to-use/'cheap' model
 - indication of how well a more powerful model may perform
 - is much faster to compute.



Criteria (2)

- Example
 - Simple measure of the 'separability' of classes given a feature
 - 1D case: Signal-to-Noise Ratio (SNR) or Fisher criterion:

$${m J}_F = rac{\left| m_1 - m_2
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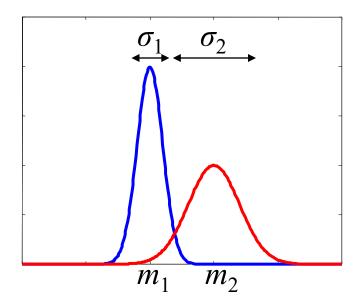


Criteria (3)

- Example
 - Simple measure of the 'separability' of classes given a feature
 - 1D case: Signal-to-Noise Ratio (SNR) or Fisher criterion:

$$J_F = \frac{\left| m_1 - m_2 \right|^2}{\left(\sigma_1^2 + \sigma_2^2 \right)}$$

- If J_F is large: good separability
- If J_F is small: poor separability



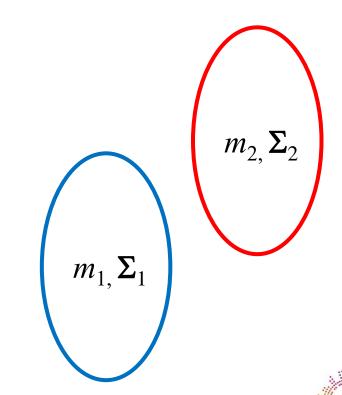


Criteria (4)

- The multi-variate equivalent of the Fisher criterion is the
- Mahalanobis distance:
 - assumes
 - Gaussian distributions with
 - equal covariance matrix Σ:

$$D_{M} = (m_{1} - m_{2})^{T} \Sigma^{-1} (m_{1} - m_{2})$$

$$\sum = \sum_{i=1}^{C} \frac{n_i}{n} \; \Sigma_i$$



Search algorithms

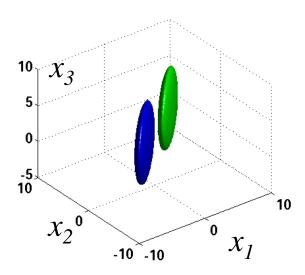
- Feature selection: select a subset of d out of p features which optimises the criterion
- Simplest solution: look at all possible subsets
- Problem: there are $\binom{p}{d} = \frac{p!}{(p-d)!d!}$ subsets

- *e.g.* p = 50 features, d = 2:
 - d = 2 : 1225 subsets
 - $d = 5 : 2.1 \times 10^6$ subsets
 - d = 25: 1.3 x 10¹⁴ subsets

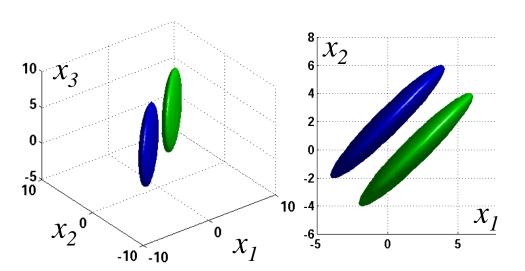


- Sub-optimal algorithms: select or deselect one feature (or a few features) at a time
- Simplest: best individual d
 but these are not necessarily the best d!
- Demonstration: two Gaussians;
 select 2 features out of 3 for classification

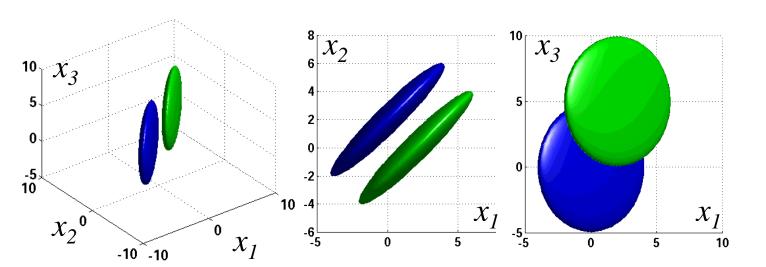




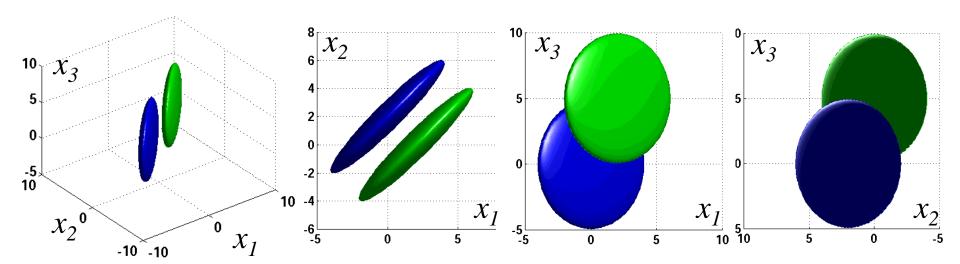




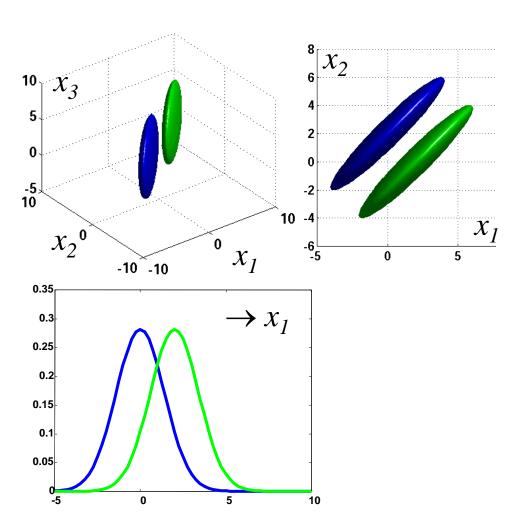




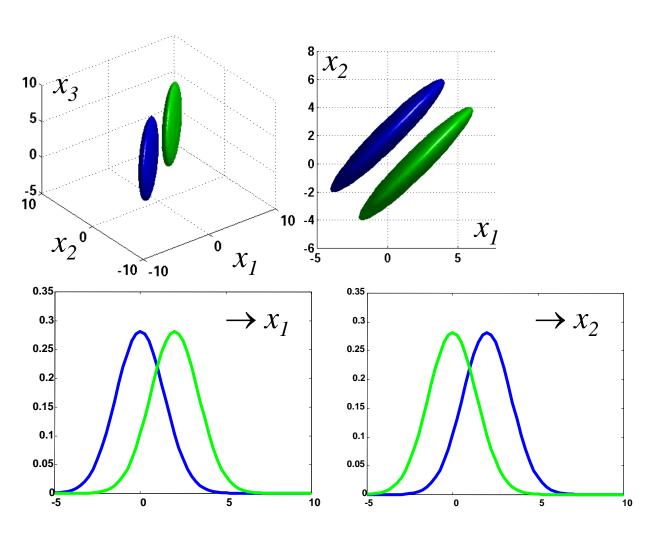




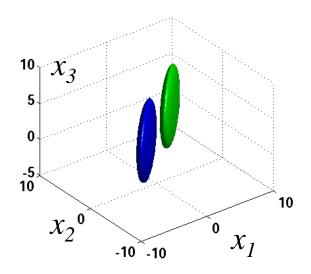


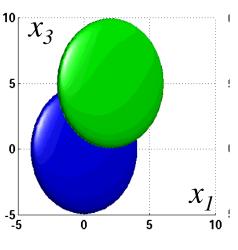


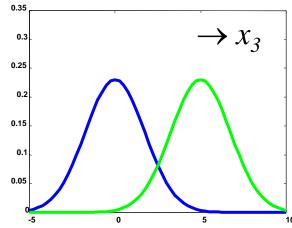




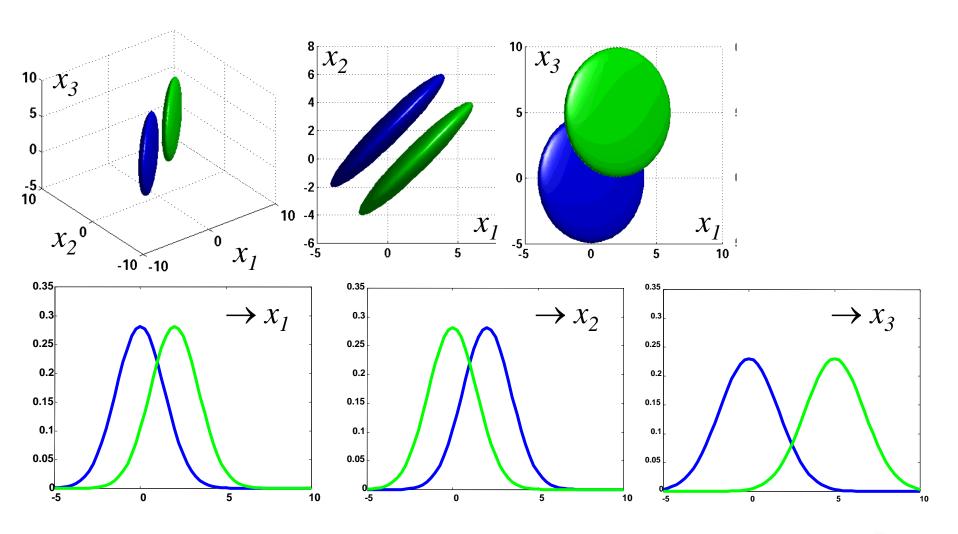














- Other sub-optimal algorithms:
 - Forward selection (for when d is low)
 - start with empty set
 - keep adding one feature at a time so that the entire subset so far performs best



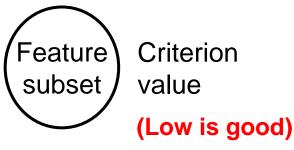
- Other sub-optimal algorithms:
 - Forward selection (for when d is low)
 - start with empty set
 - keep adding one feature at a time
 so that the entire subset so far performs best
 - Backward selection (for when d is high)
 - start with entire set
 - keep removing one feature at a time so that the entire subset so far performs best

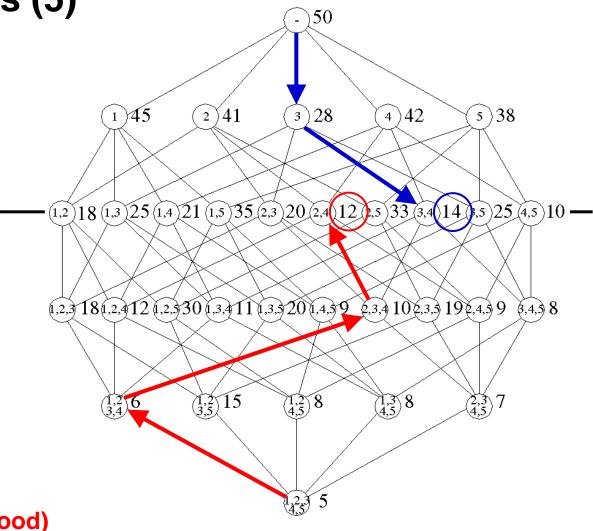


- Other sub-optimal algorithms:
 - Forward selection (for when d is low)
 - start with empty set
 - keep adding one feature at a time so that the entire subset so far performs best
 - Backward selection (for when d is high)
 - start with entire set
 - keep removing one feature at a time so that the entire subset so far performs best
 - Plus-*l*-takeaway-*r* (may be slightly better)
 - start with empty set (if l > r) or entire set (if l < r)
 - keep adding best l and removing worst r



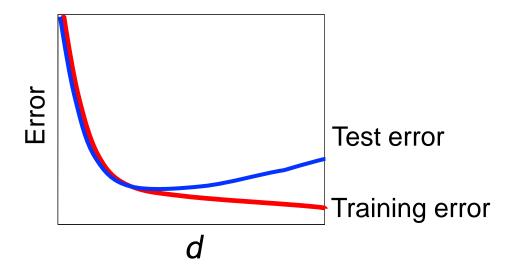
- Select d = 2out of p = 5features
- Sub-optimality illustrated:
 - forward
 - backward







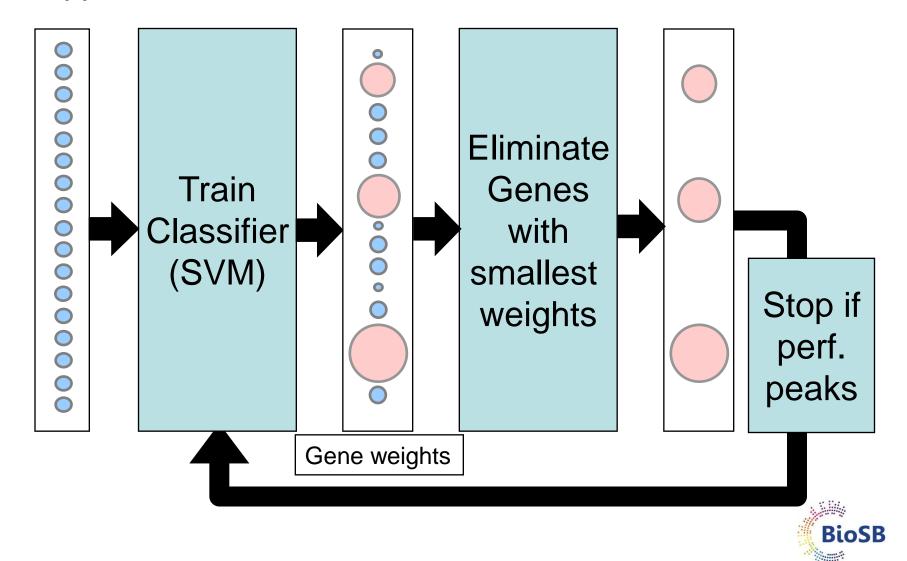
- When should we stop?
 - Due to estimation problems (e.g. covariance matrix),
 we may be overtraining on training set
 - This is revealed by increasing error on the test set



 Otherwise (with very large sample sizes), we will have to specify a desired number of measurements

Example: Recursive feature elimination (RFE)

Wrapper, Backward search



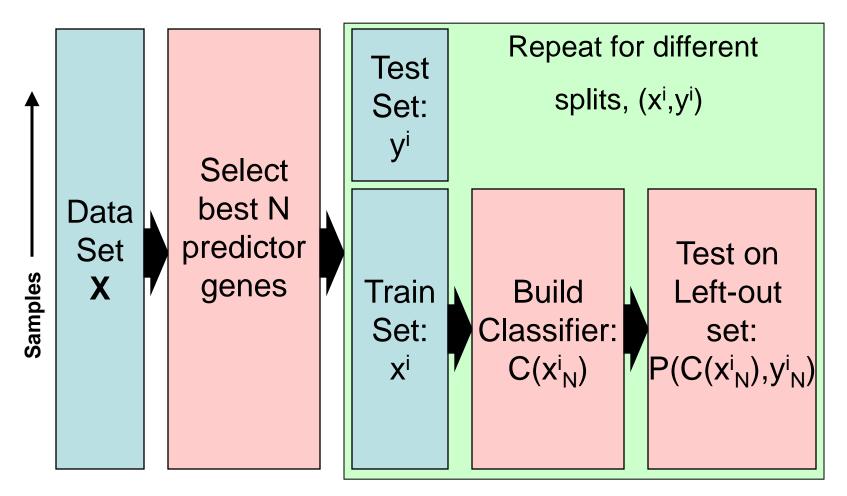
What can go wrong?

Selection bias...

- Guyon et al. (2002). Machine Learning 46, 389 422.
- Ambroise and McLachlan (2002). PNAS 99, 6562-6566.

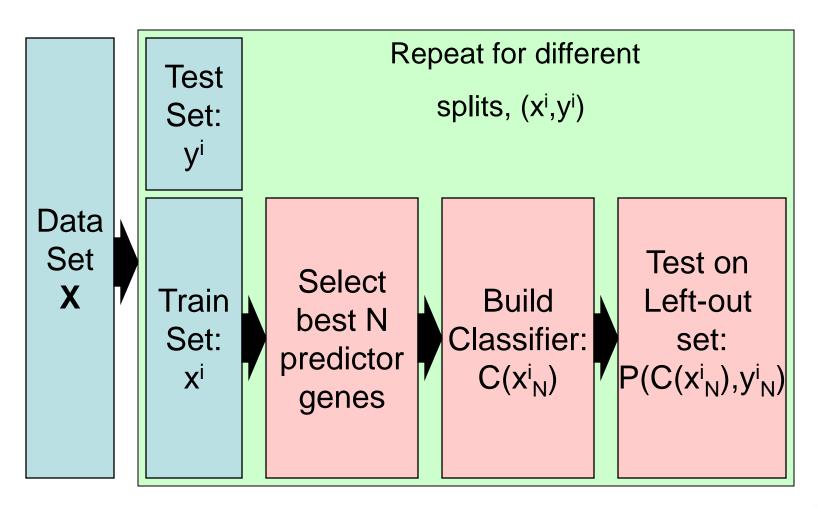


Biased selection



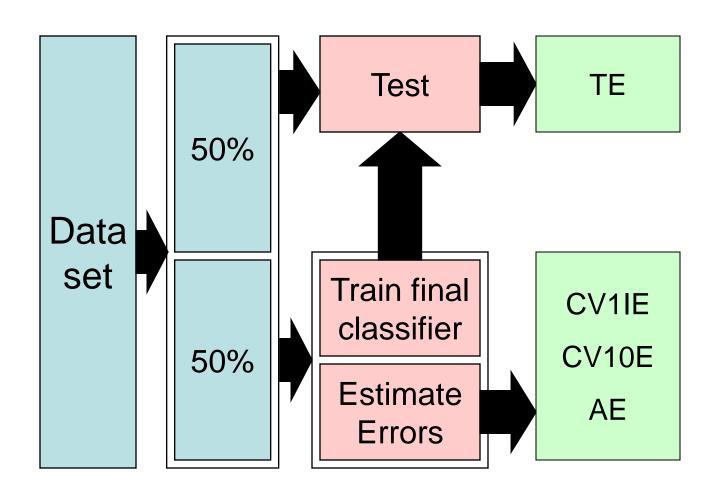


Unbiased selection





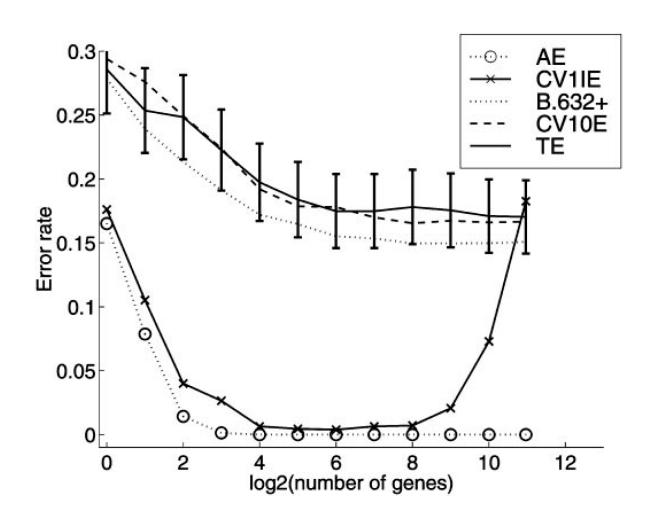
Ambroise & McLachlan experiments





Ambroise & McLachlan experiments

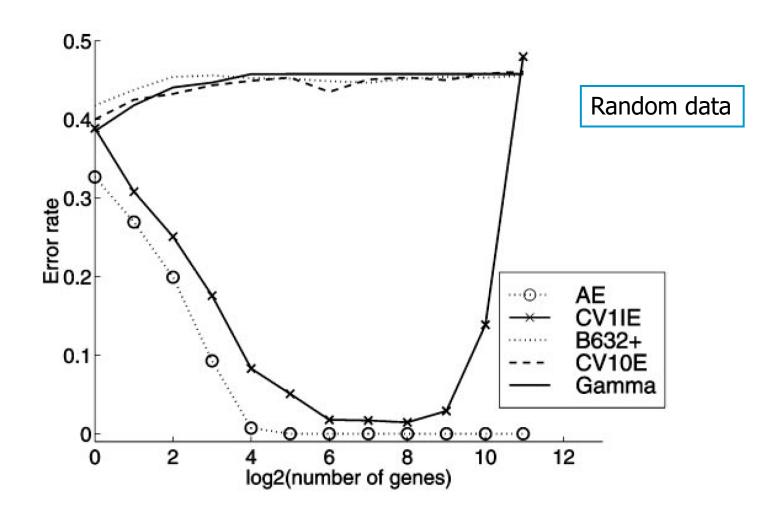
Colon vs. normal data





Ambroise & McLachlan experiments

Random data





Cross-validation

Remember:

Note:

we should never use the training set to calculate performance; this will give a biased estimate!

- for small sample size: use cross-validation
- Cross-validation should be applied to every choice made, including:
 - the number of features to use
 - the features to use
 - the type of classifier to use
 - •



Feature selection: summary

- Feature selection can improve performance and help interpretation
- Requirements: a criterion and a search algorithm
- Methodology (cross-validation) is very important, especially for RNAseq data ('p >> n')
- There seems to be some evidence that the simplest methods (individual selection) work best



Shrinkage

- Feature selection: selects a subset of features (1/0)
- Feature extraction: combinations of features are constructed based on variance and accuracy arguments
- Regularization 1: control contribution of genes to classifier based on individual quality and control degree of contribution with cross-validated classification error
- Regularization 2: combines accuracy (error) and penalty on large weights (= simple models) in one criterion.



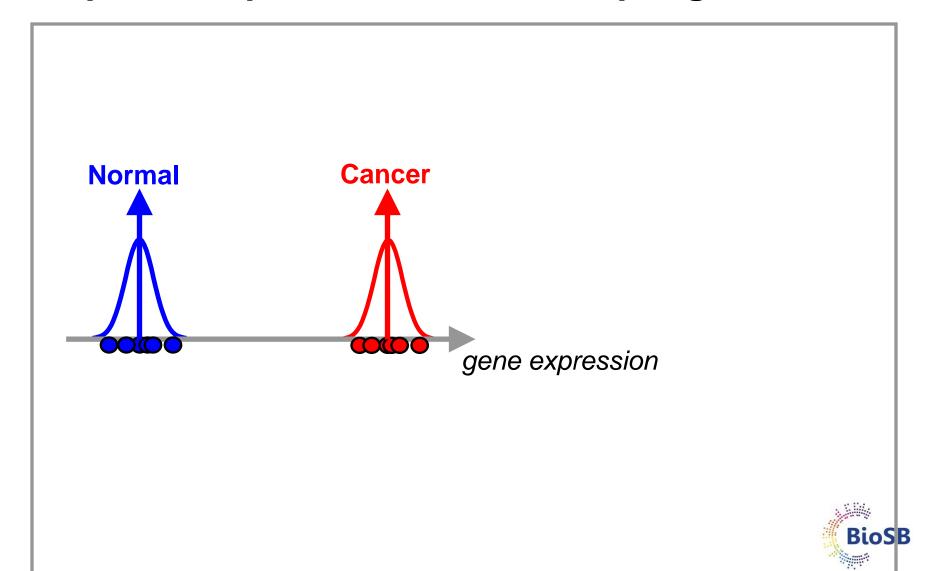
Shrunken centroids

- Same principle as forward filtering
- Genes are evaluated individually
- BUT, do not start with the best and keep adding;
- RATHER, start removing worst genes from the back
- In PAM* genes can participate 'partially', in forward filtering a gene is either 100% in or out.

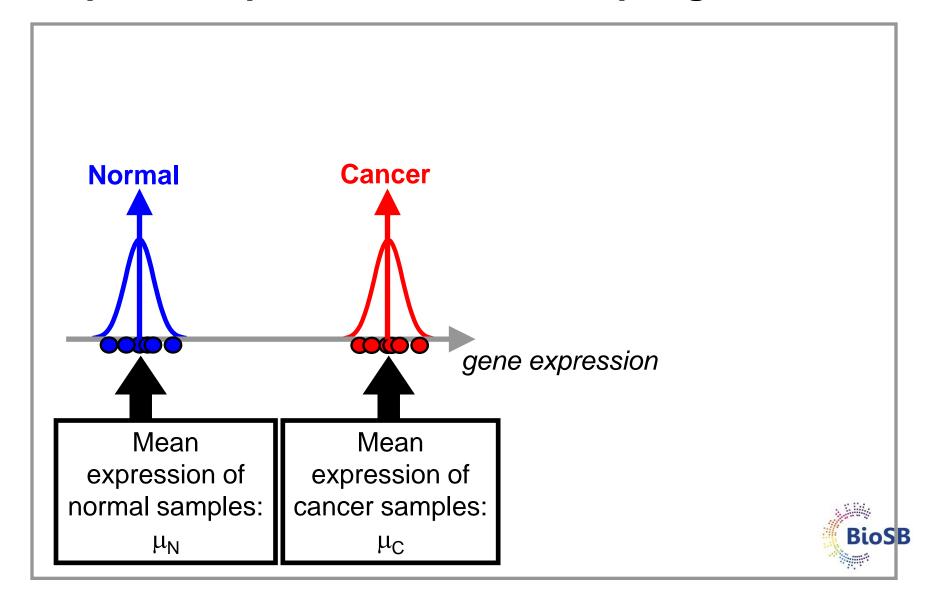


^{*} PAM: Prediction analysis of micro-arrays; R. Tibshirani, T. Hastie, B. Narasimhan and G. Chu. Diagnosis of multiple cancer types by shrunken centroids of gene expression. PNAS 99(10):6567 6572, 2002.

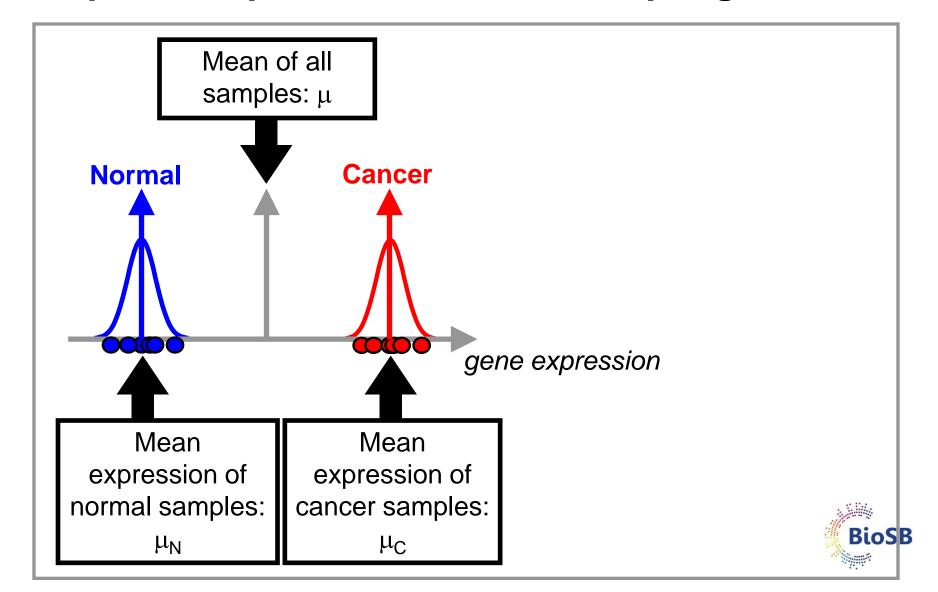
Shrunken centroids (1) Step 1: Compute class centroids per gene



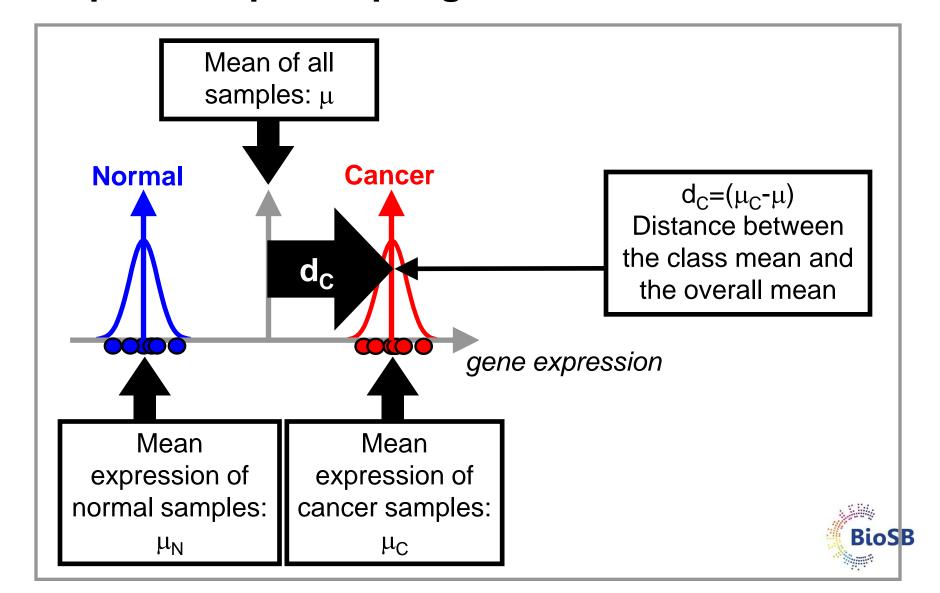
Shrunken centroids (2) Step 1: Compute class centroids per gene



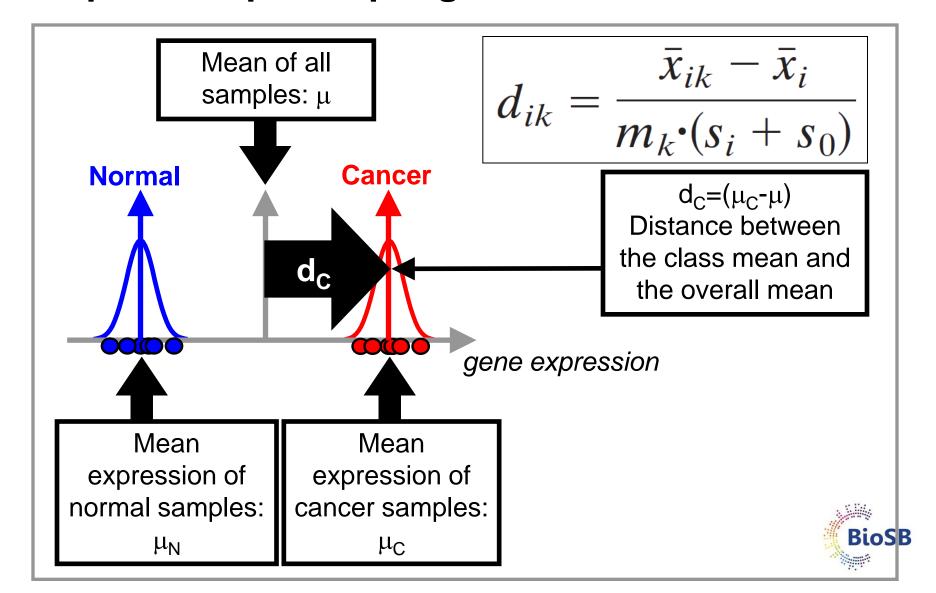
Shrunken centroids (3) Step 2: Compute overall centroids per gene



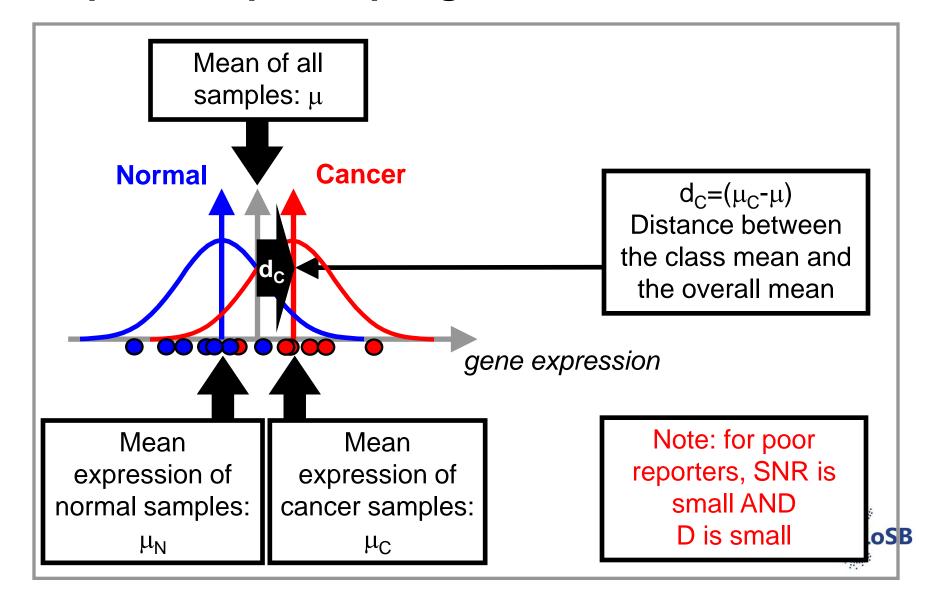
Shrunken centroids (4) Step 3: Compute d per gene



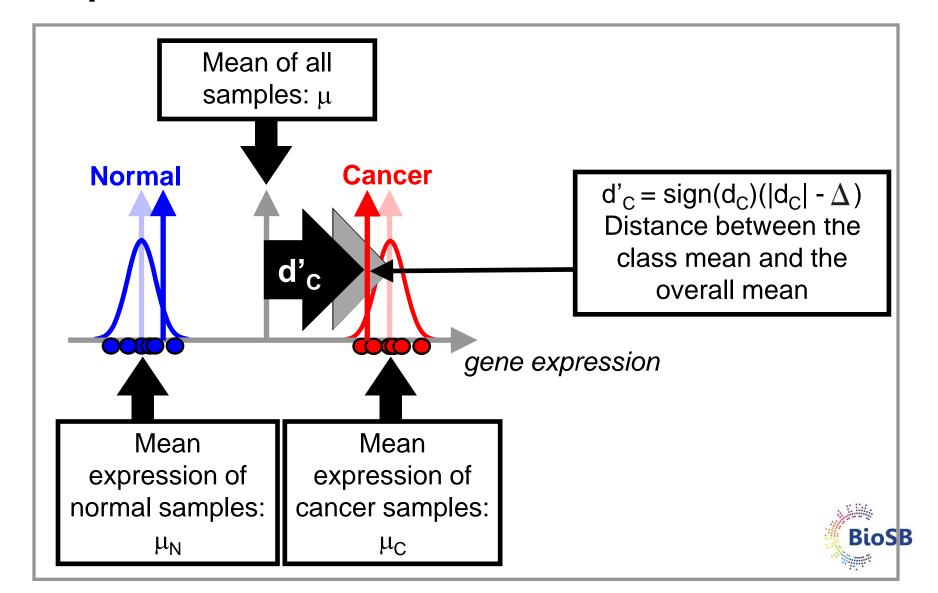
Shrunken centroids (4) Step 3: Compute d per gene



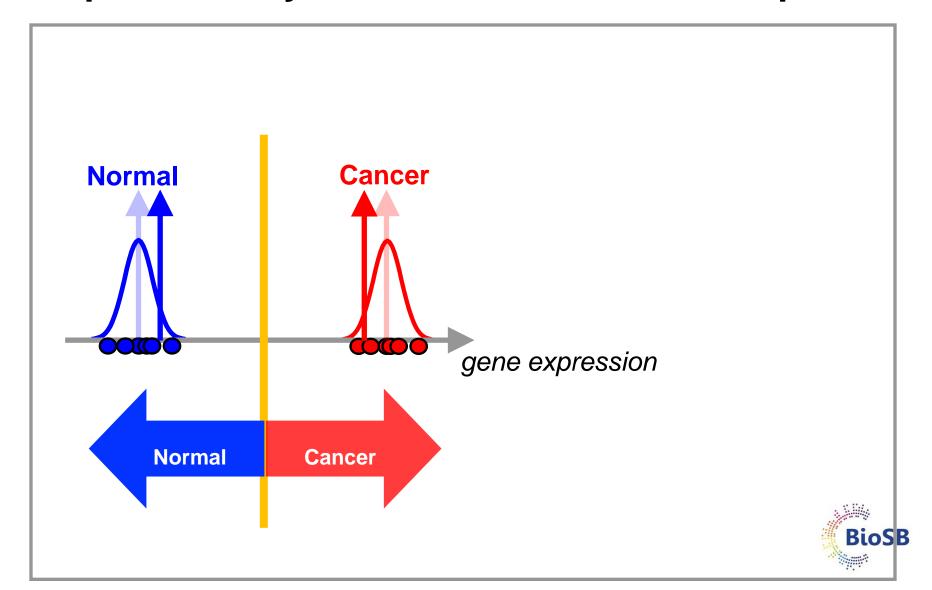
Shrunken centroids (5) Step 3: Compute d per gene

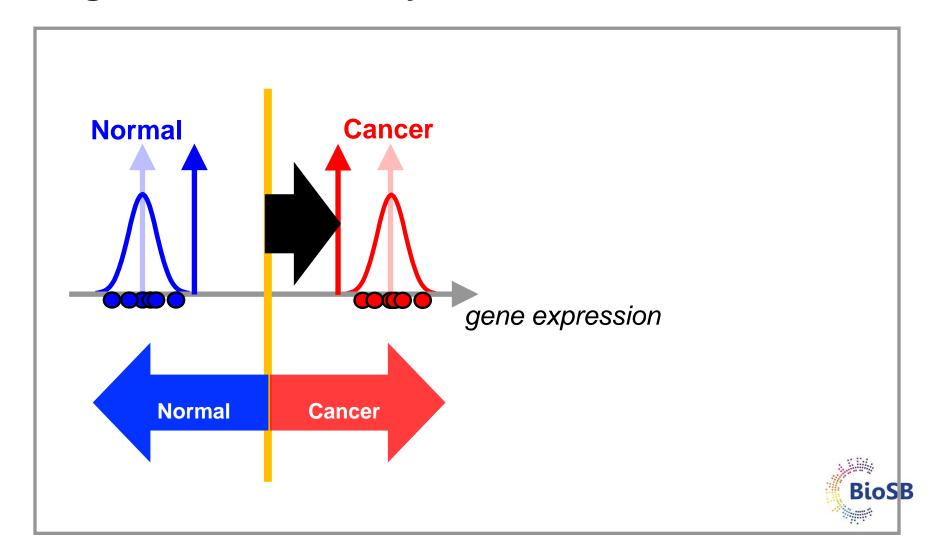


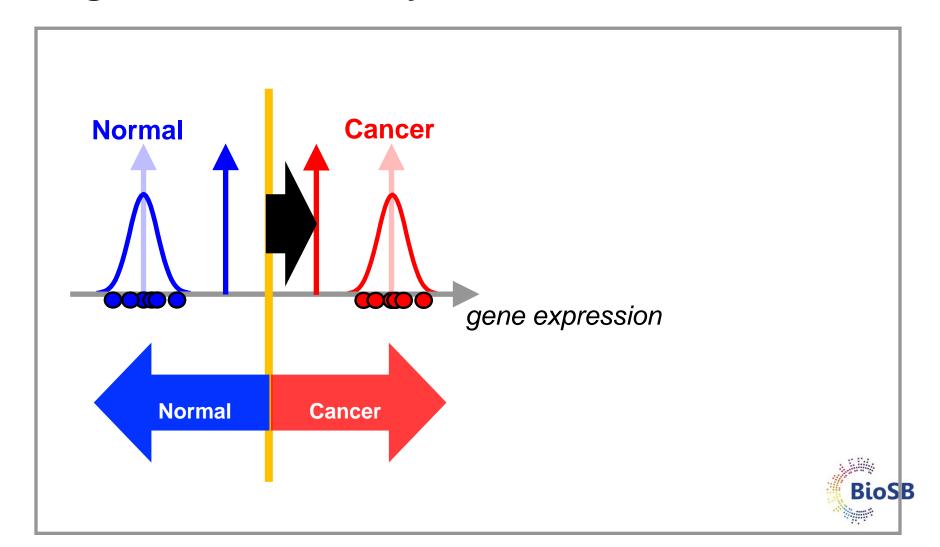
Shrunken centroids (6) Step 4: Shrink the centroids

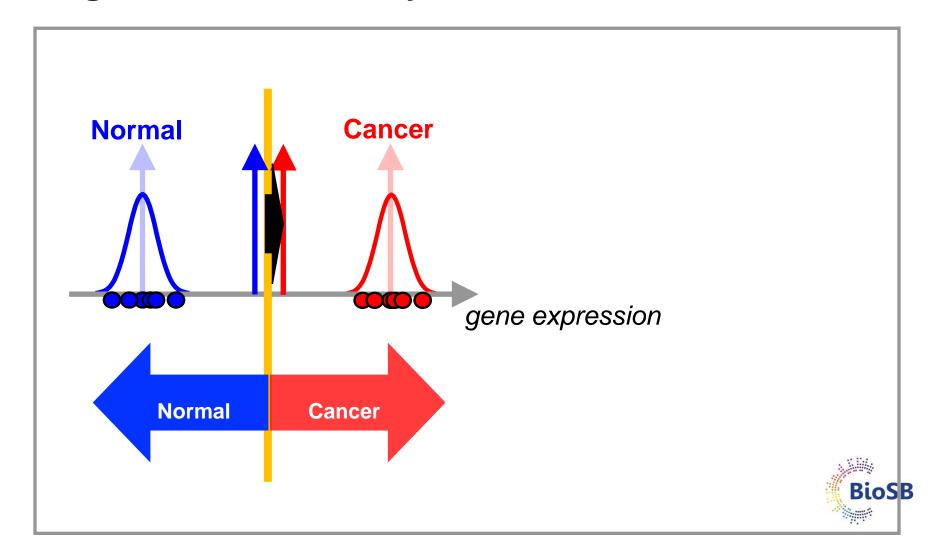


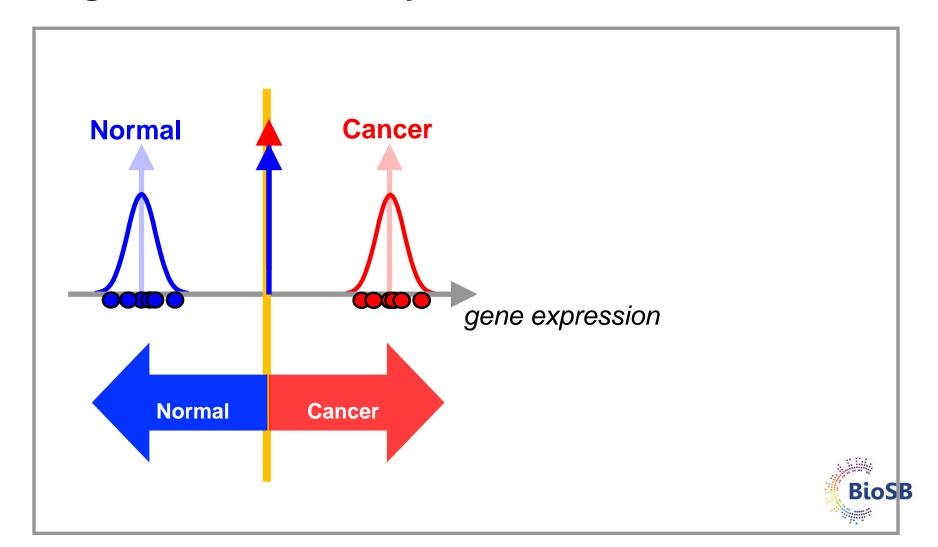
Shrunken centroids (7) Step 5: Classify with shrunken centroids / perf.



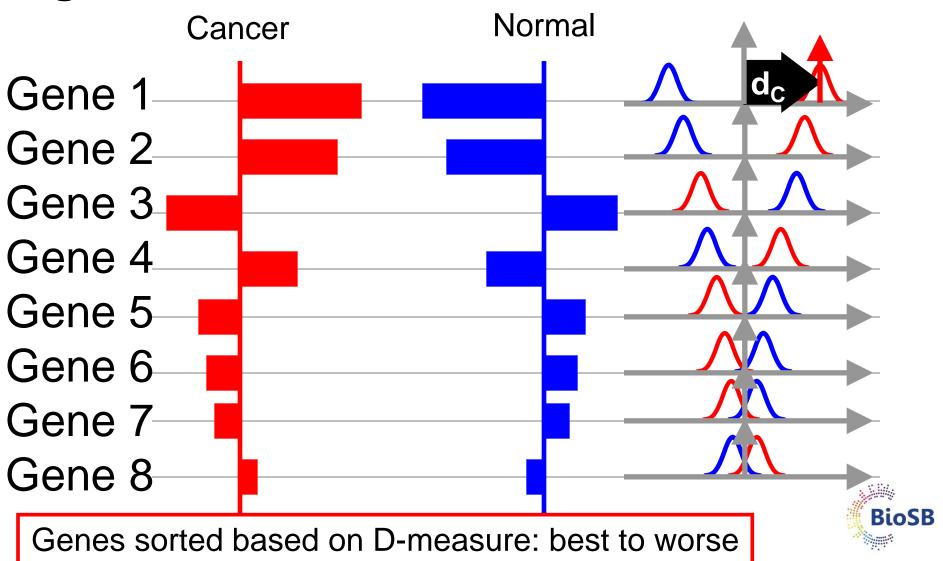




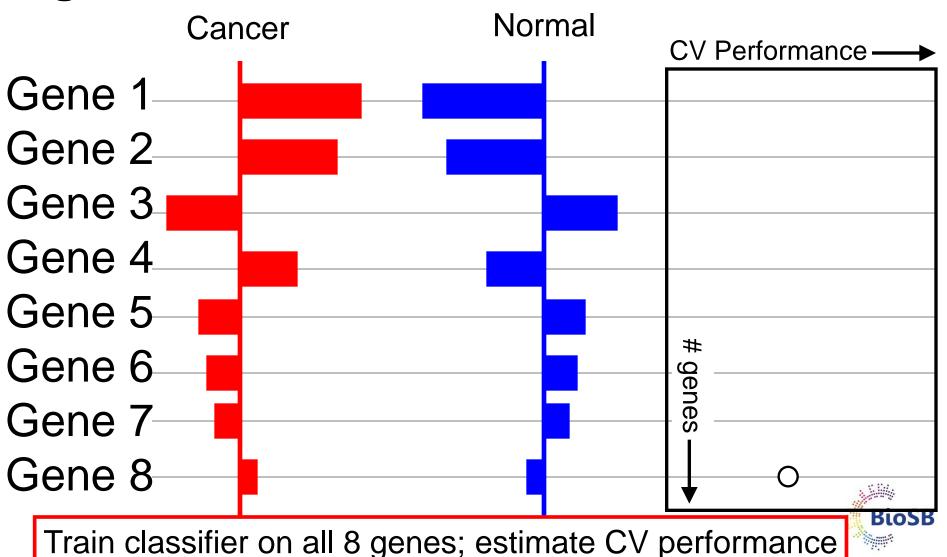




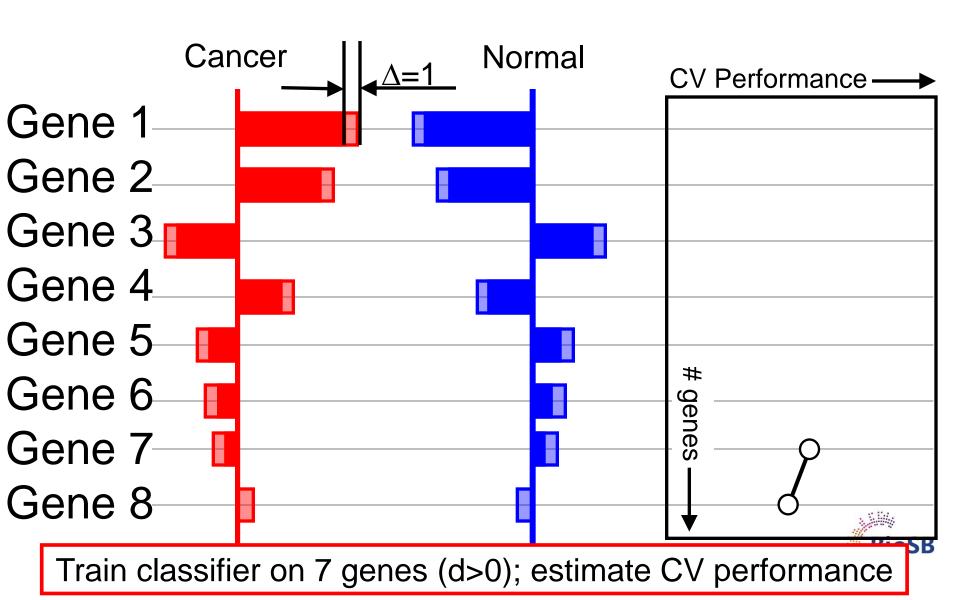
Shrunken centroids: selecting the genes



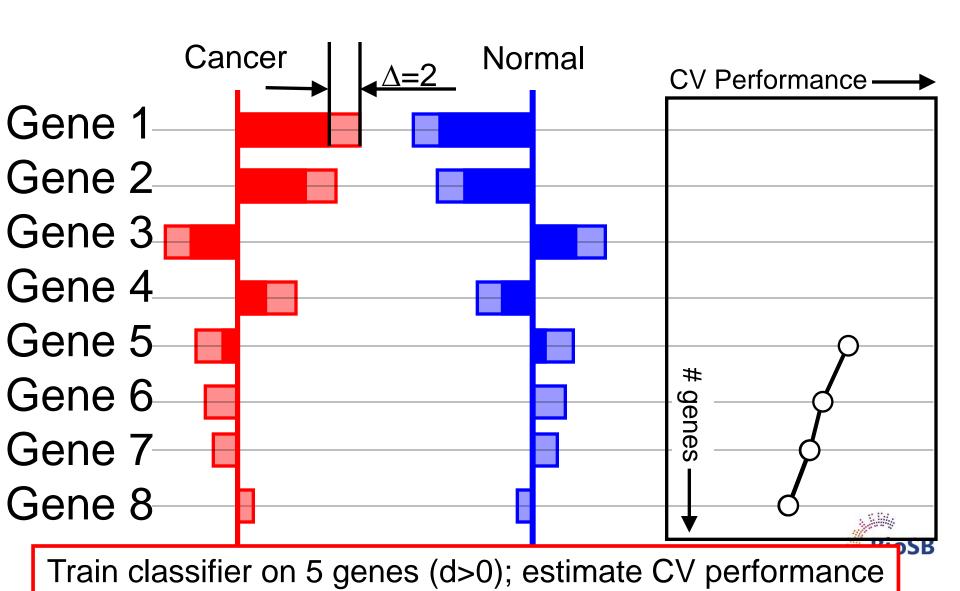
Shrunken centroids: selecting the genes



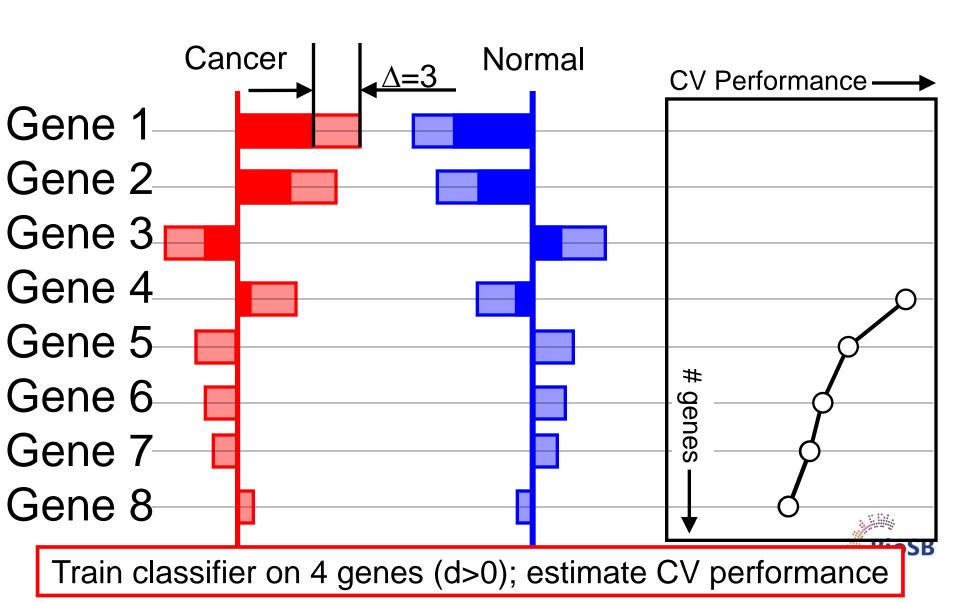
Shrink all d by $\Delta=1$: reduce length by 1



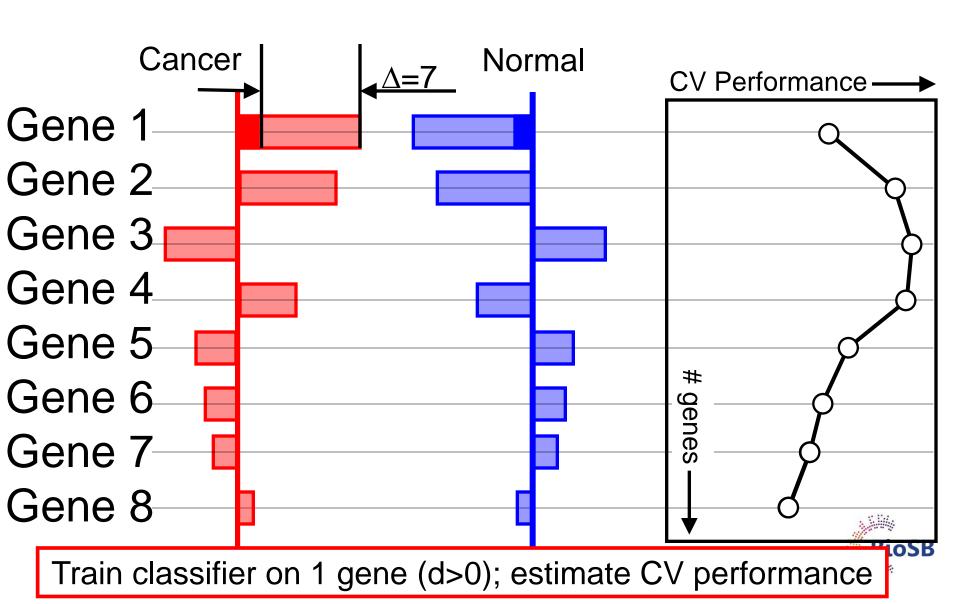
Shrink all d by $\Delta=2$: reduce length by 2



Shrink all d by $\Delta=3$: reduce length by 3

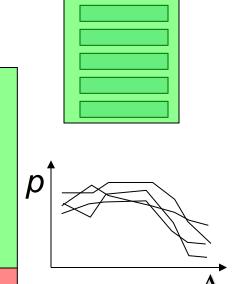


Shrink all d by $\Delta=7$: reduce length by 7

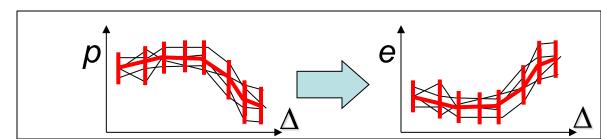


Determining the optimal Δ

- 1. Split the data (X) in 10 equal parts $(x_1,...x_{10})$
- 2. For each of the 10 folds (i=1,2,...,10)
- 3. On the training set $(X \setminus x_i)$
 - 1. Compute the class and overall centroids
 - 2. For a range of Δ (Δ = [0,0.5,...,7])
 - Shrink d for all genes
 - ii. Compute 'shrunken centroids' on training set
 - iii. Test the resulting classifier on the test set (x_i)
 - 3. Result: 10 Curves of performance vs. Δ

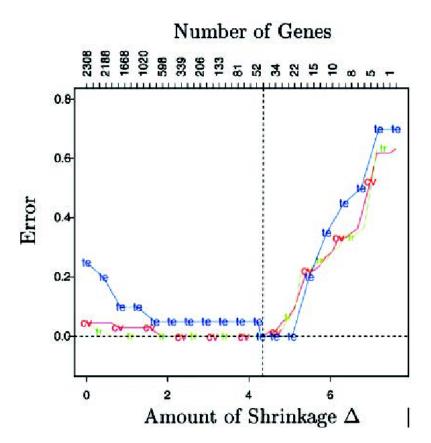


- 4. Average all 10 curves and compute std. dev. at each Δ
- 5. Pick the Δ where the performance is maximal (error min.)



PAM

- For the Khan datatset; 4 classes: BL, EWS, NB, RMS
- At optimal Δ : 43 genes *not* shrunk away

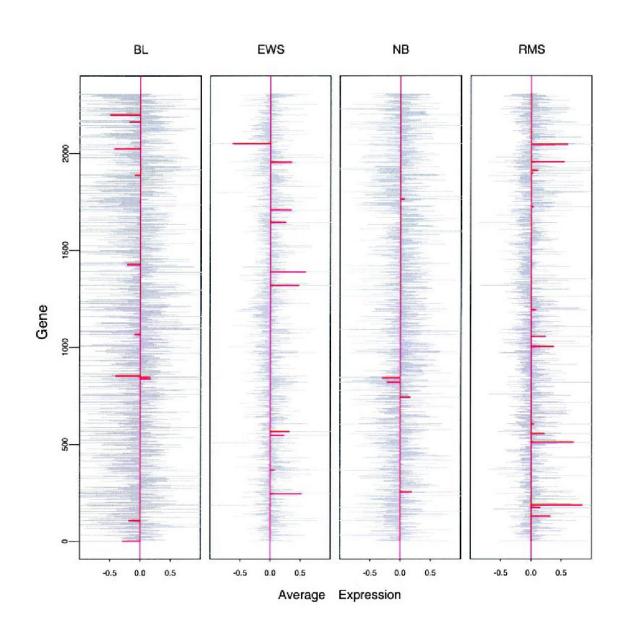


Neuroblastoma (NB) Rhabdomyosarcoma (RMS) Burkitt lymphoma (BL) Ewing family of tumors (EWS),



R. Tibshirani et al. (2002) PNAS 99(10):6567-6572, 2002.

PAM (2)



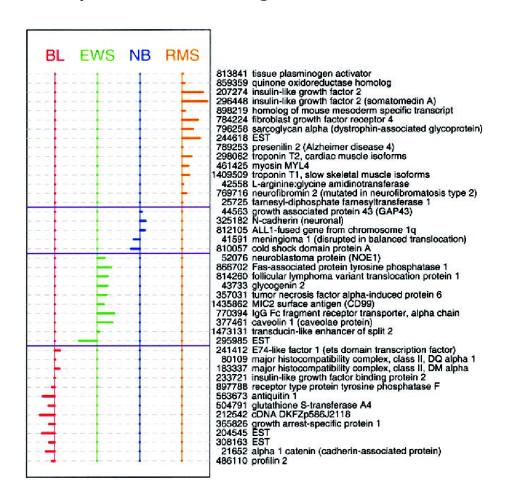






PAM (3)

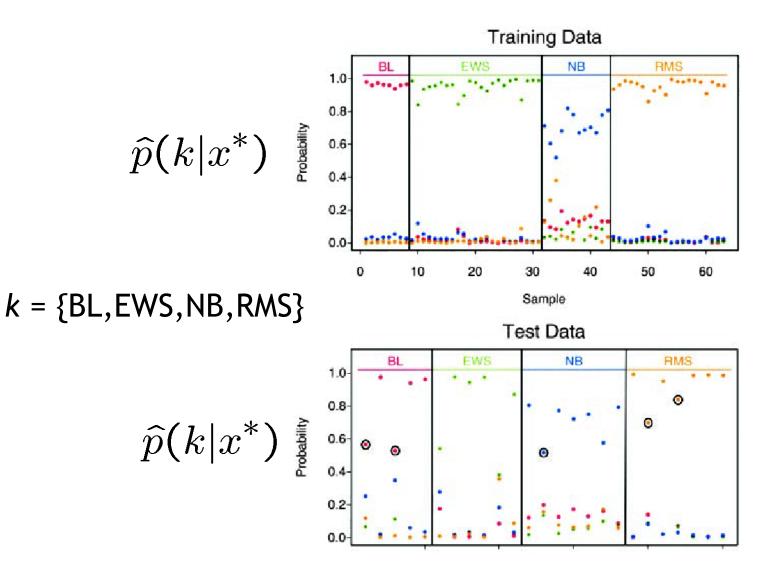
At optimal Δ : 43 genes *not* shrunk away



- Neuroblastoma (NB)
- Rhabdomyosarcoma (RMS)
- Burkitt lymphoma (BL)
- Ewing family of tumors (EWS),



Scoring samples by posterior prob's





Shrinkage

- PAM: controls contribution of genes to classifier based on individual quality (d-measure) and controls degree of contribution with cross-validated classification error
- Other approach: regularisation, combine error and penalty for number of genes explicitly



Shrinkage (2)

• Model:
$$y = \beta_0 + \sum_{i=1}^p \beta_i x_i + \varepsilon$$

- Penalised (aka regularised) least squares:
 - Ridge regression:

$$\hat{\boldsymbol{\beta}} = \arg\min_{\boldsymbol{\beta}} \left| \sum_{j=1}^{n} \left(y_j - \beta_0 - \sum_{i=1}^{p} \beta_i x_{j,i} \right)^2 + \lambda \sum_{i=1}^{p} \beta_i^2 \right|$$

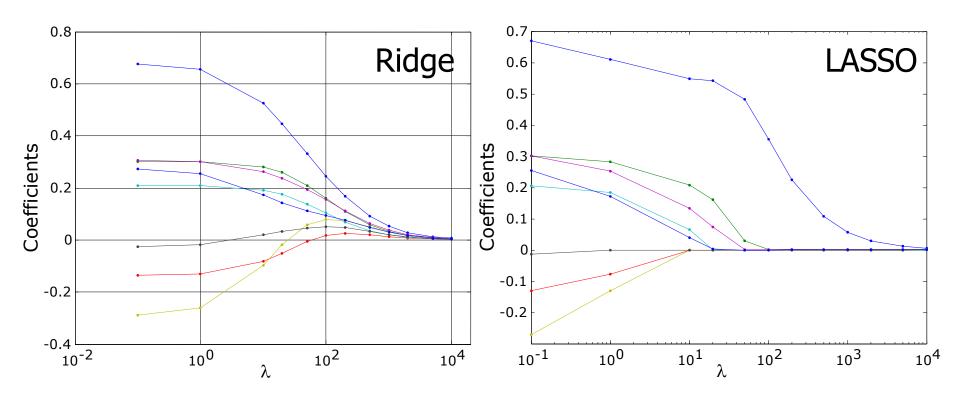
LASSO: minimise

$$\hat{\boldsymbol{\beta}} = \arg\min_{\boldsymbol{\beta}} \left[\sum_{j=1}^{n} \left(y_j - \beta_0 - \sum_{i=1}^{p} \beta_i x_{j,i} \right)^2 + \lambda \sum_{i=1}^{p} \left| \beta_i \right| \right]$$



LASSO

 Difference seems small, but effect of LASSO is that genes are no longer used (like in PAM!)





Final summary

- Feature extraction:
 - Linear:
 - PCA,
 - Fisher
 - Non-linear
 - MDS
- Feature selection:
 - Criteria
 - search algorithms
 - forward,
 - backward,
 - branch & bound.
- Sparse classifiers:
 - Ridge,
 - LASSO

